view_frames Result

Recorded at time: 1548798334.643

base_link

Broadcaster: /tool_change
Average rate: 936.317 Hz
Most recent transform: 1548798334.643 (-0.000 sec old)
Buffer length: 4.978 sec

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1548798334.584 (0.059 sec old)
Buffer length: 4.898 sec

Broadcaster: /kinect
Average rate: 1.250 Hz
Most recent transform: 1548798335.165 (-0.522 sec old)
Buffer length: 4.000 sec

tool_change_clearance

Broadcaster: /tool_1
Average rate: 935.660 Hz
Most recent transform: 1548798334.644 (-0.001 sec old)
Buffer length: 4.978 sec

Broadcaster: /tool_2
Average rate: 935.786 Hz
Most recent transform: 1548798334.643 (-0.000 sec old)
Buffer length: 4.975 sec

Broadcaster: /tool_3
Average rate: 935.732 Hz
Most recent transform: 1548798334.643 (0.000 sec old)
Buffer length: 4.975 sec

link_1

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1548798334.584 (0.059 sec old)
Buffer length: 4.898 sec

camera_link

Broadcaster: /camera_base_link
Average rate: 10.191 Hz
Most recent transform: 1548798334.720 (-0.077 sec old)
Buffer length: 4.907 sec

Broadcaster: /camera_base_link1
Average rate: 10.193 Hz
Most recent transform: 1548798334.718 (-0.075 sec old)
Buffer length: 4.905 sec

tool_tes

tool_vac

tool_j17

link_2

camera_depth_frame

camera_rgb_frame

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1548798334.584 (0.059 sec old)
Buffer length: 4.898 sec

Broadcaster: /camera_base_link2
Average rate: 10.197 Hz
Most recent transform: 1548798334.715 (-0.071 sec old)
Buffer length: 4.904 sec

Broadcaster: /camera_base_link3
Average rate: 10.196 Hz
Most recent transform: 1548798334.729 (-0.085 sec old)
Buffer length: 4.904 sec

link_3

camera_depth_optical_frame

camera_rgb_optical_frame

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1548798334.584 (0.059 sec old)
Buffer length: 4.898 sec

Broadcaster: /cv_pc_fusion
Average rate: 2.016 Hz
Most recent transform: 1548798334.554 (0.090 sec old)
Buffer length: 4.465 sec

link_4

flap_raw

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1548798334.584 (0.059 sec old)
Buffer length: 4.898 sec

link_5

Broadcaster: /robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1548798334.584 (0.059 sec old)
Buffer length: 4.898 sec

link_6

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1548798334.643 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1548798334.643 sec old)
Buffer length: 0.000 sec

Broadcaster: /camera
Average rate: 935.513 Hz
Most recent transform: 1548798334.644 (-0.001 sec old)
Buffer length: 4.981 sec

eoat

tool0

arm_camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1548798334.643 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1548798334.643 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1548798334.643 sec old)
Buffer length: 0.000 sec

blue

green

red