Efficient Calculation of Interaction Features on Sparse Matrices

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Abstract

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1 Introduction

Introduction Interaction features are a way of capturing correlations between features in a machine learning setting. A feature vector \vec{x} of dimensionality D has second degree interaction features $\{x_i \cdot x_j : i, j \in \{0, 1, ..., D-1\} \land i < j\}$, so a D dimensional vector has $\binom{D}{2} = \frac{D^2 - D}{2}$ second degree interaction features. A naive approach to calculating these features is to simply iterate through the combinations of the column indices. For a sparse vector, many of the resulting interaction features would be zero, and could therefore be ignored. This work describes a method to efficiently calculate second degree interaction features for a sparse matrix that has time and space complexities that decrease quadratically with the density of the input matrix with respect to the naive approach.

2 Approach

Let the list of nonzero columns for a given row \vec{x} be denoted by N_{zc} . The nonzero second degree interaction features are simply the products of all combinations of two elements whose columns are in N_{zc} . However, to properly place an interaction feature into the correct column, a mapping from the column index pairs of N_{zc} into the columns of the interaction matrix is

needed. The mapping is from pairs (a, b), where a and b are in 1, 2, ..., D, and a < b, to $1, 2, ..., \frac{D^2 - D}{2}$, Such a mapping essentially consists of mapping the indices of entries in the upper triangle of a matrix to indices in a flat list. We now describe the construction of such a mapping.

2.1 Mapping construction

We seek a map from matrix indices (i,j) (with i < j and $0 \le i < D$) to numbers f(i,j) with $0 \le f(i,j) < \frac{D(D-1)}{2}$, one that follows the pattern indicated by

$$\begin{bmatrix} x & 0 & 1 & 2 \\ x & x & 3 & 4 \\ x & x & x & 5 \\ x & x & x & x \end{bmatrix}$$
 (1)

It's considerably easier, however, to consider the same indices, but subtracted from 6 (or more generally, from $\frac{D(D-1)}{2}$; that gives the pattern

$$\begin{bmatrix} x & 6 & 5 & 4 \\ x & x & 3 & 2 \\ x & x & x & 1 \\ x & x & x & x \end{bmatrix}$$
 (2)

We'll call the function defined by this example $(i, j) \mapsto g(i, j)$, and then observe that

$$f(i,j) = \frac{D(D-1)}{2} - g(i,j)$$
 (3)

To simplify slightly, we introduce a notation for the nth triangular number,

$$\left[T_2(n) = \frac{n(n+1)}{2}\right] \tag{4}$$

The subscript 2 is there to indicate that these are triangles in two dimensions; we'll use $T_3(n)$ to indicate the nth tetrahedral number, and so on for higher dimensions.

The codomain of g is now numbers from 1 to $T_2(D-1)$, inclusive.

Observe that in Equation ??, each entry in row i lies in the range

$$T_2(D-i-1) < e \le T_2(D-i).$$
 (5)

For instance, in row 2 in our example, where D=4, the entries range from 2 to 3, while $T_2(D-i-1)=T_2(1)=1$ and $T_2(D-i)=T_2(2)=3$. (Note that row indices start at zero.) Unfortunately, the numbers increase from right to left. The entry in column j is just $T_2(D-i-1)+D-j$, which adds one for the rightmost column (because D-(D-1)=1). Thus, the formula for g is simply

$$g(i,j) = T_2(D-i-1) + (D-j)$$
(6)

$$= \frac{(D-i-1)(D-i)}{2} + D - j \tag{7}$$

$$=\frac{(D^2 - (2i)D - D - i^2 - i) + 2D - 2j}{2} \tag{8}$$

$$=\frac{D^2 - (2i)D + D - i^2 - i - 2j}{2} \tag{9}$$

and hence

$$f(i,j) = \frac{D(D-1)}{2} - g(i,j)$$
(10)

$$=\frac{D^2-D}{2}-\frac{D^2-(2i)D+D-i^2-i-2j}{2}$$
(11)

$$=\frac{D^2-D-D^2+(2i)D-D+i^2+i+2j}{2}$$
 (12)

$$=\frac{(2i)D - 2D + i^2 + i + 2j}{2} \tag{13}$$

[WRONG] Correct result:

$$R = \frac{2in - i^2 + 2j - 3i - 2}{2}. (14)$$

2.1.1 Other indices

With one-based indexing, the formula above becomes

$$f_1(i,j) = \dots (15)$$

column

INSERT JOHN'S PROOF HERE

With this mapping, an algorithm for generating second degree interaction features on a matrix A can be formulated as follows:

```
Sparse Interaction(A)  \max(a,b) = \frac{2Da - a^2 + 2b - 3a - 2}{2} 
N = \text{row count of } A
D = \text{column count of } A
 B = \text{Compressed Sparse Row Matrix of size } N \times \frac{D^2 - D}{2} 
 \text{for } row \text{ in } A
 N_{zc} = \text{nonzero columns of } row 
 \text{for } i = 0 \text{ to } |N_{zc}| - 1 
 \text{for } j = i + 1 \text{ to } |N_{zc}| 
 k = \max(i,j) 
 r = \text{index of } row 
 B[r,k] = row[i] \cdot row[j]
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3 Complexity Analysis

Assume that A is a matrix with sparsity 0 < d < 1, N rows, and D columns. Finding interaction features with the proposed algorithm has time and space complexity $O(dND^2)$, whereas a naive approach of using non-sparse matrices and multiplying all column combinations has time and space complexity $O(ND^2)$. The algorithm is therefore an improvement by a factor of the density factor of A.

This can represent a large gain in speed and time. For example, the 20 Newsgroups dataset has density d of 0.12 when its unigrams are represented in a vector space model. This means the proposed approach would take less than $\frac{1}{8}$ time and memory.

The real benefit of this method is revealed when the average complexity is analysed. The number of interactions calculated for a given row are $\binom{|N_{zc}|}{2}$. If the matrix has density d, then on average, $N_{zc} = Dd$, so the number of interaction features calculated in total is

$$N\binom{dD}{2} = N\frac{(Dd)!}{2!(Dd-2)!}$$
$$= N\frac{(D^2d^2 - Dd)}{2}$$

This means that the average complexity decreases quadratically with the density.

4 Future Work

The approach for generating second degree interaction features required a mapping from combinations of two to the space $1, 2, ..., \frac{D^2 - D}{2}$, which is isomorphic to a mapping from the indices of an upper triangular matrix to the indices of a flat list of the same size. To generate third degree interaction features, a mapping from combinations of three (a, b, c) to the space $1, 2, ... \frac{D^3 - 3D^2 + 2D}{6}$ (which is $\binom{D}{3}$), or the upper 3-simplex of a tensor to a flat list of the same size $\frac{D^3 - 3D^2 + 2D}{6}$ would be required. In general, for interaction features of degree k, the upper k-simplex of a k-dimensional tensor must be mapped to the space $1, 2, ... \frac{D!}{k!(D-k)!}$. A similar approach for finding these mappings could be taken as the one used here for k=2.

Motivation for deriving mapping functions for higher orders of interaction features is that the average complexity of generating degree k interaction features is $N\binom{Dd}{k}$, which decreases polynomially with respect to k compared to generating the features naively.