

High- Precision Linear Translation Stage

HIGH TRAVEL ACCURACY, LARGE TRAVEL RANGES, MANY MOTOR VARIANTS



M-511 • M-521 • M-531

- __Travel ranges 102, 204 and 306 mm (4", 8", 12")
- _|_Max. velocity up to 100 mm/ s
- __Encoder resolution 50 nm
- __Load capacity to 100 kg
- _|_Zero- backlash ball screws
- __XY & XYZ combinations
- __Noncontact limit and reference point switches
- _!_MTBF >20,000 h

Reference- class linear stage

High travel accuracy and load capacity due to precision linear guides with preloaded recirculating ball bearings. Backlash- compensated recirculating ballscrews with 2 mm pitch. Stress- relieved aluminum for high stability. XY and XYZ combinations possible using M-501/ M-451 precision Z stages. Vacuum versions available

Drive types and position metrology

M-5x1.DD1: Direct drive. DC motor with integrated ActiveDrive amplifiers for high velocity in combination with directly- measuring linear encoder for high resolution and repeatability M-5x1.DD2: Version with integrated brake

Direct drive. DC motor for high velocity in combination with precision rotary encoder

M-5x1.EC: Brushless DC motor with integrated block commutation

M-5x1.PD1: DC motor with integrated ActiveDrive amplifiers

DC servo motor with gearhead in combination with precision rotary encoder for high resolution and repeatability

M-5x1.DG1: DC motor with direct control (analog)

M-5x1.PG1: DC motor with integrated ActiveDrive amplifiers

M-5x1.2S1: Stepper motor

Noncontact limit switches. Noncontact reference point switches in the middle of the travel range

Fields of Application

Science and industry. Vacuum environment up to 10⁻⁶ hPa. Inspection, MEMS fabrication



Specifications

Integrated sensor Line Sensor resolution 0.0 Design resolution 0.1 Min. incremental motion 0.1 Unidirectional repeatability 0.1 Backlash ±0 Pitch / yaw ±25 Straightness / flatness per 100 mm	near encoder 02 µm 05 1 1 1 .2* 5 / ±35 / ±35	204 (8") / M-531: 306 (12 Rotary encoder 4096 0.5 0.5 0.5 1	2") Rotary encoder 2048 0.033 0.1 0.2 1	- - 0.31** 0.1 0.2 1	mm Cts./ rev. µm µm µm µm µm µm mm/ s	typ. typ. typ. typ.
Integrated sensor Line Sensor resolution 0.0 Design resolution 0.1 Min. incremental motion 0.1 Unidirectional repeatability 0.1 Backlash ±0 Pitch / yaw ±25 Straightness / flatness per 100 mm	near encoder 02 µm 05 1 1 1 .2* 5 / ±35 / ±35	Rotary encoder 4096 0.5 0.5 0.5 1	Rotary encoder 2048 0.033 0.1 0.2	- 0.31** 0.1 0.2 1	Cts./ rev. µm µm µm µm µm µm µm µm µm µ	typ. typ. typ.
Sensor resolution 0.0 Design resolution 0.0 Min. incremental motion 0.1 Unidirectional repeatability 0.1 Backlash ±0.1 Pitch / yaw ±25 Straightness / flatness per 100 mm	D2 μm D5 I I .2* 5 / ±35 / ±35	4096 0.5 0.5 0.5 1 1	2048 0.033 0.1 0.2 1	- 0.31** 0.1 0.2 1	µm µm µm µm µrad	typ. typ. typ.
Design resolution 0.0 Min. incremental motion 0.1 Unidirectional repeatability 0.1 Backlash ±0 Pitch / yaw ±25 Straightness / flatness per 100 mm	05 	0.5 0.5 0.5 1	0.033 0.1 0.2 1	0.1 0.2 1	µm µm µm µm µrad	typ. typ. typ.
Min. incremental motion 0.1 Unidirectional repeatability 0.1 Backlash ±0 Pitch / yaw ±25 Straightness / flatness 1 per 100 mm	I I .2* 5 / ±35 / ±35	0.5 0.5 1	0.1 0.2 1	0.1 0.2 1	μm μm μm μrad	typ. typ. typ.
Unidirectional repeatability 0.1 Backlash ±0 Pitch / yaw ±25 Straightness / flatness 1 per 100 mm	1 .2* 5 / ±35 / ±35	0.5 1 1 100	0.2	0.2	μm μm μrad μm	typ.
Backlash ±0 Pitch / yaw ±25 Straightness / flatness 1 per 100 mm	.2* 5 / ±35 / ±35	1 100	1	1	μm μrad μm	typ.
Pitch / yaw ±25 Straightness / flatness 1 per 100 mm	5 / ±35 / ±35	1	1	1	μrad μm	
Straightness / flatness 1 per 100 mm		100			μm	max.
flatness 1 per 100 mm		100				max.
Valacity 50			6	20	mm/ s	max.
Velocity 50		2				
Mechanical properties		2				
Spindle pitch of ball screw 2			2	2	mm	
Gear ratio –		-	$(28/12)^4 \sim 29.6:1$	-		
Load capacity 100	00				N	max.
Push / pull force 80					N	max.
Permissible lateral force 200	0				N	max.
Drive properties						
Motor type with	th	DC motor with PWM control***	DC gear motor	2- phase stepper motor**		
Motor resolution –		_	-	6400**	steps/ rev.	
Guiding Pre	Precision linear guiding rails, recirculating ball bearings					
Operating voltage 24	(PWM)	24 (PWM)	M-5x1.DG1: 0 to ±12 M-5x1.PG1: 24 (PWM)	24	V	
Motor power 30		60	3	5	W	nominal
Torque 80		70	5	150	mNm	nominal
Reference point and limit switches	III effect	Hall effect	Hall effect	Hall effect		
Miscellaneous						
Operating temperature range	to 50	-20 to 65	-20 to 65	-20 to 65	°C	
Material Al ((black anodized)					
Mass 5 (N	M-511) / 6.1 (M-521) / 7	7.2 (M-531)			kg	±5 %
Connector Sub	b- D 15- pin, 3 m cable	incl.				
		C-863 C-884	C-863 C-884	C-663		

Ask about custom designs!
*Bidirectional repeatability for versions with linear encoder.
** Max. 0.85 A/ phase; 400 full steps/ rev.. motor resolution with C-663 stepper motor controller.
*** M-5xx.EC: Brushless DC motor with PWM control



Order Information

Stages with 102 mm travel range:

Precision Translation Stage, 102 mm, ActiveDrive DC Motor, Linear Encoder

M-511.DD2

Precision Translation Stage, 102 mm, ActiveDrive DC Motor, Linear Encoder, Motor Brake

M-511.PD1

Precision Translation Stage, 102 mm, ActiveDrive DC Motor, Rotary Encoder

M-511.EC

Precision Translation Stage, 102 mm, Brushless DC Motor, Rotary Encoder

M-511.DG1

Precision Translation Stage, 102 mm, DC Gear Motor, Rotary Encoder

M-511.PG1

Precision Translation Stage, 102 mm, ActiveDrive DC Gear Motor, Rotary Encoder

M-511.2S1

Precision Translation Stage, 102 mm, Stepper Motor

Stages with 204 mm travel range:

M-521.DD1

Precision Translation Stage, 204 mm, ActiveDrive DC Motor, Linear Encoder

M-521.DD2

Precision Translation Stage, 204 mm, ActiveDrive DC Motor, Linear Encoder, Motor Brake

M-521.PD1

Precision Translation Stage, 204 mm, ActiveDrive DC Motor, Rotary Encoder

M-521.EC

Precision Translation Stage, 204 mm, Brushless DC Motor, Rotary Encoder

M-521.DG1

Precision Translation Stage, 204 mm, DC Gear Motor, Rotary Encoder

M-521.PG1

Precision Translation Stage, 204 mm, ActiveDrive DC Gear Motor, Rotary Encoder

M-521.2S1

Precision Translation Stage, 204 mm, Stepper Motor

Stages with 306 mm travel range:

M-531.DD1

Precision Translation Stage, 306 mm, ActiveDrive DC Motor, Linear Encoder

Precision Translation Stage, 306 mm, ActiveDrive DC Motor, Linear Encoder, Motor Brake

Precision Translation Stage, 306 mm, ActiveDrive DC Motor, Rotary Encoder

M-531.EC

Precision Translation Stage, 306 mm, Brushless DC Motor, Rotary Encoder

Precision Translation Stage, 306 mm, DC Gear Motor, Rotary Encoder

M-531.PG1

Precision Translation Stage, 306 mm, ActiveDrive DC Gear Motor, Rotary Encoder

Precision Translation Stage, 306 mm, Stepper Motor

Vacuum versions and special designs available on request

Adapter plates, adapter brackets, and accessories

Controllers / Drivers / Amplifiers

C-863 Mercury Servo Controller

C-884 Four Axis Motion Controller

C-663 Mercury Step Controller



Accessories

M-060.HP Adapter Plate

M-061.HP Adapter Plate

M-062.HP Adapter Plate

M-110.01 Adapter Plate

M-403.AP1 Adapter Plate

M-403.AP3 Adapter Plate

M-590.00 Three- Point Support Set

M-592.10 Z- Axis Mounting Bracket

M-105.AP Adapter Plate

M-125.90 Z- Axis Mounting Bracket

M-592.00 Z- Axis Mounting Bracket

M-400.AP Adapter Plate

Related Products

M-406 Precision Linear Stage

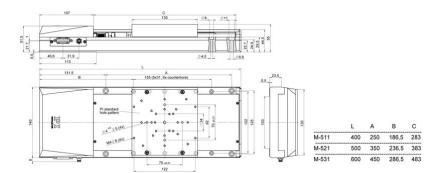
M-414 High- Load Precision Stage

M-511.HD Nano- Precision Heavy- Duty Stage

M-417 Precision Linear Stage



Drawings / Images



M-511, M-521, M-531, dimensions in mm