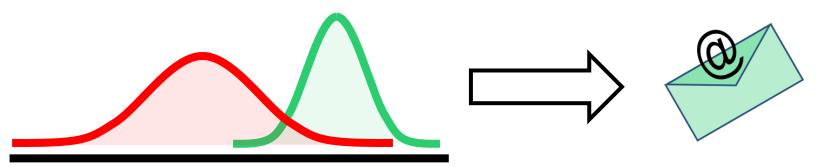
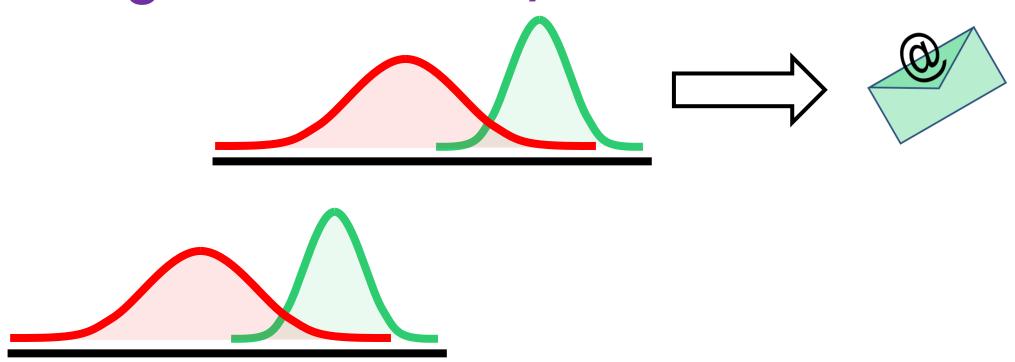
Data Modelling Methods-l

CS771: Introduction to Machine Learning
Purushottam Kar

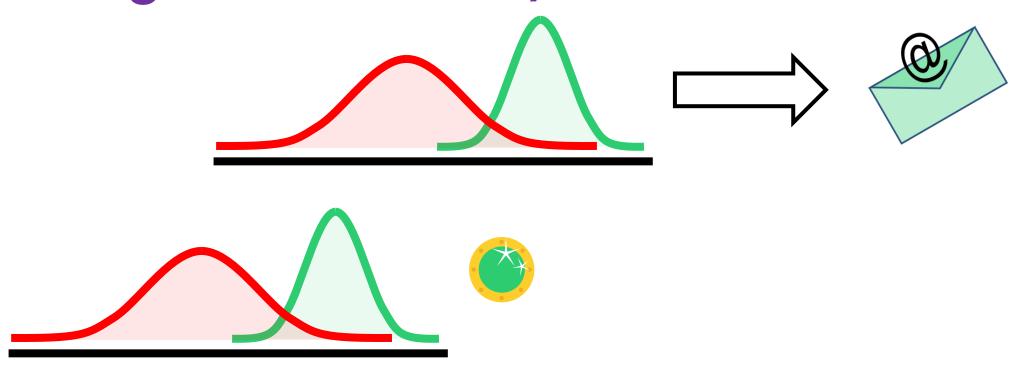




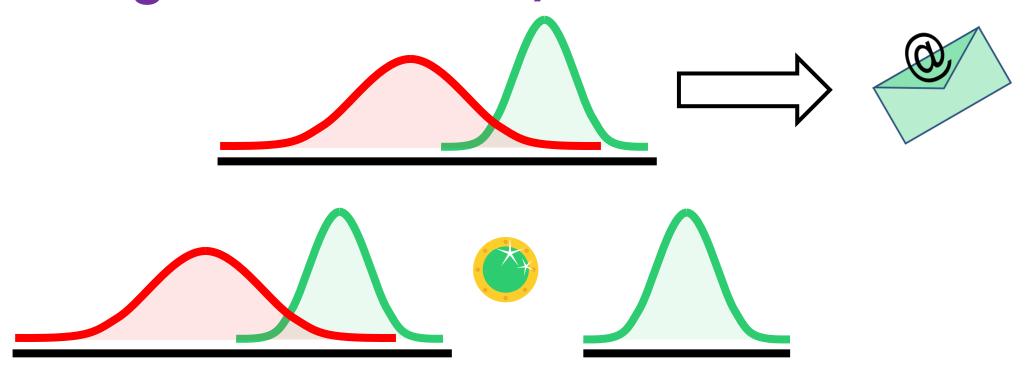




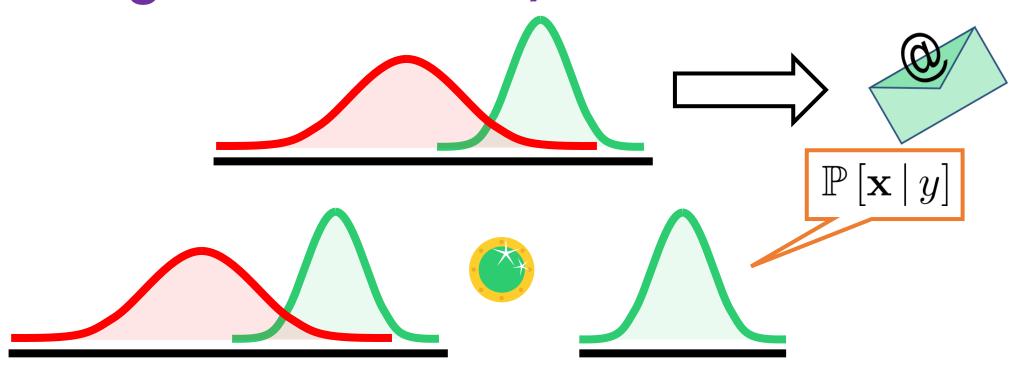




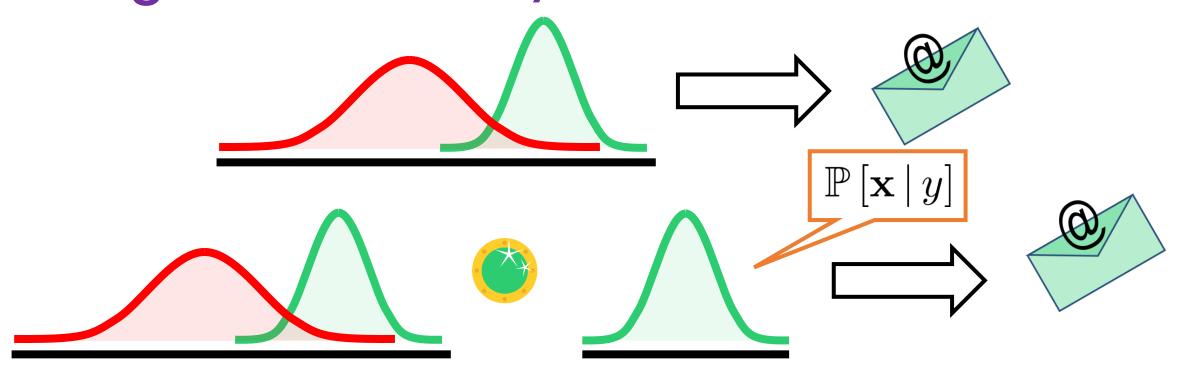




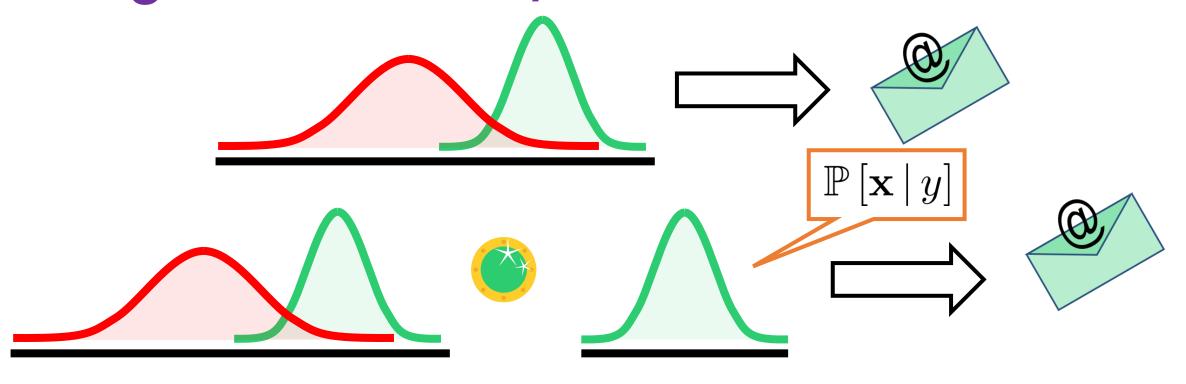


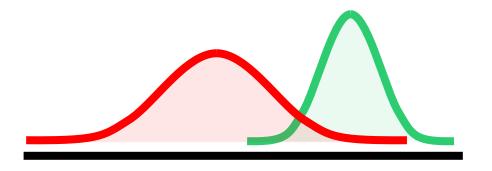




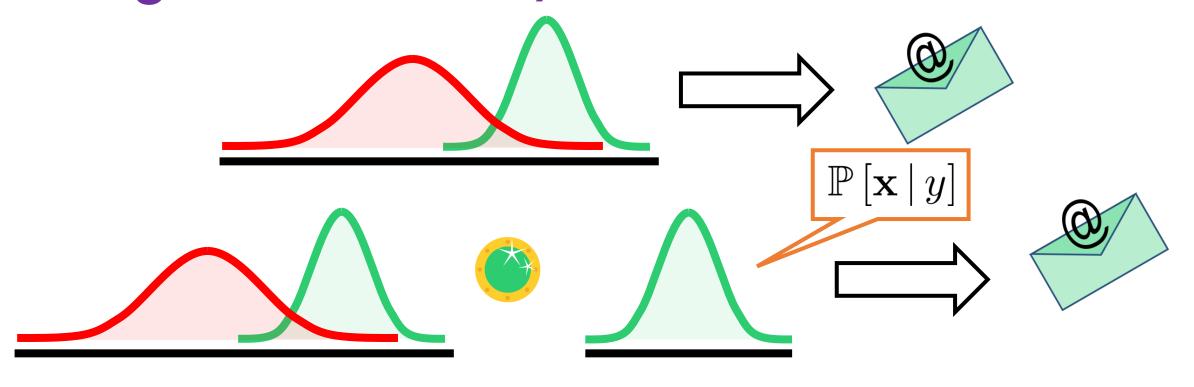


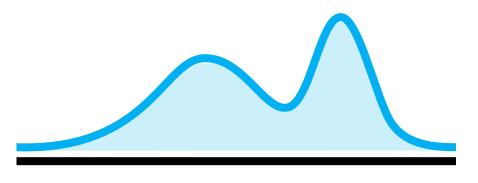




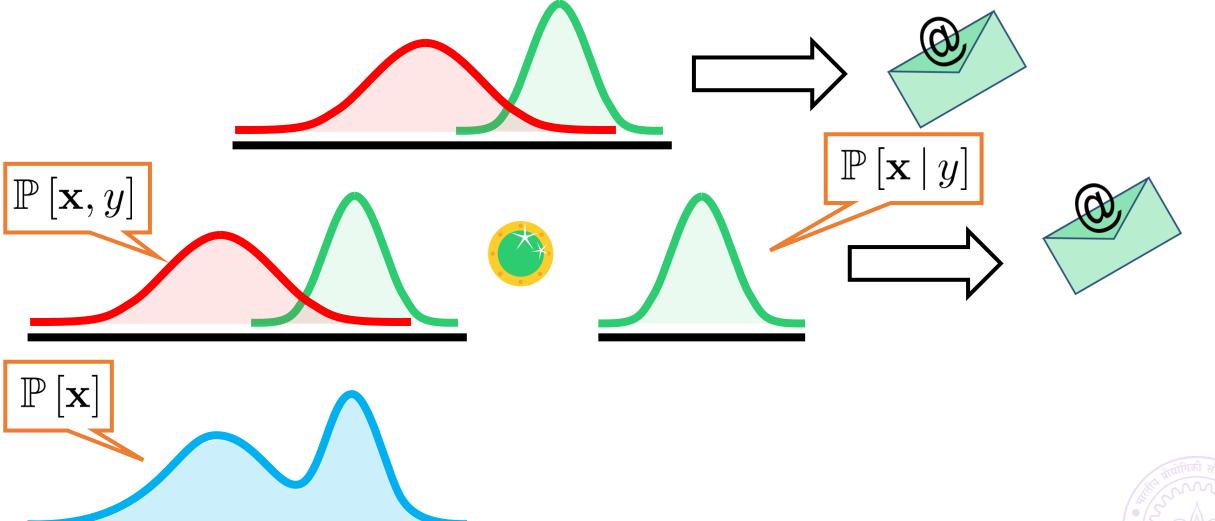




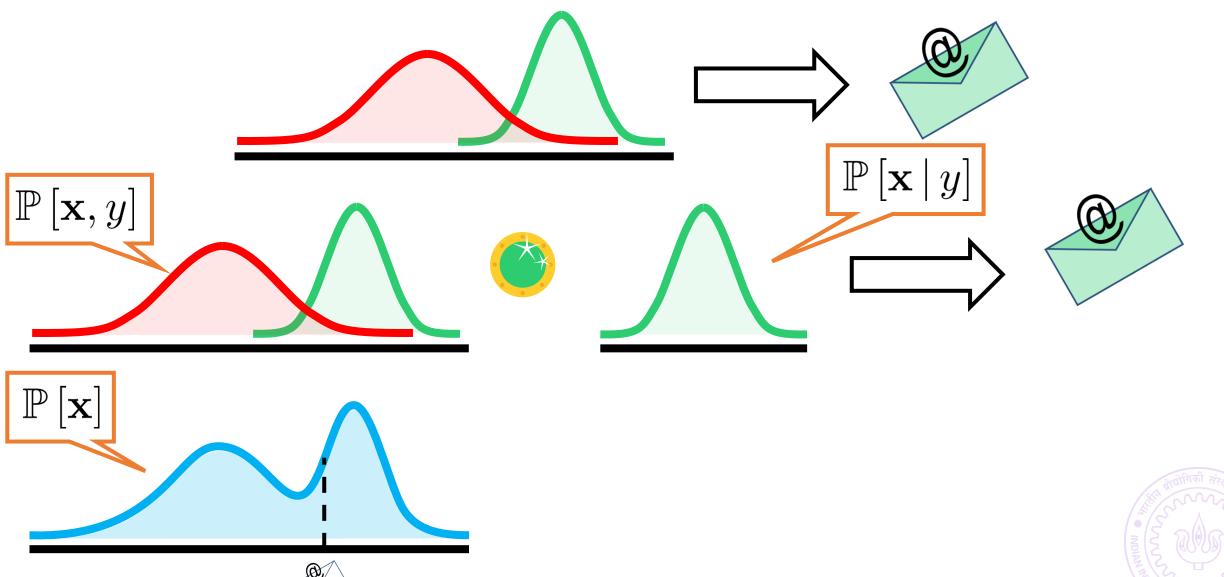




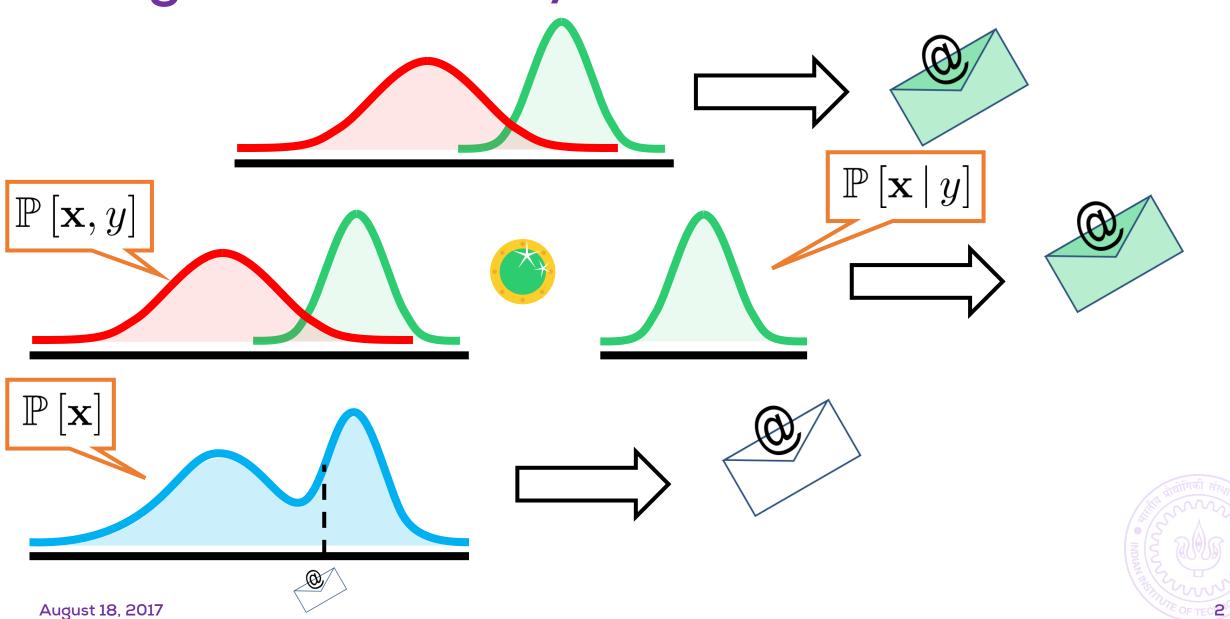


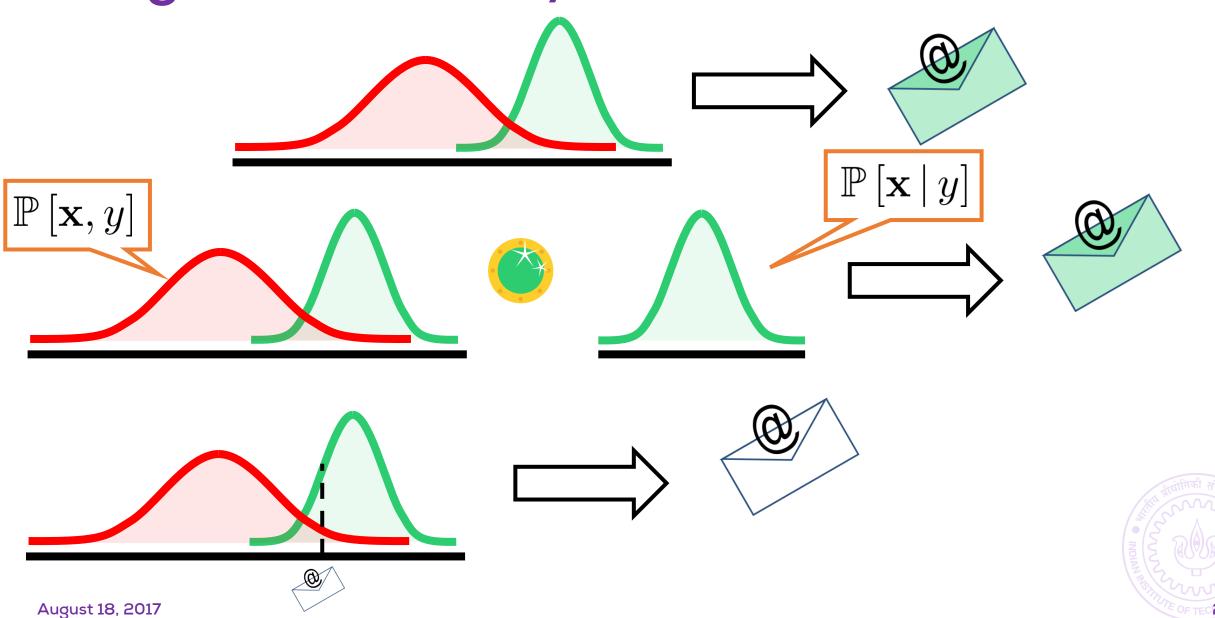


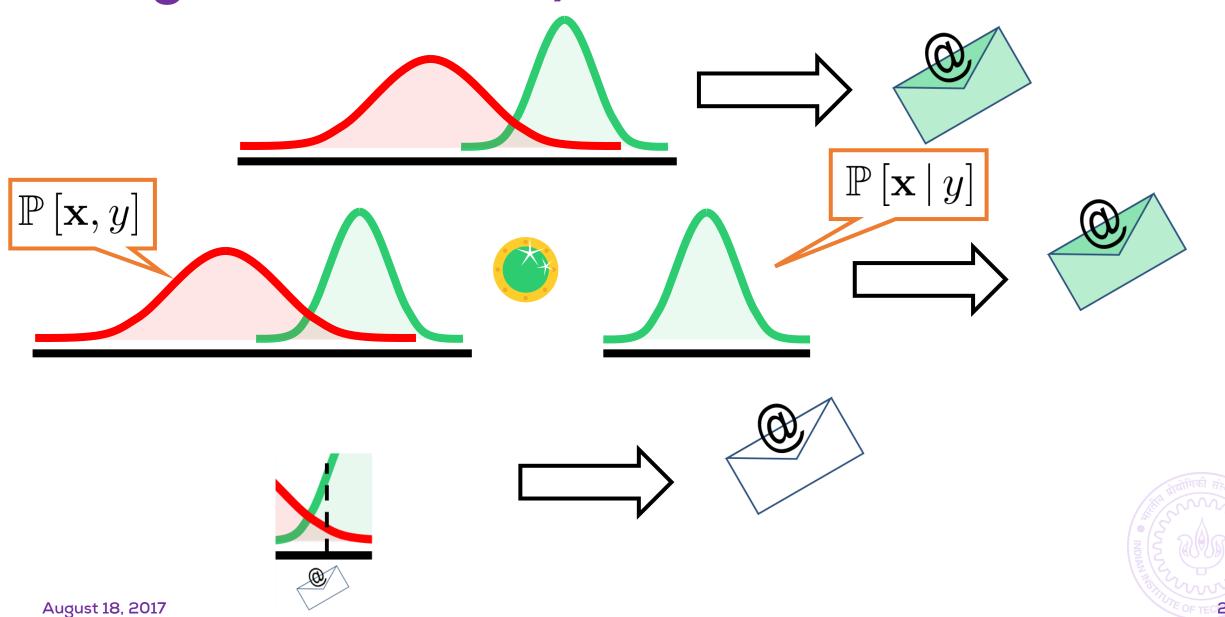
August 18, 2017



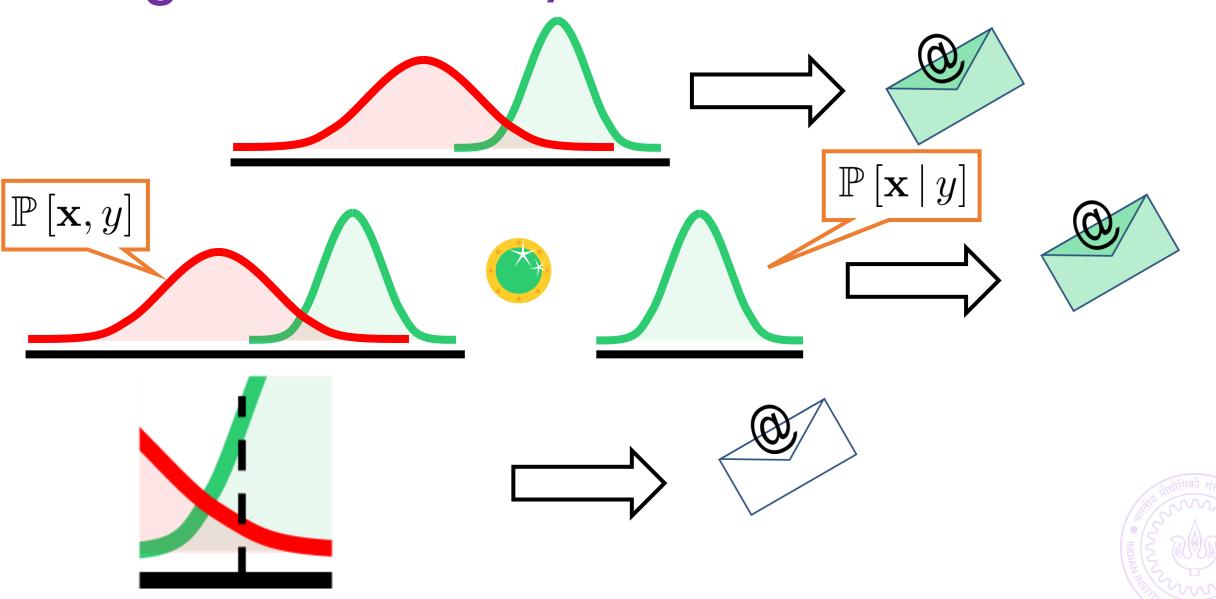


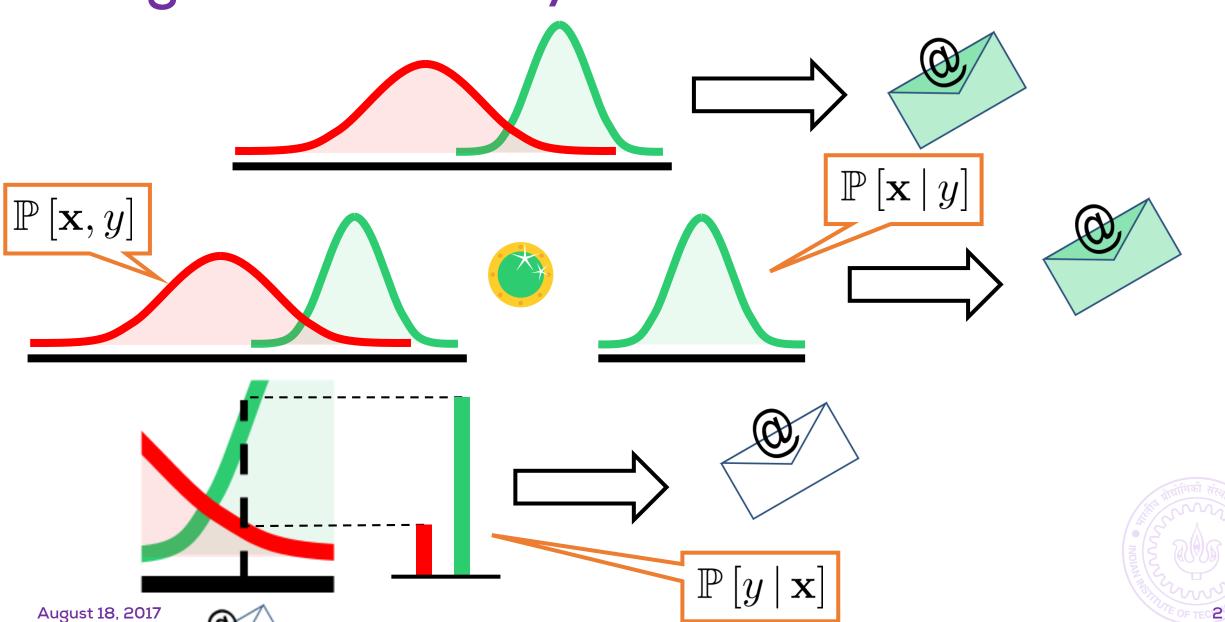


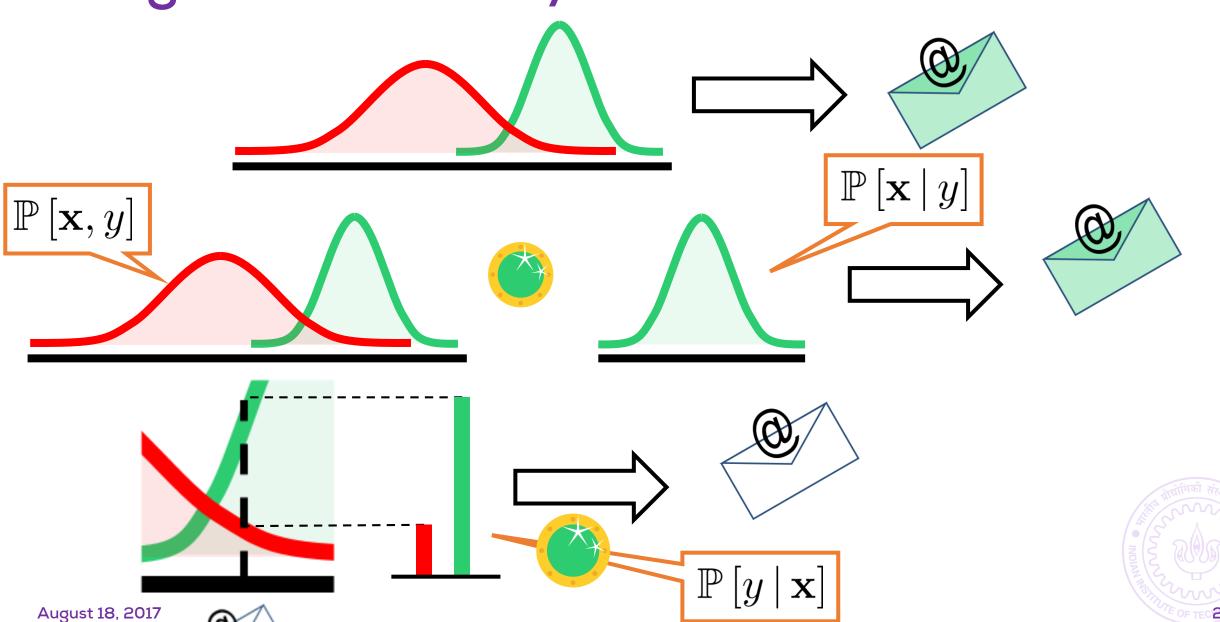


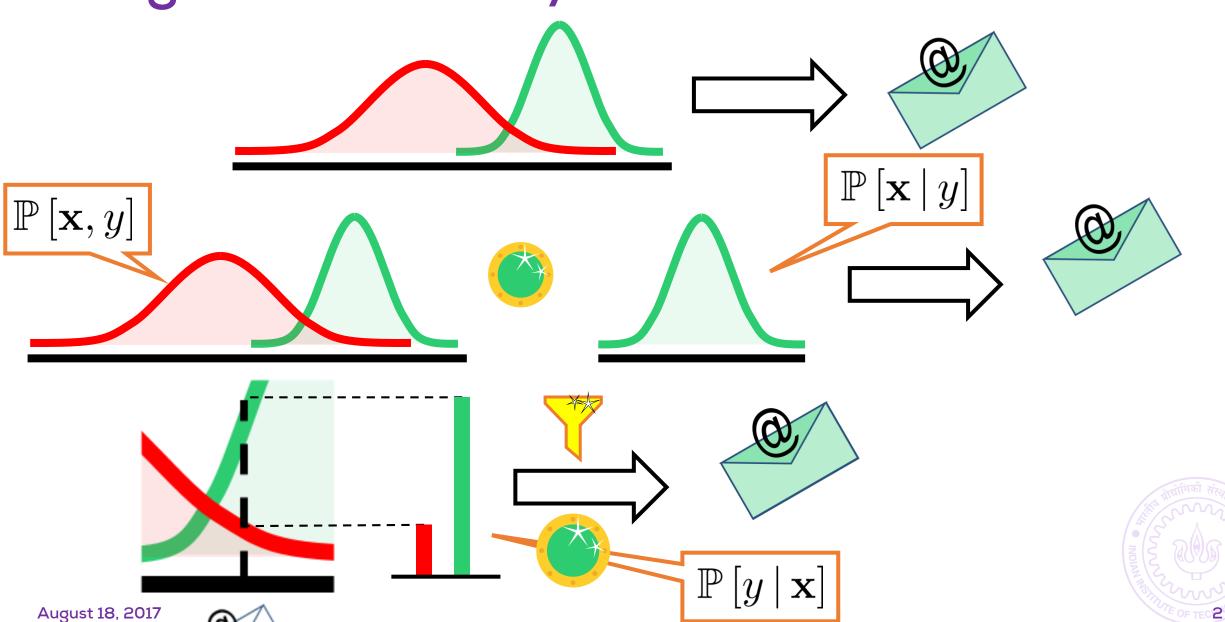


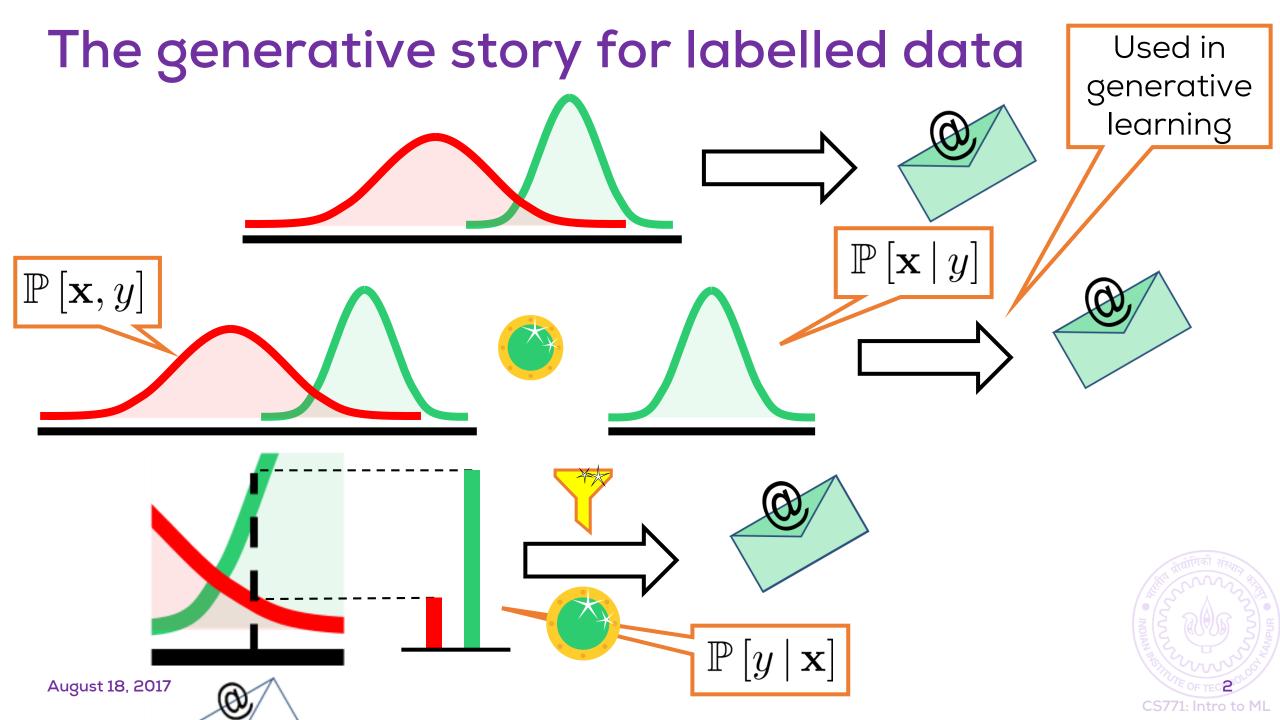
August 18, 2017

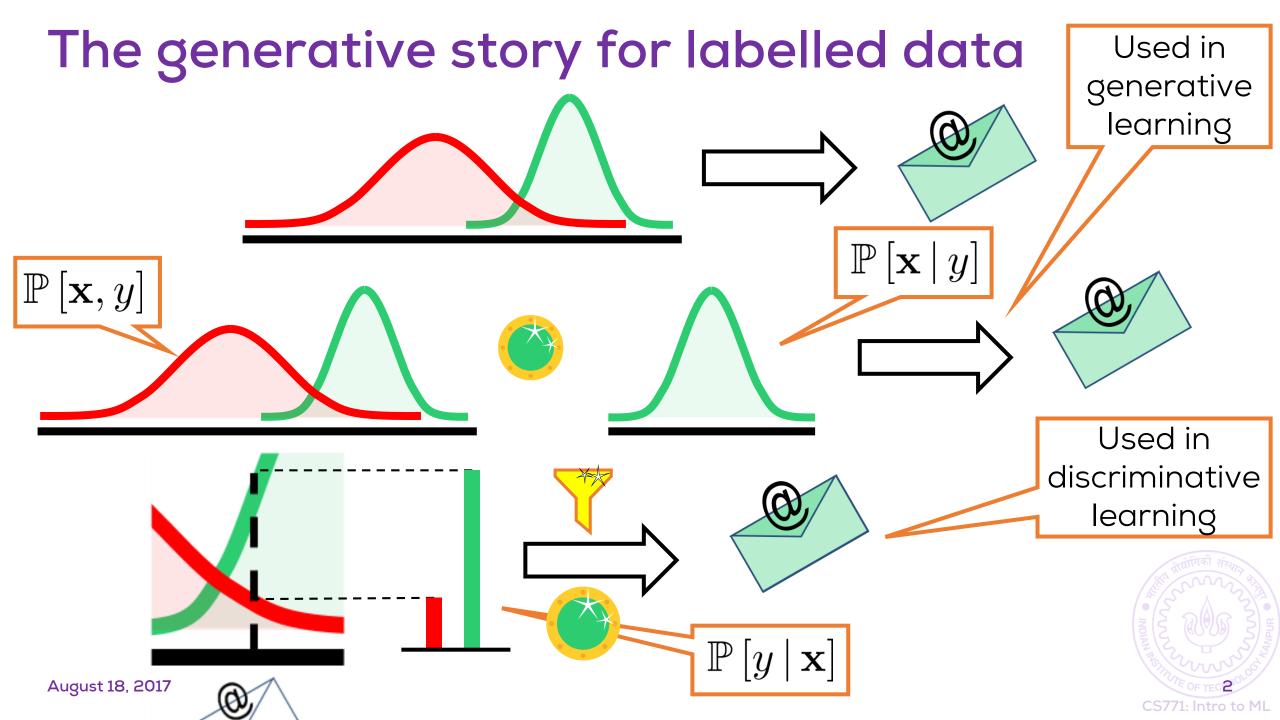


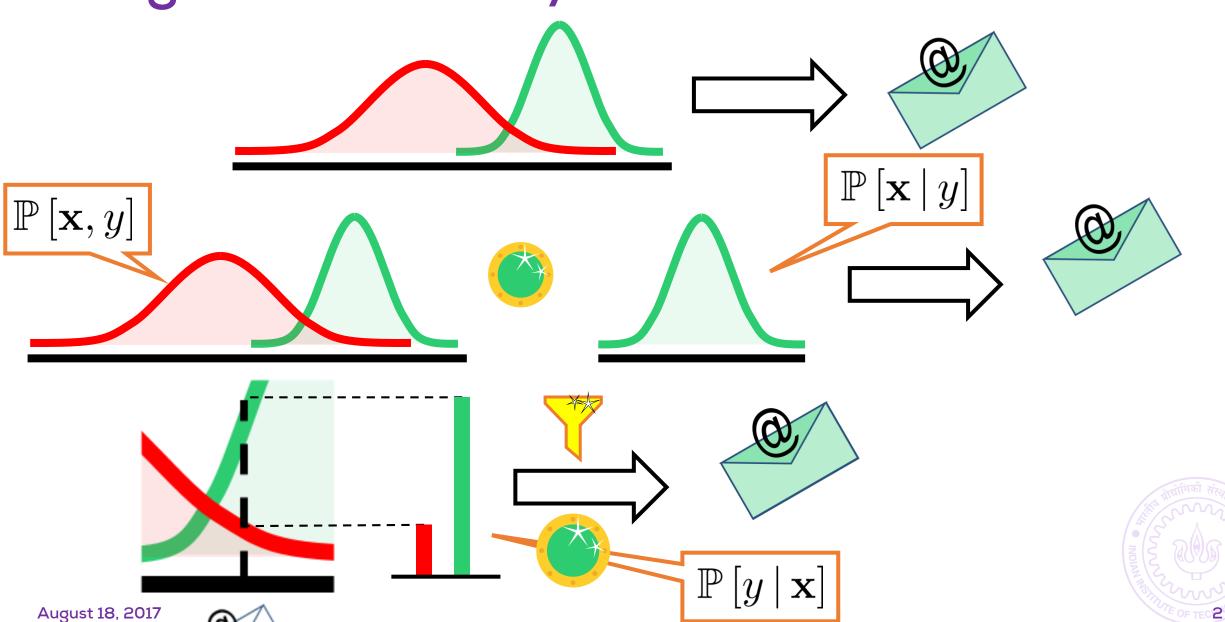






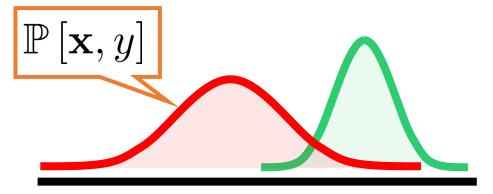




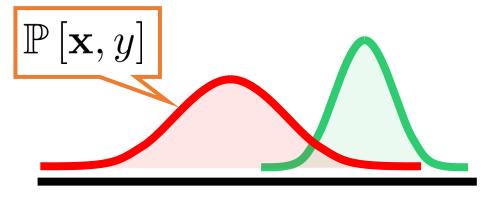


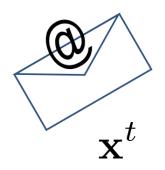
The generative story for labelled data "generative" model August 18, 2017

The generative story for labelled data "generative" model "discriminative" model August 18, 2017 CS771: Intro to ML

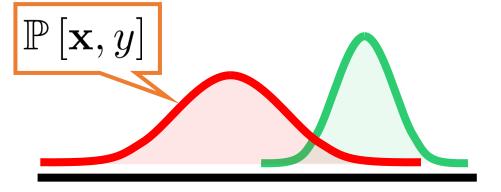


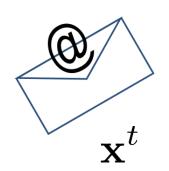






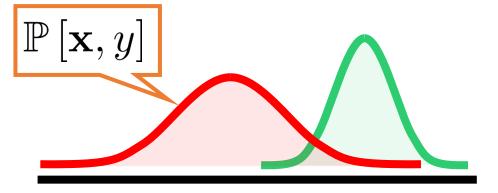


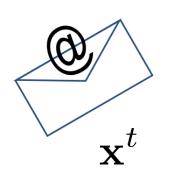




$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$



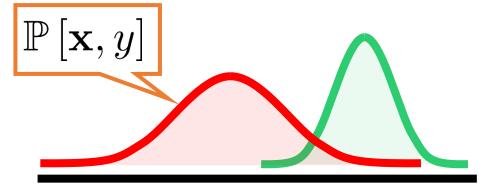


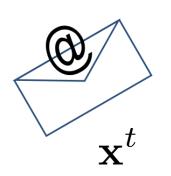


$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$

$$\mathbb{P}\left[y\,|\,\mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t,y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]} \quad \mathbb{P}\left[\bullet\,|\,\mathbf{x}^t\right] > \mathbb{P}\left[\bullet\,|\,\mathbf{x}^t\right] \quad \hat{y}^t = \bullet$$







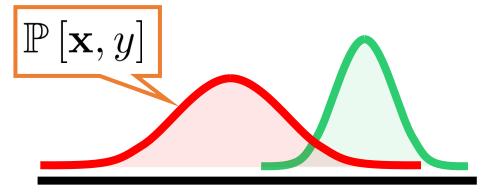
$$\mathbb{P}\left[y\,|\,\mathbf{x}^{t}\right] = \frac{\mathbb{P}\left[\mathbf{x}^{t},y\right]}{\mathbb{P}\left[\mathbf{x}^{t}\right]} \quad \mathbb{P}\left[\bullet\,|\,\mathbf{x}^{t}\right] > \mathbb{P}\left[\bullet\,|\,\mathbf{x}^{t}\right] \quad \hat{y}^{t} = \bullet$$

$$\mathbb{P}\left[\bullet\,|\,\mathbf{x}^{t}\right] > \mathbb{P}\left[\bullet\,|\,\mathbf{x}^{t}\right] \quad \hat{y}^{t} = \bullet$$

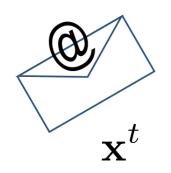
$$\mathbb{P}\left[\bullet \mid \mathbf{x}^t\right] > \mathbb{P}\left[\bullet \mid \mathbf{x}^t\right] \quad \hat{y}^t = \bullet$$

$$\mathbb{P}\left[ullet | \mathbf{x}^t
ight] > \mathbb{P}\left[ullet | \mathbf{x}^t
ight]$$





Predict the most likely label



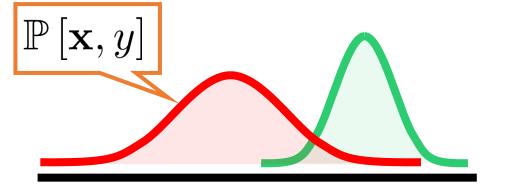
$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$

$$\mathbb{P}\left[y\,|\,\mathbf{x}^{t}\right] = \frac{\mathbb{P}\left[\mathbf{x}^{t},y\right]}{\mathbb{P}\left[\mathbf{x}^{t}\right]} \quad \mathbb{P}\left[\bullet\,|\,\mathbf{x}^{t}\right] > \mathbb{P}\left[\bullet\,|\,\mathbf{x}^{t}\right] \quad \hat{y}^{t} = \bullet$$

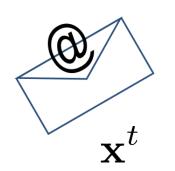
$$\mathbb{P}\left[\bullet\,|\,\mathbf{x}^{t}\right] > \mathbb{P}\left[\bullet\,|\,\mathbf{x}^{t}\right] \quad \hat{y}^{t} = \bullet$$

$$\mathbb{P}\left[ullet \left| \mathbf{x}^t
ight] > \mathbb{P}\left[ullet \left| \mathbf{x}^t
ight] \ \hat{y}^t = 0$$





Predict the most likely label



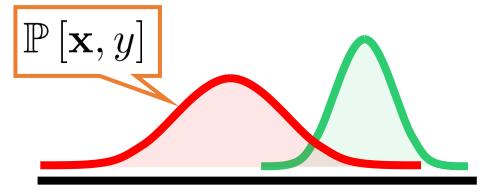
$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$

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$$\mathbb{P}\left[\bullet, \mathbf{x}^{t}\right] > \mathbb{P}\left[\bullet, \mathbf{x}^{t}\right] \quad \hat{y}^{t} = \bullet$$

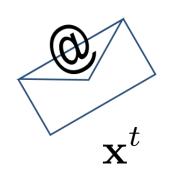
$$\mathbb{P}\left[ullet,\mathbf{x}^{t}
ight]>\mathbb{P}\left[ullet,\mathbf{x}^{t}
ight]\;\;\hat{y}^{t}=0$$





A generative model can make predictions!

Predict the most likely label

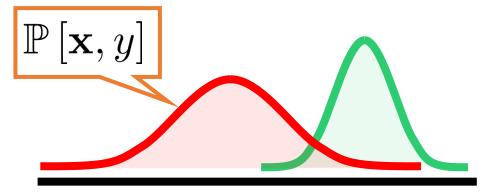


$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$

$$\mathbb{P}\left[ullet,\mathbf{x}^{t}
ight] > \mathbb{P}\left[ullet,\mathbf{x}^{t}
ight] \;\; \hat{y}^{t} = ullet$$

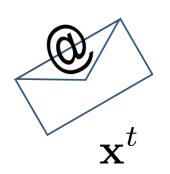
$$\mathbb{P}\left[ullet , \mathbf{x}^t
ight] > \mathbb{P}\left[ullet , \mathbf{x}^t
ight] \;\; \hat{y}^t = ullet$$





A generative model can make predictions!

Predict the most likely label



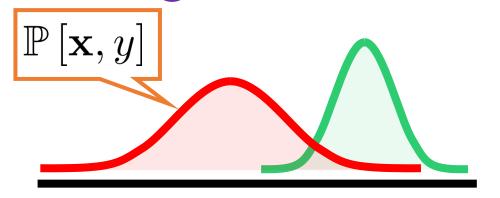
$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$

$$\mathbb{P}\left[ullet,\mathbf{x}^{t}
ight] > \mathbb{P}\left[ullet,\mathbf{x}^{t}
ight] \;\; \hat{y}^{t} = ullet$$

$$\mathbb{P}\left[ullet , \mathbf{x}^t
ight] > \mathbb{P}\left[ullet , \mathbf{x}^t
ight] \;\; \hat{y}^t = ullet$$

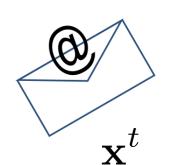






A generative model can make predictions!

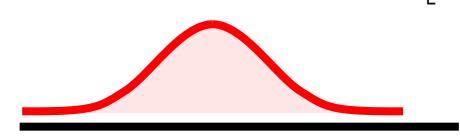
Predict the most likely label



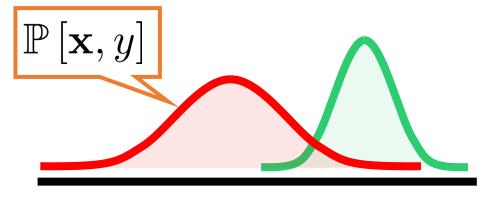
$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$

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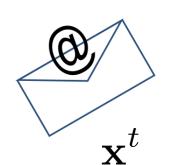






A generative model can make predictions!

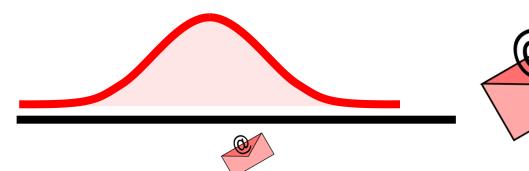
Predict the most likely label



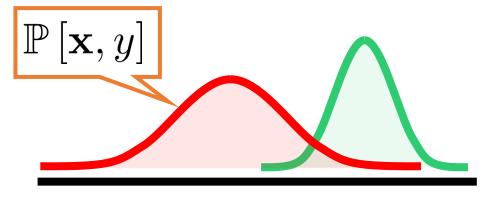
$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$

$$\mathbb{P}\left[ullet,\mathbf{x}^{t}
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$$\mathbb{P}\left[ullet ,\mathbf{x}^{t}
ight] > \mathbb{P}\left[ullet ,\mathbf{x}^{t}
ight] \;\; \hat{y}^{t} = ullet$$

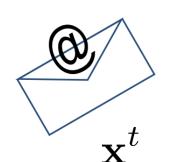






A generative model can make predictions!

Predict the most likely label



$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$

$$\mathbb{P}\left[ullet,\mathbf{x}^{t}
ight] > \mathbb{P}\left[ullet,\mathbf{x}^{t}
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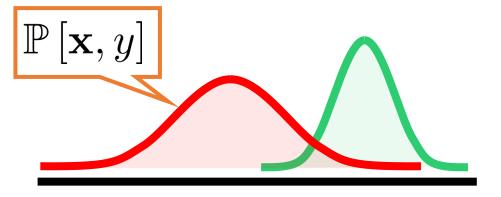
$$\mathbb{P}\left[ullet ,\mathbf{x}^{t}
ight] > \mathbb{P}\left[ullet ,\mathbf{x}^{t}
ight] \;\; \hat{y}^{t} = ullet$$



A generative model can generate data!

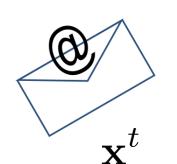






A generative model can make predictions!

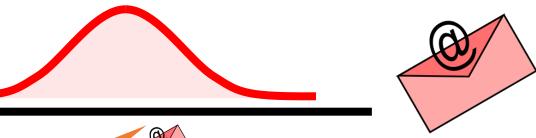
Predict the most likely label



$$\mathbb{P}\left[y \mid \mathbf{x}^t\right] = \frac{\mathbb{P}\left[\mathbf{x}^t, y\right]}{\mathbb{P}\left[\mathbf{x}^t\right]}$$

$$\mathbb{P}\left[ullet,\mathbf{x}^{t}
ight]>\mathbb{P}\left[ullet,\mathbf{x}^{t}
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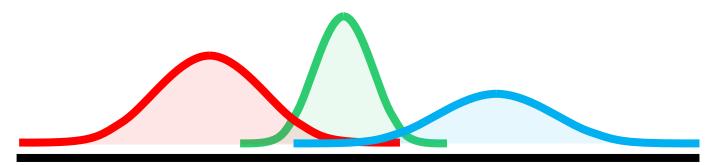




A generative model can generate data!

torch.ch

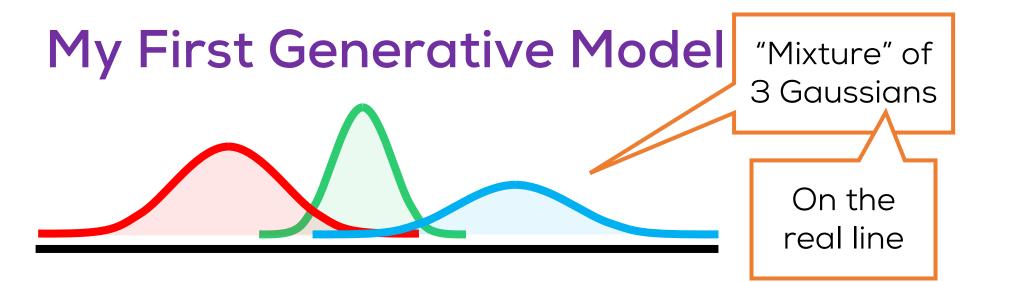




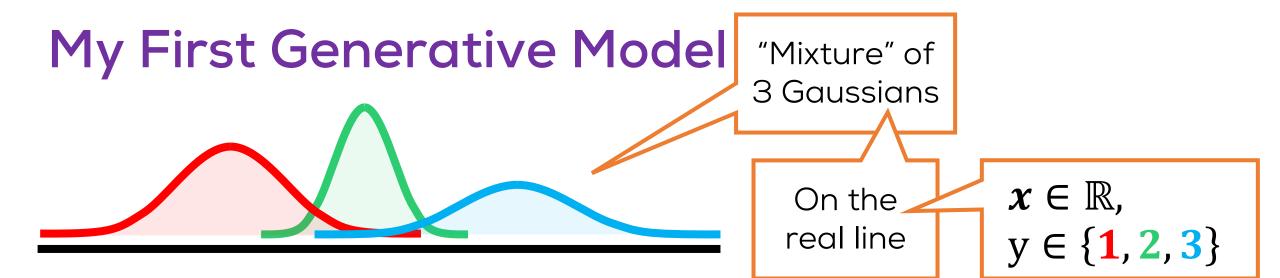


My First Generative Model
"Mixture" of 3 Gaussians





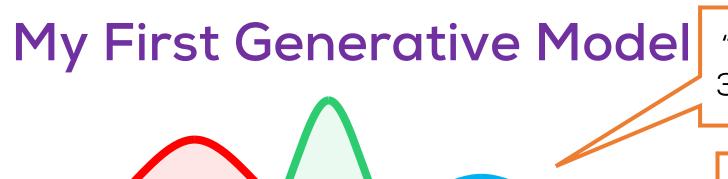












"Mixture" of 3 Gaussians

Can we try something simpler first?

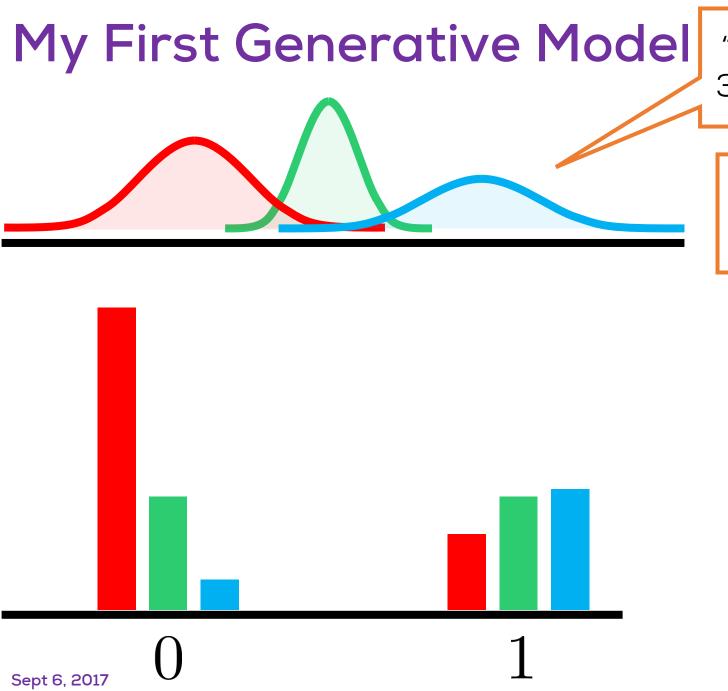
On the real line

 $x \in \mathbb{R}$, $y \in \{1, 2, 3\}$



0

1



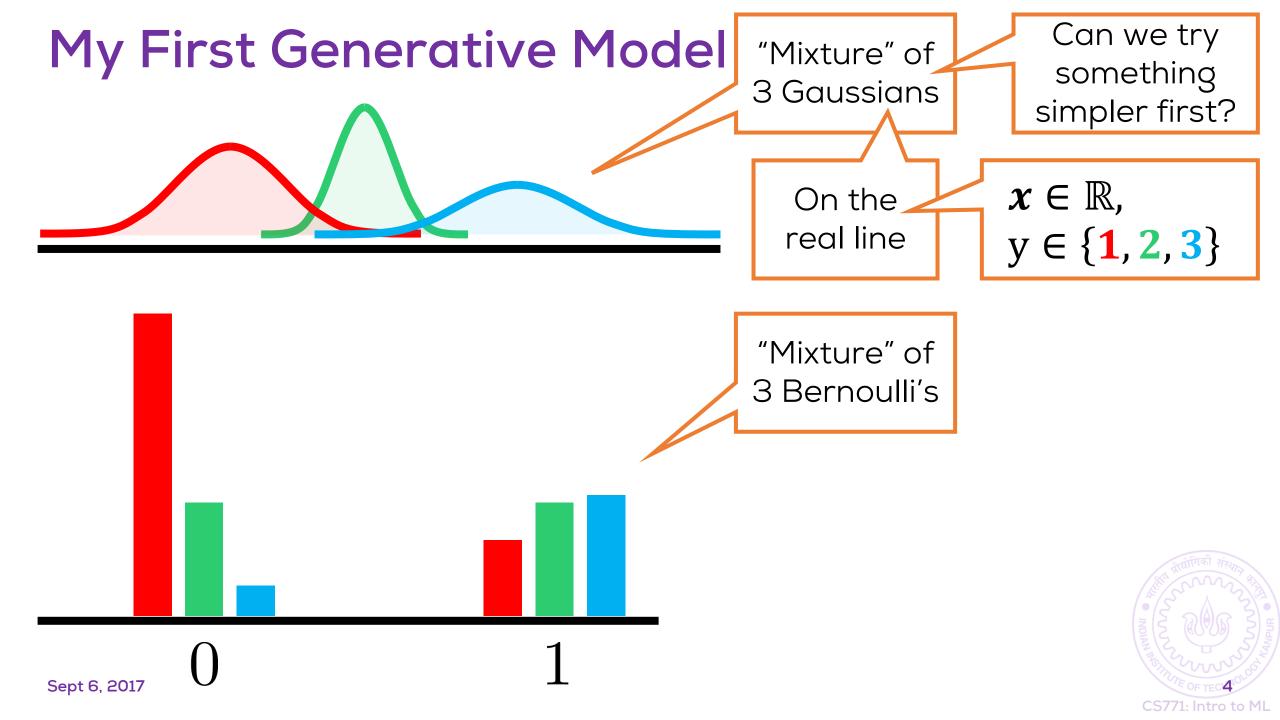
"Mixture" of 3 Gaussians

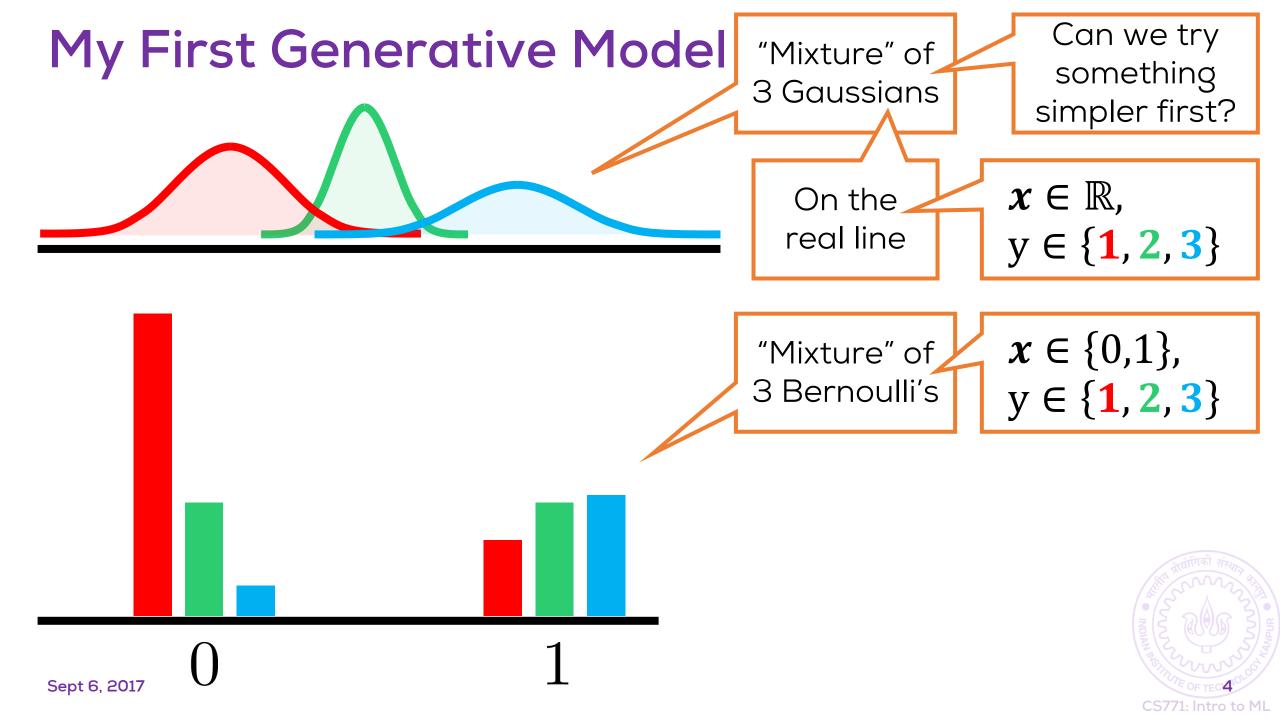
Can we try something simpler first?

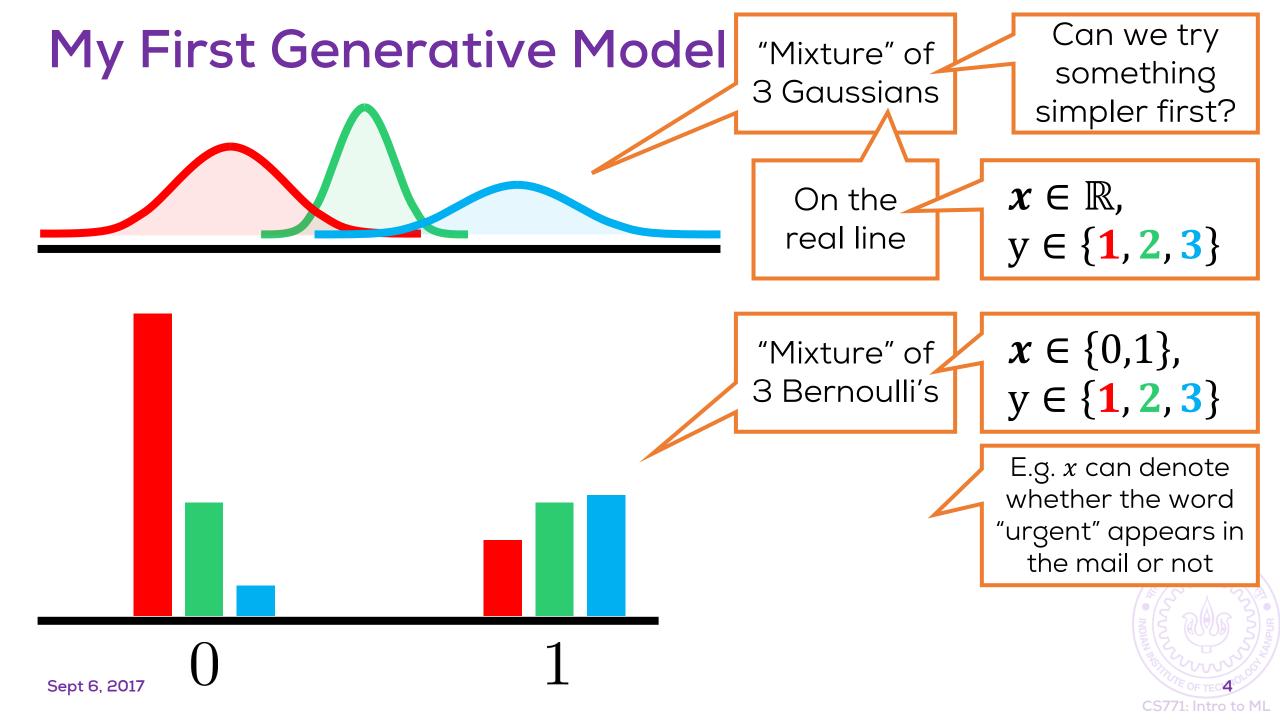
On the real line

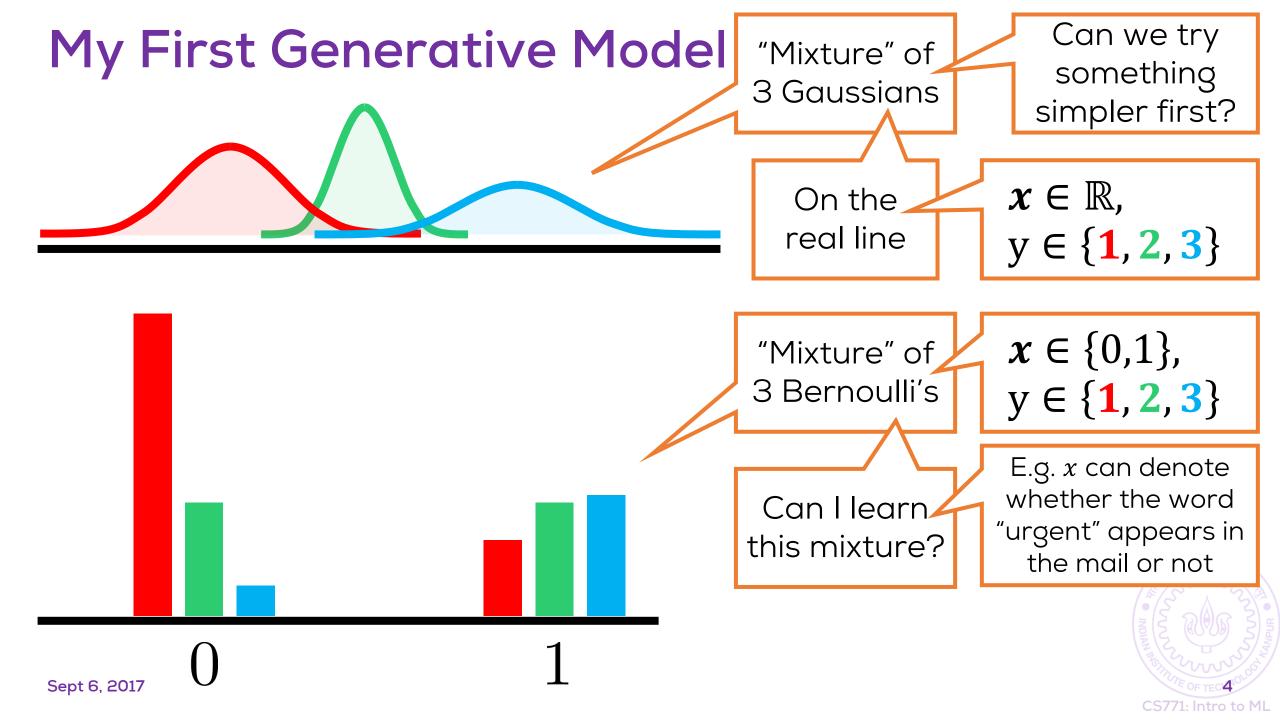
 $x \in \mathbb{R}$, $y \in \{1, 2, 3\}$

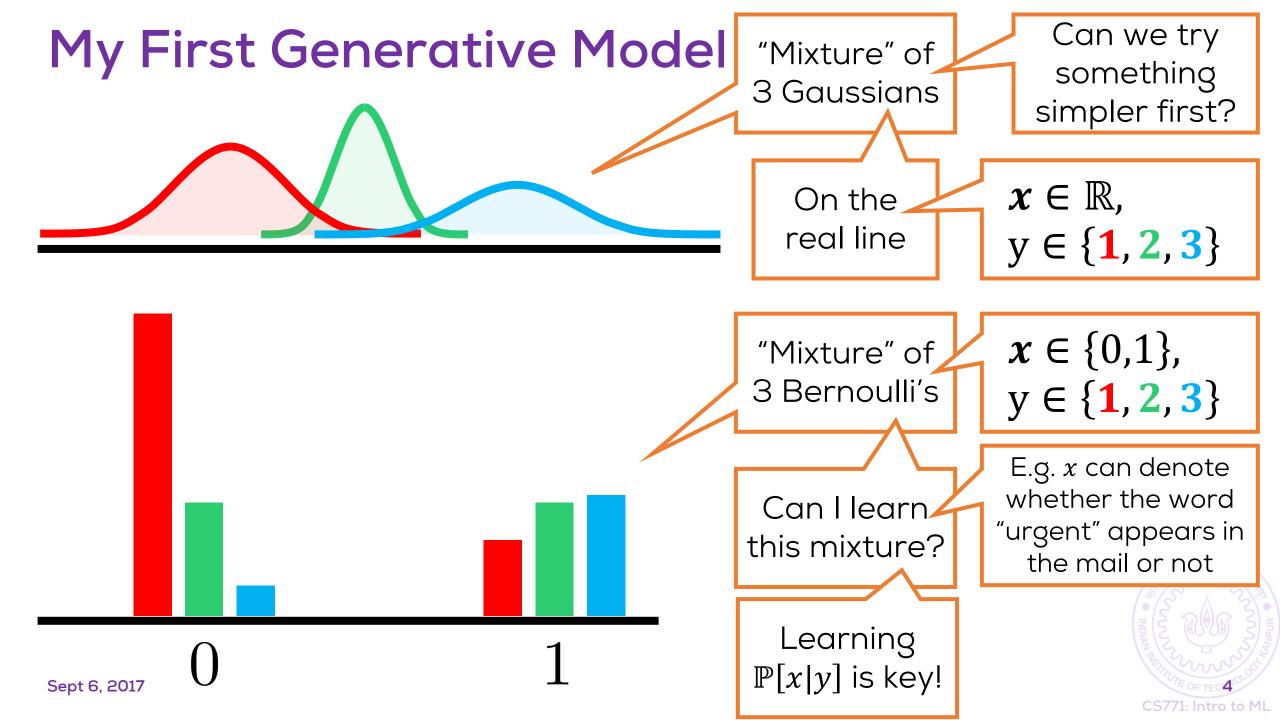


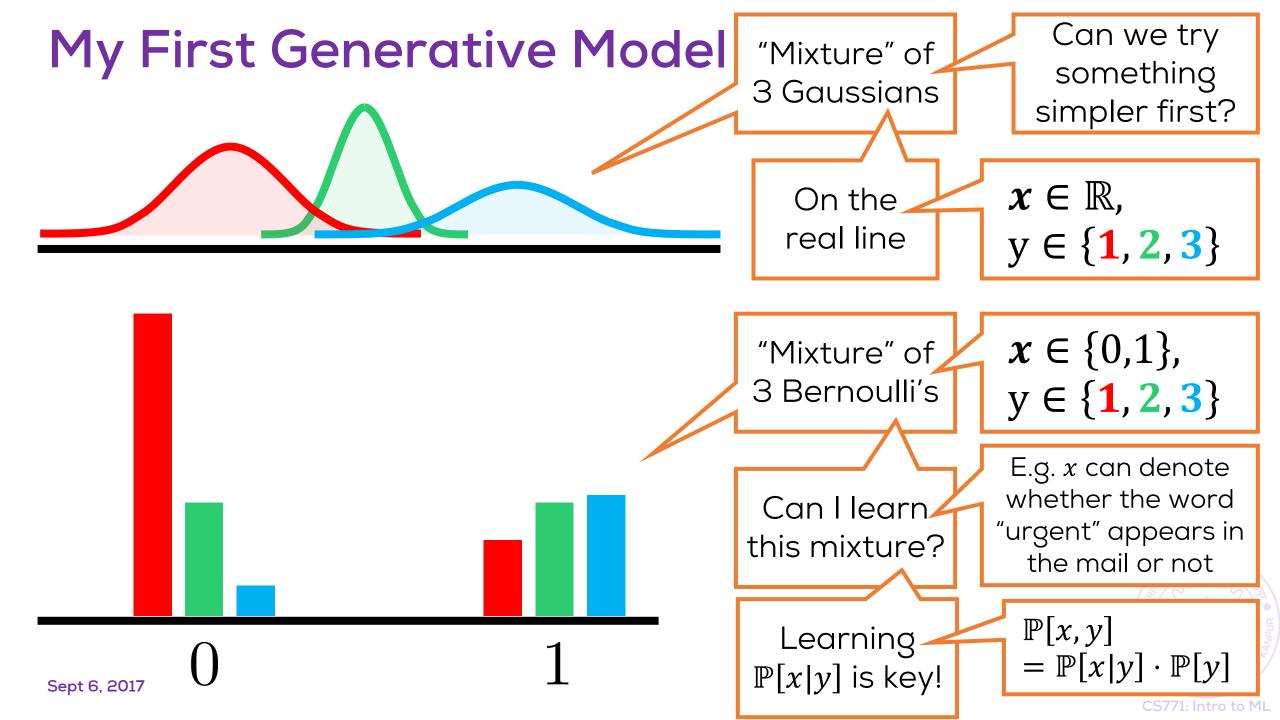


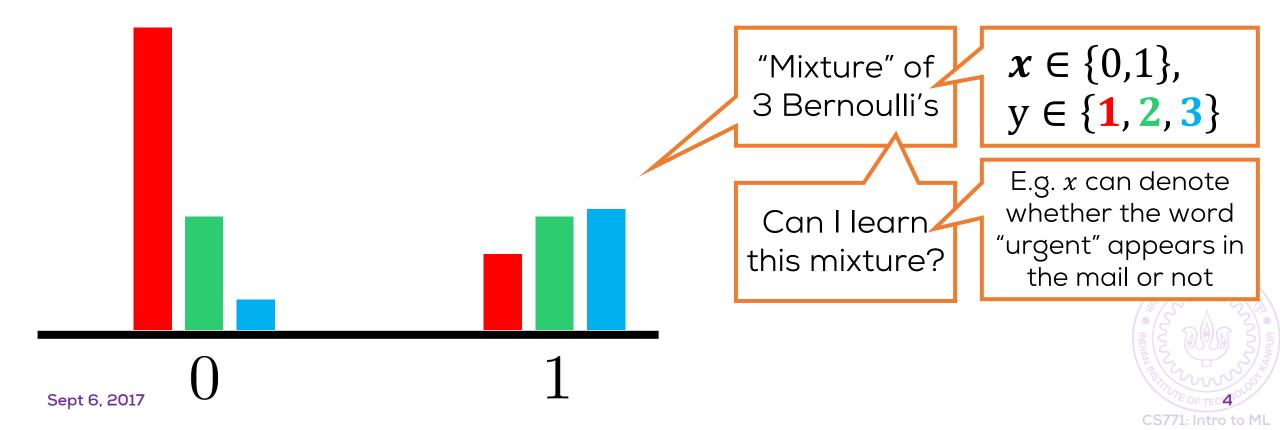


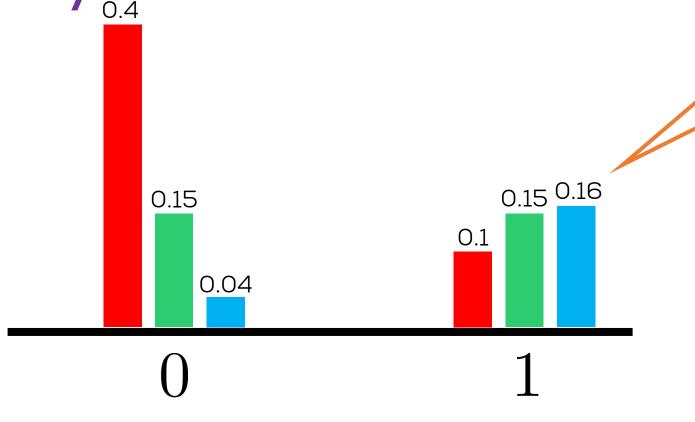










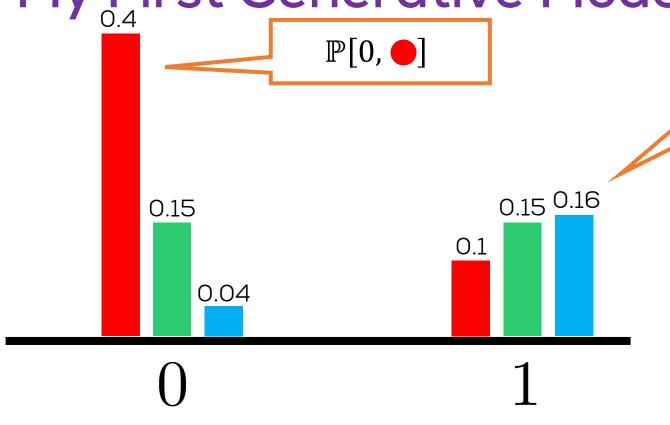


"Mixture" of 3 Bernoulli's

Can I learn this mixture?

 $x \in \{0,1\},\ y \in \{1,2,3\}$



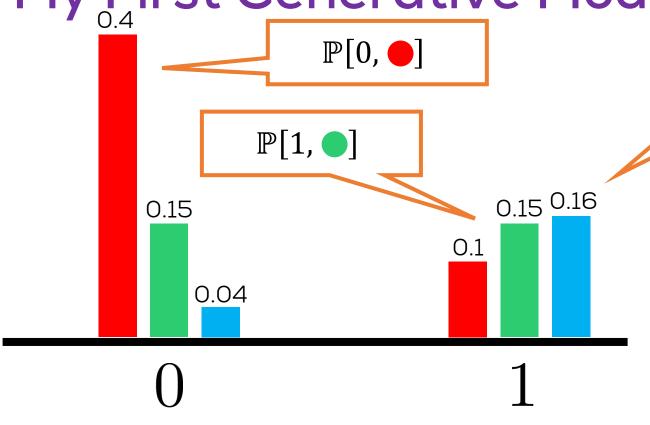


"Mixture" of 3 Bernoulli's

Can I learn this mixture?

 $x \in \{0,1\},\ y \in \{1,2,3\}$



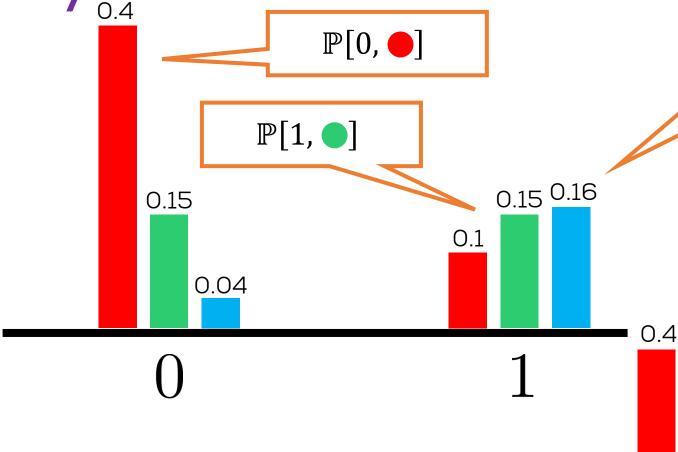


"Mixture" of 3 Bernoulli's

Can I learn this mixture?

 $x \in \{0,1\},\ y \in \{1,2,3\}$

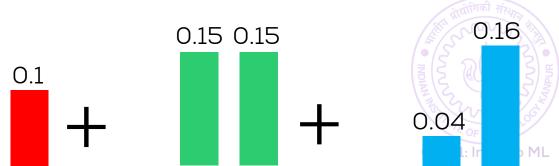


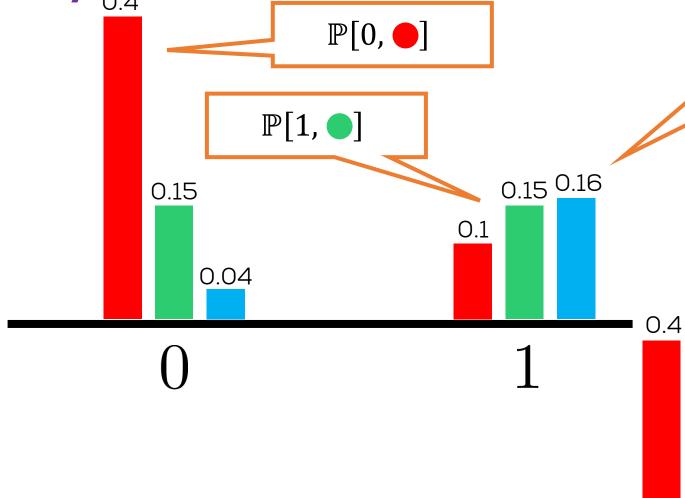


"Mixture" of 3 Bernoulli's

Can I learn/this mixture?

 $x \in \{0,1\},\ y \in \{1,2,3\}$





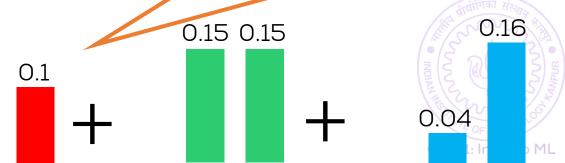
"Mixture" of 3 Bernoulli's

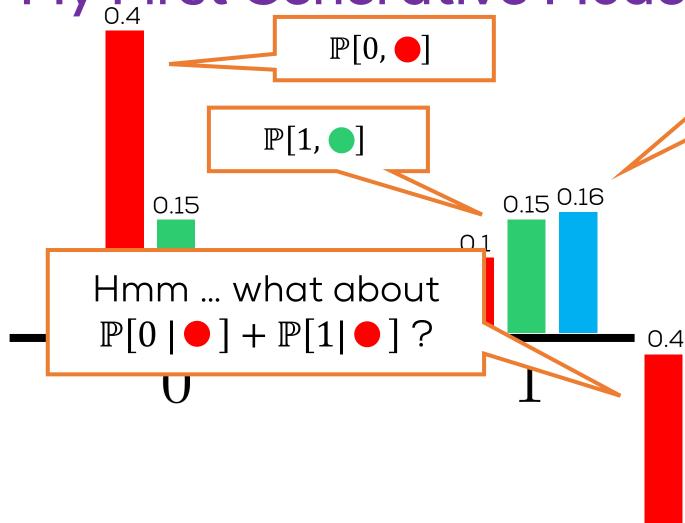
 $x \in \{0,1\},\ y \in \{1,2,3\}$

Can I learn/this mixture?

E.g. x can denote whether the word "urgent" appears in the mail or not

What is wrong? Why am I getting $\mathbb{P}[0, \bullet] + \mathbb{P}[1, \bullet] = 0.5?$





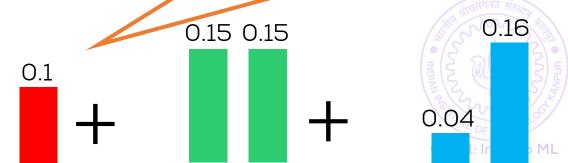
"Mixture" of 3 Bernoulli's

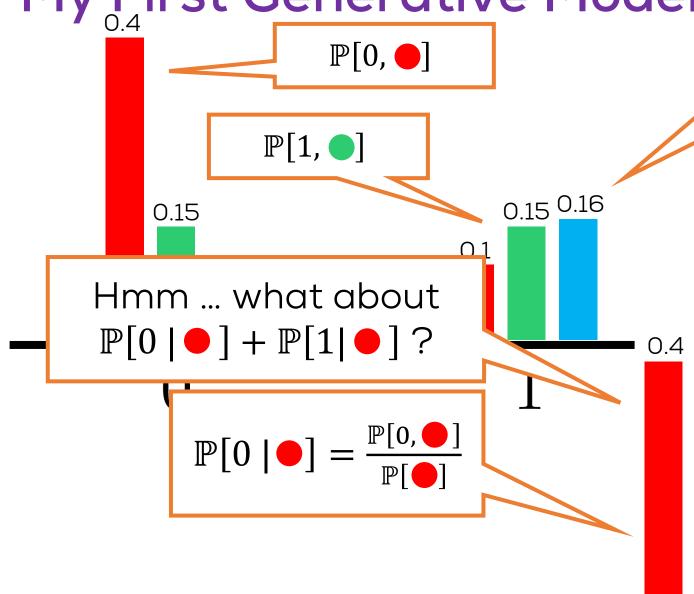
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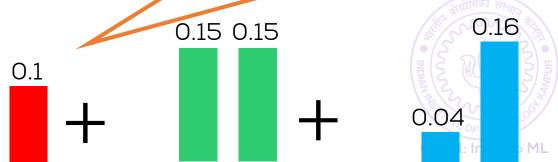
"Mixture" of 3 Bernoulli's

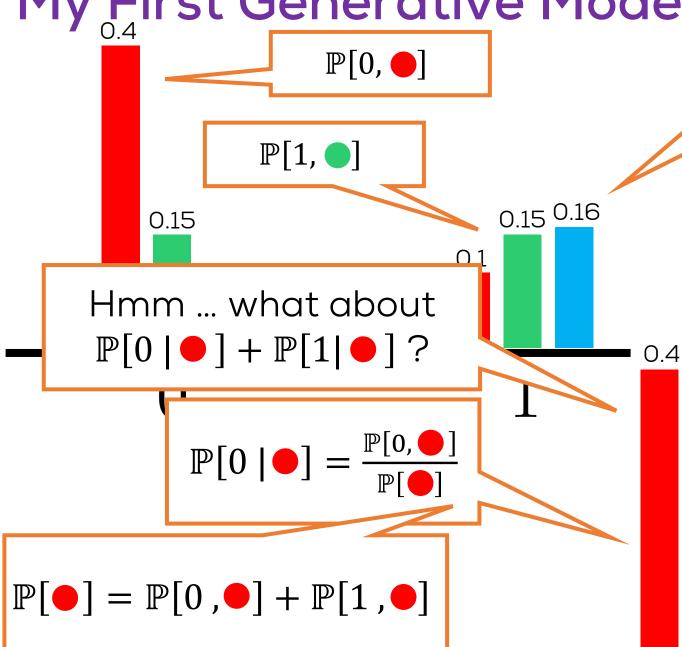
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What is wrong? Why am I getting $\mathbb{P}[0, \bullet] + \mathbb{P}[1, \bullet] = 0.5$?



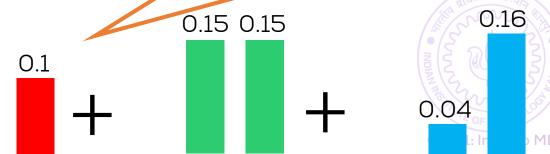


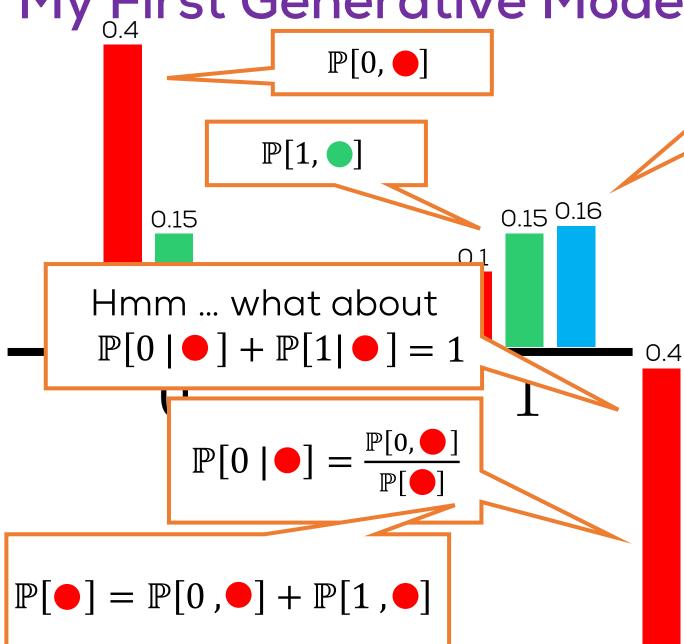
"Mixture" of 3 Bernoulli's $x \in \{0,1\},\$ $y \in \{1, 2, 3\}$

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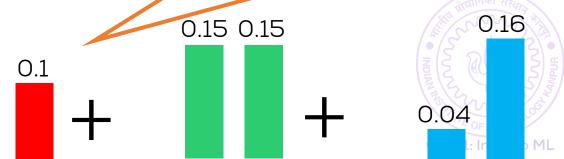


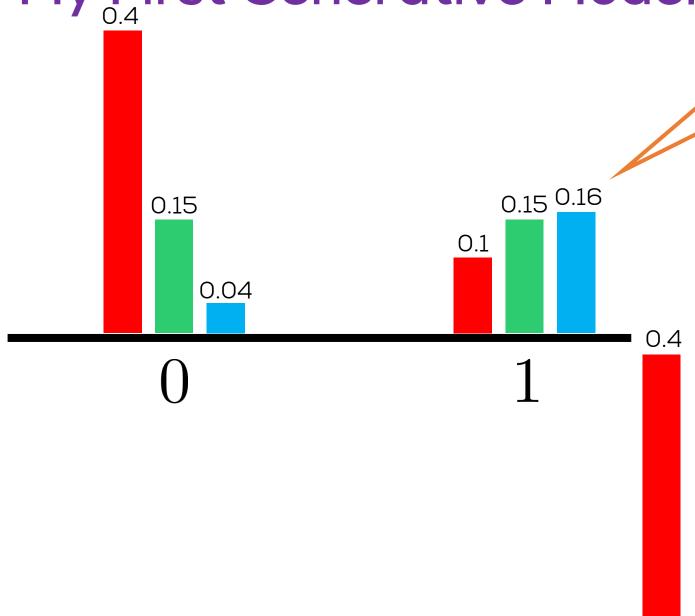
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"Mixture" of 3 Bernoulli's

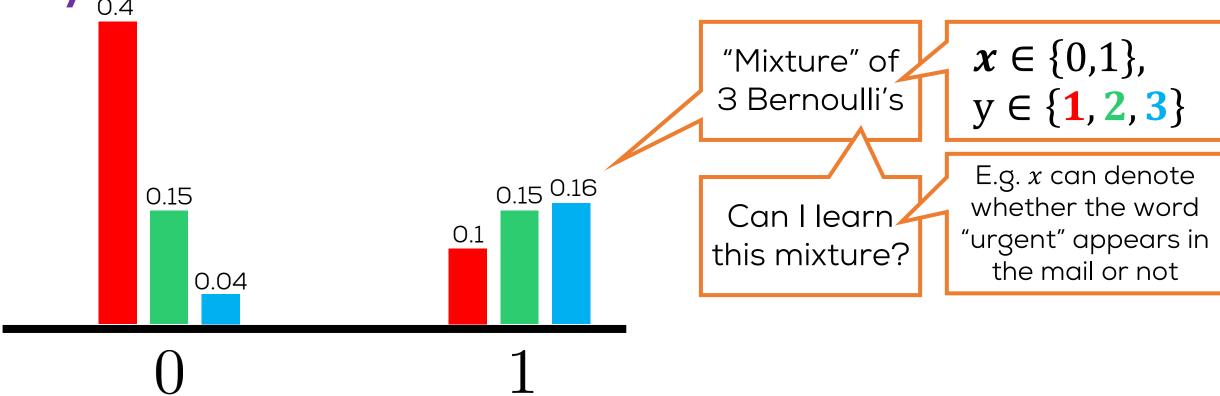
Can I learn/this mixture?

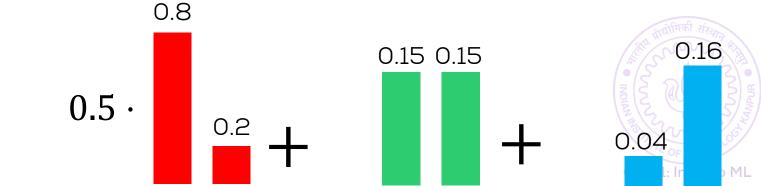
0.1

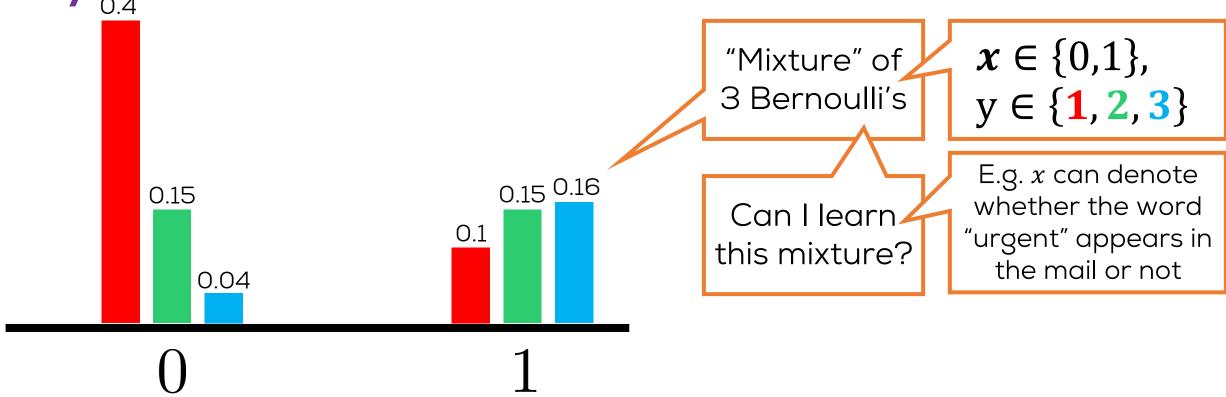
0.15 0.15

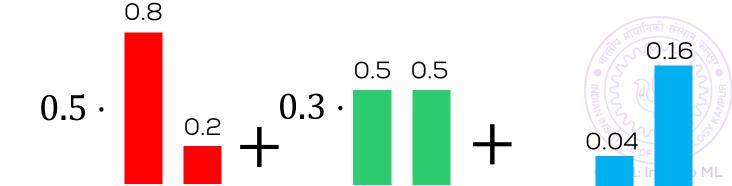
 $x \in \{0,1\},\ y \in \{1,2,3\}$

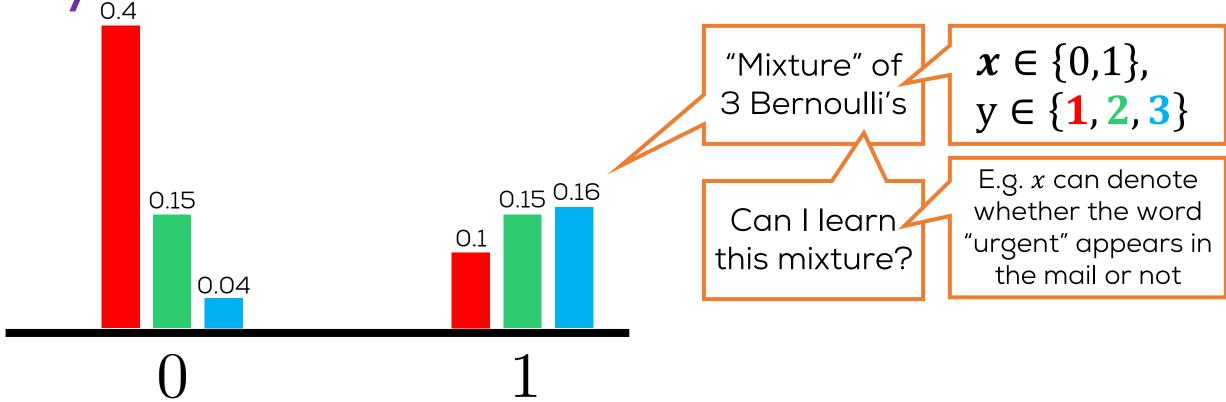


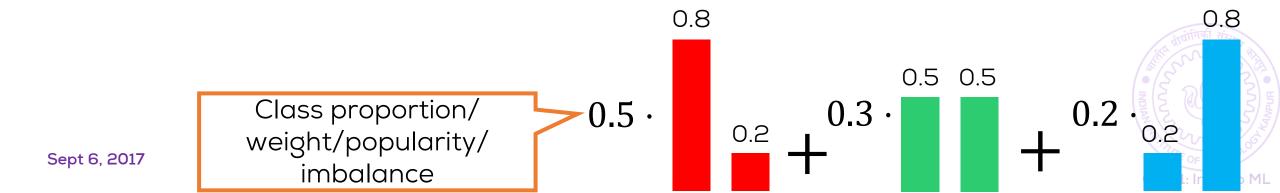






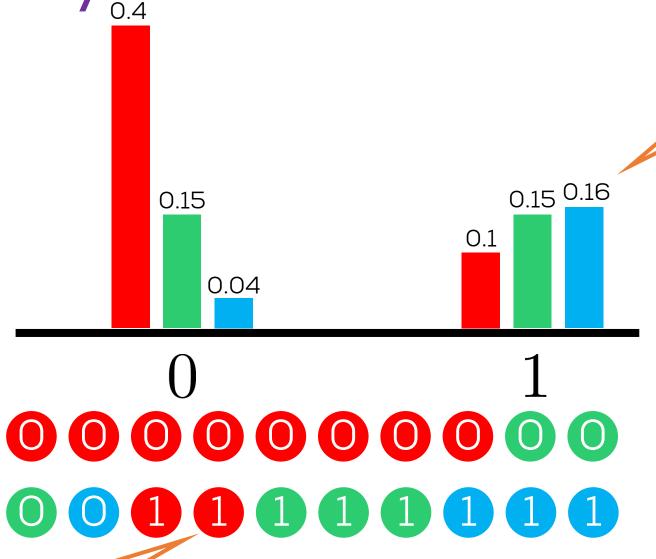






My First Generative Model $x \in \{0,1\},\$ "Mixture" of 3 Bernoulli's $y \in \{1, 2, 3\}$ E.g. x can denote 0.15 0.16 0.15 whether the word Can I learn 0.1 "urgent" appears in this mixture? the mail or not 0.04 0000000000 0.8 0.8 0.5 0.5 Class proportion/ 0.3 · 0.5 · Training 0.2 weight/popularity/ data imbalance

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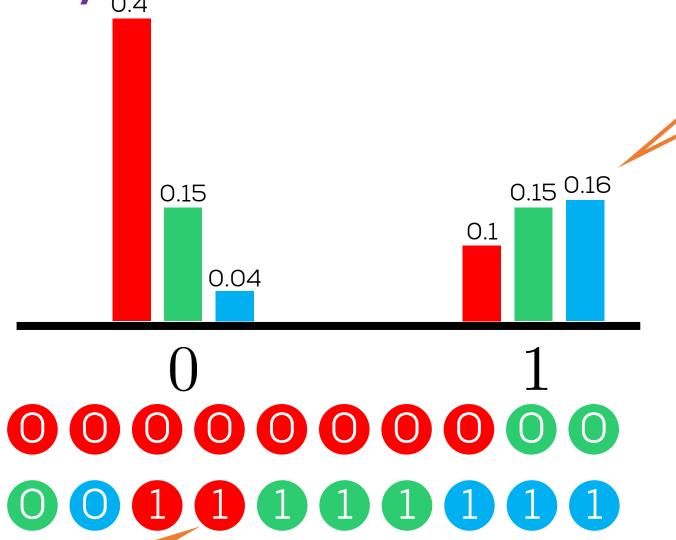
Training

data

"Mixture" of 3 Bernoulli's

Can I learn this mixture? $x \in \{0,1\},\ y \in \{1,2,3\}$





"Mixture" of 3 Bernoulli's $x \in \{0,1\},\$ $y \in \{1, 2, 3\}$

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$$\mathbb{P}\left[ullet\right]pprox rac{| au|}{-}$$

$$\mathbb{P}\left[\bullet\right] \approx \frac{|i:y^i = \bullet|}{}$$

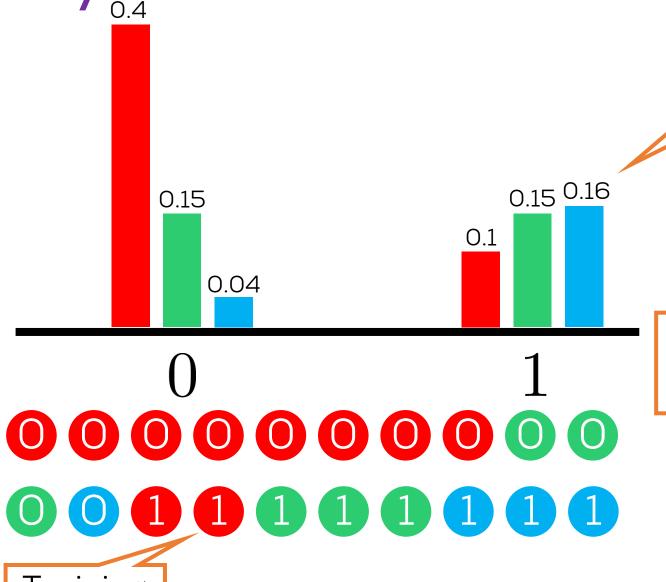
CS771: Intro to ML

Training data

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Can be shown to be the MLE!

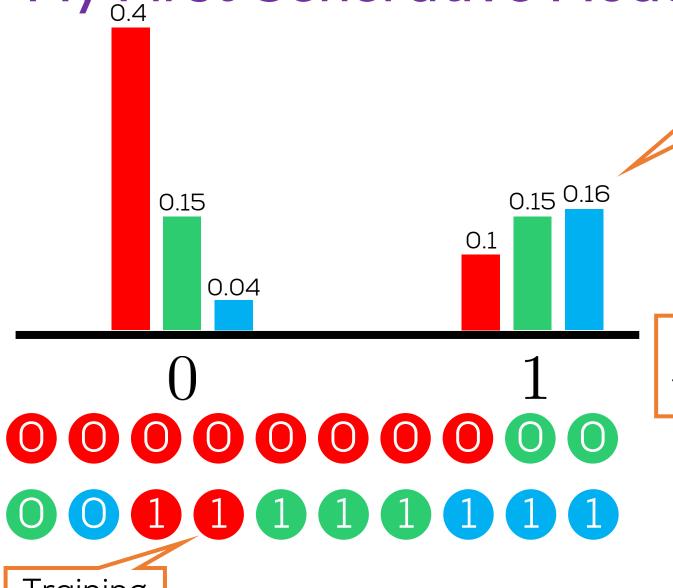


 $i:y^i=$

Total number of data points



Training data



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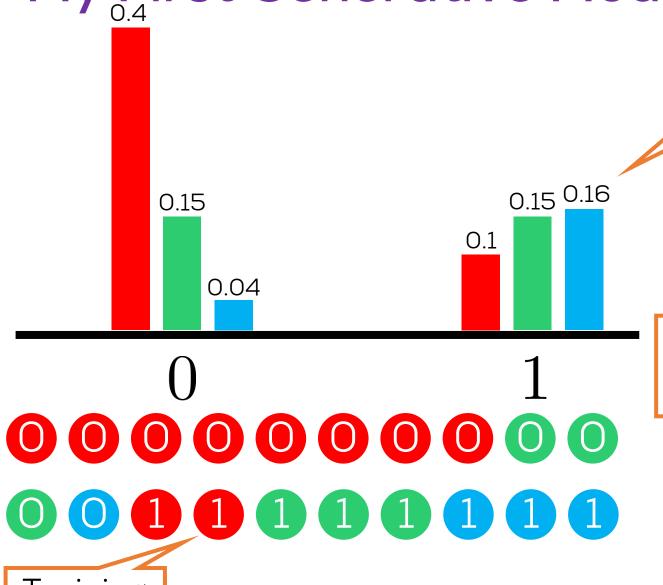
Can do Bayesian inference too!



 $i:y^i=$

Total number of data points





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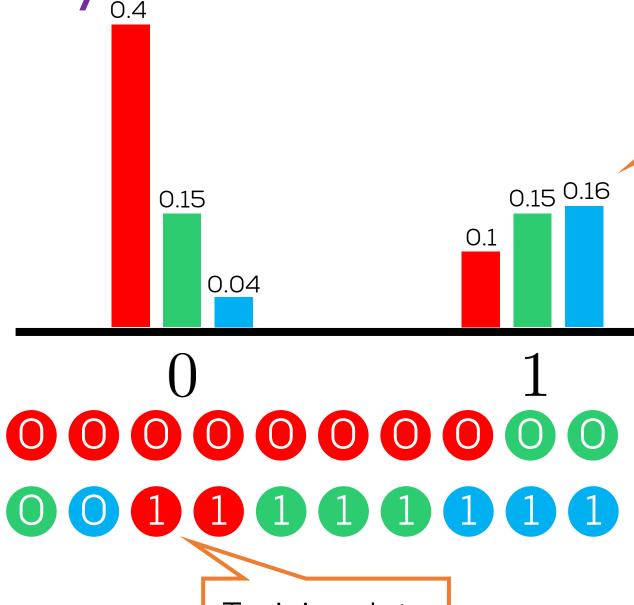
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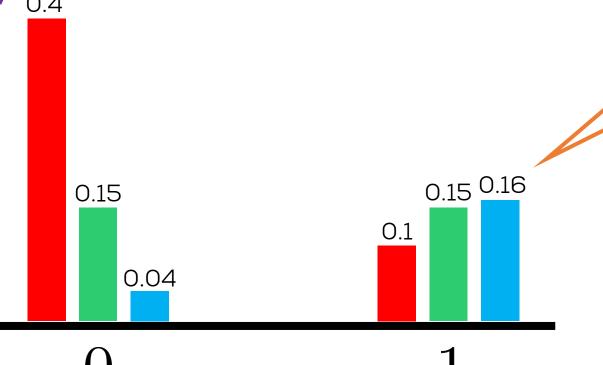
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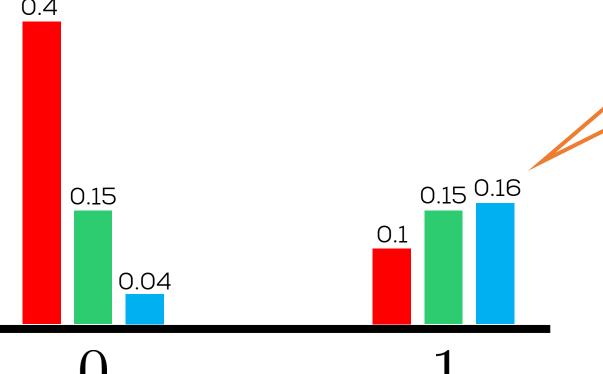
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$$\mathbb{P}\left[x=0\,|\,\bullet\,\right] \approx \frac{1}{2}$$

$$\mathbb{P}\left[x=0\,|\,\bullet\,\right] \approx \frac{\left|i:x^i=0\cap y^i=\bullet\right|}{\left|i:y^i=\bullet\right|}$$

$$|i:y^i= left$$



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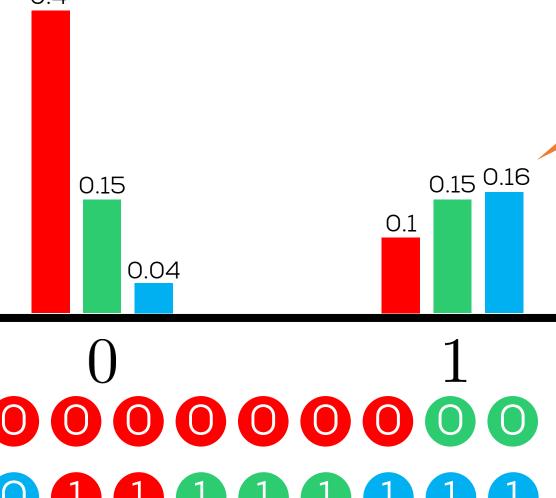
$$\mathbb{P}\left[x=0 \mid \bullet\right] \approx \frac{\left|i: x^i=0 \cap y^i=\bullet\right|}{\left|i: y^i=\bullet\right|}$$

Total number of data points with label

Training data

Sept 6, 2017

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"Mixture" of 3 Bernoulli's

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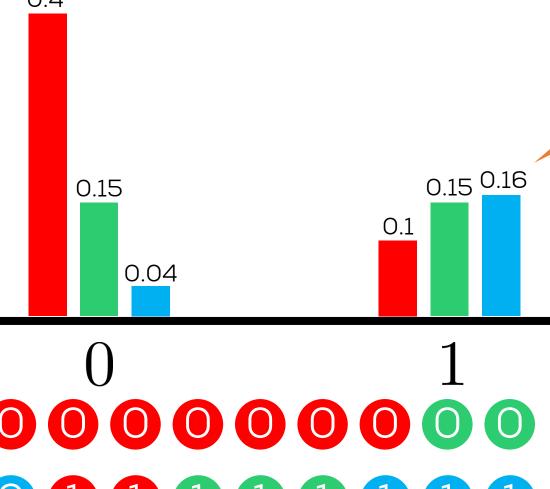
$$\mathbb{P}[x=1| \bullet] = 1 - \mathbb{P}[x=0| \bullet]$$

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Sept 6, 2017 Training data

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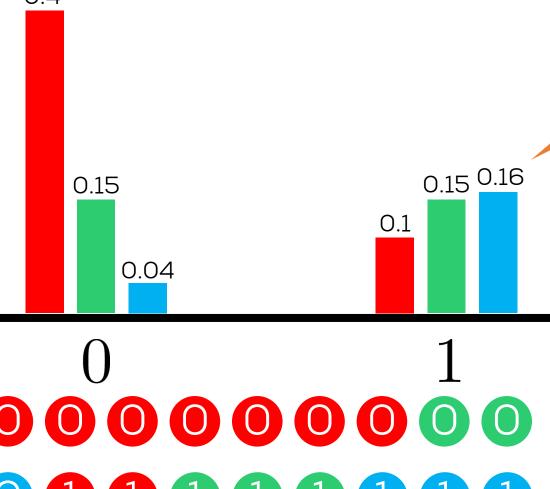
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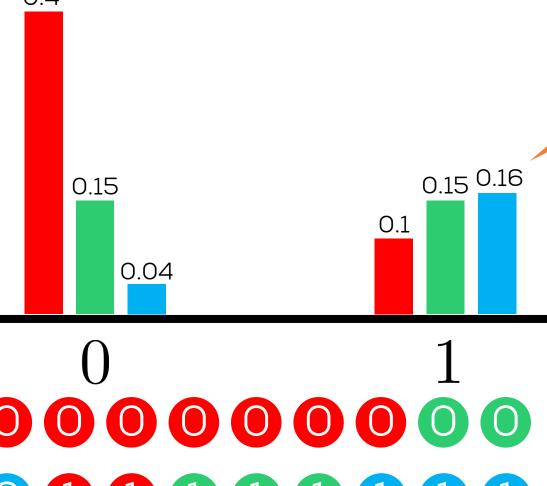
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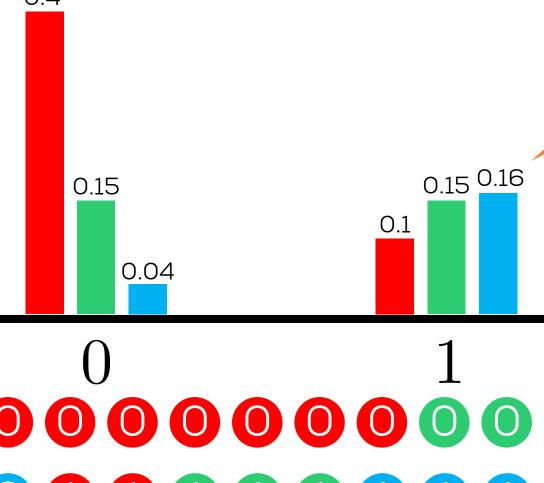
 $i:y^i=$

Total number of data points with label

Training data

Sept 6, 2017

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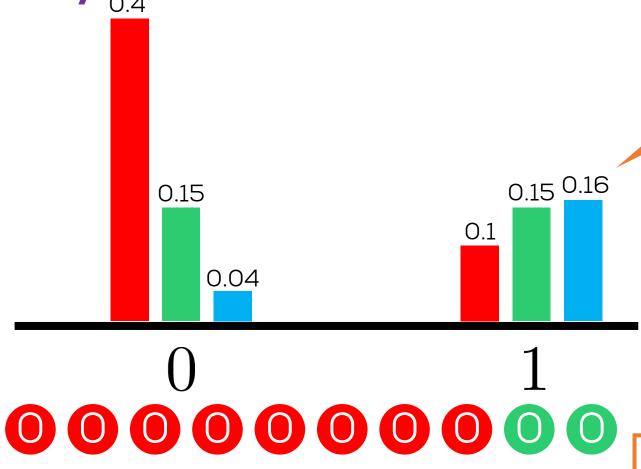
$$\mathbb{P}\left[x=0\mid\bullet\right]\approx\frac{\left|i:x^{i}=0\cap y^{i}=\bullet\right|}{\left|i:x^{i}=0\right|}$$

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Sept 6, 2017



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Generative ≠ Bayesian

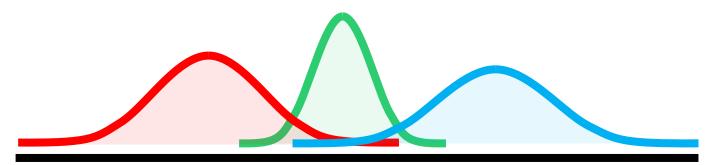
$$= 0 \cap y^i = \bigcirc$$

$$: y^i =$$

Total number of data points with label



Sept 6, 2017





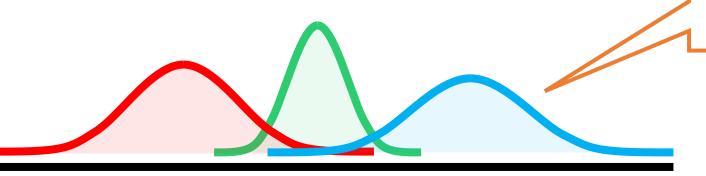
My First Generative Model "Mixture" of

3 Gaussians



"Mixture" of 3 Gaussians

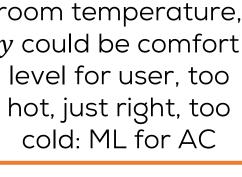
 $x \in \mathbb{R}$, $y \in \{1, 2, 3\}$





"Mixture" of 3 Gaussians $x \in \mathbb{R}$, $y \in \{1, 2, 3\}$

E.g. x could be room temperature, y could be comfort level for user, too hot, just right, too cold: ML for AC





"Mixture" of 3 Gaussians

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"Mixture" of 3 Gaussians



We know/assume they are Gaussians

What we don't know/assume is what is their mean etc

E.g. x could be room temperature, y could be comfort level for user, too hot, just right, too cold: ML for AC



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Can estimate the class proportions, and means and variances of these 1D Gaussians using training data!



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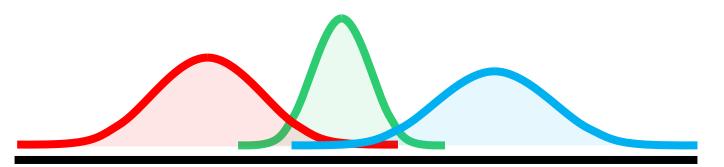
+

+

Can estimate the class proportions, and means and variances of these 1D

Gaussians using training data!

Read [DAU] Sections 9.1-9.5





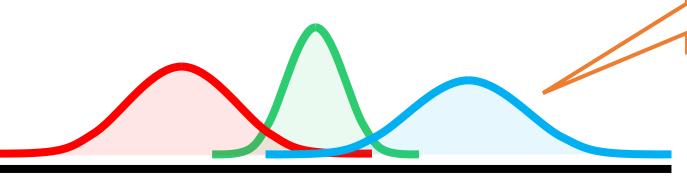


"Mixture" of 3 Gaussians



"Mixture" of 3 Gaussians

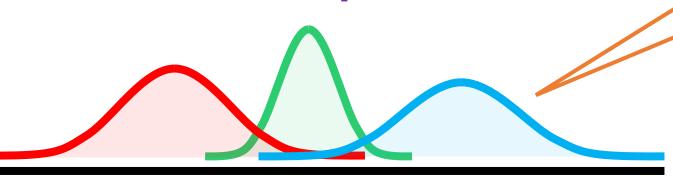
 $x \in \mathbb{R}$, $y \in \{1, 2, 3\}$





"Mixture" of 3 Gaussians

 $x \in \mathbb{R}^d$, $y \in \{1, 2, 3\}$





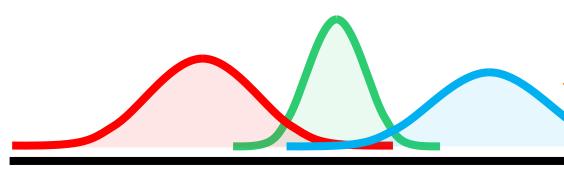
$$x \in \mathbb{R}^d$$
, $y \in \{1, 2, 3\}$

$$\mathbb{P}\left[\mathbf{x}, y\right] = \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x} \mid y\right]$$



"Mixture" of 3 Gaussians

$$x \in \mathbb{R}^d$$
, $y \in \{1, 2, 3\}$

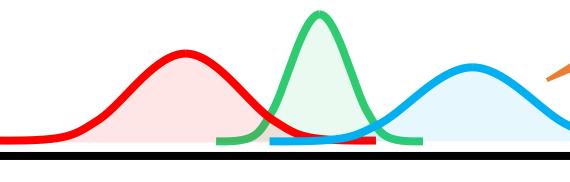


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"Mixture" of 3 Gaussians

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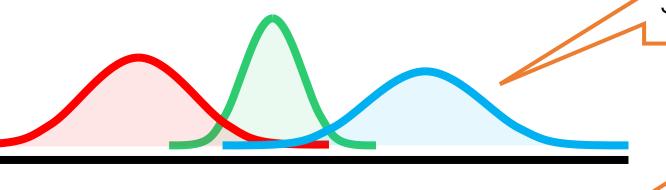


$$\mathbb{P}\left[\mathbf{x}, y\right] = \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x} \mid y\right]$$
$$= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1}, \mathbf{x}_{2}, \dots, \mathbf{x}_{d} \mid y\right]$$



"Mixture" of 3 Gaussians

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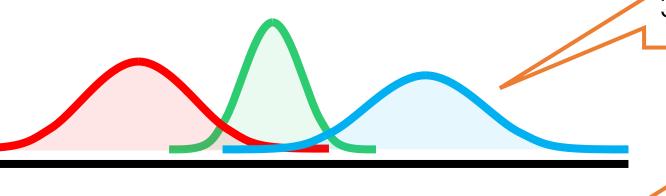
$$= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1}, \mathbf{x}_{2}, \dots, \mathbf{x}_{d} \mid y\right]$$

$$= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1} \mid \mathbf{x}_{2}, \mathbf{x}_{3}, \dots, \mathbf{x}^{d}, y\right] \cdot \mathbb{P}\left[\mathbf{x}_{2}, \mathbf{x}_{3}, \dots, \mathbf{x}^{d} \mid y\right]$$



"Mixture" of 3 Gaussians

 $x \in \mathbb{R}^d$, $y \in \{1, 2, 3\}$

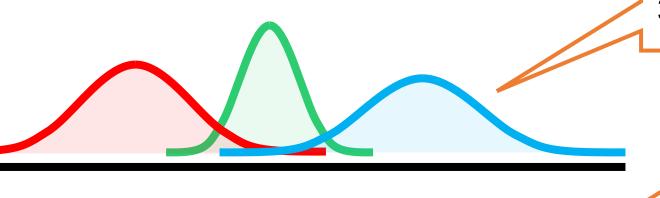


$$\mathbb{P}\left[\mathbf{x}, y\right] = \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x} \mid y\right] \\
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"Mixture" of 3 Gaussians

$$x \in \mathbb{R}^d$$
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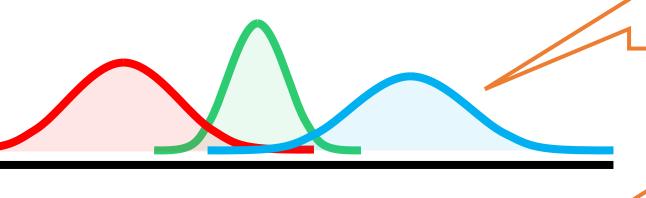
Chain rule of probabilty

$$\mathbb{P}\left[\mathbf{x}, y\right] = \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x} \mid y\right] \\
= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1}, \mathbf{x}_{2}, \dots, \mathbf{x}_{d} \mid y\right] \\
= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1} \mid \mathbf{x}_{2}, \mathbf{x}_{3}, \dots, \mathbf{x}^{d}, y\right] \cdot \mathbb{P}\left[\mathbf{x}_{2}, \mathbf{x}_{3}, \dots, \mathbf{x}^{d} \mid y\right] \\
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Naïve Bayes assumption $\mathbb{P}[x_j | x_k, y] = \mathbb{P}[x_j | y]$ if $j \neq k$

"Mixture" of 3 Gaussians

 $x \in \mathbb{R}^d$, $y \in \{1, 2, 3\}$



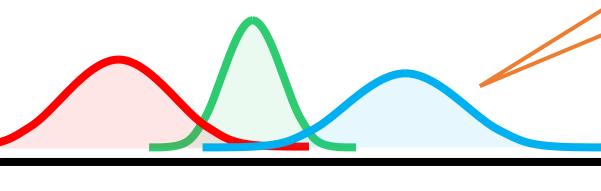
Chain rule of probabilty

$$\begin{split} \mathbb{P}\left[\mathbf{x},y\right] &= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x} \mid y\right] \\ &= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{d} \mid y\right] \\ &= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1} \mid \mathbf{x}_{2}, \mathbf{x}_{3}, \ldots, \mathbf{x}^{d}, y\right] \cdot \mathbb{P}\left[\mathbf{x}_{2}, \mathbf{x}_{3}, \ldots, \mathbf{x}^{d} \mid y\right] \\ &= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1} \mid y\right] \cdot \mathbb{P}\left[\mathbf{x}_{2}, \mathbf{x}_{3}, \ldots, \mathbf{x}^{d} \mid y\right] \\ &= \ldots \end{split}$$

Naïve Bayes assumption $\mathbb{P}[x_j | x_k, y] = \mathbb{P}[x_j | y]$ if $j \neq k$

"Mixture" of 3 Gaussians

$$x \in \mathbb{R}^d$$
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Chain rule of probabilty

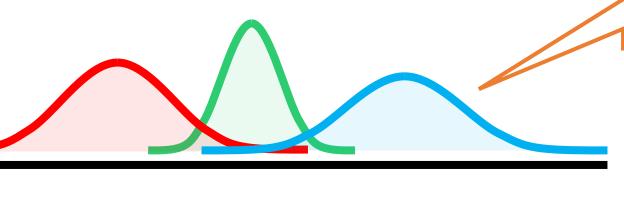
$$\begin{split} \mathbb{P}\left[\mathbf{x},y\right] &= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x} \mid y\right] \\ &= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{d} \mid y\right] \\ &= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1} \mid \mathbf{x}_{2}, \mathbf{x}_{3}, \ldots, \mathbf{x}^{d}, y\right] \cdot \mathbb{P}\left[\mathbf{x}_{2}, \mathbf{x}_{3}, \ldots, \mathbf{x}^{d} \mid y\right] \\ &= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1} \mid y\right] \cdot \mathbb{P}\left[\mathbf{x}_{2}, \mathbf{x}_{3}, \ldots, \mathbf{x}^{d} \mid y\right] \\ &= \ldots \end{split}$$

 $= \mathbb{P}\left[y\right] \cdot \prod \mathbb{P}\left[\mathbf{x}_i \mid y\right]$

Naïve Bayes assumption $\mathbb{P}[x_i|x_k,y] = \mathbb{P}[x_i|y] \text{ if } j \neq k$

"Mixture" of 3 Gaussians

$$x \in \mathbb{R}^d$$
, $y \in \{1, 2, 3\}$



Chain rule of probabilty

$$\mathbb{P}\left[\mathbf{x}, y\right] = \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x} \mid y\right] \\
= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1}, \mathbf{x}_{2}, \dots, \mathbf{x}_{d} \mid y\right] \\
= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1} \mid \mathbf{x}_{2}, \mathbf{x}_{3}, \dots, \mathbf{x}^{d}, y\right] \cdot \mathbb{P}\left[\mathbf{x}_{2}, \mathbf{x}_{3}, \dots, \mathbf{x}^{d} \mid y\right] \\
= \mathbb{P}\left[y\right] \cdot \mathbb{P}\left[\mathbf{x}_{1} \mid y\right] \cdot \mathbb{P}\left[\mathbf{x}_{2}, \mathbf{x}_{3}, \dots, \mathbf{x}^{d} \mid y\right]$$

$$= \mathbb{P}\left[y\right] \cdot \prod_{i=1}^{d} \mathbb{P}\left[\mathbf{x}_{i} \mid y\right]$$

Already seen how to model in 1D

Naïve Bayes assumption $\mathbb{P}[x_j | x_k, y] = \mathbb{P}[x_j | y]$ if $j \neq k$

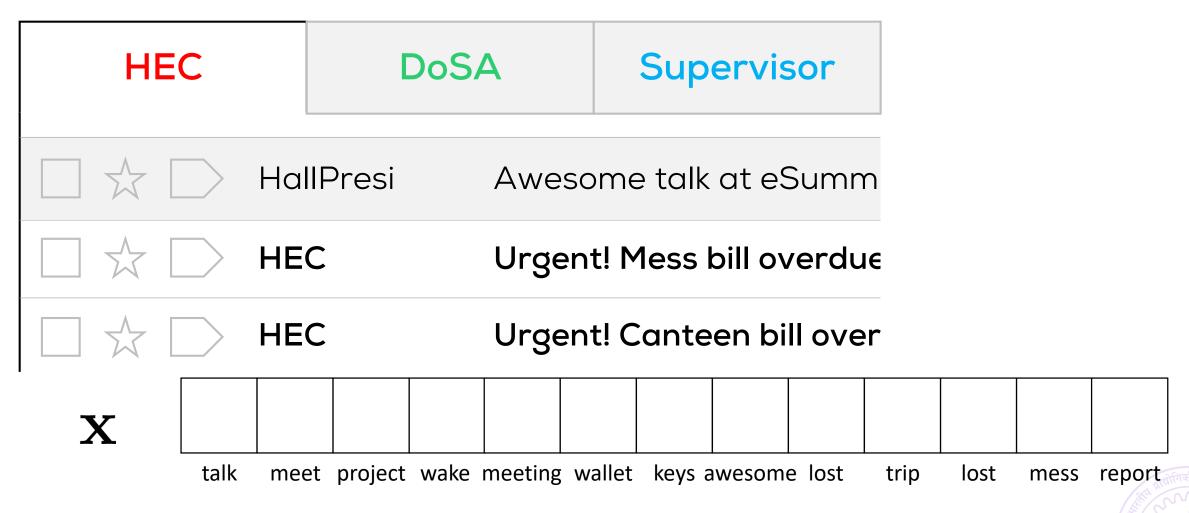
App: Email Categorizer using Naïve Bayes



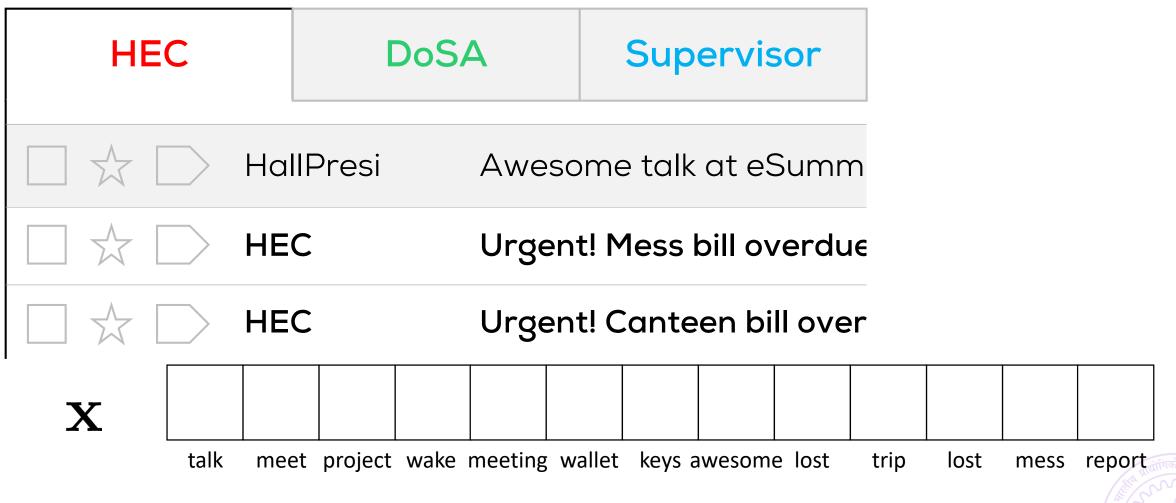
App: Email Categorizer using Naïve Bayes

HEC	Do	SA	Supervisor	
☐ ☆ □ Ho	> HallPresi		Awesome talk at eSumm	
□ ☆ □ HE	C	Urgen [.]	Urgent! Mess bill overdue	
□ ☆ □ HE	С	Urgen [.]	t! Canteen bill over	

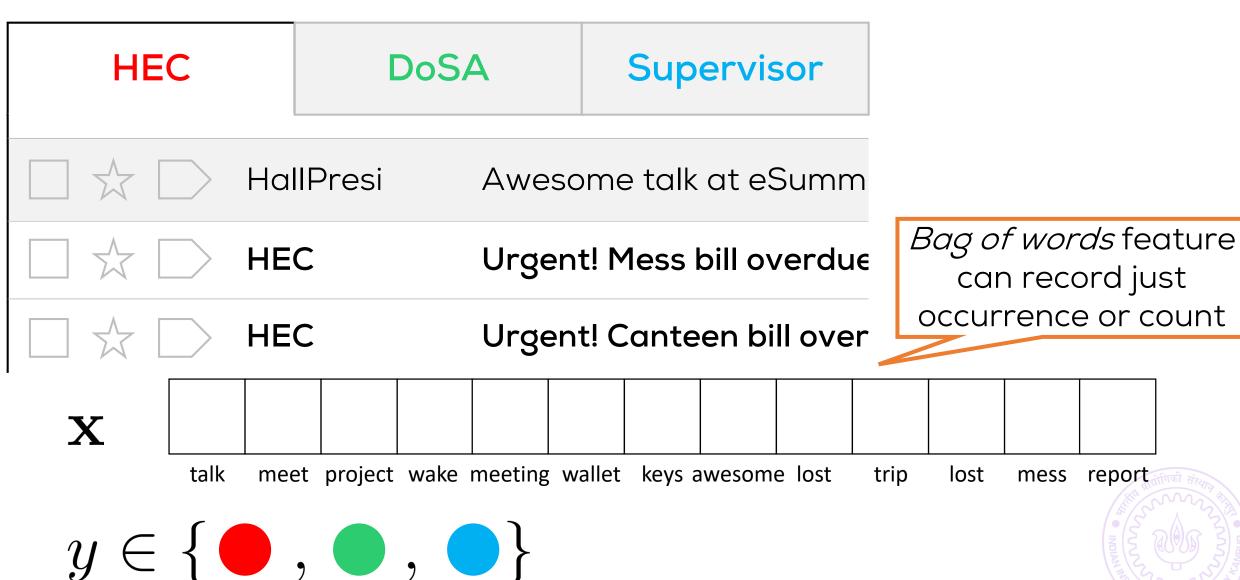




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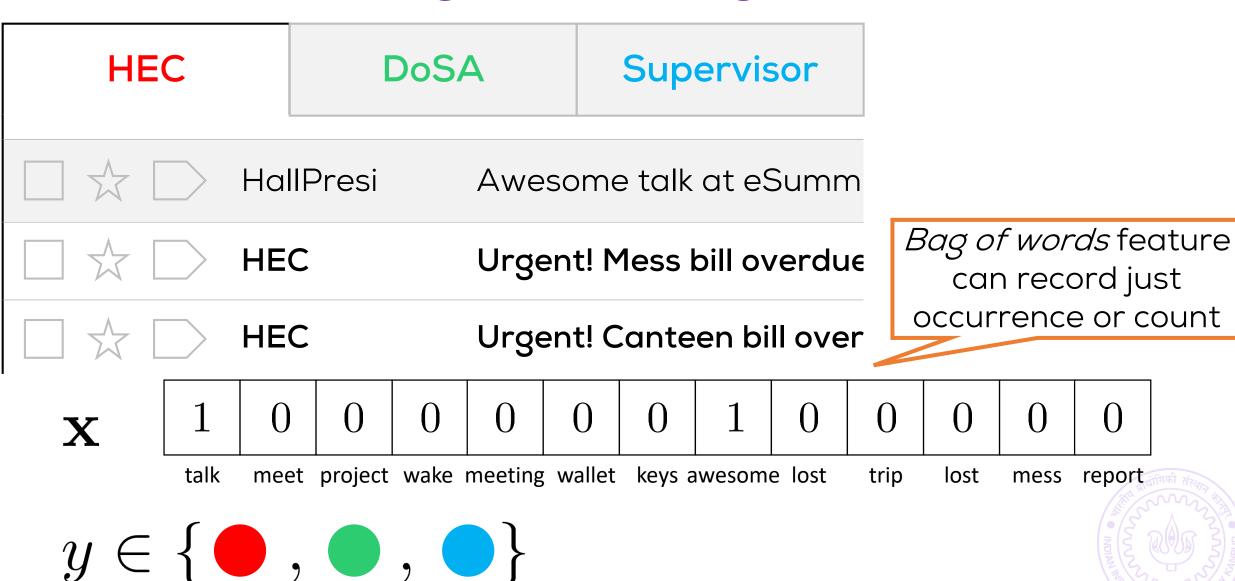


$$y \in \{ \bullet, \bullet, \bullet \}$$

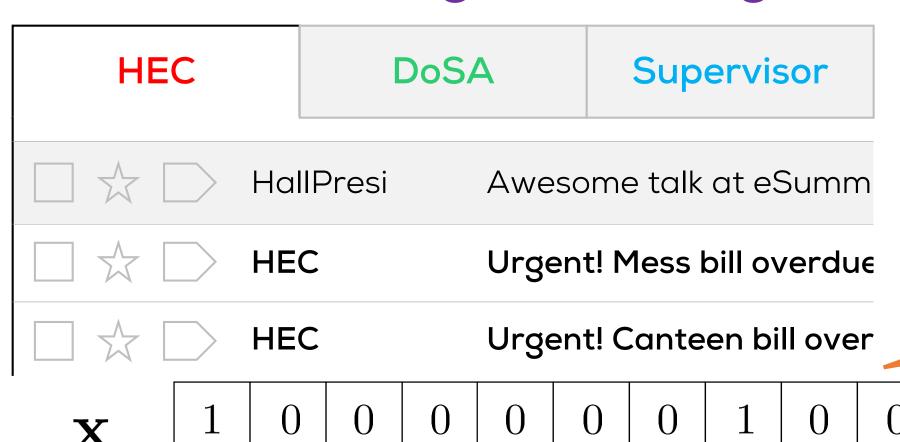


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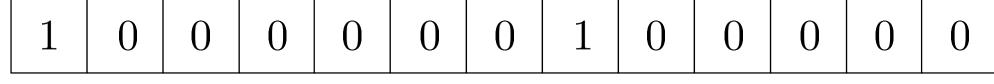
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Choice of words crucial - stemming, throw away articles etc

Bag of words feature can record just occurrence or count





talk meet project wake meeting wallet keys awesome lost trip lost mess report

$$y \in \{ \bullet, \bullet, \bullet \}$$

HEC DoSA Supervisor

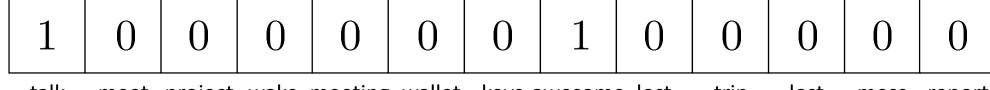
☐ ☆ ☐ HallPresi Awesome talk at eSumm
☐ ☆ ☐ HEC Urgent! Mess bill overdue
☐ ☆ ☐ HEC Urgent! Canteen bill over

Commonly used in NLP

Choice of words crucial
– stemming, throw
away articles etc

Bag of words feature can record just occurrence or count

 \mathbf{X}



talk meet project wake meeting wallet keys awesome lost trip lost mess report

$$y \in \{ \bullet, \bullet, \bullet \}$$

Commonly used in NLP HEC DoSA Supervisor Choice of words crucial - stemming, throw away articles etc HallPresi Awesome talk at eSumm Bag of words feature Urgent! Mess bill overdue HEC can record just occurrence or count **Urgent! Canteen bill over** HEC ()()0 talk meet project wake meeting wallet keys awesome lost trip lost mess report $y \in \{ \bullet, \bullet, \bullet, \bullet \}$ Usually very high dimensional

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Commonly used in NLP HEC **DoSA** Supervisor Choice of words crucial - stemming, throw away articles etc HallPresi Awesome talk at eSumm Bag of words feature Urgent! Mess bill overdue HEC can record just occurrence or count **Urgent! Canteen bill over** HEC ()()0 talk meet project wake meeting wallet keys awesome lost trip lost mess report $y \in \{ \bullet, \bullet, \bullet, \bullet \}$ Usually very high Usually very dimensional very sparse

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$$\mathbb{P}[\bullet] = \frac{|\#\text{emails from supervisor}|}{|\#\text{total emails}|}$$



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```
\mathbb{P}[\mathsf{awesome} = 1 \,|\, \bullet] = \frac{|\mathsf{#emails}\;\mathsf{from}\;\mathsf{sup}.\;\mathsf{with}\;\mathsf{"awesome"}|}{|\mathsf{#total}\;\mathsf{emails}\;\mathsf{from}\;\mathsf{supervisor}|}
```



$$\mathbb{P}[\bullet] = \frac{|\text{\#emails from supervisor}|}{|\text{\#total emails}|}$$

$$\mathbb{P}[\mathsf{awesome} = 1 \mid \bullet] = \frac{|\mathsf{#emails from sup. with "awesome"}|}{|\mathsf{#total emails from supervisor}|}$$

At test time ...



$$\mathbb{P}[\bullet] = \frac{|\text{\#emails from supervisor}|}{|\text{\#total emails}|}$$

$$\mathbb{P}[\mathsf{awesome} = 1 \mid \bullet] = \frac{|\mathsf{#emails} \; \mathsf{from} \; \mathsf{sup.} \; \mathsf{with} \; |\mathsf{awesome}||}{|\mathsf{#total} \; \mathsf{emails} \; \mathsf{from} \; \mathsf{supervisor}|}$$

At test time ...

$$\mathbb{P}[\mathbf{x}^t, \bullet] = \mathbb{P}[\bullet] \cdot \prod_{j=1}^{a} \mathbb{P}[\mathbf{x}_i^t | \bullet]$$



$$\mathbb{P}[\bullet] = \frac{|\#\text{emails from supervisor}|}{|\#\text{total emails}|}$$

$$\mathbb{P}[\text{awesome} = 1 \mid \bullet] = \frac{|\text{#emails from sup. with "awesome"}|}{|\text{#total emails from supervisor}|}$$

At test time ...

$$\mathbb{P}[awesome = 0 | \bullet]$$

$$= 1 - \mathbb{P}[awesome = 1 | \bullet]$$

$$\mathbb{P}[\mathbf{x}^t, \bullet] = \mathbb{P}[\bullet] \cdot \prod_{j=1}^{a} \mathbb{P}[\mathbf{x}_i^t | \bullet]$$



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 $\mathbb{P}[\mathbf{x}^{t}, \bullet] = \mathbb{P}[\bullet] \cdot \prod_{j=1}^{a} \mathbb{P}[\mathbf{x}_{i}^{t} | \bullet]$ $\hat{y}^{t} = \arg \max{\{\mathbb{P}[\mathbf{x}^{t}, \bullet], \mathbb{P}[\mathbf{x}^{t}, \bullet], \mathbb{P}[\mathbf{x}^{t}, \bullet]\}}$



$$\mathbb{P}[\bullet] = \frac{|\#\text{emails from supervisor}|}{|\#\text{total emails}|}$$

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$$\mathbb{P}[awesome = 0 | \bullet]$$

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$$\mathbb{P}[\mathbf{x}^t, \bullet] = \mathbb{P}[\bullet] \cdot \prod_{i=1}^{a} \mathbb{P}[\mathbf{x}_i^t | \bullet]$$

$$\hat{y}^t = \arg\max\{\mathbb{P}[\mathbf{x}^t, \bullet], \mathbb{P}[\mathbf{x}^t, \bullet], \mathbb{P}[\mathbf{x}^t, \bullet]\}$$



Will give the same result as

 $arg \max{\mathbb{P}[\bullet \mid \mathbf{x}^t], \mathbb{P}[\bullet \mid \mathbf{x}^t], \mathbb{P}[\bullet \mid \mathbf{x}^t]}$

App: Automatic Email Generator!

Class proportions

- Choose a category from {HEC, DoSA,Supervisor}
 - Toss a 3-sided "coin" aka categorical/multinoulii distribution using $\mathbb{P}[\hat{ullet}]$
 - Say we chose HEC
- ullet For each word in your dictionary of d words, toss a Bernoulli coin to decide whether to include that word in the mail or not
 - For $j \in [d]$, toss a coin that lands heads with probability $\mathbb{P}[x_j = 1 \mid \bullet]$
- Collect all words for which the toss landed heads
- Compose an email using only those words (and maybe a few articles, prepositions etc)

Already learnt from training data!

 Congratulations, you can now ask your HEC to stop sending you emails – you will generate them yourself!

Please give your Feedback

http://tinyurl.com/ml17-18afb

