# **System Test Plan**

# For

# Speech Recognition for Air Traffic Control

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#### 1. Introduction

#### 1.1. Purpose

This document is a test plan for the Speech Recognition for Air Traffic Control System Testing, produced by the Scrum team. It describes the testing strategy and approach to testing the team will use to verify the application meets the established requirements of the customer prior to release. It contains separate details for how to test both the website and the neural model. If these tests are completed, they validate the system is complete. The system is not considered to be complete until all of the tests run successfully.

#### 1.2. Objectives

Features that will be the objects of testing that are identified and classified into a hierarchy.

- Meets the requirements, specifications and the Business rules.
- Supports the intended business functions and achieves the required standards.
- Satisfies the Entrance Criteria for User Acceptance Testing.

## 2. Functional Scope

The Modules in the scope of testing for the Speech Recognition for Air Traffic Control System Testing are as follows:

- Interactive map on website
- Aeronautical map on website
- Nvidia Nemo Model

## 3. Overall Strategy and Approach

#### 3.1. Testing Strategy

The Speech Recognition for Air Traffic Control System Testing will include the testing of all functionalities that are in the scope (Refer to Functional pe Section) identified. System testing activities will include the testing of new functionalities, modified functionalities, screen level validations, workflows, functionality access, and the testing of internal and external interfaces.

#### Website

The website will be tested using Puppeteer to validate the presence of required elements on the page. Test cases will be written to navigate through the website and assert that the required items are present. The test cases will be generated from the requirements document.

#### **Neural Model**

The neural model will be tested using prepared labeled testing data made from the provided ATC data. Using this data, we will calculate word error rate and word error rate per utterance for each of the models. We will be targeting a word error rate and word error rate per utterance of around  $\sim$ .20. The current best word error rate claimed in industry is around  $\sim$ .05[1]. However, this is achieved using the resources accessible by large corporations and thus is not within the scope of our project.

#### 3.2. System Testing Entrance Criteria

In order to start system testing, certain requirements must be met for testing readiness. Readiness can be classified into:

#### Website:

The website will be ready for testing when all components that are required from the backlog to be included are present. The website must be hosted on the desktop machine provided and publicly available with a static IP address. Both versions of the maps must be functional with planes visible. The neural model must

be fully functional, and the website must be connected to the neural model.

#### Neural model:

The entrance criteria for the neural model testing is that the model(s) have been trained on the labeled ATC data. The testing scripts have been prepared and debugged and novel training data has been prepared.

#### 3.3. Testing Types

#### 3.3.1. Usability Testing

User interface attributes, cosmetic presentation and content will be tested for accuracy and general usability. The goal of Usability Testing is to ensure that the User Interface is comfortable to use and provides the user with consistent and appropriate access and navigation through the functions of the application (e.g., access keys, consistent tab order, readable fonts etc.)

#### 3.3.2. Functional Testing

The objective of this test is to ensure that each element of the component meets the functional requirements of the customer as outlined in the:

- Functional Requirements
- Business rules or conditions
- Issue resolutions
- Feedback

#### 3.4. Suspension Criteria and Resumption Requirements

This section specifies the criteria that will be used to suspend all or a portion of the testing activities on the items associated with this test plan.

#### 3.4.1. Suspension Criteria

Testing will be suspended if the incidents found will not allow further testing of the system/application under-test. If testing is halted, and changes are made to the hardware, software or database, it is up to the Testing Manager to determine whether the test plan will be re-executed, or part of the plan will be re-executed.

4.

Website Incidents:

- Website goes offline during testing
- Assertion test failed
- Unit test encounters exception
- Unable to get data from flight tracker
- Update of VFR map failed

Neural Model Incidents:

- Model fails to load
- Training data is not novel to the model

## 4.1.1. Resumption Requirements

Resumption of testing will be possible when the functionality that caused the suspension of testing has been retested successfully.

#### **4.1.2.** Website Resumption

• Check to see if data from Opensky API is writing to the correct file(s) if no

- issues found attempt to run Opensky outside of website
- Check to see if FAA map API is saving data to correct file(s) is no issues found check if FAA map download link functions

## 4.1.3. Neural Model Resumption

- Check for issues in model file e.g., corrupted file, check all dependencies installed if no issues found attempt to reload model
- Get data novel to the model either from provided datasets or other methods

#### 4.1.4.

## 5. Execution Plan

#### 5.1. Execution Plan

The execution plan will detail the test cases to be executed. The Execution plan will be put together to ensure that all the requirements are covered. The execution plan will be designed to accommodate some changes, if necessary, if testing is incomplete on any day. All the test cases of the projects under test in this release are arranged in a logical order depending upon their inter dependency.

Test Cases

| ID       | Name                   | System  | Actions   | Success Criteria   |
|----------|------------------------|---------|---|--|
| W1       | Website load           | Website | Visit the website's URL in Chrome   | The website shall load without any errors in 1 second.                           |
| W1.<br>5 | Website load           | Website | Visit the website's URL in Chrome   | The website shall display the interactive map with a toggle in 1 second.         |
| W2       | Map buttons zoom in    | Website | Click the plus button on the interactive map  | The map zooms in by one tile level.  |
| W3       | Map buttons zoom out   | Website | Click the minus button on the interactive map   | The map zooms out by one tile level.   |
| W4       | Map buttons zoom in 2  | Website | Click the plus button on the VFR map  | The map zooms in by one tile level.  |
| W5       | Map buttons zoom out 2 | Website | Click the plus button on the VFR map  | The map zooms out by one tile level.   |
| W6       | Map zoom max<br>out    | Website | Load the website, then click the minus button 13 times on the interactive map. Then click once more | On the last click, the map should not zoom out anymore. It should stay the same. |
| W7       | Map zoom max in        | Website | Click the map zoom in<br>button 5 times on the<br>interactive map. Then<br>click once more          | On the last click, the map should not zoom in anymore. It should stay the same.  |
| W8       | Map zoom max out 2     | Website | Click the map zoom out<br>button 4 times on the<br>VFR map. Then click<br>once more                 | On the last click, the map should not zoom out anymore. It should stay the same. |
| W9       | Map zoom max in        | Website | Click the map zoom in   | On the last click, the map should  |

|     | 2                                       |         | button 1 times on the<br>VFR map. Then click<br>once more  | not zoom in anymore. It should stay the same.   |
|-----|---|---------|--|---|
| W10 | Map pan                                 | Website | Click on the interactive map and drag the mouse to the right.  | The tiles of the map move, with some tiles disappearing off the left side of the screen and new tiles appearing on the right side of the screen.  |
| W11 | Map pan 2                               | Website | Click on the VFR map<br>and drag the mouse to<br>the right   | The tiles of the map move, with some tiles disappearing off the left side of the screen and new tiles appearing on the right side of the screen.  |
| W12 | Plane loading on interactive map        | Website | Visit the website's URL in Chrome. Click the minus button to zoom out 5 times.   | The interactive map should contain at least one plane icon.   |
| W13 | Plane loading on<br>VFR map             | Website | Visit the website's URL in Chrome, click the toggle button, then click the minus button to zoom out 5 times.   | The VFR map should contain at least one plane icon.   |
| W14 | Plane movement<br>on interactive<br>map | Website | Visit the website's URL in Chrome. Hover your mouse over any plane icon. Wait 15 seconds. Observe the new location of the icon.                          | The plane icon is removed from the old location and placed in the new location within 15 seconds.   |
| W15 | Plane movement<br>on VFR map            | Website | Visit the website's URL in Chrome. Click the toggle button. Hover your mouse over any plane icon. Wait 15 seconds. Observe the new location of the icon. | The plane icon is removed from the old location and placed in the new location within 15 seconds.   |
| W16 | Validate plane<br>coordinates 1         | Website | Visit the website's URL in Chrome, then click on any plane   | Copy and paste the coordinates listed in the textbox into Google Maps. Validate that the plane on the interactive map is in the same geographical location as on the Google map with a 100ft margin of error. |
| W17 | Validate plane<br>coordinates 2         | Website | Visit the website's URL in Chrome, click the toggle button, then click on any plane  | Copy and paste the coordinates listed into Google Maps. Validate that the plane on the VFR map is in the same geographical location as on the Google map with a 100ft margin of error.                        |
| W18 | Validate plane<br>heading 1             | Website | Visit the website's URL in Chrome, then click on   | The plane icon's rotation should be the number of degrees clockwise   |

|     |   |         | any plane. Observe the track field from the textbox.  | starting with 0 pointing upwards based on the value of the track value.  |
|-----|---|---------|---|--|
| W19 | Validate plane<br>heading 2                       | Website | Visit the website's URL in Chrome, click the toggle button, then click on any plane. Observe the track field from the textbox.  | The plane icon's rotation should be the number of degrees clockwise starting with 0 pointing upwards based on the value of the track value.                              |
| W20 | Toggle button                                     | Website | Visit the website's URL in Chrome, click the toggle button, then click the toggle button again.   | The map starts at the interactive map, then changes to the VFR map, then changes back to the interactive map.  |
| W21 | Info box is updated                               | Website | Visit the website. Click<br>any plane. Observe the<br>information in the<br>textbox. Wait 15<br>seconds. Observe the<br>information again.  | The value of the information in the textbox before the 15 seconds and after the 15 seconds should be different.  |
| W22 | Click plane for details                           | Website | Visit the website, click on any plane.  | The textbox is populated with data for the clicked plane.  |
| W23 | Live transcription                                | Website | Visit the website, click on any plane.  | The textbox is populated with the LiveATC stream transcription for KDAB.   |
| W24 | Live transcription update                         | Website | Visit the website, click<br>on any plane icon. Wait<br>15 seconds.  | The old ATC transcription is replaced with new transcription text.   |
| W25 | Live transcription validation                     | Website | Visit LiveATC, go to KDAB, and listen to the live audio. Then, visit the website and click on any plane icon. Observe the ATC transcription.  | Verify that the transcription roughly matches what is being said in the live audio, with some delay permitted. The audio will be said before the transcription is shown. |
| W26 | Text box drag                                     | Website | Visit the website and click on a plane. Click on the floating textbox and drag it to the right, then release the mouse.   | The textbox will move with the mouse to the right.   |
| W27 | Verify plane<br>coordinates on<br>Interactive map | Website | Visit the website, and click on any plane icon. Look at the output of the floating textbox for coordinates. Enter the plane's callsign into the OpenSky API and observe the output. | The coordinates from the text box should match the coordinates shown in the OpenSky API.   |
| W28 | Verify plane coordinates on                       | Website | Visit the website, click the toggle button, then  | Compare coordinates given in the text box with the coordinates given   |

|     | VFR map                         |              | click on any plane icon.<br>Look at the output of the<br>floating text box for<br>coordinates.  | from the open sky API   |
|-----|---------------------------------|--------------|---|---|
| W29 | Interactive Map<br>Scale        | Website      | Visit the website   | Observe that a scale shows in the bottom left of the map that says 1mi. |
| W30 | Interactive Map<br>Scale Change | Website      | Visit the website, click<br>the minus button to<br>zoom out and observe<br>how the scale changes.<br>Repeat clicking and<br>observing again.                                  | The scale should go from 1mi, then 2mi, then 3mi.                       |
| W31 | VFR Map Scale                   | Website      | Visit the website and click the toggle button   | Observe that a scale shows in the bottom left of the map that says 3mi. |
| W32 | VFR Map Scale<br>Change         | Website      | Visit the website, click<br>the toggle button, then<br>click the minus button to<br>zoom out and observe<br>how the scale changes.<br>Repeat clicking and<br>observing again. | The scale should go from 3mi, then 5mi, then 10mi.                      |
| M1  | Word error rate                 | ASR<br>Model | Run testing scripts for word error rate   | The model achieves a word error rate of .2 or less                      |
| M2  | Word error rate per utterance   | ASR<br>Model | Run testing scripts for<br>word error rate per<br>utterance   | The model achieves a word error rate of .2 or less                      |
| M3  | Precision, Recall,<br>F1 scores | ASR<br>Model | Run testing scripts for precision, recall, f1   | The model achieves scores in those                                      |

## 6. Traceability Matrix & Defect Tracking

## 6.1. Traceability Matrix

Requirements that start with an "A" indicate advanced requirements. These are not going to be addressed until a later sprint.

| Requirement | Test Case   |
|-------------|-------------|
| SIR 3       | W23, W25    |
| SIR 4       | W1, W1.5    |
| SIR 5       | W20         |
| SIR 6       | W29, W31    |
| SIR 7       | Coming soon |
| SIR 8       | W22         |
| SIR 9       | W22         |
| SIR 10      | W26         |
| SIR 11      | W1, W1.5    |
| SIR 12      | W10, W11    |

| SIR 13         | W12, W13, W14, W15, W16, W17   |
|----------------|--------------------------------|
| SIR 14         | W22                            |
| SIR 15         | W23, W24                       |
| SIR 17, SIR 18 | W30, W32                       |
| SIR 19         | W18, W19                       |
| USR 1          | W20                            |
| USR 2          | W22                            |
| USR 3          | W26                            |
| USR 4          | W2, W3, W4, W5, W6, W7, W8, W9 |
| USR 5          | W10, W11                       |
| AUSR 1         | Coming soon                    |
| AUSR 2         | Coming soon                    |
| AUSR 3         | Coming soon                    |
| AUSR 4         | Coming soon                    |
| AUSR 5         | Coming soon                    |
| AUSR 6         | Coming soon                    |
| AUSR 7         | Coming soon                    |
| AUSR 8         | Coming soon                    |

## 6.2. Defect Severity Definitions

| Critical | API data is corrupted   |
|----------|---|
|          | <ul> <li>Server is down</li> </ul>                                |
|          | Model data is corrupted   |
|          | <ul> <li>Configuration Files from ATC Stream corrupted</li> </ul> |
| Medium   | <ul> <li>Plane loads into incorrect location</li> </ul>           |
|          | Text Box doesn't appear   |
|          | <ul> <li>Toggle Button doesn't work as anticipated</li> </ul>     |
|          | • Word Error rate is higher than 0.2 for the model                |
| Low      | Website map positioning loads incorrectly                         |
|          | • Word Error rate is 0.2 for the model                            |
|          | <ul> <li>Website takes longer than 5 seconds to load</li> </ul>   |
|          | <ul> <li>Text Box loads incorrect text</li> </ul>                 |

## 7. Environment

## 7.1. Testing Tools

The System Testing Environment will be used for System Testing.

## Website:

Puppeteer

#### Neural Model:

Manual validation of statistics

## **7.2.** Testing Environment

The System Requirements for testing are as follows:

### Hardware

Dedicated Nvidia NeMo-compatible graphics card

## Software

- Desktop: RedHat Enterprise Linux V8.6 or Ubuntu 22
- Laptop: Windows 11 Pro Version 21H2

- Python Version 3.6 to 3.8
- PyTorch Version 1.8.1
- Opensky Version 1.3.0
- Pandas Version 1.5.1
- Pytz Version 2022.6
- Python-dateutil Version 2.8.2
- Requests Version 2.28.1
- See requirements file for all requirements for testing the web server.

## 8. Assumptions

- Testers have access to a compatible NVIDIA GPU
- Puppeteer test cases are run using Python
- Testers have followed the Opensky-install.txt file to get the package(s) for the Opensky API

## 9. Risks and Contingencies

| Risk                                      | Contingency  |
|---|--|
| Plane coordinate fetching API not working | Display the last locations of the planes until the |
|   | API comes back.                                    |
| Model outputs poor transcription          | Deploy an additional website for closed            |
|   | crowd-sourced model transcription validation.      |
| Website is offline                        | Display an error message in place of the website   |
|   | indicating that the website is temporarily         |
|   | unavailable.                                       |
| Model is unavailable                      | Temporarily pause transcriptions and replace with  |
|   | a message saying, "Temporarily unavailable".       |

## 10. Appendices

## a. Links

- [1] https://smartaction.ai/blog/does-word-error-rate-matter
- [2] The OpenSky Network, <a href="https://opensky-network.org">https://opensky-network.org</a>