|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| cid:image001.jpg@01D3E1F2.B4A565F0 | Supervision Meeting Notes  |  |  |  |  | | --- | --- | --- | --- | | Taught |  |  |  | |

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| Student Name | Sébastien Lambert | | | | | |
| Student Number | 416349 | | | | | |
| Course | MSc Autonomous Vehicle Dynamics and Control | | | | | |
| Supervisors | Saba Al-Rubaye, Dmitry Ignatyev, Christantus Nnamani | | | | | |
| Date of Meeting | 06/06/2024 | | | | | |
| Meeting by | In person |  | Telephone |  | Skype / Webconferencing |  |

|  |
| --- |
| Decisions / Actions agreed and by whom |
| Feedback on the presentation for the first progress review presentation:   * First slides should explain the aim of the project, the “why” * Need to add milestones to the Gantt chart   Put the optimization of the trajectory in a stretch goal |
|  |

|  |
| --- |
| Date of next meeting |
| 13/06/2024 |
|  |