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DDA:
#include <stdio.h>
#include <math.h>
#include <graphics.h>
// Function to implement DDA algorithm
void drawLine(int x0, int y0, int x1, int y1)
  int dx = x1 - x0;
  int dy = y1 - y0;
  int steps = abs(dx) > abs(dy)? abs(dx): abs(dy);
  float xIncrement = dx / (float) steps;
  float yIncrement = dy / (float) steps;
  float x = x0;
  float y = y0;
  // Put the first point
  putpixel(round(x), round(y), WHITE);
  for (int i = 0; i < steps; i++) {
     x += xIncrement;
     y += yIncrement;
     putpixel(round(x), round(y), WHITE);
  }
}
int main()
  int gd = DETECT, gm;
  initgraph(&gd, &gm, NULL);
  int x0, y0, x1, y1;
  // Taking user input for start and end points
  printf("Enter the starting coordinates (x0, y0): ");
  scanf("%d %d", &x0, &y0);
  printf("Enter the ending coordinates (x1, y1): ");
  scanf("%d %d", &x1, &y1);
  // Draw the line using DDA
```

```
drawLine(x0, y0, x1, y1);
  // Keep the graphics window open until a key is pressed
  getch();
  closegraph();
  return 0;
}
Bresenham's Algo:
#include <stdio.h>
#include <graphics.h>
void bresenham(int x0, int y0, int x1, int y1)
  int dx = abs(x1 - x0);
  int dy = abs(y1 - y0);
  int sx = (x0 < x1) ? 1 : -1;
  int sy = (y0 < y1)? 1:-1;
  int err = dx - dy;
  while (1) {
     putpixel(x0, y0, WHITE); // Plot the pixel at (x0, y0)
     if (x0 == x1 \&\& y0 == y1) // If we reach the end point
       break;
     int e2 = 2 * err;
     if (e2 > -dy) {
       err -= dy;
       x0 += sx;
     }
     if (e2 < dx) {
       err += dx;
       y0 += sy;
 }
```

```
int main()
{
  int gd = DETECT, gm;
  initgraph(&gd, &gm, NULL);
  int x0, y0, x1, y1;
  // Taking user input for start and end points
  printf("Enter the starting coordinates (x0, y0): ");
  scanf("%d %d", &x0, &y0);
  printf("Enter the ending coordinates (x1, y1): ");
  scanf("%d %d", &x1, &y1);
  // Draw the line using Bresenham's algorithm
  bresenham(x0, y0, x1, y1);
  // Keep the graphics window open until a key is pressed
  getch();
  closegraph();
  return 0;
}
Midpoint circle Algorithm:
#include <stdio.h>
#include <graphics.h>
// Function to plot points in all octants using circle symmetry
void plotCirclePoints(int xc, int yc, int x, int y)
{
  putpixel(xc + x, yc + y, WHITE); // 1st Octant
  putpixel(xc - x, yc + y, WHITE); // 2nd Octant
  putpixel(xc + x, yc - y, WHITE); // 3rd Octant
  putpixel(xc - x, yc - y, WHITE); // 4th Octant
  putpixel(xc + y, yc + x, WHITE); // 5th Octant
  putpixel(xc - y, yc + x, WHITE); // 6th Octant
  putpixel(xc + y, yc - x, WHITE); // 7th Octant
  putpixel(xc - y, yc - x, WHITE); // 8th Octant
}
// Midpoint Circle Drawing Algorithm
void midpointCircle(int xc, int yc, int r)
{
```

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int x = 0;
  int y = r;
  int p = 1 - r; // Initial decision parameter
  // Plot the initial point
  plotCirclePoints(xc, yc, x, y);
  while (x < y) {
     X++;
     // Decision parameter update
     if (p < 0) {
       p += 2 * x + 1;
     } else {
        y--;
        p += 2 * (x - y) + 1;
     plotCirclePoints(xc, yc, x, y);
  }
}
int main()
  int gd = DETECT, gm;
  initgraph(&gd, &gm, NULL);
  int xc, yc, r;
  // Taking user input for center and radius of the circle
  printf("Enter the center coordinates (xc, yc): ");
  scanf("%d %d", &xc, &yc);
  printf("Enter the radius of the circle: ");
  scanf("%d", &r);
  // Draw the circle using Midpoint algorithm
  midpointCircle(xc, yc, r);
  // Keep the graphics window open until a key is pressed
  getch();
  closegraph();
  return 0;
```

```
}
Boundary Fill:
#include <stdio.h>
#include <graphics.h>
// 8-connected Boundary Fill
void boundaryFill8(int x, int y, int fill_color, int boundary_color)
{
  int current color = getpixel(x, y);
  if (current_color != boundary_color && current_color != fill_color)
     putpixel(x, y, fill_color);
     delay(1); // To visualize the filling process
     // Recursively fill the adjacent pixels
     boundaryFill8(x + 1, y, fill color, boundary color); // Right
     boundaryFill8(x - 1, y, fill_color, boundary_color); // Left
     boundaryFill8(x, y + 1, fill color, boundary color); // Down
     boundaryFill8(x, y - 1, fill color, boundary color); // Up
     boundaryFill8(x + 1, y + 1, fill_color, boundary_color); // Bottom-right diagonal
     boundaryFill8(x - 1, y - 1, fill_color, boundary_color); // Top-left diagonal
     boundaryFill8(x + 1, y - 1, fill color, boundary color); // Top-right diagonal
     boundaryFill8(x - 1, y + 1, fill_color, boundary_color); // Bottom-left diagonal
  }
}
int main()
  int gd = DETECT, gm;
  initgraph(&gd, &gm, NULL);
  // Draw a rectangle boundary
  rectangle(150, 100, 350, 300);
  // Perform 8-connected boundary fill
  boundaryFill8(200, 150, GREEN, WHITE);
  getch();
  closegraph();
  return 0;
}
```

```
Flood Fill:
#include <stdio.h>
#include <graphics.h>
// 8-connected Flood Fill
void floodFill8(int x, int y, int fill_color, int old_color)
{
  int current_color = getpixel(x, y);
  if (current color == old color)
     putpixel(x, y, fill_color);
     delay(1); // To visualize the filling process
     // Recursively fill the adjacent pixels
     floodFill8(x + 1, y, fill_color, old_color); // Right
     floodFill8(x - 1, y, fill_color, old_color); // Left
     floodFill8(x, y + 1, fill color, old color); // Down
     floodFill8(x, y - 1, fill_color, old_color); // Up
     floodFill8(x + 1, y + 1, fill color, old color); // Bottom-right diagonal
     floodFill8(x - 1, y - 1, fill_color, old_color); // Top-left diagonal
     floodFill8(x + 1, y - 1, fill_color, old_color); // Top-right diagonal
     floodFill8(x - 1, y + 1, fill color, old color); // Bottom-left diagonal
  }
}
int main()
  int gd = DETECT, gm;
  initgraph(&gd, &gm, NULL);
  // Draw a rectangle with white color inside
  rectangle(150, 100, 350, 300);
  floodFill8(200, 150, YELLOW, BLACK);
  getch();
  closegraph();
  return 0;
}
2d Transformation:
#include <stdio.h>
#include <graphics.h>
#include <math.h>
```

```
// Function to perform translation
void translate(int *x, int *y, int tx, int ty)
  *x += tx;
  *y += ty;
// Function to perform scaling
void scale(int *x, int *y, int sx, int sy)
  *x *= sx;
  *y *= sy;
// Function to perform rotation
void rotate(int *x, int *y, int angle, int xc, int yc)
{
  float radian = angle * (PI / 180);
  int x new = xc + (*x - xc) * cos(radian) - (*y - yc) * sin(radian);
  int y_new = yc + (*x - xc) * sin(radian) + (*y - yc) * cos(radian);
  *x = x_new;
  *y = y_new;
}
// Function to draw a triangle
void drawTriangle(int x1, int y1, int x2, int y2, int x3, int y3)
  line(x1, y1, x2, y2);
  line(x2, y2, x3, y3);
  line(x3, y3, x1, y1);
}
int main()
  int gd = DETECT, gm;
  initgraph(&gd, &gm, NULL);
  int choice, tx, ty, sx, sy, angle;
  int x1 = 100, y1 = 100, x2 = 150, y2 = 50, x3 = 200, y3 = 100; // Triangle vertices
  // Original Triangle
```

```
setcolor(WHITE);
drawTriangle(x1, y1, x2, y2, x3, y3);
printf("Original Triangle drawn.\n");
// User input for the type of transformation
printf("Choose a transformation:\n");
printf("1. Translation\n");
printf("2. Scaling\n");
printf("3. Rotation\n");
printf("Enter your choice: ");
scanf("%d", &choice);
switch (choice)
  case 1:
     // Translation
     printf("Enter translation factors (tx, ty): ");
     scanf("%d %d", &tx, &ty);
     // Translate the triangle
     translate(&x1, &y1, tx, ty);
     translate(&x2, &y2, tx, ty);
     translate(&x3, &y3, tx, ty);
     setcolor(RED);
     drawTriangle(x1, y1, x2, y2, x3, y3);
     printf("Triangle translated.\n");
     break;
  case 2:
     // Scaling
     printf("Enter scaling factors (sx, sy): ");
     scanf("%d %d", &sx, &sy);
     // Scale the triangle
     scale(&x1, &y1, sx, sy);
     scale(&x2, &y2, sx, sy);
     scale(&x3, &y3, sx, sy);
     setcolor(GREEN);
     drawTriangle(x1, y1, x2, y2, x3, y3);
     printf("Triangle scaled.\n");
     break;
```

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case 3:
       // Rotation
        printf("Enter the angle of rotation (in degrees): ");
       scanf("%d", &angle);
       // Rotate the triangle around its center (x2, y2)
        rotate(&x1, &y1, angle, x2, y2);
        rotate(&x3, &y3, angle, x2, y2);
       setcolor(BLUE);
       drawTriangle(x1, y1, x2, y2, x3, y3);
        printf("Triangle rotated.\n");
       break;
     default:
       printf("Invalid choice!\n");
       break;
  }
  getch();
  closegraph();
  return 0;
}
Scaling & Sheering:
#include <stdio.h>
#include <graphics.h>
#define MAX_POINTS 3
// Function to perform shearing
void shear(int *x, int *y, float shx, float shy)
{
  int newX = *x + (shx * *y);
  int newY = *y + (shy * *x);
  *x = newX;
  *y = newY;
// Function to perform reflection
void reflect(int *x, int *y, char axis)
{
```

```
if (axis == 'x') {
     *y = -*y; // Reflection over x-axis
  } else if (axis == 'y') {
     *x = -*x; // Reflection over y-axis
  } else if (axis == 'xy') {
     *x = -*x; // Reflection over y-axis
     *y = -*y; // Reflection over x-axis
  }
}
// Function to draw a triangle
void drawTriangle(int x1, int y1, int x2, int y2, int x3, int y3)
  line(x1, y1, x2, y2);
  line(x2, y2, x3, y3);
  line(x3, y3, x1, y1);
}
int main()
  int gd = DETECT, gm;
  initgraph(&gd, &gm, NULL);
  int x[MAX POINTS] = {100, 150, 200}; // Triangle x-coordinates
  int y[MAX_POINTS] = {100, 50, 100}; // Triangle y-coordinates
  // Original Triangle
  setcolor(WHITE);
  drawTriangle(x[0], y[0], x[1], y[1], x[2], y[2]);
  printf("Original Triangle drawn.\n");
  // Shearing transformation
  float shx, shy;
  printf("Enter shearing factors (shx, shy): ");
  scanf("%f %f", &shx, &shy);
  // Apply shearing transformation
  for (int i = 0; i < MAX POINTS; i++)
     shear(&x[i], &y[i], shx, shy);
  }
  setcolor(RED);
  drawTriangle(x[0], y[0], x[1], y[1], x[2], y[2]);
```

```
printf("Triangle sheared.\n");
  // Reflection transformation
  char axis:
  printf("Enter axis for reflection (x, y, or xy): ");
  scanf(" %c", &axis);
  // Apply reflection transformation
  for (int i = 0; i < MAX_POINTS; i++)
     reflect(&x[i], &y[i], axis);
  }
  setcolor(GREEN);
  drawTriangle(x[0], y[0], x[1], y[1], x[2], y[2]);
  printf("Triangle reflected.\n");
  getch();
  closegraph();
  return 0;
}
Cohen sutherland algorithm:
#include <stdio.h>
#include <graphics.h>
// Define the region codes
#define INSIDE 0 // 0000
#define LEFT 1 // 0001
#define RIGHT 2 // 0010
#define BOTTOM 4 // 0100
#define TOP 8 // 1000
// Function to compute the region code for a point
int computeCode(float x, float y, float xmin, float ymin, float xmax, float ymax) {
  int code = INSIDE:
  if (x < xmin)
                   // to the left of the clipping window
     code |= LEFT;
  else if (x > xmax) // to the right of the clipping window
     code |= RIGHT;
  if (y < ymin)
                   // below the clipping window
     code |= BOTTOM;
```

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else if (y > ymax) // above the clipping window
     code |= TOP;
  return code;
}
// Cohen-Sutherland line clipping algorithm
void cohenSutherlandLineClip(float x1, float y1, float x2, float y2, float xmin, float ymin, float
xmax, float ymax) {
  int code1 = computeCode(x1, y1, xmin, ymin, xmax, ymax);
  int code2 = computeCode(x2, y2, xmin, ymin, xmax, ymax);
  int accept = 0;
  while (1) {
     if (!(code1 | code2)) {
       // Both points inside the clipping window
       accept = 1;
       break;
     } else if (code1 & code2) {
       // Both points are outside the clipping window
       break;
     } else {
       int codeOut:
       float x, y;
       // Choose one of the points outside the clipping window
       if (code1 != INSIDE) {
          codeOut = code1;
       } else {
          codeOut = code2;
       }
       // Find the intersection point
       if (codeOut & TOP) {
          // Point is above the clipping window
          x = x1 + (x2 - x1) * (ymax - y1) / (y2 - y1);
          y = ymax;
       } else if (codeOut & BOTTOM) {
          // Point is below the clipping window
          x = x1 + (x2 - x1) * (ymin - y1) / (y2 - y1);
          y = ymin;
       } else if (codeOut & RIGHT) {
          // Point is to the right of the clipping window
          y = y1 + (y2 - y1) * (xmax - x1) / (x2 - x1);
```

```
x = xmax:
       } else if (codeOut & LEFT) {
          // Point is to the left of the clipping window
          y = y1 + (y2 - y1) * (xmin - x1) / (x2 - x1);
          x = xmin;
       }
       // Now we move the outside point to the intersection point
       if (codeOut == code1) {
          x1 = x;
          y1 = y;
          code1 = computeCode(x1, y1, xmin, ymin, xmax, ymax);
       } else {
          x2 = x;
          y2 = y;
          code2 = computeCode(x2, y2, xmin, ymin, xmax, ymax);
       }
    }
  }
  if (accept) {
     // Draw the line after clipping
     line(x1, y1, x2, y2);
  }
}
int main() {
  int gd = DETECT, gm;
  initgraph(&gd, &gm, NULL);
  float xmin = 200, ymin = 200, xmax = 400, ymax = 400; // Clipping window
  rectangle(xmin, ymin, xmax, ymax); // Draw clipping window
  float x1 = 150, y1 = 250; // Start point of the line
  float x2 = 450, y2 = 250; // End point of the line
  setcolor(WHITE);
  line(x1, y1, x2, y2); // Draw the original line
  setcolor(RED);
  cohenSutherlandLineClip(x1, y1, x2, y2, xmin, ymin, xmax, ymax); // Clip the line
  getch();
  closegraph();
```

```
return 0;
}
Beizer Curve:
#include <stdio.h>
#include <graphics.h>
#define MAX_POINTS 10 // Maximum number of control points
// Function to compute the Bezier curve points using de Casteljau's algorithm
void bezierCurve(int controlPoints[][2], int n, int steps) {
  float t, x, y;
  for (int i = 0; i \le steps; i++) {
     t = (float)i / (float)steps;
     // Create a temporary array to hold the points for the current iteration
     int temp[MAX_POINTS][2];
     // Copy control points to temp array
     for (int j = 0; j < n; j++) {
        temp[j][0] = controlPoints[j][0];
        temp[j][1] = controlPoints[j][1];
     }
     // Perform de Casteljau's algorithm
     for (int j = 1; j < n; j++) {
        for (int k = 0; k < n - j; k++) {
           temp[k][0] = (1 - t) * temp[k][0] + t * temp[k + 1][0];
           temp[k][1] = (1 - t) * temp[k][1] + t * temp[k + 1][1];
        }
     }
     // Draw the point on the Bezier curve
     putpixel((int)temp[0][0], (int)temp[0][1], WHITE);
  }
}
// Function to draw the control points and lines
void drawControlPolygon(int controlPoints[][2], int n) {
  for (int i = 0; i < n; i++) {
     putpixel(controlPoints[i][0], controlPoints[i][1], YELLOW);
     if (i > 0) {
        line(controlPoints[i - 1][0], controlPoints[i - 1][1], controlPoints[i][0], controlPoints[i][1]);
     }
```

```
int main() {
  int gd = DETECT, gm;
  initgraph(&gd, &gm, NULL);
  int controlPoints[MAX_POINTS][2];
  int n;
  printf("Enter the number of control points (max %d): ", MAX_POINTS);
  scanf("%d", &n);
  // Input control points
  for (int i = 0; i < n; i++) {
     printf("Enter coordinates for control point %d (x y): ", i + 1);
     scanf("%d %d", &controlPoints[i][0], &controlPoints[i][1]);
  }
  // Draw control polygon
  drawControlPolygon(controlPoints, n);
  // Draw Bezier curve
  bezierCurve(controlPoints, n, 1000); // 1000 steps for smooth curve
  getch();
  closegraph();
  return 0;
}
```