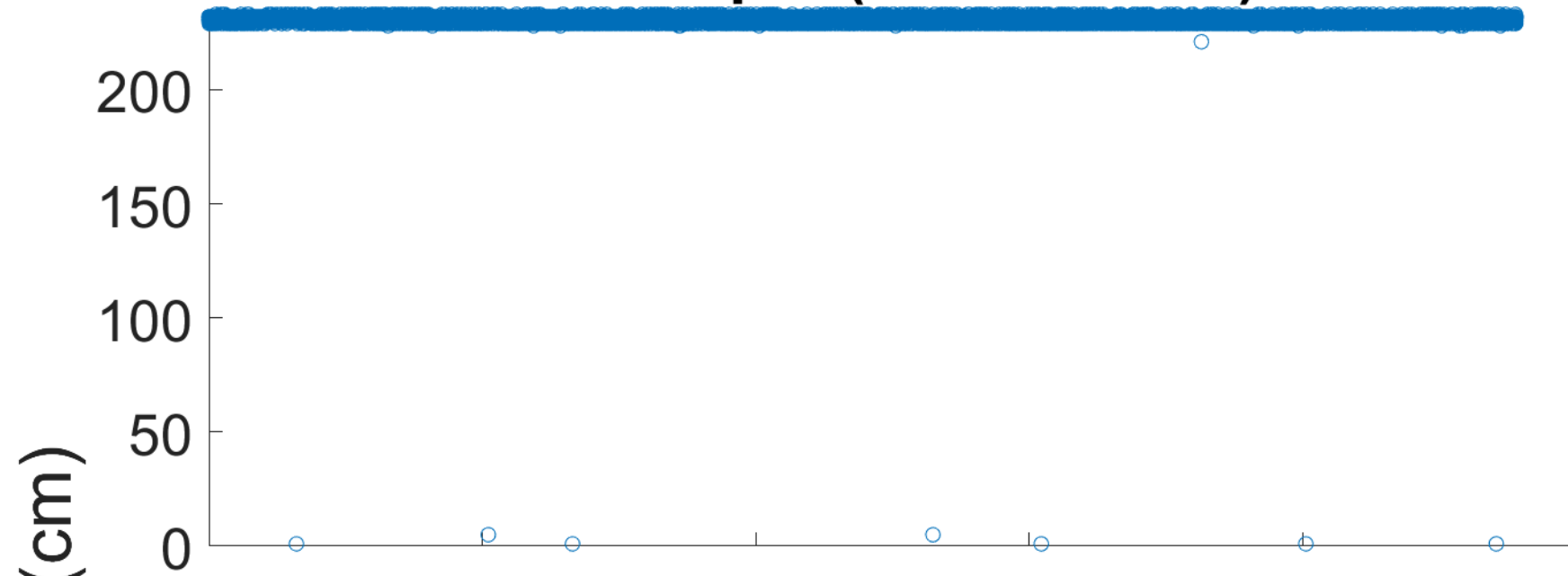
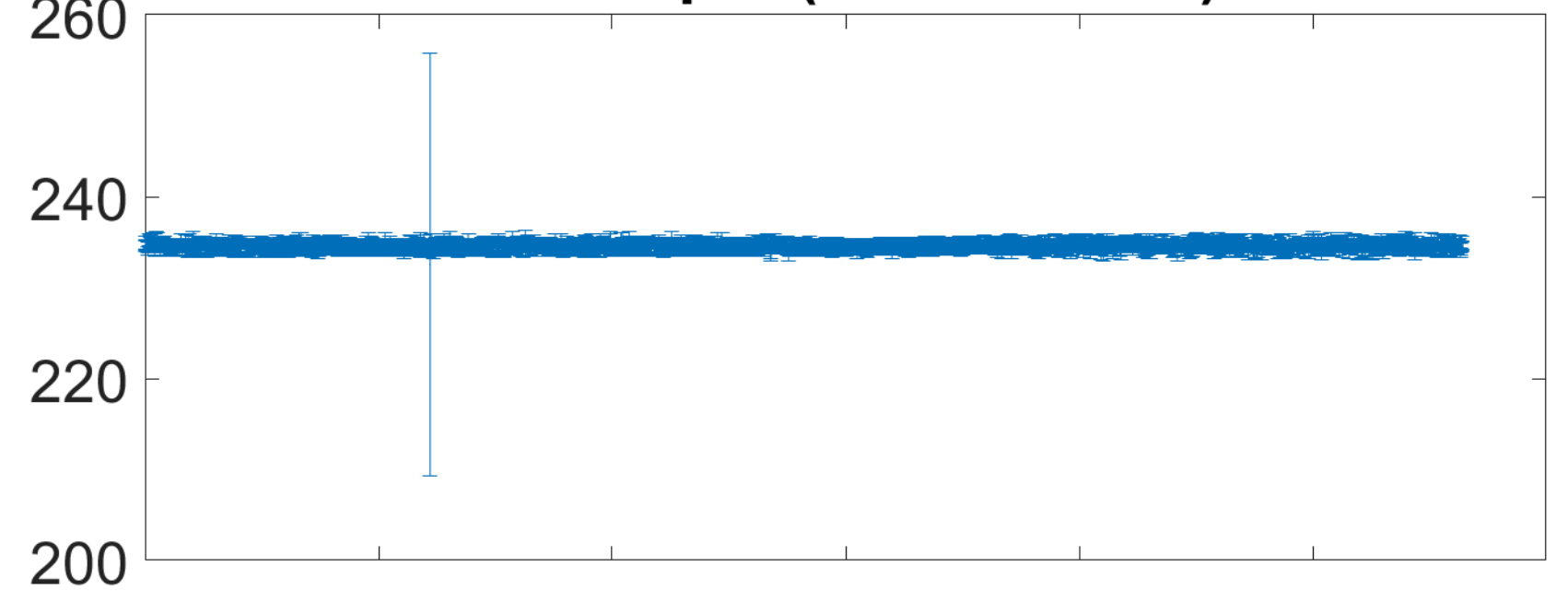


Garmin LiDAR Sensor Readings

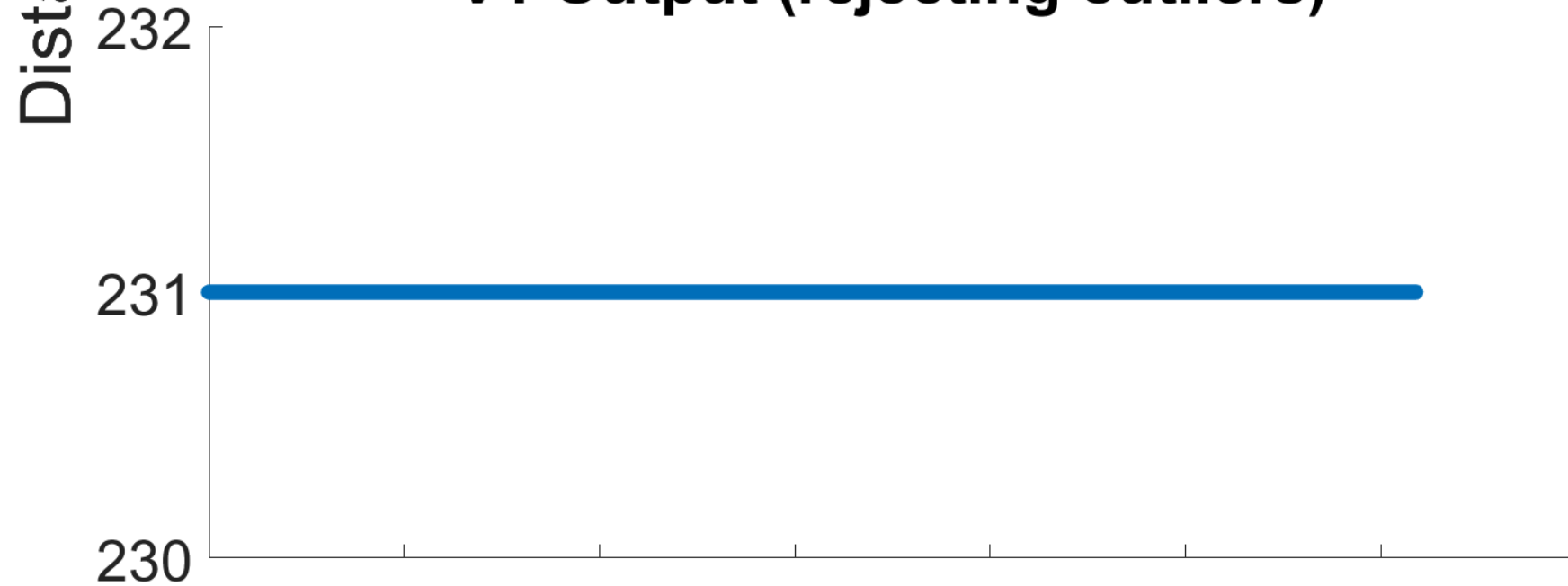
V1 Output (with outliers)



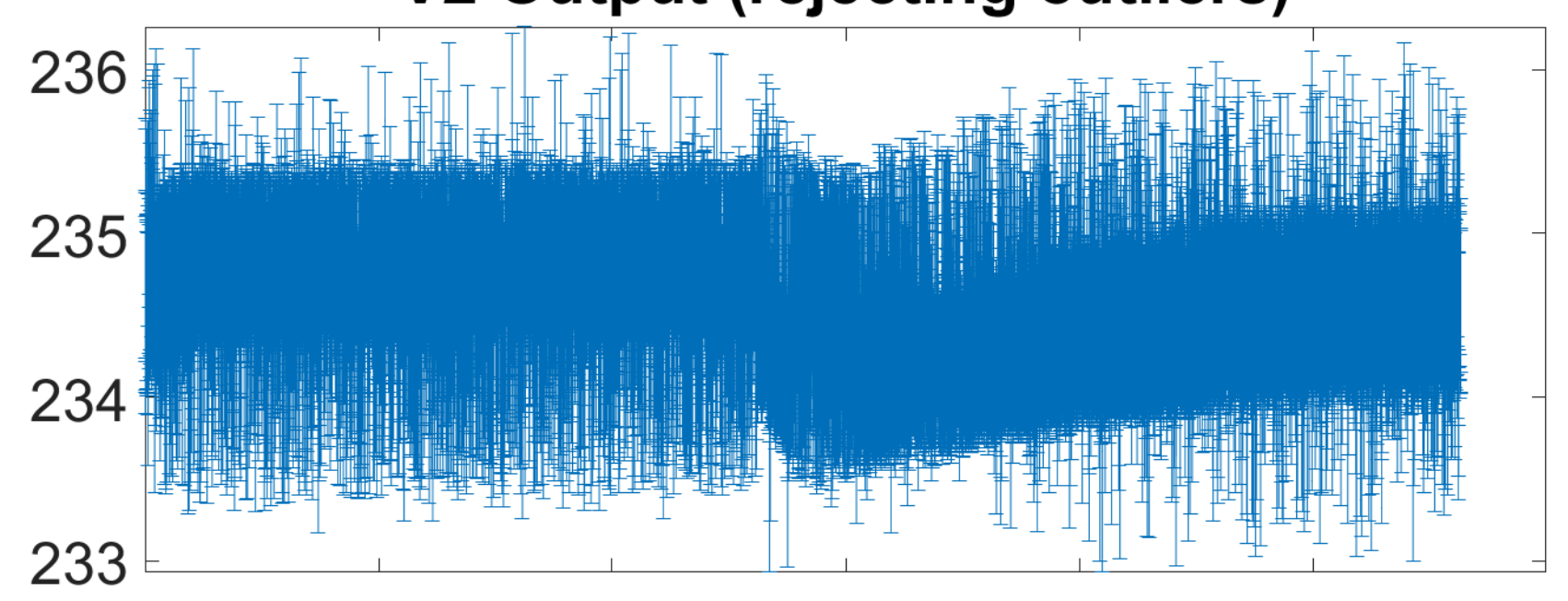
V2 Output (with outliers)



V1 Output (rejecting outliers)



V2 Output (rejecting outliers)



Sample Number