## 4<sup>th</sup> Design Iteration

الثُّرَيّا :Team Name

□Note: lengths should be in (cm), angles in (deg).

Wing Information				
Airfoil	NACA 6415			
	148 (cm)			
Span				
Root Chord	30 (cm)			
Tip Chord	30 (cm)			
Offset	40 (cm)			
AR	4.93			
$S_w$	4400 (cm <sup>2</sup> )			
Incidence Angle	0			
Twist	0			
Dihedral	4 (deg)			
Vertical Tail Information				
Airfoil	NACA 0009			
Semi Span (Total Length)	20 (cm)			
Root Chord	20 (cm)			
Tip Chord	14 (cm)			
Offset	6 (cm)			
$S_v/S_w$	0.068182			
$AR_{\nu}$	4.71			
V <sub>v</sub>	0.0680562			
Incidence Angle	0			
Tail Arm	65 (cm)			
Shifted Length in Z-Direction	-7 (cm)			
Horizontal Tail Information				
Airfoil	NACA 0009			
Span	64 (cm)			
Root Chord	20 (cm)			
Tip Chord	20 (cm)			
Offset	0			
SH/Sw	0.2955			
AR <sub>H</sub>	3.2			
V <sub>H</sub>	0.64			
Incidence Angle	-2.0 (deg)			
Tail Arm	65 (cm)			
Shifted Length in Z-Direction	-7 (cm)			

## **Propulsion System Information**

Input						
Model Weight (Drive included or without)	2100g include drive					
Desired Flight speed	44.3 km/h					
Brushless Motor	Manufac turer	Model	Voltage Constan t [KV]	No Load Current [A]	Resistanc e [ohm]	
Brasiliess riotor	ElectriFl y	RimFir e 0.15	1200	1.7	0.0415	
Battery	Manufac turer	No. Of Cells	Voltage	Capacity [mAh]	C-Rating	
Dattel y	HRB	3	11.1	5200	50	
Propeller Size (Diameter x Pitch)	10 x 4.7 in.					
Speed Controller (Current Rating Value)	60A					
Output						
Load			6.7	С		
Mixed flight Time			10.5 n	nin		
Max. Current			33.43	3 A		
Max. Power		383.4 W				
Static Thrust		1618 g				
Available Thrust [at the desired flight speed]		1151 g				
Drive Weight		636 g				
All Up Weight		2100 g				
(Power/Weight) Ratio [Watt/lb]		85 W/lb - 187 W/kg				
(Thrust/Weight) Ratio			0.77	7		

## Flight Phases

Phase 1 (payload isn't deployed)			
MTOW	1.7 (Kg)		
$\chi_{cg}$	8.8 (cm)		
Static margin (%)	0.24		
CL <sub>Cruise</sub>	0.48		
V <sub>Stall</sub>	650 (cm/s)		
V Cruise	1320 (cm/s)		
$lpha_{\mathit{Trim}}$	0.067 (deg)		
Required Static Thrust	852.49 (g)		
Required Dynamic Thrust (at <i>v</i> <sub>Cruise</sub> )	214.82 (g)		
Phase 2 (payload is deployed)			
Phase 2 (payloa	d is deployed)		
Phase 2 (payloa Mass	d is deployed) 1.3 (Kg)		
1 7			
Mass	1.3 (Kg)		
Mass X <sub>CG</sub>	1.3 (Kg) 8.8 (cm)		
Mass $X_{CG}$ Static margin (%)	1.3 (Kg) 8.8 (cm) 0.24		
Mass  X <sub>CG</sub> Static margin (%)  CL <sub>Cruise</sub>	1.3 (Kg) 8.8 (cm) 0.24 0.48		
Mass  X <sub>CG</sub> Static margin (%)  CL <sub>Cruise</sub> V <sub>Stall</sub>	1.3 (Kg) 8.8 (cm) 0.24 0.48 650 (cm/s)		
Mass  X <sub>CG</sub> Static margin (%)  CL <sub>Cruise</sub> V <sub>Stall</sub> V cruise	1.3 (Kg) 8.8 (cm) 0.24 0.48 650 (cm/s) 1150 (cm/s)		

## **Very Important Notes**

The wing is actually above the cg of the UAV by 7cm, and the tail is at the same level of the cg, or you can say the wing is at zero and both the tail and the cg is below by 7cm.