
Table of Contents

main function for low level dyn. use data 0702%%%	1
Initialization	1
Read txt exp. data	1
Calculate dot_pm, segment inflation and deflation process	1
Plot Overlay Results	1
Estimate controller parameters $d_{pm}=a * pm + b * pd$	6
Compare averaged model with different trails	6

main function for low level dyn. use data 0702%%%

Initialization

Read txt exp. data

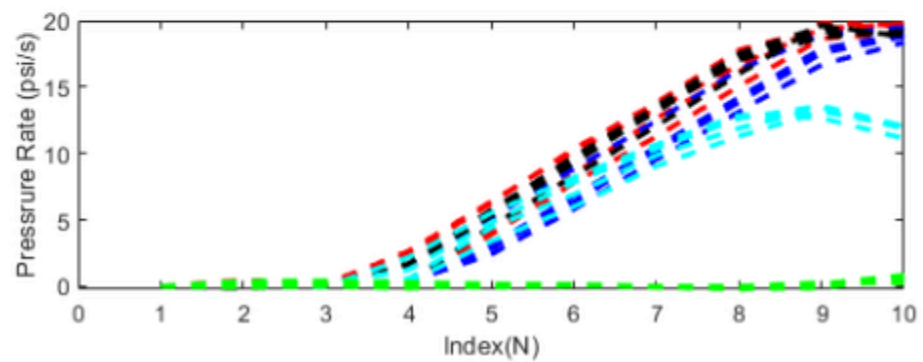
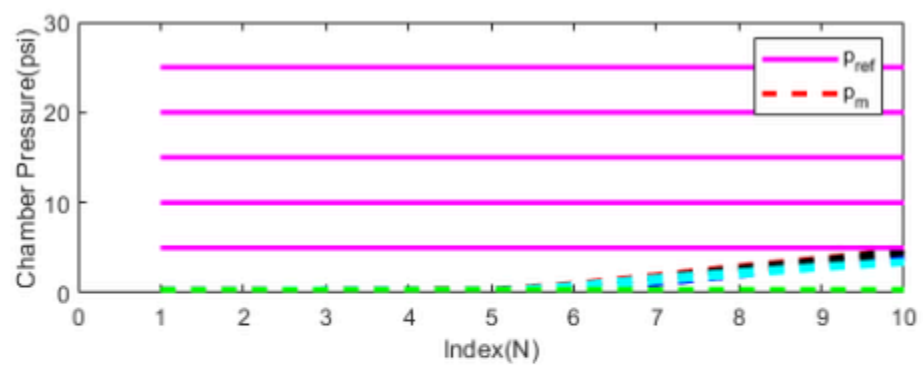
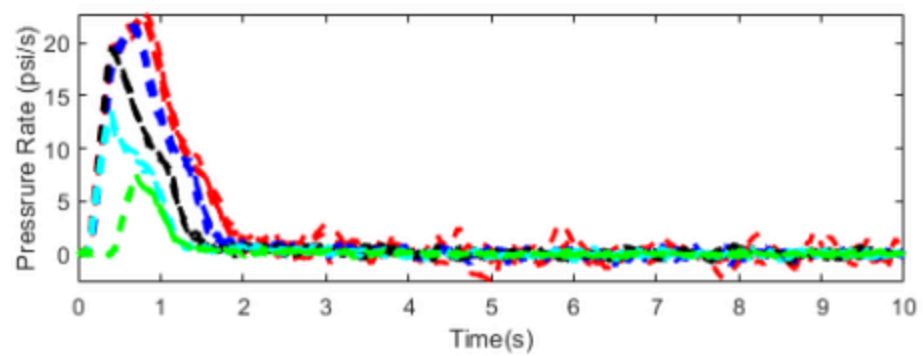
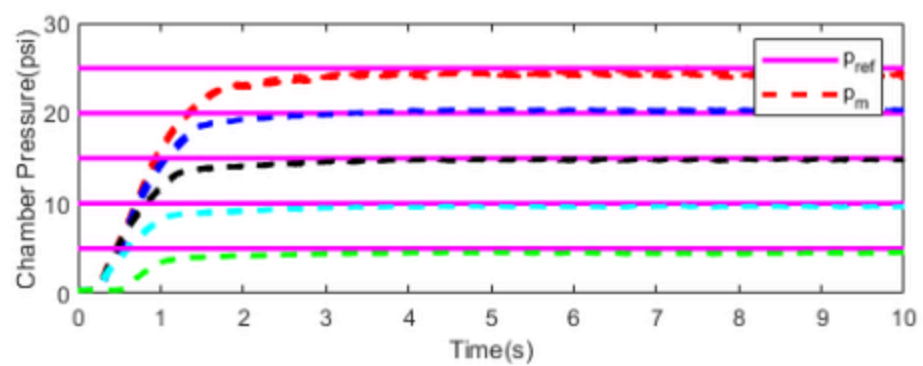
```
exp. data...
exp. data...
exp. data...
exp. data...
exp. data...
exp. data...
exp. data...
exp. data...
exp. data...
Saved
```

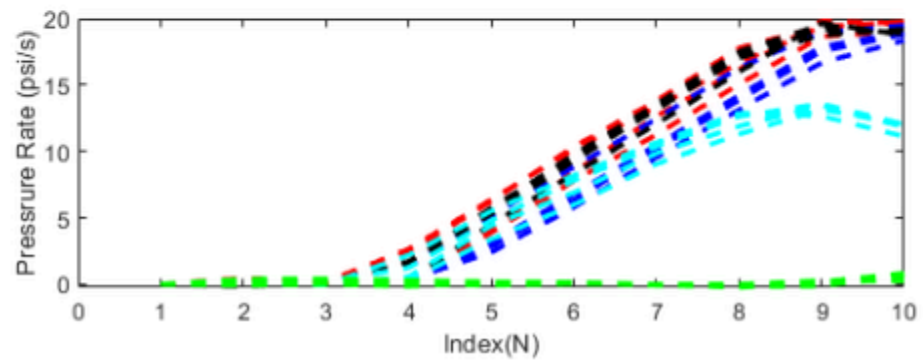
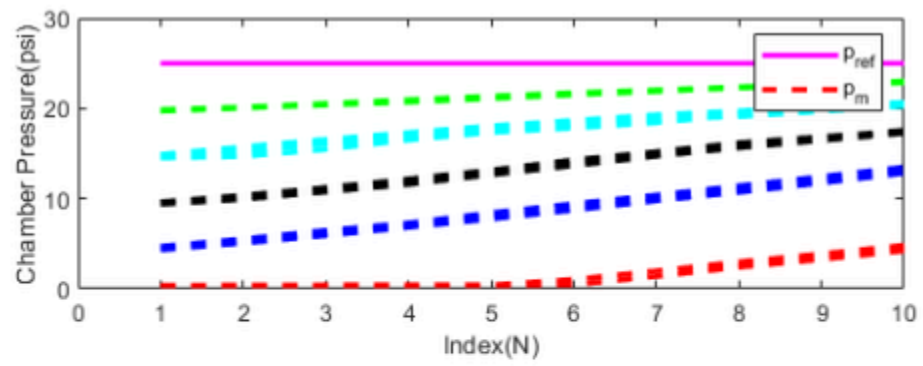
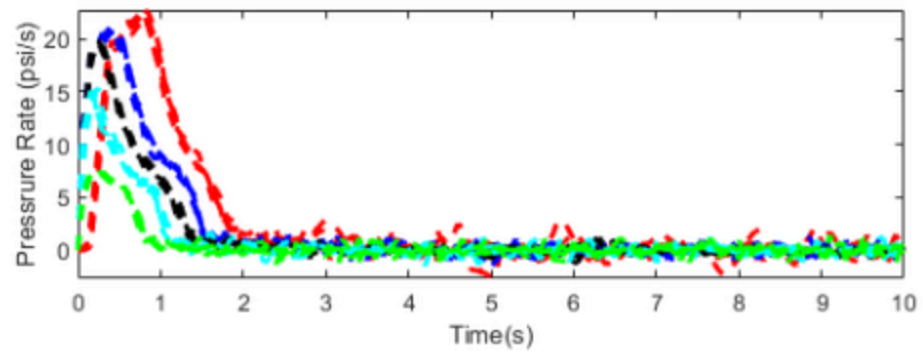
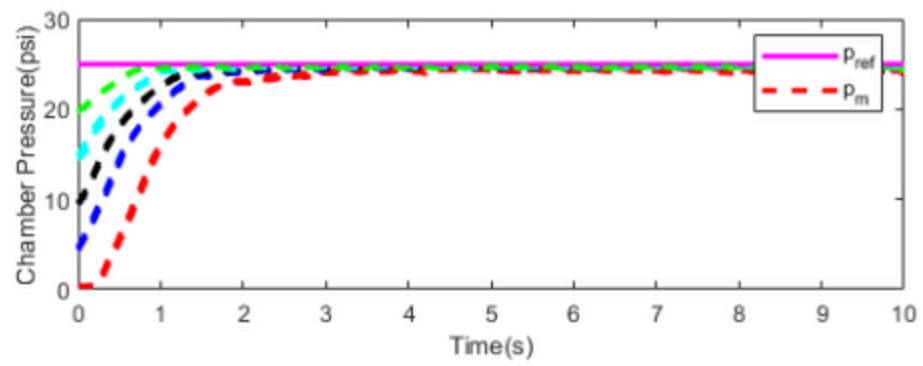
Calculate dot_pm, segment inflation and defla- tion process

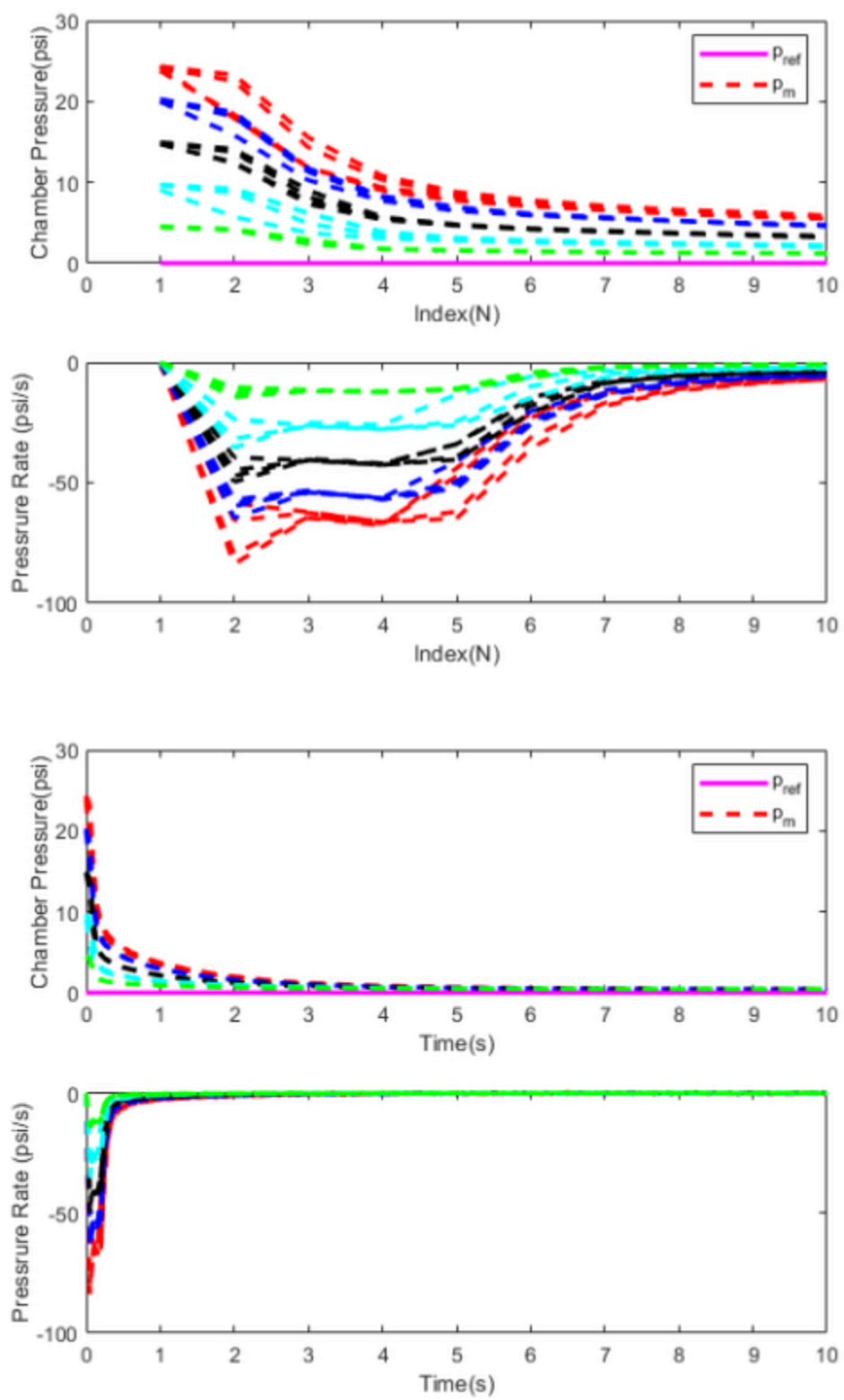
```
Splitting Inf and Def Process
Splitted Inf and Def
```

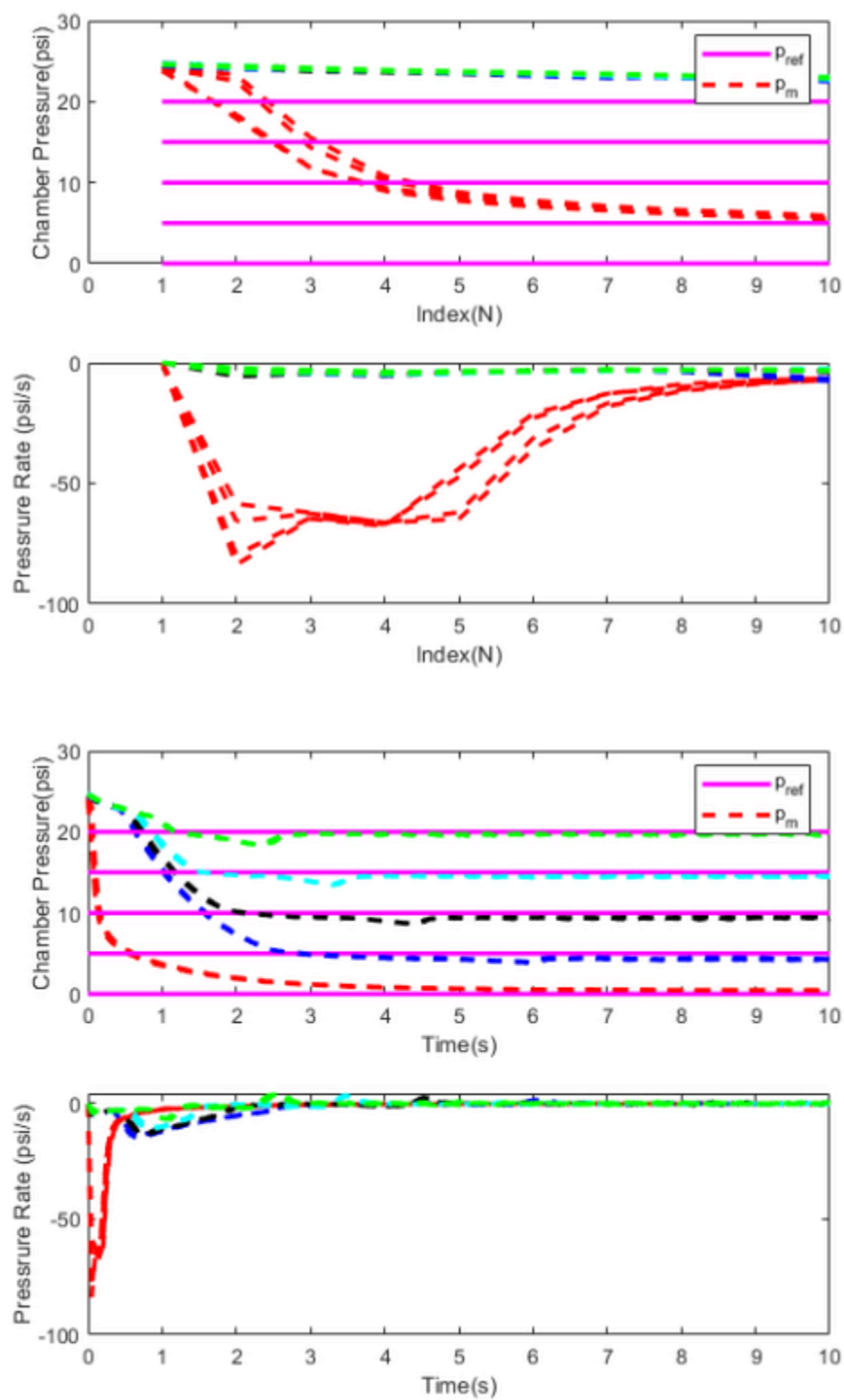
Plot Overlay Results

```
Plotting
```









Estimate controller parameters $d_{pm} = a * pm + b * pd$

Compare averaged model with different trails

Reference to non-existent field 'mean_a'.

Error in func_CompareAveragedModel (line 2)
fprintf('Averaged a is %.4f, b is %.4f',par_set.mean_a,par_set.mean_b)

Error in low_level_main_0_2 (line 51)
par_set=func_CompareAveragedModel(par_set);

Published with MATLAB® R2018b