Лабораторная работа №6

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Цель лабораторной работы: изучение методов классификации текстов.

Требования к отчету:

Отчет по лабораторной работе должен содержать:

- титульный лист;
- описание задания;
- текст программы;
- экранные формы с примерами выполнения программы.

Задание - для произвольного набора данных, предназначенного для классификации текстов, решите задачу классификации текста двумя способами:

- Способ 1. Ha основе CountVectorizer или TfidfVectorizer.
- Способ 2. На основе моделей word2vec или Glove или fastText.

```
import nltk
import spacy
import numpy as np
from sklearn.datasets import fetch_20newsgroups
nltk.download('punkt')
from nltk import tokenize
import re
import pandas as pd
[nltk_datal_Downloading_package_punkt_to_/root/pltk_data]
```

[nltk_data] Downloading package punkt to /root/nltk_data...
[nltk_data] Package punkt is already up-to-date!

Будем использовать датасет 20 newsgroups

```
In [5]:
         print('Tokenizers NLTK have')
         for i in dir(tokenize)[:16]:
           print(i)
        Tokenizers NLTK have
        BlanklineTokenizer
        LineTokenizer
        MWETokenizer
        PunktSentenceTokenizer
        RegexpTokenizer
        ReppTokenizer
        SExprTokenizer
        SpaceTokenizer
        StanfordSegmenter
        TabTokenizer
        TextTilingTokenizer
        ToktokTokenizer
        TreebankWordTokenizer
        TweetTokenizer
        WhitespaceTokenizer
        WordPunctTokenizer
       Подготовка текстов
In [6]:
         from spacy.lang.en import English
         import spacy
         from nltk.corpus import stopwords
         nlp = spacy.load("en core web sm", disable=["parser", "ner"])
         nltk.download('stopwords')
         stopwords eng = set(stopwords.words('english'))
        [nltk data] Downloading package stopwords to /root/nltk_data...
        [nltk data]
                      Package stopwords is already up-to-date!
In [7]:
         def prepare(t):
           # t = ' '.join([i.strip().lower() for i in t.split(' ')])
           t = re.sub(r'[^a-zA-Z0-9 \n]', '', t)
           t = re.sub('\s+', ' ', t)
           t = ' '.join([token.lemma .lower() for token in nlp(t) if token not in stop
           return t
         texts = newsgroups train.data
         texts array = []
         for text in texts:
           prepared_text = prepare(text)
           texts_array.append(prepared_text)
In [8]:
         len(texts array), texts array[-1]
        (2760,
Out[8]:
         'from amolitormoinknmsuedu andrew molitor subject what the clipper naysayer
        sound like to -pron- organization department of mathematical sciences lines 5
        5 distribution na nntppostinghost moinknmsuedu originator amolitormoinknmsued
        u the follow be available in some ftp archive somewhere -pron- insert -pron-
        comment liberally throughout this demonic memo of big brotherdom white house
        announcement on screw thread standards this be to announce that the american
```

national standards institute or whatever -pron- be have be give the authority to define standard dimension for screw thread look this be clearly the first

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> step toward outlaw -pron- own screw thread specification if this madness be n ot fight tooth and nail every step of the way -pron- will be a crime to use s crew thread other than those -pron- fearless leader so graciously define for -pron- the purpose of this be to permit industry to draw upon a standard pool of specification and designation to ensure interoperability of various thread object across vendor rubbish -pron- say ansi standard screw thread will have subtle weakness allow -pron- agent to disassemble -pron- automobile more easi ly cause -pron- muffler to fall off at inoppurtune moment questions and answe rs on the ansi screw thread standard q will the screw thread define by ansi b e as good as other screw thread design available elsewhere a yes hah trust -p ron- q will -pron- be able to use -pron- own screw thread if -pron- desire a of course but this will make -pron- thread object unlikely to interoperate co rrectly with other within the industry see see this be the first step -pronbe clear -pron- must band together write -pron- congressman use pretty good s crew thread not this devilinspire ansi trash protect -pron- constitutional ri ght to use whatever screw thread -pron- desire guerilla screw thread activism must become the order of the day boycott gm and build -pron- own car use scre w from stz screw thread associates screw -pron- bill clinton -pron- and -pron - totalitarianist thug amolitornmsuedu finger for pgst personal screw thread pitch or screw thread see the screw thread server must be free')

```
In [9]:
         test_texts_arr = []
         test texts = newsgroups test.data
         for text in test texts:
           prepared text = prepare(text)
           test texts arr.append(prepared text)
```

Способ 1 Ha основе CountVectorizer и TfidfVectorizer

```
In [10]:
          from sklearn.feature extraction.text import TfidfVectorizer, CountVectorizer
          from sklearn.neighbors import KNeighborsClassifier
          from sklearn.metrics import classification report
In [11]:
          tfidf vectorizer = TfidfVectorizer()
          train_feature_matrix_tfidf = tfidf_vectorizer.fit_transform(texts_array)
          test feature matrix tfidf = tfidf vectorizer.transform(test texts arr)
In [12]:
          count vectorizer = CountVectorizer()
          train feature matrix count = count vectorizer.fit transform(texts array)
          test_feature_matrix_count = count_vectorizer.transform(test_texts_arr)
In [13]:
          target values train = newsgroups train.target
          target values test = newsgroups test.target
        knn with count vectorizer
```

```
In [31]:
          from sklearn.model selection import GridSearchCV
          knn count = KNeighborsClassifier()
          parameters = {'n_neighbors': [2, 3, 5, 7, 9, 11]}
          knn_count_grid = GridSearchCV(knn_count, parameters, scoring='roc auc ovr wei
```

```
verbose=4, cv=5)
knn count grid.fit(train feature matrix count, target values train)
# print(pd.DataFrame(knn count grid.cv results ))
print('best param of n_neighbors', knn_count_grid.best_params_['n_neighbors']
best knn count = KNeighborsClassifier(n neighbors=knn count grid.best params
print(best knn count)
best knn count.fit(train feature matrix count, target values train)
best knn pred count = best knn count.predict(test feature matrix count)
print(classification report(target values test, pred count))
```

```
Fitting 5 folds for each of 6 candidates, totalling 30 fits
[CV] n neighbors=2 ......
[CV] ...... n_neighbors=2, score=0.844, total= 0.2s
[CV] n neighbors=2 ......
[Parallel(n jobs=1)]: Using backend SequentialBackend with 1 concurrent worke
                1 out of 1 | elapsed:
[Parallel(n jobs=1)]: Done
                               0.2s remaining:
0s
[CV] ...... n neighbors=2, score=0.837, total=
[CV] ...... n_neighbors=2, score=0.861, total= 0.2s
[CV] n_neighbors=2 .....
[Parallel(n jobs=1)]: Done
                2 out of 2 | elapsed:
                               0.3s remaining:
                                          0.
[Parallel(n jobs=1)]: Done
                3 out of 3 | elapsed:
                               0.5s remaining:
                                          0.
0s
[CV] ...... n neighbors=2, score=0.833, total=
[CV] n neighbors=2 .....
[CV] ..... n neighbors=2, score=0.842, total=
[CV] n neighbors=3 ......
[CV] ..... n neighbors=3, score=0.862, total= 0.2s
[CV] n neighbors=3 ......
[CV] ..... n neighbors=3, score=0.858, total= 0.2s
[CV] n neighbors=3 ......
[CV] ..... n neighbors=3, score=0.863, total= 0.2s
[CV] n neighbors=3 ......
[CV] ..... n neighbors=3, score=0.849, total= 0.2s
[CV] ..... n neighbors=3, score=0.858, total= 0.2s
[CV] n neighbors=5 ......
[CV] ...... n_neighbors=5, score=0.864, total= 0.2s
[CV] n neighbors=5 ......
[CV] ...... n_neighbors=5, score=0.858, total= 0.2s
[CV] n neighbors=5 .....
[CV] ...... n_neighbors=5, score=0.867, total= 0.2s
[CV] ...... n_neighbors=5, score=0.854, total= 0.2s
[CV] ...... n_neighbors=5, score=0.869, total= 0.2s
[CV] n_neighbors=7 ......
[CV] ...... n_neighbors=7, score=0.865, total= 0.2s
[CV] n_neighbors=7 ......
[CV] ...... n neighbors=7, score=0.863, total= 0.2s
[CV] n_neighbors=7 ......
[CV] ...... n_neighbors=7, score=0.871, total= 0.2s
[CV] n_neighbors=7 ......
[CV] ...... n_neighbors=7, score=0.840, total= 0.2s
[CV] n_neighbors=7 ......
[CV] ...... n_neighbors=7, score=0.873, total= 0.2s
[CV] n_neighbors=9 ......
[CV] ...... n_neighbors=9, score=0.861, total= 0.2s
[CV] n_neighbors=9 ......
[CV] ...... n_neighbors=9, score=0.862, total= 0.2s
[CV] n_neighbors=9 .....
[CV] ...... n_neighbors=9, score=0.874, total= 0.2s
```

```
[CV] n_neighbors=9 ......
[CV] ...... n_neighbors=9, score=0.838, total= 0.2s
[CV] n_neighbors=9 .....
[CV] ...... n_neighbors=9, score=0.871, total= 0.2s
[CV] ...... n_neighbors=11, score=0.861, total= 0.2s
[CV] n_neighbors=11 .....
[CV] ...... n_neighbors=11, score=0.857, total= 0.2s
[CV] n_neighbors=11 .....
[CV] ...... n_neighbors=11, score=0.872, total= 0.2s
[CV] n_neighbors=11 .....
[CV] ..... n neighbors=11, score=0.841, total= 0.2s
[CV] n neighbors=11 .....
[CV] ...... n neighbors=11, score=0.870, total= 0.2s
best param of n neighbors 5
KNeighborsClassifier(algorithm='auto', leaf size=30, metric='minkowski',
              metric params=None, n jobs=None, n neighbors=5, p=2,
              weights='uniform')
[Parallel(n jobs=1)]: Done 30 out of 30 | elapsed:
                                      5.1s finished
         precision
                 recall f1-score
                               support
                    0.71
       0
             0.38
                          0.49
                                  396
       1
             0.64
                   0.55
                          0.59
                                  399
       2
             0.63
                   0.53
                          0.58
                                  396
       3
            0.53
                   0.36
                          0.43
                                  396
            0.57
                   0.35
                          0.44
                                  251
                          0.51
                                 1838
  accuracy
            0.55
0.55
                   0.50
  macro avg
                          0.51
                                 1838
weighted avg
            0.55
                   0.51
                          0.51
                                 1838
```

knn with tfidf vectorizer

```
0s
                3 out of 3 | elapsed:
[Parallel(n jobs=1)]: Done
                               0.5s remaining:
[CV] ...... n_neighbors=2, score=0.833, total=
[CV] n_neighbors=2 .....
[CV] ...... n_neighbors=2, score=0.842, total= 0.2s
[CV] n_neighbors=3 ......
[CV] ...... n_neighbors=3, score=0.862, total= 0.2s
[CV] n_neighbors=3 ......
[CV] ...... n_neighbors=3, score=0.858, total= 0.2s
[CV] n_neighbors=3 .....
[CV] ...... n_neighbors=3, score=0.863, total= 0.2s
[CV] n_neighbors=3 .....
[CV] ...... n_neighbors=3, score=0.849, total= 0.2s
[CV] n neighbors=3 .....
[CV] ...... n neighbors=3, score=0.858, total= 0.2s
[CV] n neighbors=5 .....
[CV] ...... n neighbors=5, score=0.864, total= 0.2s
[CV] n neighbors=5 .....
[CV] ...... n neighbors=5, score=0.858, total= 0.2s
[CV] n neighbors=5 .....
[CV] ...... n neighbors=5, score=0.867, total= 0.2s
[CV] n neighbors=5 .....
[CV] ...... n neighbors=5, score=0.854, total= 0.2s
[CV] n neighbors=5 .....
[CV] ...... n neighbors=5, score=0.869, total= 0.2s
[CV] n neighbors=7 .....
[CV] ...... n neighbors=7, score=0.865, total= 0.2s
[CV] n neighbors=7 .....
[CV] ...... n neighbors=7, score=0.863, total= 0.2s
[CV] n neighbors=7 ......
[CV] ...... n neighbors=7, score=0.871, total= 0.2s
[CV] n neighbors=7 ......
[CV] ...... n neighbors=7, score=0.840, total= 0.2s
[CV] n neighbors=7 ......
[CV] ...... n neighbors=7, score=0.873, total= 0.2s
[CV] n neighbors=9 ......
[CV] ...... n neighbors=9, score=0.861, total= 0.2s
[CV] n neighbors=9 ......
[CV] ...... n neighbors=9, score=0.862, total= 0.2s
[CV] n neighbors=9 ......
[CV] ...... n neighbors=9, score=0.874, total= 0.2s
[CV] n neighbors=9 ......
[CV] ..... n neighbors=9, score=0.838, total= 0.2s
[CV] n_neighbors=9 ......
[CV] ...... n_neighbors=9, score=0.871, total= 0.2s
[CV] n neighbors=11 .....
[CV] ...... n_neighbors=11, score=0.861, total= 0.2s
[CV] n neighbors=11 .....
[CV] ...... n_neighbors=11, score=0.857, total= 0.2s
[CV] n neighbors=11 .....
[CV] n neighbors=11 .....
[CV] n_neighbors=11 .....
[CV] ...... n_neighbors=11, score=0.870, total=
best param of n neighbors 3
[Parallel(n_jobs=1)]: Done 30 out of 30 | elapsed:
                               5.1s finished
       precision recall f1-score
                          support
      0
          0.91
                0.93
                      0.92
                            396
      1
          0.97
                0.89
                      0.93
                            399
      2
          0.83
                0.88
                      0.86
                            396
      3
          0.95
                0.64
                      0.76
                            396
          0.57
                0.87
                      0.69
                            251
                      0.84
                           1838
  accuracy
                0.84
                      0.83
                           1838
          0.85
 macro avg
```

0.

In [7]:

import tadm

weighted avg 0.87 0.84 0.84 1838

Способ 2 На основе моделей word2vec или Glove или fastText.

```
from gensim.models import Word2Vec
         import gensim.downloader
         # gensim.downloader.info()
         # glove vectors = gensim.downloader.load('glove-twitter-25')
         glove vectors = gensim.downloader.load('glove-wiki-gigaword-50')
In [8]:
         class GloveTokenizer:
           def __init__(self, glove_tokenizer):
             self.glove = glove tokenizer
             self.token length = 800
             self.embedding size = 50
           def getitem (self, word):
               vector = glove vectors.get vector(word).reshape(1, self.embedding size)
             except KeyError as e:
               vector = np.zeros((1, self.embedding size))
             return vector
           def padd(self, sentence):
             padded sentence = np.zeros((self.token length, self.embedding size))
             for i, token in enumerate(sentence):
                 padded sentence[i] = token
             return padded_sentence
           def tokenize(self, sentence):
             encoded sentence = []
             sentence = sentence.strip(' ').split(' ')
             for i in sentence:
               token = self.__getitem__(i)
               encoded sentence.append(token)
             return np.array(self.__padd(encoded_sentence), dtype=np.float16)
         tokenizer = GloveTokenizer(glove vectors)
In [9]:
         def prepare(t):
           # t = ' '.join([i.strip().lower() for i in t.split(' ')])
           t = re.sub(r'[^a-zA-Z0-9]', '', t)
           t = re.sub('\s+', ' ', t)
           lemmas = [token.lemma_.lower() for token in nlp(t) if token not in stopword
           t = ' '.join(lemmas)
           vectors = tokenizer.tokenize(t)
           return vectors, len(lemmas)
         vectors_array_train = []
         labels_train = []
         for enum, text, label in zip(range(len(newsgroups_train.data)), newsgroups_tr
           try:
             vector, length = prepare(text)
             # print(vector, vector.shape)
             vectors_array_train.append(vector)
```

```
labels_train.append(label)
except IndexError as e:
    print(enum, e)
    continue

vectors_array_train = np.array(vectors_array_train)
print(vectors_array_train.shape)
train_data = vectors_array_train.reshape((-1, vectors_array_train.shape[1]*vetrain_data.shape
```

```
58 index 800 is out of bounds for axis 0 with size 800
93 index 800 is out of bounds for axis 0 with size 800
112 index 800 is out of bounds for axis 0 with size 800
147 index 800 is out of bounds for axis 0 with size 800
159 index 800 is out of bounds for axis 0 with size 800
214 index 800 is out of bounds for axis 0 with size 800
215 index 800 is out of bounds for axis 0 with size 800
217 index 800 is out of bounds for axis 0 with size 800
222 index 800 is out of bounds for axis 0 with size 800
265 index 800 is out of bounds for axis 0 with size 800
268 index 800 is out of bounds for axis 0 with size 800
281 index 800 is out of bounds for axis 0 with size 800
336 index 800 is out of bounds for axis 0 with size 800
361 index 800 is out of bounds for axis 0 with size 800
395 index 800 is out of bounds for axis 0 with size 800
412 index 800 is out of bounds for axis 0 with size 800
416 index 800 is out of bounds for axis 0 with size 800
424 index 800 is out of bounds for axis 0 with size 800
462 index 800 is out of bounds for axis 0 with size 800
468 index 800 is out of bounds for axis 0 with size 800
480 index 800 is out of bounds for axis 0 with size 800
568 index 800 is out of bounds for axis 0 with size 800
574 index 800 is out of bounds for axis 0 with size 800
585 index 800 is out of bounds for axis 0 with size 800
587 index 800 is out of bounds for axis 0 with size 800
588 index 800 is out of bounds for axis 0 with size 800
591 index 800 is out of bounds for axis 0 with size 800
680 index 800 is out of bounds for axis 0 with size 800
696 index 800 is out of bounds for axis 0 with size 800
708 index 800 is out of bounds for axis 0 with size 800
714 index 800 is out of bounds for axis 0 with size 800
715 index 800 is out of bounds for axis 0 with size 800
733 index 800 is out of bounds for axis 0 with size 800
734 index 800 is out of bounds for axis 0 with size 800
743 index 800 is out of bounds for axis 0 with size 800
753 index 800 is out of bounds for axis 0 with size 800
816 index 800 is out of bounds for axis 0 with size 800
901 index 800 is out of bounds for axis 0 with size 800
911 index 800 is out of bounds for axis 0 with size 800
962 index 800 is out of bounds for axis 0 with size 800
965 index 800 is out of bounds for axis 0 with size 800
1015 index 800 is out of bounds for axis 0 with size 800
1022 index 800 is out of bounds for axis 0 with size 800
1112 index 800 is out of bounds for axis 0 with size 800
1116 index 800 is out of bounds for axis 0 with size 800
1155 index 800 is out of bounds for axis 0 with size 800
1167 index 800 is out of bounds for axis 0 with size 800
1170 index 800 is out of bounds for axis 0 with size 800
1173 index 800 is out of bounds for axis 0 with size 800
1181 index 800 is out of bounds for axis 0 with size 800
1265 index 800 is out of bounds for axis 0 with size 800
1269 index 800 is out of bounds for axis 0 with size 800
1292 index 800 is out of bounds for axis 0 with size 800
1294 index 800 is out of bounds for axis 0 with size 800
1357 index 800 is out of bounds for axis 0 with size 800
1372 index 800 is out of bounds for axis 0 with size 800
```

56 index 800 is out of bounds for axis 0 with size 800

```
1398 index 800 is out of bounds for axis 0 with size 800
1412 index 800 is out of bounds for axis 0 with size 800
1413 index 800 is out of bounds for axis 0 with size 800
1422 index 800 is out of bounds for axis 0 with size 800
1426 index 800 is out of bounds for axis 0 with size 800
1429 index 800 is out of bounds for axis 0 with size 800
1442 index 800 is out of bounds for axis 0 with size 800
1462 index 800 is out of bounds for axis 0 with size 800
1481 index 800 is out of bounds for axis 0 with size 800
1501 index 800 is out of bounds for axis 0 with size 800
1527 index 800 is out of bounds for axis 0 with size 800
1551 index 800 is out of bounds for axis 0 with size 800
1584 index 800 is out of bounds for axis 0 with size 800
1586 index 800 is out of bounds for axis 0 with size 800
1592 index 800 is out of bounds for axis 0 with size 800
1605 index 800 is out of bounds for axis 0 with size 800
1620 index 800 is out of bounds for axis 0 with size 800
1625 index 800 is out of bounds for axis 0 with size 800
1672 index 800 is out of bounds for axis 0 with size 800
1728 index 800 is out of bounds for axis 0 with size 800
1766 index 800 is out of bounds for axis 0 with size 800
1781 index 800 is out of bounds for axis 0 with size 800
1804 index 800 is out of bounds for axis 0 with size 800
1811 index 800 is out of bounds for axis 0 with size 800
1812 index 800 is out of bounds for axis 0 with size 800
1819 index 800 is out of bounds for axis 0 with size 800
1825 index 800 is out of bounds for axis 0 with size 800
1832 index 800 is out of bounds for axis 0 with size 800
1854 index 800 is out of bounds for axis 0 with size 800
1883 index 800 is out of bounds for axis 0 with size 800
1891 index 800 is out of bounds for axis 0 with size 800
1908 index 800 is out of bounds for axis 0 with size 800
1924 index 800 is out of bounds for axis 0 with size 800
1958 index 800 is out of bounds for axis 0 with size 800
2005 index 800 is out of bounds for axis 0 with size 800
2061 index 800 is out of bounds for axis 0 with size 800
2086 index 800 is out of bounds for axis 0 with size 800
2105 index 800 is out of bounds for axis 0 with size 800
2138 index 800 is out of bounds for axis 0 with size 800
2149 index 800 is out of bounds for axis 0 with size 800
2167 index 800 is out of bounds for axis 0 with size 800
2175 index 800 is out of bounds for axis 0 with size 800
2180 index 800 is out of bounds for axis 0 with size 800
2220 index 800 is out of bounds for axis 0 with size 800
2243 index 800 is out of bounds for axis 0 with size 800
2260 index 800 is out of bounds for axis 0 with size 800
2262 index 800 is out of bounds for axis 0 with size 800
2304 index 800 is out of bounds for axis 0 with size 800
2328 index 800 is out of bounds for axis 0 with size 800
2356 index 800 is out of bounds for axis 0 with size 800
2373 index 800 is out of bounds for axis 0 with size 800
2391 index 800 is out of bounds for axis 0 with size 800
2419 index 800 is out of bounds for axis 0 with size 800
2428 index 800 is out of bounds for axis 0 with size 800
2462 index 800 is out of bounds for axis 0 with size 800
2466 index 800 is out of bounds for axis 0 with size 800
2469 index 800 is out of bounds for axis 0 with size 800
2487 index 800 is out of bounds for axis 0 with size 800
2500 index 800 is out of bounds for axis 0 with size 800
2517 index 800 is out of bounds for axis 0 with size 800
2559 index 800 is out of bounds for axis 0 with size 800
2603 index 800 is out of bounds for axis 0 with size 800
2616 index 800 is out of bounds for axis 0 with size 800
2628 index 800 is out of bounds for axis 0 with size 800
2652 index 800 is out of bounds for axis 0 with size 800
2669 index 800 is out of bounds for axis 0 with size 800
2678 index 800 is out of bounds for axis 0 with size 800
2683 index 800 is out of bounds for axis 0 with size 800
2743 index 800 is out of bounds for axis 0 with size 800
```

```
2754 index 800 is out of bounds for axis 0 with size 800 (2633, 800, 50)
Out[9]: (2633, 40000)
```

```
In [10]:
    vectors_array_test = []
    labels_test= []

    for enum, text, label in zip(range(len(newsgroups_test.data)), newsgroups_test
        try:
        vector, length = prepare(text)
        vectors_array_test.append(vector)
        labels_test.append(label)
        except IndexError as e:
        print(enum, e)
        continue
```

```
67 index 800 is out of bounds for axis 0 with size 800
76 index 800 is out of bounds for axis 0 with size 800
124 index 800 is out of bounds for axis 0 with size 800
137 index 800 is out of bounds for axis 0 with size 800
292 index 800 is out of bounds for axis 0 with size 800
298 index 800 is out of bounds for axis 0 with size 800
350 index 800 is out of bounds for axis 0 with size 800
432 index 800 is out of bounds for axis 0 with size 800
435 index 800 is out of bounds for axis 0 with size 800
476 index 800 is out of bounds for axis 0 with size 800
484 index 800 is out of bounds for axis 0 with size 800
525 index 800 is out of bounds for axis 0 with size 800
558 index 800 is out of bounds for axis 0 with size 800
618 index 800 is out of bounds for axis 0 with size 800
680 index 800 is out of bounds for axis 0 with size 800
710 index 800 is out of bounds for axis 0 with size 800
720 index 800 is out of bounds for axis 0 with size 800
778 index 800 is out of bounds for axis 0 with size 800
780 index 800 is out of bounds for axis 0 with size 800
802 index 800 is out of bounds for axis 0 with size 800
819 index 800 is out of bounds for axis 0 with size 800
825 index 800 is out of bounds for axis 0 with size 800
836 index 800 is out of bounds for axis 0 with size 800
862 index 800 is out of bounds for axis 0 with size 800
882 index 800 is out of bounds for axis 0 with size 800
956 index 800 is out of bounds for axis 0 with size 800
960 index 800 is out of bounds for axis 0 with size 800
989 index 800 is out of bounds for axis 0 with size 800
1064 index 800 is out of bounds for axis 0 with size 800
1101 index 800 is out of bounds for axis 0 with size 800
1108 index 800 is out of bounds for axis 0 with size 800
1152 index 800 is out of bounds for axis 0 with size 800
1187 index 800 is out of bounds for axis 0 with size 800
1193 index 800 is out of bounds for axis 0 with size 800
1293 index 800 is out of bounds for axis 0 with size 800
1313 index 800 is out of bounds for axis 0 with size 800
1386 index 800 is out of bounds for axis 0 with size 800
1443 index 800 is out of bounds for axis 0 with size 800
1455 index 800 is out of bounds for axis 0 with size 800
1463 index 800 is out of bounds for axis 0 with size 800
1477 index 800 is out of bounds for axis 0 with size 800
1482 index 800 is out of bounds for axis 0 with size 800
1529 index 800 is out of bounds for axis 0 with size 800
1552 index 800 is out of bounds for axis 0 with size 800
1560 index 800 is out of bounds for axis 0 with size 800
1561 index 800 is out of bounds for axis 0 with size 800
1629 index 800 is out of bounds for axis 0 with size 800
1631 index 800 is out of bounds for axis 0 with size 800
1639 index 800 is out of bounds for axis 0 with size 800
1664 index 800 is out of bounds for axis 0 with size 800
1709 index 800 is out of bounds for axis 0 with size 800
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1717 index 800 is out of bounds for axis 0 with size 800
         1770 index 800 is out of bounds for axis 0 with size 800
         1837 index 800 is out of bounds for axis 0 with size 800
In [11]:
          vectors array test = np.array(vectors array test)
          test data = vectors array test.reshape((-1, vectors array test.shape[1]*vectors
          test data.shape
Out[11]: (1784, 40000)
In [17]:
          from sklearn.neighbors import KNeighborsClassifier
          from sklearn.model selection import GridSearchCV
          glove knn clf = KNeighborsClassifier()
          parameters = {'n neighbors': [2, 3, 5, 7, 9]}
          glove clf grid = GridSearchCV(glove knn clf, parameters, verbose=4, cv=3,
                                       scoring='roc auc ovr weighted', n jobs=-1)
          glove clf grid.fit(train data, labels train)
          print('best param of n neighbors', glove clf grid.best params ['n neighbors']
         Fitting 3 folds for each of 5 candidates, totalling 15 fits
         [Parallel(n jobs=-1)]: Using backend LokyBackend with 2 concurrent workers.
         [Parallel(n jobs=-1)]: Done 15 out of 15 | elapsed: 22.2min finished
         best param of n neighbors 9
         NameError
                                                    Traceback (most recent call last)
         <ipython-input-17-8b00f2d61c86> in <module>()
              20
              21
         ---> 22 print(classification report(labels test[:800], best pred glove knn))
         NameError: name 'classification report' is not defined
In [18]:
          from sklearn.metrics import classification report
          best glove knn = KNeighborsClassifier(n neighbors=glove clf grid.best params
          best_glove_knn.fit(train_data, labels_train)
          best pred glove knn = best glove knn.predict(test data[:800])
          print(classification_report(labels_test[:800], best_pred_glove_knn))
                       precision
                                     recall f1-score
                                                        support
                    0
                             0.28
                                       0.83
                                                 0.42
                                                             169
                    1
                             0.49
                                       0.23
                                                 0.32
                                                             171
                    2
                             0.51
                                       0.19
                                                 0.28
                                                             180
                    3
                             0.42
                                       0.17
                                                 0.24
                                                             164
                            0.46
                                       0.32
                                                 0.38
                                                             116
                                                 0.35
                                                             800
             accuracy
                            0.43
                                       0.35
                                                 0.33
                                                             800
            macro avq
                            0.43
                                       0.35
                                                 0.32
                                                             800
         weighted avg
```