

Nonparametric Bayesian Models for Unsupervised Learning

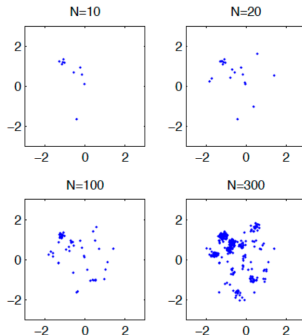
Piyush Rai

Probabilistic Machine Learning (CS772A)

Nov 4, 2017

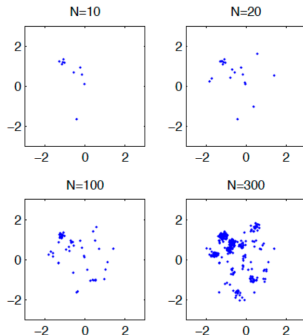
Nonparametric Bayesian Models: Motivation

- Often more/newer structures may appear as we observe more and more data



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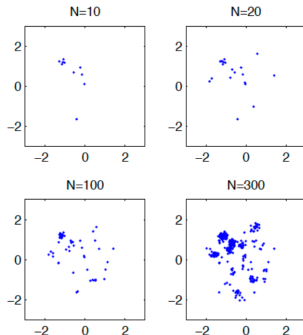
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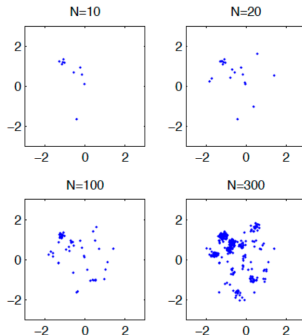
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- Would like to have models that don't assume a fixed-sized structure in advance, e.g.,
 - Would like to have a mixture model s.t. number of clusters can grow/adapt with data
 - Would like to have a neural net which can grow/adapt in size (number/width of layers) with data

Nonparametric Bayesian Models for Clustering

Finite Mixture Model

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- Integrating out $\boldsymbol{\pi}$, the marginal prior probability of cluster assignments \mathbf{Z}

$$p(\mathbf{Z}|\alpha) = \int p(\mathbf{Z}|\boldsymbol{\pi})p(\boldsymbol{\pi}|\alpha)d\boldsymbol{\pi}$$

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- Since \mathbf{z}_n 's are i.i.d. given $\boldsymbol{\pi}$, we have

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$$p(\mathbf{Z}|\alpha) = \frac{1}{B(\frac{\alpha}{K}, \frac{\alpha}{K}, \dots, \frac{\alpha}{K})} \int \prod_{k=1}^K \pi_k^{m_k + \frac{\alpha}{K} - 1} d\boldsymbol{\pi}$$

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where $m_k = \sum_{n=1}^N z_{nk}$, $B(\alpha_1, \alpha_2, \dots, \alpha_K) = \frac{\prod_{k=1}^K \Gamma(\alpha_k)}{\Gamma(\sum_{k=1}^K \alpha_k)}$, Γ is gamma func. ($\Gamma(x+1) = x\Gamma(x)$)

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- Using the above, the $p(\mathbf{Z}|\alpha) = p(\mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_N|\alpha)$ can be written as

$$p(\mathbf{Z}|\alpha) = \frac{\Gamma(\alpha)}{\Gamma(N + \alpha)} \frac{\prod_{k=1}^K \Gamma(m_k + \frac{\alpha}{K})}{\Gamma(\frac{\alpha}{K})^K} \quad (\text{verify})$$

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- Thus **prior prob. of $\mathbf{z}_n = j$ is prop. to $m_{-n,j}$** , i.e., number of other examples assigned to cluster j (this is like a “rich gets richer” phenomenon; a popular cluster will attract more examples)

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- Note: We can also derive the above result as

$$p(\mathbf{z}_n = j | \mathbf{Z}_{-n}, \alpha) = \int p(\mathbf{z}_n | \pi) p(\pi | \mathbf{Z}_{-n}, \alpha) d\pi \quad (\text{complete the exercise!})$$

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- Therefore in the limit of an unbounded number of clusters, we have

$$p(\mathbf{z}_n = j | \mathbf{Z}_{-n}, \alpha) = \begin{cases} \frac{m_{-n,j}}{N-1+\alpha} & (\text{prob. of going to } j = 1, \dots, K_+) \\ \frac{\alpha}{N-1+\alpha} & (\text{prob. of creating a new cluster } K_+ + 1) \end{cases}$$

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- Note that the probability of starting a new cluster is proportional to Dirichlet hyperparam. α

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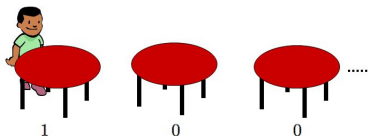
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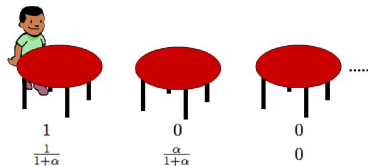
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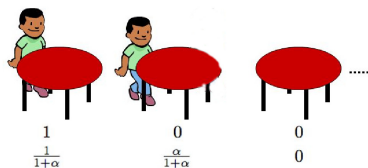
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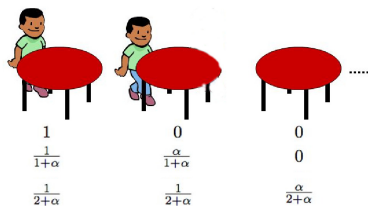
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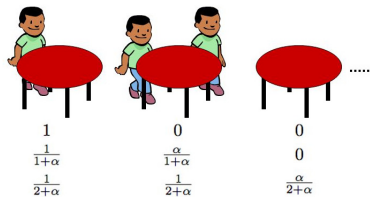
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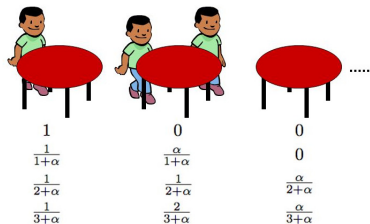
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- Also possible to do collapsed Gibbs sampling by integrating out $\{\mu_j, \Sigma_j\}_{j=1}^{K_+}$ (Neal, 2000)

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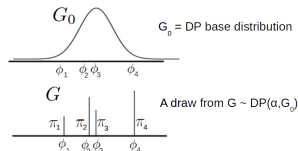
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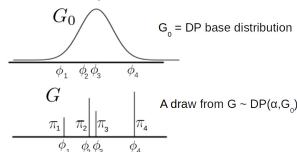
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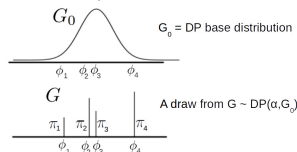
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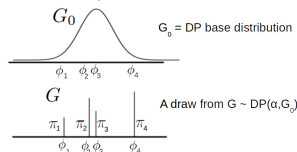
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May refer to "Dirichlet Process" by Teh (2010) for some of these connections

Nonparametric Bayesian Models for Latent Feature Learning

Learning Binary Latent Features

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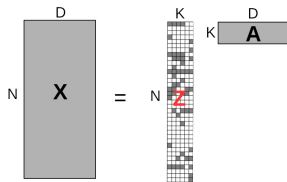
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- Note that $\mathbf{X} \approx \mathbf{Z}\mathbf{A}$ with \mathbf{Z} being $N \times K$ (binary), and \mathbf{A} being $K \times D$. Also, K usually unknown

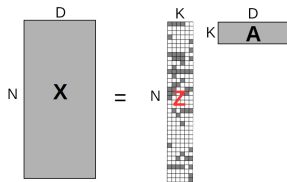


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- Suppose we have N observations $\mathbf{x}_1, \dots, \mathbf{x}_N$ and each \mathbf{x}_n can be written as

$$\mathbf{x}_n = \sum_{k=1}^K z_{nk} \mathbf{a}_k + \epsilon_n$$

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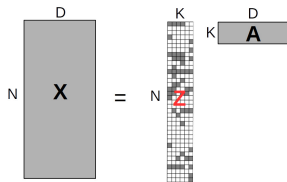
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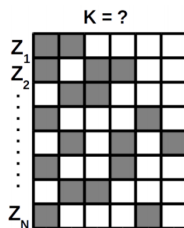
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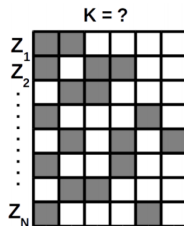
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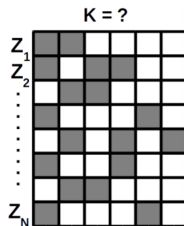
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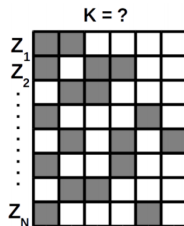
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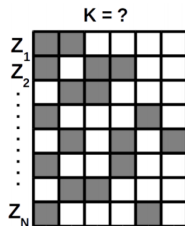
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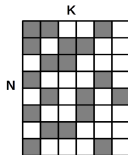
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Modeling Binary Matrices with Finite Many Columns

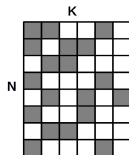
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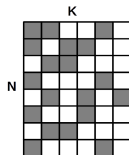


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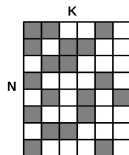
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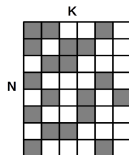
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where $m_{-n,k} = \sum_{i \neq n} z_{ik}$ denotes how many other entries in column k are equal to 1

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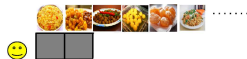
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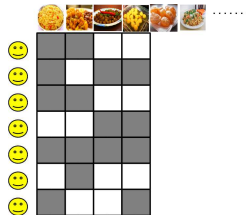
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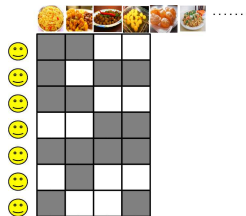
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- The above can be used as a prior for \mathbf{Z} . Refer to (Griffiths and Ghahramani, 2011) for examples and other theoretical details of the model. Also has connections to [Beta Processes](#)



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