



Operating Systems

Deadlocks-Part2

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Outline

- Liveness
- System Model
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance



Methods for Handling Deadlocks

- Ensure that the system will **never** enter a deadlock state:
 - **Deadlock prevention**
 - **Deadlock avoidance**

- Allow the system to enter a deadlock state and then recover.

- Ignore it and pretend that deadlocks never occur in the system.



Deadlock Prevention

Invalidate ***one of the four*** necessary conditions for deadlock



Deadlock Prevention-Mutual Exclusion

- **Not required for sharable resources** (e.g., read-only files)
- **Must hold** for non-sharable resources



Deadlock Prevention- Hold and Wait

- Must guarantee that whenever a process requests a resource, it does not hold any other resources.
- Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none allocated to it.
- Low resource utilization; starvation possible.



Deadlock Prevention-No Preemption

- If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released.
- Preempted resources are added to the list of resources for which the process is waiting.
- Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting.



Deadlock Prevention- Circular Wait

- Impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration.
- Invalidating the circular wait condition is most common.
- Simply assign each resource (i.e., mutex locks) a unique number.
- Resources must be acquired in order.



Circular Wait

- If:

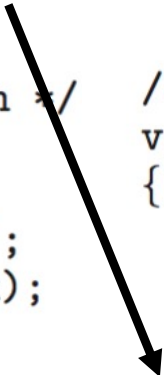
first_mutex = 1

second_mutex = 5

code for **thread_two** could not be written as follows:

```
/* thread_one runs in this function */
void *do_work_one(void *param)
{
    pthread_mutex_lock(&first_mutex);
    pthread_mutex_lock(&second_mutex);
    /**
     * Do some work
     */
    pthread_mutex_unlock(&second_mutex);
    pthread_mutex_unlock(&first_mutex);

    pthread_exit(0);
}
```



```
/* thread_two runs in this function */
void *do_work_two(void *param)
{
    pthread_mutex_lock(&second_mutex);
    pthread_mutex_lock(&first_mutex);
    /**
     * Do some work
     */
    pthread_mutex_unlock(&first_mutex);
    pthread_mutex_unlock(&second_mutex);

    pthread_exit(0);
}
```

Deadlock Avoidance

Requires that the system has some additional
a priori information available.

Deadlock Avoidance

- Simplest and most useful model requires that each process declare the ***maximum number*** of resources of each type that it may need.
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there **can never be a circular-wait condition**.
- Resource-allocation ***state*** is defined by the number of available and allocated resources, and the maximum demands of the processes.



Safe State

- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- System is in **safe state** if there exists a sequence $\langle P_1, P_2, \dots, P_n \rangle$ of ALL the processes in the systems such that for each P_i , the resources that P_i can still request can be satisfied by currently available resources + resources held by all the P_j , with $j < i$



Safe State (cont.)

■ That is:

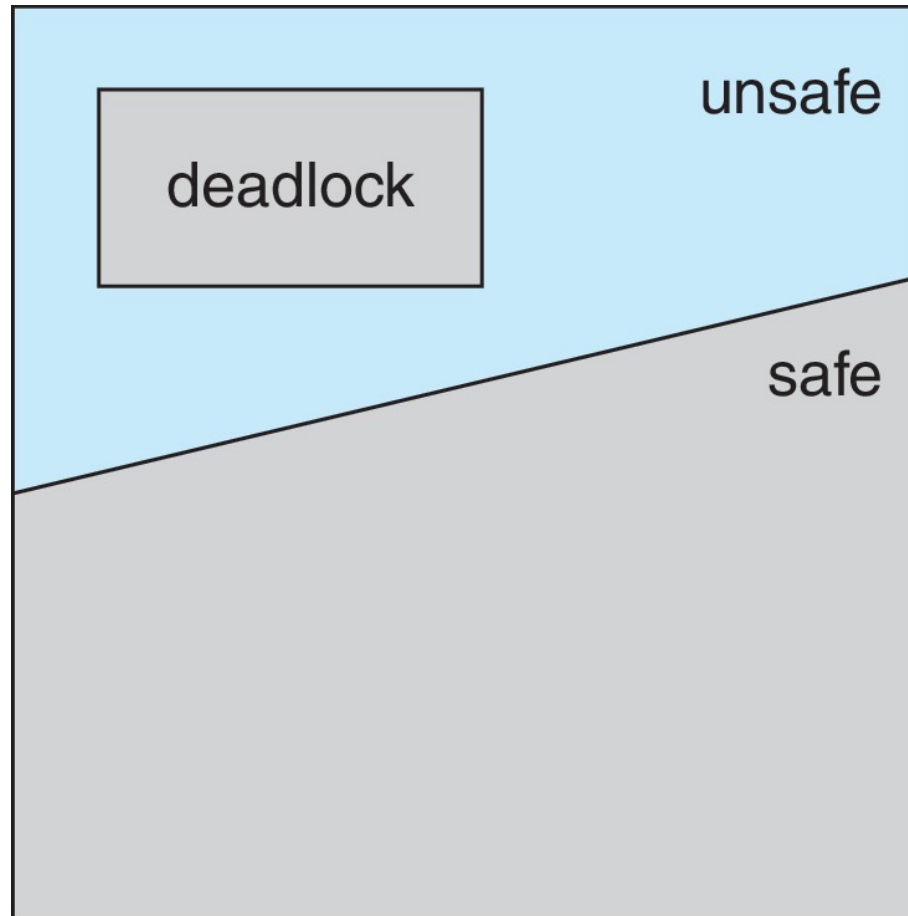
- If P_i resource needs are not immediately available, then P_i can wait until all P_j have finished
- When P_j is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate
- When P_i terminates, P_{i+1} can obtain its needed resources, and so on

Basic Facts

- If a system is in safe state \Rightarrow no deadlocks
- If a system is in unsafe state \Rightarrow possibility of deadlock
- Avoidance \Rightarrow ensure that a system will never enter an unsafe state.



Safe, Unsafe, Deadlock State



Avoidance Algorithms

- Single instance of a resource type
 - Use a resource-allocation graph

- Multiple instances of a resource type
 - Use the Banker's Algorithm



Resource-Allocation Graph Scheme

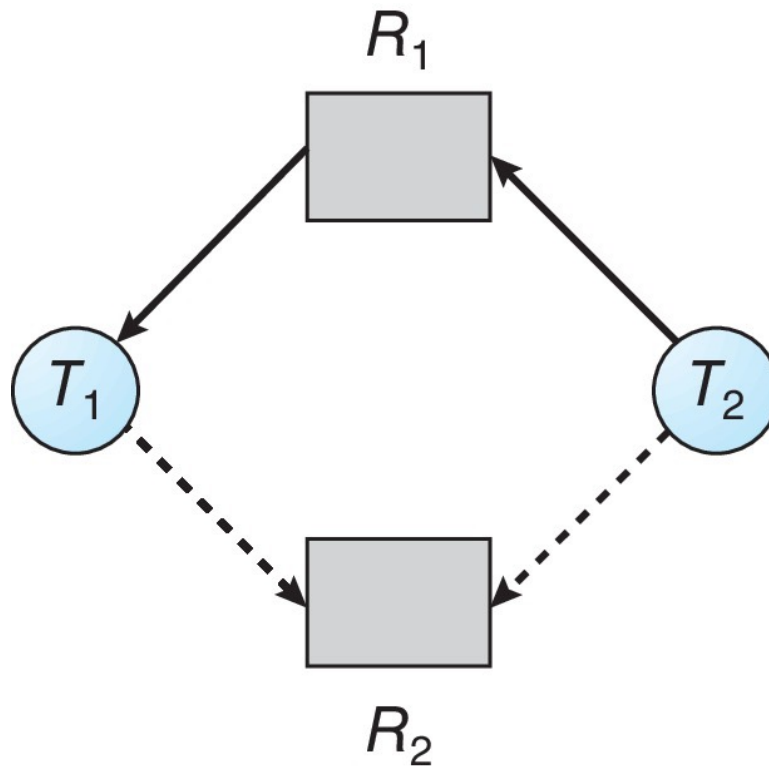
- **Claim edge** $P_i \rightarrow R_j$ indicated that process P_j may request resource R_j ; represented by a dashed line.
- **Claim edge** converts to request edge when a process requests a resource.
- Request edge converted to an assignment edge when the resource is allocated to the process.

Resource-Allocation Graph Scheme (cont.)

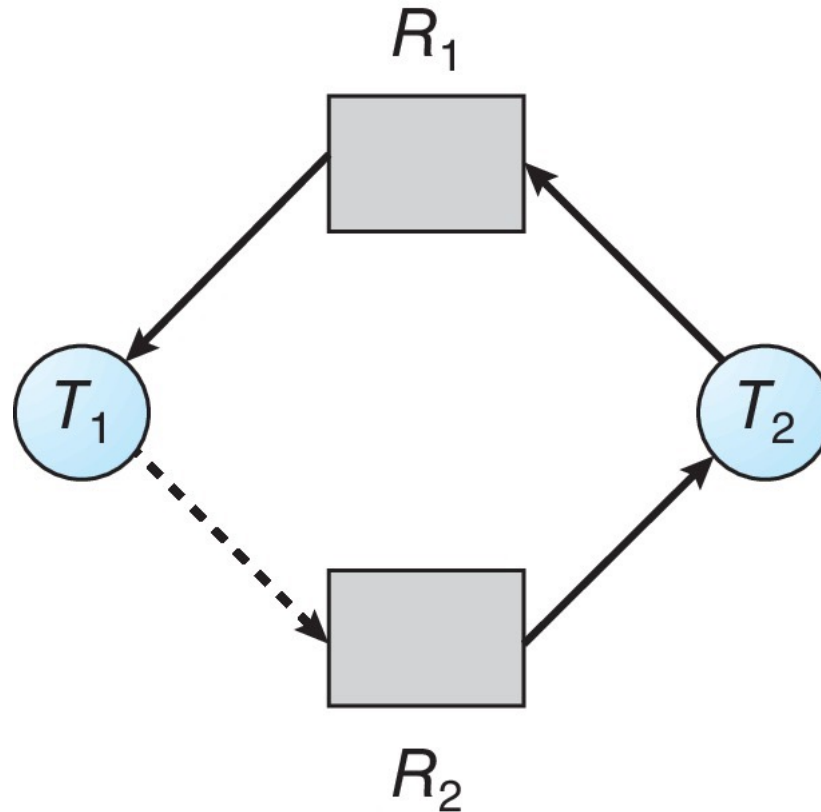
- When a resource is released by a process, assignment edge reconverts to a claim edge.
- Resources must be claimed a priori in the system.



Resource-Allocation Graph



Unsafe State In Resource-Allocation Graph

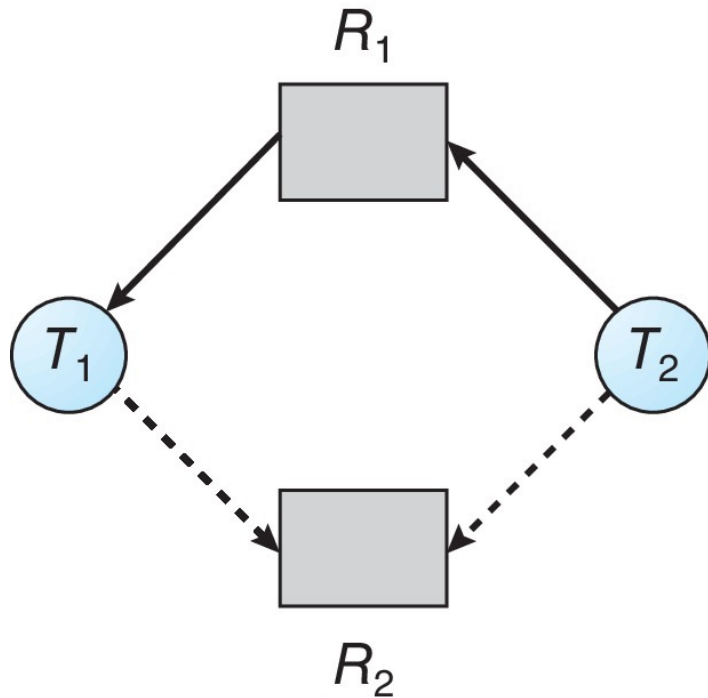


Resource-Allocation Graph Algorithm

- Suppose that process P_i requests a resource R_j .
- The request can be granted ***only if converting the request edge to an assignment edge does not result in the formation of a cycle*** in the resource allocation graph.
- If a cycle is found, then the allocation will put the system in an unsafe state. In that case, thread T_i will have to wait for its requests to be satisfied.



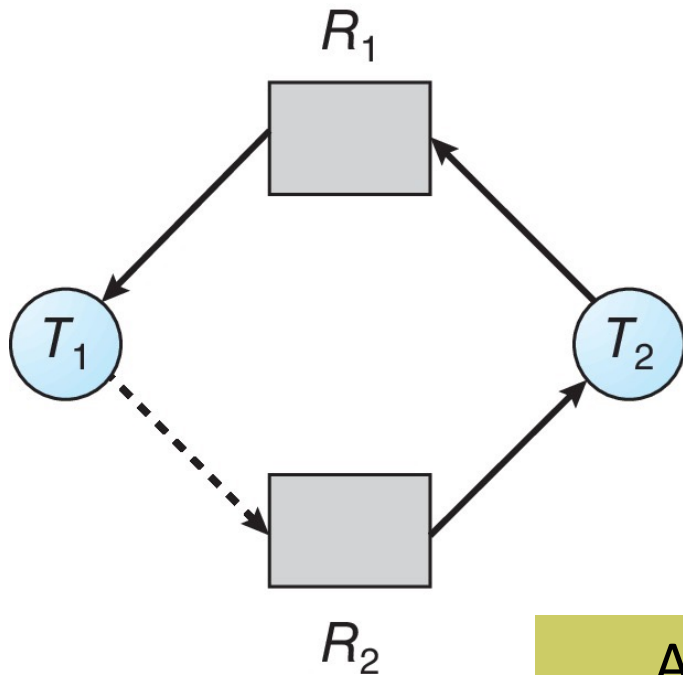
Example of Using the Algorithm



Suppose that T_2 requests R_2 .

Can the request be granted?

Example of Using the Algorithm (Cont.)



Suppose that T_2 requests R_2 .

Can the request be granted?

Although R_2 is currently free, we cannot allocate it to T_2 , since this action will create a cycle in the graph.

A cycle, indicates that the system is in an unsafe state. If T_1 requests R_2 , and T_2 requests R_1 , then a deadlock will occur.

Banker's Algorithm

- Multiple instances of resources
- Each process must a priori claim maximum use
- When a process requests a resource it may have to wait
- When a process gets all its resources it must return them in a finite amount of time.



Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- **Available:** Vector of length m . If $available[j] = k$, there are k instances of resource type R_j available
- **Max:** $n \times m$ matrix. If $Max[i,j] = k$, then process P_i may request at most k instances of resource type R_j



Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- **Allocation:** $n \times m$ matrix. If $\text{Allocation}[i,j] = k$ then P_i is currently allocated k instances of R_j
- **Need:** $n \times m$ matrix. If $\text{Need}[i,j] = k$, then P_i may need k more instances of R_j to complete its task

$$\text{Need}[i,j] = \text{Max}[i,j] - \text{Allocation}[i,j]$$



Safety Algorithm

1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively.

Initialize:

$Work = Available$

$Finish[i] = false$ for $i = 0, 1, \dots, n-1$

2. Find an *i* such that both:

(a) $Finish[i] = false$

(b) $Need_i \leq Work$

If no such *i* exists, go to step 4

3. $Work = Work + Allocation_i$

$Finish[i] = true$

go to step 2

4. If $Finish[i] == true$ for all *i*, then the system is in a safe state

Resource-Request Algorithm for Process P_i

- Algorithm determines whether requests can be safely granted.
- **$Request_i$** = ***request*** vector for process P_i
- If **$Request_i[j] = k$** then process P_i wants **k** instances of resource type R_j

Resource-Request Algorithm for Process P_i (Cont.)

1. If $Request_i \leq Need_i$ go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim.
2. If $Request_i \leq Available$, go to step 3. Otherwise, P_i must wait, since resources are not available.
3. Pretend to allocate requested resources to P_i by modifying the state as follows:
 - $Available = Available - Request_i;$
 - $Allocation_i = Allocation_i + Request_i;$
 - $Need_i = Need_i - Request_i;$
 - If safe \Rightarrow the resources are allocated to P_i
 - If unsafe $\Rightarrow P_i$ must wait, and the old resource-allocation state is restored



Example of Banker's Algorithm

- 5 processes P_0 through P_4 ;

3 resource types:

A (10 instances), B (5 instances), and C (7 instances)

- Snapshot at time T_0 :

	<u>Allocation</u>	<u>Max</u>	<u>Available</u>
	A B C	A B C	A B C
P_0	0 1 0	7 5 3	3 3 2
P_1	2 0 0	3 2 2	
P_2	3 0 2	9 0 2	
P_3	2 1 1	2 2 2	
P_4	0 0 2	4 3 3	



Example (Cont.)

- The content of the matrix ***Need*** is defined to be ***Max – Allocation***

	<u><i>Need</i></u>		
	<i>A</i>	<i>B</i>	<i>C</i>
P_0	7	4	3
P_1	1	2	2
P_2	6	0	0
P_3	0	1	1
P_4	4	3	1

- The system is in a safe state since the sequence $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria.

Example: P_1 Request (1,0,2)

- Check that Request \leq Available (that is, $(1,0,2) \leq (3,3,2) \Rightarrow$ true

	<u>Allocation</u>	<u>Need</u>	<u>Available</u>
	A B C	A B C	A B C
P_0	0 1 0	7 4 3	2 3 0
P_1	3 0 2	0 2 0	
P_2	3 0 2	6 0 0	
P_3	2 1 1	0 1 1	
P_4	0 0 2	4 3 1	

- Executing safety algorithm shows that sequence $\langle P_1, P_3, P_4, P_0, P_2 \rangle$ satisfies safety requirement
- Can request for (3,3,0) by P_4 be granted?
- Can request for (0,2,0) by P_0 be granted?