Simulation Course (ETS061) 2016-2017

Home Assignment 3: Genetic Algorithm

- * The deadline for this homework is June 9, 2017.
- * The answers must be delivered in a written report.
- * All MATLAB source files must be delivered.

You are provided with a basic implementation of a genetic algorithm for Traveling Salesman Problem (TSP) with closed tours. A closed tour starts from a node (i.e. a city) and ends at the same node. You can download the program from the course homepage under the home assignment 3 via link *GA_TSP.zip*. When you unzip it, you will find in the subfolder GA_TSP the source code and the data files needed to run the genetic algorithm. There are three data files with size 48, 70, and 96 cities. You should run the Matlab scripts *loadatt48.m*, *loadst70.m*, and *loadgr96.m* to create the three data files, respectively. To change the parameters and run the GA program you should use the Matlab script *main_ga.m*. The actual implementation of the GA operations are in the script *tsp_ga.m*. This program currently provides the basic structure of a GA including a random generation of initial population, a random mutation operator, and some necessary data structures such as the distance matrix (dmat). The purpose of this home assignment is to complete the provided program by implementing and adding the following GA operations:

- a. **Selection operation:** Implement a *roulette wheel* selection algorithm (see the last example in Lecture H3), which selects a population with a given size of popSize from the current population. The selection must be performed based on the fitness of the individuals. Fitness of an individual v (i.e. a tour) is defined as $\frac{1}{distance(v)}$ where distance(v) is the total distance of the tour v. Based on this, you should obtain the cumulative probability distribution of the population, and use it for the *roulette wheel* selection.
- b. *Elitism:* a fraction *eliteFract* of the best individuals from the current generation (i.e. current population) must directly go to the next generation by replacing the worst individuals in the current population. The selection of the elite individuals must be performed before the *roulette wheel* selection, but they must be transferred to the next population after applying the cross over and mutation operations (the order of operations is clearly specified in the provided code in script *tsp_ga.m*).
- c. *Cross-over operation:* cross-over is performed with a given probability *crossProb*. This is basically the fraction of the population that should undergo the cross over operations. Make sure an even number of individuals are selected in this step. Each cross-over operation involves two parents chosen purely random from the current population (selection of parents does not depend on their fitness). Then, the two parents are combined by the

following procedure to produce exactly one offspring, which is then replace one of its parents chosen at random:

```
Crossover (parent P_1, parent P_2)
K = [0.3 * size(P_1)] ( ] is floor operator, and size(P_1) is the number of cities in P_1)
T_1 = P_1;
T_2 = P_2;
O = \epsilon;
                                         (O is the offspring, and \varepsilon is an empty string)
 While T_1 \neq \varepsilon do
           Split T_1 in two sub-tours T_{11} and T_{12} such that length of T_{11} = \min \{ \text{length of } T_1, K \} ;
           Append T_{11} to O;
           Update T_1 by removing from it the cities in T_{11}
           Update T_2 by removing from it the cities in T_{11}
           X = T_1;
           T_1 = T_2;
           T_2 = X;
End {while};
Return O as the offspring
```

Mutation operation: you should perform 2-opt mutation with a given probability mutProb on the offspring generated by the cross-over operation. The 2-opt mutation is performed by swapping two randomly chosen cities in a tour. This has already been implemented in the code provided for mutation; however, this code performs mutation on a randomly chosen individual from the population. Instead, you should modify the mutation code so that it is performed on the offspring created by cross-over.

Simulation Tasks: with the above operations implemented and validated, set the simulation parameters as follows: crossProb = 0.25, mutProb = 0.5, eliteFract = 0.02, and popSize = 200.

Task 1) set the number of iterations to numGen = 4000, and run your simulation once for each of the three data files. At the end of each iteration, record the solution with the best fitness value (i.e. the tour with minimum distance in the current population) and the average fitness of the population. Then, using your recorded values for all iterations, plot a graph for each data file, showing the best and average fitness with respect to iteration number. Using these plots, explain the convergence behavior of GA for the three data files (i.e. do they converge? How quickly they converge?).

Task 2) use different values for the number of iteration (numGen) from 100 to 2000 with a step size of 100. For each value of numGen, run your simulation 15 times and record the average cost (i.e. distance) of the best tour found by GA with a 95% confidence interval for 15 runs. Using these results, plot the average cost (together with the confidence interval) with respect to numGen. Do this experiment separately for the three data files loadatt48, loadst70, and loadgr96. By observing your plots, explain the convergence behavior of GA for each data file scenario and with respect to numGen. For which data file the confidence interval is tighter and what does this mean?