# Function Definitions



## Iffy Lang

$$b := T \mid F \mid if b_1 then b_2 else b_3$$

## Iffy Lang

```
p := \operatorname{func} name(x_1, ..., x_i) \{body\}
```

body := return b

$$b := x \mid name(b_1, ..., b_i) \mid T \mid F \mid if b_1 then b_2 else b_3 \mid (b)$$

# **Example Program: Negation**

```
func not(x) {
  ?
}
```

## **Example Program: Negation**

```
func and(x1, x2) {
   ?
}
```

```
func and(x1, x2) {
  return (if x1
        then x2
        else F)
}
```

```
func or(x1, x2) {
   ?
}
```

```
func or(x1, x2) {
  return (if x1
          then T
          else x2)
}
```

# **Example Program: Implication**

```
func implies(x1, x2) {
  ?
}
```

# **Example Program: Implication**

```
func implies(x1, x2) {
  return or(not(x1),x2)
}
```

### **Example Program: Necessary and Sufficient**

```
func iff(x1, x2) {
   ?
}
```

### **Example Program: Necessary and Sufficient**

```
func iff(x1, x2) {
  return and(implies(x1,x2),implies(x2,x1))
}
```

# Example Program: Exclusive-Or

```
func xor(x1, x2) {
   ?
}
```

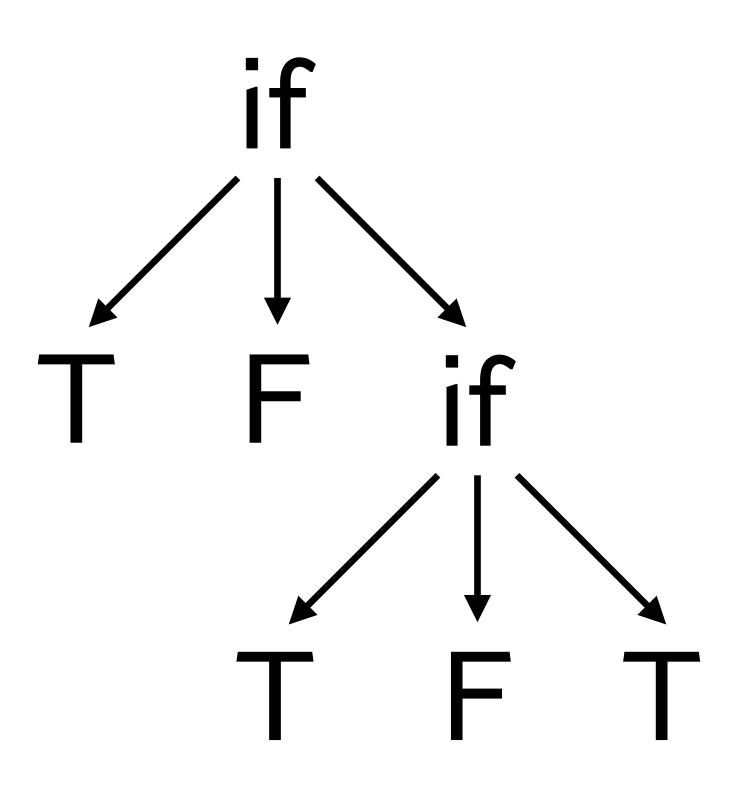
## Example Program: Exclusive-Or

```
func xor(x1, x2) {
  return or(and(x1,not(x2)),and(not(x1),x2))
}
```

### Syntax Trees

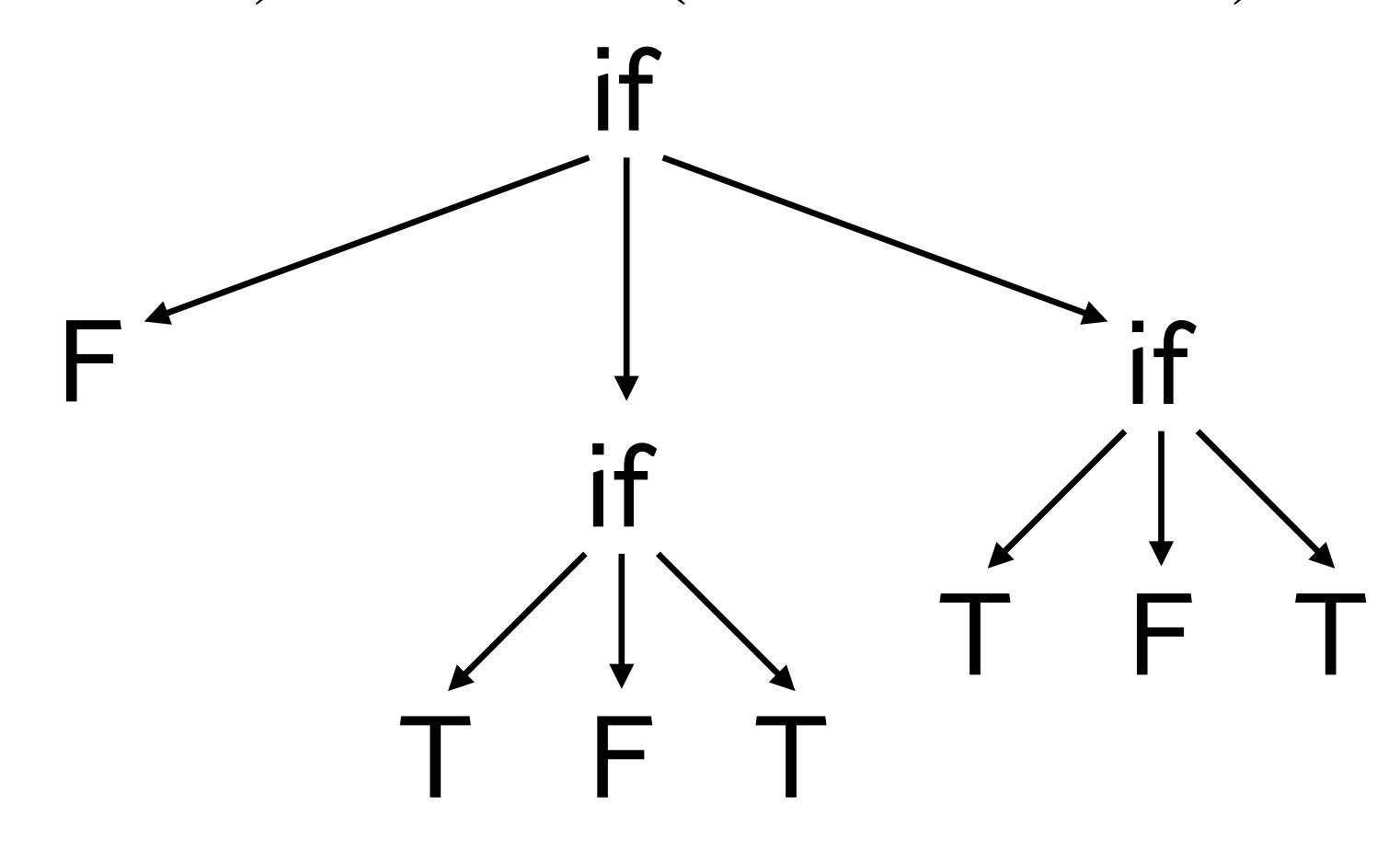
Syntax trees are a tree representation of a syntactical expression.

if F then T else (if F then T else T)

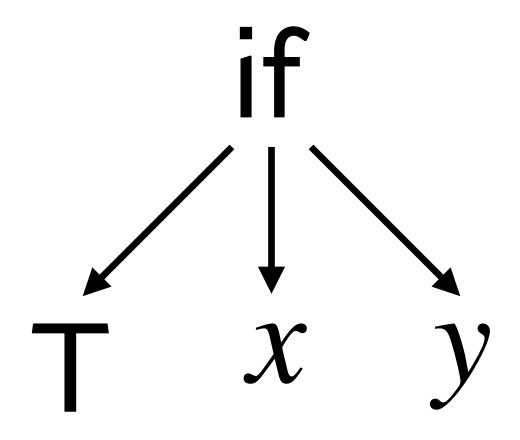


if (if F then T else T) then F else (if F then T else T)

if (if F then T else T) then F else (if F then T else T)

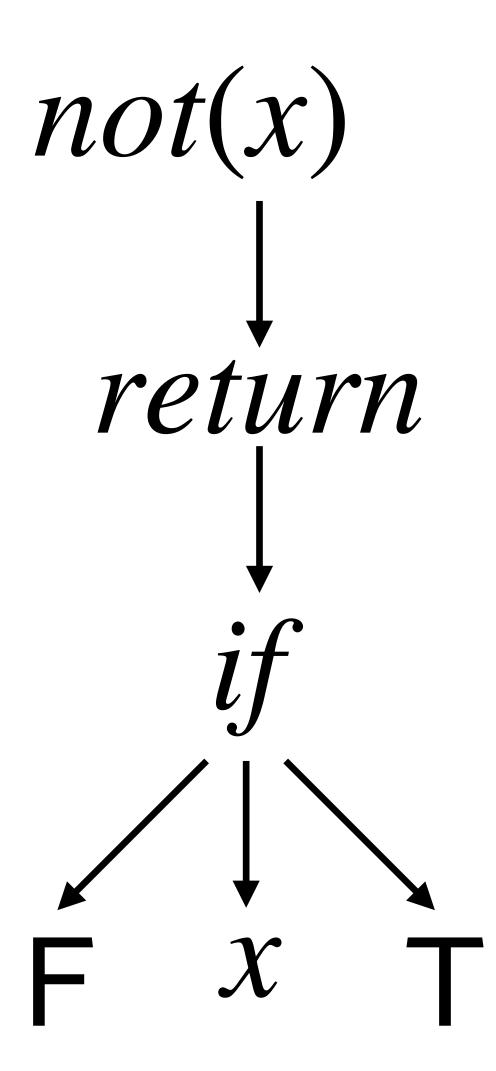


if x then Telse y



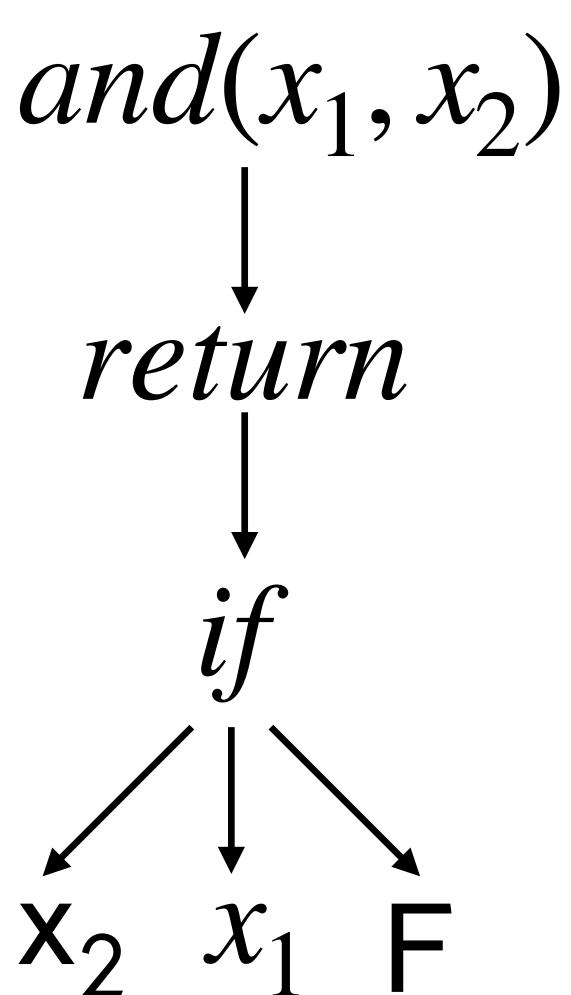
#### Syntax Trees for Function Definitions

```
func not(x) {
  return (if x
                then F
                else T)
}
```



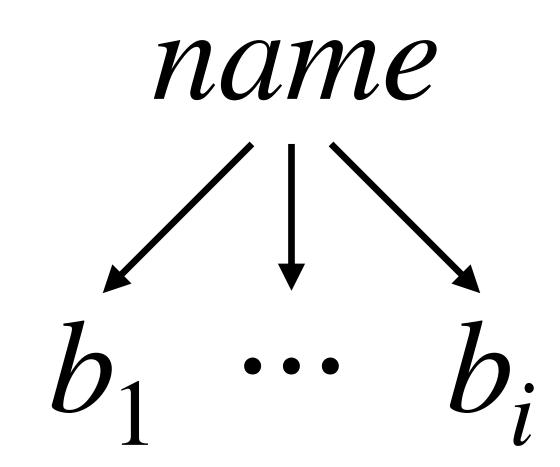
### Syntax Trees for Function Definitions

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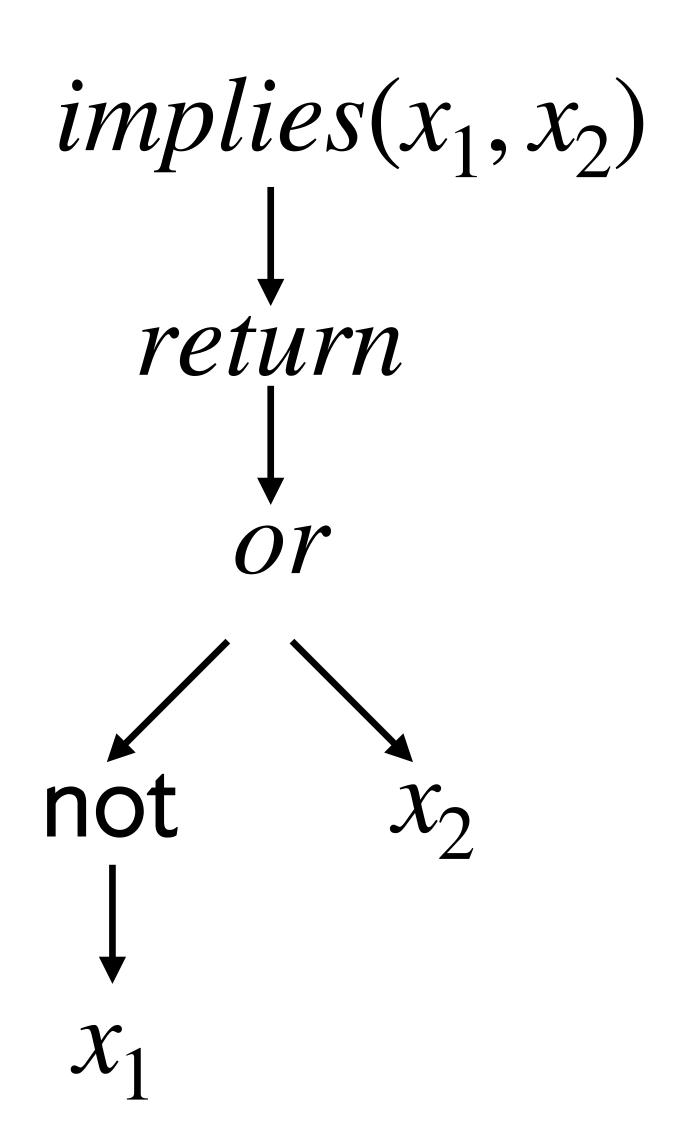
## Syntax Trees for Function Application

 $name(b_1, ..., b_i)$ 



## Syntax Trees for Function Application

```
func implies(x1, x2) {
  return or(not(x1),x2)
}
```



A **binder** is a piece of syntax that delimits the scope of a variable.

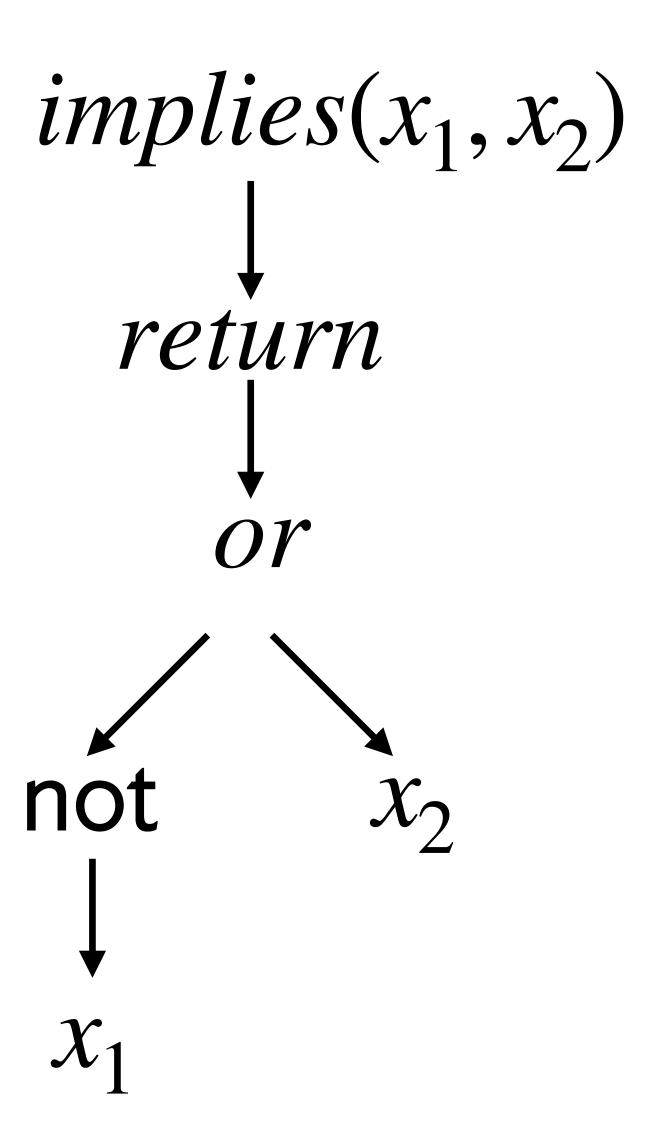
In IffyLang, the only binder, currently, is the function signature.

Here:

$$p := \operatorname{func} name(x_1, ..., x_i) \{body\}$$

The binder is "name( $x_1, ..., x_i$ )" and is said to "bind" the variables  $x_1$  through  $x_i$  to the function name.

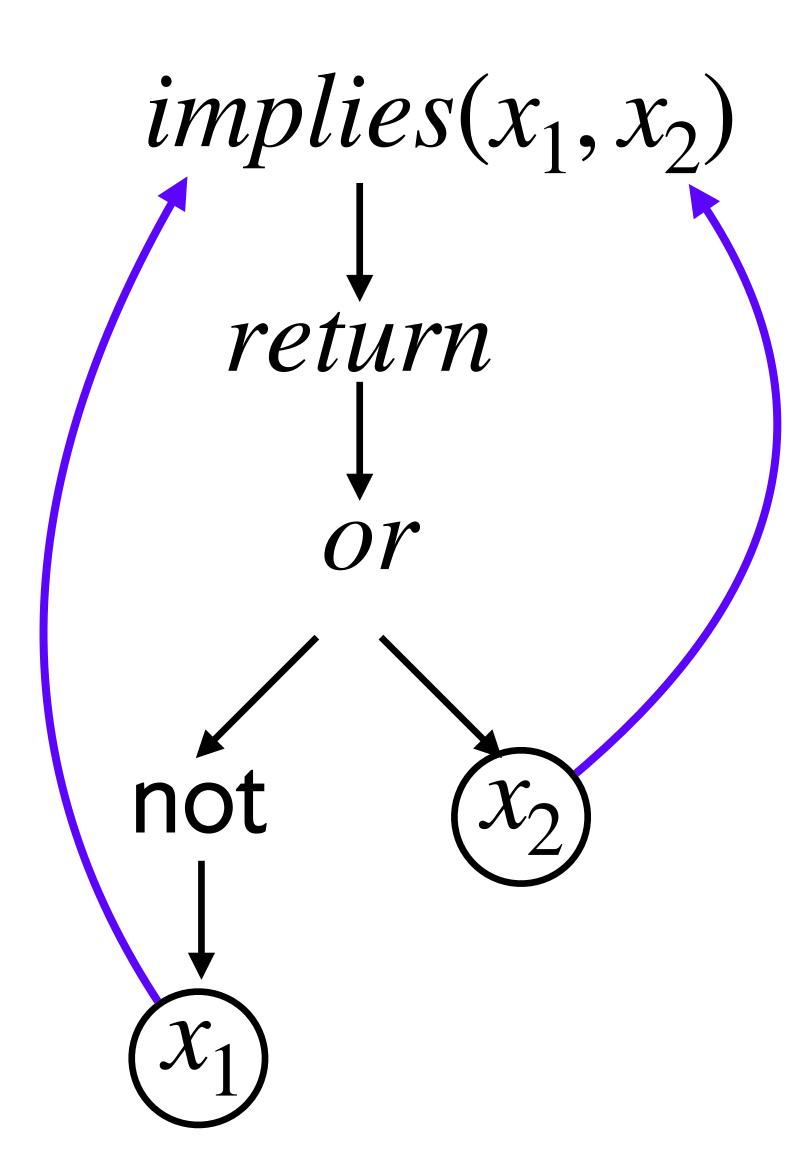
```
func implies(x1, x2) {
  return or(not(x1),x2)
}
```



A bound variable is one associated with a binder.

```
func implies(x1, x2) {
  return or(not(x1),x2)
}
```

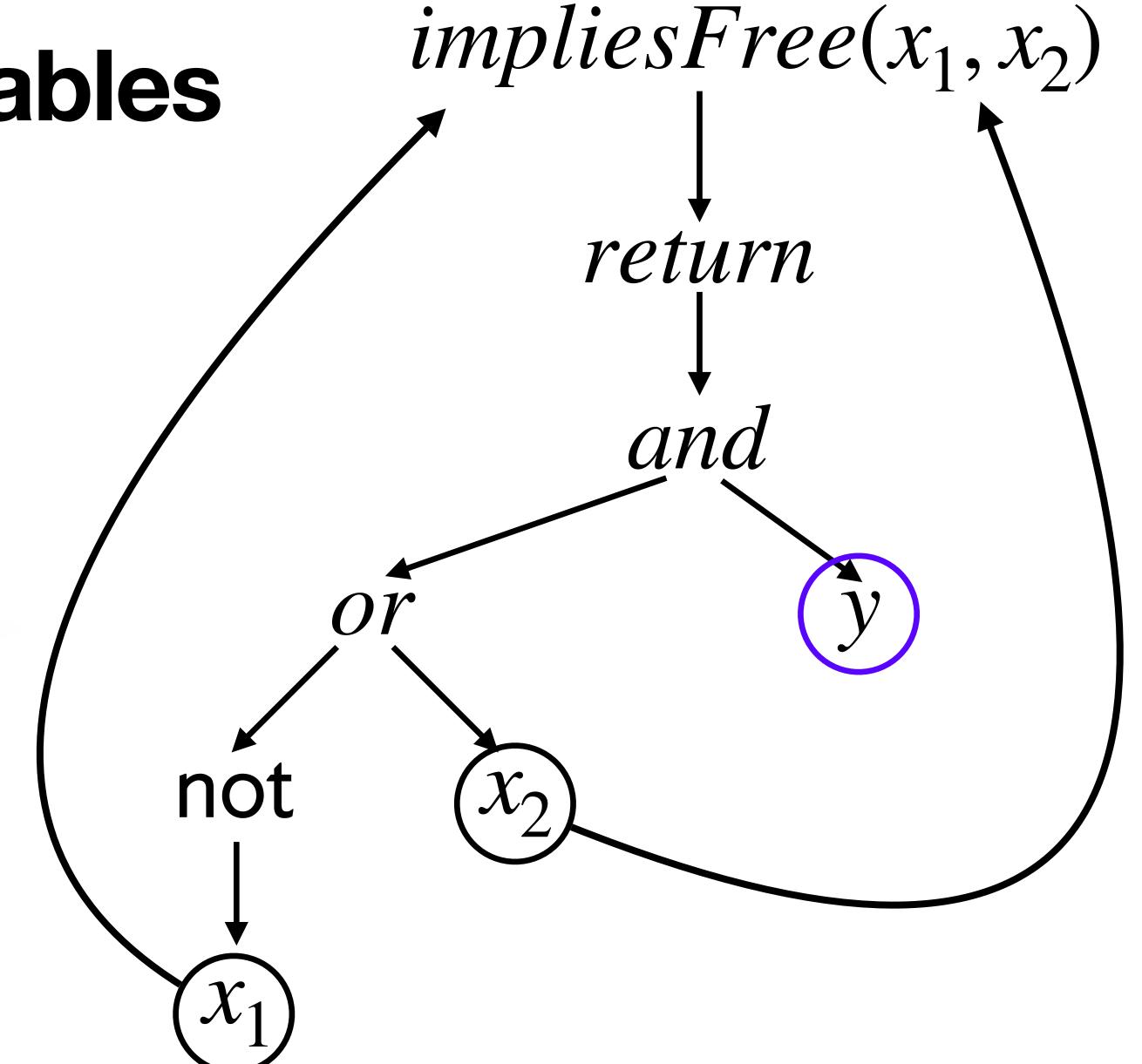
The variables  $x_1$  and  $x_2$  are said to be **bound** variables, because they have a binder above them in their syntax tree.



Any other variables are called free.

```
func impliesFree(x1, x2) {
  return and(or(not(x1),x2),y)
}
```

A **free** variable has no binder above it in the syntax tree.



#### Closed Programs

A program is called **closed** if and only if it has no free variables.

#### Closed Programs

How many programs have you ever written with a free variable?

### Closed Programs

How many programs have you ever written with a free variable?

None!

# Valid Programs

Valid programs are closed programs!

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Valid programs are closed programs!

Discuss: What are the valid programs in IffyLang?

## Evaluation

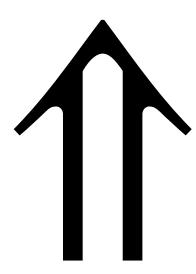
```
func implies(x1, x2) {
  return or(not(x1),x2)
}

func comp() {
  return implies(T,F)
}
```

How do we evaluate the comp function?

### Context of Function Definition

implies $(x_1, x_2)$ {return(or(not $(x_1), x_2)$ )}, comp(){return(implies(T, F)}



```
func implies(x1, x2) {
  return or(not(x1),x2)
}

func comp() {
  return implies(T,F)
}
```

Context of function definitions:

```
\Delta ::= \Delta, name(x_1, ..., x_i) \{body\} \mid empty
```

### Evaluation

Context of function definitions:

$$\Delta := \Delta, name(x_1, ..., x_i) \{body\} \mid empty$$

**Evaluation:** 

$$\Delta \vdash b_1 \rightarrow b_2$$

where  $b_1$  and  $b_2$  are closed programs.

## Evaluation

Context of function definitions:

$$\Delta ::= \Delta, name(x_1, ..., x_i) \{body\} \mid empty$$

#### **Evaluation:**

$$\Delta \vdash b_1 \leadsto b_2$$

where  $b_1$  and  $b_2$  are closed programs.

$$\Delta$$
, name(){body}  $\vdash$  name()  $\sim$  body

```
func implies(x1, x2) {
  return or(not(x1),x2)
}

func comp() {
  return implies(T,F)
}
```

## Context of Function Definition

```
implies(x_1, x_2) \{ return(or(not(x_1), x_2)) \}, comp() \{ return(implies(T, F)) \vdash comp() \\ \sim return(implies(T, F)) \\ \sim implies(T, F) \\ \sim ?
```

## Substitution

Substitution replaces a free variable in a program with a closed program.

Denoted:

$$[x \mapsto t_1]t_2$$

where  $t_1$  is closed.

$$[x \mapsto t_1]x = t_1$$

Suppose  $t_1$  is closed.

## Substitution

$$[x \mapsto t_1]y = y$$
where  $x \neq y$ 

$$[x \mapsto t_1]T = T$$

$$[x \mapsto t_1]F = F$$

 $[x \mapsto t_1]$  (if  $b_1$  then  $b_2$  else  $b_3$ ) = if  $[x \mapsto t_1]b_1$  then  $[x \mapsto t_1]b_2$  else  $[x \mapsto t_1]b_3$ 

 $[x \mapsto t_1](\text{func } name(x_1, ..., x_i)\{body\}) = \text{func } name(x_1, ..., x_i)\{[x \mapsto t_1]body\}$ 

$$[x \mapsto t_1]name(b_1, ..., b_i) = name([x \mapsto t_1]b_1, ..., [x \mapsto t_1]b_i)$$

 $[x \mapsto t_1]$  (if  $b_1$  then  $b_2$  else  $b_3$ ) = if  $[x \mapsto t_1]b_1$  then  $[x \mapsto t_1]b_2$  else  $[x \mapsto t_1]b_3$ 

$$[x \mapsto t_1](\operatorname{func} name(x_1, ..., x_i)\{body\}) =$$

$$\operatorname{func} name(x_1, ..., x_i)\{[x \mapsto t_1]body\}$$

$$[x \mapsto t_1]name(b_1, ..., b_i) =$$
  
 $name([x \mapsto t_1]b_1, ..., [x \mapsto t_1]b_i)$ 

$$[x \mapsto b_1]x = b_1$$

Suppose  $t_1$  is closed.

## Substitution

$$[x \mapsto b_1]y = y$$
where  $x \neq y$ 

$$[x \mapsto b_1]T = T$$

$$[x \mapsto b_1]F = F$$

$$[x \mapsto b_1](\text{if } b_2 \text{ then } b_3 \text{ else } b_4) = \text{if } [x \mapsto b_1]b_2 \text{ then } [x \mapsto b_1]b_3 \text{ else } [x \mapsto b_1]b_4$$

$$[x \mapsto b_1]name(b'_1, ..., b'_i) = name([x \mapsto b_1]b'_1, ..., [x \mapsto b_1]b'_i)$$

$$[x \mapsto b_1]return(b_2) = return([x \mapsto b_1]b_2)$$

# **Evaluating Functions**

$$\Delta, \operatorname{name}(x_1, ..., x_i) \{ \operatorname{body} \} \vdash \operatorname{name}(b_1, ..., b_i) \leadsto [x_1, ..., x_i \mapsto b_1, ..., b_i] \operatorname{body}$$