Discriminative Embeddings of Latent Variable Models for Structured Data

by Hanjun Dai, Bo Dai, Le Song

presentation by Breandan Considine McGill University

breandan.considine@mail.mcgill.ca

April 10, 2022

What is a kernel?

A feature map transforms the input space to a feature space:

Input space Feature space
$$\varphi: \stackrel{\textstyle \mathsf{Feature space}}{\textstyle } \xrightarrow{\textstyle \mathsf{R}^m} \qquad \qquad (1)$$

A kernel function k is a real-valued function with two inputs:

$$k: \Omega \times \Omega \to \mathbb{R} \tag{2}$$

Kernel functions generalize the notion of inner products to feature maps:

$$k(\mathbf{x}, \mathbf{y}) = \varphi(\mathbf{x})^{\mathsf{T}} \varphi(\mathbf{y}) \tag{3}$$

Gives us $\varphi(x)^{\mathsf{T}}\varphi(y)$ without directly computing $\varphi(x)$ or $\varphi(y)$.

What is a kernel?

Consider the univariate polynomial regression algorithm:

$$\hat{f}(x;\beta) = \beta \varphi(x) = \beta_0 + \beta_1 x + \beta_2 x^2 + \dots + \beta_m x^m = \sum_{j=0}^m \beta_j x^j$$
 (4)

Where $\varphi(x) = [1, x, x^2, x^3, \dots, x^m]$. We seek β minimizing the error:

$$\beta^* = \underset{\beta}{\operatorname{argmin}} ||\mathbf{Y} - \hat{\mathbf{f}}(\mathbf{X}; \beta)||^2$$
 (5)

Can solve for β^* using the normal equation or gradient descent:

$$\boldsymbol{\beta}^* = (\mathsf{X}^\mathsf{T}\mathsf{X})^{-1}\mathsf{X}^\mathsf{T}\mathsf{Y} \tag{6}$$

$$\beta' \leftarrow \beta - \alpha \nabla_{\beta} ||\mathbf{Y} - \hat{\mathbf{f}}(\mathbf{X}; \beta)||^2$$
 (7)

What happens if we want to approximate a multivariate polynomial?

$$z(x,y) = 1 + \beta_x x + \beta_y y + \beta_{xy} xy + \beta_{x^2} x^2 + \beta_{y^2} y^2 + \beta_{xy^2} xy^2 + \dots$$
 (8)

What is a kernel?

Consider the polynomial kernel $k(x, y) = (1 + x^T y)^2$ with $x, y \in \mathbb{R}^2$.

$$k(x,y) = (1 + x^{T}y)^{2} = (1 + x_{1} y_{1} + x_{2} y_{2})^{2}$$

$$= 1 + x_{1}^{2} y_{1}^{2} + x_{2}^{2} y_{2}^{2} + 2x_{1} y_{1} + 2x_{2} y_{2} + 2x_{1} x_{2} y_{1} y_{2}$$
(10)

This gives us the same result as computing the 6 dimensional feature map:

$$k(\mathbf{x}, \mathbf{y}) = \varphi(\mathbf{x})^{\mathsf{T}} \varphi(\mathbf{y}) \tag{11}$$

$$= [1, x_1^2, x_2^2, \sqrt{2}x_1, \sqrt{2}x_2, \sqrt{2}x_1x_2]^{\mathsf{T}} \begin{bmatrix} 1\\ y_1^2\\ y_2^2\\ \sqrt{2}y_1\\ \sqrt{2}y_2\\ \sqrt{2}y_1y_2 \end{bmatrix}$$
(12)

But does not require computing $\varphi(x)$ or $\varphi(y)$.

Examples of common kernels

Popular kernels

Polynomial	$k(x,y) := (x^T y + r)^n$	$x, y \in \mathbb{R}^d, n \in \mathbb{N}, r \ge 0$
Laplacian	$k(x,y) := \exp\left(-\frac{\ x-y\ }{\sigma}\right)$	$x, y \in \mathbb{R}^d, \sigma > 0$
Gaussian RBF	$k(x,y) := \exp\left(-\frac{\ x-y\ ^2}{2\sigma^2}\right)$	$x,y\in\mathbb{R}^d,\sigma>0$

Popular Graph Kernels

RW	$k_{ imes}(G,H) \coloneqq \sum\limits_{i,j=1}^{ V_{ imes} } [\sum\limits_{n=1}^{\infty} \lambda^n A_{ imes}^n]_{ij} = e^{\intercal} (I - \lambda A_{ imes})^{-1} e$	$\mathcal{O}(n^6)$	
SP	$k_{SP}(G,H) := \sum_{s_1 \in SD(G)} \sum_{s_2 \in SD(H)} k(s_1,s_2)$		
	$I^{(i)}(G) \coloneqq egin{cases} deg_{v}, orall v \in G & i = 1 \ HASH(\{\{I^{(i-1)}(u), orall u \in \mathcal{N}(v)\}\}) & i > 1 \end{cases}$		
WL	$HASH(\{\{I^{(i-1)}(u), \forall u \in \mathcal{N}(v)\}\}) i > 1$	$\mathcal{O}(hm)$	
	$k_{WL}(G, H) := \langle \psi_{WL}(G), \psi_{WL}(H) \rangle$		

https://people.mpi-inf.mpg.de/~mehlhorn/ftp/genWLpaper.pdf

Positive definite kernels

Positive Definite Matrix

A symmetric matrix $K \in \mathbb{R}^{N^2}$ is **positive definite** if $x^TKx > 0, \forall x \in \mathbb{R}^N \setminus 0$.

Positive Definite Kernel

A symmetric kernel k is called positive definite on Ω if its associated kernel matrix $K = [k(x_i, x_j)]_{i,i=0}^N$ is positive definite $\forall N \in \mathbb{N}, \forall \{x_1, \dots, x_N\} \subset \Omega$.

http://www.math.iit.edu/~fass/PDKernels.pdf

What is an inner product space?

Linear function

Let X be a vector space over \mathbb{R} . A function $f: X \to \mathbb{R}$ is **linear** iff $f(\alpha x) = \alpha f(x)$ and f(x + z) = f(x) + f(z) for all $\alpha \in \mathbb{R}, x, z \in X$.

Inner product space

X is an **inner product space** if there exists a symmetric bilinear map $\langle \cdot, \cdot \rangle : X \times X \to \mathbb{R}$ if $\forall x \in X, \langle x, x \rangle > 0$ (i.e. is positive definite).

Cauchy-Schwartz Inequality

If X is an inner product space, then $\forall u, v \in \mathcal{X}, |\langle u, v \rangle|^2 \leq \langle u, u \rangle \cdot \langle v, v \rangle$.

Scalar Product Vector Dot Product Random Variable

$$\langle x, y \rangle := xy \qquad \left\langle \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}, \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} \right\rangle := x^{\mathsf{T}}y \qquad \langle X, Y \rangle := \mathbb{E}(XY)$$

What is a Hilbert space?

Let $d: X \times X \to \mathbb{R}^{\geq 0}$ be a metric on the space X.

Cauchy sequence

A sequence $\{x_n\}$ is called a **Cauchy sequence** if

 $\forall \varepsilon > 0, \exists N \in \mathbb{N}, \text{ such that } \forall n, m \geq N, d(x_n, x_m) \leq \varepsilon.$

Completeness

X is called **complete** if every Cauchy sequence converges to a point in X.

Separability

X is called **separable** if there exists a sequence $\{x_n\}_{n=1}^{\infty} \in X$ s.t. every nonempty open subset of X contains at least one element of the sequence.

Hilbert space

A Hilbert space ${\cal H}$ is an inner product space that is complete and separable.

Properties of Hilbert Spaces

Hilbert space inner products are kernels

The inner product $\langle \cdot, \cdot \rangle_{\mathcal{H}} : \mathcal{H} \times \mathcal{H} \to \mathbb{R}$ is a positive definite kernel:

$$\sum_{i,j=1}^{n} c_{i} c_{j}(x_{i}, x_{j})_{\mathcal{H}} = \left(\sum_{i=1}^{n} c_{i} x_{i}, \sum_{j=1}^{n} c_{j} x_{j} \right)_{\mathcal{H}} = \left\| \sum_{i=1}^{n} c_{i} x_{i} \right\|_{\mathcal{H}}^{2} \ge 0$$

Reproducing Kernel Hilbert Space (RKHS)

Any continuous, symmetric, positive definite kernel $k: X \times X \to \mathbb{R}$ has a corresponding Hilbert space, which induces a feature map $\varphi: X \to \mathcal{H}$ satisfying $k(x,y) = \langle \varphi(x), \varphi(y) \rangle_{\mathcal{H}}$.

http://jmlr.csail.mit.edu/papers/volume11/vishwanathan10a/vishwanathan10a.pdf https://marcocuturi.net/Papers/pdk_in_ml.pdf

Hilbert Space Embedding of Distributions

Maps distributions into potentially infinite dimensional feature spaces:

$$\mu_X := \mathbb{E}_X[\phi(X)] = \int_{\mathcal{X}} \phi(x) p(x) dx : \mathcal{P} \mapsto \mathcal{F}$$
 (13)

By choosing the right kernel, we can make this mapping injective.

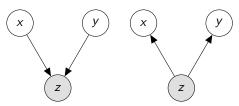
$$f(p(x)) = \tilde{f}(\mu_x), f: \mathcal{P} \mapsto \mathbb{R}$$
 (14)

$$\mathcal{T} \circ p(x) = \tilde{\mathcal{T}} \circ \mu_x, \tilde{\mathcal{T}} : \mathcal{F} \mapsto \mathbb{R}^d$$
 (15)

Belief Networks

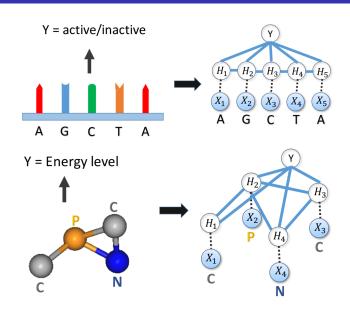
Belief network is a distribution of the form:

$$P(x_1,...,x_D) = \prod_{i=1}^{D} P(x_i|pa(x_i))$$
 (16)



$$P(X, Y|Z) \propto P(Z|X, Y)P(X)P(Y) \ P(X, Y|Z) = P(X|Z)P(Y|Z)$$

Latent Variable Models



Embedded mean field

Algorithm 1 Embedded Mean Field

```
1: Input: parameter W in \widetilde{\mathcal{T}}
2: Initialize \widetilde{\mu}_i^{(0)} = \mathbf{0}, for all i \in \mathcal{V}
3: for t = 1 to T do
4: for i \in \mathcal{V} do
5: l_i = \sum_{j \in \mathcal{N}(i)} \widetilde{\mu}_i^{(t-1)}
           \widetilde{\mu}_i^{(t)} = \sigma(W_1 x_i + W_2 l_i)
7: end for
8: end for{fixed point equation update}
9: return \{\widetilde{\mu}_i^T\}_{i\in\mathcal{V}}
```

Embedded loopy belief propagation

Algorithm 2 Embedding Loopy BP

```
1: Input: parameter W in \mathcal{T}_1 and \mathcal{T}_2
 2: Initialize \widetilde{\nu}_{ij}^{(0)} = \mathbf{0}, for all (i, j) \in \mathcal{E}
 3: for t = 1 to T do
 4: for (i, j) \in \mathcal{E} do
               \widetilde{\nu}_{ij}^t = \sigma(W_1 x_i + W_2 \sum_{k \in \mathcal{N}(i) \setminus j} \widetilde{\nu}_{ki}^{(t-1)})
         end for
 7: end for
 8: for i \in \mathcal{V} do
       \widetilde{\mu}_i = \sigma(W_3 x_i + W_4 \sum_{k \in \mathcal{N}(i) \setminus i} \widetilde{\nu}_{ki}^{(T)})
10: end for
11: return \{\widetilde{\mu}_i\}_{i\in\mathcal{V}}
```

Discriminative Embedding

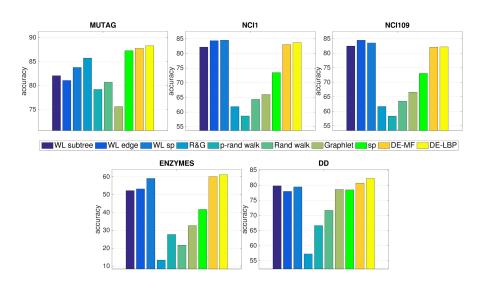
Algorithm 3 Discriminative Embedding

```
Input: Dataset \mathcal{D} = \{\chi_n, y_n\}_{n=1}^N, loss function l(f(\chi), y). Initialize \mathbf{U}^0 = \{\mathbf{W}^0, \mathbf{u}^0\} randomly. for t=1 to T do

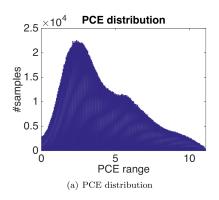
Sample \{\chi_t, y_t\} uniform randomly from \mathcal{D}.

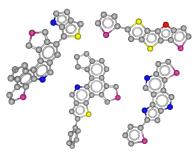
Construct latent variable model p(\{H_i^t\}|\chi_n) as \{\widetilde{\boldsymbol{\mu}}_i^n\}_{i\in\mathcal{V}_n} by Algorithm \mathbf{U} or \mathbf{U} with \mathbf{W}^{t-1}. Update \mathbf{U}^t = \mathbf{U}^{t-1} + \lambda_t \nabla_{\mathbf{U}^{t-1}} l(f(\widetilde{\boldsymbol{\mu}}^n; \mathbf{U}^{t-1}), y_n). end for return \mathbf{U}^T = \{\mathbf{W}^T, \mathbf{u}^T\}
```

Graph Dataset Results



Harvard Clean Energy Project (CEP)





(b) Sample molecules

CEP Results

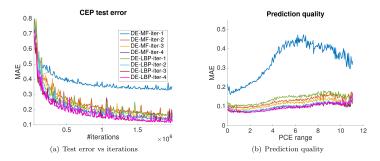


Figure 4: Details of training and prediction results for DE-MF and DE-LBP with different number of fixed point iterations.

	test MAE	test RMSE	# params
Mean Predictor	1.9864	2.4062	1
WL lv-3	0.1431	0.2040	1.6m
WL lv-6	0.0962	0.1367	1378m
DE-MF	0.0914	0.1250	0.1m
DE-LBP	0.0850	0.1174	0.1m

Table 3: Test prediction performance on CEP dataset. WL lv-k stands for Weisfeiler-lehman with degree k.

Resources

- Dai et al., Discriminative Embeddings of Latent Variable Models
- Cristianini and Shawe-Taylor, Kernel Methods for Pattern Analysis
- Kriege et al., Survey on Graph Kernels
- Panangaden, Notes on Metric Spaces
- Fasshauer, Positive Definite Kernels: Past, Present and Future
- Cuturi, Positive Definite Kernels in Machine Learning
- Gormley and Eisner, Structured Belief Propagation for NLP
- Forsyth, Mean Field Inference
- Tseng, Probabilistic Graphical Models
- Görtler, et al. A Visual Exploration of Gaussian Processes