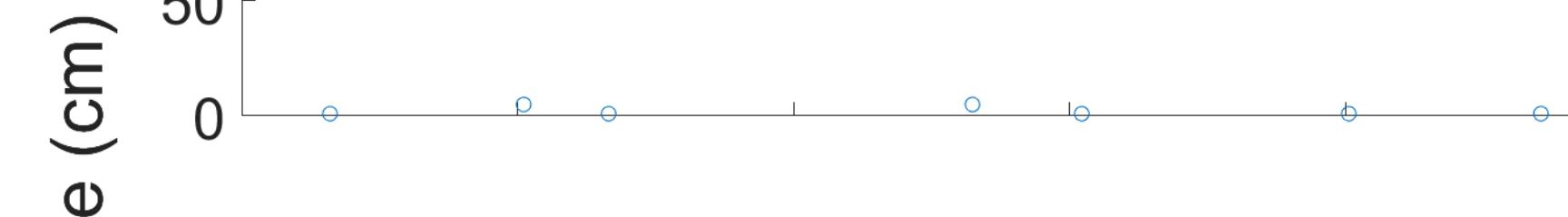
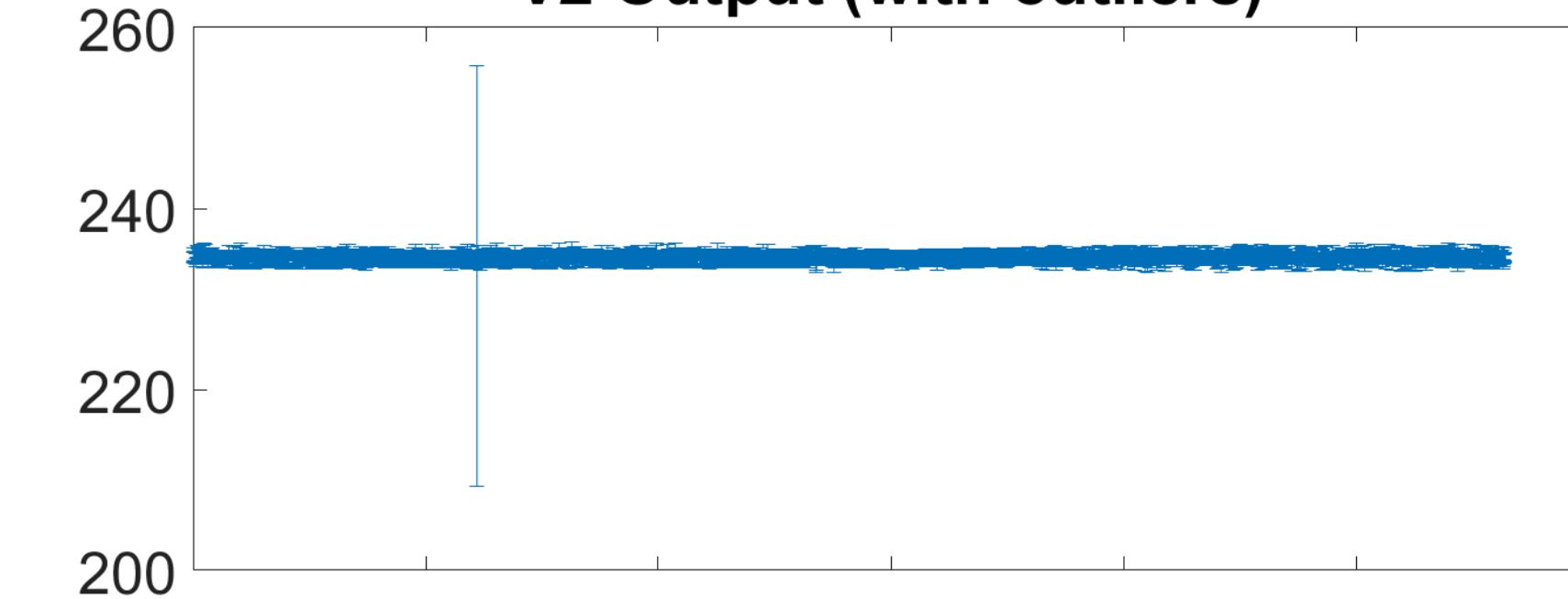


# Garmin LiDAR Sensor Readings

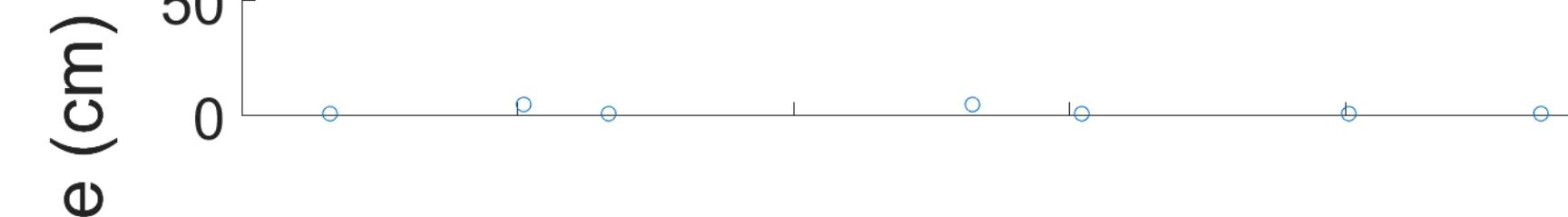
**V1 Output (with outliers)**



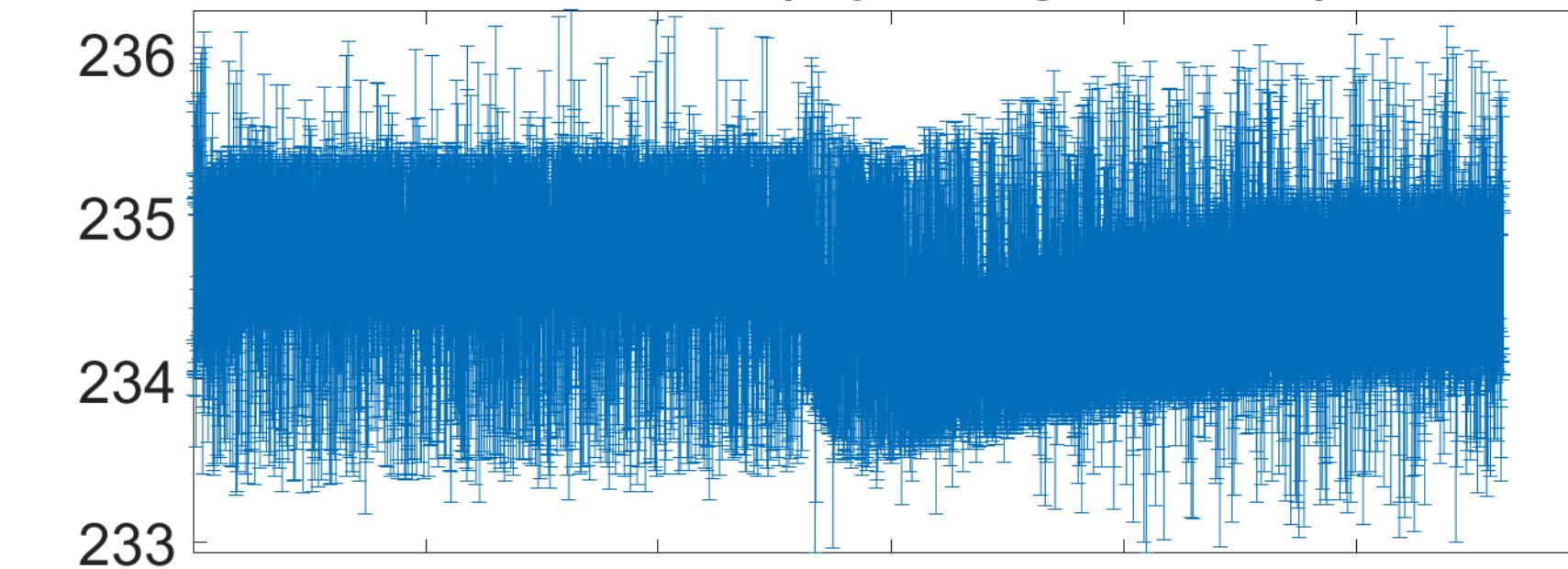
**V2 Output (with outliers)**



**V1 Output (rejecting outliers)**



**V2 Output (rejecting outliers)**



Sample Number