** This is a placeholder document and will be replaced with the real final project document**

With the move towards sustainability, EV, or electric vehicles play a crucial role in reducing air pollution.

The goal of this project is to be able to program a self driving car to be able to drive through to an EV station and get charged.

Parameters:
  ● There are 2 loops: The highway and the charging station.
  ● There is an offramp going to the charging station

Tasks:
  ● Implement line following capabilities to the car
  ● Know the charge state of the car