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Systems 1

Tutorials in assembly language

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1 Numbers ...

1.1 Converting between number systems

Convert the following decimal numbers first to 16-bit binary and then to hexadecimal representation:

- a) 67 b) 49155 c) 65534

Convert the following 16-bit hexadecimal numbers first to binary and then to decimal representation:

- a) 1000 b) ABCD c) FFFF

1.2 Number spaces

How many different numbers can we write with this many bits?

- a) 8 b) 10 c) 16 d) 20 e) 32

How many bits do we need, to address:

- a) 14 B b) 64 KB c) 1 MB d) 100 MB e) 1 GB

Suppose we have a 16-bit addressing space. Divide this space into 4 blocks of equal sizes. Write down the first and the last address of each block. *We will write hexadecimal addresses with the prefix 0x.*

How many addresses are between 0x1000 and 0x2000 including the starting and the ending address?

We want to store 1000 numbers, each number at its own address, starting with the address 0x0200. What is the address of the last number?

1.3 Computer arithmetic

Calculate the sums of hexadecimal numbers:

- a) $A + B$ b) $A781 + 1942$ c) $A000 + 7000$

Suppose we operate with 16-bit numbers only. What is then the result of addition $A000 + 7000$?

In the 16-bit number space let $x = 0xA123$. Which number in that space is equivalent to $-x$, i.e. for which number $y = -x$ it holds $x + y = 0$?

2 Introduction to assembly language

Task 2.1 Explain the meaning and the function of all the registers of our simulated computer system.

Solution:

A, B, C, D General purpose registers for performing arithmetic logic operations.
IP *Instruction pointer* - memory location of the next instruction.
SP *Stack pointer* - memory location of the top of the stack
SR *Status register* - all status flags

Status flags:

M *Interrupt mask* - globally enables/disables interrupts.
C *Carry* - set when an overflow occurs after an arithmetic operation.
Z *Zero* - set when the result of the arithmetic operation is 0.
F *Fault* - set when there an error occurs during program execution.
H *Halt* - set after the program execution has stopped.

Task 2.2 Compile and run the following assembly program:

```
1 MOV A, 0x10
2 ADD A, 10
3 HLT
```

Write down and explain the compiled machine code. Trace the program step by step and explain its behavior.

Solution:

Compiler produced the following machine code: 06 00 00 10 14 00 00 0A 00.

Explanation:

MOV [06] A [00], 0x10 [00 10]
ADD [14] A [00], 10 [00 0A]
HLT [00]

The program moves hexadecimal number 10 to the 16-bit register *A* and adds to it decimal number 10.

Task 2.3 Move $AL \leftarrow 120$ and $BL \leftarrow 180$. Do the 8-bit and the 16-bit addition of those values. Explain the different outcomes.

Solution:

```
1 ; 8-bit addition           ; 16-bit addition
2 MOV AL, 120               MOV AL, 120
3 MOV BL, 180               MOV BL, 180
4 ADDB AL, BL               ADD A, B
5 HLT                      HLT
```

8-bit addition results in $A = 44$ and 16-bit in $A = 300$. With 8-bit addition the overflow occurs and the carry bit (C) is set.

Task 2.4 Two 8-bit values x and y are stored in the 16-bit register A , so that $AH = x$ and $AL = y$. Write a program that moves these values so that $A = x$ and $B = y$. Use AND masking.

Solution:

```
1 MOV B, A
2 SHR A, 8
3 AND B, 0x00FF
```

Prepare for the exam:

- 16-bit registers A and B hold 8-bit values x and y respectively. Write a program that moves these values so that $AH = x$ and $AL = y$.
- Do the same thing by using only 16-bit instructions and OR operation.
- What does the following program in machine code do: 0x10 0x10 0x00 0x41?
- Run the below assembly program and observe the status register after the execution has finished. Explain why each status bit has changed.

```
1 MOV A, 0xFF00
2 ADD A, 0x0100
3 HLT
```


3 Memory addressing and variables

Review the different addressing modes listed in Appendix A.3. Remember:

- Square brackets [] represent memory access.
- Every CPU instruction can make at most one access to memory.

Task 3.1 What is the difference between programs:

```
1 MOV D, 100
2 MOV A, D
```

and

```
1 MOV D, 100
2 MOV A, [D]
```

Solution: The first program loads decimal value 100 into register *A*, while the second program loads whatever resides on the memory address 100 (0x64).

Task 3.2 Write the hexadecimal value 0xABCD to memory address 0x0100. Which addresses store which parts of this value? Now write the 8-bit number 0x33 to memory address 0x0102. Write a program that adds the value on address 0x0102 to the value on address 0x0100.

Solution:

```
1 MOV [0x0100], 0xABCD ; 16-bit value x
2 MOVB [0x0102], 0x33  ; 8-bit value y
3
4 ; Implementation of x = x + y
5 MOV A, [0x0100]      ; Get the value of variable x.
6 MOV B, 0             ; We use B to convert y to a 16-bit value.
7 MOVB BL, [0x0102]    ; Move y to the lower byte of B.
8 ADD A, B             ; x + y -> A as 16-bit addition.
9 MOV [0x0100], A      ; Store the result x + y to x.
10 HLT
```

Address 0x0100 stores the value 0xAB and address 0x0101 stores the value 0xCD.

Task 3.3 Define a 16-bit variable *x* with initial value 0xABCD. Then increase the value of this variable by 3. Define the variable *x* in the following ways:

- a) as a fixed memory address 0x0100,
- b) as a label below the program code,
- c) as a label above the program code,
- d) as a label at memory address 0x0100.

Solutions:

a) As a fixed memory address 0x0100.

```

1 ; The programmer decides that value x is stored at memory address 0x0100.
2 MOV [0x0100], 0xABCD ; Set x = 0xABCD
3 ; The following three lines implement x = x + 3.
4 MOV A, [0x0100] ; Get the value of x.
5 ADD A, 3 ; Add 3 to the value.
6 MOV [0x0100], A ; Store the new value back to x.
7 HLT

```

b) As a label below the program code.

```

1 ; The programmer does not care about the actual address of variable x,
2 ; let the assembler determine it.
3 MOV A, [x] ; Get the value from address x.
4 ADD A, 3 ; Add 3 to the value.
5 MOV [x], A ; Store the new value back to address x.
6 HLT ; Must (!) stop before data begins.
7 x: DW 0xABCD ; Let label x determine the memory address after HLT.

```

c) As a label above the program code.

```

1 ; Let variable x reside before the program code.
2 JMP main
3 x: DW 0xABCD ; define and initialize x = 0xABCD
4
5 ; let label main determine the address of the MOV opcode below.
6 main:
7     MOV A, [x] ; Get the value from address x.
8     ADD A, 3 ; Add 3 to the value.
9     MOV [x], A ; Store the new value back to address x.
10    HLT

```

d) As a label at memory address 0x0100.

```

1 ; Let variable x reside at a specific address in memory.
2 MOV A, [x]
3 ADD A, 3
4 MOV [x], A
5
6 ; Instruction to the compiler where in memory to compile the code below.
7 ORG 0x0100
8 x: DW 0xABCD

```

Task 3.4 Define 16-bit variables x , y , and z . Write a program that computes $z = 3z - (x + y)/2$.

Solution:

```
1 JMP main
2 x: DW 3 ; define x = 1
3 y: DW 5 ; define y = 3
4 z: DW 7 ; define z = 7
5
6 main:
7     ; z = z - (x + y)
8     MOV A, [z] ; A <- z
9     MUL 3      ; A <- 3*z
10    MOV B, [x] ; B <- x
11    ADD B, [y] ; B <- x + y
12    SHR B, 1   ; B <- (x + y)/2
13    SUB A, B   ; A <- 3*z - (x + y)/2
14    MOV [z], A ; z <- 3*z - (x + y)/2
15    HLT
```

Prepare for the exam:

- Define variables x and y with the initial values of your choice. Write a program that switches the values of x and y .
- Write a program that computes $z = 16 \cdot (2x - y)$. Use bit shifting for multiplication.
- Write a program that computes $z = x^2 - y^2$. Use instruction `MUL` to square a value.

4 Conditional statements

Task 4.1 Define 16-bit variables x and y with some initial values. Subtract $x - y$. How does the subtraction affect the status flags if:

a) $x > y$,

b) $x = y$,

c) $x < y$.

Solution:

```
1 JMP main:
2 x: DW 7
3 y: DW 5
4
5 main:
6     MOV A, [x]
7     SUB A, [y]
8     HLT
```

a) $Z = 0, C = 0$,

b) $Z = 1, C = 0$,

c) $Z = 0, C = 1$.

Task 4.2 What does the **CMP** instruction do and what is the advantage of using **CMP** instead of **SUB**?

Solution: The instruction **CMP** performs the same arithmetic operation as instruction **SUB**, but alters only the status register. When using **CMP**, we keep the values x and y .

Task 4.3 Write a program that compares values x and y . How are status flags **C** and **Z** affected for every possible comparison relation? Which conditional jump instructions are associated with what relation?

Solution:

```
1 JMP main:
2 x: DW 7
3 y: DW 5
4
5 main:
6     MOV A, [x]
7     CMP A, [y] ; Use CMP instead of SUB.
8     HLT
```

| Condition | Z | C | Jump instruction |
|------------|---|---|------------------|
| $x = y$ | 1 | - | JZ, JE |
| $x \neq y$ | 0 | - | JNZ, JNE |
| $x > y$ | 0 | 0 | JA, JNBE |
| $x \geq y$ | - | 0 | JNC, JAE, JNB |
| $x < y$ | - | 1 | JC, JB, JNAE |
| $x \leq y$ | 1 | - | JNA, JBE |
| | - | 1 | |

Task 4.4 Implement the following conditional statement in assembly language:

```
if (x < y)
    x = x + 1;
```

Solution: In assembly, it is sometimes the easier to negate the condition and skip the if body when the negated condition is true.

```
1 JMP main:
2 x: DW 7
3 y: DW 5
4
5 main:
6     MOV A, [x]
7     CMP A, [y]
8     JAE continue    ; if (x >= y) skip the if body
9     INC A
10    MOV [x], A
11 continue:
12    HLT
```

Task 4.5 Implement the following conditional statement in assembly language:

```
if (x < y) z = y;
else z = x;
```

Solution:

```
1 main:
2     MOV A, [x]
3     MOV B, [y]
4     CMP A, B
5     JAE else        ; if not (x < y) go to else
6     MOV [z], B      ; z = y (if body)
7     JMP continue
8 else:
9     MOV [z], A      ; z = x (else body)
10 continue:
11    HLT              ; exit the if statement
```

Task 4.6 Implement the following conditional statement in assembly language:

```
if (x >= 100 && x < 200)
    x = x / 2;
```

Solution: We may rewrite the above condition as:

```
if (x < 100 || x >= 200) {
}
else {
    x = x / 2;
}
```

And implement it as:

```
1 main:
2     MOV A, [x]
3     CMP A, 100 ; if (x < 100) don't do it
4     JC out
5     CMP A, 200 ; if (x >= 200) don't do it
6     JNC out
7     SHR A, 1 ; do it
8     MOV [x], A ; x = x / 2
9 out:
10    HLT
```

Prepare for the exam:

Implement the following conditions in assembly language:

- a) if (x + 1 > y)
 x = x - 1;
- b) if (x % 2 == 0)
 x = x / 2;
- c) if (x == 0 || x == 2 || x > y) {
 x = x - y;
 }
 else {
 if (x < y)
 x = x + y;
 }

5 Loops

Task 5.1 Implement the following *while* loop in assembly language:

```
int i = 0;
while (i < 10) {
    i = i + 1;
}
```

Consider the possibilities for loop optimization.

Solution:

```
1 JMP main
2 i: DW 0          ; i = 0
3 main:
4     MOV A, [i] ; Get the value of i.
5 while:
6     CMP A, 10  ; Compare i with 10.
7     JAE break  ; If above or equal, end the loop
8     MOV A, [i] ; Get the value of i.
9     INC A      ; i = i + 1
10    MOV [i], A ; Store the new value of i.
11    JMP while  ; Loop.
12 break:
13    HLT
```

The loop can be optimized by keeping the value of *i* in a register:

```
1 JMP main
2 i: DW 0          ; i = 0
3 main:
4     MOV A, [i] ; Get the value of i.
5 while:
6     CMP A, 10  ; Compare i with 10.
7     JAE break  ; If above or equal, end the loop
8     INC A      ; i = i + 1
9     JMP while  ; Loop.
10 break:
11    MOV [i], A ; Store the last value of i.
12    HLT
```

Potential problems could occur if variable *i* was shared between different threads. But because we use a single-thread system, we don't need to be careful about such issues.

Task 5.2 Implement an optimized *for* loop in assembly language that sums the numbers from 1 to 10.

Solution: Let us first write a solution in C:

```
int sum = 0;
for (int i = 1; i <= 10; i++) {
    sum = sum + i;
}
```

Because *i* is a local variable (visible only within the loop), we can optimize the code by storing *i* only within a register and write the value of *sum* to memory after the loop is finished.

```
1 JMP main
2 sum: DW 0
3 main:
4     MOV A, 0      ; i = 0
5     MOV B, [sum]  ; Get the value of sum.
6 for:
7     CMP A, 10     ; Compare i with 10.
8     JA break      ; if i > 10, finish the loop.
9     ADD B, A      ; sum = sum + i
10    INC A         ; i++
11    JMP for
12 break:
13    MOV [sum], B   ; Store the value of sum.
14    HLT
```

Task 5.3 Write an assembly program that computes the factorial of *n*. Suppose that multiplication is not possible on the system.

Solution: In C, we could write this program as follows:

```
int f = 1;
for (int i = 2; i <= n; i++) { // factorial loop
    f = f * i;
}
```

But because multiplication is not allowed, we implement it by addition:

```
int f = 1;
for (int i = 2; i <= n; i++) { // factorial loop
    int fi = 0;
    for (int j = i; j > 0; j--) { // multiplication loop
        fi = fi + f;
    }
    f = fi;
}
```

We then rewrite the solution in assembly:

```

1  JMP main
2  n: DW 5           ; The input parameter.
3  f: DW 1           ; The result: f = n!
4  main:
5      MOV B, [f]     ; We often need this value.
6      MOV A, 2       ; int i = 2
7  factloop:
8      CMP A, [n]     ; Has i surpassed n?
9      JA endfactloop ; yes, finish.
10     MOV C, 0       ; int fi = 0
11     MOV D, 0       ; int j = 0
12  multloop:
13     CMP D, A       ; Compare j and i.
14     JAE endmultloop ; If j reached i, multiplication is done.
15     ADD C, B       ; fi = fi + f
16     INC D          ; j++
17     JMP multloop
18  endmultloop:
19     MOV B, C       ; f = fi
20     INC A          ; i++
21     JMP factloop
22  endfactloop:
23     MOV [f], B     ; Store the value of f.
24     HLT

```

Prepare for the exam:

- Use the MUL instruction to simplify the assembly program that computes the factorial.
- Write a program that determines if a given integer is divisible by 3. The idea is to subtract the constant 3 from the given number until that number is reduced below 3. If the result is 0, the number is divisible by 3.
- Write a program that counts how many bits in register A are set to 1. This can be done by shifting left the register 16 times while checking the C flag for the value of the discarded bit.
- Write a program that determines how much memory is currently free. The idea is to read every byte of memory between the addresses 0x0000 and 0xFFFF, and count the number of zero bytes after the last non-zero byte.

6 Stack and Functions

6.1 Stack

- *Stack* is a linear data structure that allows direct access only to the last input element.
- CPU implements a stack in memory to allow function calls. It is also very handy for programmers to temporary store data.
- CPU stack instructions are: PUSH, POP, PUSHB, POPB.
- Make sure you correctly match PUSH and POP instructions.

Task 6.1 Initialize the stack. Switch values of registers A and B without using any other register.

Solution:

```
1 MOV A, 1      ; An initial value of A.
2 MOV B, 2      ; An initial value of B.
3 MOV SP, 0xFFFF ; Initialize the stack pointer.
4
5 ; One way to switch values between A and B
6 PUSH A        ; Push the value of A onto stack.
7 MOV A, B      ; Move the value of B to A.
8 POP B         ; Pop the previous value of A into B.
9
10 ; Another way to switch values between A and B
11 PUSH A        ; Push the value of A onto stack.
12 PUSH B        ; Push the value of B onto stack.
13 POP A         ; Pop the previous value of B into A.
14 POP B         ; Pop the previous value of A into B.
15 HLT
```

Task 6.2 Push 100 16-bit numbers to stack and examine the part of the memory where the numbers are being stored. How many can you push to the stack before you run into troubles? What can happen?

Solution:

```
1     MOV SP, 0xFFFF ; Initialize the stack pointer.
2     MOV A, 1       ; Start counting.
3 loop:
4     CMP A, 100      ; When counter exceeds 100
5     JA exit         ; exit.
6     PUSH A          ; Push the current value on stack.
7     INC A           ; Increase the counter.
8     JMP loop        ; Next iteration.
9 exit:
10    HLT
```

Our program takes 24 bytes, so we are left with 4072 bytes of free memory. This means we can store up to 2036 16-bit numbers before we run out of memory. If we try to store more than that, the stack starts overwriting our program. On a modern computer system, the operating system would prevent this from happening and throw a *stack overflow* exception.

6.2 Functions

- To call a function use instruction **CALL** (never **JMP**).
- A function must always return by executing the instruction **RET**.
- Parameters and return values can be passed either through registers or stack. Avoid passing parameters through fixed memory addresses or global variables.

Task 6.3 Write a function that pops two 16-bit numbers from the stack and pushes their sum back to the stack. Demonstrate the use of this function.

Solution:

```

1  JMP main
2
3  add:
4      POP D          ; Pop the return address.
5      POP B          ; Pop the second summand.
6      POP A          ; Pop the first summand.
7      ADD A, B       ; Add the summands.
8      PUSH A         ; Push the sum.
9      PUSH D         ; Push back the returned address.
10     RET            ; Return from function.
11
12 main:
13     MOV SP, 0xFFFF ; Initialize the stack pointer.
14     PUSH 5          ; Push the first summand to stack.
15     PUSH 3          ; Push the second summand to stack.
16     CALL add        ; Call the function add.
17     POP A           ; Retrieve the returned sum.
18     HLT

```

Task 6.4 Write a function `max(a, b)`, that returns the greater of the two given integers. Let the function receive the parameters *a* and *b* through registers A and B respectively.

Solution:

```

1  JMP main
2  z: DW 0             ; int z = 0;
3
4  max:
5      CMP A, B        ; If A < B then
6      JB returnb      ; return B

```

```

7      RET                ; else the result is already in register A.
8  returnb:
9      MOV A, B           ; Move the result to register A,
10     RET                ; and return it.
11
12  main:
13     MOV SP, 0xFFFF     ; Initialize the stack pointer.
14     MOV A, 2            ; Set the first argument.
15     MOV B, 5            ; Set the second argument.
16     CALL max            ; Call z = max(2, 5).
17     MOV [z], A          ; Store the returned value.
18     HLT

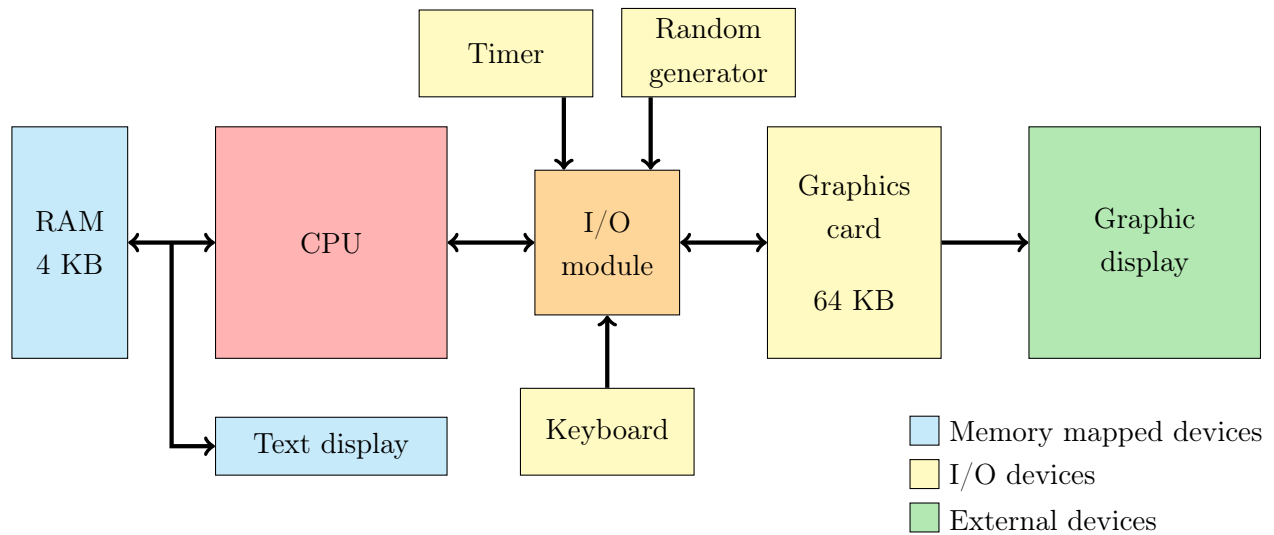
```

Prepare for the exam:

- Write a function `add(x1, x2, x3, ...)` that can receive any number of summands x_1, x_2, \dots, x_n and returns their sum in register A. Let the number of summands n be received in register A and all the summands on stack.
- Write a function `sign(x)` that returns the sign of the given 16-bit signed integer x , i.e. 1 if the number is positive, -1 if it is negative, and 0 if it is 0. Suppose that x is in the two's complement format.
- Write a function `abs(x)` that returns the absolute value of the given 16-bit signed integer x . Suppose that x is in the two's complement format.
- Write a function `fib(n)` that returns the n -th Fibonacci number.
- Write a function `isprime(x)` that checks if the given number x is prime. A number is a prime number if it is not divisible by any number between 2 and $n - 1$. You may check divisibility by first dividing (DIV) the number and then multiplying (MUL) it back. Write another function `primes(n)` that returns all prime numbers between 2 and n . You may return all the numbers through stack and the number of returned values through a register.

A Architecture of the simulated system

A.1 System architecture



A.2 CPU registers

16-bit registers:

| Register | Description | Index |
|----------|--------------------------|-------|
| A | General purpose register | 0 |
| B | General purpose register | 1 |
| C | General purpose register | 2 |
| D | General purpose register | 3 |
| SP | Stack Pointer | 4 |
| IP | Instruction Pointer | 5 |
| SR | Status Register | 6 |

8-bit registers:

| Register | Description | Index |
|----------|---------------------------|-------|
| AH | Higher part of register A | 7 |
| AL | Lower part of register A | 8 |
| BH | Higher part of register B | 9 |
| BL | Lower part of register B | 10 |
| CH | Higher part of register C | 11 |
| CL | Lower part of register C | 12 |
| DH | Higher part of register D | 13 |
| DL | Lower part of register D | 14 |

A.3 Addressing modes

| Addressing mode | Abbreviation | Example |
|-----------------|--------------|--------------|
| Immediate | IMD | ADD A, 100 |
| Register | REG | ADD A, B |
| Direct | DIR | ADD A, [100] |
| Indirect | IND | ADD A, [B] |

A.4 Instruction set

CPU instruction format:

| | | |
|--------|----------------------|----------------------|
| opcode | operand 1 (optional) | operand 2 (optional) |
|--------|----------------------|----------------------|

CPU instruction set:

| | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | A | B | C | D | E | F |
|---|-----------------|-----------------|----------------|----------------|----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| 0 | HLT | MOV REG,REG | MOV REG,IND | MOV REG,DIR | MOV IND,REG | MOV DIR,REG | MOV REG,IMD | MOV IND,IND | MOV DIR,IND | MOVB REG,REG | MOVB REG,IND | MOVB REG,DIR | MOVB IND,REG | MOVB DIR,REG | MOVB REG,IMD | MOVB IND,IND |
| 1 | MOVB DIR,IND | ADD REG,REG | ADD REG,IND | ADD REG,DIR | ADD REG,IMD | ADDB REG,REG | ADDB REG,IND | ADDB REG,DIR | ADDB REG,IMD | SUB REG,REG | SUB REG,IND | SUB REG,DIR | SUB REG,IMD | SUBB REG,REG | SUBB REG,IND | SUBB REG,DIR |
| 2 | SUBB REG,IMD | INC REG | INCB REG | DEC REG | DECB REG | CMP REG,REG | CMP REG,IND | CMP REG,DIR | CMP REG,IMD | CMPB REG,REG | CMPB REG,IND | CMPB REG,DIR | CMPB REG,IMD | JMP IND | JMP DIR | JC IND |
| 3 | JC DIR | JNC IND | JNC DIR | JZ DIR | JZ IND | JNZ IND | JNZ DIR | JA IND | JA DIR | JNA IND | JNA DIR | PUSH REG | PUSH IMD | | | PUSHB REG |
| 4 | PUSHB IMD | | | POP REG | POPB REG | CALL IND | CALL DIR | RET | MUL REG | MUL IND | MUL DIR | MUL IMD | MULB REG | MULB IND | MULB DIR | MULB IMD |
| 5 | DIV REG | DIV IND | DIV DIR | DIV IMD | DIVB REG | DIVB IND | DIVB DIR | DIVB IMD | AND REG,REG | AND REG,IND | AND REG,DIR | AND REG,IMD | ANDB REG,REG | ANDB REG,IND | ANDB REG,DIR | ANDB REG,IMD |
| 6 | OR REG,REG | OR REG,IND | OR REG,DIR | OR REG,IMD | ORB REG,REG | ORB REG,IND | ORB REG,DIR | ORB REG,IMD | XOR REG,REG | XOR REG,IND | XOR REG,DIR | XOR REG,IMD | XORB REG,REG | XORB REG,IND | XORB REG,DIR | XORB REG,IMD |
| 7 | NOT REG | NOTB REG | SHL REG,REG | SHL REG,IND | SHL REG,DIR | SHL REG,IMD | SHLB REG,REG | SHLB REG,IND | SHLB REG,DIR | SHLB REG,IMD | SHR REG,REG | SHR REG,IND | SHR REG,DIR | SHR REG,IMD | SHRB REG,REG | SHRB REG,IND |
| 8 | SHRB REG,DIR | SHRB REG,IMD | CLI | STI | IRET | | | IN REG | IN IND | IN DIR | IN IMD | OUT REG | OUT IND | OUT DIR | OUT IM | |

A.5 Memory map

| Address range | Component |
|-----------------|--|
| 0x0000 – 0x0FFF | RAM (4 KB) |
| 0x1000 – 0x101F | Text display (2 lines × 16 ASCII characters) |

A.6 Input / Output module

I/O Registers:

| Register | Description | Index |
|------------|--|-------|
| IRQMASK | Enable/Disable specific interrupt requests | 0 |
| IRQSTATUS | Currently requested interrupts | 1 |
| IRQEIO | Clear a specific interrupt request | 2 |
| TMRPRELOAD | The initial timer value | 3 |
| TMRCOUNTER | The current timer value | 4 |
| KBDSTATUS | Keyboard status (a keypress has been detected) | 5 |
| KBDATA | The data received from the keyboard | 6 |
| VIDMODE | Graphics card mode | 7 |
| VIDADDR | Address in the VRAM data | 8 |
| VIDDATA | Data at the VRAM address VIDADDR | 9 |
| RNDGEN | A randomly generated number | 10 |

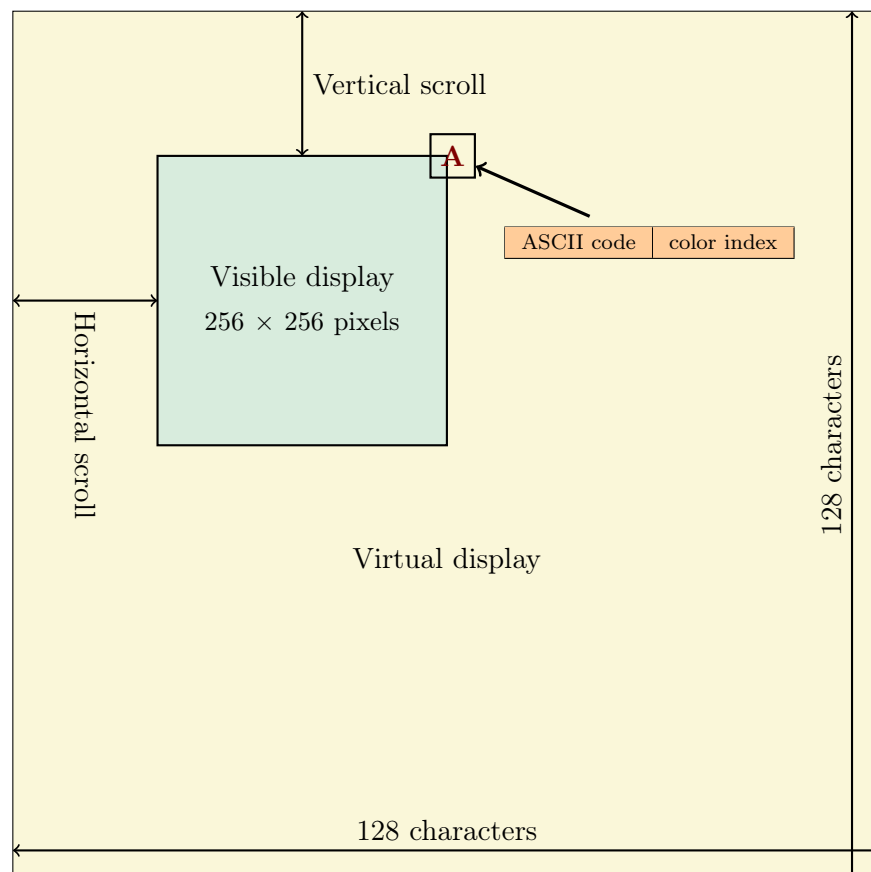
A.7 Graphics card

| VIDMODE | Video mode | Description |
|---------|------------|---|
| 0 | DISABLED | Graphics card is disabled (default). |
| 1 | TEXT | Display text and custom-defined tiles. |
| 2 | BITMAP | Display individual pixels. |
| 3 | CLEAR | Clears the display. It works in both graphic modes. |
| 4 | RESET | Resets and disables the graphics card. |

A.7.1 Text mode (VIDMODE = 1)

Text display properties:

- The size of each character is 16×16 pixels.
- Every displayed character has two properties: ASCII code (8-bit) and color index (8-bit).
- Default shape definitions of all 256 characters are stored in VRAM at addresses `0x8000 – 0x9FFF` and can be overwritten. By resetting the graphics card, the default values are restored.
- The standard RRRGGGBB palette is stored in VRAM at addresses `0xA000 – 0xA2FF` (3 bytes/color) and can be overwritten. By resetting the graphics card, the default values are restored.
- The size of the virtual display is 128×128 characters, but only a display window of 256×256 pixels is visible on the screen. The display window can be moved to achieve smooth scrolling effect.
- Eight characters can be placed on the visual display at any pixel position (256×256), independently of the virtual display content and scrolling state (sprite graphics).



VRAM Usage in text mode:

| VRAM location | Size | Usage |
|-----------------|---------|---|
| 0x0000 – 0x7FFF | 32 KB | Virtual display area (128 × 128 characters, 2 bytes/character). |
| 0x8000 – 0x9FFF | 8 KB | Character set definition (256 characters, 32 bytes/character). |
| 0xA000 – 0xA2FF | 0.75 KB | Color palette (256 colors, 3 bytes/color). |
| 0xA300 – 0xA301 | 2 B | Background color (color index 0 – 255, address 0xA300 is unused). |
| 0xA302 – 0xA303 | 2 B | Horizontal scroll (display window x-offset in pixels). |
| 0xA304 – 0xA305 | 2 B | Vertical scroll (display window y-offset in pixels). |
| 0xA306 – 0xA309 | 4 B | Sprite 1 (character, color, x, y). |
| 0xA30A – 0xA30D | 4 B | Sprite 2 (character, color, x, y). |
| 0xA30E – 0xA311 | 4 B | Sprite 3 (character, color, x, y). |
| 0xA312 – 0xA315 | 4 B | Sprite 4 (character, color, x, y). |
| 0xA316 – 0xA319 | 4 B | Sprite 5 (character, color, x, y). |
| 0xA31A – 0xA31D | 4 B | Sprite 6 (character, color, x, y). |
| 0xA31E – 0xA321 | 4 B | Sprite 7 (character, color, x, y). |
| 0xA322 – 0xA325 | 4 B | Sprite 8 (character, color, x, y). |
| 0xA326 – 0xFFFF | | Free memory (23754 bytes). |

Character shape data (32 bytes):

[illegible]

Virtual display area:

| | | | |
|---------------|------------|-------------|---------|
| character 0 | ASCII code | color index | } 32 kB |
| character 1 | ASCII code | color index | |
| ⋮ | ⋮ | | |
| character n | ASCII code | color index | |

Character set definition:

| | | |
|----------------|----------------|--------|
| ASCII code 0 | shape data 0 | } 8 KB |
| ASCII code 1 | shape data 1 | |
| ⋮ | ⋮ | |
| ASCII code 255 | shape data 255 | |

Color palette definition:

| | | | | |
|-----------|-------------|---------------|--------------|-------------|
| color 0 | red (8-bit) | green (8-bit) | blue (8-bit) | } 765 bytes |
| color 1 | red (8-bit) | green (8-bit) | blue (8-bit) | |
| ⋮ | ⋮ | | | |
| color 255 | red (8-bit) | green (8-bit) | blue (8-bit) | |

Sprite data:

| | | | | |
|----------|------------|-------|---|---|
| sprite 1 | ASCII code | color | x | y |
| sprite 2 | ASCII code | color | x | y |
| ⋮ | ⋮ | | | |
| sprite 8 | ASCII code | color | x | y |

} 32 bytes

A.7.2 Bitmap mode (VIDMODE = 2)

The entire 64 KB VRAM is used to display a bitmap image (256×256 pixels). The standard 8-bit color palette RRRGGGBB is used, which cannot be redefined.