

DaisySP

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# Contents

<b>1</b>	<b>libdaisy</b>	<b>1</b>
1.1	Using libdaisy . . . . .	1
1.1.1	daisy.h . . . . .	2
1.1.2	daisy_seed.h . . . . .	2
1.1.3	daisy_platform.h . . . . .	2
<b>2</b>	<b>Module Index</b>	<b>3</b>
2.1	Modules . . . . .	3
<b>3</b>	<b>Namespace Index</b>	<b>5</b>
3.1	Namespace List . . . . .	5
<b>4</b>	<b>Class Index</b>	<b>7</b>
4.1	Class List . . . . .	7
<b>5</b>	<b>File Index</b>	<b>9</b>
5.1	File List . . . . .	9
<b>6</b>	<b>Module Documentation</b>	<b>11</b>
6.1	USBD_CDC_IF_Private_TypesDefinitions . . . . .	11
6.2	USBD_CDC_IF_Private_Defines . . . . .	12
6.2.1	Detailed Description . . . . .	12
6.3	USBD_CDC_IF_Private_Macros . . . . .	13
6.4	USBD_CDC_IF_Private_Variables . . . . .	14
6.4.1	Detailed Description . . . . .	14
6.4.2	Variable Documentation . . . . .	14

6.4.2.1	UserRxBufferFS . . . . .	14
6.4.2.2	UserRxBufferHS . . . . .	14
6.4.2.3	UserTxBufferFS . . . . .	14
6.4.2.4	UserTxBufferHS . . . . .	14
6.5	USBD_CDC_IF_Exported_Variables . . . . .	15
6.5.1	Detailed Description . . . . .	15
6.5.2	Variable Documentation . . . . .	15
6.5.2.1	USBD_Interface_fops_FS . . . . .	15
6.5.2.2	USBD_Interface_fops_HS . . . . .	15
6.6	USBD_CDC_IF_Private_FunctionPrototypes . . . . .	16
6.6.1	Detailed Description . . . . .	16
6.7	USBD_CDC_IF . . . . .	17
6.7.1	Detailed Description . . . . .	17
6.7.2	Function Documentation . . . . .	18
6.7.2.1	CDC_Transmit_FS() . . . . .	18
6.7.2.2	CDC_Transmit_HS() . . . . .	18
6.7.3	Variable Documentation . . . . .	18
6.7.3.1	USBD_Interface_fops_FS . . . . .	19
6.7.3.2	USBD_Interface_fops_HS . . . . .	19
6.8	USBD_CDC_IF_Exported_Defines . . . . .	20
6.9	USBD_CDC_IF_Exported_Types . . . . .	21
6.9.1	Detailed Description . . . . .	21
6.10	USBD_CDC_IF_Exported_Macros . . . . .	22
6.11	USBD_CDC_IF_Exported_FunctionsPrototype . . . . .	23
6.11.1	Detailed Description . . . . .	23
6.11.2	Function Documentation . . . . .	23
6.11.2.1	CDC_Transmit_FS() . . . . .	23
6.11.2.2	CDC_Transmit_HS() . . . . .	24
6.12	USBD_CONF . . . . .	25
6.12.1	Detailed Description . . . . .	25

6.13	USBD_CONF_Exported_Variables	26
6.14	USBD_CONF_Exported_Defines	27
6.14.1	Detailed Description	27
6.15	USBD_CONF_Exported_Macros	28
6.15.1	Detailed Description	28
6.15.2	Macro Definition Documentation	28
6.15.2.1	USBD_DbgLog	28
6.15.2.2	USBD_Delay	28
6.15.2.3	USBD_ErrLog	29
6.15.2.4	USBD_free	29
6.15.2.5	USBD_malloc	29
6.15.2.6	USBD_memcpy	29
6.15.2.7	USBD_memset	29
6.15.2.8	USBD_UsrLog	29
6.16	USBD_CONF_Exported_Types	30
6.17	USBD_CONF_Exported_FunctionsPrototype	31
6.18	USBD_DESC_Private_TypesDefinitions	32
6.19	USBD_DESC_Private_Defines	33
6.19.1	Detailed Description	33
6.20	USBD_DESC_Private_Macros	34
6.21	USBD_DESC_Private_FunctionPrototypes	35
6.21.1	Detailed Description	35
6.22	USBD_DESC_Private_Variables	36
6.22.1	Detailed Description	36
6.22.2	Variable Documentation	36
6.22.2.1	__ALIGN_END	36
6.22.2.2	FS_Desc	37
6.22.2.3	HS_Desc	37
6.23	USBD_DESC_Private_Functions	38
6.23.1	Detailed Description	38

6.23.2	Function Documentation	38
6.23.2.1	USBD_FS_ConfigStrDescriptor()	38
6.23.2.2	USBD_FS_DeviceDescriptor()	39
6.23.2.3	USBD_FS_InterfaceStrDescriptor()	39
6.23.2.4	USBD_FS_LangIDStrDescriptor()	40
6.23.2.5	USBD_FS_ManufacturerStrDescriptor()	40
6.23.2.6	USBD_FS_ProductStrDescriptor()	40
6.23.2.7	USBD_FS_SerialStrDescriptor()	41
6.23.2.8	USBD_HS_ConfigStrDescriptor()	41
6.23.2.9	USBD_HS_DeviceDescriptor()	42
6.23.2.10	USBD_HS_InterfaceStrDescriptor()	42
6.23.2.11	USBD_HS_LangIDStrDescriptor()	42
6.23.2.12	USBD_HS_ManufacturerStrDescriptor()	43
6.23.2.13	USBD_HS_ProductStrDescriptor()	43
6.23.2.14	USBD_HS_SerialStrDescriptor()	44
6.24	USBD_DESC	45
6.24.1	Detailed Description	45
6.25	USBD_DESC_Exported_Constants	46
6.25.1	Detailed Description	46
6.26	USBD_DESC_Exported_Defines	47
6.27	USBD_DESC_Exported_TypesDefinitions	48
6.28	USBD_DESC_Exported_Macros	49
6.29	USBD_DESC_Exported_Variables	50
6.29.1	Detailed Description	50
6.29.2	Variable Documentation	50
6.29.2.1	FS_Desc	50
6.29.2.2	HS_Desc	50
6.30	USBD_DESC_Exported_FunctionsPrototype	51
6.31	CMSIS	52
6.31.1	Detailed Description	52

6.32	Stm32h7xx_system	53
6.32.1	Detailed Description	53
6.33	STM32H7xx_System_Private_Includes	54
6.33.1	Detailed Description	54
6.33.2	Macro Definition Documentation	54
6.33.2.1	CSI_VALUE	54
6.33.2.2	HSE_VALUE	54
6.33.2.3	HSI_VALUE	54
6.34	STM32H7xx_System_Private_TypesDefinitions	55
6.35	STM32H7xx_System_Private_Defines	56
6.35.1	Detailed Description	56
6.35.2	Macro Definition Documentation	56
6.35.2.1	VECT_TAB_OFFSET	56
6.36	STM32H7xx_System_Private_Macros	57
6.37	STM32H7xx_System_Private_Variables	58
6.37.1	Detailed Description	58
6.38	STM32H7xx_System_Private_FunctionPrototypes	59
6.39	STM32H7xx_System_Private_Functions	60
6.39.1	Detailed Description	60
6.39.2	Function Documentation	60
6.39.2.1	SystemCoreClockUpdate()	60
6.39.2.2	SystemInit()	61
6.40	STM32_USB_OTG_DEVICE_LIBRARY	62
6.40.1	Detailed Description	62
6.41	USBD_OTG_DRIVER	63
6.41.1	Detailed Description	63

<b>7 Namespace Documentation</b>	<b>65</b>
7.1 daisy Namespace Reference	65
7.1.1 Detailed Description	66
7.1.2 Enumeration Type Documentation	67
7.1.2.1 anonymous enum	67
7.1.2.2 anonymous enum	67
7.1.2.3 MidiMessageType	67
7.1.2.4 SdmmcBitWidth	67
7.1.2.5 SdmmcMode	67
7.1.2.6 SdmmcSpeed	67
7.1.3 Function Documentation	67
7.1.3.1 daisy_field_init()	68
<b>8 Class Documentation</b>	<b>69</b>
8.1 daisy::AdcChannelConfig Struct Reference	69
8.1.1 Detailed Description	69
8.1.2 Member Function Documentation	69
8.1.2.1 InitMux()	70
8.1.2.2 InitSingle()	70
8.2 daisy::AdcHandle Class Reference	70
8.2.1 Member Function Documentation	70
8.2.1.1 Get()	71
8.2.1.2 GetMux()	71
8.2.1.3 Init()	71
8.2.1.4 Start()	71
8.2.1.5 Stop()	71
8.3 daisy::AnalogControl Class Reference	71
8.3.1 Member Function Documentation	72
8.3.1.1 Init()	72
8.3.1.2 InitBipolarCv()	72
8.3.1.3 Process()	72



8.3.1.4	Value()	72
8.4	codec_frame_t Struct Reference	73
8.5	color Struct Reference	73
8.5.1	Detailed Description	73
8.6	daisy::Color Class Reference	73
8.6.1	Member Enumeration Documentation	74
8.6.1.1	PresetColor	74
8.6.2	Member Function Documentation	74
8.6.2.1	Init() [1/2]	74
8.6.2.2	Init() [2/2]	74
8.6.2.3	Red()	74
8.7	daisy::ControlChangeEvent Struct Reference	74
8.7.1	Detailed Description	75
8.8	daisy::daisy_field Struct Reference	75
8.9	daisy::DaisyPatch Class Reference	75
8.9.1	Member Enumeration Documentation	76
8.9.1.1	Ctrl	76
8.9.2	Member Function Documentation	76
8.9.2.1	AudioSampleRate()	76
8.9.2.2	Init()	76
8.9.2.3	SetAudioBlockSize()	76
8.9.3	Member Data Documentation	76
8.9.3.1	gate_output	77
8.9.3.2	seed	77
8.10	daisy::DaisyPetal Class Reference	77
8.11	daisy::DaisyPod Class Reference	78
8.11.1	Member Function Documentation	79
8.11.1.1	AudioSampleRate()	79
8.11.1.2	Init()	79
8.11.1.3	SetAudioBlockSize()	79

8.11.2 Member Data Documentation . . . . .	79
8.11.2.1 seed . . . . .	79
8.12 daisy::DaisySeed Class Reference . . . . .	79
8.12.1 Member Function Documentation . . . . .	80
8.12.1.1 AudioSampleRate() . . . . .	80
8.12.1.2 Configure() . . . . .	80
8.12.1.3 GetPin() . . . . .	80
8.12.1.4 Init() . . . . .	80
8.12.1.5 SetAudioBlockSize() . . . . .	81
8.12.1.6 SetLed() . . . . .	81
8.12.1.7 SetTestPoint() . . . . .	81
8.12.1.8 StartAudio() . . . . .	81
8.12.2 Member Data Documentation . . . . .	81
8.12.2.1 sdram_handle . . . . .	81
8.13 dsy_adc Struct Reference . . . . .	82
8.14 dsy_audio Struct Reference . . . . .	82
8.15 dsy_audio_handle Struct Reference . . . . .	82
8.15.1 Detailed Description . . . . .	83
8.16 dsy_dac_handle Struct Reference . . . . .	83
8.16.1 Detailed Description . . . . .	83
8.17 dsy_dac_t Struct Reference . . . . .	83
8.18 dsy_gpio Struct Reference . . . . .	84
8.18.1 Detailed Description . . . . .	84
8.19 dsy_gpio_pin Struct Reference . . . . .	84
8.20 dsy_i2c_handle Struct Reference . . . . .	84
8.20.1 Detailed Description . . . . .	84
8.21 dsy_led_driver_t Struct Reference . . . . .	85
8.22 dsy_qspi Struct Reference . . . . .	85
8.23 dsy_qspi_handle Struct Reference . . . . .	85
8.23.1 Detailed Description . . . . .	86

8.24	<a href="#">dsy_sai_handle Struct Reference</a>	86
8.24.1	<a href="#">Detailed Description</a>	86
8.25	<a href="#">DSY_SD_CardInfoTypeDef Struct Reference</a>	86
8.25.1	<a href="#">Detailed Description</a>	87
8.25.2	<a href="#">Member Data Documentation</a>	87
8.25.2.1	<a href="#">BlockNbr</a>	87
8.25.2.2	<a href="#">BlockSize</a>	87
8.25.2.3	<a href="#">CardSpeed</a>	87
8.25.2.4	<a href="#">CardType</a>	87
8.25.2.5	<a href="#">CardVersion</a>	87
8.25.2.6	<a href="#">Class</a>	87
8.25.2.7	<a href="#">LogBlockNbr</a>	88
8.25.2.8	<a href="#">LogBlockSize</a>	88
8.25.2.9	<a href="#">RelCardAdd</a>	88
8.26	<a href="#">dsy_sdram_t Struct Reference</a>	88
8.27	<a href="#">dsy_sr_4021_handle Struct Reference</a>	88
8.27.1	<a href="#">Detailed Description</a>	89
8.28	<a href="#">dsy_tim Struct Reference</a>	89
8.29	<a href="#">dsy_wm8731_handle_t Struct Reference</a>	89
8.30	<a href="#">daisy::Encoder Class Reference</a>	89
8.30.1	<a href="#">Member Function Documentation</a>	90
8.30.1.1	<a href="#">Debounce()</a>	90
8.30.1.2	<a href="#">FallingEdge()</a>	90
8.30.1.3	<a href="#">Increment()</a>	90
8.30.1.4	<a href="#">Init()</a>	90
8.30.1.5	<a href="#">Pressed()</a>	90
8.30.1.6	<a href="#">RisingEdge()</a>	90
8.30.1.7	<a href="#">TimeHeldMs()</a>	91
8.31	<a href="#">FontDef Struct Reference</a>	91
8.31.1	<a href="#">Member Data Documentation</a>	91

8.31.1.1	<a href="#">data</a>	91
8.31.1.2	<a href="#">FontHeight</a>	91
8.31.1.3	<a href="#">FontWidth</a>	91
8.32	<a href="#">daisy::GateIn Class Reference</a>	92
8.32.1	<a href="#">Member Function Documentation</a>	92
8.32.1.1	<a href="#">Init()</a>	92
8.32.1.2	<a href="#">Trig()</a>	92
8.33	<a href="#">led Struct Reference</a>	92
8.34	<a href="#">daisy::Led Class Reference</a>	93
8.34.1	<a href="#">Member Function Documentation</a>	93
8.34.1.1	<a href="#">Init()</a>	93
8.34.1.2	<a href="#">Set()</a>	93
8.34.1.3	<a href="#">Update()</a>	93
8.35	<a href="#">daisy::MidiEvent Struct Reference</a>	93
8.35.1	<a href="#">Detailed Description</a>	94
8.35.2	<a href="#">Member Function Documentation</a>	94
8.35.2.1	<a href="#">AsControlChange()</a>	94
8.35.2.2	<a href="#">AsNoteOn()</a>	94
8.35.3	<a href="#">Member Data Documentation</a>	94
8.35.3.1	<a href="#">type</a>	94
8.36	<a href="#">daisy::MidiHandler Class Reference</a>	95
8.36.1	<a href="#">Member Enumeration Documentation</a>	95
8.36.1.1	<a href="#">MidiInputMode</a>	95
8.36.2	<a href="#">Member Function Documentation</a>	95
8.36.2.1	<a href="#">HasEvents()</a>	95
8.36.2.2	<a href="#">Init()</a>	95
8.36.2.3	<a href="#">Parse()</a>	96
8.36.2.4	<a href="#">PopEvent()</a>	96
8.36.2.5	<a href="#">StartReceive()</a>	96
8.37	<a href="#">daisy::NoteOnEvent Struct Reference</a>	96

8.37.1 Detailed Description . . . . .	96
8.38 NVIC_TypeDef Struct Reference . . . . .	97
8.39 daisy::OledDisplay Class Reference . . . . .	97
8.39.1 Member Enumeration Documentation . . . . .	97
8.39.1.1 Pins . . . . .	97
8.39.2 Member Function Documentation . . . . .	98
8.39.2.1 DrawPixel() . . . . .	98
8.39.2.2 Fill() . . . . .	98
8.39.2.3 Init() . . . . .	98
8.39.2.4 SetCursor() . . . . .	98
8.39.2.5 Update() . . . . .	98
8.39.2.6 WriteChar() . . . . .	99
8.39.2.7 WriteString() . . . . .	99
8.40 daisy::Parameter Class Reference . . . . .	99
8.40.1 Member Enumeration Documentation . . . . .	99
8.40.1.1 Curve . . . . .	99
8.40.2 Member Function Documentation . . . . .	100
8.40.2.1 Init() . . . . .	100
8.40.2.2 Process() . . . . .	100
8.40.2.3 Value() . . . . .	100
8.41 rgb_led Struct Reference . . . . .	100
8.42 daisy::RgbLed Class Reference . . . . .	101
8.42.1 Member Function Documentation . . . . .	101
8.42.1.1 Init() . . . . .	101
8.42.1.2 Set() . . . . .	101
8.42.1.3 SetColor() . . . . .	101
8.42.1.4 Update() . . . . .	101
8.43 daisy::RingBuffer< T, size > Class Template Reference . . . . .	102
8.43.1 Member Function Documentation . . . . .	102
8.43.1.1 capacity() . . . . .	102

8.43.1.2	Flush()	102
8.43.1.3	ImmediateRead() [1/2]	102
8.43.1.4	ImmediateRead() [2/2]	102
8.43.1.5	Init()	103
8.43.1.6	Overwrite() [1/2]	103
8.43.1.7	Overwrite() [2/2]	103
8.43.1.8	Read()	103
8.43.1.9	readable()	103
8.43.1.10	Swallow()	103
8.43.1.11	writable()	104
8.43.1.12	Write()	104
8.44	daisy::RingBuffer< T, 0 > Class Template Reference	104
8.45	daisy::SdmmcHandler Class Reference	104
8.45.1	Member Function Documentation	105
8.45.1.1	Init()	105
8.46	daisy::SdmmcHandlerInit Struct Reference	105
8.46.1	Detailed Description	105
8.47	ShiftRegister595 Class Reference	105
8.47.1	Member Enumeration Documentation	106
8.47.1.1	Pins	106
8.47.2	Member Function Documentation	106
8.47.2.1	Init()	106
8.47.2.2	Set()	106
8.47.2.3	Write()	106
8.48	daisy::SpiHandle Class Reference	107
8.49	SSD1309_t Struct Reference	107
8.50	daisy::Switch Class Reference	107
8.50.1	Member Enumeration Documentation	107
8.50.1.1	Polarity	108
8.50.1.2	Pull	108

8.50.1.3	Type	108
8.50.2	Member Function Documentation	108
8.50.2.1	Debounce()	108
8.50.2.2	FallingEdge()	108
8.50.2.3	Init()	108
8.50.2.4	Pressed()	109
8.50.2.5	RisingEdge()	109
8.50.2.6	TimeHeldMs()	109
8.51	uart_handle Struct Reference	109
8.52	daisy::UartHandler Class Reference	109
8.52.1	Member Function Documentation	110
8.52.1.1	CheckError()	110
8.52.1.2	FlushRx()	110
8.52.1.3	Init()	110
8.52.1.4	PollReceive()	110
8.52.1.5	PollTx()	110
8.52.1.6	PopRx()	110
8.52.1.7	Readable()	111
8.52.1.8	RxActive()	111
8.52.1.9	StartRx()	111
8.53	daisy::UsbHandle Class Reference	111
8.53.1	Member Typedef Documentation	111
8.53.1.1	ReceiveCallback	112
8.53.2	Member Enumeration Documentation	112
8.53.2.1	UsbPeriph	112
8.53.3	Member Function Documentation	112
8.53.3.1	Init()	112
8.53.3.2	SetReceiveCallback()	112
8.53.3.3	TransmitExternal()	112
8.53.3.4	TransmitInternal()	113

8.54	WAV_FormatTypeDef Struct Reference	113
8.55	daisy::WavFileInfo Struct Reference	113
8.55.1	Detailed Description	114
8.56	daisy::WavPlayer Class Reference	114
8.56.1	Detailed Description	114
8.56.2	Member Function Documentation	114
8.56.2.1	Close()	114
8.56.2.2	GetCurrentFile()	115
8.56.2.3	GetLooping()	115
8.56.2.4	GetNumberFiles()	115
8.56.2.5	Init()	115
8.56.2.6	Open()	115
8.56.2.7	Prepare()	115
8.56.2.8	Restart()	115
8.56.2.9	SetLooping()	115
8.56.2.10	Stream()	115
<b>9</b>	<b>File Documentation</b>	<b>117</b>
9.1	src/system_stm32h7xx.c File Reference	117
9.1.1	Detailed Description	118
9.2	src/usbd_cdc_if.c File Reference	118
9.2.1	Detailed Description	119
9.3	src/usbd_cdc_if.h File Reference	119
9.3.1	Detailed Description	120
9.4	src/usbd_conf.c File Reference	120
9.4.1	Detailed Description	122
9.4.2	Function Documentation	122
9.4.2.1	HAL_PCD_ConnectCallback()	122
9.4.2.2	HAL_PCD_DataInStageCallback()	123
9.4.2.3	HAL_PCD_DataOutStageCallback()	123
9.4.2.4	HAL_PCD_DisconnectCallback()	124



9.4.2.5	HAL_PCD_ISOINIncompleteCallback()	124
9.4.2.6	HAL_PCD_ISOOUTIncompleteCallback()	124
9.4.2.7	HAL_PCD_MspDeInit()	125
9.4.2.8	HAL_PCD_MsplInit()	125
9.4.2.9	HAL_PCD_ResetCallback()	125
9.4.2.10	HAL_PCD_ResumeCallback()	125
9.4.2.11	HAL_PCD_SetupStageCallback()	127
9.4.2.12	HAL_PCD_SOFCallback()	127
9.4.2.13	HAL_PCD_SuspendCallback()	127
9.4.2.14	USBD_Get_USB_Status()	128
9.4.2.15	USBD_LL_ClearStallEP()	128
9.4.2.16	USBD_LL_CloseEP()	129
9.4.2.17	USBD_LL_DeInit()	129
9.4.2.18	USBD_LL_Delay()	129
9.4.2.19	USBD_LL_FlushEP()	130
9.4.2.20	USBD_LL_GetRxDataSize()	130
9.4.2.21	USBD_LL_Init()	130
9.4.2.22	USBD_LL_IsStallEP()	131
9.4.2.23	USBD_LL_OpenEP()	131
9.4.2.24	USBD_LL_PrepareReceive()	132
9.4.2.25	USBD_LL_SetUSBAddress()	132
9.4.2.26	USBD_LL_StallEP()	133
9.4.2.27	USBD_LL_Start()	133
9.4.2.28	USBD_LL_Stop()	133
9.4.2.29	USBD_LL_Transmit()	134
9.5	src/usbd_conf.h File Reference	134
9.5.1	Detailed Description	135
9.6	src/usbd_desc.c File Reference	135
9.6.1	Detailed Description	136



# Chapter 1

## libdaisy

Multi-layer hardware abstraction library for Daisy Product family

On STM32H7 MCUs

Lower-levels use STM32 HAL (local copy w/ modifications in Drivers/)

Prefixes and their meanings:

- sys - System level configuration (clocks, dma, etc.)
- per - Peripheral level, internal to MCU (i2c, spi, etc.)
- dev - External device support (external flash chips, DACs, codecs, etc.)
- hid - User level interface elements (encoders, switches, audio, etc.)
- util - library level elements used within the library (not included via [daisy.h](#))
- daisy - core API files (specific boards, platforms have extended user APIs that configure libdaisy more below).

Also included is a core/ folder containing:

- a generic Makefile that can be included in a project Makefile to simplify getting started
- a linker script for defining the sections of memory used by the firmware
- core files for starting the hardware ([system\\_stm32h7xx.c](#), [startup\\_stm32h750xx.s](#), etc.)

### 1.1 Using libdaisy

Due to the amount of hardware configuration and flexibility of the daisy platform, (in the present, and the future), a user can use libdaisy to define their own custom hardware, or include one of our supported board files to jumpstart the creativity, and hack on an existing piece of hardware.

If you are getting started, and have one of the Daisy Family Products, you can skip ahead to that section below.

### 1.1.1 daisy.h

The base-level include file. This is all you need to include to create your own custom hardware that uses libdaisy.

[daisy\\_seed.h](#) is an example of a board level file that utilizes libdaisy to define some hardware, and provide flexible access.

### 1.1.2 daisy\_seed.h

The SOM-level include file. This can be used with any boards that use the Daisy Seed hardware.

Additional configuration files, with more specific hardware access are provided below for our supported hardware platforms.

### 1.1.3 daisy\_platform.h

Several other pairs of files exist in the repo for each of the supported hardware platforms that work with Daisy Seed.

These are:

- `daisy_field`
- `daisy_patch`
- `daisy_petal`
- `daisy_pod`

With these files a number of additional initialization, and configuration is done by the library.

This allows a user to jump right into their new product with a simple api to do things without having a full understanding of what's going on under the hood.

With this flexible approach to the hardware configuration, we hope to promote a lot of fantastic hardware along with code to go with it.

## Chapter 2

# Module Index

### 2.1 Modules

Here is a list of all modules:

CMSIS . . . . .	52
Stm32h7xx_system . . . . .	53
STM32H7xx_System_Private_Includes . . . . .	54
STM32H7xx_System_Private_TypesDefinitions . . . . .	55
STM32H7xx_System_Private_Defines . . . . .	56
STM32H7xx_System_Private_Macros . . . . .	57
STM32H7xx_System_Private_Variables . . . . .	58
STM32H7xx_System_Private_FunctionPrototypes . . . . .	59
STM32H7xx_System_Private_Functions . . . . .	60
STM32_USB_OTG_DEVICE_LIBRARY . . . . .	62
USBDCDC_IF . . . . .	17
USBDCDC_IF_Private_TypesDefinitions . . . . .	11
USBDCDC_IF_Private_Defines . . . . .	12
USBDCDC_IF_Private_Macros . . . . .	13
USBDCDC_IF_Private_Variables . . . . .	14
USBDCDC_IF_Exported_Variables . . . . .	15
USBDCDC_IF_Private_FunctionPrototypes . . . . .	16
USBDCDC_IF_Exported_Defines . . . . .	20
USBDCDC_IF_Exported_Types . . . . .	21
USBDCDC_IF_Exported_Macros . . . . .	22
USBDCDC_IF_Exported_FunctionsPrototype . . . . .	23
USBDESC . . . . .	45
USBDESC_Private_TypesDefinitions . . . . .	32
USBDESC_Private_Defines . . . . .	33
USBDESC_Private_Macros . . . . .	34
USBDESC_Private_FunctionPrototypes . . . . .	35
USBDESC_Private_Variables . . . . .	36
USBDESC_Private_Functions . . . . .	38
USBDESC_Exported_Constants . . . . .	46
USBDESC_Exported_Defines . . . . .	47
USBDESC_Exported_TypesDefinitions . . . . .	48
USBDESC_Exported_Macros . . . . .	49
USBDESC_Exported_Variables . . . . .	50
USBDESC_Exported_FunctionsPrototype . . . . .	51

USBD_OTG_DRIVER . . . . .	63
USBD_CONF . . . . .	25
USBD_CONF_Exported_Variables . . . . .	26
USBD_CONF_Exported_Defines . . . . .	27
USBD_CONF_Exported_Macros . . . . .	28
USBD_CONF_Exported_Types . . . . .	30
USBD_CONF_Exported_FunctionsPrototype . . . . .	31

## Chapter 3

# Namespace Index

### 3.1 Namespace List

Here is a list of all documented namespaces with brief descriptions:

<a href="#">daisy</a> . . . . .	<a href="#">65</a>
---------------------------------	--------------------





## Chapter 4

# Class Index

### 4.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

daisy::AdcChannelConfig	69
daisy::AdcHandle	70
daisy::AnalogControl	71
codec_frame_t	73
color	73
daisy::Color	73
daisy::ControlChangeEvent	74
daisy::daisy_field	75
daisy::DaisyPatch	75
daisy::DaisyPetal	77
daisy::DaisyPod	78
daisy::DaisySeed	79
dsy_adc	82
dsy_audio	82
dsy_audio_handle	82
dsy_dac_handle	83
dsy_dac_t	83
dsy_gpio	84
dsy_gpio_pin	84
dsy_i2c_handle	84
dsy_led_driver_t	85
dsy_qspi	85
dsy_qspi_handle	85
dsy_sai_handle	86
DSY_SD_CardInfoTypeDef	86
dsy_sdram_t	88
dsy_sr_4021_handle	88
dsy_tim	89
dsy_wm8731_handle_t	89
daisy::Encoder	89
FontDef	91
daisy::GateIn	92
led	92
daisy::Led	93
daisy::MidiEvent	93

daisy::MidiHandler	95
daisy::NoteOnEvent	96
NVIC_TypeDef	97
daisy::OledDisplay	97
daisy::Parameter	99
rgb_led	100
daisy::RgbLed	101
daisy::RingBuffer< T, size >	102
daisy::RingBuffer< T, 0 >	104
daisy::SdmmcHandler	104
daisy::SdmmcHandlerInit	105
ShiftRegister595	105
daisy::SpiHandle	107
SSD1309_t	107
daisy::Switch	107
uart_handle	109
daisy::UartHandler	109
daisy::UsbHandle	111
WAV_FormatTypeDef	113
daisy::WavFileInfo	113
daisy::WavPlayer	114

## Chapter 5

# File Index

### 5.1 File List

Here is a list of all documented files with brief descriptions:

src/ <b>daisy.h</b>	??
src/ <b>daisy_core.h</b>	??
src/ <b>daisy_field.h</b>	??
src/ <b>daisy_patch.h</b>	??
src/ <b>daisy_petal.h</b>	??
src/ <b>daisy_pod.h</b>	??
src/ <b>daisy_seed.h</b>	??
src/ <b>dev_codec_ak4556.h</b>	??
src/ <b>dev_codec_pcm3060.h</b>	??
src/ <b>dev_codec_wm8731.h</b>	??
src/ <b>dev_codec_wm8731_frame.h</b>	??
src/ <b>dev_flash_IS25LP064A.h</b>	??
src/ <b>dev_flash_IS25LP080D.h</b>	??
src/ <b>dev_leddriver.h</b>	??
src/ <b>dev_sdram.h</b>	??
src/ <b>dev_sr_4021.h</b>	??
src/ <b>dev_sr_595.h</b>	??
src/ <b>fatfs.h</b>	??
src/ <b>ffconf.h</b>	??
src/ <b>hid_audio.h</b>	??
src/ <b>hid_ctrl.h</b>	??
src/ <b>hid_encoder.h</b>	??
src/ <b>hid_gatein.h</b>	??
src/ <b>hid_led.h</b>	??
src/ <b>hid_midi.h</b>	??
src/ <b>hid_oled_display.h</b>	??
src/ <b>hid_parameter.h</b>	??
src/ <b>hid_rgb_led.h</b>	??
src/ <b>hid_switch.h</b>	??
src/ <b>hid_usb.h</b>	??
src/ <b>hid_wavplayer.h</b>	??
src/ <b>per_adc.h</b>	??
src/ <b>per_dac.h</b>	??
src/ <b>per_gpio.h</b>	??
src/ <b>per_i2c.h</b>	??

src/per_qspi.h . . . . .	??
src/per_sai.h . . . . .	??
src/per_sdmmc.h . . . . .	??
src/per_spi.h . . . . .	??
src/per_tim.h . . . . .	??
src/per_uart.h . . . . .	??
src/stm32h7xx_hal_conf.h . . . . .	??
src/sys_dma.h . . . . .	??
src/sys_system.h . . . . .	??
src/system_stm32h7xx.c	
CMSIS Cortex-Mx Device Peripheral Access Layer System Source File . . . . .	117
src/usbd_cdc_if.c	
: Usb device for Virtual Com Port . . . . .	118
src/usbd_cdc_if.h	
: Header for usbd_cdc_if.c file . . . . .	119
src/usbd_conf.c	
: This file implements the board support package for the USB device library . . . . .	120
src/usbd_conf.h	
: Header for usbd_conf.c file . . . . .	134
src/usbd_desc.c	
: This file implements the USB device descriptors . . . . .	135
src/usbd_desc.h . . . . .	??
src/util_bsp_sd_diskio.h . . . . .	??
src/util_color.h . . . . .	??
src/util_hal_map.h . . . . .	??
src/util_oled_fonts.h . . . . .	??
src/util_ringbuffer.h . . . . .	??
src/util_sd_diskio.h . . . . .	??
src/util_unique_id.h . . . . .	??
src/util_wav_format.h . . . . .	??

## Chapter 6

# Module Documentation

### 6.1 USBDCDCIFPrivateTypesDefinitions

Private types.

Private types.

## 6.2 USB\_D\_CDC\_IF\_Private\_Defines

Private defines.

### Macros

- `#define APP_RX_DATA_SIZE 2048`
- `#define APP_TX_DATA_SIZE 2048`

### 6.2.1 Detailed Description

Private defines.

## 6.3 USBD\_CDC\_IF\_Private\_Macros

Private macros.

Private macros.

## 6.4 USB\_DCD\_IF\_Private\_Variables

Private variables.

### Functions

- void **dummy\_rx\_callback** (uint8\_t \*buf, uint32\_t \*len)

### Variables

- uint8\_t [UserRxBufferFS](#) [2048]
- uint8\_t [UserTxBufferFS](#) [2048]
- uint8\_t [UserRxBufferHS](#) [2048]
- uint8\_t [UserTxBufferHS](#) [2048]
- CDC\_ReceiveCallback **rx\_callback\_fs**

### 6.4.1 Detailed Description

Private variables.

### 6.4.2 Variable Documentation

#### 6.4.2.1 UserRxBufferFS

```
uint8_t UserRxBufferFS[2048]
```

Received data over USB are stored in this buffer

#### 6.4.2.2 UserRxBufferHS

```
uint8_t UserRxBufferHS[2048]
```

Received data over USB are stored in this buffer

#### 6.4.2.3 UserTxBufferFS

```
uint8_t UserTxBufferFS[2048]
```

Data to send over USB CDC are stored in this buffer

#### 6.4.2.4 UserTxBufferHS

```
uint8_t UserTxBufferHS[2048]
```

Data to send over USB CDC are stored in this buffer



## 6.5 USB\_D\_CDC\_IF\_Exported\_Variables

Public variables.

### Variables

- USBD\_HandleTypeDef **hUsbDeviceFS**
- USBD\_HandleTypeDef **hUsbDeviceHS**
- USBD\_CDC\_ItfTypeDef [USB\\_D\\_Interface\\_fops\\_FS](#)
- USBD\_CDC\_ItfTypeDef [USB\\_D\\_Interface\\_fops\\_HS](#)

### 6.5.1 Detailed Description

Public variables.

### 6.5.2 Variable Documentation

#### 6.5.2.1 USB\_D\_Interface\_fops\_FS

USB\_D\_CDC\_ItfTypeDef USB\_D\_Interface\_fops\_FS

CDC Interface callback.

#### 6.5.2.2 USB\_D\_Interface\_fops\_HS

USB\_D\_CDC\_ItfTypeDef USB\_D\_Interface\_fops\_HS

CDC Interface callback.

## 6.6 USB\_D\_CDC\_IF\_Private\_FunctionPrototypes

Private functions declaration.

### 6.6.1 Detailed Description

Private functions declaration.

## 6.7 USB\_D\_CDC\_IF

Usb VCP device module.

### Modules

- [USB\\_D\\_CDC\\_IF\\_Private\\_TypesDefinitions](#)  
*Private types.*
- [USB\\_D\\_CDC\\_IF\\_Private\\_Defines](#)  
*Private defines.*
- [USB\\_D\\_CDC\\_IF\\_Private\\_Macros](#)  
*Private macros.*
- [USB\\_D\\_CDC\\_IF\\_Private\\_Variables](#)  
*Private variables.*
- [USB\\_D\\_CDC\\_IF\\_Exported\\_Variables](#)  
*Public variables.*
- [USB\\_D\\_CDC\\_IF\\_Private\\_FunctionPrototypes](#)  
*Private functions declaration.*
- [USB\\_D\\_CDC\\_IF\\_Exported\\_Defines](#)  
*Defines.*
- [USB\\_D\\_CDC\\_IF\\_Exported\\_Types](#)  
*Types.*
- [USB\\_D\\_CDC\\_IF\\_Exported\\_Macros](#)  
*Aliases.*
- [USB\\_D\\_CDC\\_IF\\_Exported\\_FunctionsPrototype](#)  
*Public functions declaration.*

### Functions

- `uint8_t CDC_Transmit_FS (uint8_t *Buf, uint16_t Len)`  
*CDC\_Transmit\_FS Data to send over USB IN endpoint are sent over CDC interface through this function.*
- `uint8_t CDC_Transmit_HS (uint8_t *Buf, uint16_t Len)`  
*Data to send over USB IN endpoint are sent over CDC interface through this function.*
- `void CDC_Set_Rx_Callback_FS (CDC_ReceiveCallback cb)`

### Variables

- `USB_D_CDC_ItfTypeDef USB_Interface_fops_FS = {CDC_Init_FS, CDC_DeInit_FS, CDC_Control_FS, CDC_Receive_FS}`
- `USB_D_CDC_ItfTypeDef USB_Interface_fops_HS = {CDC_Init_HS, CDC_DeInit_HS, CDC_Control_HS, CDC_Receive_HS}`

#### 6.7.1 Detailed Description

Usb VCP device module.

## 6.7.2 Function Documentation

### 6.7.2.1 CDC\_Transmit\_FS()

```
uint8_t CDC_Transmit_FS (
    uint8_t * Buf,
    uint16_t Len )
```

CDC\_Transmit\_FS Data to send over USB IN endpoint are sent over CDC interface through this function.

#### Note

#### Parameters

<i>Buf</i>	Buffer of data to be sent
<i>Len</i>	Number of data to be sent (in bytes)

#### Return values

<i>USBD_OK</i>	if all operations are OK else USBD_FAIL or USBD_BUSY
----------------	------------------------------------------------------

### 6.7.2.2 CDC\_Transmit\_HS()

```
uint8_t CDC_Transmit_HS (
    uint8_t * Buf,
    uint16_t Len )
```

Data to send over USB IN endpoint are sent over CDC interface through this function.

#### Parameters

<i>Buf</i>	Buffer of data to be sent
<i>Len</i>	Number of data to be sent (in bytes)

#### Return values

<i>Result</i>	of the operation: USBD_OK if all operations are OK else USBD_FAIL or USBD_BUSY
---------------	--------------------------------------------------------------------------------

## 6.7.3 Variable Documentation

### 6.7.3.1 USBD\_Interface\_fops\_FS

```
USBDCDC_ItfTypeDef USBD_Interface_fops_FS = {CDC_Init_FS, CDC_DeInit_FS, CDC_Control_FS, CD←  
C_Receive_FS}
```

CDC Interface callback.

### 6.7.3.2 USBD\_Interface\_fops\_HS

```
USBDCDC_ItfTypeDef USBD_Interface_fops_HS = {CDC_Init_HS, CDC_DeInit_HS, CDC_Control_HS, CD←  
C_Receive_HS}
```

CDC Interface callback.

## 6.8 USB\_D\_CDC\_IF\_Exported\_Defines

Defines.

Defines.

## 6.9 USB\_D\_CDC\_IF\_Exported\_Types

Types.

### Typedefs

- typedef void(\* **CDC\_ReceiveCallback**) (uint8\_t \*buf, uint32\_t \*size)

### 6.9.1 Detailed Description

Types.

## 6.10 USB\_D\_CDC\_IF\_Exported\_Macros

Aliases.

Aliases.



## 6.11 USBD\_CDC\_IF\_Exported\_FunctionsPrototype

Public functions declaration.

### Functions

- void **CDC\_Set\_Rx\_Callback\_FS** (CDC\_ReceiveCallback cb)
- uint8\_t **CDC\_Transmit\_FS** (uint8\_t \*Buf, uint16\_t Len)  
*CDC\_Transmit\_FS Data to send over USB IN endpoint are sent over CDC interface through this function.*
- uint8\_t **CDC\_Transmit\_HS** (uint8\_t \*Buf, uint16\_t Len)  
*Data to send over USB IN endpoint are sent over CDC interface through this function.*

### 6.11.1 Detailed Description

Public functions declaration.

### 6.11.2 Function Documentation

#### 6.11.2.1 CDC\_Transmit\_FS()

```
uint8_t CDC_Transmit_FS (  
    uint8_t * Buf,  
    uint16_t Len )
```

CDC\_Transmit\_FS Data to send over USB IN endpoint are sent over CDC interface through this function.

#### Note

#### Parameters

<i>Buf</i>	Buffer of data to be sent
<i>Len</i>	Number of data to be sent (in bytes)

#### Return values

<i>USBD_OK</i>	if all operations are OK else USBD_FAIL or USBD_BUSY
----------------	------------------------------------------------------

### 6.11.2.2 CDC\_Transmit\_HS()

```
uint8_t CDC_Transmit_HS (
    uint8_t * Buf,
    uint16_t Len )
```

Data to send over USB IN endpoint are sent over CDC interface through this function.

#### Parameters

<i>Buf</i>	Buffer of data to be sent
<i>Len</i>	Number of data to be sent (in bytes)

#### Return values

<i>Result</i>	of the operation: USBD_OK if all operations are OK else USBD_FAIL or USBD_BUSY
---------------	--------------------------------------------------------------------------------

## 6.12 USBD\_CONF

Configuration file for Usb otg low level driver.

### Modules

- [USB\\_CONF\\_Exported\\_Variables](#)  
*Public variables.*
- [USB\\_CONF\\_Exported\\_Defines](#)  
*Defines for configuration of the Usb device.*
- [USB\\_CONF\\_Exported\\_Macros](#)  
*Aliases.*
- [USB\\_CONF\\_Exported\\_Types](#)  
*Types.*
- [USB\\_CONF\\_Exported\\_FunctionsPrototype](#)  
*Declaration of public functions for Usb device.*

### 6.12.1 Detailed Description

Configuration file for Usb otg low level driver.

## 6.13 USBD\_CONF\_Exported\_Variables

Public variables.

Public variables.

## 6.14 USBD\_CONF\_Exported\_Defines

Defines for configuration of the Usb device.

### Macros

- `#define USBD_MAX_NUM_INTERFACES 1U`
- `#define USBD_MAX_NUM_CONFIGURATION 1U`
- `#define USBD_MAX_STR_DESC_SIZ 512U`
- `#define USBD_SUPPORT_USER_STRING 0U`
- `#define USBD_DEBUG_LEVEL 3U`
- `#define USBD_LPM_ENABLED 0U`
- `#define USBD_SELF_POWERED 1U`
- `#define DEVICE_FS 0`
- `#define DEVICE_HS 1`

### 6.14.1 Detailed Description

Defines for configuration of the Usb device.

## 6.15 USBD\_CONF\_Exported\_Macros

Aliases.

### Macros

- #define `USBD_malloc` `malloc`
- #define `USBD_free` `free`
- #define `USBD_memset` `memset`
- #define `USBD_memcpy` `memcpy`
- #define `USBD_Delay` `HAL_Delay`
- #define `USBD_UsrLog(...)`
- #define `USBD_ErrLog(...)`
- #define `USBD_DbgLog(...)`

### 6.15.1 Detailed Description

Aliases.

### 6.15.2 Macro Definition Documentation

#### 6.15.2.1 USBD\_DbgLog

```
#define USBD_DbgLog(  
    ... )
```

**Value:**

```
printf("DEBUG : "); \  
printf(__VA_ARGS__); \  
printf("\n");
```

#### 6.15.2.2 USBD\_Delay

```
#define USBD_Delay HAL_Delay
```

Alias for delay.

### 6.15.2.3 USBD\_ErrLog

```
#define USBD_ErrLog(  
    ... )
```

**Value:**

```
printf("ERROR: "); \  
    printf(__VA_ARGS__); \  
    printf("\n");
```

### 6.15.2.4 USBD\_free

```
#define USBD_free free
```

Alias for memory release.

### 6.15.2.5 USBD\_malloc

```
#define USBD_malloc malloc
```

Alias for memory allocation.

### 6.15.2.6 USBD\_memcpy

```
#define USBD_memcpy memcpy
```

Alias for memory copy.

### 6.15.2.7 USBD\_memset

```
#define USBD_memset memset
```

Alias for memory set.

### 6.15.2.8 USBD\_UsrLog

```
#define USBD_UsrLog(  
    ... )
```

**Value:**

```
printf(__VA_ARGS__); \  
    printf("\n");
```

## 6.16 USBD\_CONF\_Exported\_Types

Types.

Types.



## 6.17 USBD\_CONF\_Exported\_FunctionsPrototype

Declaration of public functions for Usb device.

Declaration of public functions for Usb device.

## 6.18 USBD\_DESC\_Private\_TypesDefinitions

Private types.

Private types.

## 6.19 USBD\_DESC\_Private\_Defines

Private defines.

### Macros

- `#define USBD_VID 1155`
- `#define USBD_LANGID_STRING 1033`
- `#define USBD_MANUFACTURER_STRING "Electrosmith"`
- `#define USBD_PID_HS 22336`
- `#define USBD_PRODUCT_STRING_HS "Daisy Seed External"`
- `#define USBD_CONFIGURATION_STRING_HS "CDC Config"`
- `#define USBD_INTERFACE_STRING_HS "CDC Interface"`
- `#define USBD_PID_FS 22336`
- `#define USBD_PRODUCT_STRING_FS "Daisy Seed Built In"`
- `#define USBD_CONFIGURATION_STRING_FS "CDC Config"`
- `#define USBD_INTERFACE_STRING_FS "CDC Interface"`

### 6.19.1 Detailed Description

Private defines.

## 6.20 USBD\_DESC\_Private\_Macros

Private macros.

Private macros.

## 6.21 USBD\_DESC\_Private\_FunctionPrototypes

Private functions declaration.

### 6.21.1 Detailed Description

Private functions declaration.

Private functions declaration for HS.

Private functions declaration for FS.

## 6.22 USBD\_DESC\_Private\_Variables

Private variables.

### Variables

- USBD\_DescriptorsTypeDef [FS\\_Desc](#)
- `__ALIGN_BEGIN uint8_t USBD_FS_DeviceDesc [USB_LEN_DEV_DESC] __ALIGN_END`
- USBD\_DescriptorsTypeDef [HS\\_Desc](#)

### 6.22.1 Detailed Description

Private variables.

### 6.22.2 Variable Documentation

#### 6.22.2.1 \_\_ALIGN\_END

```
__ALIGN_BEGIN uint8_t USBD_StringSerial [ 0x1A ] __ALIGN_END
```

**Initial value:**

```
=
{
    0x12,
    USB_DESC_TYPE_DEVICE,
    0x00,
    0x02,
    0x02,
    0x02,
    0x00,
    USB_MAX_EP0_SIZE,
    LOBYTE( 1155 ),
    HIBYTE( 1155 ),
    LOBYTE( 22336 ),
    HIBYTE( 22336 ),
    0x00,
    0x02,
    USBD_IDX_MFC_STR,
    USBD_IDX_PRODUCT_STR,
    USBD_IDX_SERIAL_STR,
    1U
}
```

USB standard device descriptor.

USB lang indentifier descriptor.

IAR Compiler

### 6.22.2.2 FS\_Desc

USBD\_DescriptorsTypeDef FS\_Desc

**Initial value:**

```
=
{
    USBD_FS_DeviceDescriptor
,   USBD_FS_LangIDStrDescriptor
,   USBD_FS_ManufacturerStrDescriptor
,   USBD_FS_ProductStrDescriptor
,   USBD_FS_SerialStrDescriptor
,   USBD_FS_ConfigStrDescriptor
,   USBD_FS_InterfaceStrDescriptor
}
```

Descriptor for the Usb device.

### 6.22.2.3 HS\_Desc

USBD\_DescriptorsTypeDef HS\_Desc

**Initial value:**

```
=
{
    USBD_HS_DeviceDescriptor
,   USBD_HS_LangIDStrDescriptor
,   USBD_HS_ManufacturerStrDescriptor
,   USBD_HS_ProductStrDescriptor
,   USBD_HS_SerialStrDescriptor
,   USBD_HS_ConfigStrDescriptor
,   USBD_HS_InterfaceStrDescriptor
}
```

Descriptor for the Usb device.

## 6.23 USBD\_DESC\_Private\_Functions

Private functions.

### Functions

- `uint8_t * USBD_HS_DeviceDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the device descriptor.*
- `uint8_t * USBD_HS_LangIDStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the LangID string descriptor.*
- `uint8_t * USBD_HS_ProductStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the product string descriptor.*
- `uint8_t * USBD_HS_ManufacturerStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the manufacturer string descriptor.*
- `uint8_t * USBD_HS_SerialStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the serial number string descriptor.*
- `uint8_t * USBD_HS_ConfigStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the configuration string descriptor.*
- `uint8_t * USBD_HS_InterfaceStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the interface string descriptor.*
- `uint8_t * USBD_FS_DeviceDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the device descriptor.*
- `uint8_t * USBD_FS_LangIDStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the LangID string descriptor.*
- `uint8_t * USBD_FS_ProductStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the product string descriptor.*
- `uint8_t * USBD_FS_ManufacturerStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the manufacturer string descriptor.*
- `uint8_t * USBD_FS_SerialStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the serial number string descriptor.*
- `uint8_t * USBD_FS_ConfigStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the configuration string descriptor.*
- `uint8_t * USBD_FS_InterfaceStrDescriptor` (`USB_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the interface string descriptor.*

### 6.23.1 Detailed Description

Private functions.

### 6.23.2 Function Documentation

#### 6.23.2.1 USBD\_FS\_ConfigStrDescriptor()

```
uint8_t * USBD_FS_ConfigStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the configuration string descriptor.



## Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

## Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

## 6.23.2.2 USBD\_FS\_DeviceDescriptor()

```
uint8_t * USBD_FS_DeviceDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the device descriptor.

## Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

## Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

## 6.23.2.3 USBD\_FS\_InterfaceStrDescriptor()

```
uint8_t * USBD_FS_InterfaceStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the interface string descriptor.

## Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

## Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

#### 6.23.2.4 USBD\_FS\_LangIDStrDescriptor()

```
uint8_t * USBD_FS_LangIDStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the LangID string descriptor.

##### Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

##### Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

#### 6.23.2.5 USBD\_FS\_ManufacturerStrDescriptor()

```
uint8_t * USBD_FS_ManufacturerStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the manufacturer string descriptor.

##### Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

##### Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

#### 6.23.2.6 USBD\_FS\_ProductStrDescriptor()

```
uint8_t * USBD_FS_ProductStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the product string descriptor.

## Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

## Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

## 6.23.2.7 USBD\_FS\_SerialStrDescriptor()

```
uint8_t * USBD_FS_SerialStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the serial number string descriptor.

## Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

## Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

## 6.23.2.8 USBD\_HS\_ConfigStrDescriptor()

```
uint8_t * USBD_HS_ConfigStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the configuration string descriptor.

## Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

## Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

#### 6.23.2.9 USB\_D\_HS\_DeviceDescriptor()

```
uint8_t * USB_D_HS_DeviceDescriptor (
    USB_D_SpeedTypeDef speed,
    uint16_t * length )
```

Return the device descriptor.

##### Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

##### Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

#### 6.23.2.10 USB\_D\_HS\_InterfaceStrDescriptor()

```
uint8_t * USB_D_HS_InterfaceStrDescriptor (
    USB_D_SpeedTypeDef speed,
    uint16_t * length )
```

Return the interface string descriptor.

##### Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

##### Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

#### 6.23.2.11 USB\_D\_HS\_LangIDStrDescriptor()

```
uint8_t * USB_D_HS_LangIDStrDescriptor (
    USB_D_SpeedTypeDef speed,
    uint16_t * length )
```

Return the LangID string descriptor.

## Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

## Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

## 6.23.2.12 USBD\_HS\_ManufacturerStrDescriptor()

```
uint8_t * USBD_HS_ManufacturerStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the manufacturer string descriptor.

## Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

## Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

## 6.23.2.13 USBD\_HS\_ProductStrDescriptor()

```
uint8_t * USBD_HS_ProductStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the product string descriptor.

## Parameters

<i>speed</i>	: current device speed
<i>length</i>	: pointer to data length variable

## Return values

<i>pointer</i>	to descriptor buffer
----------------	----------------------

#### 6.23.2.14 USBD\_HS\_SerialStrDescriptor()

```
uint8_t * USBD_HS_SerialStrDescriptor (
    USB_SpeedTypeDef speed,
    uint16_t * length )
```

Return the serial number string descriptor.

##### Parameters

<i>speed</i>	: Current device speed
<i>length</i>	: Pointer to data length variable

##### Return values

<i>Pointer</i>	to descriptor buffer
----------------	----------------------

## 6.24 USBD\_DESC

Usb device descriptors module.

### Modules

- [USB\\_DDESC\\_Private\\_TypesDefinitions](#)  
*Private types.*
- [USB\\_DDESC\\_Private\\_Defines](#)  
*Private defines.*
- [USB\\_DDESC\\_Private\\_Macros](#)  
*Private macros.*
- [USB\\_DDESC\\_Private\\_FunctionPrototypes](#)  
*Private functions declaration.*
- [USB\\_DDESC\\_Private\\_Variables](#)  
*Private variables.*
- [USB\\_DDESC\\_Private\\_Functions](#)  
*Private functions.*
- [USB\\_DDESC\\_Exported\\_Constants](#)  
*Constants.*
- [USB\\_DDESC\\_Exported\\_Defines](#)  
*Defines.*
- [USB\\_DDESC\\_Exported\\_TypesDefinitions](#)  
*Types.*
- [USB\\_DDESC\\_Exported\\_Macros](#)  
*Aliases.*
- [USB\\_DDESC\\_Exported\\_Variables](#)  
*Public variables.*
- [USB\\_DDESC\\_Exported\\_FunctionsPrototype](#)  
*Public functions declaration.*

### 6.24.1 Detailed Description

Usb device descriptors module.

## 6.25 USB\_DESCRIPTOR\_Exported\_Constants

Constants.

### Macros

- `#define DEVICE_ID1 (UID_BASE)`
- `#define DEVICE_ID2 (UID_BASE + 0x4)`
- `#define DEVICE_ID3 (UID_BASE + 0x8)`
- `#define USB_SIZ_STRING_SERIAL 0x1A`

### 6.25.1 Detailed Description

Constants.



## 6.26 USBD\_DESC\_Exported\_Defines

Defines.

Defines.

## 6.27 USBD\_DESC\_Exported\_TypesDefinitions

Types.

Types.

## 6.28 USBD\_DESC\_Exported\_Macros

Aliases.

Aliases.

## 6.29 USBD\_DESC\_Exported\_Variables

Public variables.

### Variables

- USBD\_DescriptorsTypeDef [HS\\_Desc](#)
- USBD\_DescriptorsTypeDef [FS\\_Desc](#)

### 6.29.1 Detailed Description

Public variables.

### 6.29.2 Variable Documentation

#### 6.29.2.1 FS\_Desc

USB\_DescriptorsTypeDef FS\_Desc

Descriptor for the Usb device.

#### 6.29.2.2 HS\_Desc

USB\_DescriptorsTypeDef HS\_Desc

Descriptor for the Usb device.

## 6.30 USBD\_DESC\_Exported\_FunctionsPrototype

Public functions declaration.

Public functions declaration.

## 6.31 CMSIS

### Modules

- [Stm32h7xx\\_system](#)

### 6.31.1 Detailed Description

## 6.32 Stm32h7xx\_system

### Modules

- [STM32H7xx\\_System\\_Private\\_Includes](#)
- [STM32H7xx\\_System\\_Private\\_TypesDefinitions](#)
- [STM32H7xx\\_System\\_Private\\_Defines](#)
- [STM32H7xx\\_System\\_Private\\_Macros](#)
- [STM32H7xx\\_System\\_Private\\_Variables](#)
- [STM32H7xx\\_System\\_Private\\_FunctionPrototypes](#)
- [STM32H7xx\\_System\\_Private\\_Functions](#)

### 6.32.1 Detailed Description

## 6.33 STM32H7xx\_System\_Private\_Includes

### Macros

- #define [HSE\\_VALUE](#) ((uint32\_t)25000000)
- #define [CSI\\_VALUE](#) ((uint32\_t)4000000)
- #define [HSI\\_VALUE](#) ((uint32\_t)64000000)

### 6.33.1 Detailed Description

### 6.33.2 Macro Definition Documentation

#### 6.33.2.1 CSI\_VALUE

```
#define CSI_VALUE ((uint32_t)4000000)
```

Value of the Internal oscillator in Hz

#### 6.33.2.2 HSE\_VALUE

```
#define HSE_VALUE ((uint32_t)25000000)
```

Value of the External oscillator in Hz

#### 6.33.2.3 HSI\_VALUE

```
#define HSI_VALUE ((uint32_t)64000000)
```

Value of the Internal oscillator in Hz



## 6.34 STM32H7xx\_System\_Private\_TypesDefinitions

## 6.35 STM32H7xx\_System\_Private\_Defines

### Macros

- #define [VECT\\_TAB\\_OFFSET](#) 0x00000000UL

#### 6.35.1 Detailed Description

#### 6.35.2 Macro Definition Documentation

##### 6.35.2.1 VECT\_TAB\_OFFSET

```
#define VECT_TAB_OFFSET 0x00000000UL
```

< Uncomment the following line if you need to use initialized data in D2 domain SRAM (AHB SRAM)

< Uncomment the following line if you need to relocate your vector Table in Internal SRAM. Vector Table base offset field. This value must be a multiple of 0x200.

## 6.36 STM32H7xx\_System\_Private\_Macros

## 6.37 STM32H7xx\_System\_Private\_Variables

### Variables

- uint32\_t **SystemCoreClock** = 64000000
- uint32\_t **SystemD2Clock** = 64000000
- const uint8\_t **D1CorePrescTable** [16] = {0, 0, 0, 0, 1, 2, 3, 4, 1, 2, 3, 4, 6, 7, 8, 9}

### 6.37.1 Detailed Description

## 6.38 STM32H7xx\_System\_Private\_FunctionPrototypes

## 6.39 STM32H7xx\_System\_Private\_Functions

### Functions

- void [SystemInit](#) (void)  
*Setup the microcontroller system Initialize the FPU setting and vector table location configuration.*
- void [SystemCoreClockUpdate](#) (void)  
*Update SystemCoreClock variable according to Clock Register Values. The SystemCoreClock variable contains the core clock , it can be used by the user application to setup the SysTick timer or configure other parameters.*

### 6.39.1 Detailed Description

### 6.39.2 Function Documentation

#### 6.39.2.1 SystemCoreClockUpdate()

```
void SystemCoreClockUpdate (
    void )
```

Update SystemCoreClock variable according to Clock Register Values. The SystemCoreClock variable contains the core clock , it can be used by the user application to setup the SysTick timer or configure other parameters.

#### Note

Each time the core clock changes, this function must be called to update SystemCoreClock variable value. Otherwise, any configuration based on this variable will be incorrect.

- The system frequency computed by this function is not the real frequency in the chip. It is calculated based on the predefined constant and the selected clock source:

- If SYSCLK source is CSI, SystemCoreClock will contain the [CSI\\_VALUE\(\\*\)](#)
- If SYSCLK source is HSI, SystemCoreClock will contain the [HSI\\_VALUE\(\\*\\*\)](#)
- If SYSCLK source is HSE, SystemCoreClock will contain the [HSE\\_VALUE\(\\*\\*\\*\)](#)
- If SYSCLK source is PLL, SystemCoreClock will contain the [CSI\\_VALUE\(\\*\)](#), [HSI\\_VALUE\(\\*\\*\)](#) or [HSE\\_VALUE\(\\*\\*\\*\)](#) multiplied/divided by the PLL factors.

(\*) CSI\_VALUE is a constant defined in stm32h7xx\_hal.h file (default value 4 MHz) but the real value may vary depending on the variations in voltage and temperature. (\*\*) HSI\_VALUE is a constant defined in stm32h7xx\_hal.h file (default value 64 MHz) but the real value may vary depending on the variations in voltage and temperature.

(\*\*\*)HSE\_VALUE is a constant defined in stm32h7xx\_hal.h file (default value 25 MHz), user has to ensure that HSE\_VALUE is same as the real frequency of the crystal used. Otherwise, this function may have wrong result.

- The result of this function could be not correct when using fractional value for HSE crystal.

**Parameters**

None	
------	--

**Return values**

None	
------	--

< Value of the Internal oscillator in Hz

< Value of the Internal oscillator in Hz

< Value of the External oscillator in Hz

< Value of the Internal oscillator in Hz

< Value of the Internal oscillator in Hz

< Value of the External oscillator in Hz

< Value of the Internal oscillator in Hz

< Value of the Internal oscillator in Hz

**6.39.2.2 SystemInit()**

```
void SystemInit (
    void )
```

Setup the microcontroller system Initialize the FPU setting and vector table location configuration.

**Parameters**

None	
------	--

**Return values**

None	
------	--

< Vector Table base offset field. This value must be a multiple of 0x200.

## 6.40 STM32\_USB\_OTG\_DEVICE\_LIBRARY

Usb device library.

### Modules

- [USBD\\_CDC\\_IF](#)  
*Usb VCP device module.*
- [USBD\\_DESC](#)  
*Usb device descriptors module.*

### 6.40.1 Detailed Description

Usb device library.

For Usb device.



## 6.41 USBD\_OTG\_DRIVER

### Modules

- [USBD\\_CONF](#)

*Configuration file for Usb otg low level driver.*

### 6.41.1 Detailed Description



## Chapter 7

# Namespace Documentation

### 7.1 daisy Namespace Reference

#### Classes

- struct [AdcChannelConfig](#)
- class [AdcHandle](#)
- class [AnalogControl](#)
- class [Color](#)
- struct [ControlChangeEvent](#)
- struct [daisy\\_field](#)
- class [DaisyPatch](#)
- class [DaisyPetal](#)
- class [DaisyPod](#)
- class [DaisySeed](#)
- class [Encoder](#)
- class [GateIn](#)
- class [Led](#)
- struct [MidiEvent](#)
- class [MidiHandler](#)
- struct [NoteOnEvent](#)
- class [OledDisplay](#)
- class [Parameter](#)
- class [RgbLed](#)
- class [RingBuffer](#)
- class [RingBuffer< T, 0 >](#)
- class [SdmmcHandler](#)
- struct [SdmmcHandlerInit](#)
- class [SpiHandle](#)
- class [Switch](#)
- class [UartHandler](#)
- class [UsbHandle](#)
- struct [WavFileInfo](#)
- class [WavPlayer](#)

## Enumerations

- enum { **SW\_2**, **SW\_1**, **SW\_3**, **SW\_LAST** }
- enum { **KNOB\_1**, **KNOB\_3**, **KNOB\_5**, **KNOB\_2**, **KNOB\_4**, **KNOB\_6**, **KNOB\_7**, **KNOB\_8**, **KNOB\_LAST** }
- enum { **CV\_1**, **CV\_2**, **CV\_3**, **CV\_4**, **CV\_LAST** }
- enum { **LED\_KEY\_A8**, **LED\_KEY\_A7**, **LED\_KEY\_A6**, **LED\_KEY\_A5**, **LED\_KEY\_A4**, **LED\_KEY\_A3**, **LED\_KEY\_A2**, **LED\_KEY\_A1**, **LED\_KEY\_B1**, **LED\_KEY\_B2**, **LED\_KEY\_B3**, **LED\_KEY\_B4**, **LED\_KEY\_B5**, **LED\_KEY\_B6**, **LED\_KEY\_B7**, **LED\_KEY\_B8**, **LED\_KNOB\_1**, **LED\_KNOB\_2**, **LED\_KNOB\_3**, **LED\_KNOB\_4**, **LED\_KNOB\_5**, **LED\_KNOB\_6**, **LED\_KNOB\_7**, **LED\_KNOB\_8**, **LED\_SW\_1**, **LED\_SW\_2**, **LED\_LAST** }
- enum [MidiMessageType](#) { **NoteOff**, **NoteOn**, **PolyphonicKeyPressure**, **ControlChange**, **ProgramChange**, **ChannelPressure**, **PitchBend**, **MessageLast** }
- enum [SdmmcMode](#) { **SDMMC\_MODE\_FATFS** }
- enum [SdmmcBitWidth](#) { **SDMMC\_BITS\_1**, **SDMMC\_BITS\_4** }
- enum [SdmmcSpeed](#) { **SDMMC\_SPEED\_400KHZ**, **SDMMC\_SPEED\_12MHZ** }
- enum **SpiPeriph** { **SPI\_PERIPH\_1**, **SPI\_PERIPH\_3**, **SPI\_PERIPH\_6** }
- enum **SpiPin** { **SPI\_PIN\_CS**, **SPI\_PIN\_SCK**, **SPI\_PIN\_MOSI**, **SPI\_PIN\_MISO** }

## Functions

- **FORCE\_INLINE** void [daisy\\_field\\_init](#) ([daisy\\_field](#) \*p)

## Variables

- const size\_t **kUartMaxBufferSize** = 32

### 7.1.1 Detailed Description

- Get this set up to work with the dev\_leddriver stuff as well

Setup Hardware PWM for pins that have it

Simple parameter mapping tool that takes a 0-1 input from an hid\_ctrl.

TODO:

- Add documentation
- Add configuration
- Add reception
- Add IT
- Add DMA

## 7.1.2 Enumeration Type Documentation

### 7.1.2.1 anonymous enum

anonymous enum

enums for controls, etc.

### 7.1.2.2 anonymous enum

anonymous enum

All knobs connect to ADC1\_INP10 via CD4051 mux

### 7.1.2.3 MidiMessageType

enum `daisy::MidiMessageType`

Parsed from the Status Byte, these are the common Midi Messages that can be handled. At this time only 3-byte messages are correctly parsed into MidiEvents.

### 7.1.2.4 SdmmcBitWidth

enum `daisy::SdmmcBitWidth`

Sets whether 4-bit mode or 1-bit mode is used for the SDMMC

### 7.1.2.5 SdmmcMode

enum `daisy::SdmmcMode`

Operating ModeCurrently only FatFS is supported.

### 7.1.2.6 SdmmcSpeed

enum `daisy::SdmmcSpeed`

Sets the desired clock speed of the SD card bus. Initialization is always done at or below 400kHz, and then the user speed is set.

## 7.1.3 Function Documentation

### 7.1.3.1 daisy\_field\_init()

```
FORCE_INLINE void daisy::daisy_field_init (
    daisy_field * p )
```

```
dsy_gpio_port sw_ports[SW_LAST] = {SW_1_PORT, SW_2_PORT, SW_3_PORT};
```

Init Daisy Seed

Init Switches

Init Gate Input

Init Gate Output

```
Init LED Driver
```

2x PCA9685 addresses 0x00, and 0x01 TODO: add multidriver support

```
Init Keyboard Switches
```

TODO: add cd4021 with parallel data support

Init ADC (currently in daisy\_seed).

Set up mux pin

Set up CV inputs

Init all 5 channels

```
Setup Knob/CV Analog Controls
```

Mapped to ADCs

Start timer

## Chapter 8

# Class Documentation

### 8.1 daisy::AdcChannelConfig Struct Reference

```
#include <per_adc.h>
```

#### Public Types

- enum **MuxPin** { **MUX\_SEL\_0**, **MUX\_SEL\_1**, **MUX\_SEL\_2**, **MUX\_SEL\_LAST** }

#### Public Member Functions

- void **InitSingle** ([dsy\\_gpio\\_pin](#) pin)
- void **InitMux** ([dsy\\_gpio\\_pin](#) adc\_pin, [dsy\\_gpio\\_pin](#) mux\_0, [dsy\\_gpio\\_pin](#) mux\_1, [dsy\\_gpio\\_pin](#) mux\_2, [size\\_t](#) channels)

#### Public Attributes

- [dsy\\_gpio\\_pin](#) **pin\_**
- [dsy\\_gpio\\_mux\\_pin](#) **pin\_** [MUX\_SEL\_LAST]
- [uint8\\_t](#) **mux\_channels\_**

#### 8.1.1 Detailed Description

Configuration Structure for a given channel While there may not be many configuration options here, using a struct like this allows us to add more configuration later without breaking existing functionality.

#### 8.1.2 Member Function Documentation

### 8.1.2.1 InitMux()

```
void AdcChannelConfig::InitMux (
    dsy_gpio_pin adc_pin,
    dsy_gpio_pin mux_0,
    dsy_gpio_pin mux_1,
    dsy_gpio_pin mux_2,
    size_t channels )
```

Initializes a single ADC pin as a Multiplexed ADC. Requires a CD4051 Multiplexor connected to the pin. Internal Callbacks handle the pin addressing. channels must be 1-8

### 8.1.2.2 InitSingle()

```
void AdcChannelConfig::InitSingle (
    dsy_gpio_pin pin )
```

Initializes a single ADC pin as an ADC.

The documentation for this struct was generated from the following files:

- src/per\_adc.h
- src/per\_adc.cpp

## 8.2 daisy::AdcHandle Class Reference

### Public Types

- enum **OverSampling** {  
**OVS\_NONE**, **OVS\_4**, **OVS\_8**, **OVS\_16**,  
**OVS\_32**, **OVS\_64**, **OVS\_128**, **OVS\_256**,  
**OVS\_512**, **OVS\_1024**, **OVS\_LAST** }

### Public Member Functions

- void **Init** ([AdcChannelConfig](#) \*cfg, size\_t num\_channels, OverSampling ovs=OVS\_32)
- void **Start** ()
- void **Stop** ()
- uint16\_t **Get** (uint8\_t chn)
- uint16\_t \* **GetPtr** (uint8\_t chn)
- float **GetFloat** (uint8\_t chn)
- uint16\_t **GetMux** (uint8\_t chn, uint8\_t idx)
- uint16\_t \* **GetMuxPtr** (uint8\_t chn, uint8\_t idx)
- float **GetMuxFloat** (uint8\_t chn, uint8\_t idx)

### 8.2.1 Member Function Documentation



#### 8.2.1.1 Get()

```
uint16_t AdcHandle::Get (
    uint8_t chn )
```

These are getters for a single channel

#### 8.2.1.2 GetMux()

```
uint16_t AdcHandle::GetMux (
    uint8_t chn,
    uint8_t idx )
```

These are getters for multiplexed inputs on a single channel (up to 8 per ADC input).

#### 8.2.1.3 Init()

```
void AdcHandle::Init (
    AdcChannelConfig * cfg,
    size_t num_channels,
    OverSampling ovs = OVS_32 )
```

Initializes the ADC with the pins passed in. \* \*cfg: an array of [AdcChannelConfig](#) of the desired channel num\_↵  
channels: number of ADC channels to initialize ovs: Oversampling amount - Defaults to OVS\_32

#### 8.2.1.4 Start()

```
void AdcHandle::Start ( )
```

Starts reading from the ADC

#### 8.2.1.5 Stop()

```
void AdcHandle::Stop ( )
```

Stops reading from the ADC

The documentation for this class was generated from the following files:

- [src/per\\_adc.h](#)
- [src/per\\_adc.cpp](#)

## 8.3 daisy::AnalogControl Class Reference

### Public Member Functions

- void [Init](#) (uint16\_t \*adcptr, float sr, bool flip=false, bool invert=false, float slew\_seconds=0.002f)
- void [InitBipolarCv](#) (uint16\_t \*adcptr, float sr)
- float [Process](#) ()
- float [Value](#) () const

### 8.3.1 Member Function Documentation

#### 8.3.1.1 Init()

```
void AnalogControl::Init (
    uint16_t * adcptr,
    float sr,
    bool flip = false,
    bool invert = false,
    float slew_seconds = 0.002f )
```

Initializes the control adcptr is a pointer to the raw adc read value – This can acquired with dsy\_adc\_get\_rawptr(), or dsy\_adc\_get\_mux\_rawptr() sr is the samplerate in Hz that the Process function will be called at. slew\_seconds is the slow time in seconds that it takes for the control to change to a new value. flip determines whether the input is flipped (i.e. 1.f - input) or not before being processed. invert determines whether the input is inverted (i.e. -1.f \* input) or not before being processed.

#### 8.3.1.2 InitBipolarCv()

```
void AnalogControl::InitBipolarCv (
    uint16_t * adcptr,
    float sr )
```

This Initializes the [AnalogControl](#) for a -5V to 5V inverted input All of the Init details are the same otherwise

#### 8.3.1.3 Process()

```
float AnalogControl::Process ( )
```

filters, and transforms a raw ADC read into a normalized range. this should be called at the rate of specified by samplerate at Init time. Default Initializations will return 0.0 -> 1.0 Bi-polar CV inputs will return -1.0 -> 1.0

#### 8.3.1.4 Value()

```
float daisy::AnalogControl::Value ( ) const [inline]
```

Returns the current stored value, without reprocessing

The documentation for this class was generated from the following files:

- src/hid\_ctrl.h
- src/hid\_ctrl.cpp

## 8.4 codec\_frame\_t Struct Reference

### Public Attributes

- short **l**
- short **r**

The documentation for this struct was generated from the following file:

- src/dev\_codec\_wm8731\_frame.h

## 8.5 color Struct Reference

```
#include <dev_leddriver.h>
```

### Public Attributes

- uint16\_t **red**
- uint16\_t **green**
- uint16\_t **blue**

### 8.5.1 Detailed Description

Simple color struct Different from util\_color only in type (0-4095 vs 0-1) This could easily be migrated to work with those instead.

The documentation for this struct was generated from the following file:

- src/dev\_leddriver.h

## 8.6 daisy::Color Class Reference

### Public Types

- enum **PresetColor** {  
    **RED, GREEN, BLUE, WHITE,**  
    **PURPLE, CYAN, GOLD, OFF,**  
    **LAST }**

### Public Member Functions

- void **Init** (**PresetColor** c)
- void **Init** (float red, float green, float blue)
- float **Red** () const
- float **Green** () const
- float **Blue** () const

## 8.6.1 Member Enumeration Documentation

### 8.6.1.1 PresetColor

```
enum daisy::Color::PresetColor
```

List of colors that have a preset RGB value

## 8.6.2 Member Function Documentation

### 8.6.2.1 Init() [1/2]

```
void Color::Init (
    PresetColor c )
```

Initializes the [Color](#) with a given preset.

### 8.6.2.2 Init() [2/2]

```
void Color::Init (
    float red,
    float green,
    float blue )
```

Initializes the [Color](#) with a specific RGB value

red, green, and blue should be floats between 0 and 1

### 8.6.2.3 Red()

```
float daisy::Color::Red ( ) const [inline]
```

Returns the 0-1 value for the given color

The documentation for this class was generated from the following files:

- src/util\_color.h
- src/util\_color.cpp

## 8.7 daisy::ControlChangeEvent Struct Reference

```
#include <hid_midi.h>
```

### Public Attributes

- int **channel**
- uint8\_t **control\_number**
- uint8\_t **value**

#### 8.7.1 Detailed Description

Struct containing control number, and value for a given channel. Can be made from [MidiEvent](#)

The documentation for this struct was generated from the following file:

- src/hid\_midi.h

## 8.8 daisy::daisy\_field Struct Reference

### Public Attributes

- [daisy::DaisySeed](#) **seed**
- [daisy::Switch](#) **switches** [SW\_LAST]
- [dsy\\_gpio](#) **gate\_in**
- [dsy\\_gpio](#) **gate\_out**
- [dsy\\_sr\\_4021\\_handle](#) **keyboard\_sr**
- [AnalogControl](#) **knobs** [KNOB\_LAST]
- [AnalogControl](#) **cvs** [CV\_LAST]

The documentation for this struct was generated from the following file:

- src/daisy\_field.h

## 8.9 daisy::DaisyPatch Class Reference

### Public Types

- enum [Ctrl](#) {  
    **CTRL\_1**, **CTRL\_2**, **CTRL\_3**, **CTRL\_4**,  
    **CTRL\_LAST** }
- enum **GateInput** { **GATE\_IN\_1**, **GATE\_IN\_2**, **GATE\_IN\_LAST** }

### Public Member Functions

- void [Init](#) ()
- void **DelayMs** (size\_t del)
- void [SetAudioBlockSize](#) (size\_t size)
- void **StartAudio** (dsy\_audio\_mc\_callback cb)
- void **ChangeAudioCallback** (dsy\_audio\_callback cb)
- void **StartAdc** ()
- float [AudioSampleRate](#) ()
- size\_t **AudioBlockSize** ()
- float **AudioCallbackRate** ()
- void **UpdateAnalogControls** ()
- float **GetCtrlValue** ([Ctrl](#) k)
- void **DebounceControls** ()
- void **DisplayControls** (bool invert=true)

## Public Attributes

- [DaisySeed](#) **seed**
- [Encoder](#) **encoder**
- [AnalogControl](#) **controls** [CTRL\_LAST]
- [GateIn](#) **gate\_input** [GATE\_IN\_LAST]
- [MidiHandler](#) **midi**
- [OledDisplay](#) **display**
- [dsy\\_gpio](#) **gate\_output**

## 8.9.1 Member Enumeration Documentation

### 8.9.1.1 Ctrl

```
enum daisy::DaisyPatch::Ctrl
```

Enum of Ctrls to represent the four CV/Knob combos on the Patch

## 8.9.2 Member Function Documentation

### 8.9.2.1 AudioSampleRate()

```
float DaisyPatch::AudioSampleRate ( )
```

Hardware Accessors

### 8.9.2.2 Init()

```
void DaisyPatch::Init ( )
```

Initializes the daisy seed, and patch hardware.

### 8.9.2.3 SetAudioBlockSize()

```
void DaisyPatch::SetAudioBlockSize (
    size_t size )
```

Audio Block size defaults to 48. Change it using this function before StartingAudio

## 8.9.3 Member Data Documentation

## 8.9.3.1 gate\_output

`dsy_gpio` `daisy::DaisyPatch::gate_output`

TODO: Add class for Gate output

## 8.9.3.2 seed

`DaisySeed` `daisy::DaisyPatch::seed`

These are exposed for the user to access and manipulate directly. Helper functions above provide easier access to much of what they are capable of.

The documentation for this class was generated from the following files:

- `src/daisy_patch.h`
- `src/daisy_patch.cpp`

## 8.10 daisy::DaisyPetal Class Reference

## Public Types

- enum **Sw** {  
    **SW\_1**, **SW\_2**, **SW\_3**, **SW\_4**,  
    **SW\_5**, **SW\_6**, **SW\_7**, **SW\_LAST**}
- enum **Knob** {  
    **KNOB\_1**, **KNOB\_2**, **KNOB\_3**, **KNOB\_4**,  
    **KNOB\_5**, **KNOB\_6**, **KNOB\_LAST**}
- enum **RingLed** {  
    **RING\_LED\_1**, **RING\_LED\_2**, **RING\_LED\_3**, **RING\_LED\_4**,  
    **RING\_LED\_5**, **RING\_LED\_6**, **RING\_LED\_7**, **RING\_LED\_8**,  
    **RING\_LED\_LAST**}
- enum **FootswitchLed** {  
    **FOOTSWITCH\_LED\_1**, **FOOTSWITCH\_LED\_2**, **FOOTSWITCH\_LED\_3**, **FOOTSWITCH\_LED\_4**,  
    **FOOTSWITCH\_LED\_LAST**}

## Public Member Functions

- void **Init** ()
- void **DelayMs** (size\_t del)
- void **SetAudioBlockSize** (size\_t size)
- void **StartAudio** (dsy\_audio\_callback cb)
- void **ChangeAudioCallback** (dsy\_audio\_callback cb)
- void **StartAdc** ()
- float **AudioSampleRate** ()
- size\_t **AudioBlockSize** ()
- float **AudioCallbackRate** ()
- void **UpdateAnalogControls** ()
- float **GetKnobValue** (Knob k)
- float **GetExpression** ()
- void **DebounceControls** ()
- void **ClearLeds** ()
- void **UpdateLeds** ()
- void **SetRingLed** (RingLed idx, float r, float g, float b)
- void **SetFootswitchLed** (FootswitchLed idx, float bright)

## Public Attributes

- [DaisySeed](#) **seed**
- [Encoder](#) **encoder**
- [AnalogControl](#) **knob** [KNOB\_LAST]
- [AnalogControl](#) **expression**
- [Switch](#) **switches** [SW\_LAST]
- [RgbLed](#) **ring\_led** [8]
- [Led](#) **footswitch\_led** [4]

The documentation for this class was generated from the following files:

- src/daisy\_petal.h
- src/daisy\_petal.cpp

## 8.11 daisy::DaisyPod Class Reference

### Public Types

- enum **Sw** { **BUTTON\_1**, **BUTTON\_2**, **BUTTON\_LAST** }
- enum **Knob** { **KNOB\_1**, **KNOB\_2**, **KNOB\_LAST** }

### Public Member Functions

- void [Init](#) ()
- void **DelayMs** (size\_t del)
- void [SetAudioBlockSize](#) (size\_t size)
- void **StartAudio** (dsy\_audio\_callback cb)
- void **ChangeAudioCallback** (dsy\_audio\_callback cb)
- void **StartAdc** ()
- float [AudioSampleRate](#) ()
- size\_t **AudioBlockSize** ()
- float **AudioCallbackRate** ()
- void **UpdateAnalogControls** ()
- float **GetKnobValue** (Knob k)
- void **DebounceControls** ()
- void **ClearLeds** ()
- void **UpdateLeds** ()

### Public Attributes

- [DaisySeed](#) **seed**
- [Encoder](#) **encoder**
- [AnalogControl](#) **knob1**
- [AnalogControl](#) **knob2**
- [AnalogControl](#) \* **knobs** [KNOB\_LAST]
- [Switch](#) **button1**
- [Switch](#) **button2**
- [Switch](#) \* **buttons** [BUTTON\_LAST]
- [RgbLed](#) **led1**
- [RgbLed](#) **led2**



### 8.11.1 Member Function Documentation

#### 8.11.1.1 AudioSampleRate()

```
float DaisyPod::AudioSampleRate ( )
```

Hardware Accessors

#### 8.11.1.2 Init()

```
void DaisyPod::Init ( )
```

Functions Init related stuff.

#### 8.11.1.3 SetAudioBlockSize()

```
void DaisyPod::SetAudioBlockSize (
    size_t size )
```

Audio Block size defaults to 48. Change it using this function before StartingAudio

### 8.11.2 Member Data Documentation

#### 8.11.2.1 seed

```
DaisySeed daisy::DaisyPod::seed
```

Public Members.

The documentation for this class was generated from the following files:

- src/daisy\_pod.h
- src/daisy\_pod.cpp

## 8.12 daisy::DaisySeed Class Reference

### Public Member Functions

- void [Configure](#) ()
- void [Init](#) ()
- [dsy\\_gpio\\_pin GetPin](#) (uint8\_t pin\_idx)
- void [StartAudio](#) (dsy\_audio\_callback cb)
- void [SetLed](#) (bool state)
- void [SetTestPoint](#) (bool state)
- float [AudioSampleRate](#) ()
- void [SetAudioBlockSize](#) (size\_t blocksize)

## Public Attributes

- `dsy_sdram_handle` [sdram\\_handle](#)
- `dsy_qspi_handle` [qspi\\_handle](#)
- `dsy_audio_handle` [audio\\_handle](#)
- `dsy_sai_handle` [sai\\_handle](#)
- `dsy_i2c_handle` [i2c1\\_handle](#)
- `dsy_i2c_handle` [i2c2\\_handle](#)
- `AdcHandle` [adc](#)
- `dsy_dac_handle` [dac\\_handle](#)
- `UsbHandle` [usb\\_handle](#)

## 8.12.1 Member Function Documentation

### 8.12.1.1 AudioSampleRate()

```
float DaisySeed::AudioSampleRate ( )
```

Returns the audio sample rate in Hz as a floating point number.

### 8.12.1.2 Configure()

```
void DaisySeed::Configure ( )
```

configures the settings for all internal peripherals, but does not initialize them. This allows for modification of the configuration handles prior to initialization. Defaults listed below: TODO: Add defaults

### 8.12.1.3 GetPin()

```
dsy_gpio_pin DaisySeed::GetPin (
    uint8_t pin_idx )
```

Returns the gpio\_pin corresponding to the index 0-31. For the given GPIO on the Daisy Seed (labeled 1-32 in docs).

### 8.12.1.4 Init()

```
void DaisySeed::Init ( )
```

Initializes the Daisy Seed and the following peripherals: SDRAM, QSPI, 24-bit 48kHz Audio via AK4556, Internal USB, as well as the built-in LED and Testpoint. ADCs, DACs, and other special peripherals (such as I2C, SPI, etc.) can be initialized using their specific initializers within libdaisy for a specific application.

#### 8.12.1.5 SetAudioBlockSize()

```
void DaisySeed::SetAudioBlockSize (
    size_t blocksize )
```

Sets the number of samples processed per channel by the audio callback.

#### 8.12.1.6 SetLed()

```
void DaisySeed::SetLed (
    bool state )
```

Sets the state of the built in LED

#### 8.12.1.7 SetTestPoint()

```
void DaisySeed::SetTestPoint (
    bool state )
```

Sets the state of the test point near pin 10

#### 8.12.1.8 StartAudio()

```
void DaisySeed::StartAudio (
    dsy_audio_callback cb )
```

Begins the audio for the seeds builtin audio. the specified callback will get called whenever new data is ready to be prepared.

### 8.12.2 Member Data Documentation

#### 8.12.2.1 sdram\_handle

```
dsy_sdram_handle daisy::DaisySeed::sdram_handle
```

While the library is still in heavy development, most of the configuration handles will remain public.

The documentation for this class was generated from the following files:

- src/daisy\_seed.h
- src/daisy\_seed.cpp

## 8.13 dsy\_adc Struct Reference

### Public Attributes

- [AdcChannelConfig](#) **pin\_cfg** [14]
- uint8\_t **channels**
- uint8\_t **mux\_channels** [14]
- uint16\_t **mux\_index** [14]
- uint16\_t \* **dma\_buffer**
- uint16\_t(\* **mux\_cache**)[14][8]
- ADC\_HandleTypeDef **hadc1**
- DMA\_HandleTypeDef **hdma\_adc1**

The documentation for this struct was generated from the following file:

- src/per\_adc.cpp

## 8.14 dsy\_audio Struct Reference

### Public Attributes

- dsy\_audio\_callback **callback**
- dsy\_audio\_mc\_callback **mc\_callback**
- int32\_t \* **dma\_buffer\_rx**
- int32\_t \* **dma\_buffer\_tx**
- float **in** [128 \*2]
- float **out** [128 \*2]
- size\_t **block\_size**
- size\_t **offset**
- size\_t **dma\_size**
- uint8\_t **bitdepth**
- uint8\_t **device**
- uint8\_t **channels**
- [dsy\\_i2c\\_handle](#) \* **device\_control\_hi2c**
- [dsy\\_audio\\_handle](#) \* **config\_handle**

The documentation for this struct was generated from the following file:

- src/hid\_audio.c

## 8.15 dsy\_audio\_handle Struct Reference

```
#include <hid_audio.h>
```

### Public Attributes

- `size_t` **block\_size**
- `dsy_sai_handle` \* **sai**
- `dsy_i2c_handle` \* **dev0\_i2c**
- `dsy_i2c_handle` \* **dev1\_i2c**

#### 8.15.1 Detailed Description

Simple config struct that holds peripheral drivers.

The documentation for this struct was generated from the following file:

- `src/hid_audio.h`

## 8.16 dsy\_dac\_handle Struct Reference

```
#include <per_dac.h>
```

### Public Attributes

- `dsy_dac_mode` **mode**
- `dsy_dac_bitdepth` **bitdepth**
- `dsy_gpio_pin` **pin\_config** [DSY\_DAC\_CHN\_LAST]

#### 8.16.1 Detailed Description

Configuration structure for DAC initialization and settings.

`pin_config` must be filled out. However, the DACs are pretty consistently on pins PA4, and PA5 across all STM32 MCUs that I've used.

The documentation for this struct was generated from the following file:

- `src/per_dac.h`

## 8.17 dsy\_dac\_t Struct Reference

### Public Attributes

- `DAC_HandleTypeDef` **hdac1**
- `dsy_dac_handle` \* **dsy\_hdac**
- `uint8_t` **initialized**
- `dsy_dac_channel` **active\_channels**

The documentation for this struct was generated from the following file:

- `src/per_dac.c`

## 8.18 dsy\_gpio Struct Reference

```
#include <per_gpio.h>
```

### Public Attributes

- [dsy\\_gpio\\_pin](#) **pin**
- [dsy\\_gpio\\_mode](#) **mode**
- [dsy\\_gpio\\_pull](#) **pull**

### 8.18.1 Detailed Description

Struct for holding the pin, and configuration

The documentation for this struct was generated from the following file:

- `src/per_gpio.h`

## 8.19 dsy\_gpio\_pin Struct Reference

### Public Attributes

- [dsy\\_gpio\\_port](#) **port**
- [uint8\\_t](#) **pin**

The documentation for this struct was generated from the following file:

- `src/daisy_core.h`

## 8.20 dsy\_i2c\_handle Struct Reference

```
#include <per_i2c.h>
```

### Public Attributes

- [dsy\\_i2c\\_periph](#) **periph**
- [dsy\\_gpio\\_pin](#) **pin\_config** [DSY\_I2C\_PIN\_LAST]
- [dsy\\_i2c\\_speed](#) **speed**

### 8.20.1 Detailed Description

this object will be used to initialize the I2C interface, and can be passed to dev\_ drivers that require I2C.

The documentation for this struct was generated from the following file:

- `src/per_i2c.h`

## 8.21 dsy\_led\_driver\_t Struct Reference

### Public Attributes

- [led](#) **leds** [16 \*8]
- uint16\_t \* **sorted\_bright** [8][16]
- uint16\_t **dummy\_bright**
- float **master\_dim**
- uint8\_t **temp\_buff** [((16 \*4)+1)]
- uint8\_t **current\_drv**
- [color](#) **standard\_colors** [LED\_COLOR\_LAST]
- uint8\_t **num\_drivers**
- uint8\_t **driver\_addr** [8]
- I2C\_HandleTypeDef \* **i2c**
- [dsy\\_i2c\\_handle](#) \* **dsy\_i2c**

The documentation for this struct was generated from the following file:

- src/dev\_leddriver.c

## 8.22 dsy\_qspi Struct Reference

### Public Attributes

- QSPI\_HandleTypeDef **hqspi**
- uint8\_t **board**
- [dsy\\_qspi\\_handle](#) \* **dsy\_hqspi**

The documentation for this struct was generated from the following file:

- src/per\_qspi.c

## 8.23 dsy\_qspi\_handle Struct Reference

```
#include <per_qspi.h>
```

### Public Attributes

- dsy\_qspi\_mode **mode**
- dsy\_qspi\_device **device**
- [dsy\\_gpio\\_pin](#) **pin\_config** [DSY\_QSPI\_PIN\_LAST]

### 8.23.1 Detailed Description

Configuration structure for interfacing with QSPI Driver.

The documentation for this struct was generated from the following file:

- `src/per_qspi.h`

## 8.24 dsy\_sai\_handle Struct Reference

```
#include <per_sai.h>
```

### Public Attributes

- `dsy_audio_sai` **init**
- `dsy_audio_samplerate` **samplerate** [DSY\_SAI\_LAST]
- `dsy_audio_bitdepth` **bitdepth** [DSY\_SAI\_LAST]
- `dsy_audio_dir` **a\_direction** [DSY\_SAI\_LAST]
- `dsy_audio_dir` **b\_direction** [DSY\_SAI\_LAST]
- `dsy_audio_sync` **sync\_config** [DSY\_SAI\_LAST]
- `dsy_audio_device` **device** [DSY\_SAI\_LAST]
- [dsy\\_gpio\\_pin](#) **sai1\_pin\_config** [DSY\_SAI\_PIN\_LAST]
- [dsy\\_gpio\\_pin](#) **sai2\_pin\_config** [DSY\_SAI\_PIN\_LAST]

### 8.24.1 Detailed Description

Configuration structure for SAI contains all above settings, and passes them to internal structure for hardware initialization.

The documentation for this struct was generated from the following file:

- `src/per_sai.h`

## 8.25 DSY\_SD\_CardInfoTypeDef Struct Reference

```
#include <util_bsp_sd_diskio.h>
```

### Public Attributes

- `uint32_t` [CardType](#)
- `uint32_t` [CardVersion](#)
- `uint32_t` [Class](#)
- `uint32_t` [RelCardAdd](#)
- `uint32_t` [BlockNbr](#)
- `uint32_t` [BlockSize](#)
- `uint32_t` [LogBlockNbr](#)
- `uint32_t` [LogBlockSize](#)
- `uint32_t` [CardSpeed](#)



### 8.25.1 Detailed Description

This struct is identical to the struct provided as "HAL\_SD\_CardInfoTypeDef" I'm using this to allow users to link to the fatfs middleware without having to then link in the entire HAL to their project.

### 8.25.2 Member Data Documentation

#### 8.25.2.1 BlockNbr

```
uint32_t DSY_SD_CardInfoTypeDef::BlockNbr
```

Specifies the Card Capacity in blocks

#### 8.25.2.2 BlockSize

```
uint32_t DSY_SD_CardInfoTypeDef::BlockSize
```

Specifies one block size in bytes

#### 8.25.2.3 CardSpeed

```
uint32_t DSY_SD_CardInfoTypeDef::CardSpeed
```

Specifies the card Speed

#### 8.25.2.4 CardType

```
uint32_t DSY_SD_CardInfoTypeDef::CardType
```

Specifies the card Type

#### 8.25.2.5 CardVersion

```
uint32_t DSY_SD_CardInfoTypeDef::CardVersion
```

Specifies the card version

#### 8.25.2.6 Class

```
uint32_t DSY_SD_CardInfoTypeDef::Class
```

Specifies the class of the card class

#### 8.25.2.7 LogBlockNbr

```
uint32_t DSY_SD_CardInfoTypeDef::LogBlockNbr
```

Specifies the Card logical Capacity in blocks

#### 8.25.2.8 LogBlockSize

```
uint32_t DSY_SD_CardInfoTypeDef::LogBlockSize
```

Specifies logical block size in bytes

#### 8.25.2.9 RelCardAdd

```
uint32_t DSY_SD_CardInfoTypeDef::RelCardAdd
```

Specifies the Relative Card Address

The documentation for this struct was generated from the following file:

- src/util\_bsp\_sd\_diskio.h

## 8.26 dsy\_sdram\_t Struct Reference

### Public Attributes

- uint8\_t **board**
- SDRAM\_HandleTypeDef **hsdram**
- dsy\_sdram\_handle \* **dsy\_hsdram**

The documentation for this struct was generated from the following file:

- src/dev\_sdram.c

## 8.27 dsy\_sr\_4021\_handle Struct Reference

```
#include <dev_sr_4021.h>
```

### Public Attributes

- [dsy\\_gpio\\_pin](#) **pin\_config** [DSY\_SR\_4021\_PIN\_LAST]
- uint8\_t **num\_parallel**
- uint8\_t **num\_daisychained**
- [dsy\\_gpio](#) **cs**
- [dsy\\_gpio](#) **clk**
- [dsy\\_gpio](#) **data** [2]
- uint8\_t **states** [8 \*1 \*2]

### 8.27.1 Detailed Description

configuration strucutre for 4021

pin config is used to initialize the [dsy\\_gpio](#) num\_parallel is the number of devices connected that share the same clk/cs, etc. but have independent data num\_daisy chained is the number of devices in a daisy-chain configuration

The documentation for this struct was generated from the following file:

- `src/dev_sr_4021.h`

## 8.28 dsy\_tim Struct Reference

### Public Attributes

- `uint32_t scale` [SCALE\_LAST]
- `TIM_HandleTypeDef htim2`

The documentation for this struct was generated from the following file:

- `src/per_tim.c`

## 8.29 dsy\_wm8731\_handle\_t Struct Reference

### Public Attributes

- `uint8_t mcu_is_master`
- `uint8_t bitdepth`
- `int32_t sample_rate`
- `size_t block_size`
- `size_t stride`
- `I2C_HandleTypeDef * i2c`

The documentation for this struct was generated from the following file:

- `src/dev_codec_wm8731.c`

## 8.30 daisy::Encoder Class Reference

### Public Member Functions

- `void Init (dsy_gpio_pin a, dsy_gpio_pin b, dsy_gpio_pin click, float update_rate)`
- `void Debounce ()`
- `int32_t Increment () const`
- `bool RisingEdge () const`
- `bool FallingEdge () const`
- `bool Pressed () const`
- `float TimeHeldMs () const`

### 8.30.1 Member Function Documentation

#### 8.30.1.1 Debounce()

```
void Encoder::Debounce ( )
```

Called at `update_rate` to debounce and handle timing for the switch. In order for events not to be missed, its important that the Edge/Pressed checks be made at the same rate as the debounce function is being called.

#### 8.30.1.2 FallingEdge()

```
bool daisy::Encoder::FallingEdge ( ) const [inline]
```

Returns true if the encoder was just released.

#### 8.30.1.3 Increment()

```
int32_t daisy::Encoder::Increment ( ) const [inline]
```

Returns +1 if the encoder was turned clockwise, -1 if it was turned counter-clockwise, or 0 if it was not just turned.

#### 8.30.1.4 Init()

```
void Encoder::Init (
    dsy_gpio_pin a,
    dsy_gpio_pin b,
    dsy_gpio_pin click,
    float update_rate )
```

Initializes the encoder with the specified hardware pins. Update rate should be the rate at which [Debounce\(\)](#) gets called in Hertz.

#### 8.30.1.5 Pressed()

```
bool daisy::Encoder::Pressed ( ) const [inline]
```

Returns true while the encoder is held down.

#### 8.30.1.6 RisingEdge()

```
bool daisy::Encoder::RisingEdge ( ) const [inline]
```

Returns true if the encoder was just pressed.

### 8.30.1.7 TimeHeldMs()

```
float daisy::Encoder::TimeHeldMs ( ) const [inline]
```

Returns the time in milliseconds that the encoder has been held down.

The documentation for this class was generated from the following files:

- src/hid\_encoder.h
- src/hid\_encoder.cpp

## 8.31 FontDef Struct Reference

### Public Attributes

- const uint8\_t [FontWidth](#)
- uint8\_t [FontHeight](#)
- const uint16\_t \* [data](#)

### 8.31.1 Member Data Documentation

#### 8.31.1.1 data

```
const uint16_t* FontDef::data
```

Pointer to data font data array

#### 8.31.1.2 FontHeight

```
uint8_t FontDef::FontHeight
```

Font height in pixels

#### 8.31.1.3 FontWidth

```
const uint8_t FontDef::FontWidth
```

Font width in pixels

The documentation for this struct was generated from the following file:

- src/util\_oled\_fonts.h

## 8.32 daisy::GateIn Class Reference

### Public Member Functions

- void [Init](#) ([dsy\\_gpio\\_pin](#) \*pin\_cfg)
- bool [Trig](#) ()

### 8.32.1 Member Function Documentation

#### 8.32.1.1 Init()

```
void GateIn::Init (
    dsy\_gpio\_pin * pin_cfg )
```

Initializes the gate input with specified hardware pin

#### 8.32.1.2 Trig()

```
bool GateIn::Trig ( )
```

Checks current state of gate input. Returns FALSE if pin is low, and TRUE if high

The documentation for this class was generated from the following files:

- src/hid\_gatein.h
- src/hid\_gatein.cpp

## 8.33 led Struct Reference

### Public Attributes

- uint16\_t **bright**
- uint16\_t **addr**
- uint16\_t **drv**

The documentation for this struct was generated from the following file:

- src/dev\_leddriver.c

## 8.34 daisy::Led Class Reference

### Public Member Functions

- void [Init](#) ([dsy\\_gpio\\_pin](#) pin, bool invert, float samplerate=1000.0f)
- void [Set](#) (float val)
- void [Update](#) ()

### 8.34.1 Member Function Documentation

#### 8.34.1.1 Init()

```
void Led::Init (
    dsy\_gpio\_pin pin,
    bool invert,
    float samplerate = 1000.0f )
```

Initializes an LED using the specified hardware pin. invert will set whether to internally invert the brightness due to hardware config. samplerate sets the rate at which '[Update\(\)](#)' will be called (used for software PWM)

#### 8.34.1.2 Set()

```
void Led::Set (
    float val )
```

Sets the brightness of the Led. val will be cubed for gamma correction, and then quantized to 8-bit values for Software PWM. 8-bit is for more flexible update rate options, as 12-bit or more would require faster update rates.

#### 8.34.1.3 Update()

```
void Led::Update ( )
```

This processes the pwm of the LED sets the hardware accordingly.

The documentation for this class was generated from the following files:

- src/hid\_led.h
- src/hid\_led.cpp

## 8.35 daisy::MidiEvent Struct Reference

```
#include <hid_midi.h>
```

## Public Member Functions

- [NoteOnEvent AsNoteOn](#) ()
- [ControlChangeEvent AsControlChange](#) ()

## Public Attributes

- [MidiMessageType](#) **type**
- int **channel**
- uint8\_t **data** [2]

### 8.35.1 Detailed Description

Simple [MidiEvent](#) with message type, channel, and data[2] members.

### 8.35.2 Member Function Documentation

#### 8.35.2.1 AsControlChange()

```
ControlChangeEvent daisy::MidiEvent::AsControlChange ( ) [inline]
```

Returns the data within the [MidiEvent](#) as a [NoteOnEvent](#) struct.

#### 8.35.2.2 AsNoteOn()

```
NoteOnEvent daisy::MidiEvent::AsNoteOn ( ) [inline]
```

Returns the data within the [MidiEvent](#) as a [NoteOnEvent](#) struct.

### 8.35.3 Member Data Documentation

#### 8.35.3.1 type

```
MidiMessageType daisy::MidiEvent::type
```

Newer ish.

The documentation for this struct was generated from the following file:

- src/hid\_midi.h



## 8.36 daisy::MidiHandler Class Reference

### Public Types

- enum [MidiInputMode](#) { **INPUT\_MODE\_NONE** = 0x00, **INPUT\_MODE\_UART1** = 0x01, **INPUT\_MODE\_USB\_INT** = 0x02, **INPUT\_MODE\_USB\_EXT** = 0x04 }
- enum **MidiOutputMode** { **OUTPUT\_MODE\_NONE** = 0x00, **OUTPUT\_MODE\_UART1** = 0x01, **OUTPUT\_MODE\_USB\_INT** = 0x02, **OUTPUT\_MODE\_USB\_EXT** = 0x04 }

### Public Member Functions

- void [Init](#) ([MidiInputMode](#) in\_mode, [MidiOutputMode](#) out\_mode)
- void [StartReceive](#) ()
- void **Listen** ()
- void [Parse](#) (uint8\_t byte)
- bool [HasEvents](#) () const
- [MidiEvent](#) [PopEvent](#) ()

### 8.36.1 Member Enumeration Documentation

#### 8.36.1.1 MidiInputMode

```
enum daisy::MidiHandler::MidiInputMode
```

Input and Output can be configured separately Multiple Input modes can be selected by OR'ing the values.

### 8.36.2 Member Function Documentation

#### 8.36.2.1 HasEvents()

```
bool daisy::MidiHandler::HasEvents ( ) const [inline]
```

Checks if there are unhandled messages in the queue

#### 8.36.2.2 Init()

```
void MidiHandler::Init (
    MidiInputMode in_mode,
    MidiOutputMode out_mode )
```

Initializes the [MidiHandler](#)

### 8.36.2.3 Parse()

```
void MidiHandler::Parse (
    uint8_t byte )
```

Feed in bytes to state machine from a queue. Populates internal FIFO queue with MIDI Messages For example with  
uart: midi.Parse(uart.PopRx());

### 8.36.2.4 PopEvent()

```
MidiEvent daisy::MidiHandler::PopEvent ( ) [inline]
```

Pops the oldest unhandled [MidiEvent](#) from the internal queue

### 8.36.2.5 StartReceive()

```
void MidiHandler::StartReceive ( )
```

Starts listening on the selected input mode(s). [MidiEvent](#) Queue will begin to fill, and can be checked with

The documentation for this class was generated from the following files:

- src/hid\_midi.h
- src/hid\_midi.cpp

## 8.37 daisy::NoteOnEvent Struct Reference

```
#include <hid_midi.h>
```

### Public Attributes

- int **channel**
- uint8\_t **note**
- uint8\_t **velocity**

### 8.37.1 Detailed Description

Struct containing note, and velocity data for a given channel. Can be made from [MidiEvent](#)

The documentation for this struct was generated from the following file:

- src/hid\_midi.h

## 8.38 NVIC\_TypeDef Struct Reference

### Public Attributes

- volatile uint32\_t **ISER** [2]
- uint32\_t **RESERVED0** [30]
- volatile uint32\_t **ICER** [2]
- uint32\_t **RSERVED1** [30]
- volatile uint32\_t **ISPR** [2]
- uint32\_t **RESERVED2** [30]
- volatile uint32\_t **ICPR** [2]
- uint32\_t **RESERVED3** [30]
- volatile uint32\_t **IABR** [2]
- uint32\_t **RESERVED4** [62]
- volatile uint32\_t **IPR** [15]

The documentation for this struct was generated from the following file:

- src/sys\_system.c

## 8.39 daisy::OledDisplay Class Reference

### Public Types

- enum Pins { **DATA\_COMMAND**, **RESET**, **NUM\_PINS** }

### Public Member Functions

- void **Init** (dsy\_gpio\_pin \*pin\_cfg)
- void **Fill** (bool on)
- void **DrawPixel** (uint8\_t x, uint8\_t y, bool on)
- char **WriteChar** (char ch, FontDef font, bool on)
- char **WriteString** (char \*str, FontDef font, bool on)
- void **SetCursor** (uint8\_t x, uint8\_t y)
- void **Update** ()

### 8.39.1 Member Enumeration Documentation

#### 8.39.1.1 Pins

```
enum daisy::OledDisplay::Pins
```

GPIO Pins that need to be used independent of peripheral used.

## 8.39.2 Member Function Documentation

### 8.39.2.1 DrawPixel()

```
void OledDisplay::DrawPixel (
    uint8_t x,
    uint8_t y,
    bool on )
```

Sets the pixel at the specified coordinate to be on/off.

### 8.39.2.2 Fill()

```
void OledDisplay::Fill (
    bool on )
```

Fills the entire display with either on/off.

### 8.39.2.3 Init()

```
void OledDisplay::Init (
    dsy_gpio_pin * pin_cfg )
```

TODO: - add I2C Support.

- add configuration for specific spi/i2c peripherals (currently only uses SPI1, w/ hardware controlled chip select.
- re-add support for SSD1306 displays Takes an argument for the pin cfg pin\_cfg should be a pointer to an array of OledDisplay::NUM\_PINS dsy\_gpio\_pins

### 8.39.2.4 SetCursor()

```
void OledDisplay::SetCursor (
    uint8_t x,
    uint8_t y )
```

Moves the 'Cursor' position used for WriteChar, and WriteStr to the specified coordinate.

### 8.39.2.5 Update()

```
void OledDisplay::Update (
    void )
```

Writes the current display buffer to the OLED device using SPI or I2C depending on how the object was initialized.

## 8.39.2.6 WriteChar()

```
char OledDisplay::WriteChar (
    char ch,
    FontDef font,
    bool on )
```

Writes the character with the specific [FontDef](#) to the display buffer at the current Cursor position.

## 8.39.2.7 WriteString()

```
char OledDisplay::WriteString (
    char * str,
    FontDef font,
    bool on )
```

Similar to WriteChar, except it will handle an entire String. Wrapping does not happen automatically, so the width of the string must be kept within the dimensions of the screen.

The documentation for this class was generated from the following files:

- src/hid\_oled\_display.h
- src/hid\_oled\_display.cpp

## 8.40 daisy::Parameter Class Reference

## Public Types

- enum [Curve](#) {  
    **LINEAR**, **EXPONENTIAL**, **LOGARITHMIC**, **CUBE**,  
    **LAST** }

## Public Member Functions

- void [Init](#) ([AnalogControl](#) input, float min, float max, [Curve](#) curve)
- float [Process](#) ()
- float [Value](#) ()

## 8.40.1 Member Enumeration Documentation

## 8.40.1.1 Curve

```
enum daisy::Parameter::Curve
```

Curves are applied to the output signal

## 8.40.2 Member Function Documentation

### 8.40.2.1 Init()

```
void Parameter::Init (
    AnalogControl input,
    float min,
    float max,
    Curve curve )
```

initialize a parameter using an hid\_ctrl object. hid\_ctrl input - object containing the direct link to a hardware control source. min - bottom of range. (when input is 0.0) max - top of range (when input is 1.0) curve - the scaling curve for the input->output transformation.

### 8.40.2.2 Process()

```
float Parameter::Process ( )
```

processes the input signal, this should be called at the samplerate of the hid\_ctrl passed in. returns a float with the specified transformation applied.

### 8.40.2.3 Value()

```
float daisy::Parameter::Value ( ) [inline]
```

returns the current value from the parameter without processing another sample. this is useful if you need to use the value multiple times, and don't store the output of process in a local variable.

The documentation for this class was generated from the following files:

- src/hid\_parameter.h
- src/hid\_parameter.cpp

## 8.41 rgb\_led Struct Reference

### Public Attributes

- color **c**
- uint16\_t **addr\_r**
- uint16\_t **addr\_g**
- uint16\_t **addr\_b**
- uint16\_t **drv\_r**
- uint16\_t **drv\_g**
- uint16\_t **drv\_b**

The documentation for this struct was generated from the following file:

- src/dev\_leddriver.c

## 8.42 daisy::RgbLed Class Reference

### Public Member Functions

- void [Init](#) ([dsy\\_gpio\\_pin](#) red, [dsy\\_gpio\\_pin](#) green, [dsy\\_gpio\\_pin](#) blue, bool invert)
- void [Set](#) (float r, float g, float b)
- void [SetColor](#) ([Color](#) c)
- void [Update](#) ()

### 8.42.1 Member Function Documentation

#### 8.42.1.1 Init()

```
void RgbLed::Init (  
    dsy\_gpio\_pin red,  
    dsy\_gpio\_pin green,  
    dsy\_gpio\_pin blue,  
    bool invert )
```

Initializes 3x GPIO Pins as red, green, and blue elements of an RGB LED

Invert will flip polarity of LED.

#### 8.42.1.2 Set()

```
void RgbLed::Set (  
    float r,  
    float g,  
    float b )
```

Sets each element of the LED with a floating point number 0-1

#### 8.42.1.3 SetColor()

```
void RgbLed::SetColor (  
    Color c )
```

Sets the RGB using a [Color](#) object.

#### 8.42.1.4 Update()

```
void RgbLed::Update (  
    void )
```

Updates the PWM of the LED based on the current values. Should be called at a regular interval. (i.e. 1kHz/1ms)

The documentation for this class was generated from the following files:

- [src/hid\\_rgb\\_led.h](#)
- [src/hid\\_rgb\\_led.cpp](#)

## 8.43 daisy::RingBuffer< T, size > Class Template Reference

### Public Member Functions

- void [Init](#) ()
- size\_t [capacity](#) () const
- size\_t [writable](#) () const
- size\_t [readable](#) () const
- void [Write](#) (T v)
- void [Overwrite](#) (T v)
- T [Read](#) ()
- T [ImmediateRead](#) ()
- void [Flush](#) ()
- void [Swallow](#) (size\_t n)
- void [ImmediateRead](#) (T \*destination, size\_t num\_elements)
- void [Overwrite](#) (const T \*source, size\_t num\_elements)

### 8.43.1 Member Function Documentation

#### 8.43.1.1 capacity()

```
template<typename T, size_t size>
size_t daisy::RingBuffer< T, size >::capacity ( ) const [inline]
```

Returns the total size of the ring buffer

#### 8.43.1.2 Flush()

```
template<typename T, size_t size>
void daisy::RingBuffer< T, size >::Flush ( ) [inline]
```

Flushes unread elements from the ring buffer

#### 8.43.1.3 ImmediateRead() [1/2]

```
template<typename T, size_t size>
T daisy::RingBuffer< T, size >::ImmediateRead ( ) [inline]
```

Reads next element from ring buffer immediately

#### 8.43.1.4 ImmediateRead() [2/2]

```
template<typename T, size_t size>
void daisy::RingBuffer< T, size >::ImmediateRead (
    T * destination,
    size_t num_elements ) [inline]
```

Reads a number of elements into a buffer immediately



#### 8.43.1.5 Init()

```
template<typename T, size_t size>
void daisy::RingBuffer< T, size >::Init ( ) [inline]
```

Initializes the Ring Buffer

#### 8.43.1.6 Overwrite() [1/2]

```
template<typename T, size_t size>
void daisy::RingBuffer< T, size >::Overwrite (
    T v ) [inline]
```

Writes the new element to the ring buffer, overwriting unread data if necessary.

#### 8.43.1.7 Overwrite() [2/2]

```
template<typename T, size_t size>
void daisy::RingBuffer< T, size >::Overwrite (
    const T * source,
    size_t num_elements ) [inline]
```

Overwrites a number of elements using the source buffer as input.

#### 8.43.1.8 Read()

```
template<typename T, size_t size>
T daisy::RingBuffer< T, size >::Read ( ) [inline]
```

Reads the first available element from the ring buffer

#### 8.43.1.9 readable()

```
template<typename T, size_t size>
size_t daisy::RingBuffer< T, size >::readable ( ) const [inline]
```

Returns number of unread elements in ring buffer

#### 8.43.1.10 Swallow()

```
template<typename T, size_t size>
void daisy::RingBuffer< T, size >::Swallow (
    size_t n ) [inline]
```

Read enough samples to make it possible to read 1 sample.

#### 8.43.1.11 writable()

```
template<typename T, size_t size>
size_t daisy::RingBuffer< T, size >::writable ( ) const [inline]
```

Returns the number of samples that can be written to ring buffer without overwriting unread data.

#### 8.43.1.12 Write()

```
template<typename T, size_t size>
void daisy::RingBuffer< T, size >::Write (
    T v ) [inline]
```

Writes the value to the next available position in the ring buffer

The documentation for this class was generated from the following file:

- src/util\_ringbuffer.h

## 8.44 daisy::RingBuffer< T, 0 > Class Template Reference

### Public Member Functions

- void **Init** ()
- size\_t **capacity** () const
- size\_t **writable** () const
- size\_t **readable** () const
- void **Write** (T v)
- void **Overwrite** (T v)
- T **Read** ()
- T **ImmediateRead** ()
- void **Flush** ()
- void **ImmediateRead** (T \*destination, size\_t num\_elements)
- void **Overwrite** (const T \*source, size\_t num\_elements)

The documentation for this class was generated from the following file:

- src/util\_ringbuffer.h

## 8.45 daisy::SdmmcHandler Class Reference

### Public Member Functions

- void **Init** ()

### 8.45.1 Member Function Documentation

#### 8.45.1.1 Init()

```
void SdmmcHandler::Init ( )
```

Initializes the SD Card Interface For now all settings are fixed (See todo at top of section)

The documentation for this class was generated from the following files:

- `src/per_sdmmc.h`
- `src/per_sdmmc.cpp`

## 8.46 daisy::SdmmcHandlerInit Struct Reference

```
#include <per_sdmmc.h>
```

### Public Attributes

- [SdmmcBitWidth](#) **bitdepth**
- [SdmmcSpeed](#) **speed**

### 8.46.1 Detailed Description

Structure for setting the options above.

Used to intiaillize [SdmmcHandler](#)

The documentation for this struct was generated from the following file:

- `src/per_sdmmc.h`

## 8.47 ShiftRegister595 Class Reference

### Public Types

- enum [Pins](#) { **PIN\_LATCH**, **PIN\_CLK**, **PIN\_DATA**, **NUM\_PINS** }

### Public Member Functions

- void [Init](#) ([dsy\\_gpio\\_pin](#) \*pin\_cfg, size\_t num\_daisy\_chained=1)
- void [Set](#) (uint8\_t idx, bool state)
- void [Write](#) ()

## 8.47.1 Member Enumeration Documentation

### 8.47.1.1 Pins

```
enum ShiftRegister595::Pins
```

The following pins correspond to the hardware connections to the 595.

LATCH corresponds to Pin 12 "RCLK" CLK corresponds to Pin 11 "SRCLK" DATA corresponds to Pin 14 "SER" *SRCLR* is not added here, but is tied to 3v3 on test hardware.

## 8.47.2 Member Function Documentation

### 8.47.2.1 Init()

```
void ShiftRegister595::Init (
    dsy_gpio_pin * pin_cfg,
    size_t num_daisy_chained = 1 )
```

Initializes the GPIO, and data for the ShiftRegister

Arguments:

\*pin\_cfg is an array of [dsy\\_gpio\\_pin](#) corresponding the the Pins enum above. num\_daisy\_chained (default = 1) is the number of 595 devices daisy chained together.

### 8.47.2.2 Set()

```
void ShiftRegister595::Set (
    uint8_t idx,
    bool state )
```

Sets the state of the specified output. The index starts with QA on the first device and ends with QH on the last device.

a true state will set the output HIGH, while a false state will set the output LOW.

### 8.47.2.3 Write()

```
void ShiftRegister595::Write ( )
```

Writes the states of shift register out to the connected devices.

The documentation for this class was generated from the following files:

- src/dev\_sr\_595.h
- src/dev\_sr\_595.cpp

## 8.48 daisy::SpiHandle Class Reference

### Public Member Functions

- void **Init** ()
- void **BlockingTransmit** (uint8\_t \*buff, size\_t size)

The documentation for this class was generated from the following files:

- src/per\_spi.h
- src/per\_spi.cpp

## 8.49 SSD1309\_t Struct Reference

### Public Attributes

- uint16\_t **CurrentX**
- uint16\_t **CurrentY**
- uint8\_t **Inverted**
- uint8\_t **Initialized**

The documentation for this struct was generated from the following file:

- src/hid\_oled\_display.cpp

## 8.50 daisy::Switch Class Reference

### Public Types

- enum [Type](#) { **TYPE\_TOGGLE**, **TYPE\_MOMENTARY** }
- enum [Polarity](#) { **POLARITY\_NORMAL**, **POLARITY\_INVERTED** }
- enum [Pull](#) { **PULL\_UP**, **PULL\_DOWN**, **PULL\_NONE** }

### Public Member Functions

- void [Init](#) ([dsy\\_gpio\\_pin](#) pin, float update\_rate, [Type](#) t, [Polarity](#) pol, [Pull](#) pu)
- void **Init** ([dsy\\_gpio\\_pin](#) pin, float update\_rate)
- void [Debounce](#) ()
- bool [RisingEdge](#) () const
- bool [FallingEdge](#) () const
- bool [Pressed](#) () const
- float [TimeHeldMs](#) () const

### 8.50.1 Member Enumeration Documentation

#### 8.50.1.1 Polarity

```
enum daisy::Switch::Polarity
```

Specifies whether the pressed is HIGH or LOW.

#### 8.50.1.2 Pull

```
enum daisy::Switch::Pull
```

Specifies whether to use built-in Pull Up/Down resistors to hold button at a given state when not engaged.

#### 8.50.1.3 Type

```
enum daisy::Switch::Type
```

Specifies the expected behavior of the switch

### 8.50.2 Member Function Documentation

#### 8.50.2.1 Debounce()

```
void Switch::Debounce ( )
```

Called at `update_rate` to debounce and handle timing for the switch. In order for events not to be missed, its important that the Edge/Pressed checks be made at the same rate as the debounce function is being called.

#### 8.50.2.2 FallingEdge()

```
bool daisy::Switch::FallingEdge ( ) const [inline]
```

Returns true if the button was just released

#### 8.50.2.3 Init()

```
void Switch::Init (
    dsy_gpio_pin pin,
    float update_rate,
    Type t,
    Polarity pol,
    Pull pu )
```

Initializes the switch object with a given port/pin combo. Parameters: - pin: port/pin object to tell the switch which hardware pin to use.

- `update_rate`: the rate at which the [Debounce\(\)](#) function will be called. (used for timing).
- `t`: switch type – Default: `TYPE_MOMENTARY`
- `pol`: switch polarity – Default: `POLARITY_INVERTED`
- `pu`: switch pull up/down – Default: `PULL_UP`

8.50.2.4 `Pressed()`

```
bool daisy::Switch::Pressed ( ) const [inline]
```

Returns true if the button is held down (or if the toggle is on).

8.50.2.5 `RisingEdge()`

```
bool daisy::Switch::RisingEdge ( ) const [inline]
```

Returns true if a button was just pressed.

8.50.2.6 `TimeHeldMs()`

```
float daisy::Switch::TimeHeldMs ( ) const [inline]
```

Returns the time in milliseconds that the button has been held (or toggle has been on)

The documentation for this class was generated from the following files:

- `src/hid_switch.h`
- `src/hid_switch.cpp`

8.51 `uart_handle` Struct Reference

## Public Attributes

- `UART_HandleTypeDef` **huart1**
- `DMA_HandleTypeDef` **hdma\_usart1\_rx**
- `uint8_t *` **dma\_buffer\_rx**
- `bool` **receiving**
- `size_t` **rx\_size**
- `RingBuffer< uint8_t, 64 >` **queue\_rx**
- `bool` **rx\_active**
- `bool` **tx\_active**

The documentation for this struct was generated from the following file:

- `src/per_uart.cpp`

8.52 `daisy::UartHandler` Class Reference

## Public Member Functions

- `void` **Init** ()
- `int` **PollReceive** (`uint8_t *` buff, `size_t` size, `uint32_t` timeout)
- `int` **StartRx** (`size_t` size)
- `bool` **RxActive** ()
- `int` **FlushRx** ()
- `int` **PollTx** (`uint8_t *` buff, `size_t` size)
- `uint8_t` **PopRx** ()
- `size_t` **Readable** ()
- `int` **CheckError** ()

## 8.52.1 Member Function Documentation

### 8.52.1.1 CheckError()

```
int UartHandler::CheckError ( )
```

Returns the result of HAL\_UART\_GetError() to the user.

### 8.52.1.2 FlushRx()

```
int UartHandler::FlushRx ( )
```

Flushes the Receive Queue

### 8.52.1.3 Init()

```
void UartHandler::Init ( )
```

Initializes the UART Peripheral

### 8.52.1.4 PollReceive()

```
int UartHandler::PollReceive (
    uint8_t * buff,
    size_t size,
    uint32_t timeout )
```

Reads the amount of bytes in blocking mode with a 10ms timeout.

### 8.52.1.5 PollTx()

```
int UartHandler::PollTx (
    uint8_t * buff,
    size_t size )
```

Sends an amount of data in blocking mode.

### 8.52.1.6 PopRx()

```
uint8_t UartHandler::PopRx ( )
```

Pops the oldest byte from the FIFO.



#### 8.52.1.7 Readable()

```
size_t UartHandler::Readable ( )
```

Checks if there are any unread bytes in the FIFO

#### 8.52.1.8 RxActive()

```
bool UartHandler::RxActive ( )
```

Returns whether Rx DMA is listening or not.

#### 8.52.1.9 StartRx()

```
int UartHandler::StartRx (
    size_t size )
```

Starts a DMA Receive callback to fill a buffer of specified size. Data is populated into a FIFO queue, and can be queried with the functions below. Maximum Buffer size is defined above. If a value outside of the maximum is specified, the size will be set to the maximum.

The documentation for this class was generated from the following files:

- src/per\_uart.h
- src/per\_uart.cpp

## 8.53 daisy::UsbHandle Class Reference

### Public Types

- enum [UsbPeriph](#) { **FS\_INTERNAL**, **FS\_EXTERNAL**, **FS\_BOTH** }
- typedef void(\* [ReceiveCallback](#)) (uint8\_t \*buff, uint32\_t \*len)

### Public Member Functions

- void [Init](#) ([UsbPeriph](#) dev)
- void [TransmitInternal](#) (uint8\_t \*buff, size\_t size)
- void [TransmitExternal](#) (uint8\_t \*buff, size\_t size)
- void [SetReceiveCallback](#) ([ReceiveCallback](#) cb)

#### 8.53.1 Member Typedef Documentation

### 8.53.1.1 ReceiveCallback

```
typedef void(* daisy::UsbHandle::ReceiveCallback) (uint8_t *buff, uint32_t *len)
```

Function called upon reception of a buffer

## 8.53.2 Member Enumeration Documentation

### 8.53.2.1 UsbPeriph

```
enum daisy::UsbHandle::UsbPeriph
```

Specified which of the two USB Peripherals to initialize. FS External D- pin is Pin 37 (GPIO31) FS External D+ pin is Pin 38 (GPIO32)

## 8.53.3 Member Function Documentation

### 8.53.3.1 Init()

```
void UsbHandle::Init (  
    UsbPeriph dev )
```

Initializes the specified peripheral(s) as USB CDC Devices

### 8.53.3.2 SetReceiveCallback()

```
void UsbHandle::SetReceiveCallback (  
    ReceiveCallback cb )
```

sets the callback to be called upon reception of new data

### 8.53.3.3 TransmitExternal()

```
void UsbHandle::TransmitExternal (  
    uint8_t * buff,  
    size_t size )
```

Transmits a buffer of 'size' bytes from a USB port connected to the external USB Pins of the daisy seed.

#### 8.53.3.4 TransmitInternal()

```
void UsbHandle::TransmitInternal (
    uint8_t * buff,
    size_t size )
```

Transmits a buffer of 'size' bytes from the on board USB FS port.

The documentation for this class was generated from the following files:

- src/hid\_usb.h
- src/hid\_usb.cpp

## 8.54 WAV\_FormatTypeDef Struct Reference

### Public Attributes

- uint32\_t **ChunkId**
- uint32\_t **FileSize**
- uint32\_t **FileFormat**
- uint32\_t **SubChunk1ID**
- uint32\_t **SubChunk1Size**
- uint16\_t **AudioFormat**
- uint16\_t **NbrChannels**
- uint32\_t **SampleRate**
- uint32\_t **ByteRate**
- uint16\_t **BlockAlign**
- uint16\_t **BitPerSample**
- uint32\_t **SubChunk2ID**
- uint32\_t **SubCHunk2Size**

The documentation for this struct was generated from the following file:

- src/util\_wav\_format.h

## 8.55 daisy::WavFileInfo Struct Reference

```
#include <hid_wavplayer.h>
```

### Public Attributes

- [WAV\\_FormatTypeDef](#) **raw\_data**
- char **name** [256]

### 8.55.1 Detailed Description

Struct containing details of Wav File. TODO: add bitrate, samplerate, length, etc.

The documentation for this struct was generated from the following file:

- src/hid\_wavplayer.h

## 8.56 daisy::WavPlayer Class Reference

```
#include <hid_wavplayer.h>
```

### Public Member Functions

- void [Init](#) ()
- int [Open](#) (size\_t sel)
- int [Close](#) ()
- int16\_t [Stream](#) ()
- void [Prepare](#) ()
- void [Restart](#) ()
- void [SetLooping](#) (bool loop)
- bool [GetLooping](#) () const
- size\_t [GetNumberFiles](#) () const
- size\_t [GetCurrentFile](#) () const

### 8.56.1 Detailed Description

Class for handling playback of WAV files.

TODO:

- Make template-y to reduce memory usage.

### 8.56.2 Member Function Documentation

#### 8.56.2.1 Close()

```
int WavPlayer::Close ( )
```

Closes whatever file is currently open.

#### 8.56.2.2 GetCurrentFile()

```
size_t daisy::WavPlayer::GetCurrentFile ( ) const [inline]
```

Returns currently selected file.

#### 8.56.2.3 GetLooping()

```
bool daisy::WavPlayer::GetLooping ( ) const [inline]
```

Returns whether the [WavPlayer](#) is looping or not.

#### 8.56.2.4 GetNumberFiles()

```
size_t daisy::WavPlayer::GetNumberFiles ( ) const [inline]
```

Returns the number of files loaded by the [WavPlayer](#)

#### 8.56.2.5 Init()

```
void WavPlayer::Init ( )
```

Initializes the [WavPlayer](#), loading up to max\_files of wav files from an SD Card.

#### 8.56.2.6 Open()

```
int WavPlayer::Open (
    size_t sel )
```

Opens the file at index sel for reading.

#### 8.56.2.7 Prepare()

```
void WavPlayer::Prepare ( )
```

Collects buffer for playback when needed.

#### 8.56.2.8 Restart()

```
void WavPlayer::Restart ( )
```

Resets the playback position to the beginning of the file immediately

#### 8.56.2.9 SetLooping()

```
void daisy::WavPlayer::SetLooping (
    bool loop ) [inline]
```

Sets whether or not the current file will repeat after completing playback.

#### 8.56.2.10 Stream()

```
int16_t WavPlayer::Stream ( )
```

Returns the next sample if playing, otherwise returns 0

The documentation for this class was generated from the following files:

- src/hid\_wavplayer.h
- src/hid\_wavplayer.cpp



## Chapter 9

# File Documentation

### 9.1 src/system\_stm32h7xx.c File Reference

CMSIS Cortex-Mx Device Peripheral Access Layer System Source File.

```
#include "stm32h7xx.h"  
#include <math.h>
```

#### Macros

- #define **HSE\_VALUE** ((uint32\_t)25000000)
- #define **CSI\_VALUE** ((uint32\_t)4000000)
- #define **HSI\_VALUE** ((uint32\_t)64000000)
- #define **VECT\_TAB\_OFFSET** 0x00000000UL

#### Functions

- void **SystemInit** (void)  
*Setup the microcontroller system Initialize the FPU setting and vector table location configuration.*
- void **SystemCoreClockUpdate** (void)  
*Update SystemCoreClock variable according to Clock Register Values. The SystemCoreClock variable contains the core clock , it can be used by the user application to setup the SysTick timer or configure other parameters.*

#### Variables

- uint32\_t **SystemCoreClock** = 64000000
- uint32\_t **SystemD2Clock** = 64000000
- const uint8\_t **D1CorePrescTable** [16] = {0, 0, 0, 0, 1, 2, 3, 4, 1, 2, 3, 4, 6, 7, 8, 9}

### 9.1.1 Detailed Description

CMSIS Cortex-Mx Device Peripheral Access Layer System Source File.

#### Author

MCD Application Team This file provides two functions and one global variable to be called from user application:

- [SystemInit\(\)](#): This function is called at startup just after reset and before branch to main program. This call is made inside the "startup\_stm32h7xx.s" file.
- SystemCoreClock variable: Contains the core clock (HCLK), it can be used by the user application to setup the SysTick timer or configure other parameters.
- [SystemCoreClockUpdate\(\)](#): Updates the variable SystemCoreClock and must be called whenever the core clock is changed during program execution.

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## 9.2 src/usbd\_cdc\_if.c File Reference

: Usb device for Virtual Com Port.

```
#include "usbd_cdc_if.h"
```

#### Macros

- #define **APP\_RX\_DATA\_SIZE** 2048
- #define **APP\_TX\_DATA\_SIZE** 2048

#### Functions

- void **dummy\_rx\_callback** (uint8\_t \*buf, uint32\_t \*len)
- uint8\_t **CDC\_Transmit\_FS** (uint8\_t \*Buf, uint16\_t Len)  
*CDC\_Transmit\_FS Data to send over USB IN endpoint are sent over CDC interface through this function.*
- uint8\_t **CDC\_Transmit\_HS** (uint8\_t \*Buf, uint16\_t Len)  
*Data to send over USB IN endpoint are sent over CDC interface through this function.*
- void **CDC\_Set\_Rx\_Callback\_FS** (CDC\_ReceiveCallback cb)



## Variables

- uint8\_t [UserRxBufferFS](#) [2048]
- uint8\_t [UserTxBufferFS](#) [2048]
- uint8\_t [UserRxBufferHS](#) [2048]
- uint8\_t [UserTxBufferHS](#) [2048]
- CDC\_ReceiveCallback **rx\_callback\_fs**
- USBD\_HandleTypeDef **hUsbDeviceFS**
- USBD\_HandleTypeDef **hUsbDeviceHS**
- USBD\_CDC\_ItfTypeDef [USBD\\_Interface\\_fops\\_FS](#) = {CDC\_Init\_FS, CDC\_DeInit\_FS, CDC\_Control\_FS, CDC\_Receive\_FS}
- USBD\_CDC\_ItfTypeDef [USBD\\_Interface\\_fops\\_HS](#) = {CDC\_Init\_HS, CDC\_DeInit\_HS, CDC\_Control\_HS, CDC\_Receive\_HS}

### 9.2.1 Detailed Description

: Usb device for Virtual Com Port.

#### Version

: v1.0\_Cube

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## 9.3 src/usbd\_cdc\_if.h File Reference

: Header for [usbd\\_cdc\\_if.c](#) file.

```
#include "usbd_cdc.h"
```

## Typedefs

- typedef void(\* **CDC\_ReceiveCallback**) (uint8\_t \*buf, uint32\_t \*size)

## Functions

- void **CDC\_Set\_Rx\_Callback\_FS** (CDC\_ReceiveCallback cb)
- uint8\_t **CDC\_Transmit\_FS** (uint8\_t \*Buf, uint16\_t Len)  
*CDC\_Transmit\_FS Data to send over USB IN endpoint are sent over CDC interface through this function.*
- uint8\_t **CDC\_Transmit\_HS** (uint8\_t \*Buf, uint16\_t Len)  
*Data to send over USB IN endpoint are sent over CDC interface through this function.*

## Variables

- USB\_D\_CDC\_ItfTypeDef [USB\\_D\\_Interface\\_fops\\_FS](#)
- USB\_D\_CDC\_ItfTypeDef [USB\\_D\\_Interface\\_fops\\_HS](#)

### 9.3.1 Detailed Description

: Header for [usbd\\_cdc\\_if.c](#) file.

#### Version

: v1.0\_Cube

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## 9.4 src/usbd\_conf.c File Reference

: This file implements the board support package for the USB device library

```
#include "stm32h7xx.h"
#include "stm32h7xx_hal.h"
#include "usbd_def.h"
#include "usbd_core.h"
```

## Functions

- void **Error\_Handler** (void)
- USB\_StatusTypeDef **USB\_Get\_USB\_Status** (HAL\_StatusTypeDef hal\_status)  
*Returns the USB status depending on the HAL status:*
- void **HAL\_PCD\_MspInit** (PCD\_HandleTypeDef \*pcdHandle)
- void **HAL\_PCD\_MspDeInit** (PCD\_HandleTypeDef \*pcdHandle)
- void **HAL\_PCD\_SetupStageCallback** (PCD\_HandleTypeDef \*hpcd)  
*Setup stage callback.*
- void **HAL\_PCD\_DataOutStageCallback** (PCD\_HandleTypeDef \*hpcd, uint8\_t epnum)  
*Data Out stage callback.*
- void **HAL\_PCD\_DataInStageCallback** (PCD\_HandleTypeDef \*hpcd, uint8\_t epnum)  
*Data In stage callback.*
- void **HAL\_PCD\_SOFCallback** (PCD\_HandleTypeDef \*hpcd)  
*SOF callback.*
- void **HAL\_PCD\_ResetCallback** (PCD\_HandleTypeDef \*hpcd)  
*Reset callback.*
- void **HAL\_PCD\_SuspendCallback** (PCD\_HandleTypeDef \*hpcd)  
*Suspend callback. When Low power mode is enabled the debug cannot be used (IAR, Keil doesn't support it)*
- void **HAL\_PCD\_ResumeCallback** (PCD\_HandleTypeDef \*hpcd)  
*Resume callback. When Low power mode is enabled the debug cannot be used (IAR, Keil doesn't support it)*
- void **HAL\_PCD\_ISOOUTIncompleteCallback** (PCD\_HandleTypeDef \*hpcd, uint8\_t epnum)  
*ISOOUTIncomplete callback.*
- void **HAL\_PCD\_ISOINIncompleteCallback** (PCD\_HandleTypeDef \*hpcd, uint8\_t epnum)  
*ISOINIncomplete callback.*
- void **HAL\_PCD\_ConnectCallback** (PCD\_HandleTypeDef \*hpcd)  
*Connect callback.*
- void **HAL\_PCD\_DisconnectCallback** (PCD\_HandleTypeDef \*hpcd)  
*Disconnect callback.*
- USB\_StatusTypeDef **USB\_LL\_Init** (USB\_HandleTypeDef \*pdev)  
*Initializes the low level portion of the device driver.*
- USB\_StatusTypeDef **USB\_LL\_DeInit** (USB\_HandleTypeDef \*pdev)  
*De-Initializes the low level portion of the device driver.*
- USB\_StatusTypeDef **USB\_LL\_Start** (USB\_HandleTypeDef \*pdev)  
*Starts the low level portion of the device driver.*
- USB\_StatusTypeDef **USB\_LL\_Stop** (USB\_HandleTypeDef \*pdev)  
*Stops the low level portion of the device driver.*
- USB\_StatusTypeDef **USB\_LL\_OpenEP** (USB\_HandleTypeDef \*pdev, uint8\_t ep\_addr, uint8\_t ep\_type, uint16\_t ep\_mps)  
*Opens an endpoint of the low level driver.*
- USB\_StatusTypeDef **USB\_LL\_CloseEP** (USB\_HandleTypeDef \*pdev, uint8\_t ep\_addr)  
*Closes an endpoint of the low level driver.*
- USB\_StatusTypeDef **USB\_LL\_FlushEP** (USB\_HandleTypeDef \*pdev, uint8\_t ep\_addr)  
*Flushes an endpoint of the Low Level Driver.*
- USB\_StatusTypeDef **USB\_LL\_StallEP** (USB\_HandleTypeDef \*pdev, uint8\_t ep\_addr)  
*Sets a Stall condition on an endpoint of the Low Level Driver.*
- USB\_StatusTypeDef **USB\_LL\_ClearStallEP** (USB\_HandleTypeDef \*pdev, uint8\_t ep\_addr)  
*Clears a Stall condition on an endpoint of the Low Level Driver.*
- uint8\_t **USB\_LL\_IsStallEP** (USB\_HandleTypeDef \*pdev, uint8\_t ep\_addr)  
*Returns Stall condition.*
- USB\_StatusTypeDef **USB\_LL\_SetUSBAddress** (USB\_HandleTypeDef \*pdev, uint8\_t dev\_addr)

*Assigns a USB address to the device.*

- USB\_D\_StatusTypeDef [USB\\_D\\_LL\\_Transmit](#) (USB\_D\_HandleTypeDef \*pdev, uint8\_t ep\_addr, uint8\_t \*pbuf, uint16\_t size)

*Transmits data over an endpoint.*

- USB\_D\_StatusTypeDef [USB\\_D\\_LL\\_PrepareReceive](#) (USB\_D\_HandleTypeDef \*pdev, uint8\_t ep\_addr, uint8\_t \*pbuf, uint16\_t size)

*Prepares an endpoint for reception.*

- uint32\_t [USB\\_D\\_LL\\_GetRxDataSize](#) (USB\_D\_HandleTypeDef \*pdev, uint8\_t ep\_addr)

*Returns the last transferred packet size.*

- void [USB\\_D\\_LL\\_Delay](#) (uint32\_t Delay)

*Delays routine for the USB device library.*

## Variables

- PCD\_HandleTypeDef **hpcd\_USB\_OTG\_FS**
- PCD\_HandleTypeDef **hpcd\_USB\_OTG\_HS**

### 9.4.1 Detailed Description

: This file implements the board support package for the USB device library

#### Version

: v1.0\_Cube

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### 9.4.2 Function Documentation

#### 9.4.2.1 HAL\_PCD\_ConnectCallback()

```
void HAL_PCD_ConnectCallback (
    PCD_HandleTypeDef * hpcd )
```

Connect callback.

## Parameters

<i>hpcd</i>	PCD handle
-------------	------------

## Return values

<i>None</i>	
-------------	--

## 9.4.2.2 HAL\_PCD\_DataInStageCallback()

```
void HAL_PCD_DataInStageCallback (
    PCD_HandleTypeDef * hpcd,
    uint8_t epnum )
```

Data In stage callback.

## Parameters

<i>hpcd</i>	PCD handle
<i>epnum</i>	Endpoint number

## Return values

<i>None</i>	
-------------	--

## 9.4.2.3 HAL\_PCD\_DataOutStageCallback()

```
void HAL_PCD_DataOutStageCallback (
    PCD_HandleTypeDef * hpcd,
    uint8_t epnum )
```

Data Out stage callback.

## Parameters

<i>hpcd</i>	PCD handle
<i>epnum</i>	Endpoint number

## Return values

<i>None</i>	
-------------	--

#### 9.4.2.4 HAL\_PCD\_DisconnectCallback()

```
void HAL_PCD_DisconnectCallback (
    PCD_HandleTypeDef * hpcd )
```

Disconnect callback.

##### Parameters

<i>hpcd</i>	PCD handle
-------------	------------

##### Return values

<i>None</i>	
-------------	--

#### 9.4.2.5 HAL\_PCD\_ISOINIncompleteCallback()

```
void HAL_PCD_ISOINIncompleteCallback (
    PCD_HandleTypeDef * hpcd,
    uint8_t epnum )
```

ISOINIncomplete callback.

##### Parameters

<i>hpcd</i>	PCD handle
<i>epnum</i>	Endpoint number

##### Return values

<i>None</i>	
-------------	--

#### 9.4.2.6 HAL\_PCD\_ISOOUTIncompleteCallback()

```
void HAL_PCD_ISOOUTIncompleteCallback (
    PCD_HandleTypeDef * hpcd,
    uint8_t epnum )
```

ISOOUTIncomplete callback.

##### Parameters

<i>hpcd</i>	PCD handle
<i>epnum</i>	Endpoint number

## Return values

<i>None</i>	
-------------	--

## 9.4.2.7 HAL\_PCD\_MspDeInit()

```
void HAL_PCD_MspDeInit (
    PCD_HandleTypeDef * pcdHandle )
```

USB\_OTG\_FS GPIO Configuration PA12 —> USB\_OTG\_FS\_DP PA11 —> USB\_OTG\_FS\_DM PA9 —> USB\_OTG\_FS\_VBUS

USB\_OTG\_HS GPIO Configuration PB14 -----> USB\_OTG\_HS\_DM PB15 -----> USB\_OTG\_HS\_DP

## 9.4.2.8 HAL\_PCD\_MspInit()

```
void HAL_PCD_MspInit (
    PCD_HandleTypeDef * pcdHandle )
```

USB\_OTG\_FS GPIO Configuration PA12 —> USB\_OTG\_FS\_DP PA11 —> USB\_OTG\_FS\_DM PA9 —> USB\_OTG\_FS\_VBUS

USB\_OTG\_HS GPIO Configuration PB14 -----> USB\_OTG\_HS\_DM PB15 -----> USB\_OTG\_HS\_DP

## 9.4.2.9 HAL\_PCD\_ResetCallback()

```
void HAL_PCD_ResetCallback (
    PCD_HandleTypeDef * hpcd )
```

Reset callback.

## Parameters

<i>hpcd</i>	PCD handle
-------------	------------

## Return values

<i>None</i>	
-------------	--

## 9.4.2.10 HAL\_PCD\_ResumeCallback()

```
void HAL_PCD_ResumeCallback (
    PCD_HandleTypeDef * hpcd )
```

Resume callback. When Low power mode is enabled the debug cannot be used (IAR, Keil doesn't support it)



**Parameters**

<i>hpcd</i>	PCD handle
-------------	------------

**Return values**

<i>None</i>	
-------------	--

**9.4.2.11 HAL\_PCD\_SetupStageCallback()**

```
void HAL_PCD_SetupStageCallback (
    PCD_HandleTypeDef * hpcd )
```

Setup stage callback.

**Parameters**

<i>hpcd</i>	PCD handle
-------------	------------

**Return values**

<i>None</i>	
-------------	--

**9.4.2.12 HAL\_PCD\_SOFCallback()**

```
void HAL_PCD_SOFCallback (
    PCD_HandleTypeDef * hpcd )
```

SOF callback.

**Parameters**

<i>hpcd</i>	PCD handle
-------------	------------

**Return values**

<i>None</i>	
-------------	--

**9.4.2.13 HAL\_PCD\_SuspendCallback()**

```
void HAL_PCD_SuspendCallback (
```

```
PCD_HandleTypeDef * hpcd )
```

Suspend callback. When Low power mode is enabled the debug cannot be used (IAR, Keil doesn't support it)

#### Parameters

<i>hpcd</i>	PCD handle
-------------	------------

#### Return values

<i>None</i>	
-------------	--

#### 9.4.2.14 USB\_D\_Get\_USB\_Status()

```
USB_StatusTypeDef USB_D_Get_USB_Status (
    HAL_StatusTypeDef hal_status )
```

Returns the USB status depending on the HAL status:

#### Parameters

<i>hal_status</i>	HAL status
-------------------	------------

#### Return values

<i>USB</i>	status
------------	--------

#### 9.4.2.15 USB\_LL\_ClearStallEP()

```
USB_StatusTypeDef USB_LL_ClearStallEP (
    USB_HandleTypeDef * pdev,
    uint8_t ep_addr )
```

Clears a Stall condition on an endpoint of the Low Level Driver.

#### Parameters

<i>pdev</i>	Device handle
<i>ep_addr</i>	Endpoint number

#### Return values

<i>USB</i>	status
------------	--------

#### 9.4.2.16 USBD\_LL\_CloseEP()

```
USB_StatusTypeDef USBD_LL_CloseEP (
    USB_HandleTypeDef * pdev,
    uint8_t ep_addr )
```

Closes an endpoint of the low level driver.

##### Parameters

<i>pdev</i>	Device handle
<i>ep_addr</i>	Endpoint number

##### Return values

<i>USB</i>	status
------------	--------

#### 9.4.2.17 USBD\_LL\_DeInit()

```
USB_StatusTypeDef USBD_LL_DeInit (
    USB_HandleTypeDef * pdev )
```

De-Initializes the low level portion of the device driver.

##### Parameters

<i>pdev</i>	Device handle
-------------	---------------

##### Return values

<i>USB</i>	status
------------	--------

#### 9.4.2.18 USBD\_LL\_Delay()

```
void USBD_LL_Delay (
    uint32_t Delay )
```

Delays routine for the USB device library.

##### Parameters

<i>Delay</i>	Delay in ms
--------------	-------------

## Return values

<i>None</i>	
-------------	--

**9.4.2.19 USBD\_LL\_FlushEP()**

```
USB_StatusTypeDef USBD_LL_FlushEP (
    USB_HandleTypeDef * pdev,
    uint8_t ep_addr )
```

Flushes an endpoint of the Low Level Driver.

## Parameters

<i>pdev</i>	Device handle
<i>ep_addr</i>	Endpoint number

## Return values

<i>USB</i>	status
------------	--------

**9.4.2.20 USBD\_LL\_GetRxDataSize()**

```
uint32_t USBD_LL_GetRxDataSize (
    USB_HandleTypeDef * pdev,
    uint8_t ep_addr )
```

Returns the last transfered packet size.

## Parameters

<i>pdev</i>	Device handle
<i>ep_addr</i>	Endpoint number

## Return values

<i>Recived</i>	Data Size
----------------	-----------

**9.4.2.21 USBD\_LL\_Init()**

```
USB_StatusTypeDef USBD_LL_Init (
    USB_HandleTypeDef * pdev )
```

Initializes the low level portion of the device driver.

#### Parameters

<i>pdev</i>	Device handle
-------------	---------------

#### Return values

<i>USB_D</i>	status
--------------	--------

#### 9.4.2.22 USB\_D\_LL\_IsStallEP()

```
uint8_t USB_D_LL_IsStallEP (
    USB_D_HandleTypeDef * pdev,
    uint8_t ep_addr )
```

Returns Stall condition.

#### Parameters

<i>pdev</i>	Device handle
<i>ep_addr</i>	Endpoint number

#### Return values

<i>Stall</i>	(1: Yes, 0: No)
--------------	-----------------

#### 9.4.2.23 USB\_D\_LL\_OpenEP()

```
USB_D_StatusTypeDef USB_D_LL_OpenEP (
    USB_D_HandleTypeDef * pdev,
    uint8_t ep_addr,
    uint8_t ep_type,
    uint16_t ep_mps )
```

Opens an endpoint of the low level driver.

#### Parameters

<i>pdev</i>	Device handle
<i>ep_addr</i>	Endpoint number
<i>ep_type</i>	Endpoint type
<i>ep_mps</i>	Endpoint max packet size

## Return values

<i>USB</i>	status
------------	--------

**9.4.2.24 USBD\_LL\_PrepareReceive()**

```
USB_StatusTypeDef USBD_LL_PrepareReceive (
    USB_HandleTypeDef * pdev,
    uint8_t ep_addr,
    uint8_t * pbuf,
    uint16_t size )
```

Prepares an endpoint for reception.

## Parameters

<i>pdev</i>	Device handle
<i>ep_addr</i>	Endpoint number
<i>pbuf</i>	Pointer to data to be received
<i>size</i>	Data size

## Return values

<i>USB</i>	status
------------	--------

**9.4.2.25 USBD\_LL\_SetUSBAddress()**

```
USB_StatusTypeDef USBD_LL_SetUSBAddress (
    USB_HandleTypeDef * pdev,
    uint8_t dev_addr )
```

Assigns a USB address to the device.

## Parameters

<i>pdev</i>	Device handle
<i>dev_addr</i>	Device address

## Return values

<i>USB</i>	status
------------	--------

#### 9.4.2.26 USBD\_LL\_StallEP()

```
USB_StatusTypeDef USBD_LL_StallEP (
    USB_HandleTypeDef * pdev,
    uint8_t ep_addr )
```

Sets a Stall condition on an endpoint of the Low Level Driver.

##### Parameters

<i>pdev</i>	Device handle
<i>ep_addr</i>	Endpoint number

##### Return values

<i>USB</i>	status
------------	--------

#### 9.4.2.27 USBD\_LL\_Start()

```
USB_StatusTypeDef USBD_LL_Start (
    USB_HandleTypeDef * pdev )
```

Starts the low level portion of the device driver.

##### Parameters

<i>pdev</i>	Device handle
-------------	---------------

##### Return values

<i>USB</i>	status
------------	--------

#### 9.4.2.28 USBD\_LL\_Stop()

```
USB_StatusTypeDef USBD_LL_Stop (
    USB_HandleTypeDef * pdev )
```

Stops the low level portion of the device driver.

##### Parameters

<i>pdev</i>	Device handle
-------------	---------------

## Return values

<i>USB</i>	status
------------	--------

## 9.4.2.29 USB\_LL\_Transmit()

```

USB_StatusTypeDef USB_LL_Transmit (
    USB_HandleTypeDef * pdev,
    uint8_t ep_addr,
    uint8_t * pbuf,
    uint16_t size )

```

Transmits data over an endpoint.

## Parameters

<i>pdev</i>	Device handle
<i>ep_addr</i>	Endpoint number
<i>pbuf</i>	Pointer to data to be sent
<i>size</i>	Data size

## Return values

<i>USB</i>	status
------------	--------

## 9.5 src/usbd\_conf.h File Reference

: Header for [usbd\\_conf.c](#) file.

```

#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "stm32h7xx.h"
#include "stm32h7xx_hal.h"

```

## Macros

- #define **USB\_MAX\_NUM\_INTERFACES** 1U
- #define **USB\_MAX\_NUM\_CONFIGURATION** 1U
- #define **USB\_MAX\_STR\_DESC\_SIZ** 512U
- #define **USB\_SUPPORT\_USER\_STRING** 0U
- #define **USB\_DEBUG\_LEVEL** 3U
- #define **USB\_LPM\_ENABLED** 0U
- #define **USB\_SELF\_POWERED** 1U



- #define **DEVICE\_FS** 0
- #define **DEVICE\_HS** 1
- #define **USBD\_malloc** malloc
- #define **USBD\_free** free
- #define **USBD\_memset** memset
- #define **USBD\_memcpy** memcpy
- #define **USBD\_Delay** HAL\_Delay
- #define **USBD\_UsrLog**(...)
- #define **USBD\_ErrLog**(...)
- #define **USBD\_DbgLog**(...)

### 9.5.1 Detailed Description

: Header for [usbd\\_conf.c](#) file.

#### Version

: v1.0\_Cube

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## 9.6 src/usbd\_desc.c File Reference

: This file implements the USB device descriptors.

```
#include "usbd_core.h"
#include "usbd_desc.h"
#include "usbd_conf.h"
```

#### Macros

- #define **USBD\_VID** 1155
- #define **USBD\_LANGID\_STRING** 1033
- #define **USBD\_MANUFACTURER\_STRING** "Electrosmith"
- #define **USBD\_PID\_HS** 22336
- #define **USBD\_PRODUCT\_STRING\_HS** "Daisy Seed External"
- #define **USBD\_CONFIGURATION\_STRING\_HS** "CDC Config"
- #define **USBD\_INTERFACE\_STRING\_HS** "CDC Interface"
- #define **USBD\_PID\_FS** 22336
- #define **USBD\_PRODUCT\_STRING\_FS** "Daisy Seed Built In"
- #define **USBD\_CONFIGURATION\_STRING\_FS** "CDC Config"
- #define **USBD\_INTERFACE\_STRING\_FS** "CDC Interface"

## Functions

- `uint8_t * USBDF_FS_DeviceDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the device descriptor.*
- `uint8_t * USBDF_FS_LangIDStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the LangID string descriptor.*
- `uint8_t * USBDF_FS_ManufacturerStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the manufacturer string descriptor.*
- `uint8_t * USBDF_FS_ProductStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the product string descriptor.*
- `uint8_t * USBDF_FS_SerialStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the serial number string descriptor.*
- `uint8_t * USBDF_FS_ConfigStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the configuration string descriptor.*
- `uint8_t * USBDF_FS_InterfaceStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the interface string descriptor.*
- `uint8_t * USBDF_HS_DeviceDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the device descriptor.*
- `uint8_t * USBDF_HS_LangIDStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the LangID string descriptor.*
- `uint8_t * USBDF_HS_ManufacturerStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the manufacturer string descriptor.*
- `uint8_t * USBDF_HS_ProductStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the product string descriptor.*
- `uint8_t * USBDF_HS_SerialStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the serial number string descriptor.*
- `uint8_t * USBDF_HS_ConfigStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the configuration string descriptor.*
- `uint8_t * USBDF_HS_InterfaceStrDescriptor` (`USBDF_SpeedTypeDef speed`, `uint16_t *length`)  
*Return the interface string descriptor.*

## Variables

- `USBDF_DescriptorsTypeDef FS_Desc`
- `__ALIGN_BEGIN uint8_t USBDF_FS_DeviceDesc [USB_LEN_DEV_DESC] __ALIGN_END`
- `USBDF_DescriptorsTypeDef HS_Desc`

### 9.6.1 Detailed Description

: This file implements the USB device descriptors.

: Header for `usbdf_conf.c` file.

Version

: v1.0\_Cube

Attention

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# Index

- `__ALIGN_END`
  - `USB_D_DESC_Private_Variables`, [36](#)
- `AsControlChange`
  - `daisy::MidiEvent`, [94](#)
- `AsNoteOn`
  - `daisy::MidiEvent`, [94](#)
- `AudioSampleRate`
  - `daisy::DaisyPatch`, [76](#)
  - `daisy::DaisyPod`, [79](#)
  - `daisy::DaisySeed`, [80](#)
- `BlockNbr`
  - `DSY_SD_CardInfoTypeDef`, [87](#)
- `BlockSize`
  - `DSY_SD_CardInfoTypeDef`, [87](#)
- `CDC_Transmit_FS`
  - `USB_D_CDC_IF_Exported_FunctionsPrototype`, [23](#)
  - `USB_D_CDC_IF`, [18](#)
- `CDC_Transmit_HS`
  - `USB_D_CDC_IF_Exported_FunctionsPrototype`, [23](#)
  - `USB_D_CDC_IF`, [18](#)
- `CMSIS`, [52](#)
- `CSI_VALUE`
  - `STM32H7xx_System_Private_Includes`, [54](#)
- `capacity`
  - `daisy::RingBuffer`, [102](#)
- `CardSpeed`
  - `DSY_SD_CardInfoTypeDef`, [87](#)
- `CardType`
  - `DSY_SD_CardInfoTypeDef`, [87](#)
- `CardVersion`
  - `DSY_SD_CardInfoTypeDef`, [87](#)
- `CheckError`
  - `daisy::UartHandler`, [110](#)
- `Class`
  - `DSY_SD_CardInfoTypeDef`, [87](#)
- `Close`
  - `daisy::WavPlayer`, [114](#)
- `codec_frame_t`, [73](#)
- `color`, [73](#)
- `Configure`
  - `daisy::DaisySeed`, [80](#)
- `Ctrl`
  - `daisy::DaisyPatch`, [76](#)
- `Curve`
  - `daisy::Parameter`, [99](#)
- `DSY_SD_CardInfoTypeDef`, [86](#)
- `BlockNbr`, [87](#)
- `BlockSize`, [87](#)
- `CardSpeed`, [87](#)
- `CardType`, [87](#)
- `CardVersion`, [87](#)
- `Class`, [87](#)
- `LogBlockNbr`, [87](#)
- `LogBlockSize`, [88](#)
- `RelCardAdd`, [88](#)
- `daisy`, [65](#)
  - `daisy_field_init`, [67](#)
  - `MidiMessageType`, [67](#)
  - `SdmmcBitWidth`, [67](#)
  - `SdmmcMode`, [67](#)
  - `SdmmcSpeed`, [67](#)
- `daisy::AdcChannelConfig`, [69](#)
  - `InitMux`, [69](#)
  - `InitSingle`, [70](#)
- `daisy::AdcHandle`, [70](#)
  - `Get`, [70](#)
  - `GetMux`, [71](#)
  - `Init`, [71](#)
  - `Start`, [71](#)
  - `Stop`, [71](#)
- `daisy::AnalogControl`, [71](#)
  - `Init`, [72](#)
  - `InitBipolarCv`, [72](#)
  - `Process`, [72](#)
  - `Value`, [72](#)
- `daisy::Color`, [73](#)
  - `Init`, [74](#)
  - `PresetColor`, [74](#)
  - `Red`, [74](#)
- `daisy::ControlChangeEvent`, [74](#)
- `daisy::DaisyPatch`, [75](#)
  - `AudioSampleRate`, [76](#)
  - `Ctrl`, [76](#)
  - `gate_output`, [76](#)
  - `Init`, [76](#)
  - `seed`, [77](#)
  - `SetAudioBlockSize`, [76](#)
- `daisy::DaisyPetal`, [77](#)
- `daisy::DaisyPod`, [78](#)
  - `AudioSampleRate`, [79](#)
  - `Init`, [79](#)
  - `seed`, [79](#)
  - `SetAudioBlockSize`, [79](#)
- `daisy::DaisySeed`, [79](#)
  - `AudioSampleRate`, [80](#)

- Configure, [80](#)
- GetPin, [80](#)
- Init, [80](#)
- sdram\_handle, [81](#)
- SetAudioBlockSize, [80](#)
- SetLed, [81](#)
- SetTestPoint, [81](#)
- StartAudio, [81](#)
- daisy::Encoder, [89](#)
  - Debounce, [90](#)
  - FallingEdge, [90](#)
  - Increment, [90](#)
  - Init, [90](#)
  - Pressed, [90](#)
  - RisingEdge, [90](#)
  - TimeHeldMs, [90](#)
- daisy::GateIn, [92](#)
  - Init, [92](#)
  - Trig, [92](#)
- daisy::Led, [93](#)
  - Init, [93](#)
  - Set, [93](#)
  - Update, [93](#)
- daisy::MidiEvent, [93](#)
  - AsControlChange, [94](#)
  - AsNoteOn, [94](#)
  - type, [94](#)
- daisy::MidiHandler, [95](#)
  - HasEvents, [95](#)
  - Init, [95](#)
  - MidiInputMode, [95](#)
  - Parse, [95](#)
  - PopEvent, [96](#)
  - StartReceive, [96](#)
- daisy::NoteOnEvent, [96](#)
- daisy::OledDisplay, [97](#)
  - DrawPixel, [98](#)
  - Fill, [98](#)
  - Init, [98](#)
  - Pins, [97](#)
  - SetCursor, [98](#)
  - Update, [98](#)
  - WriteChar, [98](#)
  - WriteString, [99](#)
- daisy::Parameter, [99](#)
  - Curve, [99](#)
  - Init, [100](#)
  - Process, [100](#)
  - Value, [100](#)
- daisy::RgbLed, [101](#)
  - Init, [101](#)
  - Set, [101](#)
  - SetColor, [101](#)
  - Update, [101](#)
- daisy::RingBuffer
  - capacity, [102](#)
  - Flush, [102](#)
  - ImmediateRead, [102](#)
  - Init, [102](#)
  - Overwrite, [103](#)
  - Read, [103](#)
  - readable, [103](#)
  - Swallow, [103](#)
  - writable, [103](#)
  - Write, [104](#)
- daisy::RingBuffer< T, 0 >, [104](#)
- daisy::RingBuffer< T, size >, [102](#)
- daisy::SdmmcHandler, [104](#)
  - Init, [105](#)
- daisy::SdmmcHandlerInit, [105](#)
- daisy::SpiHandle, [107](#)
- daisy::Switch, [107](#)
  - Debounce, [108](#)
  - FallingEdge, [108](#)
  - Init, [108](#)
  - Polarity, [107](#)
  - Pressed, [108](#)
  - Pull, [108](#)
  - RisingEdge, [109](#)
  - TimeHeldMs, [109](#)
  - Type, [108](#)
- daisy::UartHandler, [109](#)
  - CheckError, [110](#)
  - FlushRx, [110](#)
  - Init, [110](#)
  - PollReceive, [110](#)
  - PollTx, [110](#)
  - PopRx, [110](#)
  - Readable, [110](#)
  - RxActive, [111](#)
  - StartRx, [111](#)
- daisy::UsbHandle, [111](#)
  - Init, [112](#)
  - ReceiveCallback, [111](#)
  - SetReceiveCallback, [112](#)
  - TransmitExternal, [112](#)
  - TransmitInternal, [112](#)
  - UsbPeriph, [112](#)
- daisy::WavFileInfo, [113](#)
- daisy::WavPlayer, [114](#)
  - Close, [114](#)
  - GetCurrentFile, [114](#)
  - GetLooping, [115](#)
  - GetNumberFiles, [115](#)
  - Init, [115](#)
  - Open, [115](#)
  - Prepare, [115](#)
  - Restart, [115](#)
  - SetLooping, [115](#)
  - Stream, [115](#)
- daisy::daisy\_field, [75](#)
- daisy\_field\_init
  - daisy, [67](#)
- data
  - FontDef, [91](#)
- Debounce

- daisy::Encoder, [90](#)
  - daisy::Switch, [108](#)
- DrawPixel
  - daisy::OledDisplay, [98](#)
- dsy\_adc, [82](#)
- dsy\_audio, [82](#)
- dsy\_audio\_handle, [82](#)
- dsy\_dac\_handle, [83](#)
- dsy\_dac\_t, [83](#)
- dsy\_gpio, [84](#)
- dsy\_gpio\_pin, [84](#)
- dsy\_i2c\_handle, [84](#)
- dsy\_led\_driver\_t, [85](#)
- dsy\_qspi, [85](#)
- dsy\_qspi\_handle, [85](#)
- dsy\_sai\_handle, [86](#)
- dsy\_sdram\_t, [88](#)
- dsy\_sr\_4021\_handle, [88](#)
- dsy\_tim, [89](#)
- dsy\_wm8731\_handle\_t, [89](#)
- FS\_Desc
  - USB\_DESC\_Exported\_Variables, [50](#)
  - USB\_DESC\_Private\_Variables, [36](#)
- FallingEdge
  - daisy::Encoder, [90](#)
  - daisy::Switch, [108](#)
- Fill
  - daisy::OledDisplay, [98](#)
- Flush
  - daisy::RingBuffer, [102](#)
- FlushRx
  - daisy::UartHandler, [110](#)
- FontDef, [91](#)
  - data, [91](#)
  - FontHeight, [91](#)
  - FontWidth, [91](#)
- FontHeight
  - FontDef, [91](#)
- FontWidth
  - FontDef, [91](#)
- gate\_output
  - daisy::DaisyPatch, [76](#)
- Get
  - daisy::AdcHandle, [70](#)
- GetCurrentFile
  - daisy::WavPlayer, [114](#)
- GetLooping
  - daisy::WavPlayer, [115](#)
- GetMux
  - daisy::AdcHandle, [71](#)
- GetNumberFiles
  - daisy::WavPlayer, [115](#)
- GetPin
  - daisy::DaisySeed, [80](#)
- HAL\_PCD\_ConnectCallback
  - usbd\_conf.c, [122](#)
- HAL\_PCD\_DataInStageCallback
  - usbd\_conf.c, [123](#)
- HAL\_PCD\_DataOutStageCallback
  - usbd\_conf.c, [123](#)
- HAL\_PCD\_DisconnectCallback
  - usbd\_conf.c, [123](#)
- HAL\_PCD\_ISOINIncompleteCallback
  - usbd\_conf.c, [124](#)
- HAL\_PCD\_ISOOUTIncompleteCallback
  - usbd\_conf.c, [124](#)
- HAL\_PCD\_MspDeInit
  - usbd\_conf.c, [125](#)
- HAL\_PCD\_Msplnit
  - usbd\_conf.c, [125](#)
- HAL\_PCD\_ResetCallback
  - usbd\_conf.c, [125](#)
- HAL\_PCD\_ResumeCallback
  - usbd\_conf.c, [125](#)
- HAL\_PCD\_SOFCallback
  - usbd\_conf.c, [127](#)
- HAL\_PCD\_SetupStageCallback
  - usbd\_conf.c, [127](#)
- HAL\_PCD\_SuspendCallback
  - usbd\_conf.c, [127](#)
- HS\_Desc
  - USB\_DESC\_Exported\_Variables, [50](#)
  - USB\_DESC\_Private\_Variables, [37](#)
- HSE\_VALUE
  - STM32H7xx\_System\_Private\_Includes, [54](#)
- HSI\_VALUE
  - STM32H7xx\_System\_Private\_Includes, [54](#)
- HasEvents
  - daisy::MidiHandler, [95](#)
- ImmediateRead
  - daisy::RingBuffer, [102](#)
- Increment
  - daisy::Encoder, [90](#)
- Init
  - daisy::AdcHandle, [71](#)
  - daisy::AnalogControl, [72](#)
  - daisy::Color, [74](#)
  - daisy::DaisyPatch, [76](#)
  - daisy::DaisyPod, [79](#)
  - daisy::DaisySeed, [80](#)
  - daisy::Encoder, [90](#)
  - daisy::Gateln, [92](#)
  - daisy::Led, [93](#)
  - daisy::MidiHandler, [95](#)
  - daisy::OledDisplay, [98](#)
  - daisy::Parameter, [100](#)
  - daisy::RgbLed, [101](#)
  - daisy::RingBuffer, [102](#)
  - daisy::SdmmcHandler, [105](#)
  - daisy::Switch, [108](#)
  - daisy::UartHandler, [110](#)
  - daisy::UsbHandle, [112](#)
  - daisy::WavPlayer, [115](#)
  - ShiftRegister595, [106](#)

- InitBipolarCv
  - daisy::AnalogControl, [72](#)
- InitMux
  - daisy::AdcChannelConfig, [69](#)
- InitSingle
  - daisy::AdcChannelConfig, [70](#)
- led, [92](#)
- LogBlockNbr
  - DSY\_SD\_CardInfoTypeDef, [87](#)
- LogBlockSize
  - DSY\_SD\_CardInfoTypeDef, [88](#)
- MidiInputMode
  - daisy::MidiHandler, [95](#)
- MidiMessageType
  - daisy, [67](#)
- NVIC\_TypeDef, [97](#)
- Open
  - daisy::WavPlayer, [115](#)
- Overwrite
  - daisy::RingBuffer, [103](#)
- Parse
  - daisy::MidiHandler, [95](#)
- Pins
  - daisy::OledDisplay, [97](#)
  - ShiftRegister595, [106](#)
- Polarity
  - daisy::Switch, [107](#)
- PollReceive
  - daisy::UartHandler, [110](#)
- PollTx
  - daisy::UartHandler, [110](#)
- PopEvent
  - daisy::MidiHandler, [96](#)
- PopRx
  - daisy::UartHandler, [110](#)
- Prepare
  - daisy::WavPlayer, [115](#)
- PresetColor
  - daisy::Color, [74](#)
- Pressed
  - daisy::Encoder, [90](#)
  - daisy::Switch, [108](#)
- Process
  - daisy::AnalogControl, [72](#)
  - daisy::Parameter, [100](#)
- Pull
  - daisy::Switch, [108](#)
- Read
  - daisy::RingBuffer, [103](#)
- Readable
  - daisy::UartHandler, [110](#)
- readable
  - daisy::RingBuffer, [103](#)
- ReceiveCallback
  - daisy::UsbHandle, [111](#)
- Red
  - daisy::Color, [74](#)
- RelCardAdd
  - DSY\_SD\_CardInfoTypeDef, [88](#)
- Restart
  - daisy::WavPlayer, [115](#)
- rgb\_led, [100](#)
- RisingEdge
  - daisy::Encoder, [90](#)
  - daisy::Switch, [109](#)
- RxActive
  - daisy::UartHandler, [111](#)
- SSD1309\_t, [107](#)
- STM32\_USB\_OTG\_DEVICE\_LIBRARY, [62](#)
- STM32H7xx\_System\_Private\_Defines, [56](#)
  - VECT\_TAB\_OFFSET, [56](#)
- STM32H7xx\_System\_Private\_FunctionPrototypes, [59](#)
- STM32H7xx\_System\_Private\_Functions, [60](#)
  - SystemCoreClockUpdate, [60](#)
  - SystemInit, [61](#)
- STM32H7xx\_System\_Private\_Includes, [54](#)
  - CSI\_VALUE, [54](#)
  - HSE\_VALUE, [54](#)
  - HSI\_VALUE, [54](#)
- STM32H7xx\_System\_Private\_Macros, [57](#)
- STM32H7xx\_System\_Private\_TypesDefinitions, [55](#)
- STM32H7xx\_System\_Private\_Variables, [58](#)
- SdmmcBitWidth
  - daisy, [67](#)
- SdmmcMode
  - daisy, [67](#)
- SdmmcSpeed
  - daisy, [67](#)
- sdram\_handle
  - daisy::DaisySeed, [81](#)
- seed
  - daisy::DaisyPatch, [77](#)
  - daisy::DaisyPod, [79](#)
- Set
  - daisy::Led, [93](#)
  - daisy::RgbLed, [101](#)
  - ShiftRegister595, [106](#)
- SetAudioBlockSize
  - daisy::DaisyPatch, [76](#)
  - daisy::DaisyPod, [79](#)
  - daisy::DaisySeed, [80](#)
- SetColor
  - daisy::RgbLed, [101](#)
- SetCursor
  - daisy::OledDisplay, [98](#)
- SetLed
  - daisy::DaisySeed, [81](#)
- SetLooping
  - daisy::WavPlayer, [115](#)
- SetReceiveCallback
  - daisy::UsbHandle, [112](#)
- SetTestPoint

- daisy::DaisySeed, 81
- ShiftRegister595, 105
  - Init, 106
  - Pins, 106
  - Set, 106
  - Write, 106
- src/system\_stm32h7xx.c, 117
- src/usbd\_cdc\_if.c, 118
- src/usbd\_cdc\_if.h, 119
- src/usbd\_conf.c, 120
- src/usbd\_conf.h, 134
- src/usbd\_desc.c, 135
- Start
  - daisy::AdcHandle, 71
- StartAudio
  - daisy::DaisySeed, 81
- StartReceive
  - daisy::MidiHandler, 96
- StartRx
  - daisy::UartHandler, 111
- Stm32h7xx\_system, 53
- Stop
  - daisy::AdcHandle, 71
- Stream
  - daisy::WavPlayer, 115
- Swallow
  - daisy::RingBuffer, 103
- SystemCoreClockUpdate
  - STM32H7xx\_System\_Private\_Functions, 60
- SystemInit
  - STM32H7xx\_System\_Private\_Functions, 61
- TimeHeldMs
  - daisy::Encoder, 90
  - daisy::Switch, 109
- TransmitExternal
  - daisy::UsbHandle, 112
- TransmitInternal
  - daisy::UsbHandle, 112
- Trig
  - daisy::GateIn, 92
- Type
  - daisy::Switch, 108
- type
  - daisy::MidiEvent, 94
- USBD\_CDC\_IF\_Exported\_Defines, 20
- USBD\_CDC\_IF\_Exported\_FunctionsPrototype, 23
  - CDC\_Transmit\_FS, 23
  - CDC\_Transmit\_HS, 23
- USBD\_CDC\_IF\_Exported\_Macros, 22
- USBD\_CDC\_IF\_Exported\_Types, 21
- USBD\_CDC\_IF\_Exported\_Variables, 15
  - USBD\_Interface\_fops\_FS, 15
  - USBD\_Interface\_fops\_HS, 15
- USBD\_CDC\_IF\_Private\_Defines, 12
- USBD\_CDC\_IF\_Private\_FunctionPrototypes, 16
- USBD\_CDC\_IF\_Private\_Macros, 13
- USBD\_CDC\_IF\_Private\_TypesDefinitions, 11
- USBD\_CDC\_IF\_Private\_Variables, 14
  - UserRxBufferFS, 14
  - UserRxBufferHS, 14
  - UserTxBufferFS, 14
  - UserTxBufferHS, 14
- USBD\_CDC\_IF, 17
  - CDC\_Transmit\_FS, 18
  - CDC\_Transmit\_HS, 18
  - USBD\_Interface\_fops\_FS, 18
  - USBD\_Interface\_fops\_HS, 19
- USBD\_CONF\_Exported\_Defines, 27
- USBD\_CONF\_Exported\_FunctionsPrototype, 31
- USBD\_CONF\_Exported\_Macros, 28
  - USBD\_DbgLog, 28
  - USBD\_Delay, 28
  - USBD\_ErrLog, 28
  - USBD\_UsrLog, 29
  - USBD\_free, 29
  - USBD\_malloc, 29
  - USBD\_memcpy, 29
  - USBD\_memset, 29
- USBD\_CONF\_Exported\_Types, 30
- USBD\_CONF\_Exported\_Variables, 26
- USBD\_CONF, 25
- USBD\_DESC\_Exported\_Constants, 46
- USBD\_DESC\_Exported\_Defines, 47
- USBD\_DESC\_Exported\_FunctionsPrototype, 51
- USBD\_DESC\_Exported\_Macros, 49
- USBD\_DESC\_Exported\_TypesDefinitions, 48
- USBD\_DESC\_Exported\_Variables, 50
  - FS\_Desc, 50
  - HS\_Desc, 50
- USBD\_DESC\_Private\_Defines, 33
- USBD\_DESC\_Private\_FunctionPrototypes, 35
- USBD\_DESC\_Private\_Functions, 38
  - USBD\_FS\_ConfigStrDescriptor, 38
  - USBD\_FS\_DeviceDescriptor, 39
  - USBD\_FS\_InterfaceStrDescriptor, 39
  - USBD\_FS\_LangIDStrDescriptor, 40
  - USBD\_FS\_ManufacturerStrDescriptor, 40
  - USBD\_FS\_ProductStrDescriptor, 40
  - USBD\_FS\_SerialStrDescriptor, 41
  - USBD\_HS\_ConfigStrDescriptor, 41
  - USBD\_HS\_DeviceDescriptor, 42
  - USBD\_HS\_InterfaceStrDescriptor, 42
  - USBD\_HS\_LangIDStrDescriptor, 42
  - USBD\_HS\_ManufacturerStrDescriptor, 43
  - USBD\_HS\_ProductStrDescriptor, 43
  - USBD\_HS\_SerialStrDescriptor, 44
- USBD\_DESC\_Private\_Macros, 34
- USBD\_DESC\_Private\_TypesDefinitions, 32
- USBD\_DESC\_Private\_Variables, 36
  - \_\_ALIGN\_END, 36
  - FS\_Desc, 36
  - HS\_Desc, 37
- USBD\_DESC, 45
- USBD\_DbgLog
  - USBD\_CONF\_Exported\_Macros, 28

- USB\_Delay
  - USB\_CONF\_Exported\_Macros, 28
- USB\_ErrLog
  - USB\_CONF\_Exported\_Macros, 28
- USB\_FS\_ConfigStrDescriptor
  - USB\_DESC\_Private\_Functions, 38
- USB\_FS\_DeviceDescriptor
  - USB\_DESC\_Private\_Functions, 39
- USB\_FS\_InterfaceStrDescriptor
  - USB\_DESC\_Private\_Functions, 39
- USB\_FS\_LangIDStrDescriptor
  - USB\_DESC\_Private\_Functions, 40
- USB\_FS\_ManufacturerStrDescriptor
  - USB\_DESC\_Private\_Functions, 40
- USB\_FS\_ProductStrDescriptor
  - USB\_DESC\_Private\_Functions, 40
- USB\_FS\_SerialStrDescriptor
  - USB\_DESC\_Private\_Functions, 41
- USB\_Get\_USB\_Status
  - usb\_conf.c, 128
- USB\_HS\_ConfigStrDescriptor
  - USB\_DESC\_Private\_Functions, 41
- USB\_HS\_DeviceDescriptor
  - USB\_DESC\_Private\_Functions, 42
- USB\_HS\_InterfaceStrDescriptor
  - USB\_DESC\_Private\_Functions, 42
- USB\_HS\_LangIDStrDescriptor
  - USB\_DESC\_Private\_Functions, 42
- USB\_HS\_ManufacturerStrDescriptor
  - USB\_DESC\_Private\_Functions, 43
- USB\_HS\_ProductStrDescriptor
  - USB\_DESC\_Private\_Functions, 43
- USB\_HS\_SerialStrDescriptor
  - USB\_DESC\_Private\_Functions, 44
- USB\_Interface\_fops\_FS
  - USB\_CDC\_IF\_Exported\_Variables, 15
  - USB\_CDC\_IF, 18
- USB\_Interface\_fops\_HS
  - USB\_CDC\_IF\_Exported\_Variables, 15
  - USB\_CDC\_IF, 19
- USB\_LL\_ClearStallEP
  - usb\_conf.c, 128
- USB\_LL\_CloseEP
  - usb\_conf.c, 129
- USB\_LL\_DelInit
  - usb\_conf.c, 129
- USB\_LL\_Delay
  - usb\_conf.c, 129
- USB\_LL\_FlushEP
  - usb\_conf.c, 130
- USB\_LL\_GetRxDataSize
  - usb\_conf.c, 130
- USB\_LL\_Init
  - usb\_conf.c, 130
- USB\_LL\_IsStallEP
  - usb\_conf.c, 131
- USB\_LL\_OpenEP
  - usb\_conf.c, 131
- USB\_LL\_PrepareReceive
  - usb\_conf.c, 132
- USB\_LL\_SetUSBAddress
  - usb\_conf.c, 132
- USB\_LL\_StallEP
  - usb\_conf.c, 132
- USB\_LL\_Start
  - usb\_conf.c, 133
- USB\_LL\_Stop
  - usb\_conf.c, 133
- USB\_LL\_Transmit
  - usb\_conf.c, 134
- USB\_OTG\_DRIVER, 63
- USB\_UsrLog
  - USB\_CONF\_Exported\_Macros, 29
- USB\_free
  - USB\_CONF\_Exported\_Macros, 29
- USB\_malloc
  - USB\_CONF\_Exported\_Macros, 29
- USB\_memcpy
  - USB\_CONF\_Exported\_Macros, 29
- USB\_memset
  - USB\_CONF\_Exported\_Macros, 29
- uart\_handle, 109
- Update
  - daisy::Led, 93
  - daisy::OledDisplay, 98
  - daisy::RgbLed, 101
- UsbPeriph
  - daisy::UsbHandle, 112
- usb\_conf.c
  - HAL\_PCD\_ConnectCallback, 122
  - HAL\_PCD\_DataInStageCallback, 123
  - HAL\_PCD\_DataOutStageCallback, 123
  - HAL\_PCD\_DisconnectCallback, 123
  - HAL\_PCD\_ISOINIncompleteCallback, 124
  - HAL\_PCD\_ISOOUTIncompleteCallback, 124
  - HAL\_PCD\_MspDelInit, 125
  - HAL\_PCD\_MspInit, 125
  - HAL\_PCD\_ResetCallback, 125
  - HAL\_PCD\_ResumeCallback, 125
  - HAL\_PCD\_SOFCallback, 127
  - HAL\_PCD\_SetupStageCallback, 127
  - HAL\_PCD\_SuspendCallback, 127
  - USB\_Get\_USB\_Status, 128
  - USB\_LL\_ClearStallEP, 128
  - USB\_LL\_CloseEP, 129
  - USB\_LL\_DelInit, 129
  - USB\_LL\_Delay, 129
  - USB\_LL\_FlushEP, 130
  - USB\_LL\_GetRxDataSize, 130
  - USB\_LL\_Init, 130
  - USB\_LL\_IsStallEP, 131
  - USB\_LL\_OpenEP, 131
  - USB\_LL\_PrepareReceive, 132
  - USB\_LL\_SetUSBAddress, 132
  - USB\_LL\_StallEP, 132
  - USB\_LL\_Start, 133



- USB\_D\_LL\_Stop, [133](#)
- USB\_D\_LL\_Transmit, [134](#)
- UserRxBufferFS
  - USB\_D\_CDC\_IF\_Private\_Variables, [14](#)
- UserRxBufferHS
  - USB\_D\_CDC\_IF\_Private\_Variables, [14](#)
- UserTxBufferFS
  - USB\_D\_CDC\_IF\_Private\_Variables, [14](#)
- UserTxBufferHS
  - USB\_D\_CDC\_IF\_Private\_Variables, [14](#)
- VECT\_TAB\_OFFSET
  - STM32H7xx\_System\_Private\_Defines, [56](#)
- Value
  - daisy::AnalogControl, [72](#)
  - daisy::Parameter, [100](#)
- WAV\_FormatTypeDef, [113](#)
- writable
  - daisy::RingBuffer, [103](#)
- Write
  - daisy::RingBuffer, [104](#)
  - ShiftRegister595, [106](#)
- WriteChar
  - daisy::OledDisplay, [98](#)
- WriteString
  - daisy::OledDisplay, [99](#)