

~/ros2\_ws3/src/talkerlistener/setup.py

```
1 from setuptools import setup, find_packages
2 import os
3 from glob import glob
4
5 package_name = 'talkerlistener'
6
7 setup(
8     name=package_name,
9     version='0.0.0',
10    packages=find_packages(exclude=['test']),
11    data_files=[
12        ('share/ament_index/resource_index/packages',
13         ['resource/talkerlistener']),
14        ('share/talkerlistener', ['package.xml']),
15        (os.path.join('share', 'talkerlistener', 'launch'), glob('launch/
16 *.py')),
17    ],
18    install_requires=['setuptools'],
19    zip_safe=True,
20    maintainer='sunidhi270',
21    maintainer_email='sunidhi270@todo.todo',
22    description='TODO: Package description',
23    license='TODO: License declaration',
24    tests_require=['pytest'],
25    entry_points={
26        'console_scripts': [
27            'talker = talkerlistener.talker:main',
28            'listener = talkerlistener.listener:main',
29        ],
30    },
31 )
```