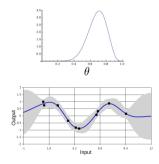
#### **Basics of Parameter Estimation in Probabilistic Models**

Piyush Rai

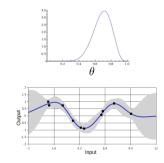
Probabilistic Machine Learning (CS772A)

Aug 3, 2017

 $\bullet$  Gives a principle way to model the  $\underline{uncertainty}$  in data, parameters, and in future predictions

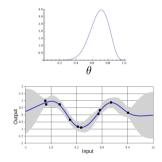


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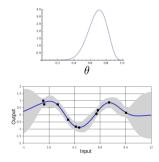
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- Can construct complex models in "modular" fashion by combining simpler probabilistic models
- Probabilistic modeling gives us a "language" to do such things naturally

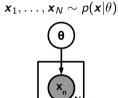


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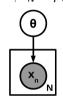


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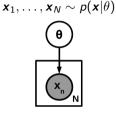
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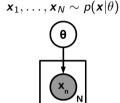
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- Goal: To estimate the unknowns of the model ( $\theta$  in this case), given the observed data **X** (and use these estimates to make predictions about future data)

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- Note: It's easy if the likelihood and prior are "conjugate" to each other (we will see it later)

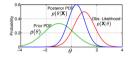
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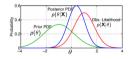
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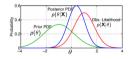


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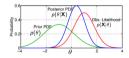
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• .. and some other methods such as "method of moments"



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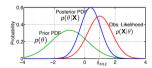
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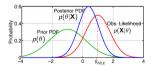


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• Note: MLE is "consistent", i.e., as  $N \longrightarrow \infty$ ,  $\hat{\theta}$  converges to the true  $\theta$  (will see it later)

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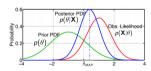
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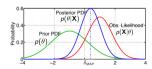


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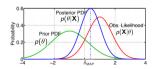
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- Despite using the prior, MAP is NOT considered a Bayesian approach (still gives a point estimate)

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# Point Estimation (MLE/MAP) vs Loss Function Minimization

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- Thus MLE is like empirical loss/risk minization (ERM) and MAP is like regularized ERM



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- MLE doesn't have a way to express our prior belief about  $\theta$ . Can be problematic especially when the number of observations is very small (e.g., suppose very few or zero heads when N is small).



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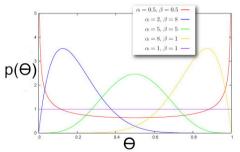
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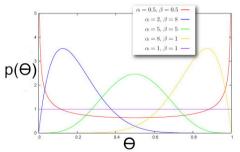
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• Note that each likelihood term is still a Bernoulli:  $p(\mathbf{x}_n|\theta) = \theta^{\mathbf{x}_n}(1-\theta)^{1-\mathbf{x}_n}$ 

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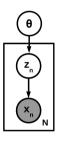
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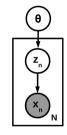
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• Becomes harder if there are latent variables in the model

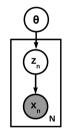


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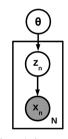
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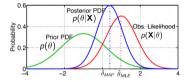
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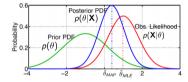


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- More on this when we will look at latent variable models

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- MAP does incorporate prior knowledge but still only gives a point estimate

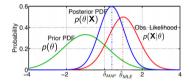


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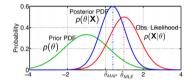
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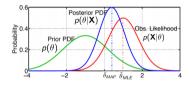
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- In other cases, it can be approximated via **approximate Bayesian inference** methods such as MCMC and variational inference (more on this later during the semester)

- Recall that each likelihood term was Bernoulli:  $p(\mathbf{x}_n|\theta) = \theta^{\mathbf{x}_n}(1-\theta)^{1-\mathbf{x}_n}$
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- Here, the posterior has the same form as the prior (both Beta): property of conjugate priors.

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- Many pairs of distributions are conjugate to each other. E.g.,
  - Bernoulli (likelihood) + Beta (prior) ⇒ Beta posterior
  - Binomial (likelihood) + Beta (prior)  $\Rightarrow$  Beta posterior
  - ullet Multinomial (likelihood) + Dirichlet (prior)  $\Rightarrow$  Dirichlet posterior
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  - E.g., recall the forms of Bernoulli and Beta

Bernoulli 
$$\propto \theta^{x} (1-\theta)^{1-x}$$
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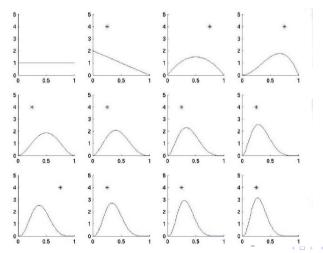
$$\mathsf{Bernoulli} \propto \theta^{\mathsf{x}} (1-\theta)^{1-\mathsf{x}}, \quad \mathsf{Beta} \propto \theta^{\alpha-1} (1-\theta)^{\beta-1}$$

More on conjugate priors when we will look at exponental family distributions



### Posterior Evolution with Observed Data

• Assume starting with a uniform prior (equivalent to Beta(1,1)) in the coin-toss example and observing a sequence of heads and tails



- The posterior distribution for the coin-toss example  $p(\theta|\mathbf{X}) = \text{Beta}(\theta|\alpha + N_1, \beta + N_0)$  where
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- Note: Doing MAP  $(\theta_{MAP} = \arg \max_{\theta} P(\theta | \mathbf{X}))$  and MLE  $(\theta_{MLE} = \arg \max_{\theta} P(\mathbf{X} | \theta))$  directly will also give us the same answers as above. But we won't get the full posterior in these cases.



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- Note that the predictive distribution doesn't depend on a single value of  $\theta$  ( $\theta_{MLE}$  or  $\theta_{MAP}$ )