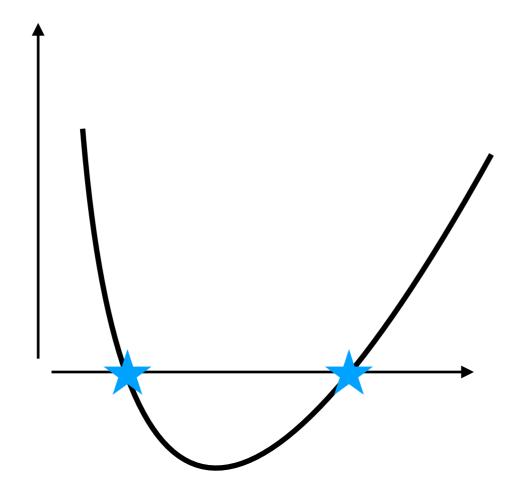
Root finding



Trial and error

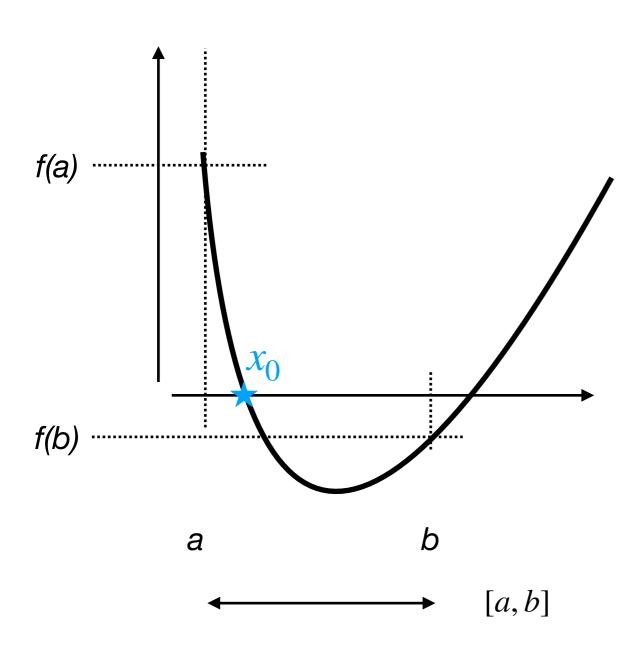
1. guess x_1 (trial)

2. Is
$$f(x_1) = 0$$
? (error)

3. improve x_1

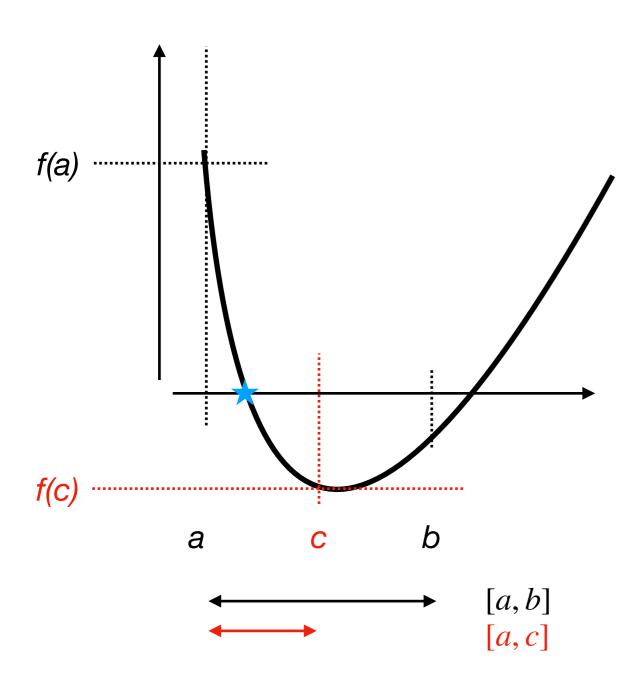


until error < eps (or iterations > max)



$$a < x_0 < b$$

$$f(a) > 0$$
 and $f(b) < 0$

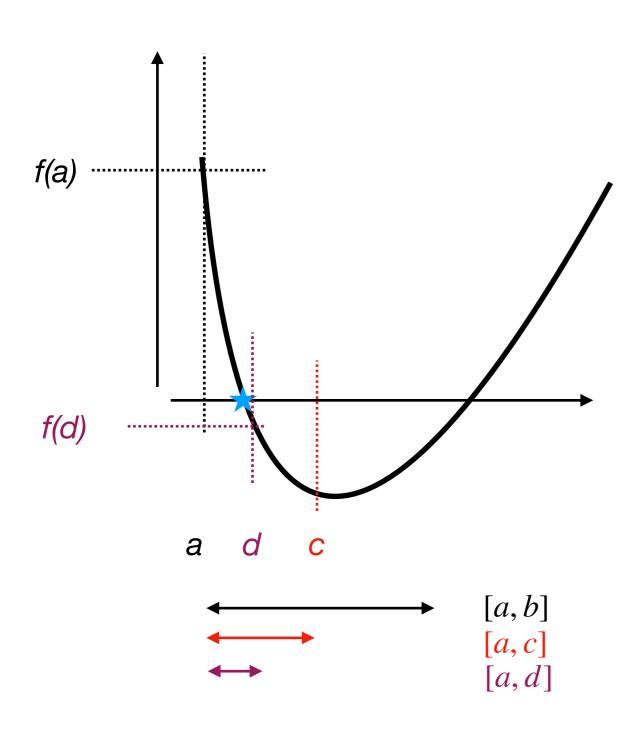


$$f(a) > 0$$
 and $f(c) < 0$
 $a < x_0 < c$

Note:

$$f(c) < 0$$
 and $f(b) < 0$

so root x_0 is not in [c, b]



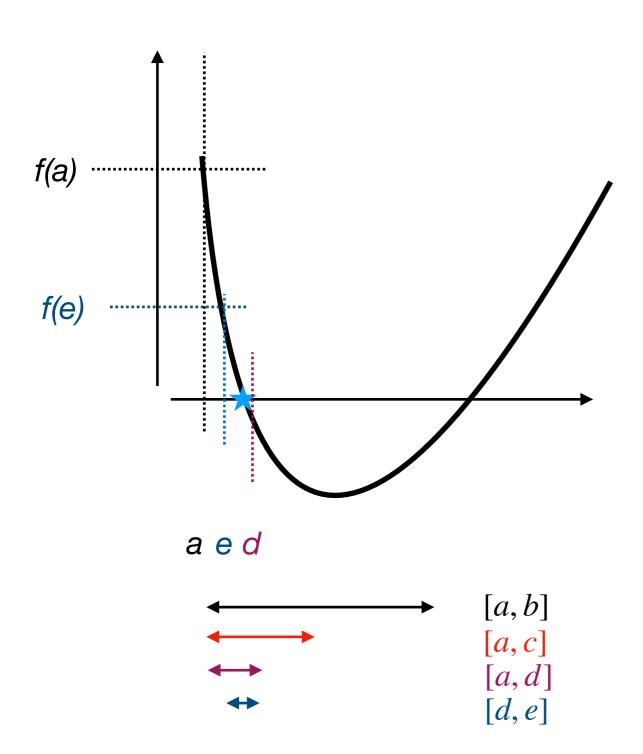
$$f(a) > 0$$
 and $f(d) < 0$

$$a < x_0 < d$$

Note:

$$f(c) < 0$$
 and $f(d) < 0$

so root x_0 is *not* in [d, c]



$$f(e) > 0$$
 and $f(d) < 0$
 $e < x_0 < d$

Note:

$$f(a) > 0$$
 and $f(e) > 0$

so root x_0 is *not* in [a, e]

Bisection algorithm

1.bisect

2.pick half with sign change

$$x = \frac{1}{2}(a+b)$$

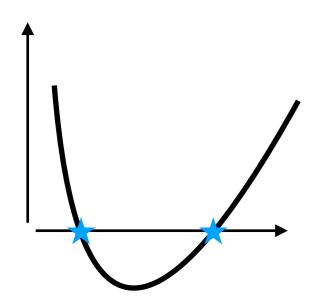
if
$$f(a)f(x) < 0$$

$$x_0 \in [a, x]$$

$$b \leftarrow x$$
else
$$x_0 \in [x, b]$$

$$a \leftarrow x$$

Root finding with trial and error



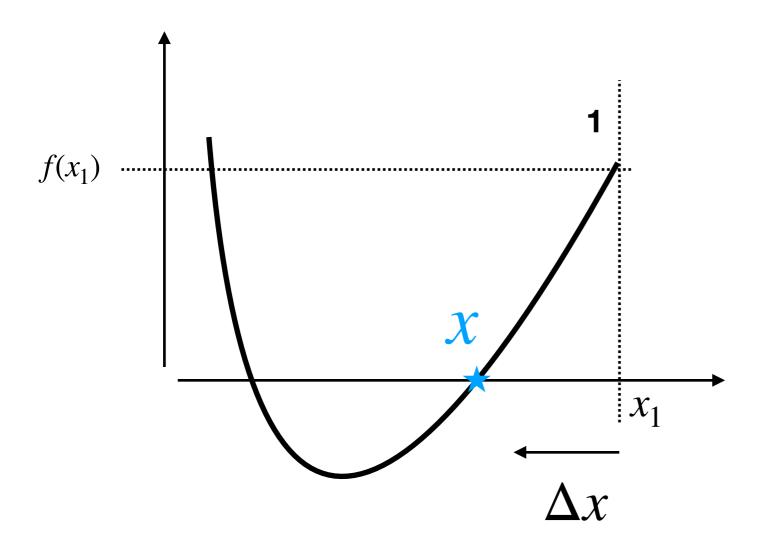
1. guess x_1 (trial)

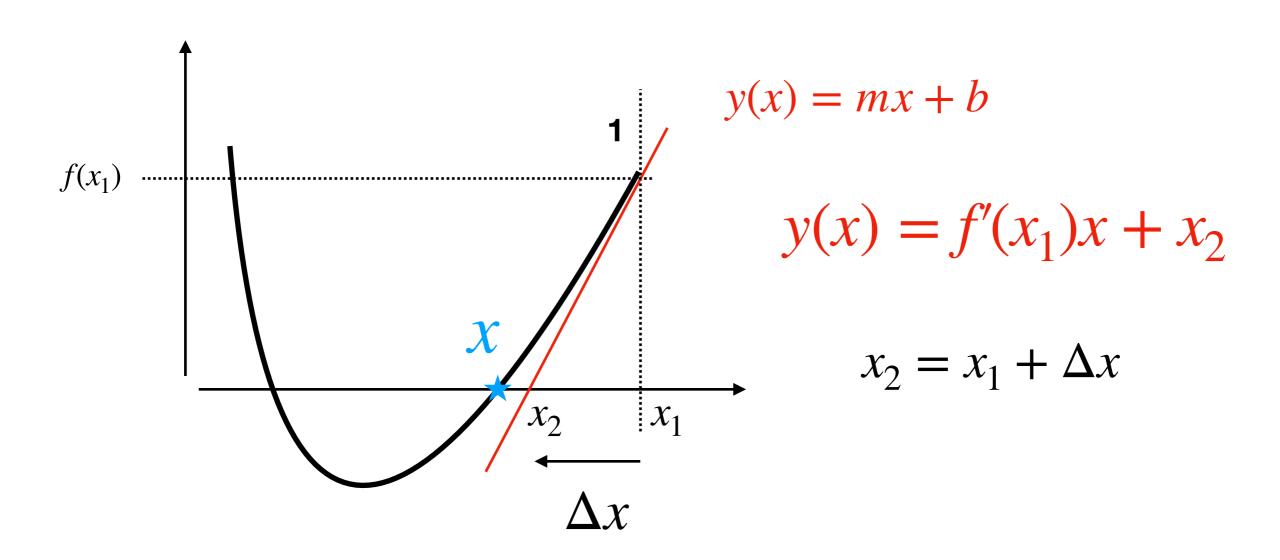
2. Is $f(x_1) = 0$? (error)

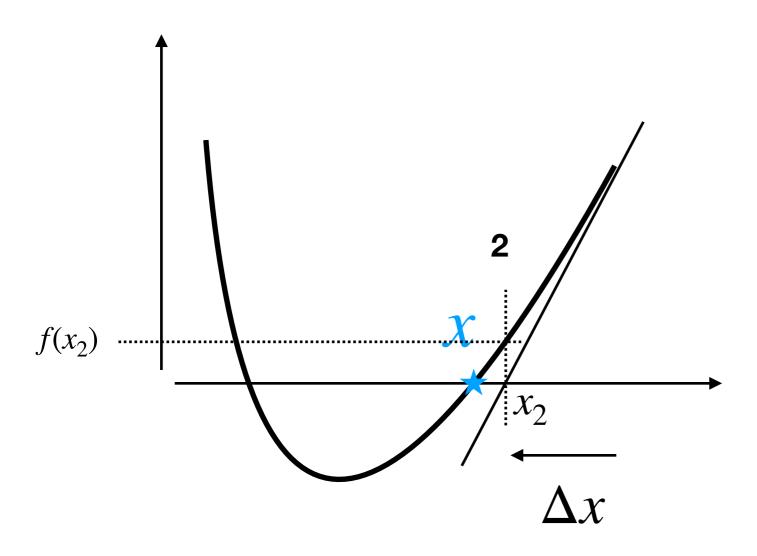
3. improve x_1

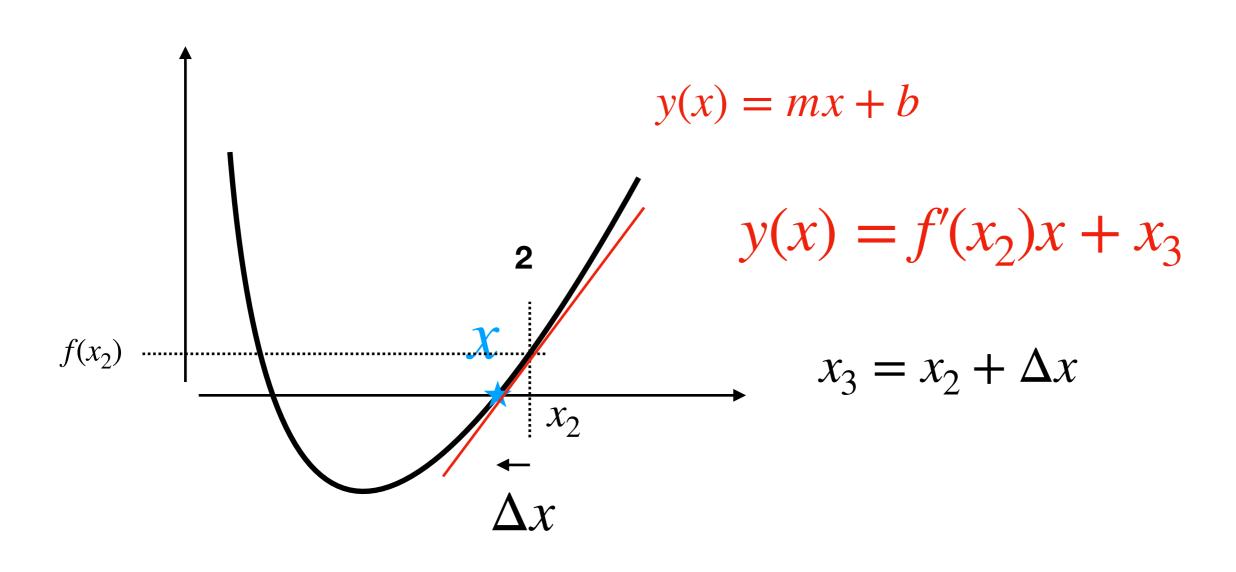


until error < eps (or iterations > max)









NR algorithm

 $egin{array}{ll} \mathcal{X}_0 & \text{initial guess for root} \\ \mathcal{X} & \text{updated guess} \end{array}$

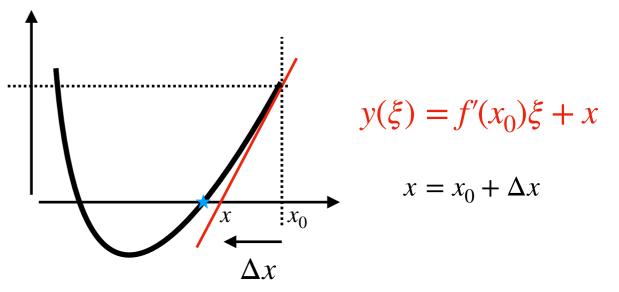
$$x = x_0 + \Delta x$$

correction?

$$f(x = x_0 + \Delta x) \approx f(x_0) + \Delta x \frac{df}{dx} \Big|_{x_0}$$

$$f(x_0) + f'(x_0)\Delta x = 0$$

$$\Delta x = -\frac{f(x_0)}{f'(x_0)}$$



while
$$|f(x) > \epsilon|$$

$$\Delta x = -\frac{f(x)}{f'(x)}$$

$$x \leftarrow x + \Delta x$$

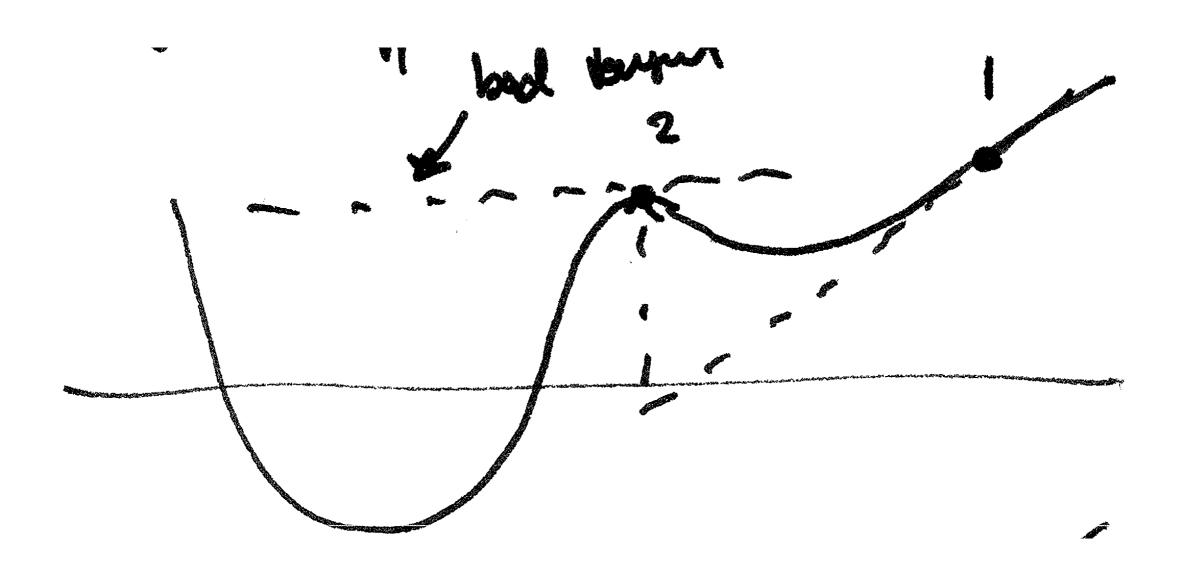
Advantages

- converges very quickly (quadratical convergence!!)
- fast
- works best with analytical derivative (but can use numerical ones)

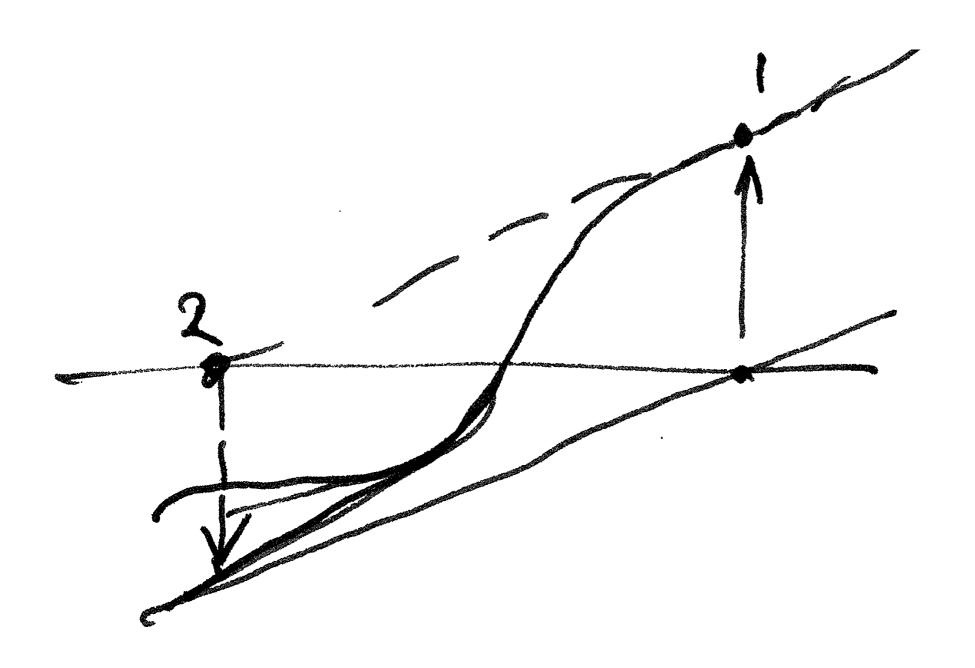
Disadvantages

- guess must be close to root
- can fail/loop in certain situations:

NR - FAILS!



NR – FAILS!



Improvements

- start with bisection to get close to root, then home in with Newton-Raphson
- implement backtracking: if new guess increases error then go back and try smaller guess

$$x \leftarrow x + \Delta x/2$$

