R



آنچه گذشت

پیادهسازی mutex

Mutex Lock Operations

- Lock (*mutex*)
 - Acquire the lock if it is free ... and continue
 - Otherwise wait until it can be acquired
- Unlock (*mutex*)
 - Release the lock
 - If there are waiting threads wake one up

Peterson's Algorithm for Thread i

```
while (true) {
  flag[i] = true;
  turn = j;
  while (flag[j] \&\& turn = = j);
     /* critical section */
  flag[i] = false;
  /* remainder section */
```

Test-and-Set-Lock (TSL) Instruction

- ☐ Test-and-set-lock does the following *atomically*:
 - Get the (old) value
 - Set the lock to TRUE
 - Return the old value

If the returned value was FALSE...

■ Then you got the lock!!!

If the returned value was TRUE...

Then someone else has the lock (so try again later)

Implementing a Mutex With TSL

```
1 repeat
2 while(TSL(mylock))
3    no-op;
4 critical section
5 mylock = FALSE;
6 remainder section
7 until FALSE
Unlock (mylock)
```

- Note that processes are busy while waiting
 - this kind of mutex is called a spin lock

Busy Waiting

- Also called polling or spinning
 - The thread consumes CPU cycles to evaluate when the lock becomes free!
- Problem on a single CPU system...
 - A busy-waiting thread can prevent the lock holder from running & completing its critical section & releasing the lock!
 - time spent spinning is wasted on a single CPU system
 - Why not block instead of busy wait ?

Concurrency in the Kernel

Solution 1: Disable interrupts during critical sections

- Ensures that interrupt handling code will not run
- ... but what if there are multiple CPUs?

Solution 2: Use mutex locks based on TSL for critical sections

 Ensures mutual exclusion for all code that follows that convention

Disabling interrupts is not enough on MPs...

Disabling interrupts during critical sections

- Ensures that interrupt handling code will not run
- But what if there are multiple CPUs?
- A thread on a different CPU might make a system call which invokes code that manipulates the ready queue
- Disabling interrupts on one CPU didn't prevent this!

■ Solution: use a mutex lock (based on TSL)

- Ensures mutual exclusion for all code that uses it

Mutex is not enough

■ Interrupt inside interrupt handler

جلسهی جدید

سمافور و مسائل کلاسیک همروندی

مسئلهی نویسنده، خواننده

The Producer-Consumer Problem

- An example of the pipelined model
 - One thread produces data items
 - Another thread consumes them
- Use a bounded buffer between the threads
- The buffer is a shared resource
 - Code that manipulates it is a critical section
- Must suspend the producer thread if the buffer is full
- Must suspend the consumer thread if the buffer is empty

Is This Solution Correct?

```
thread consumer {
thread producer {
                                            while(1){
    while(1){
                                              while (count==0) {
      // Produce char c
      while (count==n) {
                                               no_op
        no op
                                              c = buf[OutP]
                                             OutP = OutP + 1 \mod n
      buf[InP] = c
                                              count--
      InP = InP + 1 \mod n
                                             // Consume char
      count++
Global variables:
    char buf[n]
    int InP = 0 // place to add
    int OutP = 0 // place to get
    int count
```

This Code is Incorrect!

- The "count" variable can be corrupted:
 - Increments or decrements may be lost!
 - Possible Consequences:
 - Both threads may spin forever
 - Buffer contents may be over-written
- What is this problem called?

This Code is Incorrect!

- What is this problem called?
- Race Condition
- Code that manipulates count must be made into a ??? and protected using ???

This Code is Incorrect!

- What is this problem called?
- Race Condition
- Code that manipulates count must be made into a *critical section* and protected using *mutual exclusion*

More Problems With This Code

- What if buffer is full?
 - Producer will busy-wait
- What if buffer is empty?
 - Consumer will busy-wait
- We need a solution based on blocking!

A Solution Based On Blocking

```
0 thread consumer {
1   while(1) {
2    if(count==0) {
3       sleep(empty)
4    }
5    c = buf[OutP]
6    OutP = OutP + 1 mod n
7    count--;
8    if (count == n-1)
9       wakeup(full)
10       // Consume char
11   }
12 }
```

```
Global variables:

char buf[n]

int InP = 0 // place to add

int OutP = 0 // place to get

int count
```

Use a Mutex to Fix The Problem

```
0 thread consumer {
1   while(1) {
2    if(count==0) {
3       sleep(empty)
4    }
5    c = buf[OutP]
6    OutP = OutP + 1 mod n
7    count--;
8    if (count == n-1)
9       wakeup(full)
10       // Consume char
11   }
12 }
```

```
Global variables:

char buf[n]

int InP = 0 // place to add

int OutP = 0 // place to get

int count
```

Problems

- 1. Sleeping while holding the mutex causes deadlock!
- 2. Releasing the mutex then sleeping opens up a window during which a context switch might occur ... again risking deadlock
- 3. How can we release the mutex and sleep in a single atomic operation?

We need a more powerful synchronization primitive

Semaphores

An abstract data type that can be used for condition synchronization and mutual exclusion

What is the difference between mutual exclusion and condition synchronization?

Semaphores

- Condition synchronization
 - wait until condition holds before proceeding
 - signal when condition holds so others may proceed
- Mutual exclusion
 - only one at a time in a critical section

Semaphores

- An abstract data type
 - containing an integer variable (S)
 - Two operations: Wait (S) and Signal (S)
- Alternative names for the two operations
 - Wait(S) = Down(S) = P(S)
 - Signal(S) = Up(S) = V(S)
- Blitz names its semaphore operations Down and Up

Classical Definition

```
Down (S)
        while S <= 0 do noop; /* busy wait!
  */
        S = S - 1;
                            /* S >= 0 */
Up(S)
        S = S + 1;
```

Problems With The Definition

- Waiting threads hold the CPU
 - Waste of time in single CPU systems
 - Required preemption to avoid deadlock

Blocking Semaphores

Semaphore S has a value, S.val, and a thread list, S.list.

```
Down (S)
     S.val = S.val - 1
     If S.val < 0
                                                /* negative value of S.val */
         { add calling thread to S.list; /* is # waiting threads */
                                                          /* sleep */
                    block;
<u>Up (S)</u>
     S.val = S.val + 1
     If S.val \le 0
         { remove a thread T from S.list;
                    wakeup (T);
```

Implementing Semaphores

■ Down () and Up () are assumed to be atomic

How can we ensure that they are atomic?

Implementing Semaphores

- Implement Down() and Up() as system calls?
 - How can the kernel ensure Down() and Up() are completed atomically?
 - Same solutions as before (disable interrupts, or use TSL-based mutex)

Semaphores With Disabling

```
struct semaphore {
    int val;
    list L;
}
```

```
Down(semaphore sem)
  DISABLE_INTS
    sem.val--
    if (sem.val < 0) {
       add thread to sem.L
       sleep(thread)
    }
  ENABLE_INTS</pre>
```

```
Up(semaphore sem)
DISABLE_INTS
sem.val++
if (sem.val <= 0) {
   th = remove next
      thread from sem.L
   wakeup(th)
  }
ENABLE_INTS</pre>
```

Semaphores With Disabling

```
struct semaphore {
    int val;
    list L;
}
```

```
Down(semaphore sem)
  DISABLE_INTS
    sem.val--
    if (sem.val < 0) {
       add thread to sem.L
       sleep(thread)
    }
  ENABLE_INTS</pre>
```

```
Up(semaphore sem)
  DISABLE_INTS
    sem.val++
  if (sem.val <= 0) {
     th = remove next
        thread from sem.L
     wakeup(th)
  }
  ENABLE_INTS</pre>
```

```
method Down()
   var oldIntStat: int
   oldIntStat = SetInterruptsTo (DISABLED)
   if count == 0x80000000
         FatalError ("Semaphore count underflowed during 'Wait'operation")
   EndIf
   count = count - 1
   if count < 0 waitingThreads.AddToEnd (currentThread)</pre>
         currentThread.Sleep ()
   endIf
   oldIntStat = SetInterruptsTo (oldIntStat)
endMethod
```

```
method Down()
   var oldIntStat: int
   oldIntStat = SetInterruptsTo (DISABLED)
   if count == 0x80000000
        FatalError ("Semaphore count underflowed during 'Wait' operation")
   EndIf
   count = count - 1
   if count < 0 waitingThreads.AddToEnd (currentThread)</pre>
        currentThread.Sleep ()
   endIf
   oldIntStat = SetInterruptsTo (oldIntStat)
endMethod
```

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method Down()
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   if count == 0x80000000
        FatalError ("Semaphore count underflowed during 'Wait' operation")
   EndIf
   count = count - 1
   if count < 0 waitingThreads.AddToEnd (currentThread)</pre>
        currentThread.Sleep ()
   endIf
   oldIntStat = SetInterruptsTo (oldIntStat)
endMethod
```

```
method Down()
  var oldIntStat: int
  oldIntStat = SetInterruptsTo (DISABLED)
  if count == 0x80000000
      FatalError ("Semaphore count underflowed during 'Wait' operation")
  EndIf
  count = count - 1
  if count < 0 waitingThreads.AddToEnd (currentThread)
      currentThread.Sleep ()
  endIf
  oldIntStat = SetInterruptsTo (oldIntStat)
endMethod</pre>
```

What is currentThread.Sleep ()?

- If sleep stops a thread from executing, how, where, and when does it return?
 - which thread enables interrupts following sleep?
 - the thread that called sleep shouldn 't return until another thread has called signal!
 - ... but how does that other thread get to run?
 - ... where exactly does the thread switch occur?
- Trace down through the Blitz code until you find a call to switch()
 - Switch is called in one thread but returns in another!
 - See where registers are saved and restored

Study The Blitz Code

- Thread.c
 - Thread.Sleep ()
 - Run (nextThread)
- Switch.s
 - Switch (prevThread, nextThread)

Blitz Code For Semaphore.up

```
method Up ()
    var oldIntStat: int
    t: ptr to Thread
    oldIntStat = SetInterruptsTo (DISABLED)
    if count == 0x7fffffff
          FatalError ("Semaphore count overflowed during 'Signal' operation")
    endIf
    count = count + 1
    if count <= 0
          t = waitingThreads.Remove ()
          t.status = READY
          readyList.AddToEnd (t)
    endIf
    oldIntStat = SetInterruptsTo (oldIntStat)
endMethod
```

Using Atomic Instructions

- Implementing semaphores with interrupt disabling only works on uni-processors
 - What should we do on a multiprocessor?
- Special (hardware) atomic instructions for synchronization
 - test and set lock (TSL)
 - compare and swap (CAS)
- Semaphore can be built using atomic instructions
 - 1. build mutex locks from atomic instructions
 - 2. build semaphores from mutex locks

پیادهسازی سمافور با میوتکس!؟

How about this solution?

```
var m1: Mutex = unlocked -- Protects access to "cnt"
   m2: Mutex = locked -- Locked when waiting
                          Up():
Down ():
 Lock (m1)
                           Lock (m1)
 cnt = cnt - 1
                           cnt = cnt + 1
 if cnt<0
                           if cnt<=0
   Lock (m2)
                             Unlock (m2)
   Unlock (m1)
                           endIf
 else
                           Unlock (m1)
   Unlock (m1)
 endIf
```

How about this solution?

```
var cnt: int = 0
                             Signal count
var m1: Mutex = unlocked -- Protects access to "cnt"
                             Locked when waiting
    m2: Mutex = locked
Down ():
  Lock (m
  cnt = c
  if cnt
                                 if cat<=0
    Lock (m2)
                                   Unlock (m2)
    Unlock (m1
                                 endIf
  else
                                Unlock (m1)
    Unlock (n1
  endIf
```

How about this solution then?

```
var m1: Mutex = unlocked -- Protects access to "cnt"
   m2: Mutex = locked -- Locked when waiting
Down ():
                          Up():
 Lock (m1)
                           Lock (m1)
 cnt = cnt - 1
                           cnt = cnt + 1
 if cnt<0
                           if cnt<=0
   Unlock (m1)
                             Unlock (m2)
   Lock (m2)
                           endIf
 else
                           Unlock (m1)
   Unlock (m1)
 endIf
```

How about this solution then?

```
var cnt: int = 0
                             Signal count
var m1: Mutex = unlocked -- Protects access to "cnt"
                             Locked when waiting
    m2: Mutex = locked
Down ():
  Lock (m.
  if cnt
                                 if cat<=0
    Unlock (m1)
                                   Unlock (m2)
    Lock (m2)
                                endIf
                                Unlock (m1)
  else
```

Another solution?

```
var m1: Mutex = ulocked -- Protects access to "cnt"
   m2: Mutex = locked -- Locked when waiting
                         Up():
Down ():
                           Lock (m1)
 Lock (m1)
                           cnt = cnt + 1
 cnt = cnt - 1
                           if cnt<=0
 if cnt<0
                             Unlock (m2)
   Unlock (m1)
                           else
   Lock (m2)
                             Unlock (m1)
 endIf
                           endIf
 Unlock (m1)
```

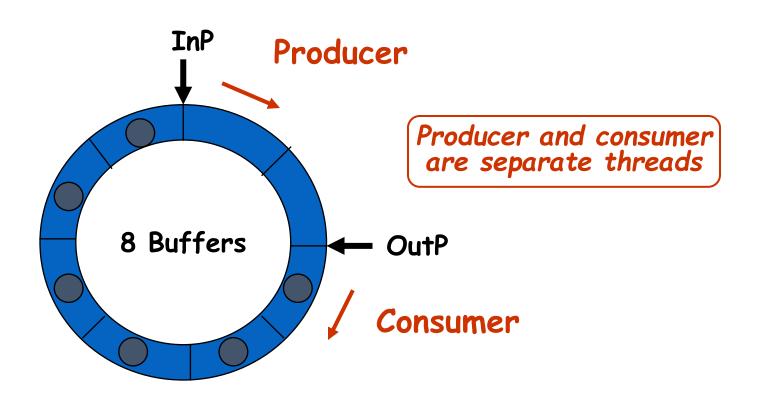
مسئلهی کلاسیک همزمانی

Classical Synchronization Problems

- Producer Consumer (bounded buffer)
- Dining philosophers
- Sleeping barber
- Readers and writers

Producer Consumer Problem

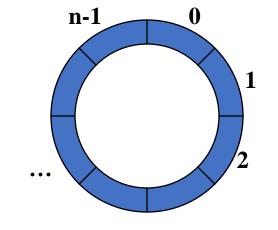
Also known as the bounded buffer problem



Is This a Valid Solution?

```
thread producer {
    while (1) {
        // Produce char c
        while (count==n) {
            no_op
        }
        buf[InP] = c
        InP = InP + 1 mod n
        count++
     }
}
```

```
thread consumer {
    while (1) {
        while (count==0) {
            no_op
        }
        c = buf[OutP]
        OutP = OutP + 1 mod n
        count--
        // Consume char
    }
}
```



Does This Solution Work?

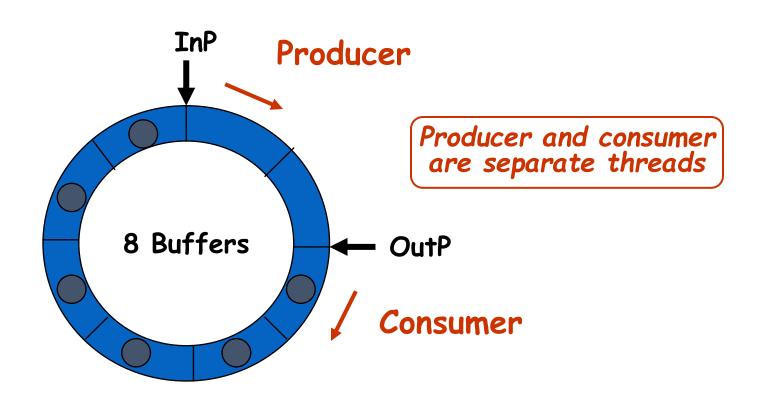
```
Global variables
  semaphore full_buffs = 0;
  semaphore empty_buffs = n;
  char buff[n];
  int InP, OutP;
```

```
0 thread producer {
1   while(1) {
2      // Produce char c...
3      down(empty_buffs)
4      buf[InP] = c
5      InP = InP + 1 mod n
6      up(full_buffs)
7   }
8 }
```

```
0 thread consumer {
1   while(1) {
2     down(full_buffs)
3     c = buf[OutP]
4     OutP = OutP + 1 mod n
5     up(empty_buffs)
6     // Consume char...
7   }
8 }
```

Producer Consumer Problem

- What is the shared state in the last solution?
- Does it apply mutual exclusion? If so, how?



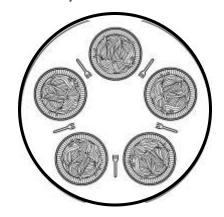
Problems With Solution

- What if we have multiple producers and multiple consumers?
 - Producer-specific and consumer-specific data becomes shared
 - We need to define and protect critical sections
- You'll do this in the next parts of the current Blitz project, using the mutex locks you built!

Dining Philosophers Problem

- Five philosophers sit at a table
- One chopstick between each philosopher

(need two to eat)



Each philosopher is modeled with a thread

```
while(TRUE) {
   Think();
   Grab first chopstick;
   Grab second chopstick;
   Eat();
   Put down first chopstick;
   Put down second chopstick;
}
```

Why do they need to synchronize? How should they do it?

Is This a Valid Solution?

```
#define N 5
Philosopher() {
  while(TRUE) {
    Think();
    take_chopstick(i);
    take_chopstick((i+1)% N);
   Eat();
   put_chopstick(i);
   put_chopstick((i+1)% N);
```

Problems

■ Potential for deadlock!

Working Towards a Solution

```
#define N 5
                             take_chopsticks(i)
Philosopher() {
  while(TRUE) {
    Think();
    take chopstick(i);
                               put_chopsticks(i)
    take chopstick((i+1) \}
    Eat();
   put chopstick(i);
   put chopstick((i+1)% N);
```

Working Towards a Solution

```
#define N 5

Philosopher() {
    while(TRUE) {
        Think();
        take_chopsticks(i);
        Eat();
        put_chopsticks(i);
    }
}
```

Taking Chopsticks

```
int state[N]
semaphore mutex = 1
semaphore sem[i]
```

```
take_chopsticks(int i) {
  down(mutex);
  state [i] = HUNGRY;
  test(i);
  up(mutex);
  down(sem[i]);
}
```

```
// only called with mutex set!

test(int i) {
  if (state[i] == HUNGRY &&
    state[LEFT] != EATING &&
    state[RIGHT] != EATING) {
    state[i] = EATING;
    up(sem[i]);
  }
}
```

Putting Down Chopsticks

```
int state[N]
semaphore mutex = 1
semaphore sem[i]
```

```
put_chopsticks(int i) {
   down(mutex);
   state [i] = THINKING;
   test(LEFT);
   test(RIGHT);
   up(mutex);
}
```

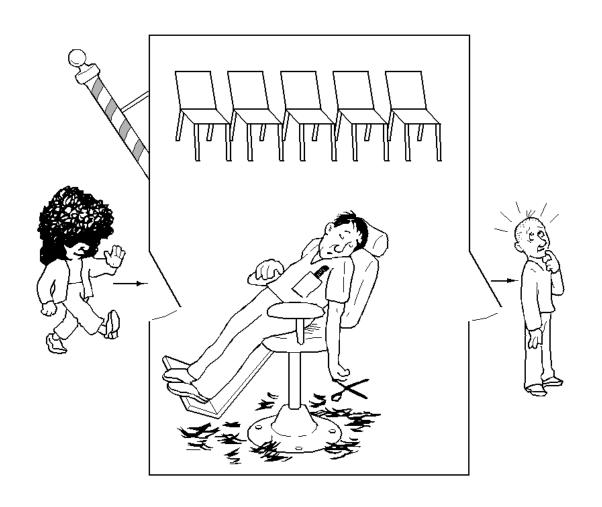
```
// only called with mutex set!

test(int i) {
  if (state[i] == HUNGRY &&
    state[LEFT] != EATING &&
    state[RIGHT] != EATING) {
    state[i] = EATING;
    up(sem[i]);
  }
}
```

Dining Philosophers

- Is the previous solution correct?
- What does it mean for it to be correct?
- Is there an easier way?

The Sleeping Barber Problem



The Sleeping Barber Problem

■ Barber:

- While there are people waiting for a hair cut, put one in the barber chair, and cut their hair
- When done, move to the next customer
- Else go to sleep, until someone comes in

■ Customer:

- If barber is asleep wake him up for a haircut
- If someone is getting a haircut wait for the barber to become free by sitting in a chair
- If all chairs are all full, leave the barbershop

Designing a Solution

- How will we model the barber and customers?
- What state variables do we need?
 - .. and which ones are shared?
 - and how will we protect them?
- How will the barber sleep?
- How will the barber wake up?
- How will customers wait?
- What problems do we need to look out for?

Is This a Good Solution?

```
const CHAIRS = 5
var customers: Semaphore
  barbers: Semaphore
  lock: Mutex
  numWaiting: int = 0
```

```
Barber Thread:
   while true
        Down(customers)
        Lock(lock)
        numWaiting = numWaiting-1
        Up(barbers)
        Unlock(lock)
        CutHair()
        endWhile
```

```
Customer Thread:
Lock(lock)
if numWaiting < CHAIRS
   numWaiting = numWaiting+1
   Up(customers)
   Unlock(lock)
   Down(barbers)
   GetHaircut()
else -- give up & go home
   Unlock(lock)
endIf</pre>
```

Readers and Writers Problem

- Multiple readers and writers want to access a database (each one is a thread)
- Multiple readers can proceed concurrently
- Writers must synchronize with readers and other writers
 - only one writer at a time!
 - when someone is writing, there must be no readers!

Goals:

- Maximize concurrency
- Prevent starvation

Designing a Solution

- How will we model the readers and writers?
- What state variables do we need?
 - .. and which ones are shared?
 - and how will we protect them?
- How will the writers wait?
- How will the writers wake up?
- How will readers wait?
- How will the readers wake up?
- What problems do we need to look out for?

Is This a Valid Solution?

```
var mut: Mutex = unlocked
                                     Reader Thread:
    db: Semaphore = 1
                                       while true
    rc: int = 0
                                         Lock (mut)
                                         rc = rc + 1
                                         if rc == 1
                                           Down (db)
                                         endIf
Writer Thread:
                                         Unlock (mut)
  while true
                                         ... Read shared data...
    ...Remainder Section...
    Down (db)
                                         Lock (mut)
                                         rc = rc - 1
    ...Write shared data...
                                         if rc == 0
    Up (db)
  endWhile
                                           Up (db)
                                         endIf
                                         Unlock (mut)
                                          ... Remainder Section...
                                       endWhile
```

Readers and writers solution

- Does the previous solution have any problems?
 - Is it "fair"?
 - Can any threads be starved? If so, how could this be fixed?
 - How much confidence would you have in your solution?

Recap

- What is a race condition?
- How can we protect against race conditions?
- Can locks be implemented simply by reading and writing to a binary variable in memory?
- How can a kernel make synchronization-related system calls atomic on a uniprocessor?
 - Why wouldn't this work on a multiprocessor?
- Why is it better to block rather than spin on a uniprocessor?
- Why is it sometimes better to spin rather than block on a multiprocessor?

Recap

- When faced with a concurrent programming problem, what strategy would you follow in designing a solution?
- What does all of this have to do with Operating Systems?