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# Deep Neural Networks

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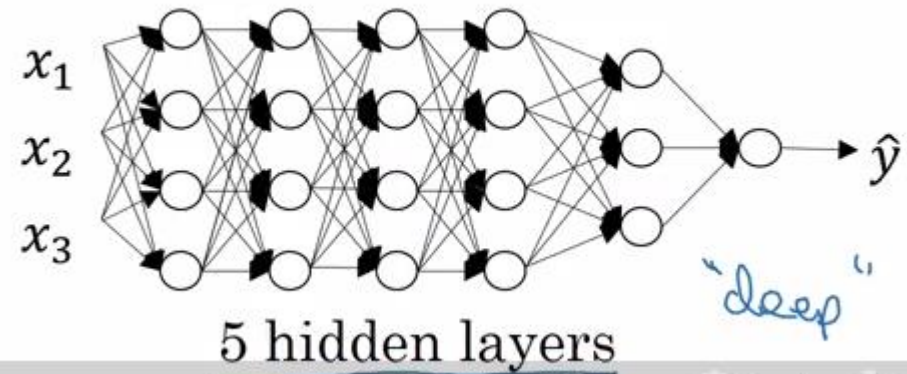
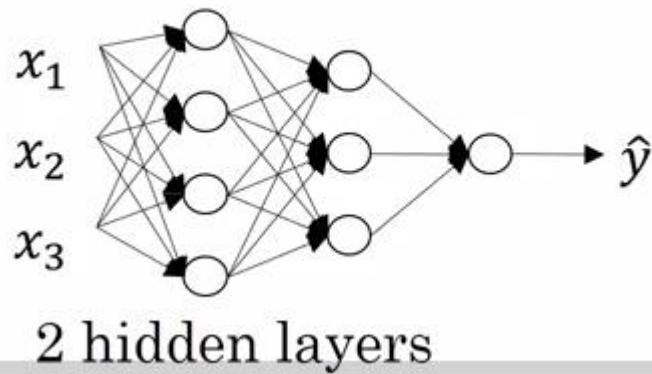
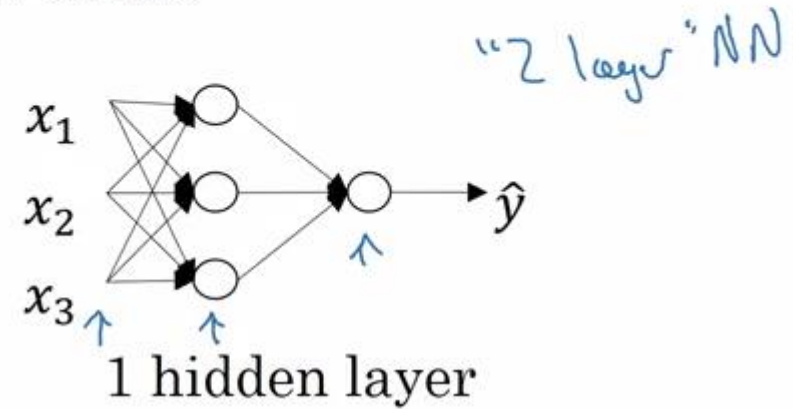
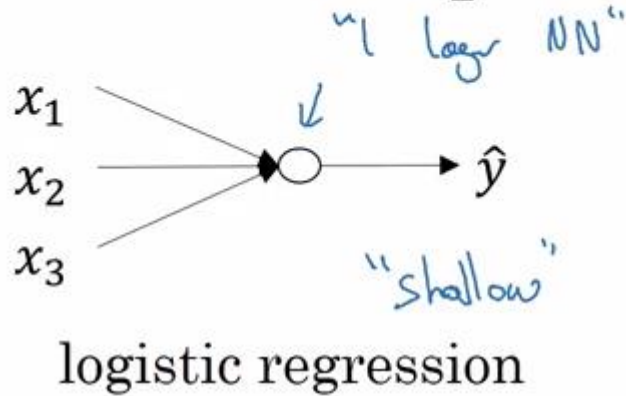
## Deep L-layer Neural network



0:01 / 5:51



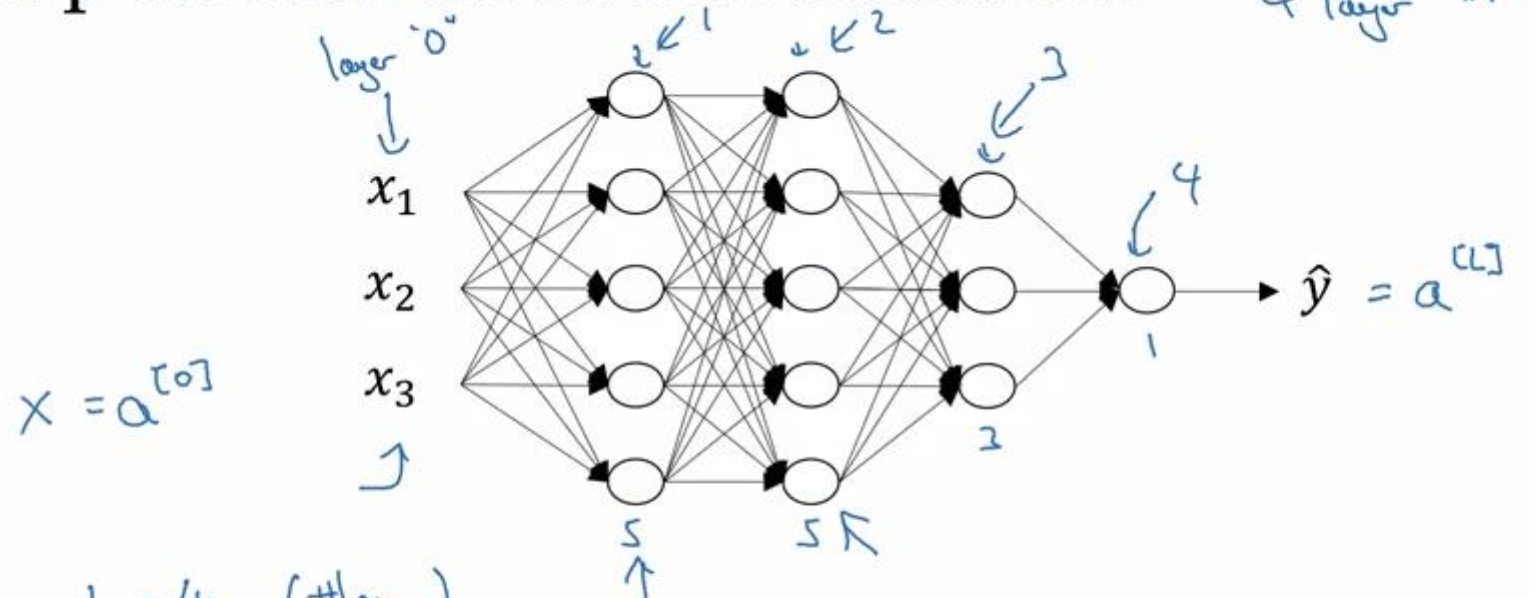
# What is a deep neural network?



2:30 / 5:51

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# Deep neural network notation



$L = 4$  (#layers)

$n^{[l]} = \# \text{units in layer } l$

$a^{[l]} = \text{activations in layer } l$

$a^{[l]} = g(z^{[l]})$ ,  $w_{\delta}^{[l]} = \text{weights for } \underline{z^{[l]}}$

$n^{[1]} = 5, n^{[2]} = 5, n^{[3]} = 3, n^{[4]} = n^{[L]} = 1$   
 $n^{[0]} = n_x = 3$



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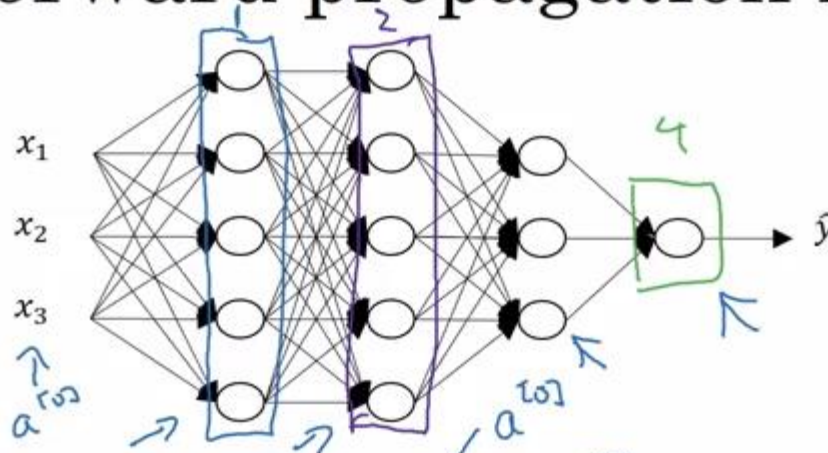
## Forward Propagation in a Deep Network



0:02 / 7:15



# Forward propagation in a deep network



$$X: z^{[1]} = W^{[1]} a^{[0]} + b^{[1]}$$

$$a^{[1]} = g(z^{[1]})$$

$$z^{[2]} = W^{[2]} a^{[1]} + b^{[2]}$$

$$a^{[2]} = g(z^{[2]})$$

$$z^{[4]} = W^{[4]} a^{[3]} + b^{[4]}, a^{[4]} = g(z^{[4]}) = \hat{y}$$

$$\begin{aligned} z^{[l]} &= W^{[l]} A^{[l-1]} + b^{[l]} \\ A^{[l]} &= g(z^{[l]}) \end{aligned}$$

$A^{[0]} = X$

Vertical:

$$\begin{aligned} z^{[1]} &= W^{[1]} A^{[0]} + b^{[1]} \\ A^{[1]} &= g(z^{[1]}) \\ z^{[2]} &= W^{[2]} A^{[1]} + b^{[2]} \\ A^{[2]} &= g(z^{[2]}) \\ &\vdots \\ z^{[4]} &= W^{[4]} A^{[3]} + b^{[4]} \\ A^{[4]} &= g(z^{[4]}) = \hat{y} \end{aligned}$$

$X = A^{[0]}$   
for  $l=1 \dots 4$



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# Deep Neural Networks

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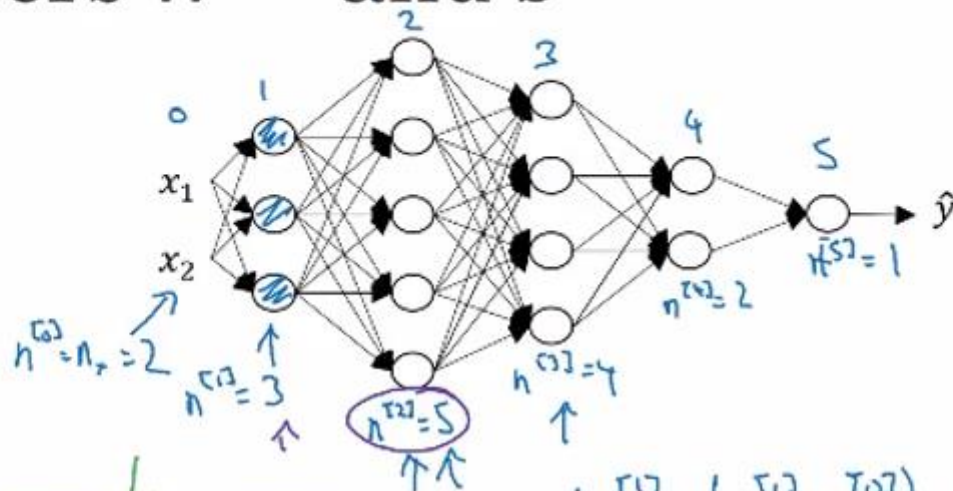
Getting your matrix  
dimensions right



# Parameters $W^{[l]}$ and $b^{[l]}$

$L=5$

$\downarrow z^{[L]} = g^{[L]}(a^{[L]})$   
 $\uparrow$   
 $\downarrow a^{[L]}$



$\rightarrow W^{[L]}: (n^{[L]}, n^{[L-1]})$   
 $\rightarrow b^{[L]}: (n^{[L]}, 1)$   
 $\rightarrow \Delta W^{[L]}: (n^{[L]}, n^{[L-1]})$   
 $\rightarrow \Delta b^{[L]}: (n^{[L]}, 1)$

$\downarrow z^{[1]} = W^{[1]} \cdot x + b^{[1]}$   
 $(3,1) \leftarrow (3,2) \quad (2,1)$   
 $(n^{[1]},1) \quad (n^{[1]},n^{[0]}) \quad (n^{[1]},1)$

$\begin{bmatrix} \vdots \\ \vdots \end{bmatrix} = \begin{bmatrix} \vdots \\ \vdots \end{bmatrix} \begin{bmatrix} \vdots \\ \vdots \end{bmatrix}$

$W^{[1]}: (n^{[1]}, n^{[0]})$

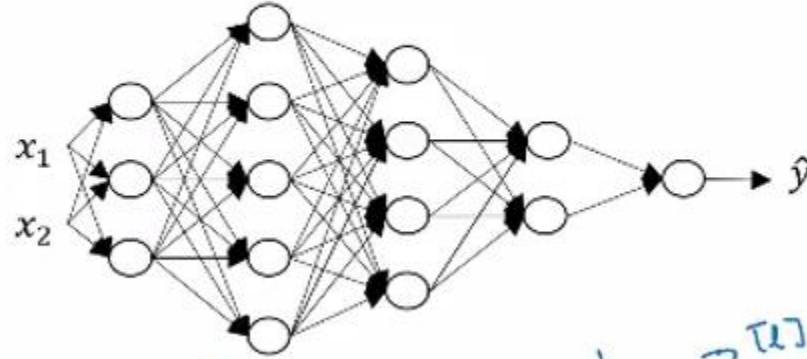
$W^{[2]}: (5, 3) \quad (n^{[2]}, n^{[1]})$

$z^{[2]} = W^{[2]} \cdot a^{[1]} + b^{[2]}$   
 $\uparrow \quad \uparrow \quad \uparrow$   
 $\rightarrow (5,1) \quad (5,3) \quad (3,1) \quad (5,1)$   
 $(n^{[2]},1)$

$W^{[3]}: (4, 5)$

$W^{[4]}: (2, 4), \quad W^{[5]}: (1, 2)$

# Vectorized implementation



$$z^{[1]} = W^{[0]} \cdot x + b^{[1]}$$

$(n^{[0]}, 1)$   $(n^{[0]}, n^{[0]})$   $(n^{[0]}, 1)$   $(n^{[1]}, 1)$

$[z^{[0]}, z^{[1]}, \dots, z^{[L-1]}]$

$$Z^{[1]} = W^{[0]} \cdot X + b^{[1]}$$

$(n^{[0]}, m)$   $(n^{[0]}, n^{[0]})$   $(n^{[0]}, m)$   $(n^{[1]}, 1)$   $(n^{[1]}, m)$

$$z^{[1]}, a^{[1]} : (n^{[1]}, 1)$$

$$z^{[2]}, A^{[2]} : (n^{[2]}, m)$$

$$l=0 \quad A^{[0]} = X = (n^{[0]}, m)$$

$$dz^{[1]}, dA^{[1]} : (n^{[1]}, m)$$





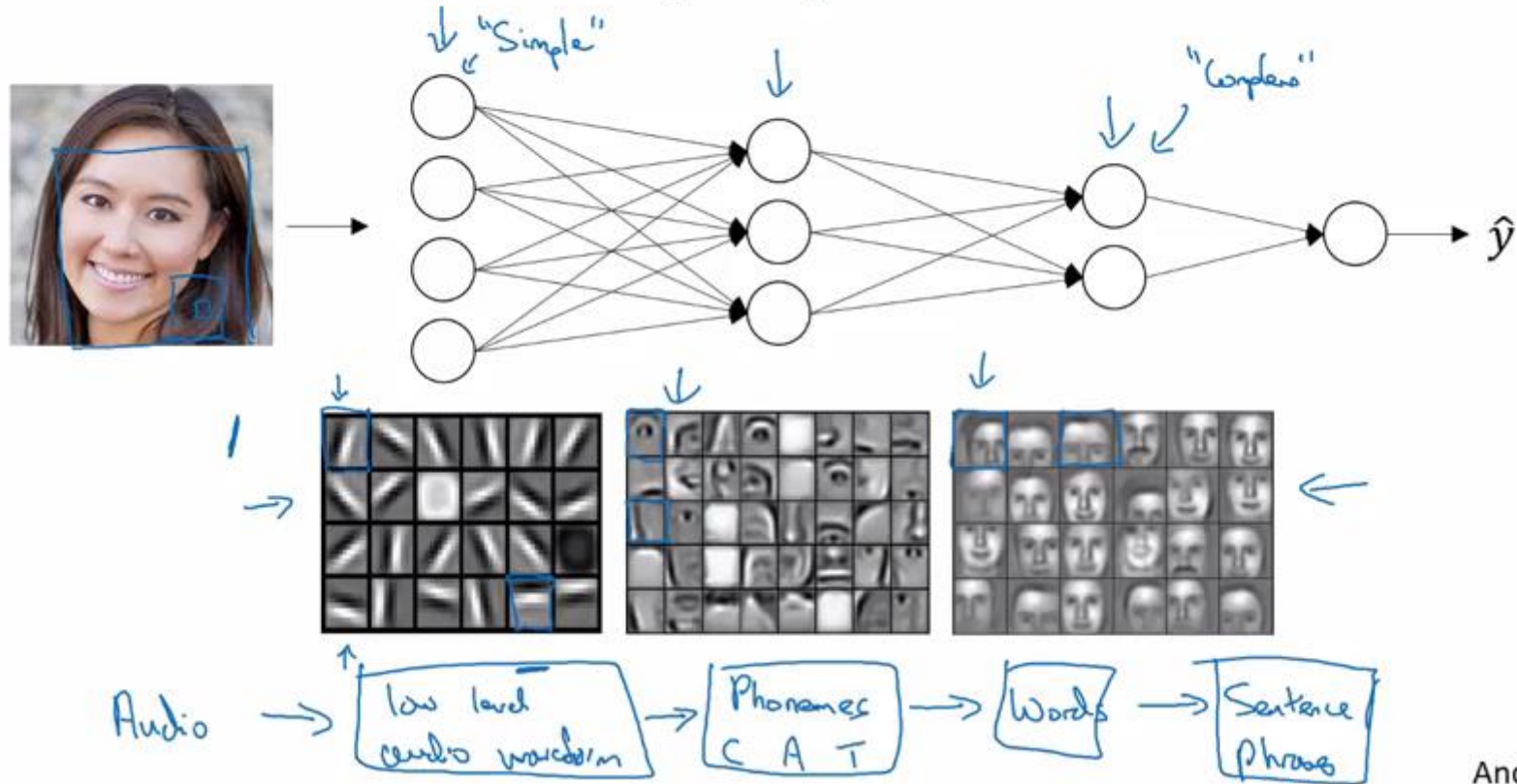
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# Deep Neural Networks

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## Why deep representations?

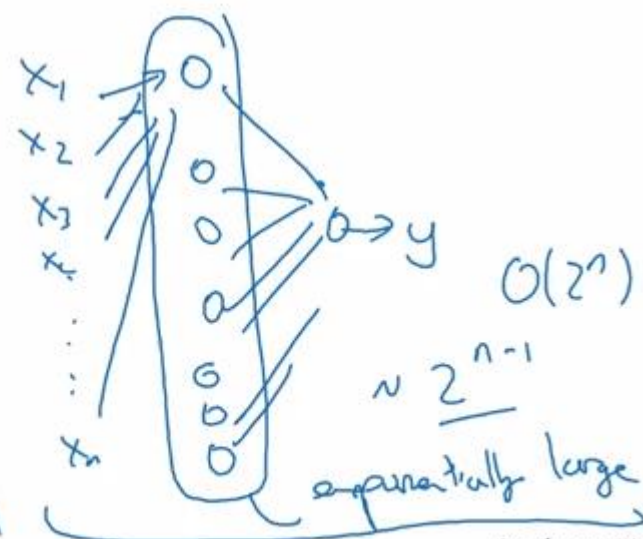
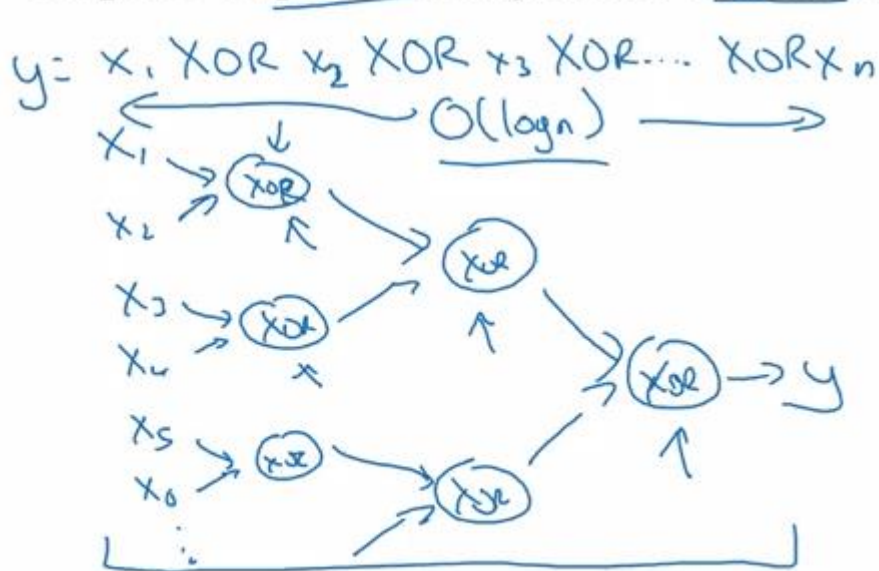
# Intuition about deep representation



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# Circuit theory and deep learning

Informally: There are functions you can compute with a “small” L-layer deep neural network that shallower networks require exponentially more hidden units to compute.



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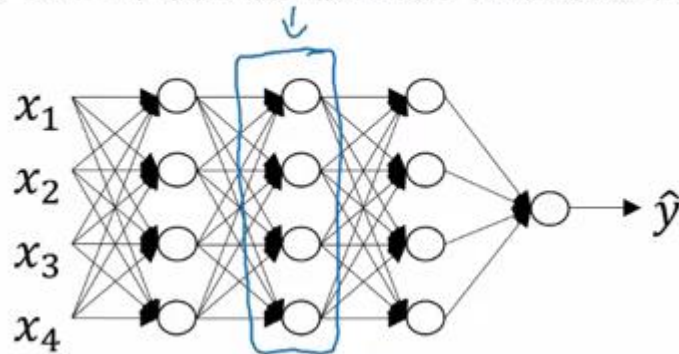
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# Deep Neural Networks

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Building blocks of  
deep neural networks

# Forward and backward functions



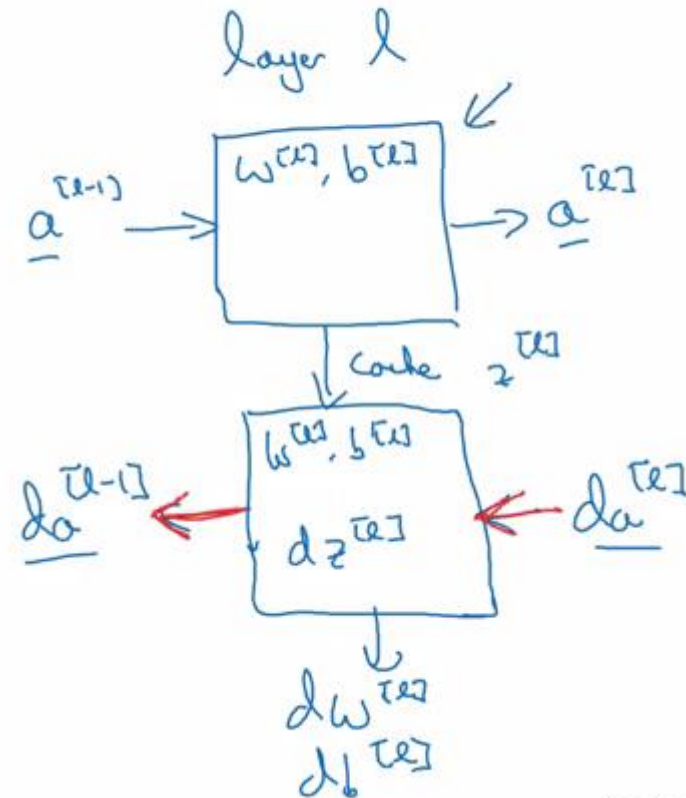
layer  $l$ :  $W^{[l]}, b^{[l]}$

→ Forward: Input  $a^{[l-1]}$ , output  $a^{[l]}$

$$z^{[l]} = W^{[l]} a^{[l-1]} + b^{[l]} \quad \text{cache } z^{[l]}$$

$$a^{[l]} = g^{[l]}(z^{[l]})$$

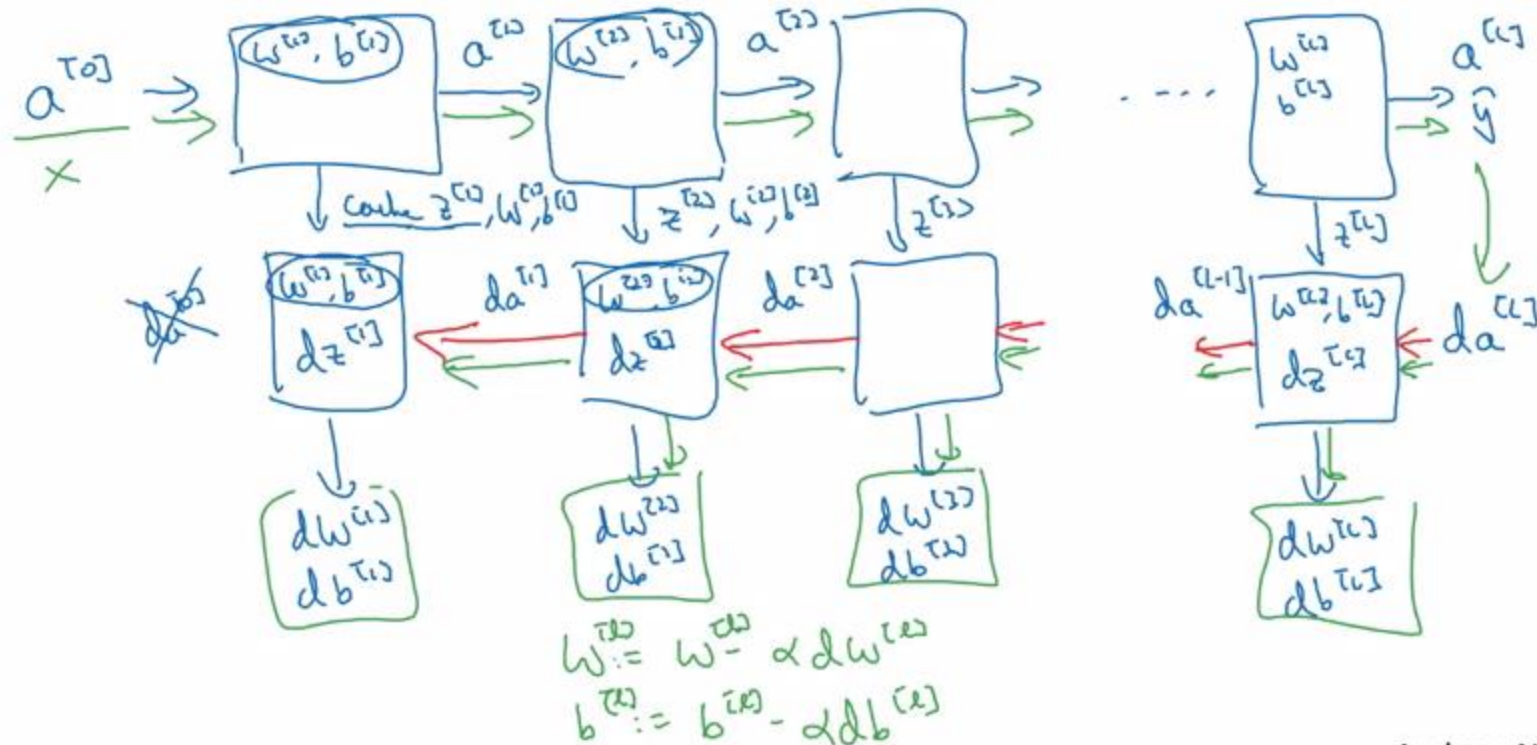
→ Backward: Input  $da^{[l]}$ , output  $da^{[l-1]}$   
cache  $(z^{[l]})$   
 $\frac{da^{[l-1]}}{dz^{[l]}}$   
 $\frac{dw^{[l]}}{dz^{[l]}}$   
 $\frac{db^{[l]}}{dz^{[l]}}$



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# Forward and backward functions





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# Deep Neural Networks


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Forward and backward  
propagation

# Forward propagation for layer $l$

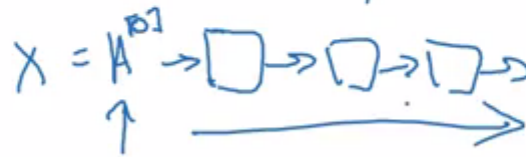
→ Input  $a^{[l-1]} \leftarrow$

 → Output  $a^{[l]}$ , cache ( $z^{[l]}$ )

  $z^{[l]} = W^{[l]} \cdot a^{[l-1]} + b^{[l]}$

$$a^{[l]} = g^{[l]}(z^{[l]})$$

$$\begin{matrix} a^{[0]} \\ A^{[0]} \end{matrix}$$



Vertwrigl:

$$z^{[l]} = W^{[l]} \cdot A^{[l-1]} + b^{[l]}$$

$$A^{[l]} = g^{[l]}(z^{[l]})$$

# Backward propagation for layer $l$

→ Input  $da^{[l]}$

→ Output  $da^{[l-1]}$ ,  $dW^{[l]}$ ,  $db^{[l]}$

$$dz^{[l]} = da^{[l]} * g^{[l]'}(z^{[l]})$$

$$dW^{[l]} = dz^{[l]} \cdot a^{[l-1]}$$

$$db^{[l]} = dz^{[l]}$$

$$da^{[l-1]} = W^{[l]T} \cdot dz^{[l]}$$

$$dz^{[l-1]} = W^{[l-1]T} dz^{[l]} * g^{[l-1]'}(z^{[l-1]})$$

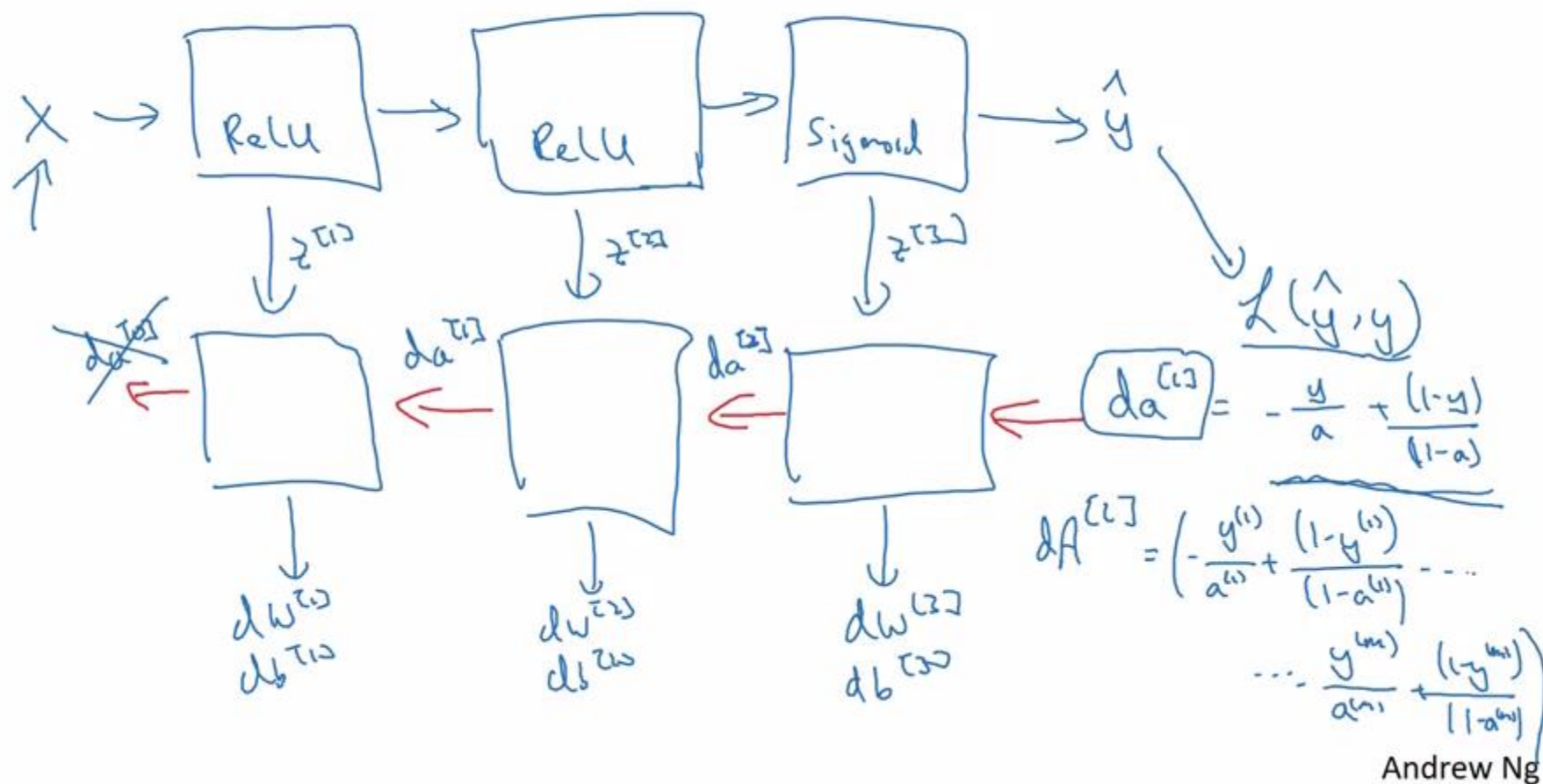
$$dz^{[l]} = dA^{[l]} * g^{[l]'}(z^{[l]})$$

$$dW^{[l]} = \frac{1}{n} dz^{[l]} \cdot A^{[l-1]T}$$

$$db^{[l]} = \frac{1}{n} \text{np.sum}(dz^{[l]}, \text{axis}=1, \text{keepdims}=\text{True})$$

$$dA^{[l-1]} = W^{[l]T} \cdot dz^{[l]}$$

# Summary








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# Deep Neural Networks

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## Parameters vs Hyperparameters

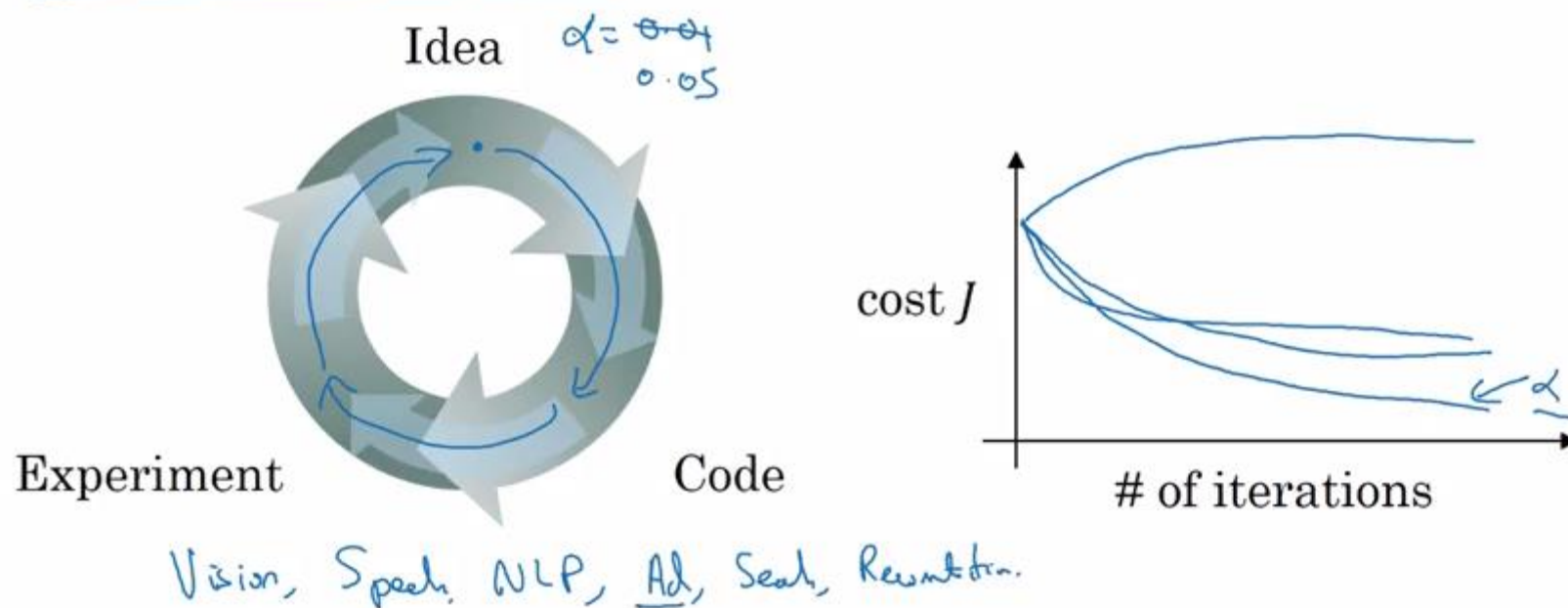
# What are hyperparameters?

 Parameters:  $W^{[1]}, b^{[1]}, W^{[2]}, b^{[2]}, W^{[3]}, b^{[3]} \dots$

Hyperparameters:   $\left. \begin{array}{l} \text{learning rate } \alpha \\ \text{\#iterations} \\ \text{\#hidden layers } L \\ \text{\#hidden units } n^{[1]}, n^{[2]}, \dots \\ \text{choice of activation function} \end{array} \right\}$

Later: Momentum, mini-batch size, regularizations, ...

# Applied deep learning is a very empirical process





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# Deep Neural Networks

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What does this  
have to do with  
the brain?

# Forward and backward propagation



$$\begin{aligned} Z^{[1]} &= W^{[1]}X + b^{[1]} \\ A^{[1]} &= g^{[1]}(Z^{[1]}) \\ Z^{[2]} &= W^{[2]}A^{[1]} + b^{[2]} \\ A^{[2]} &= g^{[2]}(Z^{[2]}) \\ &\vdots \\ A^{[L]} &= g^{[L]}(Z^{[L]}) = \hat{Y} \end{aligned}$$

"It's like the brain."



$$\begin{aligned} dZ^{[L]} &= A^{[L]} - Y \\ dW^{[L]} &= \frac{1}{m} dZ^{[L]} A^{[L]T} \\ db^{[L]} &= \frac{1}{m} np.sum(dZ^{[L]}, axis = 1, keepdims = True) \\ dZ^{[L-1]} &= dW^{[L]T} dZ^{[L]} g'^{[L]}(Z^{[L-1]}) \\ &\vdots \\ dZ^{[1]} &= dW^{[L]T} dZ^{[2]} g'^{[1]}(Z^{[1]}) \\ dW^{[1]} &= \frac{1}{m} dZ^{[1]} A^{[1]T} \\ db^{[1]} &= \frac{1}{m} np.sum(dZ^{[1]}, axis = 1, keepdims = True) \end{aligned}$$

