

# ***RAVEN Workshop***

## ***Advanced UQ With Collocation Methods***

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## ***Overview***

## ***Overview: Session Goal***

Use advanced methods to accelerate UQ

- For low dimensionality, far fewer runs
- For smooth responses, provides accurate ROMs
- ROMs contain analytic mean, variance, sensitivities

## ***Motivations***

## ***Motivations: Monte Carlo***

Gold standard in UQ is Monte Carlo, Latin Hypercube

- Consistently convergent (central limit theorem)
- Easy to develop
- Error diminishes slowly
- Requires  $1/\epsilon^2$  samples to achieve error  $\epsilon$

## ***Motivations: Alternatives to Monte Carlo***

Some structured samplers can improve greatly on Monte Carlo

Example: Stochastic Collocation for generalized Polynomial Chaos

- Expand model in orthogonal polynomials
- Use integration to determine expansion coefficients
- Quadrature methods perform polynomial integrations

Input dimensions need to be orthogonalized before running

## ***Methods***



## ***Methods: generalized Polynomial Chaos expansion***

$$f(x) \approx G(x) = \sum_{k \in \Lambda} c_k \Phi_k(x), \quad (1)$$

where

- $f(x)$  is the original model,
- $x$  are the uncertain inputs in  $f(x)$ ,
- $G(x)$  is the generalized Polynomial Chaos expansion,
- $k$  is a multi-index to a polynomial, e.g. (3,1,2),
- $\Lambda$  is a pre-determined set of polynomial indices,
- $c_k$  are expansion coefficients,
- $\Phi_k(x)$  are multidimensional orthogonal polynomials

## Methods: gPC Coefficients

$$f(x) \approx G(x) = \sum_{k \in \Lambda} c_k \Phi_k(x), \quad (2)$$

$\Phi_k(x)$  are orthogonal,

$$c_k = \int_{\Omega} \rho(x) f(x) \Phi_k(x) dx \quad (3)$$

where  $\rho(x)$  is the joint probability distribution.

Numerically, use quadratures for  $c_k$

$$c_k \approx \sum_{\ell=1}^L w_{\ell} f(x_{\ell}) \Phi_k(x_{\ell}) \quad (4)$$

where  $w_{\ell}$  are the weights and  $x_{\ell}$  are the points

## ***Methods: Large Dimensionality***

Tensor SCgPC only efficient if  $N < 4$

Fight curse of dimensionality using Sparse Grids

- Hyperbolic Cross
- Total Degree
  
- Smolyak Quadrature

## Methods: SCgPC in RAVEN

### ROM

```
<ROM name="rom" subType="GaussPolynomialRom">
  <Target>ans</Target>
  <Features>y1,y2</Features>
  <IndexSet>TensorProduct</IndexSet>
  <PolynomialOrder>2</PolynomialOrder>
</ROM>
```

### Sampler

```
<SparseGridCollocation name="sc">
  <variable name="y1">
    <distribution>uni</distribution>
  </variable>
  <variable name="y2">
    <distribution>uni</distribution>
  </variable>
  <ROM class="Models" type="ROM">rom</ROM>
  <Restart class="DataObjects" type="PointSet">collset</Restart>
</SparseGridCollocation>
```

## Methods: SCgPC in RAVEN

### Steps

```
<MultiRun name="sample" sleepTime="1e-4">  
  <Input class="DataObjects" type="PointSet">dummyIN</Input>  
  <Sampler class="Samplers" type="SparseGridCollocation">sc</Sampler>  
  <Model class="Models" type="ExternalModel">poly</Model>  
  <Output class="DataObjects" type="PointSet">collset</Output>  
</MultiRun>
```

```
<RomTrainer name="train">  
  <Input class="DataObjects" type="PointSet">collset</Input>  
  <Output class="Models" type="ROM">rom</Output>  
</RomTrainer>
```

```
<IOStep name="stats">  
  <Input class="Models" type="ROM">rom</Input>  
  <Output class="OutStreams" type="Print">stats_tp2</Output>  
</IOStep>
```

## ***Methods: Interpolation Node***

What if I want to use a different quadrature?

What if some dimensions require higher-order polynomials than others?

Specify through an interpolation node

```
<ROM name="rom" subType="GaussPolynomialRom">  
  <Target>ans</Target>  
  <Features>y1,y2</Features>  
  <IndexSet>TotalDegree</IndexSet>  
  <PolynomialOrder>3</PolynomialOrder>  
  <Interpolation quad="Legendre" weight="0.7">y1</Interpolation>  
  <Interpolation quad="Legendre" weight="0.5">y2</Interpolation>  
</ROM>
```

## Methods: Adaptive

What if I don't know what dimensions are higher order?

Use the Adaptive SCgPC sampler!

```
<AdaptiveSparseGrid name="sc">
  <variable name="y1">
    <distribution>uni</distribution>
  </variable>
  <variable name="y2">
    <distribution>uni</distribution>
  </variable>
  <ROM class="Models" type="ROM">rom</ROM>
  <Restart class="DataObjects" type="PointSet">collset</Restart>
  <TargetEvaluation class="DataObjects" type="PointSet">collset</TargetEvaluation>
  <Convergence maxRuns="100" target="variance">1e-15</Convergence>
  <convergenceStudy>
    <runStatePoints>4, 8, 16, 32, 64</runStatePoints>
    <baseFilename>stats_adapt</baseFilename>
  </convergenceStudy>
</AdaptiveSparseGrid>
```

## ***Methods: Sobol Decomposition***



## Methods: Sobol Decomposition

Another kind of expansion

$$\begin{aligned}
 f(x, y, z) = & f_0 \\
 & + f_1(x) + f_2(y) + f_3(z) \\
 & + f_{1,2}(x, y) + f_{1,3}(x, z) + f_{2,3}(y, z) \\
 & + f_{1,2,3}(x, y, z),
 \end{aligned}$$

where  $f_1(x) = \int \int f(x, y, z) dy dz$ , etc.

Benefits:

- Many problems dominated by low-order interactions
- Provides easy access to Sobol sensitivities
- Each sub-term can be modelled as SCgPC ROM
  - Most are dimension 2 or less!
- Can also be constructed adaptively
  - Highest efficiency: Adaptive Sobol with Adaptive SCgPC

## Methods: Sobol in RAVEN

### Sampler

```

<AdaptiveSobol name="sc">
  <variable name="y1">
    <distribution>uni</distribution>
  </variable>
  <variable name="y2">
    <distribution>uni</distribution>
  </variable>
  <ROM class="Models" type="ROM">rom</ROM>
  <Restart class="DataObjects" type="PointSet">collset</Restart>
  <TargetEvaluation class="DataObjects" type="PointSet">collset</TargetEvaluation>
  <convergenceStudy>
    <runStatePoints>4, 8, 16, 32, 64</runStatePoints>
    <baseFilename>stats_adsob</baseFilename>
  </convergenceStudy>
  <estimateMethod>product</estimateMethod>
  <Convergence>
    <relTolerance>1e-30</relTolerance>
    <maxRuns>100</maxRuns>
    <maxSobolOrder>2</maxSobolOrder>
    <logFile>adsob.log</logFile>
  </Convergence>
</AdaptiveSobol>
  
```

## Methods: Sobol in RAVEN

### ROM

```
<ROM name="rom" subType="HDMRRom">  
  <Target>ans</Target>  
  <Features>y1,y2</Features>  
  <IndexSet>TotalDegree</IndexSet>  
  <PolynomialOrder>1</PolynomialOrder>  
  <SobolOrder>5</SobolOrder>  
</ROM>
```

## ***Demonstration: Attenuation Problem***

## Demonstration: the Model

$$f(x) = \prod_{n=1}^N \exp(-x_n/N), \quad (5)$$

$$x_n \sim \mathcal{U}(0, 1). \quad (6)$$

Taylor expansion suggests many combinations of high-order terms

$$\exp(-x) = 1 - x + \frac{x^2}{2!} - \frac{x^3}{3!} + \cdots \quad (7)$$

Expected:

- Tensor Product, Total Degree, Adaptive perform well
- Hyperbolic Cross should struggle

## ***Demonstration: Attenuation Problem***

### Files:

- `hc6.xml`
- `td3.xml`
- `tp2.xml`
- `adaptSC.xml`
- `adaptSobol.xml`
- `stats_[case].xml`

# Demonstration: Results

## Two-dimension case

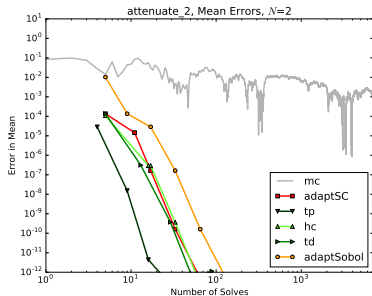


Figure : Mean,  $N = 2$

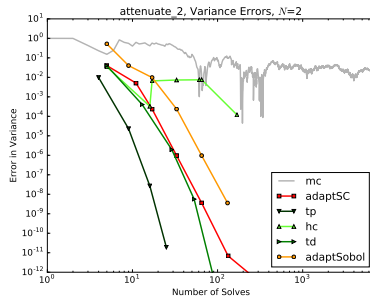


Figure : Variance,  $N = 2$

## Demonstration: Results

### Four-dimension case

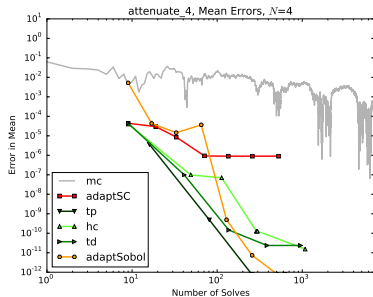


Figure : Mean,  $N = 4$

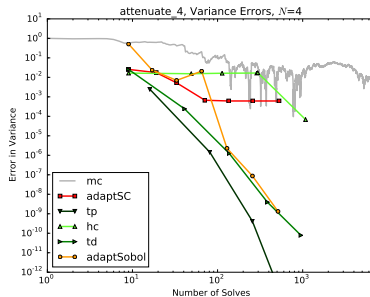


Figure : Variance,  $N = 4$



# Demonstration: Results

## Six-dimension case

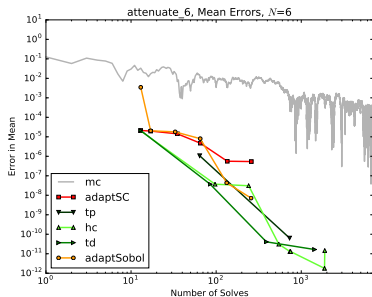


Figure : Mean,  $N = 6$

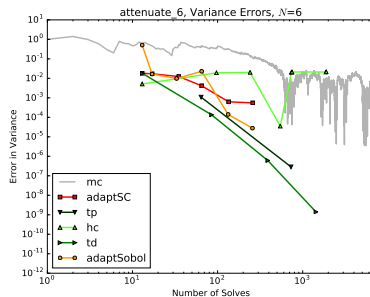


Figure : Variance,  $N = 6$

## ***End of Session***

## Demonstration: Results

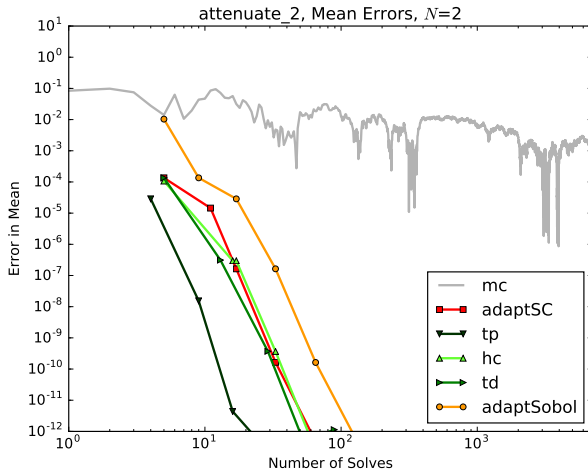


Figure : Mean,  $N = 2$

## Demonstration: Results

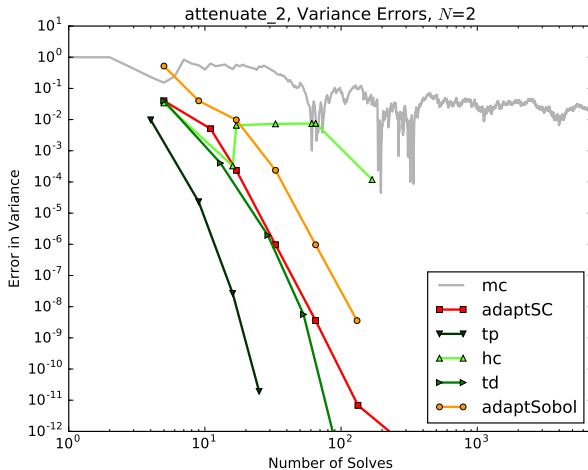


Figure : Variance,  $N = 2$

# Appendix

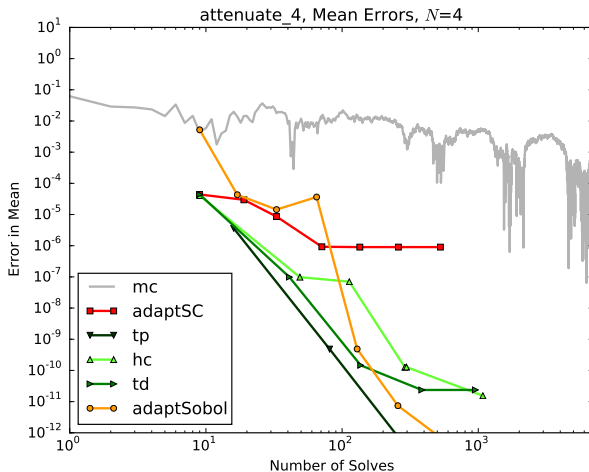


Figure : Mean,  $N = 4$

# Appendix

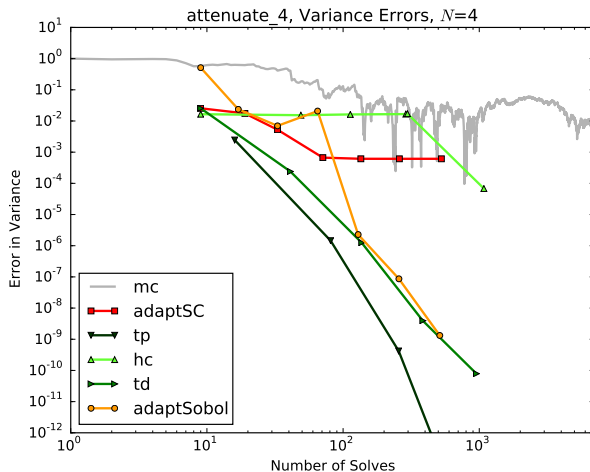


Figure : Variance,  $N = 4$

# Appendix

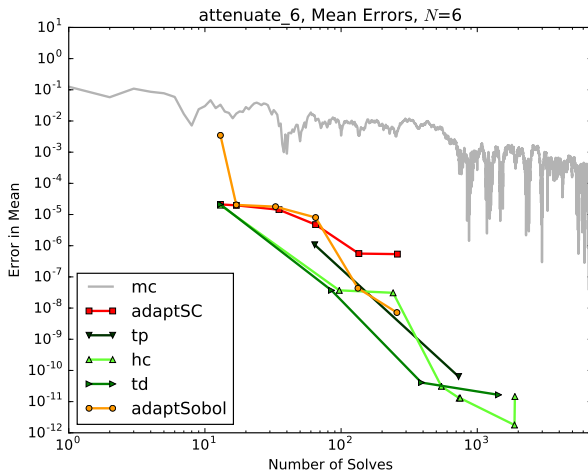


Figure : Mean,  $N = 6$

# Appendix

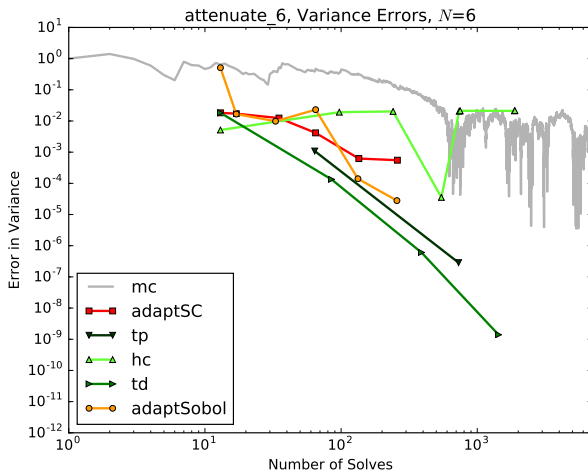


Figure : Variance,  $N = 6$