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# تكنولوژي كامپيوتر

جلسهی هفدهم مصائب سیستمهای توزیعشده

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سیستمهای توزیعشده، تفاوت و مشکلاتش نسبت به یک کامپیوتر، مدل ریاضی مسئله، خطیسازی

## FAULT VS PARTIAL FAULT

### Single Computer

- Deterministic
- Fault
  - Blue Screen
  - Usually a computer fully crash
  - In single-system applications with proper code an application either works or it doesn't

### Distributed systems

- Partial Fault
  - We know individual systems will fail or groups of systems will fail but we need the overall system to continue working
  - it may sometimes work and sometimes unpredictably fail.
- You may not even know whether something succeeded or not, as the time it takes for a message to travel across a network is also nondeterministic!

# Building a Reliable System from Unreliable Components??

- TCP from unreliable IP
  - But cannot remove delays in the network
- Error-correcting codes
  - But only can deal with small number of single-bit errors

## UNRELIABLE NETWORKS

### shared-nothing systems

- The internet and most internal networks in datacenters (often Ethernet) are asynchronous packet networks
- one node can send a message (a packet) to another node
  - no guarantees as to when it will arrive
  - Or no guarantees whether it will arrive at all.

- If you send a request and expect a response, many things could go wrong
  - Your request may have been lost
  - Your request may be waiting in a queue and will be delivered later
  - The remote node may have failed
  - The remote node may have temporarily stopped responding
  - The remote node may have processed your request, but the response has been lost on the network
  - The remote node may have processed your request, but the response has been delayed and will be delivered later

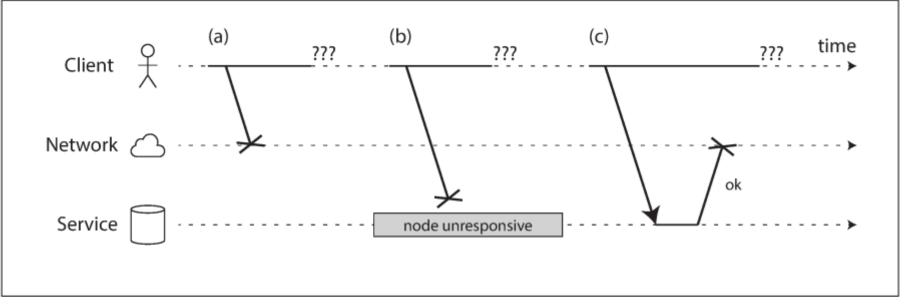


Figure 8-1. If you send a request and don't get a response, it's not possible to distinguish whether (a) the request was lost, (b) the remote node is down, or (c) the response was lost.

- the only information you have is that you haven't received a response yet!
- If you send a request to another node and don't receive a response, it is <u>impossible</u> to tell why
- The usual way of handling this issue is a **timeout**

#### Network Faults in Practice

- Network problems can be surprisingly common! ⊗
- Network partitions
  - When one part of the network is cut off from the rest due to a network fault
  - called a network partition or netsplit

#### Network Faults in Practice

- Handling network fault?
  - Tolerating them?
  - If your network is normally fairly reliable, a valid approach may be to simply show an error message to users while your network is experiencing problems

### **Detecting Faults**

- Automatically detect faulty nodes
- Why?
  - A load balancer needs to stop sending requests to a node that is dead (i.e., take it out of rotation)
  - In a distributed database with single-leader replication, if the leader fails, one of the followers needs to be promoted to be the new leader

### Detecting Fault?

- If the system is still up but application has run into a problem then possible to get a return from the system saying it is present but non-operational
- No way of knowing what requests it may have received and left unanswered or what data was sent to it and lost
- Possible for OS to directly announce it has failed so other systems don't have to wait for timeout
- Possible to use remote management tools to check on systems if you are closely networked

### Timeouts and Unbounded Delays

- How long should the timeout be?
  - There is unfortunately no simple answer. 🙈
  - Long Timeout ...
  - Short timeout ...

### When delay happen?

- Often delays are caused by queuing of some sort
  - Multiple systems trying to send info to the same system, all have to be handled in whatever order they are received, but some will have to wait
  - If all CPU cores of a system are busy it will have to wait for cycles to address the information
  - In virtual systems they can be temporarily frozen while other VMs are doing things
- Possible to have a noisy neighbor that is causing delays for you by using up networking capacity

■ Have to determine appropriate timeout lengths experimentally

# Synchronous Versus Asynchronous Networks

- Distributed systems would be a lot simpler if we could rely on the network to deliver packets with some fixed maximum delay, and not to drop packets
- traditional fixed-line telephone network
  - is extremely reliable
  - delayed audio frames and dropped calls are very rare

# Synchronous Versus Asynchronous Networks

- When you make a call over the telephone network
  - it establishes a <u>circuit</u>
  - a fixed, guaranteed amount of bandwidth is allocated for the call, along the entire route between the two callers.

# Synchronous Versus Asynchronous Networks

- Can we not simply make network delays predictable?
- The answer is that they are optimized for bursty traffic.
- Latency and Resource Utilization

## UNRELIABLE CLOCKS

#### **Unreliable Clocks**

- 1. Has this request timed out yet?
- 2. What's the 99th percentile response time of this service?
- 3. How many queries per second did this service handle on average in the last five
- minutes?
- 4. How long did the user spend on our site?
- 5. When was this article published?
- 6. At what date and time should the reminder email be sent?
- 7. When does this cache entry expire?
- 8. What is the timestamp on this error message in the log file?

### Clocks in your computer

- Time-of-day clocks
  - Time-of-day clocks are usually synchronized with NTP
  - System.currentTimeMillis() in java
- Monotonic clocks
  - System.nanoTime() in java
  - NTP may adjust the frequency at which the monotonic clock moves forward

### Clock Synchronization and Accuracy

NTP synchronization can only be as good as the network delay

**...** 

### Relying on Synchronized Clocks

- they seem simple and easy to use But ...
- a day may not have exactly 86,400 seconds!
- time-of-day clocks may move backward in time
- time on one node may be quite different from the time on another node
- -> robust software needs to be prepared to deal with incorrect clocks.

### Timestamps for ordering events

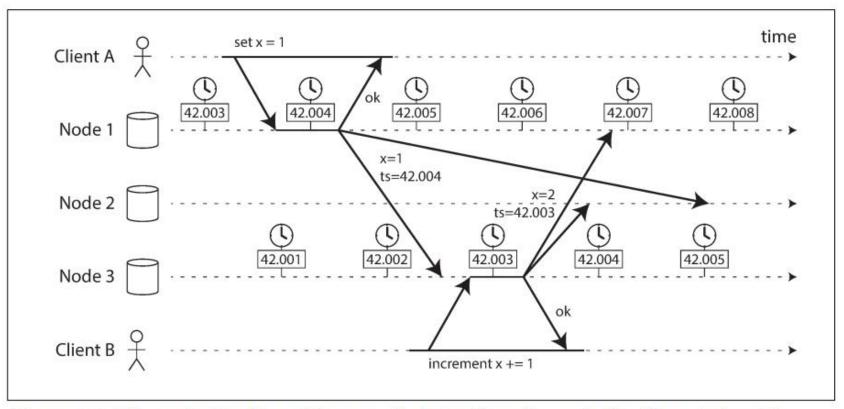


Figure 8-3. The write by client B is causally later than the write by client A, but B's write has an earlier timestamp.

- You may be able to read a machine's time-of-day clock with microsecond or even nanosecond resolution
  - Is it mean that the value is actually accurate to such precision?
  - No 🕾

- Unfortunately, most systems don't expose this uncertainty
  - for example, when you call clock\_gettime(), the return value doesn't tell you the expected error of the timestamp,
  - you don't know if its confidence interval is five milliseconds or five years.

- The uncertainty bound can be calculated based on your time source...
- If
  - GPS receiver
  - atomic (caesium) clock
- directly attached to your computer

- Google's Spanner TrueTime API
  - which explicitly reports the confidence interval on the local clock
  - you get back two values: [earliest, latest]
    - the earliest possible
    - And the latest possible timestamp.

### Synchronized clocks for global snapshots

- Snapshot isolation...
  - Monotonically increasing transaction ID
  - To implement MVVC
- Can we use timestamp for transaction id in distributed system?
- Spanner implementation of snapshot isolation

#### **Process Pauses**

```
while (true) {
request = getIncomingRequest();
// Ensure that the lease always has at least 10 seconds remaining
if (lease.expiryTimeMillis - System.currentTimeMillis() < 10000) {</pre>
    lease = lease.renew();
if (lease.isValid()) {
    process(request);
```

#### **Process Pauses**

- Garbage collector
- Suspend in virtual machines
- Suspend in laptops
- Context switching
- Stop process using stop signal

### Preventing garbage collector pauses?

- Short lived processes
- Restart using rolling upgrade

# KNOWLEDGE, TRUTH, AND LIES

# Knowledge

- A node in the network cannot know anything for sure
- it can only make guesses based on the messages it receives (or doesn't receive) via the network
- If a remote node doesn't respond...
  - Is node has a problem? Which node?
  - Is network has a problem?

# The truth?

#### Example

- Node receive message from others
- But can't send message to others
- Other nodes think that it is dead
- the semi-disconnected node is dragged to the graveyard, kicking and screaming "I'm not dead!"

- Example
  - Node with long stop-the-world GC

# The Truth Is Defined by the Majority

- the quorum is an absolute majority of more than half the nodes
- it is safe, because there can only be only one majority in the system
- ... consensus algorithms ...

#### The leader and the lock

- Lock for distributed systems
  - Only one node is allowed to be the leader for a database partition, to avoid split brain
  - Only one transaction or client is allowed to hold the lock for a particular resource or object, to prevent concurrently writing to it and corrupting it.
  - Only one user is allowed to register a particular username, because a username must uniquely identify a user.

#### The leader and the lock

- even if a node believes that it is "the chosen one"
- Is it mean that quorum of nodes agrees?
  - No!
  - Example...

#### The leader and the lock

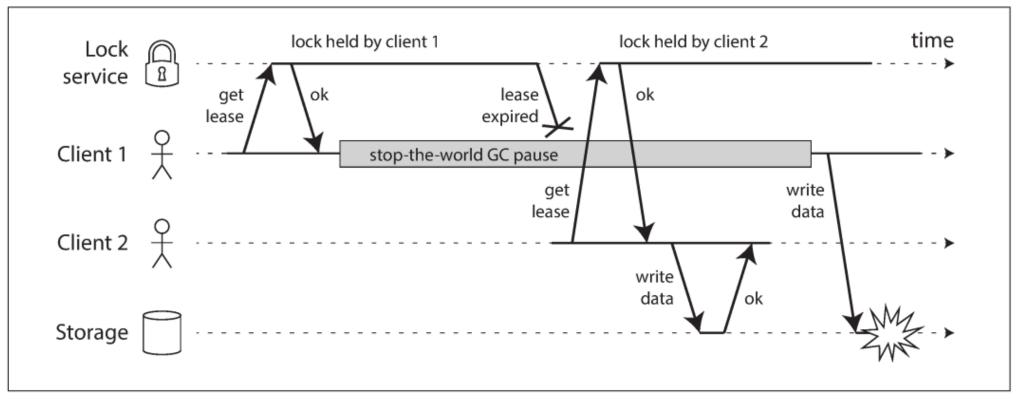


Figure 8-4. Incorrect implementation of a distributed lock: client 1 believes that it still has a valid lease, even though it has expired, and thus corrupts a file in storage.

# The leader and the lock - Fencing tokens

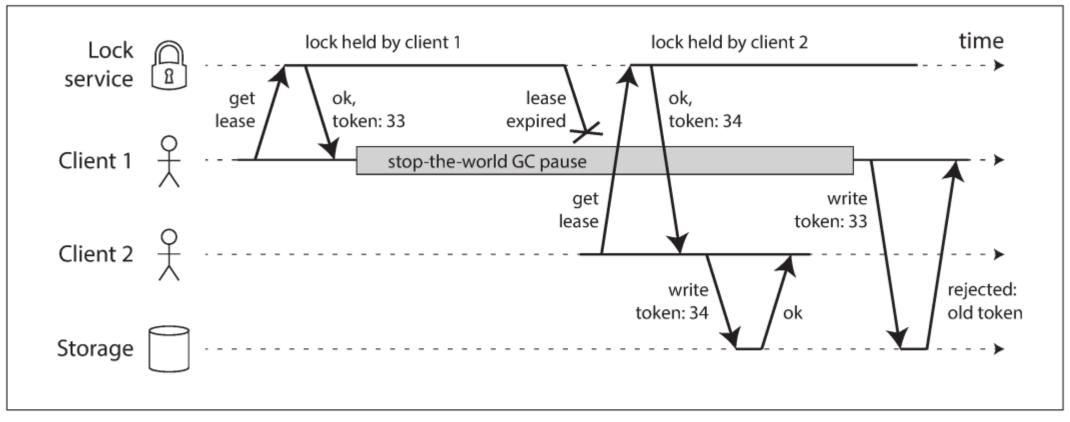


Figure 8-5. Making access to storage safe by allowing writes only in the order of increasing fencing tokens.

# Byzantine Faults

# SYSTEM MODEL AND REALITY

# Timing assumptions

- Synchronous model
  - bounded network delay, bounded process pau- ses, and bounded clock error
- Partially synchronous model
  - system behaves like a synchronous system most of the time, but it sometimes exceeds the bounds for network delay, process pauses, and clock drift
- Asynchronous model
  - an algorithm is not allowed to make any timing assumption

#### Node failures

- Crash-stop faults
- Crash-recovery faults
- Byzantine (arbitrary) faults

## Correctness of an algorithm?

- Example on fencing token
- Uniqueness
  - No two requests for a fencing token return the same value.
- Monotonic sequence
  - If request x returned token tx, and request y returned token ty, and x completed before y began, then tx < ty</li>
- Availability
  - A node that requests a fencing token and does not crash eventually receives a response

## Correctness of an algorithm?

- Safety and liveness
- Safety
  - nothing bad happens
- Liveness
  - something good eventually happens

# LINEARIZABILITY

# **Consistency Guarantees**

■ Eventual consistency

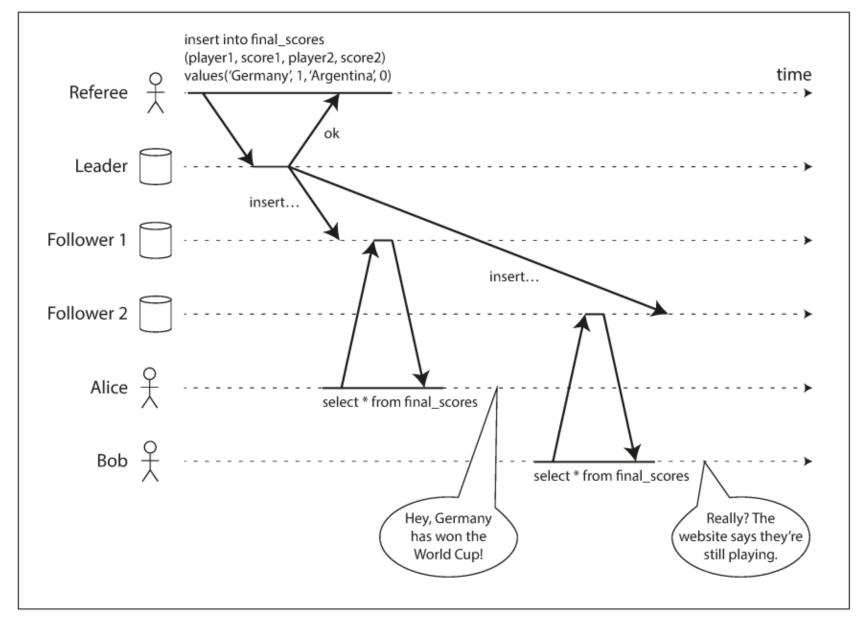


Figure 9-1. This system is not linearizable, causing football fans to be confused.

- atomic consistency
- strong consistency
- immediate consistency
- external consistency

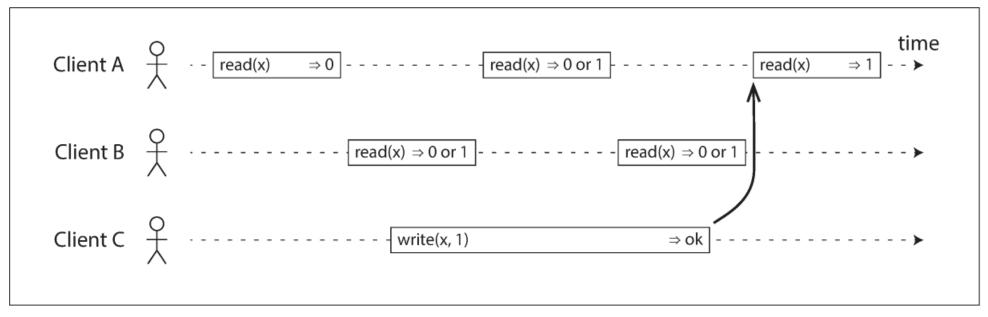


Figure 9-2. If a read request is concurrent with a write request, it may return either the old or the new value.

To make the system linearizable, we need to add another constraint, illustrated in Figure 9-3.

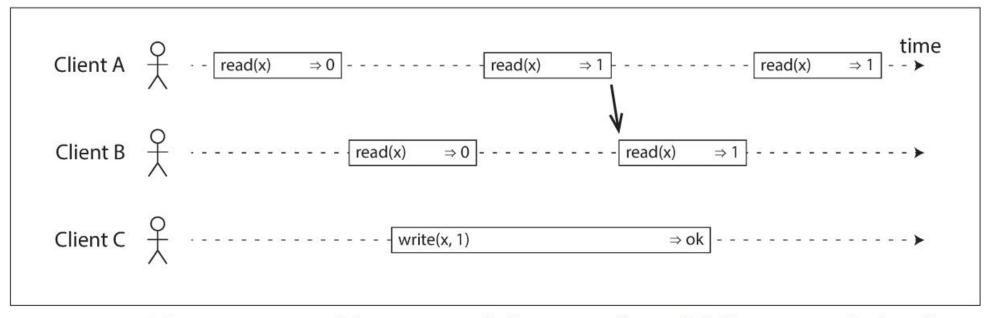


Figure 9-3. After any one read has returned the new value, all following reads (on the same or other clients) must also return the new value.

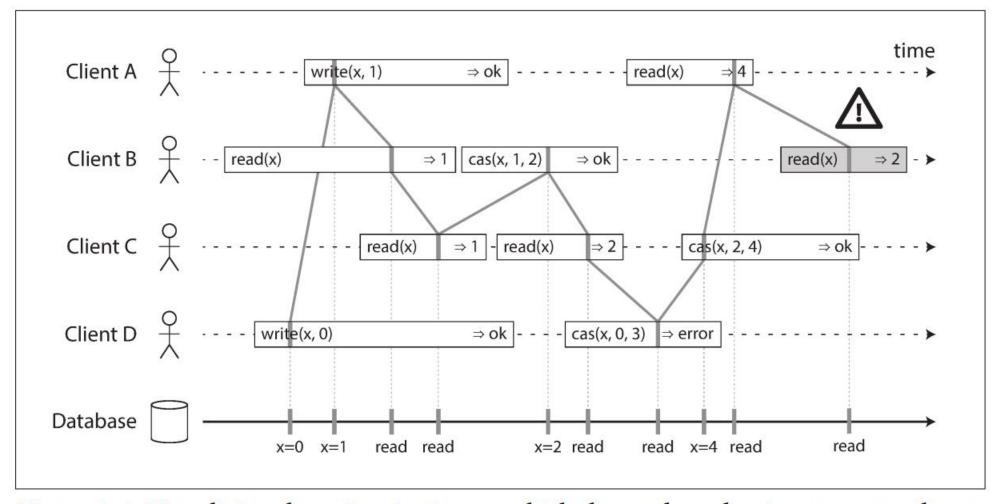


Figure 9-4. Visualizing the points in time at which the reads and writes appear to have taken effect. The final read by B is not linearizable.

# Linearizability Versus Serializability

# جلسهی بعد