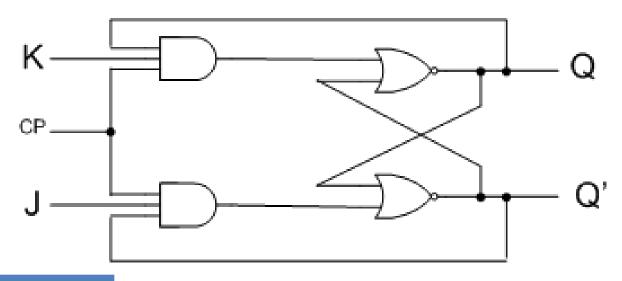
# JK Flip-flop

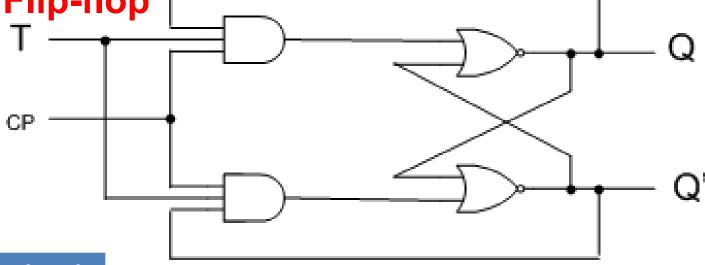


Q	J	K	Q(t+1)
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	1
1	0	0	1
1	0	1	0
1	1	0	1
1	1	1	0

$$Q(t+1) = J\overline{Q}(t) + \overline{K}Q(t)$$

JK flip flop is refinement of RS flip flop where indeterminate state of RS flip flop is defined in JK Flip Flop.





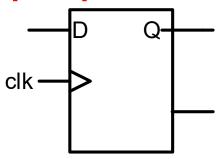
Q	Т	Q(t+1)
0	0	0
0	1	1
1	0	1
1	1	0

$$Q(t+1) = T \oplus Q(t)$$

### Characteristic table

Given a input and the present state of the flip-flop, what is the next state of the flip-flop

### D Flip-flop

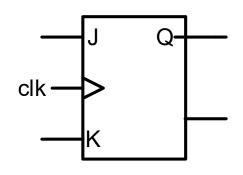


Inputs (D)	Q(t+1)
0	0
1	1

Characteristic equation: Q(t+1) = D

$$Q(t+1) = D$$

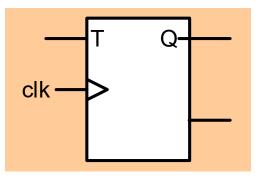
### JK Flip-flop



Inputs J	K	Q(t+1)
0	0	Q(t)
0	1	0
1	0	1
1	1	Q(t)

Characteristic equation: 
$$Q(t+1) = J\overline{Q}(t) + \overline{K}Q(t)$$

## Toggle or T Flip-flop



Inputs (T)	Q(t+1)
0	Q(t)
1	Q(t)

**Characteristic equation:** 

$$Q(t+1) = T \oplus Q(t)$$

## **Excitation Table**

What inputs are required to effect a particular state change

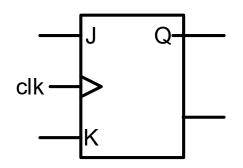
Q	Т	Q(t+1)
0	0	0
0	1	1
1	0	1
1	1	0

<b>Excitation</b>	Table
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Inputs

Q(t)	Q(t+1)	T
0	0	0
0	1	1
1	0	1
1	1	0

## **Excitation Table**



J	K	Q(t+1)
0	0	Q(t)
0	1	0
1	0	1
1	1	Q(t)

**Characteristic Table** 

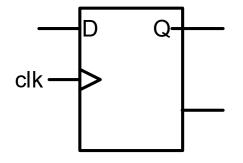
n	p	u	ts

Q(t)	Q(t+1)	J K
0	0	0 X
0	1	1 X
1	0	X 1
1	1	X 0

**Excitation Table** 

Q	J	K	Q(t+1)
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	1
1	0	0	1
1	0	1	0
1	1	0	1
1	1	1	0

## **Excitation Table**



D	Q(t+1)
0	0
1	1

**Characteristic Table** 

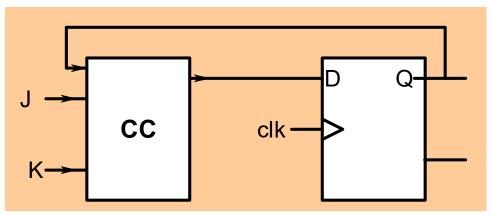
Q	D	Q(t+1)
0	0	0
0	1	1
1	0	0
1	1	1

#### Inputs

Q(t)	Q(t+1)	D
0	0	0
0	1	1
1	0	0
1	1	1

**Excitation Table** 

## **Convert a D FF to JK FF**



J	K	Q	Q(t+1)	D
0	X	0	0	0
1	X	0	1	1
X	1	1	0	0
X	0	1	1	1

Inputs

Q(t)	Q(t+1)	J K
0	0	0 X
0	1	1 X
1	0	X 1
1	1	X 0

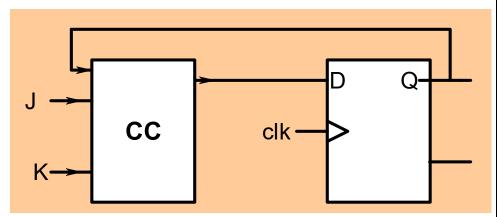
**Excitation Table** 

Inputs

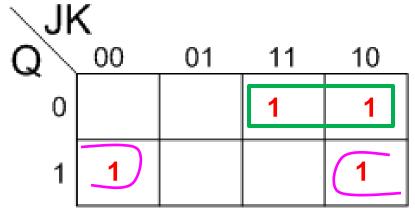
Q(t)	Q(t+1)	D
0	0	0
0	1	1
1	0	0
1	1	1

**Excitation Table** 

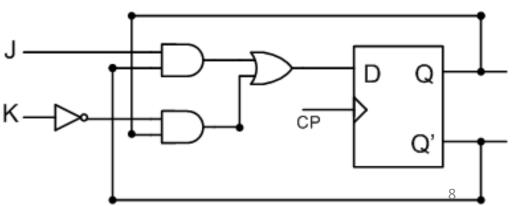
#### Convert a D FF to JK FF



J	K	Q	Q(t+1)	D
0	X	0	0	0
1	X	0	1	1
X	1	1	0	0
X	0	1	1	1

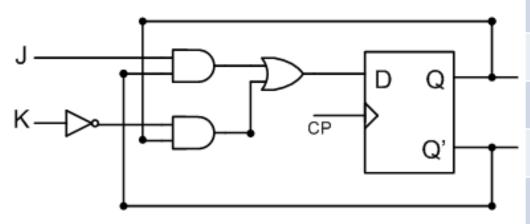


$$D = \overline{Q}.J + Q.\overline{K}$$



#### Convert a D FF to JK FF

$$D = \overline{Q}.J + Q.\overline{K}$$



Inputs J	K	Q(t+1)
0	0	Q(t)
0	1	0
1	0	1
1	1	Q(t)

Q	J	K	D	Q(t+1)
0	0	0	0	0
0	0	1	0	0
0	1	0	1	1
0	1	1	1	1
1	0	0	1	1
1	0	1	0	0
1	1	0	1	1
1	1	1	0	0