Chapter 6: More Image Enhancement

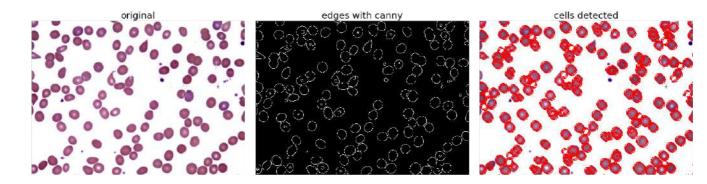
Problems

- 1. Object detection with Hough Transform and Colors
- 1.1 Counting cirular objects in an image with Circle Hough Transform

```
In [7]: print(len(cx))

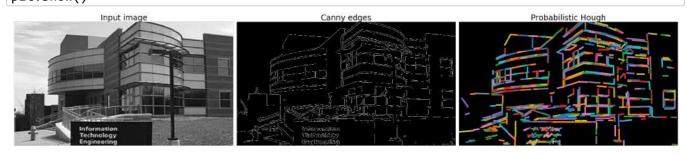
plt.figure(figsize=(20, 8))
plt.gray()
plt.subplots_adjust(0,0,1,0.975,0.05,0.05)
plt.subplot(131), plt.imshow(orig), plt.axis('off'), plt.title('original', size=20)
plt.subplot(132), plt.imshow(edges), plt.axis('off'), plt.title('edges with canny', size plt.subplot(133), plt.imshow(image), plt.axis('off'), plt.title('cells detected', size=2 plt.suptitle('Counting blood-cells with Circle Hough transform, number of cells={}'.fore plt.show()
```

Counting blood-cells with Circle Hough transform, number of cells=172



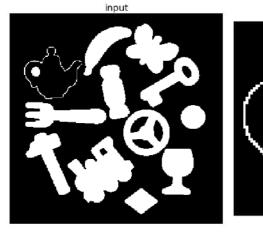
1.2 Detecting lines with Progressive Probabilistic Hough Transform

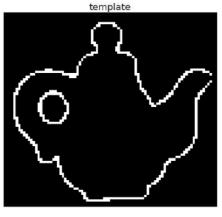
```
In [10]: fig, axes = plt.subplots(1, 3, figsize=(30, 20), sharex=True, sharey=True)
         ax = axes.ravel()
         plt.gray()
         ax[0].imshow(image, cmap=plt.cm.gray)
         ax[0].set_title('Input image', size=25)
         ax[1].imshow(edges, cmap=plt.cm.gray)
         ax[1].set_title('Canny edges', size=25)
         ax[2].imshow(edges * 0)
         for line in lines:
          p0, p1 = line
         ax[2].plot((p0[0], p1[0]), (p0[1], p1[1]), linewidth=5)
         ax[2].set_xlim((0, image.shape[1]))
         ax[2].set_ylim((image.shape[0], 0))
         ax[2].set_title('Probabilistic Hough', size=25)
         for a in ax:
          a.set_axis_off()
         plt.axis('off')
         plt.tight_layout()
         plt.show()
```

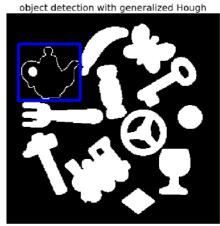


2.3 Detecting Objects of arbitrary shapes using Generalized Hough Transform

```
In [17]: plt.figure(figsize=(20, 8))
    plt.gray()
    plt.subplots_adjust(0,0,1,0.975,0.05,0.05)
    plt.subplot(131), plt.imshow(img), plt.axis('off'), plt.title('input', size=20)
    plt.subplot(132), plt.imshow(templ), plt.axis('off'), plt.title('template', size=20)
    plt.subplot(133), plt.imshow(clone), plt.axis('off'), plt.title('object detection with plt.show()
```



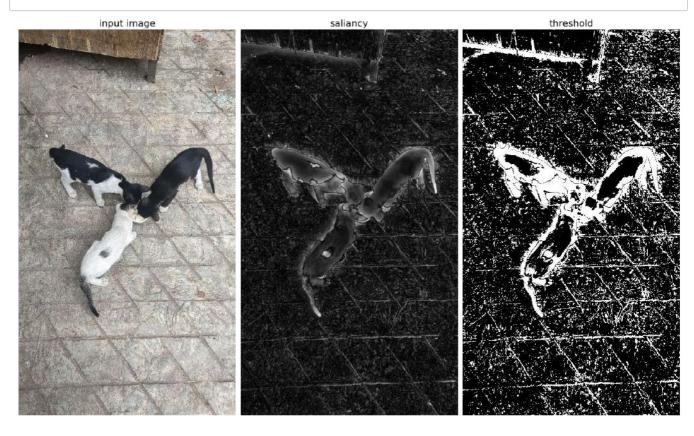




2. Object Saliency Map, Depth Map and Tone Map (HDR) with opency-python

2.1 Creating Object Saliency Map

```
In [28]: # show the images
    plt.figure(figsize=(20,20))
    plt.gray()
    plt.subplot(131), plt.imshow(cv2.cvtColor(image, cv2.COLOR_BGR2RGB)), plt.axis('off'), plt.subplot(132), plt.imshow(saliency_map), plt.axis('off'), plt.title('saliancy', size= plt.subplot(133), plt.imshow(thresh_map), plt.axis('off'), plt.title('threshold', size= plt.tight_layout()
    plt.show()
```



2.2 Creating Depth-Map from Stereo images

```
In [34]: plt.figure(figsize=(20,20))
    plt.gray()
    plt.subplot(131), plt.imshow(img_left), plt.axis('off'), plt.title('left unput image', plt.subplot(132), plt.imshow(img_right), plt.axis('off'), plt.title('right input image')
    plt.subplot(133), plt.imshow(disparity), plt.axis('off'), plt.title('disparity map', size plt.tight_layout()
    plt.show()
```

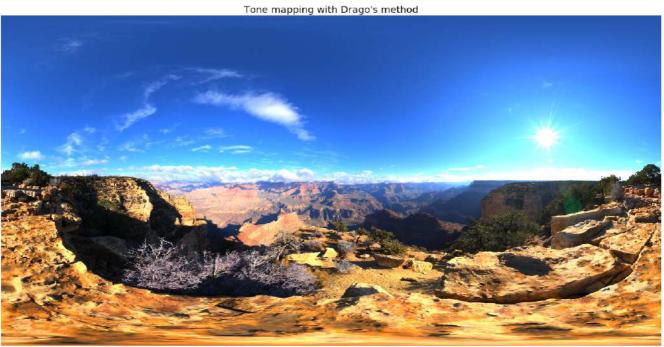


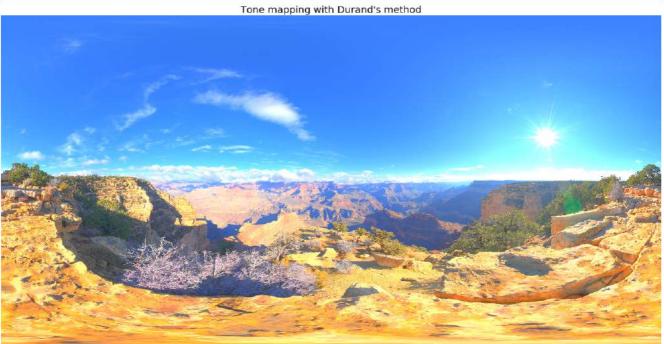
2.3 Tone mapping and High Dynamic Range (HDR) Imaging

```
In [6]: plt.figure(figsize=(20,20))
   plt.subplot(211), plt.imshow(ldr_drago), plt.axis('off'), plt.title('Tone mapping with [
        plt.subplot(212), plt.imshow(ldr_durand), plt.axis('off'), plt.title('Tone mapping with
        plt.tight_layout()
        plt.show()
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

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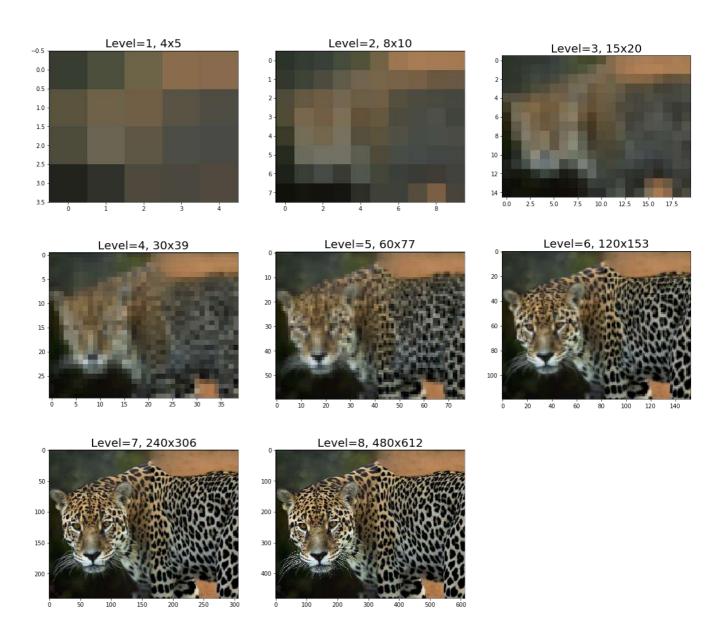
3. Pyramid Blending

```
In [34]: im = reconstruct_image_from_laplacian_pyramid(pyramidC)

plt.figure(figsize=(20,10))
   plt.imshow(im), plt.axis('off'), plt.title('Blended output image with Pyramid', size=20)
   plt.show()
```

```
(4, 5, 3) (4, 5, 3)
(8, 10, 3) (8, 10, 3)
(15, 20, 3) (15, 20, 3)
(30, 39, 3) (30, 39, 3)
(60, 77, 3) (60, 77, 3)
(120, 153, 3) (120, 153, 3)
(240, 306, 3) (240, 306, 3)
(480, 612, 3) (480, 612, 3)
```

Image constructed from the Laplacian Pyramid

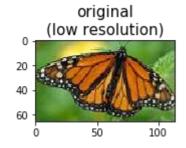


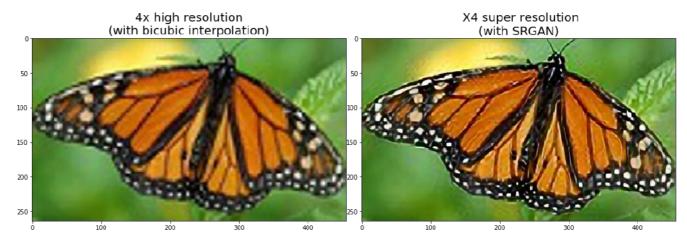
Blended output image with Pyramid



4. Image Super Resolution with deep learning model (SRGAN)

```
In [47]: plt.figure(figsize=(2.5, 1.5))
    plt.imshow(lr), plt.title('original\n(low resolution)', size=15)
    plt.show()
    plt.figure(figsize=(15, 9))
    plt.subplots_adjust(0,0,1,1,0.05,0.05)
    images = [sr, gan_sr]
    titles = ['4x high resolution\n(with bicubic interpolation)', ' X4 super resolution\n(w: positions = [1, 2]
    for i, (img, title, pos) in enumerate(zip(images, titles, positions)):
        plt.subplot(1, 2, pos)
        plt.imshow(img)
        plt.title(title, size=20)
    plt.show()
```





5. Low-light Image Enhancement Using CNNs

```
In [54]: def plot_image(image, title=None, sz=20):
    plt.imshow(image)
    plt.title(title, size=sz)
    plt.axis('off')

plt.figure(figsize=(20,10))
    plt.subplot(121), plot_image(img, 'low-light input')
    plt.subplot(122), plot_image(np.clip(out, 0, 1), 'enhanced output')
    plt.tight_layout()
    plt.show()
```





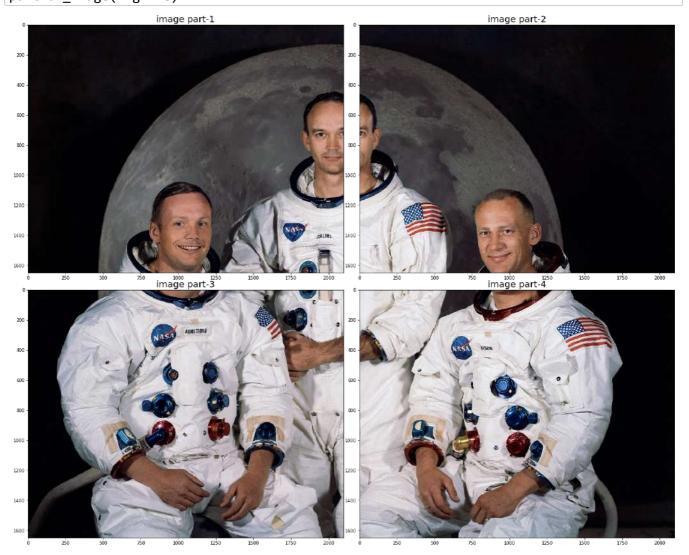
6. Realistic Image Dehazing using deep neural net

```
In [66]: plt.figure(figsize=(20,10))
   plt.subplot(121), plot_image(im, 'hazed input')
   plt.subplot(122), plot_image(out, 'de-hazed output')
   plt.tight_layout()
   plt.show()
```



7. Distributed Image Processing with Dask

In [69]: imgfile = 'images/Img_06_22.png'
partion_image(imgfile)

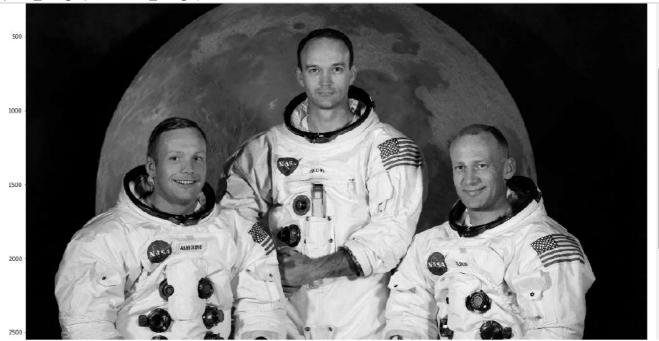


```
In [71]: result = (rgb2gray(partitioned_images))
    print(result.shape)
    plot_image(result[0])
```

(4, 1650, 2100)

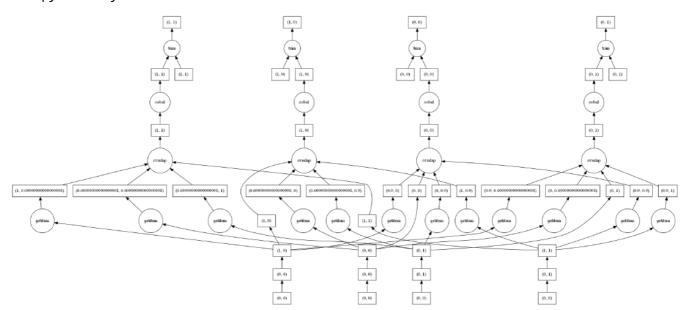


In [72]: data = [result[i, ...] for i in range(result.shape[0])]
 data = [data[i:i+2] for i in range(0, len(data), 2)]
 combined_image = dask.array.block(data)
 print(combined_image.shape)
 plot_image(combined_image)



In [73]: edges = dask_image.ndfilters.sobel(combined_image)
 print(edges)
 display(edges.visualize())

dask.array<_trim, shape=(3300, 4200), dtype=float64, chunksize=(1650, 2100), chunktype
=numpy.ndarray>



In [74]: edges = np.clip(edges, 0, 1)
plot_image(edges)

