libDaisy

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## **Chapter 1**

## libdaisy

Multi-layer hardware abstraction library for Daisy Product family

On STM32H7 MCUs

Lower-levels use STM32 HAL (local copy w/ modifications in Drivers/)

Prefixes and their meanings:

- sys System level configuration (clocks, dma, etc.)
- per Peripheral level, internal to MCU (i2c, spi, etc.)
- · dev External device support (external flash chips, DACs, codecs, etc.)
- hid User level interface elements (encoders, switches, audio, etc.)
- util library level elements used within the library (not included via daisy.h)
- daisy core API files (specific boards, platforms have extended user APIs that configure libdaisy more below).

Also included is a core/ folder containing:

- a generic Makefile that can be included in a project Makefile to simplify getting started
- · a linker script for defining the sections of memory used by the firmware
- core files for starting the hardware (system\_stm32h7xx.c, startup\_stm32h750xx.s, etc.)

## 1.1 Using libdaisy

Due to the amount of hardware configuration and flexibility of the daisy platform, (in the present, and the future), a user can use libdaisy to define their own custom hardware, or include one of our supported board files to jumpstart the creativity, and hack on an existing piece of hardware.

If you are getting started, and have one of the Daisy Family Products, you can skip ahead to that section below.

2 libdaisy

## 1.1.1 daisy.h

The base-level include file. This is all you need to include to create your own custom hardware that uses libdaisy.

daisy\_seed.h is an example of a board level file that utilizes libdaisy to define some hardware, and provide flexible access.

## 1.1.2 daisy\_seed.h

The SOM-level include file. This can be used with any boards that use the Daisy Seed hardware.

Additional configuration files, with more specific hardware access are provided below for our supported hardware platforms.

## 1.1.3 daisy\_platform.h

Several other pairs of files exist in the repo for each of the supported hardware platforms that work with Daisy Seed.

These are:

- · daisy\_field
- · daisy\_patch
- · daisy\_petal
- · daisy\_pod

With these files a number of additional initialization, and configuration is done by the library.

This allows a user to jump right into their new product with a simple api to do things without having a full understanding of what's going on under the hood.

With this flexible approach to the hardware configuration, we hope to promote a lot of fantastic hardware along with code to go with it.

# Chapter 2

# **Module Index**

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# **Chapter 3**

# **Class Index**

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Audio Driver	
Configures Audio Device and provides callback for signal processing.	
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# **Chapter 5**

# **Module Documentation**

## 5.1 LIBDAISY

The daisy library.

## **Modules**

• HUMAN\_INTERFACE

Interface with the world.

## 5.1.1 Detailed Description

The daisy library.

## 5.2 HUMAN\_INTERFACE

Interface with the world.

## Modules

• AUDIO

Embedded Audio Engine.

• CONTROLS

Hardware Controls.

## 5.2.1 Detailed Description

Interface with the world.

5.3 AUDIO 11

## 5.3 AUDIO

Embedded Audio Engine.

## **Files**

• file hid\_audio.h

Audio Driver Configures Audio Device and provides callback for signal processing. Many of the hard-coded values here will change (increase), and/or be replaced by configurable options.

## 5.3.1 Detailed Description

Embedded Audio Engine.

## 5.4 CONTROLS

Hardware Controls.

## **Files**

• file hid\_ctrl.h

## 5.4.1 Detailed Description

Hardware Controls.

5.5 USBD\_CDC\_IF

## 5.5 USBD\_CDC\_IF

Usb VCP device module.

### **Modules**

• USBD\_CDC\_IF\_Exported\_Defines

Defines.

• USBD\_CDC\_IF\_Exported\_Types

Types.

• USBD\_CDC\_IF\_Exported\_Macros

Aliases.

• USBD\_CDC\_IF\_Exported\_Variables

Public variables.

• USBD\_CDC\_IF\_Exported\_FunctionsPrototype

Public functions declaration.

## 5.5.1 Detailed Description

Usb VCP device module.

5.6 USBD CDC IF Exported	Defines	rted	Exporte	IF.	CDC	USBD	5.6
--------------------------	---------	------	---------	-----	-----	------	-----

Defines.

Defines.

## 5.7 USBD\_CDC\_IF\_Exported\_Types

Types.

## **Typedefs**

• typedef void(\* CDC\_ReceiveCallback) (uint8\_t \*buf, uint32\_t \*size)

## 5.7.1 Detailed Description

Types.

## 5.7.2 Typedef Documentation

## 5.7.2.1 CDC\_ReceiveCallback

typedef void(\* CDC\_ReceiveCallback) (uint8\_t \*buf, uint32\_t \*size)

### **Parameters**

buf	buffer
size	buffer size

## 5.8 USBD\_CDC\_IF\_Exported\_Macros

Aliases.

Aliases.

## 5.9 USBD\_CDC\_IF\_Exported\_Variables

Public variables.

### **Variables**

- USBD\_CDC\_ItfTypeDef USBD\_Interface\_fops\_FS
- USBD\_CDC\_ItfTypeDef USBD\_Interface\_fops\_HS

## 5.9.1 Detailed Description

Public variables.

## 5.9.2 Variable Documentation

#### 5.9.2.1 USBD\_Interface\_fops\_FS

USBD\_CDC\_ItfTypeDef USBD\_Interface\_fops\_FS

CDC Interface callback.

## 5.9.2.2 USBD\_Interface\_fops\_HS

USBD\_CDC\_ItfTypeDef USBD\_Interface\_fops\_HS

CDC Interface callback.

## 5.10 USBD\_CDC\_IF\_Exported\_FunctionsPrototype

Public functions declaration.

### **Functions**

```
• void CDC_Set_Rx_Callback_FS (CDC_ReceiveCallback cb)
```

- uint8\_t CDC\_Transmit\_FS (uint8\_t \*Buf, uint16\_t Len)
- uint8\_t CDC\_Transmit\_HS (uint8\_t \*Buf, uint16\_t Len)

## 5.10.1 Detailed Description

Public functions declaration.

### 5.10.2 Function Documentation

```
5.10.2.1 CDC_Set_Rx_Callback_FS()
```

&

### 5.10.2.2 CDC\_Transmit\_FS()

&

### 5.10.2.3 CDC\_Transmit\_HS()

&

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## 5.11 USBD\_CONF

Configuration file for Usb otg low level driver.

### **Modules**

• USBD\_CONF\_Exported\_Variables

Public variables.

• USBD\_CONF\_Exported\_Defines

Defines for configuration of the Usb device.

• USBD\_CONF\_Exported\_Macros

Aliases.

• USBD\_CONF\_Exported\_Types

Types.

• USBD\_CONF\_Exported\_FunctionsPrototype

Declaration of public functions for Usb device.

## 5.11.1 Detailed Description

Configuration file for Usb otg low level driver.

## 5.12 USBD\_CONF\_Exported\_Variables

Public variables.

Public variables.

## 5.13 USBD\_CONF\_Exported\_Defines

Defines for configuration of the Usb device.

#### **Macros**

- #define USBD\_MAX\_NUM\_INTERFACES 1U
- #define USBD\_MAX\_NUM\_CONFIGURATION 1U
- #define USBD\_MAX\_STR\_DESC\_SIZ 512U
- #define USBD\_SUPPORT\_USER\_STRING 0U
- #define USBD\_DEBUG\_LEVEL 3U
- #define USBD\_LPM\_ENABLED 0U
- #define USBD SELF POWERED 1U
- #define DEVICE\_FS 0
- #define DEVICE\_HS 1

## 5.13.1 Detailed Description

Defines for configuration of the Usb device.

### 5.13.2 Macro Definition Documentation

## 5.13.2.1 DEVICE\_FS

#define DEVICE\_FS 0

FS and HS identification

### 5.13.2.2 DEVICE\_HS

#define DEVICE\_HS 1

ጴ

### 5.13.2.3 USBD\_DEBUG\_LEVEL

#define USBD\_DEBUG\_LEVEL 3U

&

## 5.13.2.4 USBD\_LPM\_ENABLED

#define USBD\_LPM\_ENABLED 0U

8

## 5.13.2.5 USBD\_MAX\_NUM\_CONFIGURATION

#define USBD\_MAX\_NUM\_CONFIGURATION 1U

&

## 5.13.2.6 USBD\_MAX\_NUM\_INTERFACES

#define USBD\_MAX\_NUM\_INTERFACES 1U

R.

## 5.13.2.7 USBD\_MAX\_STR\_DESC\_SIZ

#define USBD\_MAX\_STR\_DESC\_SIZ 512U

&

## 5.13.2.8 USBD\_SELF\_POWERED

#define USBD\_SELF\_POWERED 1U

&

## 5.13.2.9 USBD\_SUPPORT\_USER\_STRING

 $\verb|#define USBD_SUPPORT_USER_STRING 0U|\\$ 

&

## 5.14 USBD\_CONF\_Exported\_Macros

Aliases.

#### **Macros**

- #define USBD\_malloc malloc
- #define USBD\_free free
- #define USBD\_memset memset
- #define USBD\_memcpy memcpy
- #define USBD\_Delay HAL\_Delay
- #define USBD\_UsrLog(...)
- #define USBD\_ErrLog(...)
- #define USBD\_DbgLog(...)

## 5.14.1 Detailed Description

Aliases.

### 5.14.2 Macro Definition Documentation

```
5.14.2.1 USBD_DbgLog
```

#### Value:

```
printf("DEBUG : "); \
   printf(__VA_ARGS__); \
   printf("\n");
```

&

## 5.14.2.2 USBD\_Delay

#define USBD\_Delay HAL\_Delay

Alias for delay.

```
5.14.2.3 USBD_ErrLog
```

Value:

```
printf("ERROR: "); \
   printf(__VA_ARGS__); \
   printf("\n");
```

&

### 5.14.2.4 USBD\_free

```
#define USBD_free free
```

Alias for memory release.

#### 5.14.2.5 USBD\_malloc

```
#define USBD_malloc malloc
```

Alias for memory allocation.

## 5.14.2.6 USBD\_memcpy

```
#define USBD_memcpy memcpy
```

Alias for memory copy.

## 5.14.2.7 USBD\_memset

```
#define USBD_memset memset
```

Alias for memory set.

### 5.14.2.8 USBD\_UsrLog

### Value:

```
\begin{array}{c} \text{printf}(\underline{\hspace{0.1cm}} \text{VA\_ARGS}\underline{\hspace{0.1cm}}); \ \backslash \\ \text{printf}("\n"); \end{array}
```

&

## 5.15 USBD\_CONF\_Exported\_Types

Types.

Types.

## 5.16 USBD\_CONF\_Exported\_FunctionsPrototype

Declaration of public functions for Usb device.

Declaration of public functions for Usb device.

5.17 USBD\_DESC 27

## 5.17 USBD\_DESC

Usb device descriptors module.

### **Modules**

• USBD\_DESC\_Exported\_Constants

Constants.

• USBD\_DESC\_Exported\_Defines

Defines.

• USBD\_DESC\_Exported\_TypesDefinitions

Types.

• USBD\_DESC\_Exported\_Macros

Aliases.

• USBD\_DESC\_Exported\_Variables

Public variables.

• USBD\_DESC\_Exported\_FunctionsPrototype

Public functions declaration.

## 5.17.1 Detailed Description

Usb device descriptors module.

## 5.18 USBD\_DESC\_Exported\_Constants

Constants.

#### **Macros**

```
• #define DEVICE_ID1 (UID_BASE)
```

- #define DEVICE\_ID2 (UID\_BASE + 0x4)
- #define DEVICE\_ID3 (UID\_BASE + 0x8)
- #define USB\_SIZ\_STRING\_SERIAL 0x1A

## 5.18.1 Detailed Description

Constants.

## 5.18.2 Macro Definition Documentation

```
5.18.2.1 DEVICE_ID1
```

```
#define DEVICE_ID1 (UID_BASE)
```

&

## 5.18.2.2 **DEVICE\_ID2**

```
#define DEVICE_ID2 (UID_BASE + 0x4)
```

&

#### 5.18.2.3 DEVICE\_ID3

```
#define DEVICE_ID3 (UID_BASE + 0x8)
```

&

## 5.18.2.4 USB\_SIZ\_STRING\_SERIAL

#define USB\_SIZ\_STRING\_SERIAL 0x1A

&

## 5.19 USBD\_DESC\_Exported\_Defines

Defines.

Defines.

5.20 USBD DESC Exported Types	Definitions	nitions
-------------------------------	-------------	---------

Types.

Types.

# 5.21 USBD\_DESC\_Exported\_Macros

Aliases.

Aliases.

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# 5.22 USBD\_DESC\_Exported\_Variables

Public variables.

## **Variables**

- USBD\_DescriptorsTypeDef HS\_Desc
- USBD\_DescriptorsTypeDef FS\_Desc

# 5.22.1 Detailed Description

Public variables.

# 5.22.2 Variable Documentation

5.22.2.1 FS\_Desc

USBD\_DescriptorsTypeDef FS\_Desc

Descriptor for the Usb device.

5.22.2.2 HS\_Desc

USBD\_DescriptorsTypeDef HS\_Desc

Descriptor for the Usb device.

# 5.23 USBD\_DESC\_Exported\_FunctionsPrototype

Public functions declaration.

Public functions declaration.

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# 5.24 STM32\_USB\_OTG\_DEVICE\_LIBRARY

For Usb device.

# **Modules**

- USBD\_CDC\_IF
  - Usb VCP device module.
- USBD\_DESC

Usb device descriptors module.

# 5.24.1 Detailed Description

For Usb device.

< Define to prevent recursive inclusion -----

# 5.25 USBD\_OTG\_DRIVER

# Modules

• USBD\_CONF

Configuration file for Usb otg low level driver.

# 5.25.1 Detailed Description

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# **Chapter 6**

# **Class Documentation**

# 6.1 daisy::AdcChannelConfig Struct Reference

```
#include <per_adc.h>
```

# **Public Types**

enum MuxPin { MUX\_SEL\_0, MUX\_SEL\_1, MUX\_SEL\_2, MUX\_SEL\_LAST }

## **Public Member Functions**

- void InitSingle (dsy\_gpio\_pin pin)
- void InitMux (dsy\_gpio\_pin adc\_pin, dsy\_gpio\_pin mux\_0, dsy\_gpio\_pin mux\_1, dsy\_gpio\_pin mux\_2, size
   \_t channels)

# **Public Attributes**

- dsy\_gpio pin\_
- dsy\_gpio mux\_pin\_ [MUX\_SEL\_LAST]
- uint8\_t mux\_channels\_

# 6.1.1 Detailed Description

Configuration Structure for a given channel

# 6.1.2 Member Enumeration Documentation

#### 6.1.2.1 MuxPin

enum daisy::AdcChannelConfig::MuxPin

Which pin to use for multiplexing

# Enumerator

MUX_SEL_0	&
MUX_SEL_1	&
MUX_SEL_2	&
MUX_SEL_LAST	&

#### 6.1.3 Member Function Documentation

#### 6.1.3.1 InitMux()

Initializes a single ADC pin as a Multiplexed ADC. Requires a CD4051 Multiplexor connected to the pin Internal Callbacks handle the pin addressing.

### **Parameters**

channels	must be 1-8
mux_0	First mux pin
mux_1	Second mux pin
mux_2	Third mux pin
adc_pin	&

## 6.1.3.2 InitSingle()

Initializes a single ADC pin as an ADC.

## **Parameters**

pin	Pin to init.

## 6.1.4 Member Data Documentation

```
6.1.4.1 mux_channels_
uint8_t daisy::AdcChannelConfig::mux_channels_
&
6.1.4.2 mux_pin_
dsy_gpio daisy::AdcChannelConfig::mux_pin_[MUX_SEL_LAST]
&
6.1.4.3 pin_
dsy_gpio daisy::AdcChannelConfig::pin_
```

The documentation for this struct was generated from the following file:

• src/per\_adc.h

# 6.2 daisy::AdcHandle Class Reference

```
#include <per_adc.h>
```

# **Public Types**

```
    enum OverSampling {
        OVS_NONE, OVS_4, OVS_8, OVS_16,
        OVS_32, OVS_64, OVS_128, OVS_256,
        OVS_512, OVS_1024, OVS_LAST }
```

#### **Public Member Functions**

```
• void Init (AdcChannelConfig *cfg, size_t num_channels, OverSampling ovs=OVS_32)
```

- void Start ()
- void Stop ()
- uint16\_t Get (uint8\_t chn)
- uint16\_t \* GetPtr (uint8\_t chn)
- float GetFloat (uint8\_t chn)
- uint16\_t GetMux (uint8\_t chn, uint8\_t idx)
- uint16\_t \* GetMuxPtr (uint8\_t chn, uint8\_t idx)
- float GetMuxFloat (uint8\_t chn, uint8\_t idx)

# 6.2.1 Detailed Description

Handler for analog to digital conversion

# 6.2.2 Member Enumeration Documentation

# 6.2.2.1 OverSampling

```
enum daisy::AdcHandle::OverSampling
```

Supported oversampling amounts

#### Enumerator

OVS_NONE	&
OVS_4	&
OVS_8	&
OVS_16	&
OVS_32	&
OVS_64	&
OVS_128	&
OVS_256	&
OVS_512	&
OVS_1024	&
OVS_LAST	&

# 6.2.3 Member Function Documentation

# 6.2.3.1 Get()

Single channel getter

# **Parameters**

chn	channel to get

#### Returns

Converted value

# 6.2.3.2 GetFloat()

```
float daisy::AdcHandle::GetFloat ( \label{eq:condition} \mbox{uint8\_t } chn \ )
```

Get floating point from single channel

#### **Parameters**

```
chn Channel to get from
```

## Returns

Floating point converted value

# 6.2.3.3 GetMux()

Getters for multiplexed inputs on a single channel (up to 8 per ADC input).

#### **Parameters**

chn	Channel to get from
idx	&

## Returns

data

#### 6.2.3.4 GetMuxFloat()

Getters for multiplexed inputs on a single channel (up to 8 per ADC input).

## **Parameters**

chn	Channel to get from
idx	&

# Returns

Floating point data

# 6.2.3.5 GetMuxPtr()

Getters for multiplexed inputs on a single channel. (Max 8 per chan)

## **Parameters**

chn	Channel to get from
idx	&

# Returns

Pointer to data

## 6.2.3.6 GetPtr()

Get pointer to a value from a single channel

# **Parameters**

chn

#### **Returns**

Pointer to converted value

#### 6.2.3.7 Init()

```
void daisy::AdcHandle::Init (
         AdcChannelConfig * cfg,
         size_t num_channels,
         OverSampling ovs = OVS_32 )
```

Initializes the ADC with the pins passed in.

#### **Parameters**

*cfg	an array of AdcChannelConfig of the desired channel
num_channels	number of ADC channels to initialize
ovs	Oversampling amount - Defaults to OVS_32

#### 6.2.3.8 Start()

```
void daisy::AdcHandle::Start ( )
```

Starts reading from the ADC

#### 6.2.3.9 Stop()

```
void daisy::AdcHandle::Stop ( )
```

# Stops reading from the ADC

The documentation for this class was generated from the following file:

• src/per\_adc.h

# 6.3 daisy::AnalogControl Class Reference

Hardware Interface for control inputs Primarily designed for ADC input controls such as potentiometers, and control voltage.

#include <hid\_ctrl.h>

#### **Public Member Functions**

- AnalogControl ()
- ∼AnalogControl ()
- void Init (uint16\_t \*adcptr, float sr, bool flip=false, bool invert=false, float slew\_seconds=0.002f)
- void InitBipolarCv (uint16\_t \*adcptr, float sr)
- float Process ()
- float Value () const

# 6.3.1 Detailed Description

Hardware Interface for control inputs Primarily designed for ADC input controls such as potentiometers, and control voltage.

.

**Author** 

Stephen Hensley

Date

November 2019

## 6.3.2 Constructor & Destructor Documentation

```
6.3.2.1 AnalogControl()
```

```
daisy::AnalogControl::AnalogControl ( ) [inline]
```

Constructor

# 6.3.2.2 $\sim$ AnalogControl()

```
daisy::AnalogControl::~AnalogControl ( ) [inline]
```

destructor

# 6.3.3 Member Function Documentation

## 6.3.3.1 Init()

Initializes the control

#### **Parameters**

*adcptr	is a pointer to the raw adc read value – This can be acquired with dsy_adc_get_rawptr(), or dsy_adc_get_mux_rawptr()
sr	is the samplerate in Hz that the Process function will be called at.
flip	determines whether the input is flipped (i.e. 1.f - input) or not before being processed.1
invert	determines whether the input is inverted (i.e1.f * input) or note before being processed.
slew_seconds	is the slew time in seconds that it takes for the control to change to a new value.

## 6.3.3.2 InitBipolarCv()

```
void daisy::AnalogControl::InitBipolarCv (  \mbox{uint16\_t} \ * \ adcptr,   \mbox{float} \ sr \ )
```

This Initializes the AnalogControl for a -5V to 5V inverted input All of the Init details are the same otherwise

#### **Parameters**

*adcptr	Pointer to analog digital converter
sr	Audio engine sample rate

#### 6.3.3.3 Process()

```
float daisy::AnalogControl::Process ( )
```

Filters, and transforms a raw ADC read into a normalized range. this should be called at the rate of specified by samplerate at Init time. Default Initializations will return 0.0 -> 1.0 Bi-polar CV inputs will return -1.0 -> 1.0

#### 6.3.3.4 Value()

```
float daisy::AnalogControl::Value ( ) const [inline]
```

Returns the current stored value, without reprocessing

The documentation for this class was generated from the following file:

• src/hid\_ctrl.h

# 6.4 codec\_frame\_t Struct Reference

```
#include <dev_codec_wm8731_frame.h>
```

# **Public Attributes**

- short I
- short r

# 6.4.1 Detailed Description

&

# 6.4.2 Member Data Documentation

The documentation for this struct was generated from the following file:

• src/dev\_codec\_wm8731\_frame.h

# 6.5 color Struct Reference

```
#include <dev_leddriver.h>
```

# **Public Attributes**

- uint16\_t red
- uint16\_t green
- uint16\_t blue

# 6.5.1 Detailed Description

Simple color struct Different from util\_color only in type (0-4095 vs 0-1) This could easily be migrated to work with those instead.

# 6.5.2 Member Data Documentation

```
6.5.2.1 blue

uint16_t color::blue

&

6.5.2.2 green

uint16_t color::green

&

6.5.2.3 red

uint16_t color::red

&
```

The documentation for this struct was generated from the following file:

• src/dev\_leddriver.h

# 6.6 daisy::Color Class Reference

```
#include <util_color.h>
```

# **Public Types**

enum PresetColor {
 RED, GREEN, BLUE, WHITE,
 PURPLE, CYAN, GOLD, OFF,
 LAST }

# **Public Member Functions**

- void Init (PresetColor c)
- void Init (float red, float green, float blue)
- float Red () const
- float Green () const
- float Blue () const

# 6.6.1 Detailed Description

Class for handling simple colors

## 6.6.2 Member Enumeration Documentation

# 6.6.2.1 PresetColor

```
enum daisy::Color::PresetColor
```

List of colors that have a preset RGB value

#### Enumerator

RED	&
GREEN	&
BLUE	&
WHITE	&
PURPLE	&
CYAN	&
GOLD	&
OFF	&
LAST	&

# 6.6.3 Member Function Documentation

```
6.6.3.1 Blue()
```

```
float daisy::Color::Blue ( ) const [inline]
```

Returns the 0-1 value for Blue

# 6.6.3.2 Green()

```
float daisy::Color::Green ( ) const [inline]
```

Returns the 0-1 value for Green

```
6.6.3.3 Init() [1/2]
```

Initializes the Color with a given preset.

#### **Parameters**

```
c Color to init to
```

Initializes the Color with a specific RGB value red, green, and blue should be floats between 0 and 1

#### **Parameters**

red	Red value
green	Green value
blue	Blue value

# 6.6.3.5 Red()

```
float daisy::Color::Red ( ) const [inline]
```

Returns the 0-1 value for Red

The documentation for this class was generated from the following file:

• src/util\_color.h

# 6.7 daisy::ControlChangeEvent Struct Reference

```
#include <hid_midi.h>
```

#### **Public Attributes**

- int channel
- uint8\_t control\_number
- uint8\_t value

# 6.7.1 Detailed Description

Struct containing control number, and value for a given channel. Can be made from MidiEvent

# 6.7.2 Member Data Documentation

# 6.7.2.1 channel int daisy::ControlChangeEvent::channel & 6.7.2.2 control\_number

uint8\_t daisy::ControlChangeEvent::control\_number

&

## 6.7.2.3 value

uint8\_t daisy::ControlChangeEvent::value

ጴ

The documentation for this struct was generated from the following file:

src/hid\_midi.h

# 6.8 daisy::daisy\_field Struct Reference

```
#include <daisy_field.h>
```

# **Public Attributes**

- daisy::DaisySeed seed
- daisy::Switch switches [SW\_LAST]
- dsy\_gpio gate\_in
- dsy\_gpio gate\_out
- dsy\_sr\_4021\_handle keyboard\_sr
- AnalogControl knobs [KNOB\_LAST]
- AnalogControl cvs [CV\_LAST]

# 6.8.1 Detailed Description

Struct containing hardware defines and daisy seed

## 6.8.2 Member Data Documentation

```
6.8.2.1 cvs
AnalogControl daisy::daisy_field::cvs[CV_LAST]
Array of cv ins
6.8.2.2 gate_in
dsy_gpio daisy::daisy_field::gate_in
Gate input.
6.8.2.3 gate_out
dsy_gpio daisy::daisy_field::gate_out
Gate output
6.8.2.4 keyboard_sr
dsy_sr_4021_handle daisy::daisy_field::keyboard_sr
Keyboard shift register
6.8.2.5 knobs
AnalogControl daisy::daisy_field::knobs[KNOB_LAST]
Array of hardware knobs
6.8.2.6 seed
daisy::DaisySeed daisy::daisy_field::seed
Daisy seed
6.8.2.7 switches
daisy::Switch daisy::daisy_field::switches[SW_LAST]
Array of hardware switches
```

The documentation for this struct was generated from the following file:

• src/daisy\_field.h

# 6.9 daisy::DaisyPatch Class Reference

Class that handles initializing all of the hardware specific to the Daisy Patch Board. Helper funtions are also in place to provide easy access to built-in controls and peripherals.

```
#include <daisy_patch.h>
```

# **Public Types**

```
    enum Ctrl {
        CTRL_1, CTRL_2, CTRL_3, CTRL_4,
        CTRL_LAST }
    enum GateInput { GATE_IN_1, GATE_IN_2, GATE_IN_LAST }
```

#### **Public Member Functions**

```
• DaisyPatch ()
```

- ∼DaisyPatch ()
- void Init ()
- void DelayMs (size\_t del)
- void SetAudioBlockSize (size\_t size)
- void StartAudio (dsy\_audio\_mc\_callback cb)
- void ChangeAudioCallback (dsy audio callback cb)
- void StartAdc ()
- float AudioSampleRate ()
- size\_t AudioBlockSize ()
- float AudioCallbackRate ()
- void UpdateAnalogControls ()
- float GetCtrlValue (Ctrl k)
- · void DebounceControls ()
- void DisplayControls (bool invert=true)

# **Public Attributes**

- · DaisySeed seed
- · Encoder encoder
- AnalogControl controls [CTRL\_LAST]
- GateIn gate\_input [GATE\_IN\_LAST]
- · MidiHandler midi
- · OledDisplay display
- dsy\_gpio gate\_output

## 6.9.1 Detailed Description

Class that handles initializing all of the hardware specific to the Daisy Patch Board. Helper funtions are also in place to provide easy access to built-in controls and peripherals.

#### Author

Stephen Hensley

Date

November 2019

## 6.9.2 Member Enumeration Documentation

```
6.9.2.1 Ctrl
```

```
enum daisy::DaisyPatch::Ctrl
```

Enum of Ctrls to represent the four CV/Knob combos on the Patch

## 6.9.2.2 GateInput

```
enum daisy::DaisyPatch::GateInput
```

Daisy patch gate inputs

Enumerator

```
GATE_IN_LAST <
```

## 6.9.3 Constructor & Destructor Documentation

## 6.9.3.1 DaisyPatch()

```
daisy::DaisyPatch::DaisyPatch ( ) [inline]
```

Constructor

# 6.9.3.2 $\sim$ DaisyPatch()

```
daisy::DaisyPatch::~DaisyPatch ( ) [inline]
```

Destructor

# 6.9.4 Member Function Documentation

# 6.9.4.1 AudioBlockSize()

```
size_t daisy::DaisyPatch::AudioBlockSize ( )
```

Get block size

#### 6.9.4.2 AudioCallbackRate()

```
float daisy::DaisyPatch::AudioCallbackRate ( )
```

Get callback rate

## 6.9.4.3 AudioSampleRate()

```
float daisy::DaisyPatch::AudioSampleRate ( )
```

Get sample rate

## 6.9.4.4 ChangeAudioCallback()

```
void daisy::DaisyPatch::ChangeAudioCallback ( {\tt dsy\_audio\_callback}\ cb\ )
```

Change to a different callback function.

#### **Parameters**

cb New callback function.

## 6.9.4.5 DebounceControls()

```
void daisy::DaisyPatch::DebounceControls ( )
```

Debounce analog controls. Call at same rate as reading controls.

# 6.9.4.6 DelayMs()

Wait some ms before going on.

## **Parameters**

```
del Delay time in ms.
```

## 6.9.4.7 DisplayControls()

```
void daisy::DaisyPatch::DisplayControls (
```

```
bool invert = true )
```

Control the display

## 6.9.4.8 GetCtrlValue()

Get value for a partiular control

#### **Parameters**

```
k Which control to get
```

## 6.9.4.9 Init()

```
void daisy::DaisyPatch::Init ( )
```

Initializes the daisy seed, and patch hardware.

#### 6.9.4.10 SetAudioBlockSize()

Audio Block size defaults to 48. Change it using this function before StartingAudio

# **Parameters**

```
size Audio block size.
```

#### 6.9.4.11 StartAdc()

```
void daisy::DaisyPatch::StartAdc ( )
```

Start analog to digital conversion.

## 6.9.4.12 StartAudio()

Start audio output.

#### **Parameters**

cb Audio callback function

```
6.9.4.13 UpdateAnalogControls()
```

```
void daisy::DaisyPatch::UpdateAnalogControls ( )
```

Call at same rate as reading controls for good reads.

#### 6.9.5 Member Data Documentation

```
6.9.5.1 controls
```

```
AnalogControl daisy::DaisyPatch::controls[CTRL_LAST]
```

Array of controls

## 6.9.5.2 display

```
OledDisplay daisy::DaisyPatch::display
```

&

# 6.9.5.3 encoder

```
Encoder daisy::DaisyPatch::encoder
```

**Encoder** object

# 6.9.5.4 gate\_input

```
GateIn daisy::DaisyPatch::gate_input[GATE_IN_LAST]
```

Gate inputs

# 6.9.5.5 gate\_output

```
dsy_gpio daisy::DaisyPatch::gate_output
```

&

```
6.9.5.6 midi
MidiHandler daisy::DaisyPatch::midi
Handles midi
6.9.5.7 seed
```

DaisySeed daisy::DaisyPatch::seed

Seed object

The documentation for this class was generated from the following file:

· src/daisy\_patch.h

# 6.10 daisy::DaisyPetal Class Reference

Helpers and hardware definitions for daisy petal.

```
#include <daisy_petal.h>
```

# **Public Types**

```
enum Sw {
    SW_1, SW_2, SW_3, SW_4,
    SW_5, SW_6, SW_7, SW_LAST }
enum Knob {
    KNOB_1, KNOB_2, KNOB_3, KNOB_4,
    KNOB_5, KNOB_6, KNOB_LAST }
enum RingLed {
    RING_LED_1, RING_LED_2, RING_LED_3, RING_LED_4,
    RING_LED_5, RING_LED_6, RING_LED_7, RING_LED_8,
    RING_LED_LAST }
enum FootswitchLed {
    FOOTSWITCH_LED_1, FOOTSWITCH_LED_2, FOOTSWITCH_LED_3, FOOTSWITCH_LED_4,
    FOOTSWITCH_LED_LAST }
```

#### **Public Member Functions**

- · DaisyPetal ()
- $\sim$ DaisyPetal ()
- void Init ()
- void DelayMs (size\_t del)
- void SetAudioBlockSize (size\_t size)
- void StartAudio (dsy\_audio\_callback cb)
- void ChangeAudioCallback (dsy\_audio\_callback cb)
- void StartAdc ()
- float AudioSampleRate ()
- size\_t AudioBlockSize ()
- float AudioCallbackRate ()
- void UpdateAnalogControls ()
- float GetKnobValue (Knob k)
- float GetExpression ()
- void DebounceControls ()
- void ClearLeds ()
- void UpdateLeds ()
- void SetRingLed (RingLed idx, float r, float g, float b)
- void SetFootswitchLed (FootswitchLed idx, float bright)

# **Public Attributes**

- DaisySeed seed
- · Encoder encoder
- AnalogControl knob [KNOB\_LAST]
- AnalogControl expression
- Switch switches [SW\_LAST]
- RgbLed ring\_led [8]
- Led footswitch\_led [4]

# 6.10.1 Detailed Description

Helpers and hardware definitions for daisy petal.

## 6.10.2 Member Enumeration Documentation

#### 6.10.2.1 FootswitchLed

enum daisy::DaisyPetal::FootswitchLed

## footswitch leds

#### Enumerator

FOOTSWITCH_LED_1	&
FOOTSWITCH_LED_2	&
FOOTSWITCH_LED_3	&
FOOTSWITCH_LED_4	&
FOOTSWITCH_LED_LAST	&

#### 6.10.2.2 Knob

enum daisy::DaisyPetal::Knob

#### Knobs

# Enumerator

KNOB_1	&
KNOB_2	&
KNOB_3	&
KNOB_4	&
KNOB_5	&
KNOB_6	&
KNOR LAST	- χ.

# 6.10.2.3 RingLed

enum daisy::DaisyPetal::RingLed

# Leds in ringled

# Enumerator

RING_LED_1	&
RING_LED_2	&
RING_LED_3	&
RING_LED_4	&
RING_LED_5	&
RING_LED_6	&
RING_LED_7	&
RING_LED_8	&
RING_LED_LAST	&

## 6.10.2.4 Sw

enum daisy::DaisyPetal::Sw

# Switches

## Enumerator

SW_1	Footswitch
SW_2	Footswitch
SW_3	Footswitch
SW_4	Footswitch
SW_5	Toggle
SW_6	Toggle
SW_7	Toggle
SW_LAST	Last enum item

## 6.10.3 Constructor & Destructor Documentation

# 6.10.3.1 DaisyPetal()

daisy::DaisyPetal::DaisyPetal ( ) [inline]

# Constructor

```
6.10.3.2 \sim DaisyPetal()
daisy::DaisyPetal::~DaisyPetal ( ) [inline]
Destructor
6.10.4 Member Function Documentation
6.10.4.1 AudioBlockSize()
size_t daisy::DaisyPetal::AudioBlockSize ( )
Get audio block size
6.10.4.2 AudioCallbackRate()
float daisy::DaisyPetal::AudioCallbackRate ( )
Get callback rate
6.10.4.3 AudioSampleRate()
float daisy::DaisyPetal::AudioSampleRate ( )
Device audio sample rate.
6.10.4.4 ChangeAudioCallback()
void daisy::DaisyPetal::ChangeAudioCallback (
              dsy_audio_callback cb )
Change callback function
Parameters
 cb | New callback function.
6.10.4.5 ClearLeds()
void daisy::DaisyPetal::ClearLeds ( )
```

Turn all leds off

## 6.10.4.6 DebounceControls()

```
void daisy::DaisyPetal::DebounceControls ( )
```

Debounce inputs.

# 6.10.4.7 DelayMs()

Wait before moving on.

#### **Parameters**

```
del Delay time in ms.
```

## 6.10.4.8 GetExpression()

```
float daisy::DaisyPetal::GetExpression ( )
```

&

# 6.10.4.9 GetKnobValue()

Get value per knob.

# **Parameters**

```
k Which knob to get
```

# Returns

Floating point knob position.

## 6.10.4.10 Init()

```
void daisy::DaisyPetal::Init ( )
```

# Initialize daisy petal

# 6.10.4.11 SetAudioBlockSize()

```
void daisy::DaisyPetal::SetAudioBlockSize ( {\tt size\_t \ size} \ )
```

Set size of audio blocks.

# **Parameters**

```
size Audio block size
```

#### 6.10.4.12 SetFootswitchLed()

Set footswitch LED

## **Parameters**

idx	Led Index
bright	Brightness

## 6.10.4.13 SetRingLed()

```
void daisy::DaisyPetal::SetRingLed (
    RingLed idx,
    float r,
    float g,
    float b)
```

Set ring LED colors

# **Parameters**

idx	Index to set
r	Red value
g	Green value
b	Blue value

```
6.10.4.14 StartAdc()
void daisy::DaisyPetal::StartAdc ( )
Start analog to digital conversion.
6.10.4.15 StartAudio()
void daisy::DaisyPetal::StartAudio (
              dsy_audio_callback cb )
Start audio callback
Parameters
 cb Callback function.
6.10.4.16 UpdateAnalogControls()
void daisy::DaisyPetal::UpdateAnalogControls ( )
Call at the same frequency as controls are read for stable readings.
6.10.4.17 UpdateLeds()
void daisy::DaisyPetal::UpdateLeds ( )
Update Leds to values you had set.
6.10.5 Member Data Documentation
6.10.5.1 encoder
Encoder daisy::DaisyPetal::encoder
&
6.10.5.2 expression
```

&

AnalogControl daisy::DaisyPetal::expression

```
6.10.5.3 footswitch_led
Led daisy::DaisyPetal::footswitch_led[4]
6.10.5.4 knob
AnalogControl daisy::DaisyPetal::knob[KNOB_LAST]
&
6.10.5.5 ring_led
RgbLed daisy::DaisyPetal::ring_led[8]
&
6.10.5.6 seed
DaisySeed daisy::DaisyPetal::seed
6.10.5.7 switches
Switch daisy::DaisyPetal::switches[SW_LAST]
< &
```

The documentation for this class was generated from the following file:

• src/daisy\_petal.h

# 6.11 daisy::DaisyPod Class Reference

Class that handles initializing all of the hardware specific to the Daisy Patch Board. Helper funtions are also in place to provide easy access to built-in controls and peripherals.

```
#include <daisy_pod.h>
```

# **Public Types**

```
• enum Sw { BUTTON_1, BUTTON_2, BUTTON_LAST }
```

enum Knob { KNOB\_1, KNOB\_2, KNOB\_LAST }

#### **Public Member Functions**

- void Init ()
- void DelayMs (size\_t del)
- void SetAudioBlockSize (size\_t size)
- void StartAudio (dsy\_audio\_callback cb)
- void ChangeAudioCallback (dsy audio callback cb)
- void StartAdc ()
- float AudioSampleRate ()
- size\_t AudioBlockSize ()
- float AudioCallbackRate ()
- void UpdateAnalogControls ()
- float GetKnobValue (Knob k)
- void DebounceControls ()
- void ClearLeds ()
- void UpdateLeds ()

#### **Public Attributes**

- · DaisySeed seed
- · Encoder encoder
- · AnalogControl knob1
- AnalogControl knob2
- AnalogControl \* knobs [KNOB\_LAST]
- Switch button1
- Switch button2
- Switch \* buttons [BUTTON\_LAST]
- · RgbLed led1
- RgbLed led2

# 6.11.1 Detailed Description

Class that handles initializing all of the hardware specific to the Daisy Patch Board. Helper funtions are also in place to provide easy access to built-in controls and peripherals.

**Author** 

Stephen Hensley

Date

November 2019

# 6.11.2 Member Enumeration Documentation

6.11.2.1 Knob

enum daisy::DaisyPod::Knob

Knobs

## Enumerator

KNOB_2	&
KNOB_LAST	&

6.11.2.2 Sw

enum daisy::DaisyPod::Sw

Switches

Enumerator

BUTTON_2	&
BUTTON_LAST	&

## 6.11.3 Member Function Documentation

```
6.11.3.1 AudioBlockSize()
```

```
size_t daisy::DaisyPod::AudioBlockSize ( )
```

Get block size

## 6.11.3.2 AudioCallbackRate()

```
float daisy::DaisyPod::AudioCallbackRate ( )
```

Get callback rate

# 6.11.3.3 AudioSampleRate()

```
float daisy::DaisyPod::AudioSampleRate ( )
```

Get sample rate

# 6.11.3.4 ChangeAudioCallback()

Switch callback functions

```
Parameters
```

```
cb New callback function.
```

#### 6.11.3.8 GetKnobValue()

del Time to wait in ms.

**Parameters** 

Audio Block size defaults to 48. Change it using this function before StartingAudio.

#### **Parameters**

```
size Block size to set.
```

```
6.11.3.11 StartAdc()
```

```
void daisy::DaisyPod::StartAdc ( )
```

Start analog to digital conversion.

## 6.11.3.12 StartAudio()

Start audio callback

#### **Parameters**

cb Callback function.

## 6.11.3.13 UpdateAnalogControls()

```
void daisy::DaisyPod::UpdateAnalogControls ( )
```

Call at same rate as analog reads for smooth reading.

## 6.11.3.14 UpdateLeds()

```
void daisy::DaisyPod::UpdateLeds ( )
```

Update Leds to set colors

#### 6.11.4 Member Data Documentation

## 6.11.4.1 button1

```
Switch daisy::DaisyPod::button1
```

&

```
6.11.4.2 button2
Switch daisy::DaisyPod::button2
&
6.11.4.3 buttons
Switch * daisy::DaisyPod::buttons[BUTTON_LAST]
6.11.4.4 encoder
Encoder daisy::DaisyPod::encoder
&
6.11.4.5 knob1
AnalogControl daisy::DaisyPod::knob1
6.11.4.6 knob2
AnalogControl daisy::DaisyPod::knob2
&
6.11.4.7 knobs
AnalogControl * daisy::DaisyPod::knobs[KNOB_LAST]
&
6.11.4.8 led1
RgbLed daisy::DaisyPod::led1
&
6.11.4.9 led2
RgbLed daisy::DaisyPod::led2
&
```

#### 6.11.4.10 seed

DaisySeed daisy::DaisyPod::seed

#### Public Members #

The documentation for this class was generated from the following file:

• src/daisy\_pod.h

## 6.12 daisy::DaisySeed Class Reference

This is the higher-level interface for the Daisy board.

All basic peripheral configuration/initialization is setup here.

```
#include <daisy_seed.h>
```

#### **Public Member Functions**

- void Configure ()
- void Init ()
- dsy\_gpio\_pin GetPin (uint8\_t pin\_idx)
- void StartAudio (dsy\_audio\_callback cb)
- void SetLed (bool state)
- void SetTestPoint (bool state)
- float AudioSampleRate ()
- void SetAudioBlockSize (size\_t blocksize)

## **Public Attributes**

- · dsy\_sdram\_handle sdram\_handle
- dsy\_qspi\_handle qspi\_handle
- dsy\_audio\_handle audio\_handle
- dsy\_sai\_handle sai\_handle
- dsy\_i2c\_handle i2c1\_handle
- dsy\_i2c\_handle i2c2\_handle
- · AdcHandle adc
- · dsy dac handle dac handle
- UsbHandle usb\_handle

## 6.12.1 Detailed Description

This is the higher-level interface for the Daisy board.
All basic peripheral configuration/initialization is setup here.

#### 6.12.2 Member Function Documentation

#### 6.12.2.1 AudioSampleRate()

```
float daisy::DaisySeed::AudioSampleRate ( )
```

Returns the audio sample rate in Hz as a floating point number.

#### 6.12.2.2 Configure()

```
void daisy::DaisySeed::Configure ( )
```

Configures the settings for all internal peripherals, but does not initialize them. This allows for modification of the configuration handles prior to initialization.&

#### 6.12.2.3 GetPin()

Returns the gpio\_pin corresponding to the index 0-31. For the given GPIO on the Daisy Seed (labeled 1-32 in docs).

#### 6.12.2.4 Init()

```
void daisy::DaisySeed::Init ( )
```

Initializes the Daisy Seed and the following peripherals: SDRAM, QSPI, 24-bit 48kHz Audio via AK4556, Internal USB, as well as the built-in LED and Testpoint.

ADCs, DACs, and other special peripherals (such as I2C, SPI, etc.) can be initialized using their specific initializers within libdaisy for a specific application.

#### 6.12.2.5 SetAudioBlockSize()

Sets the number of samples processed per channel by the audio callback.

#### 6.12.2.6 SetLed()

Sets the state of the built in LED

## 6.12.2.7 SetTestPoint()

Sets the state of the test point near pin 10

#### 6.12.2.8 StartAudio()

Begins the audio for the seeds builtin audio. the specified callback will get called whenever new data is ready to be prepared.

## 6.12.3 Member Data Documentation

```
6.12.3.1 adc
```

AdcHandle daisy::DaisySeed::adc

&

## 6.12.3.2 audio\_handle

```
dsy_audio_handle daisy::DaisySeed::audio_handle
```

&

## 6.12.3.3 dac\_handle

```
dsy_dac_handle daisy::DaisySeed::dac_handle
```

&

## 6.12.3.4 i2c1\_handle

```
dsy_i2c_handle daisy::DaisySeed::i2c1_handle
```

&

```
6.12.3.5 i2c2_handle
dsy_i2c_handle daisy::DaisySeed::i2c2_handle
6.12.3.6 qspi_handle
dsy_qspi_handle daisy::DaisySeed::qspi_handle
&
6.12.3.7 sai_handle
dsy_sai_handle daisy::DaisySeed::sai_handle
&
6.12.3.8 sdram_handle
dsy_sdram_handle daisy::DaisySeed::sdram_handle
&
6.12.3.9 usb_handle
UsbHandle daisy::DaisySeed::usb_handle
&
The documentation for this class was generated from the following file:
    • src/daisy_seed.h
```

# 6.13 dsy\_audio\_handle Struct Reference

```
#include <hid_audio.h>
```

## **Public Attributes**

- size\_t block\_size
- dsy\_sai\_handle \* sai
- dsy\_i2c\_handle \* dev0\_i2c
- dsy\_i2c\_handle \* dev1\_i2c

## 6.13.1 Detailed Description

Simple config struct that holds peripheral drivers.

## 6.13.2 Member Data Documentation

```
6.13.2.1 block_size

size_t dsy_audio_handle::block_size

&
6.13.2.2 dev0_i2c

dsy_i2c_handle* dsy_audio_handle::dev0_i2c

&
6.13.2.3 dev1_i2c

dsy_i2c_handle* dsy_audio_handle::dev1_i2c

&
6.13.2.4 sai

dsy_sai_handle* dsy_audio_handle::sai

&
```

The documentation for this struct was generated from the following file:

• src/hid\_audio.h

## 6.14 dsy\_dac\_handle Struct Reference

```
#include <per_dac.h>
```

## **Public Attributes**

- dsy\_dac\_mode mode
- dsy\_dac\_bitdepth bitdepth
- dsy\_gpio\_pin pin\_config [DSY\_DAC\_CHN\_LAST]

## 6.14.1 Detailed Description

Configuration structure for DAC initialization and settings. pin\_config must be filled out. However, the DACs are pretty consistently on pins PA4, and PA5 across all STM32 MCUs that I've used.

#### 6.14.2 Member Data Documentation

```
6.14.2.1 bitdepth
dsy_dac_bitdepth dsy_dac_handle::bitdepth
&
6.14.2.2 mode
dsy_dac_mode dsy_dac_handle::mode
&
6.14.2.3 pin_config
dsy_gpio_pin dsy_dac_handle::pin_config[DSY_DAC_CHN_LAST]
```

The documentation for this struct was generated from the following file:

• src/per\_dac.h

# 6.15 dsy\_gpio Struct Reference

```
#include <per_gpio.h>
```

## **Public Attributes**

- dsy\_gpio\_pin pin
- dsy\_gpio\_mode mode
- dsy\_gpio\_pull pull

## 6.15.1 Detailed Description

Struct for holding the pin, and configuration

## 6.15.2 Member Data Documentation

```
6.15.2.1 mode

dsy_gpio_mode dsy_gpio::mode

&

6.15.2.2 pin

dsy_gpio_pin dsy_gpio::pin

&

6.15.2.3 pull

dsy_gpio_pull dsy_gpio::pull

&
```

The documentation for this struct was generated from the following file:

• src/per\_gpio.h

# 6.16 dsy\_gpio\_pin Struct Reference

```
#include <daisy_core.h>
```

## **Public Attributes**

- dsy\_gpio\_port port
- uint8\_t pin

## 6.16.1 Detailed Description

Hardware define pins

### 6.16.2 Member Data Documentation

```
6.16.2.1 pin

uint8_t dsy_gpio_pin::pin

number 0-15

6.16.2.2 port

dsy_gpio_port dsy_gpio_pin::port

o
```

The documentation for this struct was generated from the following file:

• src/daisy\_core.h

# 6.17 dsy\_i2c\_handle Struct Reference

```
#include <per_i2c.h>
```

## **Public Attributes**

- dsy\_i2c\_periph periph
- dsy\_gpio\_pin pin\_config [DSY\_I2C\_PIN\_LAST]
- dsy\_i2c\_speed speed

## 6.17.1 Detailed Description

this object will be used to initialize the I2C interface, and can be passed to dev\_drivers that require I2C.

## 6.17.2 Member Data Documentation

```
6.17.2.1 periph

dsy_i2c_periph dsy_i2c_handle::periph

&

6.17.2.2 pin_config

dsy_gpio_pin dsy_i2c_handle::pin_config[DSY_I2C_PIN_LAST]

&
```

Generated by Doxygen

## 6.17.2.3 speed

```
dsy_i2c_speed dsy_i2c_handle::speed
```

&

The documentation for this struct was generated from the following file:

• src/per\_i2c.h

# 6.18 dsy\_qspi\_handle Struct Reference

```
#include <per_qspi.h>
```

## **Public Attributes**

- dsy\_qspi\_mode mode
- dsy\_qspi\_device device
- dsy\_gpio\_pin pin\_config [DSY\_QSPI\_PIN\_LAST]

## 6.18.1 Detailed Description

Configuration structure for interfacing with QSPI Driver

## 6.18.2 Member Data Documentation

```
6.18.2.1 device
```

```
dsy_qspi_device dsy_qspi_handle::device
```

&

## 6.18.2.2 mode

dsy\_qspi\_mode dsy\_qspi\_handle::mode

&

#### 6.18.2.3 pin\_config

```
dsy_gpio_pin dsy_qspi_handle::pin_config[DSY_QSPI_PIN_LAST]
```

&

The documentation for this struct was generated from the following file:

· src/per\_qspi.h

## 6.19 dsy\_sai\_handle Struct Reference

```
#include <per_sai.h>
```

#### **Public Attributes**

- · dsy\_audio\_sai init
- dsy\_audio\_samplerate samplerate [DSY\_SAI\_LAST]
- dsy\_audio\_bitdepth bitdepth [DSY\_SAI\_LAST]
- dsy audio dir a direction [DSY SAI LAST]
- dsy\_audio\_dir b\_direction [DSY\_SAI\_LAST]
- dsy\_audio\_sync sync\_config [DSY\_SAI\_LAST]
- dsy\_audio\_device device [DSY\_SAI\_LAST]
- dsy\_gpio\_pin sai1\_pin\_config [DSY\_SAI\_PIN\_LAST]
- dsy\_gpio\_pin sai2\_pin\_config [DSY\_SAI\_PIN\_LAST]

## 6.19.1 Detailed Description

Configuration structure for SAI contains all above settings, and passes them to internal structure for hardware initialization.

## 6.19.2 Member Data Documentation

```
6.19.2.1 a_direction

dsy_audio_dir dsy_sai_handle::a_direction[DSY_SAI_LAST]

&
6.19.2.2 b_direction

dsy_audio_dir dsy_sai_handle::b_direction[DSY_SAI_LAST]
```

&

```
6.19.2.3 bitdepth
dsy_audio_bitdepth dsy_sai_handle::bitdepth[DSY_SAI_LAST]
6.19.2.4 device
dsy_audio_device dsy_sai_handle::device[DSY_SAI_LAST]
&
6.19.2.5 init
dsy_audio_sai dsy_sai_handle::init
&
6.19.2.6 sai1_pin_config
dsy_gpio_pin dsy_sai_handle::sail_pin_config[DSY_SAI_PIN_LAST]
&
6.19.2.7 sai2_pin_config
dsy_gpio_pin dsy_sai_handle::sai2_pin_config[DSY_SAI_PIN_LAST]
&
6.19.2.8 samplerate
dsy_audio_samplerate dsy_sai_handle::samplerate[DSY_SAI_LAST]
&
6.19.2.9 sync_config
dsy_audio_sync dsy_sai_handle::sync_config[DSY_SAI_LAST]
&
The documentation for this struct was generated from the following file:
    src/per_sai.h
```

## 6.20 DSY\_SD\_CardInfoTypeDef Struct Reference

#include <util\_bsp\_sd\_diskio.h>

## **Public Attributes**

- uint32\_t CardType
- uint32\_t CardVersion
- uint32\_t Class
- uint32\_t RelCardAdd
- uint32\_t BlockNbr
- uint32\_t BlockSize
- uint32\_t LogBlockNbr
- uint32\_t LogBlockSize
- uint32\_t CardSpeed

## 6.20.1 Detailed Description

Functions for handling DisklO via SDMMC These are usually configured through the FatFS driver/interface, and won't need to be accessed directly often.

## 6.20.2 Member Data Documentation

## 6.20.2.1 BlockNbr

uint32\_t DSY\_SD\_CardInfoTypeDef::BlockNbr

Specifies the Card Capacity in blocks

## 6.20.2.2 BlockSize

uint32\_t DSY\_SD\_CardInfoTypeDef::BlockSize

## Specifies one block size in bytes

## 6.20.2.3 CardSpeed

uint32\_t DSY\_SD\_CardInfoTypeDef::CardSpeed

## Specifies the card Speed

## 6.20.2.4 CardType

uint32\_t DSY\_SD\_CardInfoTypeDef::CardType

Specifies the card Type

#### 6.20.2.5 CardVersion

uint32\_t DSY\_SD\_CardInfoTypeDef::CardVersion

Specifies the card version

#### 6.20.2.6 Class

uint32\_t DSY\_SD\_CardInfoTypeDef::Class

Specifies the class of the card class

## 6.20.2.7 LogBlockNbr

uint32\_t DSY\_SD\_CardInfoTypeDef::LogBlockNbr

Specifies the Card logical Capacity in blocks

## 6.20.2.8 LogBlockSize

uint32\_t DSY\_SD\_CardInfoTypeDef::LogBlockSize

Specifies logical block size in bytes

## 6.20.2.9 RelCardAdd

uint32\_t DSY\_SD\_CardInfoTypeDef::RelCardAdd

## Specifies the Relative Card Address

The documentation for this struct was generated from the following file:

• src/util\_bsp\_sd\_diskio.h

## 6.21 dsy\_sdram\_handle Struct Reference

#include <dev\_sdram.h>

## **Public Attributes**

- dsy\_sdram\_state state
- dsy\_gpio\_pin pin\_config [DSY\_SDRAM\_PIN\_LAST]

## 6.21.1 Detailed Description

Configuration struct for passing to initialization

#### 6.21.2 Member Data Documentation

```
6.21.2.1 pin_config

dsy_gpio_pin dsy_sdram_handle::pin_config[DSY_SDRAM_PIN_LAST]
&
6.21.2.2 state

dsy_sdram_state dsy_sdram_handle::state
```

The documentation for this struct was generated from the following file:

· src/dev sdram.h

&

## 6.22 dsy\_sr\_4021\_handle Struct Reference

```
#include <dev_sr_4021.h>
```

## **Public Attributes**

- dsy\_gpio\_pin pin\_config [DSY\_SR\_4021\_PIN\_LAST]
- uint8\_t num\_parallel
- uint8\_t num\_daisychained
- dsy\_gpio cs
- dsy\_gpio clk
- dsy\_gpio data [2]
- uint8\_t states [8 \*1 \*2]

## 6.22.1 Detailed Description

configuration strucutre for 4021 pin config is used to initialize the dsy\_gpio num\_parallel is the number of devices connected that share the same clk/cs, etc. but have independent data num\_daisychained is the number of devices in a daisy-chain configuration

## 6.22.2 Member Data Documentation

```
6.22.2.1 clk
dsy_gpio dsy_sr_4021_handle::clk
clk pin
6.22.2.2 cs
dsy_gpio dsy_sr_4021_handle::cs
cs pin
6.22.2.3 data
dsy_gpio dsy_sr_4021_handle::data[2]
array of data pins
6.22.2.4 num_daisychained
uint8_t dsy_sr_4021_handle::num_daisychained
Number of devices daisy chained
6.22.2.5 num_parallel
uint8_t dsy_sr_4021_handle::num_parallel
number of devices connected
6.22.2.6 pin_config
dsy_gpio_pin dsy_sr_4021_handle::pin_config[DSY_SR_4021_PIN_LAST]
used to initialize the dsy_gpio
```

#### 6.22.2.7 states

```
uint8_t dsy_sr_4021_handle::states[8 * 1 * 2]
```

array of states

The documentation for this struct was generated from the following file:

src/dev\_sr\_4021.h

## 6.23 daisy::Encoder Class Reference

Generic Class for handling Quadrature Encoders Inspired/influenced by Mutable Instruments (pichenettes) Encoder classes.

```
#include <hid_encoder.h>
```

## **Public Member Functions**

- void Init (dsy\_gpio\_pin a, dsy\_gpio\_pin b, dsy\_gpio\_pin click, float update\_rate)
- void Debounce ()
- int32\_t Increment () const
- bool RisingEdge () const
- bool FallingEdge () const
- bool Pressed () const
- float TimeHeldMs () const

## 6.23.1 Detailed Description

Generic Class for handling Quadrature Encoders
Inspired/influenced by Mutable Instruments (pichenettes) Encoder classes.

Author

Stephen Hensley

Date

December 2019

## 6.23.2 Member Function Documentation

#### 6.23.2.1 Debounce()

```
void daisy::Encoder::Debounce ( )
```

Called at update\_rate to debounce and handle timing for the switch. In order for events not to be missed, its important that the Edge/Pressed checks be made at the same rate as the debounce function is being called.

#### 6.23.2.2 FallingEdge()

```
bool daisy::Encoder::FallingEdge ( ) const [inline]
```

Returns true if the encoder was just released.

#### 6.23.2.3 Increment()

```
int32_t daisy::Encoder::Increment ( ) const [inline]
```

Returns +1 if the encoder was turned clockwise, -1 if it was turned counter-clockwise, or 0 if it was not just turned.

#### 6.23.2.4 Init()

Initializes the encoder with the specified hardware pins. Update rate should be the rate at which Debounce() gets called in Hertz.

#### 6.23.2.5 Pressed()

```
bool daisy::Encoder::Pressed ( ) const [inline]
```

Returns true while the encoder is held down.

#### 6.23.2.6 RisingEdge()

```
bool daisy::Encoder::RisingEdge ( ) const [inline]
```

Returns true if the encoder was just pressed.

#### 6.23.2.7 TimeHeldMs()

```
float daisy::Encoder::TimeHeldMs ( ) const [inline]
```

Returns the time in milliseconds that the encoder has been held down.

The documentation for this class was generated from the following file:

src/hid\_encoder.h

## 6.24 FontDef Struct Reference

```
#include <util_oled_fonts.h>
```

## **Public Attributes**

- const uint8\_t FontWidth
- uint8\_t FontHeight
- const uint16\_t \* data

## 6.24.1 Detailed Description

Utility for displaying fonts on OLED displays Migrated to work with libdaisy from stm32-ssd1306

**Author** 

afiskon on github. Font struct

#### 6.24.2 Member Data Documentation

#### 6.24.2.1 data

```
const uint16_t* FontDef::data
```

Pointer to data font data array

## 6.24.2.2 FontHeight

uint8\_t FontDef::FontHeight

Font height in pixels

## 6.24.2.3 FontWidth

```
const uint8_t FontDef::FontWidth
```

Font width in pixels

The documentation for this struct was generated from the following file:

src/util\_oled\_fonts.h

# 6.25 daisy::GateIn Class Reference

Generic Class for handling gate inputs through GPIO.

```
#include <hid_gatein.h>
```

## **Public Member Functions**

- GateIn ()
- ∼GateIn ()
- void Init (dsy\_gpio\_pin \*pin\_cfg)
- bool Trig ()

## 6.25.1 Detailed Description

Generic Class for handling gate inputs through GPIO.

Author

Stephen Hensley

Date

March 2020

#### 6.25.2 Constructor & Destructor Documentation

```
6.25.2.1 GateIn()

daisy::GateIn::GateIn ( ) [inline]

GateIn Constructor

6.25.2.2 ~GateIn()

daisy::GateIn::~GateIn ( ) [inline]
```

### 6.25.3 Member Function Documentation

GateIn $\sim$  Destructor

Init Initializes the gate input with specified hardware pin

```
6.25.3.2 Trig()
```

```
bool daisy::GateIn::Trig ( )
```

Trig Checks current state of gate input.

Returns

FALSE if pin is low, and TRUE if high

The documentation for this class was generated from the following file:

· src/hid gatein.h

## 6.26 daisy::Led Class Reference

LED Class providing simple Software PWM ability, etc

Eventually this will work with hardware PWM, and external LED Driver devices as well.

```
#include <hid_led.h>
```

#### **Public Member Functions**

- void Init (dsy gpio pin pin, bool invert, float samplerate=1000.0f)
- · void Set (float val)
- void Update ()

#### 6.26.1 Detailed Description

LED Class providing simple Software PWM ability, etc

Eventually this will work with hardware PWM, and external LED Driver devices as well.

Author

shensley

Date

March 2020

## 6.26.2 Member Function Documentation

```
6.26.2.1 Init()
```

Initializes an LED using the specified hardware pin.

#### **Parameters**

pin chooses LED pin		
	invert	will set whether to internally invert the brightness due to hardware config.
	samplerate	sets the rate at which 'Update()' will be called (used for software PWM)

## 6.26.2.2 Set()

```
void daisy::Led::Set (
          float val )
```

Sets the brightness of the Led.

#### **Parameters**

val

will be cubed for gamma correction, and then quantized to 8-bit values for Software PWM 8-bit is for more flexible update rate options, as 12-bit or more would require faster update rates.

#### 6.26.2.3 Update()

```
void daisy::Led::Update ( )
```

This processes the pwm of the LED sets the hardware accordingly.

The documentation for this class was generated from the following file:

• src/hid\_led.h

## 6.27 daisy::MidiEvent Struct Reference

```
#include <hid_midi.h>
```

#### **Public Member Functions**

- NoteOnEvent AsNoteOn ()
- ControlChangeEvent AsControlChange ()

## **Public Attributes**

- MidiMessageType type
- int channel
- uint8\_t data [2]

## 6.27.1 Detailed Description

Simple MidiEvent with message type, channel, and data[2] members.

## 6.27.2 Member Function Documentation

## 6.27.2.1 AsControlChange()

```
ControlChangeEvent daisy::MidiEvent::AsControlChange ( ) [inline]
```

Returns the data within the MidiEvent as a NoteOnEvent struct.

## 6.27.2.2 AsNoteOn()

```
NoteOnEvent daisy::MidiEvent::AsNoteOn ( ) [inline]
```

Returns the data within the MidiEvent as a NoteOnEvent struct

#### 6.27.3 Member Data Documentation

#### 6.27.3.1 channel

```
int daisy::MidiEvent::channel
```

&

#### 6.27.3.2 data

```
uint8_t daisy::MidiEvent::data[2]
```

ጲ

## 6.27.3.3 type

```
MidiMessageType daisy::MidiEvent::type
```

&

The documentation for this struct was generated from the following file:

• src/hid\_midi.h

## 6.28 daisy::MidiHandler Class Reference

Simple MIDI Handler

Parses bytes from an input into valid MidiEvents.

The MidiEvents fill a FIFO queue that the user can pop messages from.

```
#include <hid midi.h>
```

## **Public Types**

- enum MidiInputMode { INPUT\_MODE\_NONE = 0x00, INPUT\_MODE\_UART1 = 0x01, INPUT\_MODE\_US

  B\_INT = 0x02, INPUT\_MODE\_USB\_EXT = 0x04 }
- enum MidiOutputMode { OUTPUT\_MODE\_NONE = 0x00, OUTPUT\_MODE\_UART1 = 0x01, OUTPUT\_M
  ODE\_USB\_INT = 0x02, OUTPUT\_MODE\_USB\_EXT = 0x04 }

#### **Public Member Functions**

- void Init (MidiInputMode in\_mode, MidiOutputMode out\_mode)
- void StartReceive ()
- void Listen ()
- void Parse (uint8\_t byte)
- bool HasEvents () const
- MidiEvent PopEvent ()

## 6.28.1 Detailed Description

Simple MIDI Handler

Parses bytes from an input into valid MidiEvents.

The MidiEvents fill a FIFO queue that the user can pop messages from.

Author

shensley

Date

March 2020

#### 6.28.2 Member Enumeration Documentation

## 6.28.2.1 MidiInputMode

enum daisy::MidiHandler::MidiInputMode

Input and Output can be configured separately Multiple Input modes can be selected by OR'ing the values.

## Enumerator

INPUT_MODE_NONE	&
INPUT_MODE_UART1	&
INPUT_MODE_USB_INT	
INPUT_MODE_USB_EXT	

## 6.28.2.2 MidiOutputMode

enum daisy::MidiHandler::MidiOutputMode

## Output mode

#### Enumerator

OUTPUT_MODE_NONE	
OUTPUT_MODE_UART1	
OUTPUT_MODE_USB_INT	
OUTPUT_MODE_USB_EXT	&

## 6.28.3 Member Function Documentation

## 6.28.3.1 HasEvents()

```
bool daisy::MidiHandler::HasEvents ( ) const [inline]
```

Checks if there are unhandled messages in the queue

## Returns

True if there are events to be handled, else false.

## 6.28.3.2 Init()

Initializes the MidiHandler

#### **Parameters**

in_mode	Input mode
out_mode	Output mode

## 6.28.3.3 Listen()

```
void daisy::MidiHandler::Listen ( )
```

Start listening

#### 6.28.3.4 Parse()

Feed in bytes to state machine from a queue. Populates internal FIFO queue with MIDI Messages For example with uart: midi.Parse(uart.PopRx());

#### **Parameters**



## 6.28.3.5 PopEvent()

```
MidiEvent daisy::MidiHandler::PopEvent ( ) [inline]
```

Pops the oldest unhandled MidiEvent from the internal queue

Returns

The event to be handled

## 6.28.3.6 StartReceive()

```
void daisy::MidiHandler::StartReceive ( )
```

Starts listening on the selected input mode(s). MidiEvent Queue will begin to fill, and can be checked with

The documentation for this class was generated from the following file:

• src/hid\_midi.h

# 6.29 daisy::NoteOnEvent Struct Reference

```
#include <hid_midi.h>
```

## **Public Attributes**

- int channel
- uint8 t note
- uint8\_t velocity

## 6.29.1 Detailed Description

Struct containing note, and velocity data for a given channel. Can be made from MidiEvent

## 6.29.2 Member Data Documentation

### 6.29.2.1 channel

int daisy::NoteOnEvent::channel

&

## 6.29.2.2 note

uint8\_t daisy::NoteOnEvent::note

&

## 6.29.2.3 velocity

uint8\_t daisy::NoteOnEvent::velocity

&

The documentation for this struct was generated from the following file:

• src/hid\_midi.h

# 6.30 daisy::OledDisplay Class Reference

#include <hid\_oled\_display.h>

## **Public Types**

enum Pins { DATA\_COMMAND, RESET, NUM\_PINS }

#### **Public Member Functions**

- void Init (dsy\_gpio\_pin \*pin\_cfg)
- void Fill (bool on)
- void DrawPixel (uint8\_t x, uint8\_t y, bool on)
- char WriteChar (char ch, FontDef font, bool on)
- char WriteString (char \*str, FontDef font, bool on)
- void SetCursor (uint8\_t x, uint8\_t y)
- void Update ()

## 6.30.1 Detailed Description

Human Interface Driver for using an OLED Display (SSD1309) For all bool on arguments: true is on, false is off. Credit to Aleksander Alekseev (github.com/afiskon/stm32-ssd1306) on github for a great starting point. adapted for SSD1309 and H7 by shensley, 2020

#### 6.30.2 Member Enumeration Documentation

## 6.30.2.1 Pins

```
enum daisy::OledDisplay::Pins
```

GPIO Pins that need to be used independent of peripheral used.

## Enumerator

DATA_COMMAND	Data command pin.
RESET	Reset pin
NUM_PINS	Num pins

## 6.30.3 Member Function Documentation

#### 6.30.3.1 DrawPixel()

Sets the pixel at the specified coordinate to be on/off.

## **Parameters**

X	x Coordinate
У	y coordinate
on	on or off

## 6.30.3.2 Fill()

```
void daisy::OledDisplay::Fill (
          bool on )
```

Fills the entire display with either on/off.

## **Parameters**

```
on Sets on or off.
```

## 6.30.3.3 Init()

Takes an argument for the pin cfg

## **Parameters**

pin\_cfg should be a pointer to an array of OledDisplay::NUM\_PINS dsy\_gpio\_pins

## 6.30.3.4 SetCursor()

```
void daisy::OledDisplay::SetCursor (  \mbox{uint8\_t } x, \\ \mbox{uint8\_t } y \; )
```

Moves the 'Cursor' position used for WriteChar, and WriteStr to the specified coordinate.

#### **Parameters**

Х	x pos
У	y pos

#### 6.30.3.5 Update()

```
void daisy::OledDisplay::Update ( )
```

Writes the current display buffer to the OLED device using SPI or I2C depending on how the object was initialized.

## 6.30.3.6 WriteChar()

Writes the character with the specific FontDef to the display buffer at the current Cursor position.

#### **Parameters**

ch character to be writte	
font	font to be written in
on	on or off

## Returns

&

## 6.30.3.7 WriteString()

Similar to WriteChar, except it will handle an entire String. Wrapping does not happen automatically, so the width of the string must be kept within the dimensions of the screen.

#### **Parameters**

str	string to be written
font font to use	
on	on or off

## Returns

&

The documentation for this class was generated from the following file:

• src/hid\_oled\_display.h

# 6.31 daisy::Parameter Class Reference

```
#include <hid_parameter.h>
```

## **Public Types**

```
    enum Curve {
        LINEAR, EXPONENTIAL, LOGARITHMIC, CUBE,
        LAST }
```

## **Public Member Functions**

- Parameter ()
- ∼Parameter ()
- void Init (AnalogControl input, float min, float max, Curve curve)
- float Process ()
- float Value ()

## 6.31.1 Detailed Description

Simple parameter mapping tool that takes a 0-1 input from an hid\_ctrl.

## 6.31.2 Member Enumeration Documentation

## 6.31.2.1 Curve

```
enum daisy::Parameter::Curve
```

Curves are applied to the output signal

#### Enumerator

LINEAR	Linear curve
EXPONENTIAL	Exponential curve
LOGARITHMIC	Logarithmic curve
CUBE	Cubic curve
LAST	Final enum element.

## 6.31.3 Constructor & Destructor Documentation

```
6.31.3.1 Parameter()

daisy::Parameter::Parameter ( ) [inline]

Constructor

6.31.3.2 ~Parameter()

daisy::Parameter::~Parameter ( ) [inline]
```

## 6.31.4 Member Function Documentation

## 6.31.4.1 Init()

Destructor

initialize a parameter using an hid\_ctrl object.

#### **Parameters**

input	- object containing the direct link to a hardware control source.	
min	- bottom of range. (when input is 0.0)	
max	- top of range (when input is 1.0)	
curve	- the scaling curve for the input->output transformation.	

## 6.31.4.2 Process()

```
float daisy::Parameter::Process ( )
```

processes the input signal, this should be called at the samplerate of the hid\_ctrl passed in.

#### Returns

a float with the specified transformation applied.

#### 6.31.4.3 Value()

```
float daisy::Parameter::Value ( ) [inline]
```

#### Returns

the current value from the parameter without processing another sample. this is useful if you need to use the value multiple times, and don't store the output of process in a local variable.

The documentation for this class was generated from the following file:

• src/hid\_parameter.h

## 6.32 daisy::RgbLed Class Reference

```
#include <hid_rgb_led.h>
```

### **Public Member Functions**

- void Init (dsy\_gpio\_pin red, dsy\_gpio\_pin green, dsy\_gpio\_pin blue, bool invert)
- void Set (float r, float g, float b)
- void SetColor (Color c)
- void Update ()

## 6.32.1 Detailed Description

3x LEDs configured as an RGB for ease of use.

## 6.32.2 Member Function Documentation

## 6.32.2.1 Init()

Initializes 3x GPIO Pins as red, green, and blue elements of an RGB LED

#### **Parameters**

red	Red element
green	Green element
blue	Blue element
invert	Flips led polarity

## 6.32.2.2 Set()

Sets each element of the LED with a floating point number 0-1

#### **Parameters**

r	Red element	
g	Green element	
b	Blue element	

## 6.32.2.3 SetColor()

```
void daisy::RgbLed::SetColor ( {	t Color}\ c )
```

Sets the RGB using a Color object.

## **Parameters**

```
c Color object to set.
```

## 6.32.2.4 Update()

```
void daisy::RgbLed::Update ( )
```

Updates the PWM of the LED based on the current values. Should be called at a regular interval. (i.e. 1kHz/1ms)

The documentation for this class was generated from the following file:

```
• src/hid_rgb_led.h
```

# 6.33 daisy::RingBuffer < T, size > Class Template Reference

```
#include <util_ringbuffer.h>
```

## **Public Member Functions**

- void Init ()
- size\_t capacity () const
- size\_t writable () const
- size\_t readable () const
- void Write (T v)
- void Overwrite (T v)
- T Read ()
- T ImmediateRead ()
- void Flush ()
- void Swallow (size\_t n)
- void ImmediateRead (T \*destination, size\_t num\_elements)
- void Overwrite (const T \*source, size\_t num\_elements)

## 6.33.1 Detailed Description

```
template<typename T, size_t size> class daisy::RingBuffer< T, size >
```

Utility Ring Buffer imported from pichenettes/stmlib

## 6.33.2 Member Function Documentation

## 6.33.2.1 capacity()

```
template<typename T, size_t size>
size_t daisy::RingBuffer< T, size >::capacity ( ) const [inline]
```

## Returns

The total size of the ring buffer

## 6.33.2.2 Flush()

```
template<typename T, size_t size>
void daisy::RingBuffer< T, size >::Flush ( ) [inline]
```

Flushes unread elements from the ring buffer

#### 6.33.2.3 ImmediateRead() [1/2]

```
template<typename T, size_t size>
T daisy::RingBuffer< T, size >::ImmediateRead ( ) [inline]
```

Reads next element from ring buffer immediately

Returns

read value

#### 6.33.2.4 ImmediateRead() [2/2]

Reads a number of elements into a buffer immediately

#### **Parameters**

destination	buffer to write to
num_elements	number of elements in buffer

## 6.33.2.5 Init()

```
template<typename T, size_t size>
void daisy::RingBuffer< T, size >::Init ( ) [inline]
```

Initializes the Ring Buffer

## **6.33.2.6** Overwrite() [1/2]

Writes the new element to the ring buffer, overwriting unread data if necessary.

#### **Parameters**

```
v Value to overwrite
```

#### 6.33.2.7 Overwrite() [2/2]

Overwrites a number of elements using the source buffer as input.

#### **Parameters**

source	Input buffer
num_elements	Number of elements in source

## 6.33.2.8 Read()

```
template<typename T, size_t size>
T daisy::RingBuffer< T, size >::Read ( ) [inline]
```

Reads the first available element from the ring buffer

#### Returns

read value

## 6.33.2.9 readable()

```
template<typename T, size_t size>
size_t daisy::RingBuffer< T, size >::readable ( ) const [inline]
```

## Returns

number of unread elements in ring buffer

## 6.33.2.10 Swallow()

Read enough samples to make it possible to read 1 sample.

#### **Parameters**

```
n | Size of T?
```

#### 6.33.2.11 writable()

```
template<typename T, size_t size>
size_t daisy::RingBuffer< T, size >::writable ( ) const [inline]
```

## Returns

the number of samples that can be written to ring buffer without overwriting unread data.

## 6.33.2.12 Write()

Writes the value to the next available position in the ring buffer

#### **Parameters**

```
v Value to write
```

The documentation for this class was generated from the following file:

· src/util\_ringbuffer.h

# 6.34 daisy::RingBuffer< T, 0 > Class Template Reference

```
#include <util_ringbuffer.h>
```

#### **Public Member Functions**

- void Init ()
- size\_t capacity () const
- size\_t writable () const
- size\_t readable () const
- void Write (T v)
- void Overwrite (T v)
- T Read ()
- T ImmediateRead ()
- void Flush ()
- void ImmediateRead (T \*destination, size\_t num\_elements)
- void Overwrite (const T \*source, size\_t num\_elements)

## 6.34.1 Detailed Description

```
template < typename T> class daisy::RingBuffer < T, 0 >
```

Utility Ring Buffer imported from pichenettes/stmlib

## 6.34.2 Member Function Documentation

```
6.34.2.1 capacity()
```

```
template<typename T >
size_t daisy::RingBuffer< T, 0 >::capacity ( ) const [inline]
```

#### Returns

0

## 6.34.2.2 Flush()

```
template<typename T >
void daisy::RingBuffer< T, 0 >::Flush () [inline]
```

Flush the buffer

## **6.34.2.3** ImmediateRead() [1/2]

```
template<typename T >
T daisy::RingBuffer< T, 0 >::ImmediateRead ( ) [inline]
```

## Returns

Read value

## **6.34.2.4** ImmediateRead() [2/2]

#### **Parameters**

destination	&
num_elements	&

## 6.34.2.5 Init()

```
template<typename T >
void daisy::RingBuffer< T, 0 >::Init () [inline]
```

#### Initialize ringbuffer

## **6.34.2.6** Overwrite() [1/2]

#### **Parameters**

```
Value to overwrite
```

## **6.34.2.7 Overwrite()** [2/2]

## **Parameters**

source	3
num elements	&

## 6.34.2.8 Read()

```
template<typename T >
T daisy::RingBuffer< T, 0 >::Read ( ) [inline]
```

#### Returns

Read value

## 6.34.2.9 readable()

```
template<typename T >
size_t daisy::RingBuffer< T, 0 >::readable ( ) const [inline]
```

#### Returns

0

## 6.34.2.10 writable()

```
template<typename T >
size_t daisy::RingBuffer< T, 0 >::writable ( ) const [inline]
```

## Returns

0

## 6.34.2.11 Write()

#### **Parameters**

v Value to write

The documentation for this class was generated from the following file:

• src/util\_ringbuffer.h

# 6.35 daisy::SdmmcHandler Class Reference

```
#include <per_sdmmc.h>
```

## **Public Member Functions**

• void Init ()

## 6.35.1 Detailed Description

Configuration for interfacing with SD cards. Currently only supports operation using FatFS filesystem

## 6.35.2 Member Function Documentation

## 6.35.2.1 Init()

```
void daisy::SdmmcHandler::Init ( )
```

Initializes the SD Card Interface For now all settings are fixed (See todo at top of section)

The documentation for this class was generated from the following file:

· src/per\_sdmmc.h

## 6.36 daisy::SdmmcHandlerInit Struct Reference

```
#include <per_sdmmc.h>
```

## **Public Attributes**

- SdmmcBitWidth bitdepth
- SdmmcSpeed speed

## 6.36.1 Detailed Description

Structure for setting the options above. Used to intiailize SdmmcHandler

## 6.36.2 Member Data Documentation

## 6.36.2.1 bitdepth

SdmmcBitWidth daisy::SdmmcHandlerInit::bitdepth

&

## 6.36.2.2 speed

```
SdmmcSpeed daisy::SdmmcHandlerInit::speed
```

&

The documentation for this struct was generated from the following file:

• src/per\_sdmmc.h

# 6.37 ShiftRegister595 Class Reference

```
Device Driver for 8-bit shift register.
CD74HC595 - 8-bit serial to parallel output shift.
```

```
#include <dev_sr_595.h>
```

## **Public Types**

enum Pins { PIN\_LATCH, PIN\_CLK, PIN\_DATA, NUM\_PINS }

#### **Public Member Functions**

- void Init (dsy\_gpio\_pin \*pin\_cfg, size\_t num\_daisy\_chained=1)
- void Set (uint8\_t idx, bool state)
- void Write ()

## 6.37.1 Detailed Description

Device Driver for 8-bit shift register. CD74HC595 - 8-bit serial to parallel output shift.

**Author** 

shensley

Date

May 2020

## 6.37.2 Member Enumeration Documentation

## 6.37.2.1 Pins

```
enum ShiftRegister595::Pins
```

The following pins correspond to the hardware connections to the 595.

#### Enumerator

PIN_CLK	LATCH corresonds to Pin 12 "RCLK"
PIN_DATA	CLK corresponds to Pin 11 "SRCLK"
NUM_PINS	DATA corresponds to Pin 14 "SER"

## 6.37.3 Member Function Documentation

#### 6.37.3.1 Init()

Initializes the GPIO, and data for the ShiftRegister

#### **Parameters**

pin_cfg	is an array of dsy_gpio_pin corresponding the the Pins enum above.
num_daisy_chained	(default = 1) is the number of 595 devices daisy chained together.

## 6.37.3.2 Set()

Sets the state of the specified output.

## **Parameters**

idx	The index starts with QA on the first device and ends with QH on the last device.
state	A true state will set the output HIGH, while a false state will set the output LOW.

## 6.37.3.3 Write()

```
void ShiftRegister595::Write ( )
```

Writes the states of shift register out to the connected devices.

The documentation for this class was generated from the following file:

```
• src/dev_sr_595.h
```

# 6.38 daisy::SpiHandle Class Reference

```
#include <per_spi.h>
```

#### **Public Member Functions**

- void Init ()
- void BlockingTransmit (uint8\_t \*buff, size\_t size)

## 6.38.1 Detailed Description

Handler for serial peripheral interface

#### 6.38.2 Member Function Documentation

#### 6.38.2.1 BlockingTransmit()

## Blocking transmit

#### **Parameters**

*buff	input buffer
size	buffer size

## 6.38.2.2 Init()

```
void daisy::SpiHandle::Init ( )
```

## Initializes handler

The documentation for this class was generated from the following file:

```
• src/per_spi.h
```

# 6.39 daisy::Switch Class Reference

```
#include <hid_switch.h>
```

## **Public Types**

- enum Type { TYPE\_TOGGLE, TYPE\_MOMENTARY }
- enum Polarity { POLARITY\_NORMAL, POLARITY\_INVERTED }
- enum Pull { PULL\_UP, PULL\_DOWN, PULL\_NONE }

## **Public Member Functions**

- void Init (dsy\_gpio\_pin pin, float update\_rate, Type t, Polarity pol, Pull pu)
- void Init (dsy\_gpio\_pin pin, float update\_rate)
- void Debounce ()
- bool RisingEdge () const
- bool FallingEdge () const
- bool Pressed () const
- float TimeHeldMs () const

## 6.39.1 Detailed Description

Generic Class for handling momentary/latching switches Inspired/influenced by Mutable Instruments (pichenettes) Switch classes

Author

Stephen Hensley

Date

December 2019

#### 6.39.2 Member Enumeration Documentation

6.39.2.1 Polarity

enum daisy::Switch::Polarity

Specifies whether the pressed is HIGH or LOW.

Enumerator

POLARITY_NORMAL	
POLARITY INVERTED	&

#### 6.39.2.2 Pull

```
enum daisy::Switch::Pull
```

Specifies whether to use built-in Pull Up/Down resistors to hold button at a given state when not engaged.

#### Enumerator

PULL_UP	&
PULL_DOWN	&
PULL_NONE	&

## 6.39.2.3 Type

```
enum daisy::Switch::Type
```

Specifies the expected behavior of the switch

#### Enumerator

TYPE_TOGGLE	&
TYPE_MOMENTARY	&

## 6.39.3 Member Function Documentation

#### 6.39.3.1 Debounce()

```
void daisy::Switch::Debounce ( )
```

Called at update\_rate to debounce and handle timing for the switch. In order for events not to be missed, its important that the Edge/Pressed checks be made at the same rate as the debounce function is being called.

## 6.39.3.2 FallingEdge()

```
bool daisy::Switch::FallingEdge ( ) const [inline]
```

#### **Returns**

true if the button was just released

Initializes the switch object with a given port/pin combo.

#### **Parameters**

pin	port/pin object to tell the switch which hardware pin to use.
update_rate	the rate at which the Debounce() function will be called. (used for timing).
t	switch type – Default: TYPE_MOMENTARY
pol	switch polarity – Default: POLARITY_INVERTED
ри	switch pull up/down – Default: PULL_UP

## Simplified Init.

## **Parameters**

pin	port/pin object to tell the switch which hardware pin to use.
update_rate	the rate at which the Debounce() function will be called. (used for timing).

## 6.39.3.5 Pressed()

```
bool daisy::Switch::Pressed ( ) const [inline]
```

## Returns

true if the button is held down (or if the toggle is on)

## 6.39.3.6 RisingEdge()

```
bool daisy::Switch::RisingEdge ( ) const [inline]
```

#### Returns

true if a button was just pressed.

## 6.39.3.7 TimeHeldMs()

```
float daisy::Switch::TimeHeldMs ( ) const [inline]
```

#### Returns

the time in milliseconds that the button has been held (or toggle has been on)

The documentation for this class was generated from the following file:

• src/hid switch.h

## 6.40 daisy::UartHandler Class Reference

```
#include <per_uart.h>
```

## **Public Member Functions**

- void Init ()
- int PollReceive (uint8\_t \*buff, size\_t size, uint32\_t timeout)
- int StartRx (size\_t size)
- bool RxActive ()
- int FlushRx ()
- int PollTx (uint8\_t \*buff, size\_t size)
- uint8\_t PopRx ()
- size\_t Readable ()
- int CheckError ()

## 6.40.1 Detailed Description

**Uart Peripheral** 

**Author** 

shensley

Date

March 2020

## 6.40.2 Member Function Documentation

## 6.40.2.1 CheckError()

```
int daisy::UartHandler::CheckError ( )
```

## Returns

the result of HAL\_UART\_GetError() to the user.

## 6.40.2.2 FlushRx()

```
int daisy::UartHandler::FlushRx ( )
```

Flushes the Receive Queue

#### Returns

OK or ERROR

## 6.40.2.3 Init()

```
void daisy::UartHandler::Init ( )
```

Initializes the UART Peripheral

## 6.40.2.4 PollReceive()

Reads the amount of bytes in blocking mode with a 10ms timeout.

#### **Parameters**

*buff	Buffer to read to
size	Buff size
timeout	How long to timeout for (10ms?)

## Returns

Data received

## 6.40.2.5 PolITx()

Sends an amount of data in blocking mode.

## **Parameters**

*buff	Buffer of data to send
size	Buffer size

#### Returns

OK or ERROR

## 6.40.2.6 PopRx()

```
uint8_t daisy::UartHandler::PopRx ( )
```

Pops the oldest byte from the FIFO.

## Returns

Popped byte

## 6.40.2.7 Readable()

```
size_t daisy::UartHandler::Readable ( )
```

Checks if there are any unread bytes in the FIFO

## Returns

1 or 0 ??

#### 6.40.2.8 RxActive()

```
bool daisy::UartHandler::RxActive ( )
```

#### Returns

whether Rx DMA is listening or not.

#### 6.40.2.9 StartRx()

Starts a DMA Receive callback to fill a buffer of specified size. Data is populated into a FIFO queue, and can be queried with the functions below. Maximum Buffer size is defined above. If a value outside of the maximum is specified, the size will be set to the maximum.

#### **Parameters**

size	Queue size
------	------------

#### Returns

OK or ERROR

The documentation for this class was generated from the following file:

· src/per\_uart.h

## 6.41 daisy::UsbHandle Class Reference

Interface for initializing and using the USB Peripherals on the daisy.

```
#include <hid_usb.h>
```

## **Public Types**

- enum UsbPeriph { FS\_INTERNAL, FS\_EXTERNAL, FS\_BOTH }
- typedef void(\* ReceiveCallback) (uint8\_t \*buff, uint32\_t \*len)

## **Public Member Functions**

- void Init (UsbPeriph dev)
- void TransmitInternal (uint8\_t \*buff, size\_t size)
- void TransmitExternal (uint8\_t \*buff, size\_t size)
- void SetReceiveCallback (ReceiveCallback cb)

## 6.41.1 Detailed Description

Interface for initializing and using the USB Peripherals on the daisy.

Author

Stephen Hensley

Date

December 2019

## 6.41.2 Member Typedef Documentation

## 6.41.2.1 ReceiveCallback

```
typedef void(* daisy::UsbHandle::ReceiveCallback) (uint8_t *buff, uint32_t *len)
```

Function called upon reception of a buffer

## 6.41.3 Member Enumeration Documentation

## 6.41.3.1 UsbPeriph

```
enum daisy::UsbHandle::UsbPeriph
```

Specified which of the two USB Peripherals to initialize.

## Enumerator

FS_INTERNAL	Internal pin
FS_EXTERNAL	FS External D+ pin is Pin 38 (GPIO32). FS External D- pin is Pin 37 (GPIO31)
FS_BOTH	Both

#### 6.41.4 Member Function Documentation

## 6.41.4.1 Init()

Initializes the specified peripheral(s) as USB CDC Devices

## **Parameters**

```
dev Device to initialize
```

## 6.41.4.2 SetReceiveCallback()

sets the callback to be called upon reception of new data

#### **Parameters**

```
cb Function to serve as callback
```

## 6.41.4.3 TransmitExternal()

Transmits a buffer of 'size' bytes from a USB port connected to the external USB Pins of the daisy seed.

## **Parameters**

buff	Buffer to transmit
size	Buffer size

## 6.41.4.4 TransmitInternal()

Transmits a buffer of 'size' bytes from the on board USB FS port.

#### **Parameters**

buff	Buffer to transmit
size	Buffer size

The documentation for this class was generated from the following file:

• src/hid\_usb.h

# 6.42 WAV\_FormatTypeDef Struct Reference

#include <util\_wav\_format.h>

## **Public Attributes**

- uint32\_t Chunkld
- uint32\_t FileSize
- uint32\_t FileFormat
- uint32\_t SubChunk1ID
- uint32\_t SubChunk1Size
- uint16\_t AudioFormat
- uint16\_t NbrChannels
- uint32\_t SampleRate
- uint32\_t ByteRate
- uint16\_t BlockAlign
- uint16\_t BitPerSample
- uint32\_t SubChunk2ID
- uint32\_t SubCHunk2Size

## 6.42.1 Detailed Description

Helper struct for handling the WAV file format

## 6.42.2 Member Data Documentation

#### 6.42.2.1 AudioFormat

uint16\_t WAV\_FormatTypeDef::AudioFormat

&

# 6.42.2.2 BitPerSample uint16\_t WAV\_FormatTypeDef::BitPerSample 6.42.2.3 BlockAlign uint16\_t WAV\_FormatTypeDef::BlockAlign 6.42.2.4 ByteRate uint32\_t WAV\_FormatTypeDef::ByteRate 6.42.2.5 Chunkld uint32\_t WAV\_FormatTypeDef::ChunkId 6.42.2.6 FileFormat uint32\_t WAV\_FormatTypeDef::FileFormat & 6.42.2.7 FileSize uint32\_t WAV\_FormatTypeDef::FileSize & 6.42.2.8 NbrChannels uint16\_t WAV\_FormatTypeDef::NbrChannels &

## Generated by Doxygen

&

6.42.2.9 SampleRate

uint32\_t WAV\_FormatTypeDef::SampleRate

## 6.42.2.10 SubChunk1ID

```
uint32_t WAV_FormatTypeDef::SubChunk1ID
```

&

#### 6.42.2.11 SubChunk1Size

```
uint32_t WAV_FormatTypeDef::SubChunk1Size
```

&

#### 6.42.2.12 SubChunk2ID

```
uint32_t WAV_FormatTypeDef::SubChunk2ID
```

&

#### 6.42.2.13 SubCHunk2Size

```
uint32_t WAV_FormatTypeDef::SubCHunk2Size
```

&

The documentation for this struct was generated from the following file:

• src/util\_wav\_format.h

# 6.43 daisy::WavFileInfo Struct Reference

```
#include <hid_wavplayer.h>
```

## **Public Attributes**

- WAV\_FormatTypeDef raw\_data
- char name [256]

## 6.43.1 Detailed Description

Struct containing details of Wav File.

## 6.43.2 Member Data Documentation

#### 6.43.2.1 name

```
char daisy::WavFileInfo::name[256]
```

#### Wav filename

## 6.43.2.2 raw\_data

```
WAV_FormatTypeDef daisy::WavFileInfo::raw_data
```

#### Raw wav data

The documentation for this struct was generated from the following file:

• src/hid\_wavplayer.h

# 6.44 daisy::WavPlayer Class Reference

```
#include <hid_wavplayer.h>
```

## **Public Member Functions**

- void Init ()
- int Open (size\_t sel)
- int Close ()
- int16 t Stream ()
- void Prepare ()
- void Restart ()
- void SetLooping (bool loop)
- bool GetLooping () const
- size\_t GetNumberFiles () const
- size\_t GetCurrentFile () const

## 6.44.1 Detailed Description

Wav Player that will load .wav files from an SD Card, and then provide a method of accessing the samples with double-buffering.

## 6.44.2 Member Function Documentation

```
6.44.2.1 Close()
int daisy::WavPlayer::Close ( )
Closes whatever file is currently open.
```

Returns

&

```
6.44.2.2 GetCurrentFile()
```

```
size_t daisy::WavPlayer::GetCurrentFile ( ) const [inline]
```

Returns

currently selected file.

## 6.44.2.3 GetLooping()

```
bool daisy::WavPlayer::GetLooping ( ) const [inline]
```

## Returns

Whether the WavPlayer is looping or not.

## 6.44.2.4 GetNumberFiles()

```
size_t daisy::WavPlayer::GetNumberFiles ( ) const [inline]
```

#### Returns

The number of files loaded by the WavPlayer

## 6.44.2.5 Init()

```
void daisy::WavPlayer::Init ( )
```

Initializes the WavPlayer, loading up to max\_files of wav files from an SD Card.

## 6.44.2.6 Open()

Opens the file at index sel for reading.

#### **Parameters**

```
sel File to open
```

## 6.44.2.7 Prepare()

```
void daisy::WavPlayer::Prepare ( )
```

Collects buffer for playback when needed.

## 6.44.2.8 Restart()

```
void daisy::WavPlayer::Restart ( )
```

Resets the playback position to the beginning of the file immediately

## 6.44.2.9 SetLooping()

Sets whether or not the current file will repeat after completing playback.

#### **Parameters**

```
loop To loop or not to loop.
```

## 6.44.2.10 Stream()

```
int16_t daisy::WavPlayer::Stream ( )
```

## Returns

The next sample if playing, otherwise returns 0

The documentation for this class was generated from the following file:

• src/hid\_wavplayer.h

# **Chapter 7**

# **File Documentation**

## 7.1 src/daisy.h File Reference

```
#include <stdint.h>
#include "daisy_core.h"
#include "sys_system.h"
#include "per_qspi.h"
#include "per_dac.h"
#include "per_gpio.h"
#include "per_i2c.h"
#include "per_sai.h"
#include "per_tim.h"
#include "dev_leddriver.h"
#include "dev_sdram.h"
#include "dev_sr_4021.h"
#include "hid_audio.h"
#include "util_unique_id.h"
#include "per_adc.h"
#include "per_uart.h"
#include "hid_midi.h"
#include "hid_encoder.h"
#include "hid_switch.h"
#include "hid ctrl.h"
#include "hid_gatein.h"
#include "hid_parameter.h"
#include "hid_usb.h"
#include "per_sdmmc.h"
#include "per_spi.h"
#include "hid_oled_display.h"
#include "hid_wavplayer.h"
#include "hid led.h"
#include "hid_rgb_led.h"
#include "dev_sr_595.h"
```

## Macros

- #define FBIPMAX 0.999985f
- #define FBIPMIN (-FBIPMAX)

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```
• #define S162F_SCALE 3.0517578125e-05f
```

- #define F2S16\_SCALE 32767.0f
- #define F2S24\_SCALE 8388608.0f
- #define S242F SCALE 1.192092896e-07f
- #define S24SIGN 0x800000

## **Functions**

- FORCE\_INLINE float s162f (int16\_t x)
- FORCE\_INLINE int16\_t f2s16 (float x)
- FORCE\_INLINE float s242f (int32\_t x)
- FORCE\_INLINE int32\_t f2s24 (float x)

#### 7.1.1 Macro Definition Documentation

## 7.1.1.1 F2S16\_SCALE

```
#define F2S16_SCALE 32767.0f
```

(2 \*\* 15) - 1

## 7.1.1.2 F2S24\_SCALE

#define F2S24\_SCALE 8388608.0f

2 \*\* 23

## 7.1.1.3 FBIPMAX

#define FBIPMAX 0.999985f

close to 1.0f-LSB at 16 bit

## 7.1.1.4 FBIPMIN

#define FBIPMIN (-FBIPMAX)

• (1 - LSB)

```
7.1.1.5 S162F_SCALE
#define S162F_SCALE 3.0517578125e-05f
1 / (2** 15)
7.1.1.6 S242F_SCALE
#define S242F_SCALE 1.192092896e-07f
1 / (2 ** 23)
7.1.1.7 S24SIGN
#define S24SIGN 0x800000
2 ** 23
7.1.2 Function Documentation
7.1.2.1 f2s16()
FORCE_INLINE int16_t f2s16 (
              float x )
& < close to 1.0f-LSB at 16 bit
< - (1 - LSB)
< close to 1.0f-LSB at 16 bit
< - (1 - LSB)
< close to 1.0f-LSB at 16 bit
< close to 1.0f-LSB at 16 bit
< (2 ** 15) - 1
7.1.2.2 f2s24()
FORCE_INLINE int32_t f2s24 (
              float x )
& < close to 1.0f-LSB at 16 bit
< - (1 - LSB)
< close to 1.0f-LSB at 16 bit
< - (1 - LSB)
< close to 1.0f-LSB at 16 bit
< close to 1.0f-LSB at 16 bit
< 2 ** 23
7.1.2.3 s162f()
FORCE_INLINE float s162f (
              int16_t x )
```

Scales float by 1/(2 \(^15\)

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#### **Parameters**

```
x Number to be scaled.
```

#### Returns

Scaled number.

```
< 1 / (2** 15)
```

## 7.1.2.4 s242f()

# 7.2 src/daisy\_core.h File Reference

```
#include <stdint.h>
#include <stdlib.h>
```

## **Classes**

• struct dsy\_gpio\_pin

## **Macros**

- #define DSY\_CORE\_HW\_H
- #define DMA\_BUFFER\_MEM\_SECTION \_\_attribute\_\_((section(".sram1\_bss")))
- #define DTCM\_MEM\_SECTION \_\_attribute\_\_((section(".dtcmram\_bss")))

## **Enumerations**

```
    enum dsy_gpio_port {
        DSY_GPIOA, DSY_GPIOB, DSY_GPIOC, DSY_GPIOD,
        DSY_GPIOE, DSY_GPIOF, DSY_GPIOG, DSY_GPIOH,
        DSY_GPIOI, DSY_GPIOJ, DSY_GPIOK,
        DSY_GPIO_LAST }
```

#### **Functions**

- FORCE\_INLINE float cube (float x)
- FORCE\_INLINE dsy\_gpio\_pin dsy\_pin (dsy\_gpio\_port port, uint8\_t pin)
- FORCE\_INLINE uint8\_t dsy\_pin\_cmp (dsy\_gpio\_pin \*a, dsy\_gpio\_pin \*b)

## 7.2.1 Macro Definition Documentation

## 7.2.1.1 DMA\_BUFFER\_MEM\_SECTION

```
#define DMA_BUFFER_MEM_SECTION __attribute__((section(".sram1_bss")))
```

Macro for area of memory that is configured as cacheless This should be used primarily for DMA buffers, and the like

#### 7.2.1.2 DSY\_CORE\_HW\_H

```
#define DSY_CORE_HW_H
```

&

## 7.2.1.3 DTCM\_MEM\_SECTION

```
#define DTCM_MEM_SECTION __attribute__((section(".dtcmram_bss")))
```

THE DTCM RAM section is also non-cached. However, is not suitable for DMA transfers. Performance is on par with internal SRAM w/ cache enabled.

## 7.2.2 Enumeration Type Documentation

## 7.2.2.1 dsy\_gpio\_port

```
enum dsy_gpio_port
```

Enums and a simple struct for defining a hardware pin on the MCU These correlate with the stm32 datasheet, and are used to configure the hardware.

## Enumerator

DSY_GPIOA	&
DSY_GPIOB	&
DSY_GPIOC	&
DSY_GPIOD	&
Generated BSB ox GPIOE	&
DSY_GPIOF	&
DSY_GPIOG	&
DSY GPIOH	&

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## 7.2.3 Function Documentation

## 7.2.3.1 cube()

```
FORCE_INLINE float cube ( float x )
```

Computes cube.

**Parameters** 

```
x Number to be cubed
```

Returns

x ^ 3

## 7.2.3.2 dsy\_pin()

Helper for creating pins from port/pin combos easily

## 7.2.3.3 dsy\_pin\_cmp()

Helper for testing sameness of two dsy\_gpio\_pins

Returns

1 if same, 0 if different

# 7.3 src/daisy\_field.h File Reference

Hardware defines and helpers for daisy field platform.

```
#include "daisy_seed.h"
```

#### **Classes**

· struct daisy::daisy\_field

#### **Macros**

```
• #define DSY FIELD BSP H
```

- #define SAMPLE RATE DSY AUDIO SAMPLE RATE
- #define SW\_1\_PIN 29
- #define SW\_2\_PIN 28
- #define SW 3 PIN 27
- #define GATE\_OUT\_PIN 0
- #define GATE\_IN\_PIN 1
- #define KB SW SR CS PIN 8
- #define KB\_SW\_SR\_CLK\_PIN 9
- #define KB\_SW\_SR\_D1\_PIN 10
- #define KB SW SR D2 PIN 11
- #define MIDI\_OUT\_PIN 14
- #define MIDI\_IN\_PIN 15
- #define MUX SEL 0 PIN 21
- #define MUX\_SEL\_1\_PIN 20
- #define MUX\_SEL\_2\_PIN 19
- #define MUX ADC PIN 16
- #define CV1\_ADC\_PIN 17
- #define CV2\_ADC\_PIN 18
- #define CV3\_ADC\_PIN 23
- #define CV4 ADC PIN 22
- #define LED\_DRIVER\_I2C i2c1\_handle

#### **Enumerations**

```
enum { daisy::SW_2, daisy::SW_1, daisy::SW_3, daisy::SW_LAST }
enum {
    daisy::KNOB_1, daisy::KNOB_3, daisy::KNOB_5, daisy::KNOB_2,
    daisy::KNOB_4, daisy::KNOB_6, daisy::KNOB_7, daisy::KNOB_8,
    daisy::KNOB_LAST }
enum {
    CV_1, daisy::CV_2, daisy::CV_3, daisy::CV_4,
    daisy::CV_LAST }
enum {
    daisy::LED_KEY_A8, daisy::LED_KEY_A7, daisy::LED_KEY_A6, daisy::LED_KEY_A5,
    daisy::LED_KEY_A4, daisy::LED_KEY_A3, daisy::LED_KEY_A2, daisy::LED_KEY_A1,
    daisy::LED_KEY_B1, daisy::LED_KEY_B2, daisy::LED_KEY_B3, daisy::LED_KEY_B4,
    daisy::LED_KEY_B5, daisy::LED_KEY_B6, daisy::LED_KEY_B7, daisy::LED_KEY_B8,
    daisy::LED_KNOB_1, daisy::LED_KNOB_2, daisy::LED_KNOB_3, daisy::LED_KNOB_4,
    daisy::LED_SW_1, daisy::LED_SW_2, daisy::LED_LAST }
```

#### **Functions**

FORCE\_INLINE void daisy::daisy\_field\_init (daisy\_field \*p)

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## 7.3.1 Detailed Description

Hardware defines and helpers for daisy field platform.

## 7.3.2 Macro Definition Documentation

```
7.3.2.1 CV1_ADC_PIN
```

#define CV1\_ADC\_PIN 17

&

## 7.3.2.2 CV2\_ADC\_PIN

#define CV2\_ADC\_PIN 18

&

## 7.3.2.3 CV3\_ADC\_PIN

#define CV3\_ADC\_PIN 23

&

## 7.3.2.4 CV4\_ADC\_PIN

#define CV4\_ADC\_PIN 22

&

## 7.3.2.5 DSY\_FIELD\_BSP\_H

#define DSY\_FIELD\_BSP\_H

&

## 7.3.2.6 GATE\_IN\_PIN

#define GATE\_IN\_PIN 1

&

```
7.3.2.7 GATE_OUT_PIN
#define GATE_OUT_PIN 0
7.3.2.8 KB_SW_SR_CLK_PIN
#define KB_SW_SR_CLK_PIN 9
7.3.2.9 KB_SW_SR_CS_PIN
#define KB_SW_SR_CS_PIN 8
7.3.2.10 KB_SW_SR_D1_PIN
#define KB_SW_SR_D1_PIN 10
7.3.2.11 KB_SW_SR_D2_PIN
#define KB_SW_SR_D2_PIN 11
&
7.3.2.12 LED DRIVER I2C
#define LED_DRIVER_I2C i2c1_handle
&
7.3.2.13 MIDI_IN_PIN
#define MIDI_IN_PIN 15
&
7.3.2.14 MIDI_OUT_PIN
#define MIDI_OUT_PIN 14
```

```
7.3.2.15 MUX_ADC_PIN
#define MUX_ADC_PIN 16
&
7.3.2.16 MUX_SEL_0_PIN
#define MUX_SEL_0_PIN 21
7.3.2.17 MUX_SEL_1_PIN
#define MUX_SEL_1_PIN 20
7.3.2.18 MUX_SEL_2_PIN
#define MUX_SEL_2_PIN 19
7.3.2.19 SAMPLE_RATE
#define SAMPLE_RATE DSY_AUDIO_SAMPLE_RATE
7.3.2.20 SW_1_PIN
#define SW_1_PIN 29
7.3.2.21 SW_2_PIN
#define SW_2_PIN 28
7.3.2.22 SW_3_PIN
#define SW_3_PIN 27
&
7.3.3 Enumeration Type Documentation
7.3.3.1 anonymous enum
```

anonymous enum

enums for controls, etc.

# Enumerator

SW_2	tactile switch
SW_1	tactile switch
SW_3	toggle
SW_LAST	&

# 7.3.3.2 anonymous enum

anonymous enum

All knobs connect to ADC1\_INP10 via CD4051 mux

#### Enumerator

KNOB_1	&
KNOB_3	&
KNOB_5	&
KNOB_2	&
KNOB_4	&
KNOB_6	&
KNOB_7	&
KNOB_8	&
KNOB_LAST	&

# 7.3.3.3 anonymous enum

anonymous enum

#### Enumerator

CV_2	Connected to ADC1_INP17
CV_3	Connected to ADC1_INP15
CV_4	Connected to ADC1_INP4
CV_LAST	Connected to ADC1_INP11 &

# 7.3.3.4 anonymous enum

anonymous enum

# Enumerator

LED_KEY_A8	&
LED_KEY_A7	&
LED_KEY_A6	&
LED_KEY_A5	&
LED_KEY_A4	&
LED_KEY_A3	&
LED_KEY_A2	&
LED_KEY_A1	&
LED_KEY_B1	&
LED_KEY_B2	&
LED_KEY_B3	&
LED_KEY_B4	&
LED_KEY_B5	&
LED_KEY_B6	&
LED_KEY_B7	&
LED_KEY_B8	&
LED_KNOB↔	&
_1	
LED_KNOB↔	&
	&
LED_KNOB↔ _2	
LED_KNOB↔ _2  LED_KNOB↔ _3  LED_KNOB↔	&
LED_KNOB← _2 LED_KNOB← _3 LED_KNOB← _4	&
LED_KNOB↔ _2  LED_KNOB↔ _3  LED_KNOB↔ _4  LED_KNOB↔ _5  LED_KNOB↔	& & &
LED_KNOB↔ _2  LED_KNOB↔ _3  LED_KNOB↔ _4  LED_KNOB↔ _5  LED_KNOB↔ _6  LED_KNOB↔ _7  LED_KNOB↔ _7  LED_KNOB↔ _8	& & & &
LED_KNOB↔ _2  LED_KNOB↔ _3  LED_KNOB↔ _4  LED_KNOB↔ _5  LED_KNOB↔ _6  LED_KNOB↔ _7  LED_KNOB↔	& & & & &
LED_KNOB↔ _2  LED_KNOB↔ _3  LED_KNOB↔ _4  LED_KNOB↔ _5  LED_KNOB↔ _6  LED_KNOB↔ _7  LED_KNOB↔ _7  LED_KNOB↔ _8	& & & & & & & & & & & & & & & & & & &

# 7.3.4 Function Documentation

# 7.3.4.1 daisy\_field\_init()

```
FORCE_INLINE void daisy::daisy_field_init ( \label{eq:daisy_field} {\tt daisy\_field} \, * \, p \, )
```

# Initializes daisy field

# **Parameters**

p daisy_field struct to initialize		
< &		
< &		
< &		
< &		
< &		
< &		
< &		
< &		
< &		
< &		
< &		
< &		
< &		
< &		
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< &		
< &		

# 7.4 src/daisy\_patch.h File Reference

#include "daisy\_seed.h"

# Classes

• class daisy::DaisyPatch

Class that handles initializing all of the hardware specific to the Daisy Patch Board. Helper funtions are also in place to provide easy access to built-in controls and peripherals.

# 7.5 src/daisy\_petal.h File Reference

```
#include "daisy_seed.h"
```

#### Classes

· class daisy::DaisyPetal

Helpers and hardware definitions for daisy petal.

#### Macros

• #define DSY\_PETAL\_H

#### 7.5.1 Macro Definition Documentation

#### 7.5.1.1 DSY\_PETAL\_H

```
#define DSY_PETAL_H
```

&

# 7.6 src/daisy\_pod.h File Reference

```
#include "daisy_seed.h"
```

# Classes

· class daisy::DaisyPod

Class that handles initializing all of the hardware specific to the Daisy Patch Board. Helper funtions are also in place to provide easy access to built-in controls and peripherals.

# 7.7 src/daisy\_seed.h File Reference

```
#include "daisy.h"
```

#### Classes

· class daisy::DaisySeed

This is the higher-level interface for the Daisy board.
All basic peripheral configuration/initialization is setup here.

# 7.8 src/dev\_codec\_ak4556.h File Reference

Driver for the AK4556 Stereo Codec.

```
#include "daisy_core.h"
```

#### **Functions**

• void codec\_ak4556\_init (dsy\_gpio\_pin reset\_pin)

#### 7.8.1 Detailed Description

Driver for the AK4556 Stereo Codec.

### 7.8.2 Function Documentation

```
7.8.2.1 codec_ak4556_init()
```

#### Resets the AK4556

#### **Parameters**

reset\_pin | should be a dsy\_gpio\_pin that is connected to the RST pin of the AK4556

# 7.9 src/dev\_codec\_pcm3060.h File Reference

Driver for the PCM3060 Codec.

```
#include "per_i2c.h"
```

# **Functions**

void codec\_pcm3060\_init (dsy\_i2c\_handle \*hi2c)

# 7.9.1 Detailed Description

Driver for the PCM3060 Codec.

#### 7.9.2 Function Documentation

# 7.9.2.1 codec\_pcm3060\_init()

#### Resets the PCM060

#### **Parameters**

```
*hi2c array of pins handling i2c?
```

# 7.10 src/dev\_codec\_wm8731.h File Reference

Driver for the WM8731 Codec.

```
#include <stddef.h>
#include "per_sai.h"
#include "per_i2c.h"
```

#### **Functions**

- uint8\_t codec\_wm8731\_init (dsy\_i2c\_handle \*hi2c, uint8\_t mcu\_is\_master, int32\_t sample\_rate, uint8\_←
  t bitdepth)
- uint8\_t codec\_wm8731\_enter\_bypass (dsy\_i2c\_handle \*hi2c)
- uint8\_t codec\_wm8731\_exit\_bypass (dsy\_i2c\_handle \*hi2c)

# 7.10.1 Detailed Description

Driver for the WM8731 Codec.

# 7.10.2 Function Documentation

# 7.10.2.1 codec\_wm8731\_enter\_bypass()

Put codec into bypass mode

#### **Parameters**

```
*hi2c pins handling i2c
```

#### 7.10.2.2 codec\_wm8731\_exit\_bypass()

```
\label{eq:codec_wm8731_exit_bypass (} $$ dsy_i2c_handle * hi2c )
```

Take codec out of bypass mode

#### **Parameters**

```
*hi2c pins handling i2c
```

# 7.10.2.3 codec\_wm8731\_init()

#### Resets the WM8731

#### **Parameters**

*hi2c	array of pins handling i2c?
mcu_is_master	&
sample_rate	Sample rate to run codec at
bitdepth	Bit depth to run codec at

# 7.11 src/dev\_codec\_wm8731\_frame.h File Reference

WM8731 Codec framework.

```
#include <stddef.h>
```

#### **Classes**

• struct codec\_frame\_t

# **Typedefs**

• typedef void(\* sa\_audio\_callback) (codec\_frame\_t \*, codec\_frame\_t \*, size\_t)

# 7.11.1 Detailed Description

WM8731 Codec framework.

# 7.11.2 Typedef Documentation

```
7.11.2.1 sa_audio_callback
```

```
typedef void(* sa_audio_callback) (codec_frame_t *, codec_frame_t *, size_t)
```

&

# 7.12 src/dev\_flash\_IS25LP064A.h File Reference

IS25LP08D Commands.

#### **Macros**

- #define IS25LP064A H
- #define IS25LP064A FLASH SIZE 0x800000
- #define IS25LP064A SECTOR SIZE 0x10000
- #define IS25LP064A SUBSECTOR SIZE 0x1000
- #define IS25LP064A\_PAGE\_SIZE 0x100
- #define IS25LP064A DUMMY CYCLES READ QUAD 8
- #define IS25LP064A\_DUMMY\_CYCLES\_READ 8
- #define IS25LP064A\_DUMMY\_CYCLES\_READ\_DTR 6
- #define IS25LP064A DUMMY CYCLES READ QUAD DTR 6
- #define IS25LP064A DIE ERASE MAX TIME 460000
- #define IS25LP064A\_SECTOR\_ERASE\_MAX\_TIME 1000
- #define IS25LP064A\_SUBSECTOR\_ERASE\_MAX\_TIME 400
- #define RESET ENABLE CMD 0x66
- #define RESET\_MEMORY\_CMD 0x99
- #define READ ID CMD 0x9E
- #define READ\_ID\_CMD2 0x9F
- #define MULTIPLE\_IO\_READ\_ID\_CMD 0xAF
- #define READ\_SERIAL\_FLASH\_DISCO\_PARAM\_CMD 0x5A
- #define READ\_CMD 0x03
- #define READ\_4\_BYTE\_ADDR\_CMD 0x13
- #define FAST READ CMD 0x0B
- #define FAST READ DTR CMD 0x0D
- #define FAST READ 4 BYTE ADDR CMD 0x0C
- #define DUAL OUT FAST READ CMD 0x3B
- #define DUAL\_OUT\_FAST\_READ\_DTR\_CMD 0x3D
- #define DUAL OUT FAST READ 4 BYTE ADDR CMD 0x3C
- #define DUAL INOUT FAST READ CMD 0xBB
- #define DUAL\_INOUT\_FAST\_READ\_DTR\_CMD 0xBD
- #define DUAL\_INOUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD 0xBC
- #define QUAD\_OUT\_FAST\_READ\_CMD 0x6B
- #define QUAD\_OUT\_FAST\_READ\_DTR\_CMD 0x0D
- #define QUAD\_OUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD 0x6C
- #define QUAD\_INOUT\_FAST\_READ\_CMD 0xEB
- #define QUAD INOUT FAST READ DTR CMD 0xED
- #define QUAD\_INOUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD 0xEC
- #define WRITE ENABLE CMD 0x06
- #define WRITE\_DISABLE\_CMD 0x04
- #define READ STATUS REG CMD 0x05
- #define WRITE\_STATUS\_REG\_CMD 0x01
- #define READ\_LOCK\_REG\_CMD 0xE8
- #define WRITE LOCK REG CMD 0xE5
- #define READ\_FLAG\_STATUS\_REG\_CMD 0x70
- #define CLEAR FLAG STATUS REG CMD 0x50
- #define READ\_NONVOL\_CFG\_REG\_CMD 0xB5
- #define WRITE\_NONVOL\_CFG\_REG\_CMD 0xB1
- #define READ\_READ\_PARAM\_REG\_CMD 0x61
- #define WRITE\_READ\_PARAM\_REG\_CMD 0xC0#define READ\_ENHANCED\_VOL\_CFG\_REG\_CMD 0x81
- #define WRITE\_ENHANCED\_VOL\_CFG\_REG\_CMD 0x85
- #define READ EXT ADDR REG CMD 0xC8
- #define WRITE EXT ADDR REG CMD 0xC5
- #define PAGE PROG CMD 0x02
- #define PAGE\_PROG\_4\_BYTE\_ADDR\_CMD 0x12

- #define DUAL IN FAST PROG CMD 0xA2
- #define EXT\_DUAL\_IN\_FAST\_PROG\_CMD 0xD2
- #define QUAD IN FAST PROG\_CMD 0x32
- #define EXT\_QUAD\_IN\_FAST\_PROG\_CMD 0x38
- #define QUAD IN FAST PROG 4 BYTE ADDR CMD 0x34
- #define SUBSECTOR ERASE CMD 0xd7
- #define SUBSECTOR ERASE QPI CMD 0x20
- #define SUBSECTOR ERASE 4 BYTE ADDR CMD 0x21
- #define SECTOR ERASE CMD 0xD8
- #define SECTOR ERASE 4 BYTE ADDR CMD 0xDC
- #define BLOCK ERASE 32K CMD 0x52
- #define DIE\_ERASE\_CMD 0xC4
- #define PROG ERASE RESUME CMD 0x7A
- #define PROG ERASE SUSPEND CMD 0x75
- #define READ OTP ARRAY CMD 0x4B
- #define PROG\_OTP\_ARRAY\_CMD 0x42
- #define ENTER\_4\_BYTE\_ADDR\_MODE\_CMD 0xB7
- #define EXIT 4 BYTE ADDR MODE CMD 0xE9
- #define ENTER QUAD CMD 0x35
- #define EXIT QUAD CMD 0xF5
- #define IS25LP064A SR WIP ((uint8 t)0x01)

#### IS25LP08D Registers.

- #define IS25LP064A SR WREN ((uint8 t)0x02)
- #define IS25LP064A SR SRWREN ((uint8 t)0x80)
- #define IS25LP064A\_SR\_QE ((uint8\_t)0x40)
- #define IS25LP064A\_NVCR\_NBADDR ((uint16\_t)0x0001)
- #define IS25LP064A\_NVCR\_SEGMENT ((uint16\_t)0x0002)
- #define IS25LP064A\_NVCR\_DUAL ((uint16\_t)0x0004)
- #define IS25LP064A\_NVCR\_QUAB ((uint16\_t)0x0008)
- #define IS25LP064A\_NVCR\_RH ((uint16\_t)0x0010)
- #define IS25LP064A\_NVCR\_DTRP ((uint16\_t)0x0020)
- #define IS25LP064A\_NVCR\_ODS ((uint16\_t)0x01C0)
- #define IS25LP064A NVCR XIP ((uint16 t)0x0E00)
- #define IS25LP064A NVCR NB DUMMY ((uint16 t)0xF000)
- #define IS25LP064A\_VCR\_WRAP ((uint8\_t)0x03)
- #define IS25LP064A VCR XIP ((uint8 t)0x08)
- #define IS25LP064A VCR NB DUMMY ((uint8 t)0xF0)
- #define IS25LP064A EAR HIGHEST SE ((uint8 t)0x03)
- #define IS25LP064A EAR THIRD SEG ((uint8 t)0x02)
- #define IS25LP064A\_EAR\_SECOND\_SEG ((uint8\_t)0x01)
- #define IS25LP064A EAR LOWEST SEG ((uint8 t)0x00)
- #define 1025E1 00+7/\_E7/11\_E07/E01\_0Ed ((dinto\_t)0x00
- #define IS25LP064A\_EVCR\_ODS ((uint8\_t)0x07)
- #define IS25LP064A\_EVCR\_RH ((uint8\_t)0x10)
- #define IS25LP064A\_EVCR\_DTRP ((uint8\_t)0x20)
- #define IS25LP064A\_EVCR\_DUAL ((uint8\_t)0x40)
- #define IS25LP064A\_EVCR\_QUAD ((uint8\_t)0x80)
- #define IS25LP064A\_FSR\_NBADDR ((uint8\_t)0x01)
- #define IS25LP064A\_FSR\_PRERR ((uint8\_t)0x02)
- #define IS25LP064A\_FSR\_PGSUS ((uint8\_t)0x04)
- #define IS25LP064A\_FSR\_PGERR ((uint8\_t)0x10)
- #define IS25LP064A\_FSR\_ERERR ((uint8\_t)0x20)
- #define IS25LP064A\_FSR\_ERSUS ((uint8\_t)0x40)
- #define IS25LP064A FSR READY ((uint8 t)0x80)

# 7.12.1 Detailed Description

IS25LP08D Commands.

#### 7.12.2 Macro Definition Documentation

#### 7.12.2.1 BLOCK\_ERASE\_32K\_CMD

 ${\tt \#define~BLOCK\_ERASE\_32K\_CMD~0x52}$ 

&

# 7.12.2.2 CLEAR\_FLAG\_STATUS\_REG\_CMD

#define CLEAR\_FLAG\_STATUS\_REG\_CMD 0x50

&

# 7.12.2.3 DIE\_ERASE\_CMD

#define DIE\_ERASE\_CMD 0xC4

&

#### 7.12.2.4 DUAL\_IN\_FAST\_PROG\_CMD

#define DUAL\_IN\_FAST\_PROG\_CMD 0xA2

&

# 7.12.2.5 DUAL\_INOUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD

#define DUAL\_INOUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD 0xBC

&

# 7.12.2.6 DUAL\_INOUT\_FAST\_READ\_CMD

#define DUAL\_INOUT\_FAST\_READ\_CMD 0xBB

&

```
7.12.2.7 DUAL_INOUT_FAST_READ_DTR_CMD
#define DUAL_INOUT_FAST_READ_DTR_CMD 0xBD
7.12.2.8 DUAL_OUT_FAST_READ_4_BYTE_ADDR_CMD
#define DUAL_OUT_FAST_READ_4_BYTE_ADDR_CMD 0x3C
7.12.2.9 DUAL_OUT_FAST_READ_CMD
#define DUAL_OUT_FAST_READ_CMD 0x3B
7.12.2.10 DUAL_OUT_FAST_READ_DTR_CMD
#define DUAL_OUT_FAST_READ_DTR_CMD 0x3D
7.12.2.11 ENTER_4_BYTE_ADDR_MODE_CMD
#define ENTER_4_BYTE_ADDR_MODE_CMD 0xB7
4-byte Address Mode Operations
7.12.2.12 ENTER QUAD CMD
#define ENTER_QUAD_CMD 0x35
Quad Operations
7.12.2.13 EXIT_4_BYTE_ADDR_MODE_CMD
#define EXIT_4_BYTE_ADDR_MODE_CMD 0xE9
&
7.12.2.14 EXIT_QUAD_CMD
```

#define EXIT\_QUAD\_CMD 0xF5

&

# 7.12.2.15 EXT\_DUAL\_IN\_FAST\_PROG\_CMD #define EXT\_DUAL\_IN\_FAST\_PROG\_CMD 0xD2 & 7.12.2.16 EXT\_QUAD\_IN\_FAST\_PROG\_CMD #define EXT\_QUAD\_IN\_FAST\_PROG\_CMD 0x38 7.12.2.17 FAST\_READ\_4\_BYTE\_ADDR\_CMD #define FAST\_READ\_4\_BYTE\_ADDR\_CMD 0x0C 7.12.2.18 FAST\_READ\_CMD #define FAST\_READ\_CMD 0x0B 7.12.2.19 FAST\_READ\_DTR\_CMD #define FAST\_READ\_DTR\_CMD 0x0D & 7.12.2.20 IS25LP064A DIE ERASE MAX TIME #define IS25LP064A\_DIE\_ERASE\_MAX\_TIME 460000 & 7.12.2.21 IS25LP064A\_DUMMY\_CYCLES\_READ #define IS25LP064A\_DUMMY\_CYCLES\_READ 8 & 7.12.2.22 IS25LP064A\_DUMMY\_CYCLES\_READ\_DTR

Generated by Doxygen

&

#define IS25LP064A\_DUMMY\_CYCLES\_READ\_DTR 6

```
7.12.2.23 IS25LP064A_DUMMY_CYCLES_READ_QUAD
#define IS25LP064A_DUMMY_CYCLES_READ_QUAD 8
7.12.2.24 IS25LP064A_DUMMY_CYCLES_READ_QUAD_DTR
#define IS25LP064A_DUMMY_CYCLES_READ_QUAD_DTR 6
7.12.2.25 IS25LP064A_EAR_HIGHEST_SE
#define IS25LP064A_EAR_HIGHEST_SE ((uint8_t)0x03)
Select the Highest 128Mb segment
7.12.2.26 IS25LP064A_EAR_LOWEST_SEG
#define IS25LP064A_EAR_LOWEST_SEG ((uint8_t)0x00)
Select the Lowest 128Mb segment (default)
7.12.2.27 IS25LP064A_EAR_SECOND_SEG
#define IS25LP064A_EAR_SECOND_SEG ((uint8_t)0x01)
Select the Second 128Mb segment
7.12.2.28 IS25LP064A EAR THIRD SEG
#define IS25LP064A_EAR_THIRD_SEG ((uint8_t)0x02)
Select the Third 128Mb segment
7.12.2.29 IS25LP064A_EVCR_DTRP
#define IS25LP064A_EVCR_DTRP ((uint8_t)0x20)
Double transfer rate protocol
7.12.2.30 IS25LP064A_EVCR_DUAL
#define IS25LP064A_EVCR_DUAL ((uint8_t)0x40)
```

Dual I/O protocol

```
7.12.2.31 IS25LP064A_EVCR_ODS
#define IS25LP064A_EVCR_ODS ((uint8_t)0x07)
Output driver strength
7.12.2.32 IS25LP064A_EVCR_QUAD
#define IS25LP064A_EVCR_QUAD ((uint8_t)0x80)
Quad I/O protocol
7.12.2.33 IS25LP064A_EVCR_RH
#define IS25LP064A_EVCR_RH ((uint8_t)0x10)
Reset/hold
7.12.2.34 IS25LP064A_FLASH_SIZE
#define IS25LP064A_FLASH_SIZE 0x800000
2 * 8 MBits => 1 * 1MBytes => 1MBytes
7.12.2.35 IS25LP064A_FSR_ERERR
#define IS25LP064A_FSR_ERERR ((uint8_t)0x20)
Erase error
7.12.2.36 IS25LP064A_FSR_ERSUS
#define IS25LP064A_FSR_ERSUS ((uint8_t)0x40)
Erase operation suspended
#define IS25LP064A_FSR_NBADDR ((uint8_t)0x01)
3-bytes or 4-bytes addressing
```

# Program error

7.12.2.38 IS25LP064A\_FSR\_PGERR

#define IS25LP064A\_FSR\_PGERR ((uint8\_t)0x10)

# 7.12.2.39 IS25LP064A\_FSR\_PGSUS #define IS25LP064A\_FSR\_PGSUS ((uint8\_t)0x04) Program operation suspended 7.12.2.40 IS25LP064A\_FSR\_PRERR #define IS25LP064A\_FSR\_PRERR ((uint8\_t)0x02) Protection error #define IS25LP064A\_FSR\_READY ((uint8\_t)0x80) Ready or command in progress 7.12.2.42 IS25LP064A\_H #define IS25LP064A\_H 7.12.2.43 IS25LP064A\_NVCR\_DTRP #define IS25LP064A\_NVCR\_DTRP ((uint16\_t)0x0020) Double transfer rate protocol 7.12.2.44 IS25LP064A\_NVCR\_DUAL #define IS25LP064A\_NVCR\_DUAL ((uint16\_t)0x0004) Dual I/O protocol 7.12.2.45 IS25LP064A\_NVCR\_NB\_DUMMY

#define IS25LP064A\_NVCR\_NB\_DUMMY ((uint16\_t)0xF000)

Number of dummy clock cycles

# 

#define IS25LP064A\_NVCR\_NBADDR ((uint16\_t)0x0001)

### 3-bytes or 4-bytes addressing

#### 7.12.2.47 IS25LP064A\_NVCR\_ODS

#define IS25LP064A\_NVCR\_ODS ((uint16\_t)0x01C0)

Output driver strength

#### 7.12.2.48 IS25LP064A\_NVCR\_QUAB

#define IS25LP064A\_NVCR\_QUAB ((uint16\_t)0x0008)

Quad I/O protocol

# 7.12.2.49 IS25LP064A\_NVCR\_RH

#define IS25LP064A\_NVCR\_RH ((uint16\_t)0x0010)

Reset/hold

#### 7.12.2.50 IS25LP064A\_NVCR\_SEGMENT

#define IS25LP064A\_NVCR\_SEGMENT ((uint16\_t)0x0002)

Upper or lower 128Mb segment selected by default

#### 

#define IS25LP064A\_NVCR\_XIP ((uint16\_t)0x0E00)

XIP mode at power-on reset

#### 

#define IS25LP064A\_PAGE\_SIZE 0x100

2 \* 262144 pages of 256 bytes

#### 7.12.2.53 IS25LP064A\_SECTOR\_ERASE\_MAX\_TIME

#define IS25LP064A\_SECTOR\_ERASE\_MAX\_TIME 1000

&

# 

#define IS25LP064A\_SECTOR\_SIZE 0x10000

### 2 \* 1024 sectors of 64KBytes

```
7.12.2.55 IS25LP064A_SR_QE
#define IS25LP064A_SR_QE ((uint8_t)0x40)
&
7.12.2.56 IS25LP064A_SR_SRWREN
#define IS25LP064A_SR_SRWREN ((uint8_t)0x80)
Status register write enable/disable
7.12.2.57 IS25LP064A_SR_WIP
#define IS25LP064A_SR_WIP ((uint8_t)0x01)
IS25LP08D Registers.
Write in progress
7.12.2.58 IS25LP064A_SR_WREN
#define IS25LP064A_SR_WREN ((uint8_t)0x02)
Write enable latch
7.12.2.59 IS25LP064A_SUBSECTOR_ERASE_MAX_TIME
#define IS25LP064A_SUBSECTOR_ERASE_MAX_TIME 400
&
7.12.2.60 IS25LP064A_SUBSECTOR_SIZE
#define IS25LP064A_SUBSECTOR_SIZE 0x1000
2 * 16384 subsectors of 4kBytes
7.12.2.61 IS25LP064A_VCR_NB_DUMMY
#define IS25LP064A_VCR_NB_DUMMY ((uint8_t)0xF0)
```

Number of dummy clock cycles

```
7.12.2.62 IS25LP064A_VCR_WRAP
#define IS25LP064A_VCR_WRAP ((uint8_t)0x03)
Wrap
7.12.2.63 IS25LP064A_VCR_XIP
\#define IS25LP064A_VCR_XIP ((uint8_t)0x08)
XIP
7.12.2.64 MULTIPLE_IO_READ_ID_CMD
#define MULTIPLE_IO_READ_ID_CMD 0xAF
7.12.2.65 PAGE_PROG_4_BYTE_ADDR_CMD
#define PAGE_PROG_4_BYTE_ADDR_CMD 0x12
7.12.2.66 PAGE_PROG_CMD
#define PAGE_PROG_CMD 0x02
Program Operations
7.12.2.67 PROG_ERASE_RESUME_CMD
#define PROG_ERASE_RESUME_CMD 0x7A
&
7.12.2.68 PROG_ERASE_SUSPEND_CMD
#define PROG_ERASE_SUSPEND_CMD 0x75
&
7.12.2.69 PROG_OTP_ARRAY_CMD
#define PROG_OTP_ARRAY_CMD 0x42
&
```

```
7.12.2.70 QUAD_IN_FAST_PROG_4_BYTE_ADDR_CMD
#define QUAD_IN_FAST_PROG_4_BYTE_ADDR_CMD 0x34
7.12.2.71 QUAD_IN_FAST_PROG_CMD
#define QUAD_IN_FAST_PROG_CMD 0x32
7.12.2.72 QUAD_INOUT_FAST_READ_4_BYTE_ADDR_CMD
#define QUAD_INOUT_FAST_READ_4_BYTE_ADDR_CMD 0xEC
7.12.2.73 QUAD_INOUT_FAST_READ_CMD
#define QUAD_INOUT_FAST_READ_CMD 0xEB
7.12.2.74 QUAD_INOUT_FAST_READ_DTR_CMD
#define QUAD_INOUT_FAST_READ_DTR_CMD 0xED
&
7.12.2.75 QUAD_OUT_FAST_READ_4_BYTE_ADDR_CMD
#define QUAD_OUT_FAST_READ_4_BYTE_ADDR_CMD 0x6C
&
7.12.2.76 QUAD_OUT_FAST_READ_CMD
#define QUAD_OUT_FAST_READ_CMD 0x6B
&
7.12.2.77 QUAD_OUT_FAST_READ_DTR_CMD
```

#define QUAD\_OUT\_FAST\_READ\_DTR\_CMD 0x0D

&

# 7.12.2.78 READ\_4\_BYTE\_ADDR\_CMD #define READ\_4\_BYTE\_ADDR\_CMD 0x13 7.12.2.79 READ\_CMD #define READ\_CMD 0x03 **Read Operations** 7.12.2.80 READ\_ENHANCED\_VOL\_CFG\_REG\_CMD #define READ\_ENHANCED\_VOL\_CFG\_REG\_CMD 0x81 7.12.2.81 READ\_EXT\_ADDR\_REG\_CMD #define READ\_EXT\_ADDR\_REG\_CMD 0xC8 7.12.2.82 READ\_FLAG\_STATUS\_REG\_CMD #define READ\_FLAG\_STATUS\_REG\_CMD 0x70 & 7.12.2.83 READ\_ID\_CMD #define READ\_ID\_CMD 0x9E **Identification Operations** 7.12.2.84 READ\_ID\_CMD2 #define READ\_ID\_CMD2 0x9F & 7.12.2.85 READ\_LOCK\_REG\_CMD

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#define READ\_LOCK\_REG\_CMD 0xE8

```
7.12.2.86 READ_NONVOL_CFG_REG_CMD
#define READ_NONVOL_CFG_REG_CMD 0xB5
7.12.2.87 READ_OTP_ARRAY_CMD
#define READ_OTP_ARRAY_CMD 0x4B
One-Time Programmable Operations
7.12.2.88 READ_READ_PARAM_REG_CMD
#define READ_READ_PARAM_REG_CMD 0x61
7.12.2.89 READ_SERIAL_FLASH_DISCO_PARAM_CMD
#define READ_SERIAL_FLASH_DISCO_PARAM_CMD 0x5A
7.12.2.90 READ_STATUS_REG_CMD
#define READ_STATUS_REG_CMD 0x05
Register Operations
7.12.2.91 RESET ENABLE CMD
#define RESET_ENABLE_CMD 0x66
Reset Operations
7.12.2.92 RESET_MEMORY_CMD
#define RESET_MEMORY_CMD 0x99
```

# 7.12.2.93 SECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD

#define SECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD 0xDC

&

&

# 7.12.2.94 SECTOR\_ERASE\_CMD #define SECTOR\_ERASE\_CMD 0xD8 & 7.12.2.95 SUBSECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD #define SUBSECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD 0x21 7.12.2.96 SUBSECTOR\_ERASE\_CMD #define SUBSECTOR\_ERASE\_CMD 0xd7 **Erase Operations** 7.12.2.97 SUBSECTOR\_ERASE\_QPI\_CMD #define SUBSECTOR\_ERASE\_QPI\_CMD 0x20 7.12.2.98 WRITE\_DISABLE\_CMD #define WRITE\_DISABLE\_CMD 0x04 & 7.12.2.99 WRITE\_ENABLE\_CMD #define WRITE\_ENABLE\_CMD 0x06 Write Operations 7.12.2.100 WRITE\_ENHANCED\_VOL\_CFG\_REG\_CMD #define WRITE\_ENHANCED\_VOL\_CFG\_REG\_CMD 0x85 &

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7.12.2.101 WRITE\_EXT\_ADDR\_REG\_CMD

#define WRITE\_EXT\_ADDR\_REG\_CMD 0xC5

#### 7.12.2.102 WRITE\_LOCK\_REG\_CMD

#define WRITE\_LOCK\_REG\_CMD 0xE5

&

#### 7.12.2.103 WRITE\_NONVOL\_CFG\_REG\_CMD

#define WRITE\_NONVOL\_CFG\_REG\_CMD 0xB1

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#### 7.12.2.104 WRITE\_READ\_PARAM\_REG\_CMD

#define WRITE\_READ\_PARAM\_REG\_CMD 0xC0

&

#### 7.12.2.105 WRITE\_STATUS\_REG\_CMD

#define WRITE\_STATUS\_REG\_CMD 0x01

&

# 7.13 src/dev\_flash\_IS25LP080D.h File Reference

IS25LP08D Commands.

#### **Macros**

- #define IS25LP080D\_FLASH\_SIZE 0x100000
- #define IS25LP080D\_SECTOR\_SIZE 0x10000
- #define IS25LP080D\_SUBSECTOR\_SIZE 0x1000
- #define IS25LP080D\_PAGE\_SIZE 0x100
- #define IS25LP080D\_DUMMY\_CYCLES\_READ\_QUAD 8
- #define IS25LP080D\_DUMMY\_CYCLES\_READ 8
- #define IS25LP080D\_DUMMY\_CYCLES\_READ\_DTR 6
- #define IS25LP080D\_DUMMY\_CYCLES\_READ\_QUAD\_DTR 6
- #define IS25LP080D DIE ERASE MAX TIME 460000
- #define IS25LP080D\_SECTOR\_ERASE\_MAX\_TIME 1000
- #define IS25LP080D\_SUBSECTOR\_ERASE\_MAX\_TIME 400
- #define RESET\_ENABLE\_CMD 0x66
- #define RESET\_MEMORY\_CMD 0x99
- #define READ ID CMD 0x9E
- #define READ\_ID\_CMD2 0x9F
- #define MULTIPLE IO READ ID CMD 0xAF
- #define READ\_SERIAL\_FLASH\_DISCO\_PARAM\_CMD 0x5A

- #define READ CMD 0x03
- #define READ\_4\_BYTE\_ADDR\_CMD 0x13
- #define FAST\_READ\_CMD 0x0B
- #define FAST\_READ\_DTR\_CMD 0x0D
- #define FAST READ 4 BYTE ADDR CMD 0x0C
- #define DUAL\_OUT\_FAST\_READ\_CMD 0x3B
- #define DUAL OUT FAST READ DTR CMD 0x3D
- #define DUAL\_OUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD 0x3C
- #define DUAL\_INOUT\_FAST\_READ\_CMD 0xBB
- #define DUAL INOUT FAST READ DTR CMD 0xBD
- #define DUAL\_INOUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD 0xBC
- #define QUAD OUT FAST READ CMD 0x6B
- #define QUAD\_OUT\_FAST\_READ\_DTR\_CMD 0x0D
- #define QUAD OUT FAST READ 4 BYTE ADDR CMD 0x6C
- #define QUAD\_INOUT\_FAST\_READ\_CMD 0xEB
- #define QUAD INOUT FAST READ DTR CMD 0xED
- #define QUAD INOUT FAST READ 4 BYTE ADDR CMD 0xEC
- #define WRITE ENABLE CMD 0x06
- #define WRITE DISABLE CMD 0x04
- #define READ\_STATUS\_REG\_CMD 0x05
- #define WRITE\_STATUS\_REG\_CMD 0x01
- #define READ\_LOCK\_REG\_CMD 0xE8
- #define WRITE LOCK REG CMD 0xE5
- #define READ\_FLAG\_STATUS\_REG\_CMD 0x70
- #define CLEAR FLAG STATUS REG CMD 0x50
- #define READ\_NONVOL\_CFG\_REG\_CMD 0xB5
- #define WRITE\_NONVOL\_CFG\_REG\_CMD 0xB1
- #define READ\_READ\_PARAM\_REG\_CMD 0x61
- #define WRITE\_READ\_PARAM\_REG\_CMD 0xC0
- #define READ\_ENHANCED\_VOL\_CFG\_REG\_CMD 0x81
- #define WRITE\_ENHANCED\_VOL\_CFG\_REG\_CMD 0x85
- #define READ EXT ADDR REG CMD 0xC8
- #define WRITE\_EXT\_ADDR\_REG\_CMD 0xC5
- #define PAGE\_PROG\_CMD 0x02
- #define PAGE\_PROG\_4\_BYTE\_ADDR\_CMD 0x12
- #define DUAL\_IN\_FAST\_PROG\_CMD 0xA2
- #define EXT\_DUAL\_IN\_FAST\_PROG\_CMD 0xD2
- #define QUAD\_IN\_FAST\_PROG\_CMD 0x32
- #define EXT\_QUAD\_IN\_FAST\_PROG\_CMD 0x38
- #define QUAD\_IN\_FAST\_PROG\_4\_BYTE\_ADDR\_CMD 0x34
- #define SUBSECTOR ERASE CMD 0xd7
- #define SUBSECTOR\_ERASE\_QPI\_CMD 0x20
- #define SUBSECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD 0x21
- #define SECTOR\_ERASE\_CMD 0xD8
- #define SECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD 0xDC
- #define BLOCK ERASE 32K CMD 0x52
- #define DIE ERASE CMD 0xC4
- #define PROG\_ERASE\_RESUME\_CMD 0x7A
- #define PROG\_ERASE\_SUSPEND\_CMD 0x75
- #define READ\_OTP\_ARRAY\_CMD 0x4B
- #define PROG OTP ARRAY CMD 0x42
- #define ENTER\_4\_BYTE\_ADDR\_MODE\_CMD 0xB7
- #define EXIT\_4\_BYTE\_ADDR\_MODE\_CMD 0xE9
- #define ENTER\_QUAD\_CMD 0x35
- #define EXIT\_QUAD\_CMD 0xF5

- #define IS25LP080D\_SR\_WIP ((uint8\_t)0x01)
   IS25LP08D Registers.
- #define IS25LP080D\_SR\_WREN ((uint8\_t)0x02)
- #define IS25LP080D\_SR\_SRWREN ((uint8\_t)0x80)
- #define IS25LP080D\_SR\_QE ((uint8\_t)0x40)
- #define IS25LP080D\_NVCR\_NBADDR ((uint16\_t)0x0001)
- #define IS25LP080D NVCR SEGMENT ((uint16 t)0x0002)
- #define IS25LP080D NVCR DUAL ((uint16 t)0x0004)
- #define IS25LP080D\_NVCR\_QUAB ((uint16\_t)0x0008)
- #define IS25LP080D\_NVCR\_RH ((uint16\_t)0x0010)
- #define IS25LP080D\_NVCR\_DTRP ((uint16\_t)0x0020)
- #define IS25LP080D\_NVCR\_ODS ((uint16\_t)0x01C0)
- #define IS25LP080D\_NVCR\_XIP ((uint16\_t)0x0E00)
- #define IS25LP080D\_NVCR\_NB\_DUMMY ((uint16\_t)0xF000)
- #define IS25LP080D\_VCR\_WRAP ((uint8\_t)0x03)
- #define IS25LP080D VCR XIP ((uint8 t)0x08)
- #define IS25LP080D VCR NB DUMMY ((uint8 t)0xF0)
- #define IS25LP080D\_EAR\_HIGHEST\_SE ((uint8\_t)0x03)
- #define IS25LP080D\_EAR\_THIRD\_SEG ((uint8\_t)0x02)
- #define IS25LP080D\_EAR\_SECOND\_SEG ((uint8\_t)0x01)
- #define IS25LP080D\_EAR\_LOWEST\_SEG ((uint8\_t)0x00)
- #define IS25LP080D\_EVCR\_ODS ((uint8\_t)0x07)
- #define IS25LP080D EVCR RH ((uint8 t)0x10)
- #define IS25LP080D EVCR DTRP ((uint8 t)0x20)
- #define IS25LP080D EVCR DUAL ((uint8 t)0x40)
- #define IS25LP080D\_EVCR\_QUAD ((uint8\_t)0x80)
- #define IS25LP080D\_FSR\_NBADDR ((uint8\_t)0x01)
- #define IS25LP080D FSR PRERR ((uint8 t)0x02)
- #define IS25LP080D\_FSR\_PGSUS ((uint8\_t)0x04)
- #define IS25LP080D FSR PGERR ((uint8 t)0x10)
- #define IS25LP080D\_FSR\_ERERR ((uint8\_t)0x20)
- #define IS25LP080D FSR ERSUS ((uint8 t)0x40)
- #define IS25LP080D\_FSR\_READY ((uint8\_t)0x80)

# 7.13.1 Detailed Description

IS25LP08D Commands.

#### 7.13.2 Macro Definition Documentation

#### 7.13.2.1 BLOCK ERASE 32K CMD

#define BLOCK\_ERASE\_32K\_CMD 0x52

#### 7.13.2.2 CLEAR\_FLAG\_STATUS\_REG\_CMD

#define CLEAR\_FLAG\_STATUS\_REG\_CMD 0x50

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#### 7.13.2.3 DIE\_ERASE\_CMD

#define DIE\_ERASE\_CMD 0xC4

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# 7.13.2.4 DUAL\_IN\_FAST\_PROG\_CMD

#define DUAL\_IN\_FAST\_PROG\_CMD 0xA2

&

#### 7.13.2.5 DUAL\_INOUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD

#define DUAL\_INOUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD 0xBC

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#### 7.13.2.6 DUAL\_INOUT\_FAST\_READ\_CMD

#define DUAL\_INOUT\_FAST\_READ\_CMD 0xBB

&

#### 7.13.2.7 DUAL\_INOUT\_FAST\_READ\_DTR\_CMD

#define DUAL\_INOUT\_FAST\_READ\_DTR\_CMD 0xBD

&

# 7.13.2.8 DUAL\_OUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD

#define DUAL\_OUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD 0x3C

&

#### 7.13.2.9 DUAL\_OUT\_FAST\_READ\_CMD

#define DUAL\_OUT\_FAST\_READ\_CMD 0x3B

&

```
7.13.2.10 DUAL_OUT_FAST_READ_DTR_CMD
#define DUAL_OUT_FAST_READ_DTR_CMD 0x3D
7.13.2.11 ENTER_4_BYTE_ADDR_MODE_CMD
#define ENTER_4_BYTE_ADDR_MODE_CMD 0xB7
4-byte Address Mode Operations
7.13.2.12 ENTER_QUAD_CMD
#define ENTER_QUAD_CMD 0x35
Quad Operations
7.13.2.13 EXIT_4_BYTE_ADDR_MODE_CMD
#define EXIT_4_BYTE_ADDR_MODE_CMD 0xE9
7.13.2.14 EXIT_QUAD_CMD
#define EXIT_QUAD_CMD 0xF5
&
7.13.2.15 EXT_DUAL_IN_FAST_PROG_CMD
#define EXT_DUAL_IN_FAST_PROG_CMD 0xD2
&
7.13.2.16 EXT_QUAD_IN_FAST_PROG_CMD
#define EXT_QUAD_IN_FAST_PROG_CMD 0x38
&
7.13.2.17 FAST_READ_4_BYTE_ADDR_CMD
```

#define FAST\_READ\_4\_BYTE\_ADDR\_CMD 0x0C

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```
7.13.2.18 FAST_READ_CMD
#define FAST_READ_CMD 0x0B
&
7.13.2.19 FAST_READ_DTR_CMD
#define FAST_READ_DTR_CMD 0x0D
7.13.2.20 IS25LP080D_DIE_ERASE_MAX_TIME
#define IS25LP080D_DIE_ERASE_MAX_TIME 460000
&
7.13.2.21 IS25LP080D_DUMMY_CYCLES_READ
#define IS25LP080D_DUMMY_CYCLES_READ 8
7.13.2.22 IS25LP080D_DUMMY_CYCLES_READ_DTR
#define IS25LP080D_DUMMY_CYCLES_READ_DTR 6
&
7.13.2.23 IS25LP080D_DUMMY_CYCLES_READ_QUAD
#define IS25LP080D_DUMMY_CYCLES_READ_QUAD 8
&
7.13.2.24 IS25LP080D_DUMMY_CYCLES_READ_QUAD_DTR
#define IS25LP080D_DUMMY_CYCLES_READ_QUAD_DTR 6
&
7.13.2.25 IS25LP080D_EAR_HIGHEST_SE
#define IS25LP080D_EAR_HIGHEST_SE ((uint8_t)0x03)
Select the Highest 128Mb segment
```

```
7.13.2.26 IS25LP080D_EAR_LOWEST_SEG
#define IS25LP080D_EAR_LOWEST_SEG ((uint8_t)0x00)
Select the Lowest 128Mb segment (default)
7.13.2.27 IS25LP080D_EAR_SECOND_SEG
#define IS25LP080D_EAR_SECOND_SEG ((uint8_t)0x01)
Select the Second 128Mb segment
7.13.2.28 IS25LP080D_EAR_THIRD_SEG
#define IS25LP080D_EAR_THIRD_SEG ((uint8_t)0x02)
Select the Third 128Mb segment
7.13.2.29 IS25LP080D_EVCR_DTRP
#define IS25LP080D_EVCR_DTRP ((uint8_t)0x20)
Double transfer rate protocol
7.13.2.30 IS25LP080D_EVCR_DUAL
#define IS25LP080D_EVCR_DUAL ((uint8_t)0x40)
Dual I/O protocol
7.13.2.31 IS25LP080D_EVCR_ODS
#define IS25LP080D_EVCR_ODS ((uint8_t)0x07)
Output driver strength
7.13.2.32 IS25LP080D_EVCR_QUAD
#define IS25LP080D_EVCR_QUAD ((uint8_t)0x80)
Quad I/O protocol
7.13.2.33 IS25LP080D_EVCR_RH
#define IS25LP080D_EVCR_RH ((uint8_t)0x10)
```

Reset/hold

```
7.13.2.34 IS25LP080D_FLASH_SIZE
#define IS25LP080D_FLASH_SIZE 0x100000
2 * 8 \text{ MBits} => 1 * 1 \text{MBytes} => 1 \text{MBytes}
#define IS25LP080D_FSR_ERERR ((uint8_t)0x20)
Erase error
7.13.2.36 IS25LP080D_FSR_ERSUS
#define IS25LP080D_FSR_ERSUS ((uint8_t)0x40)
Erase operation suspended
#define IS25LP080D_FSR_NBADDR ((uint8_t)0x01)
3-bytes or 4-bytes addressing
7.13.2.38 IS25LP080D_FSR_PGERR
#define IS25LP080D_FSR_PGERR ((uint8_t)0x10)
Program error
#define IS25LP080D_FSR_PGSUS ((uint8_t)0x04)
Program operation suspended
#define IS25LP080D_FSR_PRERR ((uint8_t)0x02)
Protection error
```

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Ready or command in progress

#define IS25LP080D\_FSR\_READY ((uint8\_t)0x80)

# 7.13.2.42 IS25LP080D\_NVCR\_DTRP #define IS25LP080D\_NVCR\_DTRP ((uint16\_t)0x0020) Double transfer rate protocol 7.13.2.43 IS25LP080D\_NVCR\_DUAL #define IS25LP080D\_NVCR\_DUAL ((uint16\_t)0x0004) Dual I/O protocol 7.13.2.44 IS25LP080D\_NVCR\_NB\_DUMMY #define IS25LP080D\_NVCR\_NB\_DUMMY ((uint16\_t)0xF000) Number of dummy clock cycles #define IS25LP080D\_NVCR\_NBADDR ((uint16\_t)0x0001) 3-bytes or 4-bytes addressing 7.13.2.46 IS25LP080D\_NVCR\_ODS #define IS25LP080D\_NVCR\_ODS ((uint16\_t)0x01C0) Output driver strength 7.13.2.47 IS25LP080D\_NVCR\_QUAB

#define IS25LP080D\_NVCR\_QUAB ((uint16\_t)0x0008)

Quad I/O protocol

# 7.13.2.48 IS25LP080D\_NVCR\_RH

#define IS25LP080D\_NVCR\_RH ((uint16\_t)0x0010)

Reset/hold

### 7.13.2.49 IS25LP080D\_NVCR\_SEGMENT

#define IS25LP080D\_NVCR\_SEGMENT ((uint16\_t)0x0002)

Upper or lower 128Mb segment selected by default

```
#define IS25LP080D_NVCR_XIP ((uint16_t)0x0E00)
XIP mode at power-on reset
#define IS25LP080D_PAGE_SIZE 0x100
2 * 262144 pages of 256 bytes
7.13.2.52 IS25LP080D_SECTOR_ERASE_MAX_TIME
#define IS25LP080D_SECTOR_ERASE_MAX_TIME 1000
&
#define IS25LP080D_SECTOR_SIZE 0x10000
2 * 1024 sectors of 64KBytes
7.13.2.54 IS25LP080D_SR_QE
#define IS25LP080D_SR_QE ((uint8_t)0x40)
&
7.13.2.55 IS25LP080D_SR_SRWREN
#define IS25LP080D_SR_SRWREN ((uint8_t)0x80)
Status register write enable/disable
7.13.2.56 IS25LP080D_SR_WIP
#define IS25LP080D_SR_WIP ((uint8_t)0x01)
IS25LP08D Registers.
Status Register Write in progress
```

```
#define IS25LP080D_SR_WREN ((uint8_t)0x02)
Write enable latch
7.13.2.58 IS25LP080D_SUBSECTOR_ERASE_MAX_TIME
#define IS25LP080D_SUBSECTOR_ERASE_MAX_TIME 400
7.13.2.59 IS25LP080D_SUBSECTOR_SIZE
#define IS25LP080D_SUBSECTOR_SIZE 0x1000
2 * 16384 subsectors of 4kBytes
7.13.2.60 IS25LP080D_VCR_NB_DUMMY
#define IS25LP080D_VCR_NB_DUMMY ((uint8_t)0xF0)
Number of dummy clock cycles
#define IS25LP080D_VCR_WRAP ((uint8_t)0x03)
Wrap
7.13.2.62 IS25LP080D_VCR_XIP
#define IS25LP080D_VCR_XIP ((uint8_t)0x08)
XIP
7.13.2.63 MULTIPLE_IO_READ_ID_CMD
#define MULTIPLE_IO_READ_ID_CMD 0xAF
&
7.13.2.64 PAGE_PROG_4_BYTE_ADDR_CMD
#define PAGE_PROG_4_BYTE_ADDR_CMD 0x12
```

&

# 7.13.2.65 PAGE\_PROG\_CMD #define PAGE\_PROG\_CMD 0x02 **Program Operations** 7.13.2.66 PROG\_ERASE\_RESUME\_CMD #define PROG\_ERASE\_RESUME\_CMD 0x7A 7.13.2.67 PROG\_ERASE\_SUSPEND\_CMD #define PROG\_ERASE\_SUSPEND\_CMD 0x75 7.13.2.68 PROG\_OTP\_ARRAY\_CMD #define PROG\_OTP\_ARRAY\_CMD 0x42 7.13.2.69 QUAD\_IN\_FAST\_PROG\_4\_BYTE\_ADDR\_CMD #define QUAD\_IN\_FAST\_PROG\_4\_BYTE\_ADDR\_CMD 0x34 & 7.13.2.70 QUAD IN FAST\_PROG\_CMD #define QUAD\_IN\_FAST\_PROG\_CMD 0x32 & 7.13.2.71 QUAD\_INOUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD #define QUAD\_INOUT\_FAST\_READ\_4\_BYTE\_ADDR\_CMD 0xEC & 7.13.2.72 QUAD\_INOUT\_FAST\_READ\_CMD

Generated by Doxygen

&

#define QUAD\_INOUT\_FAST\_READ\_CMD 0xEB

```
7.13.2.73 QUAD_INOUT_FAST_READ_DTR_CMD
#define QUAD_INOUT_FAST_READ_DTR_CMD 0xED
&
7.13.2.74 QUAD_OUT_FAST_READ_4_BYTE_ADDR_CMD
#define QUAD_OUT_FAST_READ_4_BYTE_ADDR_CMD 0x6C
7.13.2.75 QUAD_OUT_FAST_READ_CMD
#define QUAD_OUT_FAST_READ_CMD 0x6B
7.13.2.76 QUAD_OUT_FAST_READ_DTR_CMD
#define QUAD_OUT_FAST_READ_DTR_CMD 0x0D
7.13.2.77 READ_4_BYTE_ADDR_CMD
#define READ_4_BYTE_ADDR_CMD 0x13
&
7.13.2.78 READ_CMD
#define READ_CMD 0x03
Read Operations
7.13.2.79 READ_ENHANCED_VOL_CFG_REG_CMD
#define READ_ENHANCED_VOL_CFG_REG_CMD 0x81
&
7.13.2.80 READ_EXT_ADDR_REG_CMD
#define READ_EXT_ADDR_REG_CMD 0xC8
```

# 7.13.2.81 READ\_FLAG\_STATUS\_REG\_CMD #define READ\_FLAG\_STATUS\_REG\_CMD 0x70

ŏ

## 7.13.2.82 READ\_ID\_CMD

#define READ\_ID\_CMD 0x9E

Identification Operations

## 7.13.2.83 READ\_ID\_CMD2

#define READ\_ID\_CMD2 0x9F

&

#### 7.13.2.84 READ\_LOCK\_REG\_CMD

#define READ\_LOCK\_REG\_CMD 0xE8

&

## 7.13.2.85 READ\_NONVOL\_CFG\_REG\_CMD

#define READ\_NONVOL\_CFG\_REG\_CMD 0xB5

&

## 7.13.2.86 READ\_OTP\_ARRAY\_CMD

#define READ\_OTP\_ARRAY\_CMD 0x4B

One-Time Programmable Operations

# 7.13.2.87 READ\_READ\_PARAM\_REG\_CMD

#define READ\_READ\_PARAM\_REG\_CMD 0x61

&

## 7.13.2.88 READ\_SERIAL\_FLASH\_DISCO\_PARAM\_CMD

#define READ\_SERIAL\_FLASH\_DISCO\_PARAM\_CMD 0x5A

## 7.13.2.89 READ\_STATUS\_REG\_CMD

#define READ\_STATUS\_REG\_CMD 0x05

**Register Operations** 

## 7.13.2.90 RESET\_ENABLE\_CMD

#define RESET\_ENABLE\_CMD 0x66

**Reset Operations** 

## 7.13.2.91 RESET\_MEMORY\_CMD

#define RESET\_MEMORY\_CMD 0x99

&

## 7.13.2.92 SECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD

#define SECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD 0xDC

&

## 7.13.2.93 SECTOR\_ERASE\_CMD

#define SECTOR\_ERASE\_CMD 0xD8

&

## 7.13.2.94 SUBSECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD

#define SUBSECTOR\_ERASE\_4\_BYTE\_ADDR\_CMD 0x21

&

# 7.13.2.95 SUBSECTOR\_ERASE\_CMD

#define SUBSECTOR\_ERASE\_CMD 0xd7

**Erase Operations** 

# 7.13.2.96 SUBSECTOR\_ERASE\_QPI\_CMD

#define SUBSECTOR\_ERASE\_QPI\_CMD 0x20

## 7.13.2.97 WRITE\_DISABLE\_CMD

#define WRITE\_DISABLE\_CMD 0x04

8

## 7.13.2.98 WRITE\_ENABLE\_CMD

#define WRITE\_ENABLE\_CMD 0x06

Write Operations

## 7.13.2.99 WRITE\_ENHANCED\_VOL\_CFG\_REG\_CMD

#define WRITE\_ENHANCED\_VOL\_CFG\_REG\_CMD 0x85

&

## 7.13.2.100 WRITE\_EXT\_ADDR\_REG\_CMD

#define WRITE\_EXT\_ADDR\_REG\_CMD 0xC5

&

# 7.13.2.101 WRITE\_LOCK\_REG\_CMD

#define WRITE\_LOCK\_REG\_CMD 0xE5

&

## 7.13.2.102 WRITE\_NONVOL\_CFG\_REG\_CMD

#define WRITE\_NONVOL\_CFG\_REG\_CMD 0xB1

&

# 7.13.2.103 WRITE\_READ\_PARAM\_REG\_CMD

#define WRITE\_READ\_PARAM\_REG\_CMD 0xC0

&

## 7.13.2.104 WRITE\_STATUS\_REG\_CMD

#define WRITE\_STATUS\_REG\_CMD 0x01

# 7.14 src/dev\_leddriver.h File Reference

Device driver for PCA9685 16-channel 12-bit PWM generator.

```
#include <stdint.h>
#include "per_i2c.h"
```

#### **Classes**

· struct color

#### **Macros**

- #define SA\_LED\_DRIVER\_H
- #define DSY\_LED\_DRIVER\_MAX\_DRIVERS 8

#### **Enumerations**

enum {
 LED\_COLOR\_RED, LED\_COLOR\_GREEN, LED\_COLOR\_BLUE, LED\_COLOR\_WHITE,
 LED\_COLOR\_PURPLE, LED\_COLOR\_CYAN, LED\_COLOR\_GOLD, LED\_COLOR\_OFF,
 LED\_COLOR\_LAST }

# **Functions**

- void dsy\_led\_driver\_init (dsy\_i2c\_handle \*dsy\_i2c, uint8\_t \*addr, uint8\_t addr\_cnt)
- void dsy\_led\_driver\_update ()
- void dsy\_led\_driver\_set\_led (uint8\_t idx, float bright)
- color \* dsy\_led\_driver\_color\_by\_name (uint8\_t name)

## 7.14.1 Detailed Description

Device driver for PCA9685 16-channel 12-bit PWM generator.

## 7.14.2 Macro Definition Documentation

## 7.14.2.1 DSY\_LED\_DRIVER\_MAX\_DRIVERS

```
#define DSY_LED_DRIVER_MAX_DRIVERS 8
```

## Maximum number of drivers

## 7.14.2.2 SA\_LED\_DRIVER\_H

```
#define SA_LED_DRIVER_H
```

Q.

# 7.14.3 Enumeration Type Documentation

## 7.14.3.1 anonymous enum

anonymous enum

## Different Led colors

#### Enumerator

LED_COLOR_RED	&
LED_COLOR_GREEN	&
LED_COLOR_BLUE	&
LED_COLOR_WHITE	&
LED_COLOR_PURPLE	&
LED_COLOR_CYAN	&
LED_COLOR_GOLD	&
LED_COLOR_OFF	&
LED_COLOR_LAST	&

## 7.14.4 Function Documentation

# 7.14.4.1 dsy\_led\_driver\_color\_by\_name()

Passing in one of the preset colors will return a pointer to a color struct

#### **Parameters**

name	Preset color

#### 7.14.4.2 dsy\_led\_driver\_init()

Initializes the LED Driver(s) on the specified I2C Bus

#### **Parameters**

*dsy_i2c	should be any dsy_i2c_handle with pins and speed configured.
addr	is either a pointer to 1 device address, or an array of addresses for multiple devices
addr_cnt	is the number of addresses passed in (use '1' for a single device)

## 7.14.4.3 dsy\_led\_driver\_set\_led()

sets the LED at the index to the specified brightness (0-1) Index is sequential so device 0 will have idx 0-15, while device 1 will have idx 16-31, etc.

## **Parameters**

idx	Index
bright	Brightness

#### 7.14.4.4 dsy\_led\_driver\_update()

```
void dsy_led_driver_update ( )
```

Updates the LED Driver with the values set using the set function Currently only updates one driver at a time due to the time it takes to update all of the devices. This can likely be set up to use DMA so that the function doesn't block for so long.

## 7.15 src/dev\_sdram.h File Reference

```
#include <stdint.h>
#include "daisy_core.h"
```

## Classes

· struct dsy\_sdram\_handle

#### **Macros**

- #define RAM AS4C16M16SA H
- #define DSY\_SDRAM\_DATA \_\_attribute\_\_((section(".sdram\_data")))
- #define DSY\_SDRAM\_BSS \_\_attribute\_\_((section(".sdram\_bss")))

#### **Enumerations**

- enum { DSY\_SDRAM\_OK, DSY\_SDRAM\_ERR }
- enum dsy\_sdram\_state { DSY\_SDRAM\_STATE\_ENABLE, DSY\_SDRAM\_STATE\_DISABLE, DSY\_SDR → AM STATE LAST }
- enum dsy\_sdram\_pin { DSY\_SDRAM\_PIN\_SDNWE, DSY\_SDRAM\_PIN\_LAST }

#### **Functions**

• uint8\_t dsy\_sdram\_init (dsy\_sdram\_handle \*dsy\_hsdram)

#### 7.15.1 Macro Definition Documentation

```
7.15.1.1 DSY_SDRAM_BSS
#define DSY_SDRAM_BSS __attribute__((section(".sdram_bss")))
Variables placed here will not be initialized.
Usage
E.g. int DSY_SDRAM_BSS uninitialized_var;

7.15.1.2 DSY_SDRAM_DATA
#define DSY_SDRAM_DATA __attribute__((section(".sdram_data")))
Usage:
E.g. int DSY_SDRAM_DATA initialized_var = 1;

7.15.1.3 RAM_AS4C16M16SA_H
#define RAM_AS4C16M16SA_H
```

SDRAM for 32MB AS4C16M16SA (and 64MB equivalent). Thanks to whoever this awesome person is: http-://main.lv/writeup/stm32f4\_sdram\_configuration.md The Init function is basically a copy and paste. He has references to timing, etc. RAM is configured at 100MHz (fastest possible on the MCU). To use these the .sdram\_data/\_bss sections must be configured correctly in the LINKER SCRIPT. using BSS is advised for most things, since the DATA section must also fit in flash in order to be initialized. Data section init not properly set up, as SDRAM is not initialized until after startup code.&

# 7.15.2 Enumeration Type Documentation

## 7.15.2.1 anonymous enum

anonymous enum

## Enumerator

DSY_SDRAM_OK	&
DSY_SDRAM_ERR	&

## 7.15.2.2 dsy\_sdram\_pin

enum dsy\_sdram\_pin

# This is PH5 on Daisy

## Enumerator

DSY_SDRAM_PIN_SDNWE	&
DSY_SDRAM_PIN_LAST	&

## 7.15.2.3 dsy\_sdram\_state

enum dsy\_sdram\_state

Determines whether chip is initialized, and activated.

## Enumerator

DSY_SDRAM_STATE_ENABLE	&
DSY_SDRAM_STATE_DISABLE	&
DSY_SDRAM_STATE_LAST	&

## 7.15.3 Function Documentation

#### 7.15.3.1 dsy\_sdram\_init()

Initializes the SDRAM peripheral

# 7.16 src/dev\_sr\_4021.h File Reference

Device driver for the CD4021. Bit-banged serial shift input.

```
#include "per_gpio.h"
```

# Classes

• struct dsy\_sr\_4021\_handle

#### **Macros**

- #define DEV\_SR\_4021\_H
- #define SR 4021 MAX PARALLEL 2
- #define SR\_4021\_MAX\_DAISYCHAIN 1

## **Enumerations**

```
    enum {
        DSY_SR_4021_PIN_CS, DSY_SR_4021_PIN_CLK, DSY_SR_4021_PIN_DATA, DSY_SR_4021_PIN_D →
        ATA2,
        DSY_SR_4021_PIN_LAST }
```

## **Functions**

- void dsy\_sr\_4021\_init (dsy\_sr\_4021\_handle \*sr)
- void dsy\_sr\_4021\_update (dsy\_sr\_4021\_handle \*sr)
- uint8\_t dsy\_sr\_4021\_state (dsy\_sr\_4021\_handle \*sr, uint8\_t idx)

## 7.16.1 Detailed Description

Device driver for the CD4021. Bit-banged serial shift input.

## 7.16.2 Macro Definition Documentation

## 7.16.2.1 DEV\_SR\_4021\_H

```
#define DEV_SR_4021_H
```

&

## 7.16.2.2 SR\_4021\_MAX\_DAISYCHAIN

```
#define SR_4021_MAX_DAISYCHAIN 1
```

fixed maximum for daisychained use

## 7.16.2.3 SR\_4021\_MAX\_PARALLEL

```
#define SR_4021_MAX_PARALLEL 2
```

Fixed maximums for parallel/daisychained use These could be expanded, but haven't been tested beyond this

# 7.16.3 Enumeration Type Documentation

## 7.16.3.1 anonymous enum

```
anonymous enum
```

Pins that need to be configured to use. DATA2 only needs to be set if num\_parallel is > 1

#### Enumerator

DSY_SR_4021_PIN_CS	CS Pin
DSY_SR_4021_PIN_CLK	CLK Pin
DSY_SR_4021_PIN_DATA	DATA pin
DSY_SR_4021_PIN_DATA2	DATA2 Pin, optional
DSY_SR_4021_PIN_LAST	Enum Last

#### 7.16.4 Function Documentation

## 7.16.4.1 dsy\_sr\_4021\_init()

```
void dsy_sr_4021_init ( \label{eq:dsy_sr_4021_handle} \ *\ sr\ )
```

Initialize CD4021 with settings from sr\_4021\_handle

#### **Parameters**

```
sr handle to initialize
```

#### 7.16.4.2 dsy\_sr\_4021\_state()

Returns the state of a pin at a given index.

#### **Parameters**

*sr	Handle containing desired pin
idx	Pin index

## 7.16.4.3 dsy\_sr\_4021\_update()

Fills internal states with CD4021 data states.

#### **Parameters**

\*sr Handle to update

# 7.17 src/dev\_sr\_595.h File Reference

```
#include "daisy_core.h"
#include "per_gpio.h"
```

#### **Classes**

• class ShiftRegister595

Device Driver for 8-bit shift register. CD74HC595 - 8-bit serial to parallel output shift.

#### **Variables**

• const size\_t kMaxSr595DaisyChain = 16

## 7.17.1 Variable Documentation

## 7.17.1.1 kMaxSr595DaisyChain

```
const size_t kMaxSr595DaisyChain = 16
```

Maximum Number of chained devices Connect device's QH' pin to the next chips serial input

# 7.18 src/fatfs.h File Reference

## fatfs support.

```
#include "ff.h"
#include "ff_gen_drv.h"
#include "util_sd_diskio.h"
```

## **Macros**

• #define \_\_fatfs\_H

## **Functions**

• void dsy\_fatfs\_init (void)

## **Variables**

- uint8\_t retSD
- char SDPath [4]
- FATFS SDFatFS
- FIL SDFile

## 7.18.1 Detailed Description

fatfs support.

## 7.18.2 Macro Definition Documentation

```
7.18.2.1 __fatfs_H
#define ___fatfs_H
7.18.3 Function Documentation
7.18.3.1 dsy_fatfs_init()
void dsy_fatfs_init (
            void )
&
7.18.4 Variable Documentation
7.18.4.1 retSD
uint8_t retSD
&
7.18.4.2 SDFatFS
FATES SDFatES
7.18.4.3 SDFile
FIL SDFile
&
7.18.4.4 SDPath
char SDPath[4]
```

#### 7.19 src/ffconf.h File Reference

```
#include "util_bsp_sd_diskio.h"
#include <stdlib.h>
```

#### **Macros**

- #define FFCONF 68300
- #define \_FS\_READONLY 0
- #define \_FS\_MINIMIZE 0
- #define \_USE\_STRFUNC 2
- #define \_USE\_FIND 0
- #define \_USE\_MKFS 1
- #define \_USE\_FASTSEEK 1
- #define USE EXPAND 0
- #define USE CHMOD 0
- #define \_USE\_LABEL 0
- #define \_USE\_FORWARD 0
- #define CODE PAGE 850
- #define USE LFN 1
- #define \_MAX\_LFN 255
- #define \_LFN\_UNICODE 0
- #define \_STRF\_ENCODE 3
- #define \_FS\_RPATH 0
- #define \_VOLUMES 1
- #define \_STR\_VOLUME\_ID 0
- #define \_VOLUME\_STRS
- #define \_MULTI\_PARTITION 0
- #define \_MIN\_SS 512
- #define \_MAX\_SS 512
- #define \_USE\_TRIM 0
- #define \_FS\_NOFSINFO 0
- #define \_FS\_TINY 0
- #define \_FS\_EXFAT 0
- #define \_FS\_NORTC 0
- #define \_NORTC\_MON 6
- #define \_NORTC\_MDAY 4
- #define \_NORTC\_YEAR 2015
- #define \_FS\_LOCK 2
- #define \_FS\_REENTRANT 0
- #define \_FS\_TIMEOUT 1000
- #define \_SYNC\_t osSemaphoreId
- #define ff\_malloc malloc
- #define ff\_free free

#### 7.19.1 Detailed Description

Further fatfs support.

## 7.19.2 Macro Definition Documentation

7.19.2.1 \_CODE\_PAGE

#define \_CODE\_PAGE 850

This option specifies the OEM code page to be used on the target system. / Incorrect setting of the code page can cause a file open failure. // 1 - ASCII (No extended character. Non-LFN cfg. only) / 437 - U.S. / 720 - Arabic / 737 - Greek / 771 - KBL / 775 - Baltic / 850 - Latin 1 / 852 - Latin 2 / 855 - Cyrillic / 857 - Turkish / 860 - Portuguese / 861 - Icelandic / 862 - Hebrew / 863 - Canadian French / 864 - Arabic / 865 - Nordic / 866 - Russian / 869 - Greek 2 / 932 - Japanese (DBCS) / 936 - Simplified Chinese (DBCS) / 949 - Korean (DBCS) / 950 - Traditional Chinese (DBCS)

7.19.2.2 \_FFCONF

#define \_FFCONF 68300

FatFs - Generic FAT file system module R0.12c (C)ChaN, 2017

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7.19.2.3 \_FS\_EXFAT

#define \_FS\_EXFAT 0

This option switches support of exFAT file system. (0:Disable or 1:Enable) / When enable exFAT, also LFN needs to be enabled. ( $\_$ USE $\_$ LFN >= 1) / Note that enabling exFAT discards C89 compatibility.

7.19.2.4 \_FS\_LOCK

#define \_FS\_LOCK 2

0:Disable or >=1:Enable The option \_FS\_LOCK switches file lock function to control duplicated file open / and illegal operation to open objects. This option must be 0 when \_FS\_READONLY / is 1. // 0: Disable file lock function. To avoid volume corruption, application program / should avoid illegal open, remove and rename to the open objects. / >0: Enable file lock function. The value defines how many files/sub-directories / can be opened simultaneously under file lock control. Note that the file / lock control is independent of re-entrancy.

#### 7.19.2.5 \_FS\_MINIMIZE

```
#define _FS_MINIMIZE 0
```

0 to 3 This option defines minimization level to remove some basic API functions. // 0: All basic functions are enabled. / 1: f\_stat(), f\_getfree(), f\_unlink(), f\_mkdir(), f\_truncate() and f\_rename() / are removed. / 2: f\_opendir(), f\_readdir() and f\_closedir() are removed in addition to 1. / 3: f\_lseek() function is removed in addition to 2.

## 7.19.2.6 \_FS\_NOFSINFO

```
#define _FS_NOFSINFO 0
```

0,1,2 or 3 If you need to know correct free space on the FAT32 volume, set bit 0 of this / option, and f\_getfree() function at first time after volume mount will force / a full FAT scan. Bit 1 controls the use of last allocated cluster number. // bit0=0: Use free cluster count in the FSINFO if available. / bit0=1: Do not trust free cluster count in the FSINFO. / bit1=0: Use last allocated cluster number in the FSINFO if available. / bit1=1: Do not trust last allocated cluster number in the FSINFO.

## 7.19.2.7 \_FS\_NORTC

```
#define _FS_NORTC 0
```

&

## 7.19.2.8 \_FS\_READONLY

```
#define _FS_READONLY 0
```

0:Read/Write or 1:Read only This option switches read-only configuration. (0:Read/Write or 1:Read-only) / Read-only configuration removes writing API functions, f\_write(), f\_sync(), / f\_unlink(), f\_mkdir(), f\_chmod(), f\_rename(), f\_truncate(), f\_getfree() / and optional writing functions as well.

## 7.19.2.9 \_FS\_REENTRANT

```
#define _FS_REENTRANT 0
```

0:Disable or 1:Enable

## 7.19.2.10 \_FS\_RPATH

```
#define _FS_RPATH 0
```

0 to 2 This option configures support of relative path. // 0: Disable relative path and remove related functions. / 1: Enable relative path. f\_chdir() and f\_chdrive() are available. / 2: f\_getcwd() function is available in addition to 1.

7.19.2.11 \_FS\_TIMEOUT

#define \_FS\_TIMEOUT 1000

Timeout period in unit of time ticks

7.19.2.12 \_FS\_TINY

#define \_FS\_TINY 0

0:Normal or 1:Tiny This option switches tiny buffer configuration. (0:Normal or 1:Tiny) / At the tiny configuration, size of file object (FIL) is reduced \_MAX\_SS bytes. / Instead of private sector buffer eliminated from the file object, common sector / buffer in the file system object (FATFS) is used for the file data transfer.

7.19.2.13 \_LFN\_UNICODE

#define \_LFN\_UNICODE 0

0:ANSI/OEM or 1:Unicode This option switches character encoding on the API. (0:ANSI/OEM or 1:UTF-16) / To use Unicode string for the path name, enable LFN and set \_LFN\_UNICODE = 1. / This option also affects behavior of string I/O functions.

7.19.2.14 MAX\_LFN

#define \_MAX\_LFN 255

Maximum LFN length to handle (12 to 255) The \_USE\_LFN switches the support of long file name (LFN). // 0: Disable support of LFN. \_MAX\_LFN has no effect. / 1: Enable LFN with static working buffer on the BSS. Always NOT thread-safe. / 2: Enable LFN with dynamic working buffer on the STACK. / 3: Enable LFN with dynamic working buffer on the HEAP. // To enable the LFN, Unicode handling functions (option/unicode.c) must be added / to the project. The working buffer occupies (\_MAX\_LFN + 1) \* 2 bytes and / additional 608 bytes at exFAT enabled. \_MAX\_LFN can be in range from 12 to 255. / It should be set 255 to support full featured LFN operations. / When use stack for the working buffer, take care on stack overflow. When use heap / memory for the working buffer, memory management functions, ff\_memalloc() and / ff\_memfree(), must be added to the project.

7.19.2.15 \_MAX\_SS

#define \_MAX\_SS 512

512, 1024, 2048 or 4096 These options configure the range of sector size to be supported. (512, 1024, / 2048 or 4096) Always set both 512 for most systems, all type of memory cards and / harddisk. But a larger value may be required for on-board flash memory and some / type of optical media. When \_MAX\_SS is larger than \_MIN\_SS, FatFs is configured / to variable sector size and GET\_SECTOR\_SIZE command must be implemented to the / disk ioctl() function.

7.19.2.16 \_MIN\_SS

#define \_MIN\_SS 512

512, 1024, 2048 or 4096

#### 7.19.2.17 \_MULTI\_PARTITION

```
#define _MULTI_PARTITION 0
```

0:Single partition, 1:Multiple partition This option switches support of multi-partition on a physical drive. / By default (0), each logical drive number is bound to the same physical drive / number and only an FAT volume found on the physical drive will be mounted. / When multi-partition is enabled (1), each logical drive number can be bound to / arbitrary physical drive and partition listed in the VolToPart[]. Also f fdisk() / function will be available.

#### 7.19.2.18 NORTC\_MDAY

```
#define _NORTC_MDAY 4
```

&

#### 7.19.2.19 NORTC\_MON

```
#define _NORTC_MON 6
```

&

## 7.19.2.20 \_NORTC\_YEAR

```
#define _NORTC_YEAR 2015
```

The option \_FS\_NORTC switches timestamp function. If the system does not have / any RTC function or valid timestamp is not needed, set \_FS\_NORTC = 1 to disable / the timestamp function. All objects modified by FatFs will have a fixed timestamp / defined by \_NORTC\_MON, \_NORTC\_MDAY and \_NORTC\_YEAR in local time. / To enable timestamp function (\_FS\_NORTC = 0), get\_fattime() function need to be / added to the project to get current time form real-time clock. \_NORTC\_MON, / \_NORTC\_MDAY and \_NORTC\_YEAR have no effect. / These options have no effect at read-only configuration (\_FS\_READONLY = 1).

#### 7.19.2.21 \_STR\_VOLUME\_ID

```
#define _STR_VOLUME_ID 0
```

0:Use only 0-9 for drive ID, 1:Use strings for drive ID

#### 7.19.2.22 STRF\_ENCODE

```
#define _STRF_ENCODE 3
```

When  $\_$ LFN $\_$ UNICODE == 1, this option selects the character encoding ON THE FILE to / be read/written via string I/O functions, f $\_$ gets(), f $\_$ putc(), f $\_$ puts and f $\_$ printf(). // 0: ANSI/OEM / 1: UTF-16LE / 2: UTF-16BE / 3: UTF-8 // This option has no effect when  $\_$ LFN $\_$ UNICODE == 0.

```
7.19.2.23 _SYNC_t
```

```
#define _SYNC_t osSemaphoreId
```

The option \_FS\_REENTRANT switches the re-entrancy (thread safe) of the FatFs / module itself. Note that regardless of this option, file access to different / volume is always re-entrant and volume control functions, f\_mount(), f\_mkfs() / and f\_fdisk() function, are always not re-entrant. Only file/directory access / to the same volume is under control of this function. // 0: Disable re-entrancy. \_FS\_TIMEOUT and \_SYNC\_t have no effect. / 1: Enable re-entrancy. Also user provided synchronization handlers, / ff\_req\_grant(), ff\_rel\_grant(), ff\_del\_syncobj() and ff\_cre\_syncobj() / function, must be added to the project. Samples are available in / option/syscall.c. // The \_FS \_ \_TIMEOUT defines timeout period in unit of time tick. / The \_SYNC\_t defines O/S dependent sync object type. e.g. HANDLE, ID, OS\_EVENT\*, / SemaphoreHandle\_t and etc.. A header file for O/S definitions needs to be / included somewhere in the scope of ff.h.

```
7.19.2.24 _USE_CHMOD
```

```
#define _USE_CHMOD 0
```

This option switches attribute manipulation functions,  $f_chmod()$  and  $f_utime()$ . / (0:Disable or 1:Enable) Also  $_F \leftarrow S_READONLY$  needs to be 0 to enable this option.

```
7.19.2.25 USE EXPAND
```

```
#define _USE_EXPAND 0
```

This option switches f\_expand function. (0:Disable or 1:Enable)

```
7.19.2.26 _USE_FASTSEEK
```

```
#define _USE_FASTSEEK 1
```

This option switches fast seek feature. (0:Disable or 1:Enable)

7.19.2.27 \_USE\_FIND

```
#define _USE_FIND 0
```

This option switches filtered directory read functions, f\_findfirst() and / f\_findnext(). (0:Disable, 1:Enable 2:Enable with matching altname[] too)

7.19.2.28 \_USE\_FORWARD

```
#define _USE_FORWARD 0
```

This option switches f\_forward() function. (0:Disable or 1:Enable)

This option switches volume label functions, f\_getlabel() and f\_setlabel(). / (0:Disable or 1:Enable)

```
7.19.2.30 _USE_LFN  
#define _USE_LFN  1
0 to 3
```

```
7.19.2.31 _USE_MKFS
```

```
#define _USE_MKFS 1
```

This option switches f\_mkfs() function. (0:Disable or 1:Enable)

```
7.19.2.32 _USE_STRFUNC
```

```
#define _USE_STRFUNC 2
```

0:Disable or 1-2:Enable This option switches string functions,  $f_gets()$ ,  $f_putc()$ ,  $f_putc()$ , and  $f_printf()$ . // 0: Disable string functions. / 1: Enable without LF-CRLF conversion.

```
7.19.2.33    _USE_TRIM
#define _USE_TRIM 0
```

This option switches support of ATA-TRIM. (0:Disable or 1:Enable) / To enable Trim function, also CTRL\_TRIM command should be implemented to the / disk\_ioctl() function.

```
7.19.2.34 _VOLUME_STRS
```

```
#define _VOLUME_STRS
```

## Value:

```
"RAM", "NAND", "CF", "SD1", "SD2", "USB1", "USB2", \
"USB3"
```

\_STR\_VOLUME\_ID switches string support of volume ID. / When \_STR\_VOLUME\_ID is set to 1, also pre-defined strings can be used as drive / number in the path name. \_VOLUME\_STRS defines the drive ID strings for each / logical drives. Number of items must be equal to \_VOLUMES. Valid characters for / the drive ID strings are: A-Z and 0-9.

```
7.19.2.35 _VOLUMES
```

```
#define _VOLUMES 1
```

Number of volumes (logical drives) to be used.

```
7.19.2.36 ff_free
```

```
#define ff_free free
```

define the ff\_malloc ff\_free macros as standard malloc free

```
7.19.2.37 ff_malloc
```

```
#define ff_malloc malloc
```

define the ff\_malloc ff\_free macros as standard malloc free

# 7.20 src/hid\_audio.h File Reference

#### Audio Driver

Configures Audio Device and provides callback for signal processing. Many of the hard-coded values here will change (increase), and/or be replaced by configurable options.

```
#include <stddef.h>
#include <stdint.h>
#include "per_sai.h"
#include "per_i2c.h"
```

## Classes

· struct dsy\_audio\_handle

## Macros

- #define DSY\_AUDIO\_H
- #define DSY\_AUDIO\_BLOCK\_SIZE\_MAX 128
- #define DSY AUDIO CHANNELS MAX 2
- #define DSY\_AUDIO\_SAMPLE\_RATE 48014.0f

# **Typedefs**

- typedef void(\* dsy\_audio\_callback) (float \*, float \*, size\_t)
- typedef void(\* dsy\_audio\_mc\_callback) (float \*\*, float \*\*, size\_t)

#### **Enumerations**

enum { DSY\_AUDIO\_INTERNAL, DSY\_AUDIO\_EXTERNAL, DSY\_AUDIO\_LAST }

#### **Functions**

- void dsy audio init (dsy audio handle \*handle)
- void dsy\_audio\_set\_callback (uint8\_t intext, dsy\_audio\_callback cb)
- void dsy\_audio\_set\_mc\_callback (dsy\_audio\_mc\_callback cb)
- void dsy\_audio\_set\_blocksize (uint8\_t intext, size\_t blocksize)
- void dsy\_audio\_start (uint8\_t intext)
- void dsy\_audio\_stop (uint8\_t intext)
- void dsy audio enter bypass (uint8 t intext)
- void dsy\_audio\_exit\_bypass (uint8\_t intext)
- void dsy\_audio\_passthru (float \*in, float \*out, size\_t size)
- void dsy\_audio\_silence (float \*in, float \*out, size\_t size)

## 7.20.1 Detailed Description

#### **Audio Driver**

Configures Audio Device and provides callback for signal processing. Many of the hard-coded values here will change (increase), and/or be replaced by configurable options.

@{

## 7.20.2 Macro Definition Documentation

## 7.20.2.1 DSY\_AUDIO\_BLOCK\_SIZE\_MAX

```
#define DSY_AUDIO_BLOCK_SIZE_MAX 128
```

Defines for generic maximums While 'Audio Channels Max' is set to 2, this is per-SAI 4x4 Audio I/O is possible using the dsy\_audio\_mc\_callback Hard-coded samplerate is calculated from original clock tree. The new clock tree has less than 0.01% error for all supported sampleratesMax block size

#### 7.20.2.2 DSY\_AUDIO\_CHANNELS\_MAX

#define DSY\_AUDIO\_CHANNELS\_MAX 2

Max number of audio channels

## 7.20.2.3 DSY\_AUDIO\_H

#define DSY\_AUDIO\_H

#### 7.20.2.4 DSY\_AUDIO\_SAMPLE\_RATE

```
#define DSY_AUDIO_SAMPLE_RATE 48014.0f
```

Default sample rate

## 7.20.3 Typedef Documentation

## 7.20.3.1 dsy\_audio\_callback

```
typedef void(* dsy_audio_callback) (float *, float *, size_t)
```

These are user-defineable callbacks that are called when audio data is ready to be received/transmitted. Function to define for using a single Stereo device for I/O audio is packed as: { LEFT | RIGHT | LEFT | RIGHT }

## 7.20.3.2 dsy\_audio\_mc\_callback

```
typedef void(* dsy_audio_mc_callback) (float **, float **, size_t)
```

Defaults to 4 channels, and is fixed for now. (still works for stereo, but will still fill buffers) audio is packed as:

```
\{\,\mathsf{LEFT}\mid\mathsf{LEFT}+\mathsf{1}\mid\ldots\mid\mathsf{LEFT}+\mathsf{SIZE}\mid\mathsf{RIGHT}\mid\mathsf{RIGHT}+\mathsf{1}\mid\ldots\mid\mathsf{RIGHT}+\mathsf{SIZE}\,\}
```

## 7.20.4 Enumeration Type Documentation

## 7.20.4.1 anonymous enum

anonymous enum

Internally, there are two separate 'audio blocks' that can be configured together or separately

#### Enumerator

DSY_AUDIO_INTERNAL	&
DSY_AUDIO_EXTERNAL	&
DSY AUDIO LAST	&

## 7.20.5 Function Documentation

#### 7.20.5.1 dsy\_audio\_enter\_bypass()

If the device supports hardware bypass, enter that mode.

#### 7.20.5.2 dsy\_audio\_exit\_bypass()

If the device supports hardware bypass, exit that mode.

## 7.20.5.3 dsy\_audio\_init()

Initializes the Audio Engine using configurations set to the sai\_handle i2c\_handles can be set to NULL if not needed.

## 7.20.5.4 dsy\_audio\_passthru()

A few useful stereo-interleaved callbacks Passes the input to the output

#### 7.20.5.5 dsy\_audio\_set\_blocksize()

Sets the number of samples (per-channel) to be handled in a single audio frame.

#### 7.20.5.6 dsy\_audio\_set\_callback()

Sets the user defined, interleaving callback to be called when audio data is ready. intext is a specifier for DSY\_AUDIO\_INT/EXT (which audio peripheral to use). When using this, each 'audio block' can have completely independent callbacks.

#### 7.20.5.7 dsy\_audio\_set\_mc\_callback()

Sets the user defined, non-interleaving callback to be called when audio data is ready. This will always use both DSY\_AUDIO\_INT and DSY\_AUDIO\_EXT blocks together. To ensure clean audio you'll want to make sure the two SAIs are set to the same samplerate

#### 7.20.5.8 dsy\_audio\_silence()

sets outputs to 0 without stopping the Audio Engine

#### 7.20.5.9 dsy\_audio\_start()

Starts Audio Engine, callbacks will begin getting called.

When using with dsy\_audio\_mc\_callback (for 4 channels), this function should be called for both audio blocks

#### 7.20.5.10 dsy\_audio\_stop()

Stops transmitting/receiving audio on the specified audio block.

## 7.21 src/hid ctrl.h File Reference

```
#include <stdint.h>
```

## Classes

· class daisy::AnalogControl

Hardware Interface for control inputs Primarily designed for ADC input controls such as potentiometers, and control voltage.

## **Macros**

• #define DSY\_KNOB\_H

## 7.21.1 Macro Definition Documentation

```
7.21.1.1 DSY_KNOB_H
#define DSY_KNOB_H
```

# 7.22 src/hid\_encoder.h File Reference

```
#include "daisy_core.h"
#include "per_gpio.h"
#include "hid_switch.h"
```

## Classes

· class daisy::Encoder

Generic Class for handling Quadrature Encoders Inspired/influenced by Mutable Instruments (pichenettes) Encoder classes.

# 7.23 src/hid\_gatein.h File Reference

```
#include "per_gpio.h"
```

## **Classes**

· class daisy::GateIn

Generic Class for handling gate inputs through GPIO.

# 7.24 src/hid\_led.h File Reference

```
#include "daisy_core.h"
#include "per_gpio.h"
```

#### Classes

· class daisy::Led

LED Class providing simple Software PWM ability, etc Eventually this will work with hardware PWM, and external LED Driver devices as well.

# 7.25 src/hid\_midi.h File Reference

```
#include <stdint.h>
#include <stdlib.h>
#include "per_uart.h"
#include "util_ringbuffer.h"
```

#### Classes

- struct daisy::NoteOnEvent
- struct daisy::ControlChangeEvent
- struct daisy::MidiEvent
- class daisy::MidiHandler

Simple MIDI Handler

Parses bytes from an input into valid MidiEvents.

The MidiEvents fill a FIFO queue that the user can pop messages from.

## **Enumerations**

enum daisy::MidiMessageType {
 daisy::NoteOff, daisy::NoteOn, daisy::PolyphonicKeyPressure, daisy::ControlChange,
 daisy::ProgramChange, daisy::ChannelPressure, daisy::PitchBend, daisy::MessageLast }

## 7.25.1 Enumeration Type Documentation

## 7.25.1.1 MidiMessageType

```
enum daisy::MidiMessageType
```

Parsed from the Status Byte, these are the common Midi Messages that can be handled. At this time only 3-byte messages are correctly parsed into MidiEvents.

#### Enumerator

&
&
&
&
&
&
&
&

# 7.26 src/hid\_oled\_display.h File Reference

```
#include <stdlib.h>
#include <stdint.h>
#include "util_oled_fonts.h"
#include "daisy_core.h"
```

## **Classes**

· class daisy::OledDisplay

## **Macros**

- #define DSY\_OLED\_DISPLAY\_H
- #define SSD1309\_HEIGHT 64
- #define SSD1309\_WIDTH 128

#### 7.26.1 Macro Definition Documentation

```
7.26.1.1 DSY_OLED_DISPLAY_H
```

```
#define DSY_OLED_DISPLAY_H
```

## Macro

## 7.26.1.2 SSD1309\_HEIGHT

```
#define SSD1309_HEIGHT 64
```

## SSD1309 height in pixels

## 7.26.1.3 SSD1309\_WIDTH

```
#define SSD1309_WIDTH 128
```

SSD1309 width in pixels

# 7.27 src/hid\_parameter.h File Reference

```
#include <stdint.h>
#include "hid_ctrl.h"
```

## Classes

• class daisy::Parameter

# 7.28 src/hid\_rgb\_led.h File Reference

```
#include "hid_led.h"
#include "util_color.h"
```

# **Classes**

· class daisy::RgbLed

# 7.29 src/hid\_switch.h File Reference

```
#include "daisy_core.h"
#include "per_gpio.h"
```

## **Classes**

· class daisy::Switch

# 7.30 src/hid\_usb.h File Reference

```
#include <stdint.h>
#include <stdlib.h>
```

## Classes

• class daisy::UsbHandle

Interface for initializing and using the USB Peripherals on the daisy.

# 7.31 src/hid\_wavplayer.h File Reference

```
#include "daisy_core.h"
#include "util_wav_format.h"
```

## Classes

- struct daisy::WavFileInfo
- class daisy::WavPlayer

#### **Macros**

- #define DSY\_WAVPLAYER\_H
- #define WAV\_FILENAME\_MAX 256

#### 7.31.1 Macro Definition Documentation

```
7.31.1.1 DSY_WAVPLAYER_H
```

```
#define DSY_WAVPLAYER_H
```

#### Macro

## 7.31.1.2 WAV\_FILENAME\_MAX

```
#define WAV_FILENAME_MAX 256
```

Maximum LFN (set to same in FatFs (ffconf.h)

# 7.32 src/per\_adc.h File Reference

```
#include <stdint.h>
#include <stdlib.h>
#include "daisy_core.h"
#include "per_gpio.h"
```

## **Classes**

- struct daisy::AdcChannelConfig
- · class daisy::AdcHandle

## Macros

- #define DSY\_ADC\_H
- #define DSY\_ADC\_MAX\_CHANNELS 14

## 7.32.1 Macro Definition Documentation

```
7.32.1.1 DSY_ADC_H
```

#define DSY\_ADC\_H

Macro

## 7.32.1.2 DSY\_ADC\_MAX\_CHANNELS

#define DSY\_ADC\_MAX\_CHANNELS 14

Maximum number of ADC channels

# 7.33 src/per\_dac.h File Reference

```
#include "daisy_core.h"
```

## Classes

• struct dsy\_dac\_handle

## **Enumerations**

- enum dsy\_dac\_mode { DSY\_DAC\_MODE\_POLLING, DSY\_DAC\_MODE\_LAST }
- enum dsy\_dac\_bitdepth { DSY\_DAC\_BITS\_8, DSY\_DAC\_BITS\_12, DSY\_DAC\_BITS\_LAST }
- enum dsy\_dac\_channel { DSY\_DAC\_CHN1, DSY\_DAC\_CHN2, DSY\_DAC\_CHN\_LAST, DSY\_DAC\_CH
   N\_BOTH }

## **Functions**

- void dsy\_dac\_init (dsy\_dac\_handle \*dsy\_hdac, dsy\_dac\_channel channel)
- void dsy\_dac\_start (dsy\_dac\_channel channel)
- void dsy\_dac\_write (dsy\_dac\_channel channel, uint16\_t val)

## 7.33.1 Enumeration Type Documentation

## 7.33.1.1 dsy\_dac\_bitdepth

```
enum dsy_dac_bitdepth
```

Sets the bit depth of the DAC output This can be set independently for each channel.

## Enumerator

DSY_DAC_BITS_8	&
DSY_DAC_BITS_12	&
DSY_DAC_BITS_LAST	&

## 7.33.1.2 dsy\_dac\_channel

enum dsy\_dac\_channel

Sets which channel(s) are initialized with the settings chosen.

#### Enumerator

DSY_DAC_CHN1	&
DSY_DAC_CHN2	&
DSY_DAC_CHN_LAST	&
DSY_DAC_CHN_BOTH	&

### 7.33.1.3 dsy\_dac\_mode

enum dsy\_dac\_mode

Driver for the built in DAC on the STM32 The STM32 has 2 Channels of independently configurable DACs, with up to 12-bit resolution. Currently only Polling is supported.

#### Enumerator

DSY_DAC_MODE_POLLING	Polling mode
DSY_DAC_MODE_LAST	3

## 7.33.2 Function Documentation

```
7.33.2.1 dsy_dac_init()
```

Initializes the specified channel(s) of the DAC

## **Parameters**

*dsy_hdac	Dac to initialize
channel	Channels to init

## 7.33.2.2 dsy\_dac\_start()

Turns on the DAC and turns on any internal timer if necessary.

#### **Parameters**

```
channel Channel to start
```

## 7.33.2.3 dsy\_dac\_write()

Sets the specified channel of the dac to the value (within bitdepth) resolution. When set to 8-bit, val should be 0-255 When set to 12-bit, val should be 0-4095

#### **Parameters**

channel	Channel to write to
val	Value to write

# 7.34 src/per\_gpio.h File Reference

```
#include "daisy_core.h"
```

# **Classes**

struct dsy\_gpio

### **Enumerations**

- enum dsy\_gpio\_mode {
   DSY\_GPIO\_MODE\_INPUT, DSY\_GPIO\_MODE\_OUTPUT\_PP, DSY\_GPIO\_MODE\_OUTPUT\_OD, DSY
   \_GPIO\_MODE\_ANALOG,
   DSY\_GPIO\_MODE\_LAST }
- enum dsy\_gpio\_pull { DSY\_GPIO\_NOPULL, DSY\_GPIO\_PULLUP, DSY\_GPIO\_PULLDOWN }

# **Functions**

- void dsy\_gpio\_init (dsy\_gpio \*p)
- void dsy\_gpio\_deinit (dsy\_gpio \*p)
- uint8\_t dsy\_gpio\_read (dsy\_gpio \*p)
- void dsy\_gpio\_write (dsy\_gpio \*p, uint8\_t state)
- void dsy\_gpio\_toggle (dsy\_gpio \*p)

# 7.34.1 Detailed Description

General Purpose IO driver

# 7.34.2 Enumeration Type Documentation

7.34.2.1 dsy\_gpio\_mode

enum dsy\_gpio\_mode

Sets the mode of the GPIO

# Enumerator

DSY_GPIO_MODE_INPUT	&
DSY_GPIO_MODE_OUTPUT_PP	Push-Pull
DSY_GPIO_MODE_OUTPUT_OD	Open-Drain
DSY_GPIO_MODE_ANALOG	&
DSY_GPIO_MODE_LAST	&

# 7.34.2.2 dsy\_gpio\_pull

```
enum dsy_gpio_pull
```

Configures whether an internal Pull up or Pull down resistor is used

### Enumerator

DSY_GPIO_NOPULL	&
DSY_GPIO_PULLUP	&
DSY_GPIO_PULLDOWN	&

# 7.34.3 Function Documentation

# 7.34.3.1 dsy\_gpio\_deinit()

Deinitializes the gpio pin

# **Parameters**

```
*p Pin pointer
```

# 7.34.3.2 dsy\_gpio\_init()

Initializes the gpio with the settings configured.

### **Parameters**

# 7.34.3.3 dsy\_gpio\_read()

Reads the state of the gpio pin

#### **Parameters**

```
*p Pin pointer
```

### Returns

1 if the pin is HIGH, and 0 if the pin is LOW

# 7.34.3.4 dsy\_gpio\_toggle()

Toggles the state of the pin so that it is not at the same state as it was previously.

### **Parameters**

```
*p Pin pointer
```

# 7.34.3.5 dsy\_gpio\_write()

Writes the state to the gpio pin Pin will be set to 3v3 when state is 1, and 0V when state is 0

# **Parameters**

*p	Pin pointer
state	State to write

# 7.35 src/per\_i2c.h File Reference

```
#include "daisy_core.h"
```

### Classes

• struct dsy\_i2c\_handle

### **Macros**

• #define DSY\_I2C\_H

# **Enumerations**

- enum dsy\_i2c\_periph { DSY\_I2C\_PERIPH\_1, DSY\_I2C\_PERIPH\_2, DSY\_I2C\_PERIPH\_3, DSY\_I2C\_PE
   RIPH\_4 }
- enum dsy\_i2c\_pin { DSY\_I2C\_PIN\_SCL, DSY\_I2C\_PIN\_SDA, DSY\_I2C\_PIN\_LAST }
- enum dsy\_i2c\_speed { DSY\_I2C\_SPEED\_100KHZ, DSY\_I2C\_SPEED\_400KHZ, DSY\_I2C\_SPEED\_1MHZ, DSY\_I2C\_SPEED\_LAST }

# **Functions**

void dsy\_i2c\_init (dsy\_i2c\_handle \*dsy\_hi2c)

# 7.35.1 Macro Definition Documentation

```
7.35.1.1 DSY_I2C_H
```

#define DSY\_I2C\_H

Macro

# 7.35.2 Enumeration Type Documentation

```
7.35.2.1 dsy_i2c_periph
```

```
enum dsy_i2c_periph
```

Driver for controlling I2C devices Specifices the internal peripheral to use (these are mapped to different pins on the hardware).

### Enumerator

DSY_I2C_PERIPH←	&
_1	
DSY_I2C_PERIPH ↔	&
_2	
DSY_I2C_PERIPH↔	&
_3	
DSY_I2C_PERIPH↔	&
_4	

7.35.2.2 dsy\_i2c\_pin

enum dsy\_i2c\_pin

List of pins associated with the peripheral. These must be set in the handle's pin\_config.

# Enumerator

DSY_I2C_PIN_SCL	&
DSY_I2C_PIN_SDA	&
DSY_I2C_PIN_LAST	&

7.35.2.3 dsy\_i2c\_speed

enum dsy\_i2c\_speed

Rate at which the clock/data will be sent/received. The device being used will have maximum speeds. 1MHZ Mode is currently 886kHz\*\*

# Enumerator

DSY_I2C_SPEED_100KHZ	&
DSY_I2C_SPEED_400KHZ	&
DSY_I2C_SPEED_1MHZ	&
DSY_I2C_SPEED_LAST	&

# 7.35.3 Function Documentation

### 7.35.3.1 dsy\_i2c\_init()

Initializes an I2C peripheral with the data given from the handle.

### **Parameters**

*dsy_hi2c	Required to initialize.
-----------	-------------------------

# 7.36 src/per\_qspi.h File Reference

```
#include <stdint.h>
#include "daisy_core.h"
```

#### Classes

• struct dsy\_qspi\_handle

### **Macros**

- #define DSY\_QSPI
- #define DSY\_MEMORY\_OK ((uint32\_t)0x00)
- #define DSY\_MEMORY\_ERROR ((uint32\_t)0x01)
- #define DSY\_QSPI\_TEXT
- #define DSY QSPI DATA
- #define DSY\_QSPI\_BSS

# **Enumerations**

- enum dsy\_qspi\_pin {
   DSY\_QSPI\_PIN\_IO0, DSY\_QSPI\_PIN\_IO1, DSY\_QSPI\_PIN\_IO2, DSY\_QSPI\_PIN\_IO3,
   DSY\_QSPI\_PIN\_CLK, DSY\_QSPI\_PIN\_NCS, DSY\_QSPI\_PIN\_LAST }

# **Functions**

- int dsy\_qspi\_init (dsy\_qspi\_handle \*hqspi)
- int dsy\_qspi\_deinit ()
- int dsy\_qspi\_writepage (uint32\_t adr, uint32\_t sz, uint8\_t \*buf)
- int dsy\_qspi\_write (uint32\_t address, uint32\_t size, uint8\_t \*buffer)
- int dsy\_qspi\_erase (uint32\_t start\_adr, uint32\_t end\_adr)
- int dsy\_qspi\_erasesector (uint32\_t addr)

# 7.36.1 Macro Definition Documentation

```
7.36.1.1 DSY_MEMORY_ERROR
\#define DSY_MEMORY_ERROR ((uint32_t)0x01)
&
7.36.1.2 DSY_MEMORY_OK
#define DSY_MEMORY_OK ((uint32_t)0x00)
&
7.36.1.3 DSY_QSPI
#define DSY_QSPI
Macro
7.36.1.4 DSY_QSPI_BSS
#define DSY_QSPI_BSS
Value:
__attribute__((section(\
    ".qspiflash_bss")))
used for reading memory in memory_mapped mode.
7.36.1.5 DSY_QSPI_DATA
#define DSY_QSPI_DATA
Value:
```

used for reading memory in memory\_mapped mode.

\_\_attribute\_\_((section(\ ".qspiflash\_data")))

# 7.36.1.6 DSY\_QSPI\_TEXT

```
#define DSY_QSPI_TEXT
```

### Value:

```
__attribute__((section(\
    ".qspiflash_text")))
```

used for reading memory in memory\_mapped mode.

# 7.36.2 Enumeration Type Documentation

# 7.36.2.1 dsy\_qspi\_device

```
enum dsy_qspi_device
```

Flash Devices supported. (Both of these are more-or-less the same, just different sizes).

#### Enumerator

DSY_QSPI_DEVICE_IS25LP080D	&
DSY_QSPI_DEVICE_IS25LP064A	&
DSY_QSPI_DEVICE_LAST	&

# 7.36.2.2 dsy\_qspi\_mode

```
enum dsy_qspi_mode
```

Modes of operation. Memory Mapped mode: QSPI configured so that the QSPI can be read from starting address 0x90000000. Writing is not possible in this mode.

Indirect Polling mode: Device driver enabled. Read/Write possible via dsy\_qspi\_\* functions

DSY_QSPI_MODE_DSY_MEMORY_MAPPED	&
DSY_QSPI_MODE_INDIRECT_POLLING	&
DSY_QSPI_MODE_LAST	&

# 7.36.2.3 dsy\_qspi\_pin

```
enum dsy_qspi_pin
```

Driver for QSPI peripheral to interface with external flash memory. Currently supported QSPI Devices: IS25LP080DList of Pins used in QSPI (passed in during Init)

### Enumerator

DSY_QSPI_PIN_IO0	&
DSY_QSPI_PIN_IO1	&
DSY_QSPI_PIN_IO2	&
DSY_QSPI_PIN_IO3	&
DSY_QSPI_PIN_CLK	&
DSY_QSPI_PIN_NCS	&
DSY_QSPI_PIN_LAST	&

### 7.36.3 Function Documentation

# 7.36.3.1 dsy\_qspi\_deinit()

```
int dsy_qspi_deinit ( )
```

Deinitializes the peripheral This should be called before reinitializing QSPI in a different mode.

# Returns

```
DSY_MEMORY_OK or DSY_MEMORY_ERROR
```

# 7.36.3.2 dsy\_qspi\_erase()

Erases the area specified on the chip. Erasures will happen by 4K, 32K or 64K increments. Smallest erase possible is 4kB at a time. (on IS25LP\*)

# **Parameters**

start_adr	Address to begin erasing from
end_adr	Address to stop erasing at

### Returns

DSY\_MEMORY\_OK or DSY\_MEMORY\_ERROR

# 7.36.3.3 dsy\_qspi\_erasesector()

```
int dsy_qspi_erasesector ( \mbox{uint32\_t} \ \ \mbox{\it addr} \ )
```

Erases a single sector of the chip. TODO: Document the size of this function.

### **Parameters**

```
addr Address of sector to erase
```

### Returns

DSY\_MEMORY\_OK or DSY\_MEMORY\_ERROR

# 7.36.3.4 dsy\_qspi\_init()

Initializes QSPI peripheral, and Resets, and prepares memory for access.

#### **Parameters**

hqspi should be populated with the mode, device and pin\_config before calling this function.

### Returns

DSY\_MEMORY\_OK or DSY\_MEMORY\_ERROR

# 7.36.3.5 dsy\_qspi\_write()

Writes data in buffer to to the QSPI. Starting at address to address+size

#### **Parameters**

address	Address to write to
size	Buffer size
buffer	Buffer to write

### Returns

```
DSY_MEMORY_OK or DSY_MEMORY_ERROR
```

# 7.36.3.6 dsy\_qspi\_writepage()

Writes a single page to to the specified address on the QSPI chip. For IS25LP\* page size is 256 bytes.

#### **Parameters**

adr	Address to write to
SZ	Buff size
buf	Buffer to write

### Returns

```
DSY_MEMORY_OK or DSY_MEMORY_ERROR
```

# 7.37 src/per\_sai.h File Reference

```
#include "daisy_core.h"
```

# Classes

• struct dsy\_sai\_handle

# **Enumerations**

- enum dsy\_audio\_sai {
   DSY\_AUDIO\_INIT\_SAI1, DSY\_AUDIO\_INIT\_SAI2, DSY\_AUDIO\_INIT\_BOTH, DSY\_AUDIO\_INIT\_NONE,
   DSY\_AUDIO\_INIT\_LAST }

```
    enum dsy_audio_bitdepth { DSY_AUDIO_BITDEPTH_16, DSY_AUDIO_BITDEPTH_24, DSY_AUDIO_BI-
TDEPTH_LAST }
```

- enum dsy\_audio\_sync { DSY\_AUDIO\_SYNC\_MASTER, DSY\_AUDIO\_SYNC\_SLAVE, DSY\_AUDIO\_SY NC\_LAST }
- enum dsy\_audio\_dir { DSY\_AUDIO\_RX, DSY\_AUDIO\_TX }
- enum dsy\_sai\_pin {
   DSY\_SAI\_PIN\_MCLK, DSY\_SAI\_PIN\_FS, DSY\_SAI\_PIN\_SCK, DSY\_SAI\_PIN\_SIN,
   DSY\_SAI\_PIN\_SOUT, DSY\_SAI\_PIN\_LAST }
- enum dsy\_audio\_device {
   DSY\_AUDIO\_NONE, DSY\_AUDIO\_DEVICE\_PCM3060, DSY\_AUDIO\_DEVICE\_WM8731, DSY\_AUDIO\_
   DEVICE\_AK4556,
   DSY\_AUDIO\_DEVICE\_LAST }
- enum { DSY\_SAI\_1, DSY\_SAI\_2, DSY\_SAI\_LAST }

### **Functions**

- void dsy\_sai\_init (dsy\_audio\_sai init, dsy\_audio\_samplerate sr[2], dsy\_audio\_bitdepth bitdepth[2], dsy\_
  audio\_sync sync\_config[2], dsy\_gpio\_pin \*sai1\_pin\_list, dsy\_gpio\_pin \*sai2\_pin\_list)
- void dsy\_sai\_init\_from\_handle (dsy\_sai\_handle \*hsai)

# 7.37.1 Enumeration Type Documentation

### 7.37.1.1 anonymous enum

anonymous enum

Index for the several arrays in the sai\_handle struct below.

#### Enumerator

DSY_SAI_1	&
DSY_SAI_2	&
DSY_SAI_LAST	&

#### 7.37.1.2 dsy\_audio\_bitdepth

enum dsy\_audio\_bitdepth

Specifies the bitdepth of the hardware connected to the SAI peripheral

DSY_AUDIO_BITDEPTH_16	&
DSY_AUDIO_BITDEPTH_24	
DSY AUDIO BITDEPTH LAST	&

# 7.37.1.3 dsy\_audio\_device

enum dsy\_audio\_device

List of devices with built in support. Devices not listed here, will need to have initialization done externally.

### Enumerator

DSY_AUDIO_NONE	For unsupported, or custom devices.
DSY_AUDIO_DEVICE_PCM3060	&
DSY_AUDIO_DEVICE_WM8731	&
DSY_AUDIO_DEVICE_AK4556	&
DSY_AUDIO_DEVICE_LAST	&

# 7.37.1.4 dsy\_audio\_dir

enum dsy\_audio\_dir

Each SAI has two datalines, they can independently be configured as inputs or outputs.

### Enumerator

DSY_AUDIO_RX	&
DSY_AUDIO_TX	&

# 7.37.1.5 dsy\_audio\_sai

enum dsy\_audio\_sai

Driver for the SAI peripheral Supports SAI1 and SAI2 with several configuration options selects which SAI (or both/none) to initialize

DSY_AUDIO_INIT_SAI1	&
DSY_AUDIO_INIT_SAI2	&
DSY_AUDIO_INIT_BOTH	&
DSY_AUDIO_INIT_NONE	&
DSY AUDIO INIT LAST	&

# 7.37.1.6 dsy\_audio\_samplerate

enum dsy\_audio\_samplerate

Currently Sample Rates are not correctly supported. All audio is currently run at 48kHz

#### Enumerator

DSY_AUDIO_SAMPLERATE_32K	&
DSY_AUDIO_SAMPLERATE_48K	&
DSY_AUDIO_SAMPLERATE_96K	
DSY_AUDIO_SAMPLERATE_LAST	

# 7.37.1.7 dsy\_audio\_sync

enum dsy\_audio\_sync

Setting for each SAI that sets whether the processor is generating the MCLK signal or not.

### Enumerator

DSY_AUDIO_SYNC_MASTER	No Crystal
DSY_AUDIO_SYNC_SLAVE	Crystal
DSY_AUDIO_SYNC_LAST	&

# 7.37.1.8 dsy\_sai\_pin

enum dsy\_sai\_pin

List of the pins that need to be initialized SIN/SOUT is a bit misleading, and should be turned into A/B since it is possible to configure two inputs or two outputs on a single SAI.

DSY_SAI_PIN_MCLK	
DSY_SAI_PIN_FS	
DSY_SAI_PIN_SCK	&
DSY_SAI_PIN_SIN	
DSY_SAI_PIN_SOUT	
DSY_SAI_PIN_LAST	

# 7.37.2 Function Documentation

# 7.37.2.1 dsy\_sai\_init()

Intializes the SAI peripheral(s) with the specified settings. Pinlists should be arrays of DSY\_SAI\_PIN\_LAST elements

### **Parameters**

init	&
sr[]	Sample rate per chan: 0, 1
bitdepth[]	Bitdepth per chan: 0, 1
sync_config[]	& sync config per chan: 0, 1
*sai1_pin_list	&
*sai2_pin_list	&

## 7.37.2.2 dsy\_sai\_init\_from\_handle()

Uses the data within \*hsai to initialize the peripheral(s)

### **Parameters**

hsai &

# 7.38 src/per\_sdmmc.h File Reference

```
#include <stdint.h>
```

# Classes

- struct daisy::SdmmcHandlerInit
- · class daisy::SdmmcHandler

# **Macros**

- #define DSY\_SDMMC\_H
- #define DSY\_SD\_OK 0
- #define DSY SD ERROR 1

# **Enumerations**

- enum daisy::SdmmcMode { daisy::SDMMC\_MODE\_FATFS }
- enum daisy::SdmmcBitWidth { daisy::SDMMC\_BITS\_1, daisy::SDMMC\_BITS\_4 }
- enum daisy::SdmmcSpeed { daisy::SDMMC\_SPEED\_400KHZ, daisy::SDMMC\_SPEED\_12MHZ }

# 7.38.1 Macro Definition Documentation

```
7.38.1.1 DSY_SD_ERROR
```

#define DSY\_SD\_ERROR 1

ERROR return

7.38.1.2 DSY\_SD\_OK

#define DSY\_SD\_OK 0

OK return

7.38.1.3 DSY\_SDMMC\_H

#define DSY\_SDMMC\_H

macro

# 7.38.2 Enumeration Type Documentation

### 7.38.2.1 SdmmcBitWidth

enum daisy::SdmmcBitWidth

Sets whether 4-bit mode or 1-bit mode is used for the SDMMC

### Enumerator

SDMMC_BITS⊷	&
_1	
SDMMC_BITS↔	&
_4	

# 7.38.2.2 SdmmcMode

enum daisy::SdmmcMode

Operating Mode. Currently only FatFS is supported.

# Enumerator

	SDMMC_	MODE	FATFS	&	
--	--------	------	-------	---	--

# 7.38.2.3 SdmmcSpeed

enum daisy::SdmmcSpeed

Sets the desired clock speed of the SD card bus. Initialization is always done at or below 400kHz, and then the user speed is set.

### Enumerator

SDMMC_SPEED_400KHZ	&
SDMMC_SPEED_12MHZ	&

# 7.39 src/per\_spi.h File Reference

#include "daisy\_core.h"

### **Classes**

• class daisy::SpiHandle

# **Enumerations**

- enum daisy::SpiPeriph { daisy::SPI\_PERIPH\_1, daisy::SPI\_PERIPH\_3, daisy::SPI\_PERIPH\_6 }

# 7.39.1 Enumeration Type Documentation

# 7.39.1.1 SpiPeriph

enum daisy::SpiPeriph

# SPI peripheral enum

### Enumerator

SPI_PERIPH↔	SPI peripheral 1
_1	
SPI_PERIPH↔	SPI peripheral 3
_3	
SPI_PERIPH↔	SPI peripheral 3
_6	

# 7.39.1.2 SpiPin

enum daisy::SpiPin

# SPI pins

# Enumerator

SPI_PIN_CS	CS pin
SPI_PIN_SCK	SCK pin
SPI_PIN_MOSI	MOSI pin
SPI_PIN_MISO	MISO pin

# 7.40 src/per\_tim.h File Reference

#include <stdint.h>

# **Functions**

- void dsy\_tim\_init ()
- void dsy\_tim\_start ()
- uint32\_t dsy\_tim\_get\_tick ()
- void dsy\_tim\_delay\_tick (uint32\_t cnt)
- uint32\_t dsy\_tim\_get\_ms ()
- void dsy\_tim\_delay\_ms (uint32\_t cnt)
- uint32\_t dsy\_tim\_get\_us ()
- void dsy\_tim\_delay\_us (uint32\_t cnt)

# 7.40.1 Function Documentation

# 7.40.1.1 dsy\_tim\_delay\_ms()

blocking delay of cnt milliseconds.

#### **Parameters**

```
cnt Delay time in ms
```

# 7.40.1.2 dsy\_tim\_delay\_tick()

blocking delay of cnt timer ticks.

### **Parameters**

```
cnt Number of ticks
```

# 7.40.1.3 dsy\_tim\_delay\_us()

blocking delay of cnt microseconds.

# **Parameters**

```
cnt Delay time in us
```

# 7.40.1.4 dsy\_tim\_get\_ms()

```
uint32_t dsy_tim_get_ms ( )
```

These functions are converted to use milliseconds as their time base.

#### Returns

the number of milliseconds through the timer period.

# 7.40.1.5 dsy\_tim\_get\_tick()

```
uint32_t dsy_tim_get_tick ( )
```

These functions are specific to the actual clock ticks at the timer frequency which is currently fixed at 200MHz

#### Returns

a number 0x00000000-0xfffffff of the current tick

# 7.40.1.6 dsy\_tim\_get\_us()

```
uint32_t dsy_tim_get_us ( )
```

These functions are converted to use microseconds as their time base.

# Returns

the number of microseconds through the timer period.

# 7.40.1.7 dsy\_tim\_init()

```
void dsy_tim_init ( )
```

General purpose timer for delays and general timing. initializes the TIM2 peripheral with maximum counter autoreload, and no prescalers.

# 7.40.1.8 dsy\_tim\_start()

```
void dsy_tim_start ( )
```

Starts the timer ticking.

# 7.41 src/per\_uart.h File Reference

```
#include "daisy_core.h"
```

# Classes

• class daisy::UartHandler

# **Macros**

• #define DSY UART H

# **Variables**

• const size\_t daisy::kUartMaxBufferSize = 32

# 7.41.1 Macro Definition Documentation

```
7.41.1.1 DSY_UART_H
```

#define DSY\_UART\_H

macro

### 7.41.2 Variable Documentation

# 7.41.2.1 kUartMaxBufferSize

```
const size_t daisy::kUartMaxBufferSize = 32
```

Maximum Queue buffer size

# 7.42 src/sys\_dma.h File Reference

# **Functions**

• void dsy\_dma\_init (void)

# 7.42.1 Function Documentation

# 7.42.1.1 dsy\_dma\_init()

```
void dsy_dma_init (
     void )
```

Initializes the Direct Memory Access Peripheral used by many internal elements of libdaisy. Initializes the DMA (specifically for the modules used within the library)

# 7.43 src/sys\_system.h File Reference

```
#include <stdint.h>
```

### **Functions**

- void dsy\_system\_init ()
- void dsy\_system\_jumpto (uint32\_t addr)
- void dsy\_system\_jumptoqspi ()
- uint32\_t dsy\_system\_getnow ()
- void dsy\_system\_delay (uint32\_t delay\_ms)

# 7.43.1 Detailed Description

Low level System Configuration

# 7.43.2 Function Documentation

# 7.43.2.1 dsy\_system\_delay()

Blocking Delay that uses the SysTick (1ms callback) to wait.

### **Parameters**

delav ms	Time to delay in ms
aciay_iiio	Title to dolay iii iiio

### 7.43.2.2 dsy\_system\_getnow()

```
uint32_t dsy_system_getnow ( )
```

#### Returns

a uint32\_t value of milliseconds since the SysTick started Note! This is a HAL\_GetTick()

### 7.43.2.3 dsy\_system\_init()

```
void dsy_system_init ( )
```

Initializes Clock tree, MPU, and internal memories voltage regulators. This function *must* be called at the beginning of any program using libdaisy Higher level daisy\_files call this through the DaisySeed object.

# 7.43.2.4 dsy\_system\_jumpto()

```
void dsy_system_jumpto ( \mbox{uint32\_t } \mbox{\it addr} \mbox{\it )}
```

Jump to an address within the internal memory

This may not work correctly, and may not be very useful with the single sector of memory on the stm32h750\*\*

#### **Parameters**

```
addr Address to jump to
```

# 7.43.2.5 dsy\_system\_jumptoqspi()

```
void dsy_system_jumptoqspi ( )
```

Jumps to the first address of the external flash chip (0x9000000) If there is no code there, the chip will likely fall through to the while() loop TODO: Documentation/Loader for using external flash coming soon.

# 7.44 src/usbd\_cdc\_if.h File Reference

```
: Header for usbd_cdc_if.c file.
#include "usbd_cdc.h"
```

# **Typedefs**

typedef void(\* CDC\_ReceiveCallback) (uint8\_t \*buf, uint32\_t \*size)

# **Functions**

```
• void CDC_Set_Rx_Callback_FS (CDC_ReceiveCallback cb)
```

- uint8\_t CDC\_Transmit\_FS (uint8\_t \*Buf, uint16\_t Len)
- uint8\_t CDC\_Transmit\_HS (uint8\_t \*Buf, uint16\_t Len)

### Variables

- USBD\_CDC\_ItfTypeDef USBD\_Interface\_fops\_FS
- USBD\_CDC\_ltfTypeDef USBD\_Interface\_fops\_HS

# 7.44.1 Detailed Description

: Header for usbd\_cdc\_if.c file.

Version

: v1.0\_Cube

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# 7.45 src/usbd\_conf.h File Reference

: Header for usbd\_conf.c file.

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "stm32h7xx.h"
#include "stm32h7xx_hal.h"
```

### **Macros**

- #define USBD\_MAX\_NUM\_INTERFACES 1U
- #define USBD MAX NUM CONFIGURATION 1U
- #define USBD\_MAX\_STR\_DESC\_SIZ 512U
- #define USBD\_SUPPORT\_USER\_STRING 0U
- #define USBD\_DEBUG\_LEVEL 3U
- #define USBD LPM ENABLED 0U
- #define USBD\_SELF\_POWERED 1U
- #define DEVICE\_FS 0
- #define DEVICE\_HS 1
- #define USBD\_malloc malloc
- #define USBD free free
- #define USBD\_memset memset
- #define USBD\_memcpy memcpy
- #define USBD\_Delay HAL\_Delay
- #define USBD UsrLog(...)
- #define USBD\_ErrLog(...)
- #define USBD\_DbgLog(...)

### 7.45.1 Detailed Description

: Header for usbd\_conf.c file.

Version

: v1.0\_Cube

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# 7.46 src/usbd\_desc.h File Reference

: Header for usbd\_conf.c file.

#include "usbd\_def.h"

# **Macros**

- #define DEVICE\_ID1 (UID\_BASE)
- #define DEVICE\_ID2 (UID\_BASE + 0x4)
- #define DEVICE\_ID3 (UID\_BASE + 0x8)
- #define USB\_SIZ\_STRING\_SERIAL 0x1A

# **Variables**

- USBD\_DescriptorsTypeDef HS\_Desc
- USBD\_DescriptorsTypeDef FS\_Desc

# 7.46.1 Detailed Description

: Header for usbd\_conf.c file.

Version

: v1.0 Cube

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# 7.47 src/util\_bsp\_sd\_diskio.h File Reference

```
#include <stdint.h>
```

### Classes

• struct DSY\_SD\_CardInfoTypeDef

### **Macros**

- #define DSY BSP SD DISKIO H
- #define BSP\_SD\_CardInfo DSY\_SD\_CardInfoTypeDef
- #define MSD OK ((uint8 t)0x00)
- #define MSD ERROR ((uint8 t)0x01)
- #define MSD ERROR SD NOT PRESENT ((uint8 t)0x02)
- #define SD\_TRANSFER\_OK ((uint8\_t)0x00)
- #define SD\_TRANSFER\_BUSY ((uint8\_t)0x01)
- #define SD\_PRESENT ((uint8\_t)0x01)
- #define SD\_NOT\_PRESENT ((uint8\_t)0x00)
- #define SD DATATIMEOUT ((uint32 t)100000000)

#### **Functions**

- uint8\_t BSP\_SD\_Init (void)
- uint8 t BSP SD ITConfig (void)
- uint8\_t BSP\_SD\_ReadBlocks (uint32\_t \*pData, uint32\_t ReadAddr, uint32\_t NumOfBlocks, uint32\_t Timeout)
- uint8\_t BSP\_SD\_WriteBlocks (uint32\_t \*pData, uint32\_t WriteAddr, uint32\_t NumOfBlocks, uint32\_t Timeout)
- uint8\_t BSP\_SD\_ReadBlocks\_DMA (uint32\_t \*pData, uint32\_t ReadAddr, uint32\_t NumOfBlocks)
- uint8\_t BSP\_SD\_WriteBlocks\_DMA (uint32\_t \*pData, uint32\_t WriteAddr, uint32\_t NumOfBlocks)
- uint8\_t BSP\_SD\_Erase (uint32\_t StartAddr, uint32\_t EndAddr)
- uint8\_t BSP\_SD\_GetCardState (void)
- void BSP SD GetCardInfo (DSY SD CardInfoTypeDef \*CardInfo)
- uint8 t BSP SD IsDetected (void)
- void BSP SD AbortCallback (void)
- · void BSP\_SD\_WriteCpltCallback (void)
- void BSP\_SD\_ReadCpltCallback (void)

### 7.47.1 Macro Definition Documentation

# 7.47.1.1 BSP\_SD\_CardInfo

#define BSP\_SD\_CardInfo DSY\_SD\_CardInfoTypeDef

&

# 7.47.1.2 DSY\_BSP\_SD\_DISKIO\_H

#define DSY\_BSP\_SD\_DISKIO\_H

&

```
7.47.1.3 MSD_ERROR
#define MSD_ERROR ((uint8_t)0x01)
7.47.1.4 MSD_ERROR_SD_NOT_PRESENT
\#define MSD\_ERROR\_SD\_NOT\_PRESENT ((uint8_t)0x02)
7.47.1.5 MSD_OK
#define MSD_OK ((uint8_t)0x00)
7.47.1.6 SD_DATATIMEOUT
#define SD_DATATIMEOUT ((uint32_t)100000000)
7.47.1.7 SD_NOT_PRESENT
#define SD_NOT_PRESENT ((uint8_t)0x00)
&
7.47.1.8 SD_PRESENT
#define SD_PRESENT ((uint8_t)0x01)
&
7.47.1.9 SD_TRANSFER_BUSY
#define SD_TRANSFER_BUSY ((uint8_t)0x01)
&
7.47.1.10 SD_TRANSFER_OK
#define SD_TRANSFER_OK ((uint8_t)0x00)
&
```

# 7.47.2 Function Documentation

# 7.47.2.1 BSP\_SD\_AbortCallback()

These functions can be modified in case the current settings (e.g. DMA stream) need to be changed for specific application needs /n

Abort the callback

# 7.47.2.2 BSP\_SD\_Erase()

Erase a section of memory

### **Parameters**

StartAddr	Address to start erasing at
EndAddr	Address to stop erasing at

# Returns

card state, ERROR, etc.

# 7.47.2.3 BSP\_SD\_GetCardInfo()

### **Parameters**

# **Parameters**

CardInfo &

```
7.47.2.4 BSP_SD_GetCardState()
```

Returns

card state, ERROR, etc.

# 7.47.2.5 BSP\_SD\_Init()

Returns

card state, ERROR, etc.

# 7.47.2.6 BSP\_SD\_IsDetected()

Returns

Is card detected

# 7.47.2.7 BSP\_SD\_ITConfig()

Returns

card state, ERROR, etc.

# 7.47.2.8 BSP\_SD\_ReadBlocks()

# **Parameters**

*pData	&
ReadAddr	Address to read from
NumOfBlocks	Number of blocks to be read
Timeout	Timeout len in ms

#### Returns

OK ERROR, etc.

# 7.47.2.9 BSP\_SD\_ReadBlocks\_DMA()

### No timeout

### **Parameters**

*pData	&
ReadAddr	Address to read from
NumOfBlocks	Number of blocks to be read

#### Returns

card state, ERROR, etc.

# 7.47.2.10 BSP\_SD\_ReadCpltCallback()

Write complete callback

# 7.47.2.11 BSP\_SD\_WriteBlocks()

# **Parameters**

*pData	&
WriteAddr	Address to write to
NumOfBlocks	Number of blocks to be written
Timeout	Timeout len in ms

### Returns

card state, ERROR, etc.

# 7.47.2.12 BSP\_SD\_WriteBlocks\_DMA()

# No timeout

# **Parameters**

*pData	&
WriteAddr	Address to write to
NumOfBlocks	Number of blocks to be read

### Returns

card state, ERROR, etc.

# 7.47.2.13 BSP\_SD\_WriteCpltCallback()

Read complete callback

# 7.48 src/util\_color.h File Reference

#include <stdint.h>

# Classes

· class daisy::Color

# **Macros**

• #define DSY\_COLOR\_H

### 7.48.1 Macro Definition Documentation

# 7.48.1.1 DSY\_COLOR\_H

```
#define DSY_COLOR_H
```

I'd like for it to be easy and not Color::PresetColor::Foo-There's no way to change a color once its been created (without unintuitively reiniting it).

# 7.49 src/util\_hal\_map.h File Reference

```
#include "stm32h7xx_hal.h"
#include "daisy_core.h"
#include "per_i2c.h"
```

# **Functions**

- GPIO\_TypeDef \* dsy\_hal\_map\_get\_port (dsy\_gpio\_pin \*p)
- uint16\_t dsy\_hal\_map\_get\_pin (dsy\_gpio\_pin \*p)
- I2C\_HandleTypeDef \* dsy\_hal\_map\_get\_i2c (dsy\_i2c\_handle \*p)

# **Variables**

- I2C\_HandleTypeDef hi2c1
- I2C HandleTypeDef hi2c2
- I2C\_HandleTypeDef hi2c3
- I2C\_HandleTypeDef hi2c4

### 7.49.1 Function Documentation

# 7.49.1.1 dsy\_hal\_map\_get\_i2c()

#### **Parameters**

```
*p dsy_i2c_handle to get
```

# Returns

The I2C\_HandleTypeDef for the given \*p

### 7.49.1.2 dsy\_hal\_map\_get\_pin()

#### **Parameters**

```
*p Pin pin to get
```

### Returns

HAL GPIO Pin as used in the HAL from a dsy\_gpio\_pin input.

## 7.49.1.3 dsy\_hal\_map\_get\_port()

#### **Parameters**

\*p Pin pin to get

### Returns

HAL GPIO\_TypeDef as used in the HAL from a dsy\_gpio\_pin input.

### 7.49.2 Variable Documentation

### 7.49.2.1 hi2c1

```
I2C_HandleTypeDef hi2c1
```

global structs, and helper functions for interfacing with the stm32 HAL library while it remains a dependancy. This file should only be included from source files (c/cpp) Including it from a header within libdaisy would expose the entire HAL to the users. This should be an option for users, but should not be required externs of HAL handles...

# 7.49.2.2 hi2c2

I2C\_HandleTypeDef hi2c2

externs of HAL handles...

### 7.49.2.3 hi2c3

I2C\_HandleTypeDef hi2c3

externs of HAL handles...

### 7.49.2.4 hi2c4

I2C\_HandleTypeDef hi2c4

externs of HAL handles...

# 7.50 src/util\_ringbuffer.h File Reference

```
#include <algorithm>
```

# Classes

- class daisy::RingBuffer< T, size >
- class daisy::RingBuffer< T, 0 >

# 7.51 src/util\_unique\_id.h File Reference

```
#include "daisy_core.h"
```

# **Functions**

void dsy\_get\_unique\_id (uint32\_t \*w0, uint32\_t \*w1, uint32\_t \*w2)

# 7.51.1 Function Documentation

# 7.51.1.1 dsy\_get\_unique\_id()

Returns 96-bit Unique ID of the MCU

Author

shensley

Date

May 2020 fills the three pointer arguments with the unique ID of the MCU.

# **Parameters**

*w0	First pointer
*W1	Second pointer
* <i>w2</i>	Third pointer

# 7.52 src/util\_wav\_format.h File Reference

```
#include <stdint.h>
```

# Classes

struct WAV\_FormatTypeDef

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