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# RAVEN Workshop

Advanced UQ With Collocation Methods

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### **Overview**



### Overview: Session Goal

Use advanced methods to accelerate UQ

- For low dimensionality, far fewer runs
- For smooth respones, provides accurate ROMs
- ROMs contain analytic mean, variance, sensitivities



# **Motivations**



### Motivations: Monte Carlo

Gold standard in UQ is Monte Carlo, Latin Hypercube

- Consistently convergent (central limit theorem)
- Easy to develop
- Error diminishes slowly
- Requires  $1/\epsilon^2$  samples to achieve error  $\epsilon$



### Motivations: Alternatives to Monte Carlo

Some structured samplers can improve greatly on Monte Carlo Example: Stochastic Collocation for generalized Polynomial Chaos

- Expand model in orthogonal polynomials
- Use integration to determine expansion coefficients
- Quadrature methods perform polynomial integrations

Input dimensions need to be orthogonalized before running



# Methods



# Methods: generalized Polynomial Chaos expansion

$$f(x) \approx G(x) = \sum_{k \in \Lambda} c_k \Phi_k(x),$$
 (1)

#### where

- f(x) is the original model,
- x are the uncertain inputs in f(x),
- G(x) is the generalized Polynomial Chaos expansion,
- k is a multi-index to a polynomial, e.g. (3,1,2),
- A is a pre-determined set of polynomial indices,
- c<sub>k</sub> are expansion coefficients,
- $\Phi_k(x)$  are multidimensional orthogonal polynomials



# Methods: gPC Coefficients

$$f(x) \approx G(x) = \sum_{k \in \Lambda} c_k \Phi_k(x),$$
 (2)

 $\Phi_k(x)$  are orthogonal,

$$c_k = \int_{\Omega} \rho(x) f(x) \Phi_k(x) dx \tag{3}$$

where  $\rho(x)$  is the joint probability distribution. Numerically, use quadratures for  $c_k$ 

$$c_k \approx \sum_{\ell=1}^L w_\ell f(x_\ell) \Phi_k(x_\ell)$$
 (4)

where  $w_{\ell}$  are the weights and  $x_{\ell}$  are the points



# Methods: Large Dimensionality

Tensor SCgPC only efficient if N < 4Fight curse of dimensionality using Sparse Grids

- Hyperbolic Cross
- Total Degree
- Smolyak Quadrature



# Methods: SCgPC in RAVEN

### **ROM**

### Sampler



# Methods: SCgPC in RAVEN

### Steps

```
<RomTrainer name="train">
     <Input class="DataObjects" type="PointSet">collset</Input>
     <Output class="Models" type="ROM">rom</Output>
     </RomTrainer>
```

```
<IOStep name="stats">
     <Input class="Models" type="ROM">rom</Input>
     <Output class="OutStreams" type="Print">stats_tp2</Output>
</IOStep>
```



# Methods: Interpolation Node

What if I want to use a different quadrature? What if some dimensions require higher-order polynomials than others? Specify through an interpolation node



# Methods: Adaptive

# What if I don't know what dimensions are higher order? Use the Adaptive SCgPC sampler!

```
<AdaptiveSparseGrid name="sc">
  <variable name="v1">
    <distribution>uni</distribution>
  </variable>
  <variable name="v2">
    <distribution>uni</distribution>
  </variable>
  <ROM class="Models" type="ROM">rom</ROM>
  <Restart class="DataObjects" type="PointSet">collset</Restart>
  <TargetEvaluation class="DataObjects" type="PointSet">collset</TargetEvaluat
  <Convergence maxRuns="100" target="variance">le-15/Convergence>
  <convergenceStudy>
    <runStatePoints>4,8,16,32,64</runStatePoints>
    <baseFilename>stats adapt/baseFilename>
  </convergenceStudy>
</AdaptiveSparseGrid>
```



# **Methods: Sobol Decomposition**



# **Methods: Sobol Decomposition**

### Another kind of expansion

$$f(x, y, z) = f_0$$
+  $f_1(x) + f_2(y) + f_3(z)$ 
+  $f_{1,2}(x, y) + f_{1,3}(x, z) + f_{2,3}(y, z)$ 
+  $f_{1,2,3}(x, y, z)$ ,

where  $f_1(x) = \int \int f(x, y, z) dy dz$ , etc. Benefits:

- Many problems dominated by low-order interacations
- Provides easy access to Sobol sensitivities
- Each sub-term can be modelled as SCgPC ROM
  - Most are dimension 2 or less!
- Can also be constructed adaptively
  - Highest efficiency: Adaptive Sobol with Adaptive SCgPC



### Methods: Sobol in RAVEN

### Sampler

```
<AdaptiveSobol name="sc">
  <variable name="y1">
    <distribution>uni</distribution>
  </variable>
  <variable name="v2">
    <distribution>uni</distribution>
  </variable>
  <ROM class="Models" type="ROM">rom</ROM>
  <Restart class="DataObjects" type="PointSet">collset</Restart>
  <TargetEvaluation class="DataObjects" type="PointSet">collset</TargetEvaluat.
  <convergenceStudy>
    <runStatePoints>4,8,16,32,64</runStatePoints>
    <baseFilename>stats adsob</baseFilename>
  </convergenceStudy>
  <estimateMethod>product</estimateMethod>
  <Convergence>
    <relTolerance>1e-30</relTolerance>
    <maxRuns>100</maxRuns>
    <maxSobolOrder>2</maxSobolOrder>
    <logFile>adsob.log</logFile>
  </Convergence>
</AdaptiveSobol>
```



### Methods: Sobol in RAVEN

### **ROM**

```
<ROM name="rom" subType="HDMRRom">
    <Target>ans</Target>
    <Features>y1,y2</Features>
    <IndexSet>TotalDegree</IndexSet>
    <PolynomialOrder>1</PolynomialOrder>
    <SobolOrder>5</SobolOrder>
</ROM>
```



# **Demonstration: Attenuation Problem**



### Demonstration: the Model

$$f(x) = \prod_{n=1}^{N} \exp(-x_n/N), \tag{5}$$

$$X_n \sim \mathcal{U}(0,1).$$
 (6)

Taylor expansion suggests many combinations of high-order terms

$$\exp(-x) = 1 - x + \frac{x^2}{2!} - \frac{x^3}{3!} + \cdots$$
 (7)

### Expected:

- · Tensor Product, Total Degree, Adaptive perform well
- · Hyperbolic Cross should struggle



# Demonstration: Results

### Two-dimension case

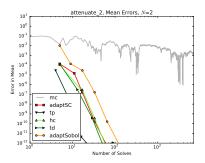


Figure: Mean, N = 2

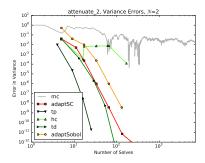


Figure: Variance, N = 2



# Demonstration: Results

### Four-dimension case

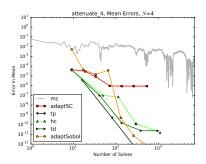


Figure: Mean, N = 4

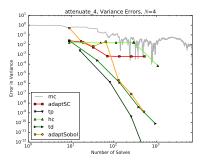


Figure: Variance, N = 4



# Demonstration: Results

### Six-dimension case

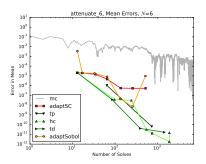


Figure: Mean, N = 6

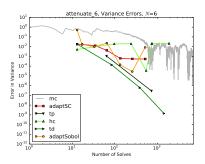


Figure: Variance, N = 6