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$$Y_{px} = \frac{1}{\sqrt{2}} (Y_{1,-1} - Y_{1,1})$$

$$Y_{py} = \frac{i}{\sqrt{2}} (Y_{1,-1} + Y_{1,1})$$

絶対値の  
2乗が  
1(0,0)  
の方向に  
電子が存在  
しやすくなる

$$\hat{H}\psi = E\psi$$

$(\psi)^2$  で粒子の存在確率を示す

$$\hat{L}_{\pm} = \hat{L}_x \pm i\hat{L}_y \quad \dots \quad (1)$$

$$\hat{L}_{\pm} |l, m\rangle = \hbar \sqrt{(l \mp m)(l \pm m + 1)} |l, m \pm 1\rangle \quad \dots \quad (2)$$

① 昇降演算子

$$\hat{L}_{\pm} = \hat{L}_x \pm i\hat{L}_y$$

$$2i\hat{L}_y$$

$$\Rightarrow \begin{cases} \hat{L}_+ = \hat{L}_x + i\hat{L}_y \\ \hat{L}_- = \hat{L}_x - i\hat{L}_y \end{cases}$$

$$\frac{\hat{L}_+ - \hat{L}_-}{2i} = \hat{L}_y$$

$$\hat{L}_+ + \hat{L}_- = 2\hat{L}_x$$

$$\Leftrightarrow \hat{L}_x = \frac{\hat{L}_+ + \hat{L}_-}{2} \quad \dots \quad (3)$$

$$\hat{L}_y = \frac{\hat{L}_+ - \hat{L}_-}{2i} \quad \dots \quad (4)$$

1.  $Y_{px}$  の場合

$$\hat{L}_x Y_{px} = \frac{\hat{L}_+ + \hat{L}_-}{2} \left\{ \frac{1}{\sqrt{2}} (Y_{1,-1} - Y_{1,1}) \right\} \quad (\because (3))$$

$$= \frac{1}{2\sqrt{2}} (\hat{L}_+ Y_{1,-1} - \hat{L}_+ Y_{1,1} + \hat{L}_- Y_{1,-1} - \hat{L}_- Y_{1,1})$$

$$\therefore \text{②より} \quad \hat{L}_+ Y_{1,-1} = \hat{L}_+ |1, -1\rangle = \hbar \sqrt{(2)(1)} |1, 0\rangle = \sqrt{2} \hbar Y_{1,0}$$

$$\hat{L}_+ Y_{1,1} = \hat{L}_+ |1, 1\rangle \Rightarrow \text{上昇不可}$$

$$\hat{L}_- Y_{1,-1} = \hat{L}_- |1, -1\rangle \Rightarrow \text{降下不可}$$

$$\hat{L}_- Y_{1,1} = \hat{L}_- |1, 1\rangle \Rightarrow \hbar \sqrt{(2)(1)} |1, 0\rangle = \sqrt{2} \hbar Y_{1,0} \quad \text{と②の7.}$$

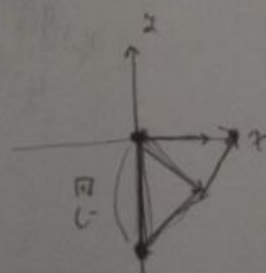
$$\hat{L}_x Y_{px} = \frac{1}{2\sqrt{2}} (\sqrt{2} \hbar Y_{1,0} - \sqrt{2} \hbar Y_{1,0})$$

$$= \frac{\hbar}{\sqrt{2}} \left( \frac{1}{\sqrt{2}} (Y_{1,0} - Y_{1,0}) \right)$$

$$= \frac{\hbar}{\sqrt{2}} Y_{px}$$

$$Y_{1,-1} = Y_{1,1}$$

$$\hat{L}_x = \frac{\hbar}{\sqrt{2}}$$



2.  $Y_{py}$  の場合

$$\hat{L}_z Y_{py} = \frac{\hat{L}_+ \hat{L}_-}{2\hbar} \left\{ \frac{1}{\sqrt{2}} (Y_{1,-1} + Y_{1,1}) \right\} \quad (\because \textcircled{4})$$

$$= \frac{1}{2\sqrt{2}} (\hat{L}_+ Y_{1,-1} + \hat{L}_+ Y_{1,1} - \hat{L}_- Y_{1,-1} - \hat{L}_- Y_{1,1})$$

ここから

② 行

$$\hat{L}_+ Y_{1,-1} = \hbar \sqrt{(2)(1)} |1,0\rangle = \sqrt{2}\hbar |1,0\rangle = \sqrt{2}\hbar Y_{1,0}$$

$$\hat{L}_+ Y_{1,1} \rightarrow \text{上昇不可}$$

$$\hat{L}_- Y_{1,-1} = \hat{L}_- |1,-1\rangle \rightarrow \text{降下不可}$$

$$\hat{L}_- Y_{1,1} = \sqrt{2}\hbar Y_{1,0} \quad \text{とちろのり}$$

$$\hat{L}_z Y_{py} = \frac{1}{2\sqrt{2}} (\sqrt{2}\hbar Y_{1,0} - \sqrt{2}\hbar Y_{1,0})$$

$$= \frac{\hbar}{\sqrt{2}} \left\{ \frac{1}{\sqrt{2}} (Y_{1,0} - Y_{1,0}) \right\}$$

$$= \frac{\hbar}{\sqrt{2}} Y_{py}$$

$$\hat{L}_z = \frac{\hbar}{\sqrt{2}}$$