# Let's wrap this up! Incremental structured decoding with resource constraints

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#### Main Idea

- Language models have trouble with single-shot constraint satisfaction
- Typically solved via rejection sampling or backtracking style decoders
- We implement an incremental structured decoder for autoregressive LLMs
- Guarantees monotonic progress and preservation of resource constraints
- Ensures all valid words are generable and all generable words are valid

#### Motivation

Suppose we want to force an autoregressive LLM to generate syntactically valid next tokens  $P(x_n \mid x_1, \ldots, x_{n-1})$ , under certain resource constraints. Here is a concrete example: "generate a valid arithmetic expression in ten or fewer tokens". If we sample the partial trajectory:

$$(a + (c * ($$

then we will spend quite a long time rejecting invalid completions, because this trajectory has past the point of no return. Even though ( is a locally valid continuation, we need to avoid this scenario, because we would like a linear sampling delay and to guarantee this, we must avoid backtracking.

### **Semiring Parsing**

Given a CFG  $\mathcal{G} = \langle V, \Sigma, P, S \rangle$  in Chomsky Normal Form (CNF), we may construct a recognizer  $R_{\mathcal{G}} : \Sigma^n \to \mathbb{B}$  for strings  $\sigma : \Sigma^n$  as follows. Let  $2^V$  be our domain, where 0 is  $\emptyset$ ,  $\oplus$  is  $\cup$ , and  $\otimes$  be defined as:

$$s_1 \otimes s_2 = \{C \mid \langle A, B \rangle \in s_1 \times s_2, (C \to AB) \in P\}$$

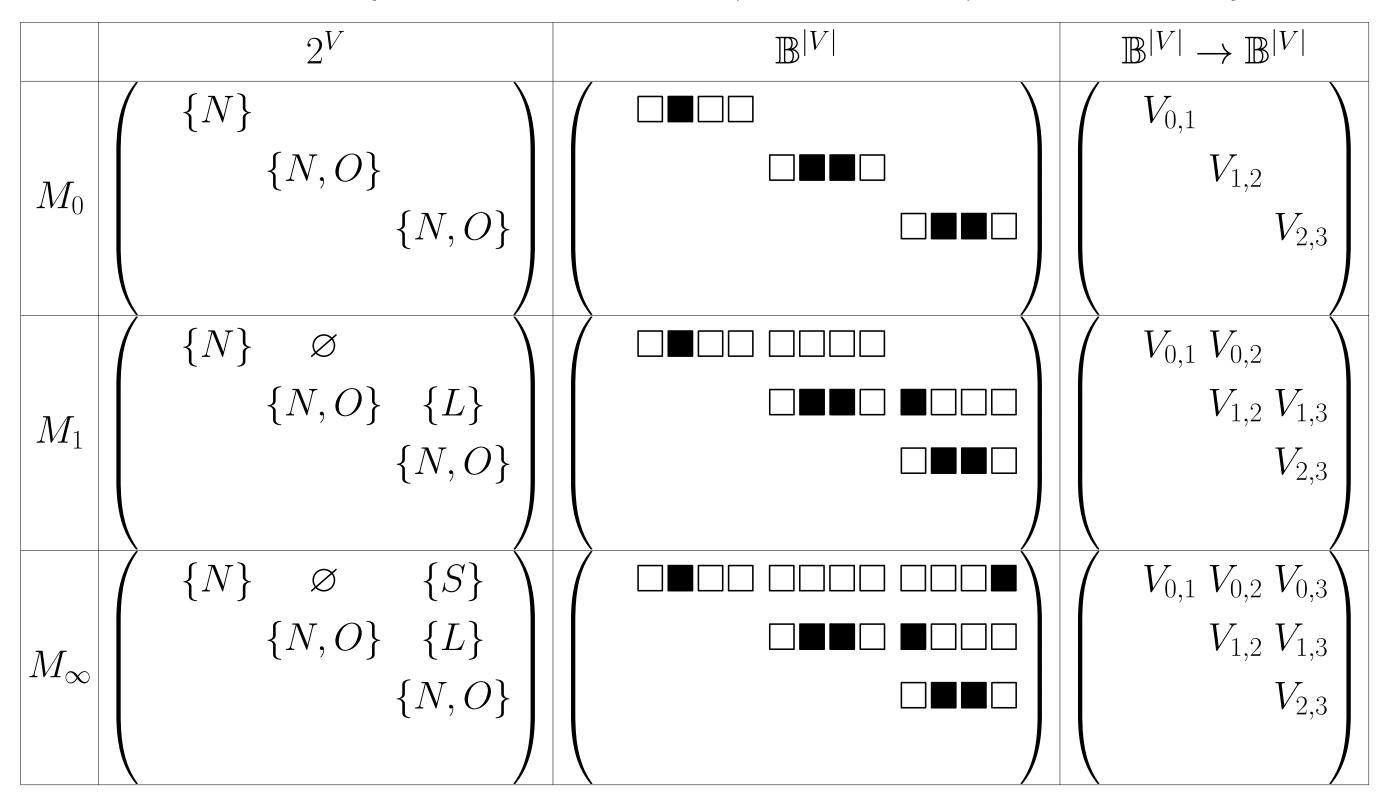
If we define  $\hat{\sigma}_r = \{w \mid (w \to \sigma_r) \in P\}$ , then construct a matrix with unit nonterminals on the superdiagonal,  $M_0[r+1=c](G',\sigma) = \hat{\sigma}_r$  the fixpoint  $M_{i+1} = M_i + M_i^2$  is fully determined by the first diagonal:

$$M_0 = \begin{pmatrix} \varnothing & \hat{\sigma}_1 & \varnothing & \varnothing & \varnothing \\ & & \varnothing & & & & \\ & & & \hat{\sigma}_n \\ \varnothing & & & \varnothing \end{pmatrix} \Rightarrow \begin{pmatrix} \varnothing & \hat{\sigma}_1 & \Lambda & & \varnothing \\ & & & \Lambda & & \\ & & & \hat{\sigma}_n \\ \varnothing & & & \varnothing \end{pmatrix} \Rightarrow \dots \Rightarrow M_{\infty} = \begin{pmatrix} \varnothing & \hat{\sigma}_1 & \Lambda & & \Lambda_{\sigma}^* \\ & & & \Lambda & & \\ & & & \hat{\sigma}_n \\ \varnothing & & & \varnothing \end{pmatrix}$$

CFL membership is recognized by  $R(G', \sigma) = [S \in \Lambda_{\sigma}^*] \Leftrightarrow [\sigma \in \mathcal{L}(G)]$ .

## **Parsing Dynamics**

Let us consider an example with two holes,  $\sigma=1$  \_\_\_\_, with the grammar being  $G=\{S\to NON,O\to +\mid \times,N\to 0\mid 1\}$ . This can be rewritten into CNF as  $G'=\{S\to NL,N\to 0\mid 1,O\to \times\mid +,L\to ON\}$ .



This procedure decides if  $\exists \sigma' \in \mathcal{L}(G) \mid \sigma' \sqsubseteq \sigma$  but forgets provenance.

## **Regular Expression Propagation**

Regular expressions that permit union, intersection and concatenation are called generalized regular expressions (GREs) and can be constructed as follows:

$$\mathcal{L}(\ \varnothing\ ) = \varnothing \qquad \qquad \mathcal{L}(\ R^*\ ) = \{\varepsilon\} \cup \mathcal{L}(R \cdot R^*)$$

$$\mathcal{L}(\ \varepsilon\ ) = \{\varepsilon\} \qquad \qquad \mathcal{L}(\ R \vee S\ ) = \mathcal{L}(R) \cup \mathcal{L}(S)$$

$$\mathcal{L}(\ a\ ) = \{a\} \qquad \qquad \mathcal{L}(\ R \wedge S\ ) = \mathcal{L}(R) \cap \mathcal{L}(S)$$

$$\mathcal{L}(\ R \cdot S\ ) = \mathcal{L}(R) \times \mathcal{L}(S)$$

Finite slices of a CFL are finite and thus regular a fortiori. Just like sets, bitvectors and other datatypes, we can also propagate GREs through a parse chart. Here, the algebra will carry  $GRE^{|V|}$ , where 0 is  $\varnothing$ , and  $\oplus$ ,  $\otimes$  are defined:

$$s_1 \otimes s_2 = \left[ \bigvee_{(v \to AB) \in P} s_1[A] \cdot s_2[B] \right]_{v \in V} \qquad s_1 \oplus s_2 = \left[ s_1[v] \lor s_2[v] \right]_{v \in V}$$

Initially, we have  $M_0[r+1=c](G',\sigma)=\sigma_r$  Now after computing the fixpoint, when we unpack  $\Lambda_{\sigma}^*[S]$ , this has type GRE, recognizing the finite CFL slice.

#### **Brzozowski Differentiation**

Janusz Brzozowski (1964) introduced a derivative operator  $\partial_a: Reg \to Reg$ , which slices the prefix off a language:  $\partial_a S = \{b \in \Sigma^* \mid ab \in S\}$ . The Brzozowski derivative over a GRE is a effectively a normalizing rewrite system:

$$\begin{array}{llll} \partial_{a} & \varnothing & = \varnothing & & \delta(&\varnothing &) = \varnothing \\ \partial_{a} & \varepsilon & = \varnothing & & \delta(&\varepsilon &) = \varepsilon \\ \partial_{a} & a & = \varepsilon & & \delta(&a &) = \varnothing \\ \partial_{a} & b & = \varnothing \text{ for each } a \neq b & & \delta(&R^{*}) = \varepsilon \\ \partial_{a} & R^{*} & = (\partial_{x}R) \cdot R^{*} & & \delta(&\neg R) = \varepsilon \text{ if } \delta(R) = \varnothing \\ \partial_{a} & \neg R & = \neg \partial_{a}R & & \delta(&\neg R) = \varnothing \text{ if } \delta(R) = \varepsilon \\ \partial_{a} & R \cdot S & = (\partial_{a}R) \cdot S \vee \delta(R) \cdot \partial_{a}S & & \delta(&R \cdot S) = \delta(R) \wedge \delta(S) \\ \partial_{a} & R \vee S & = \partial_{a}R \vee \partial_{a}S & & \delta(&R \vee S) = \delta(R) \vee \delta(S) \\ \partial_{a} & R \wedge S & = \partial_{a}R \wedge \partial_{a}S & & \delta(&R \wedge S) = \delta(R) \wedge \delta(S) \end{array}$$

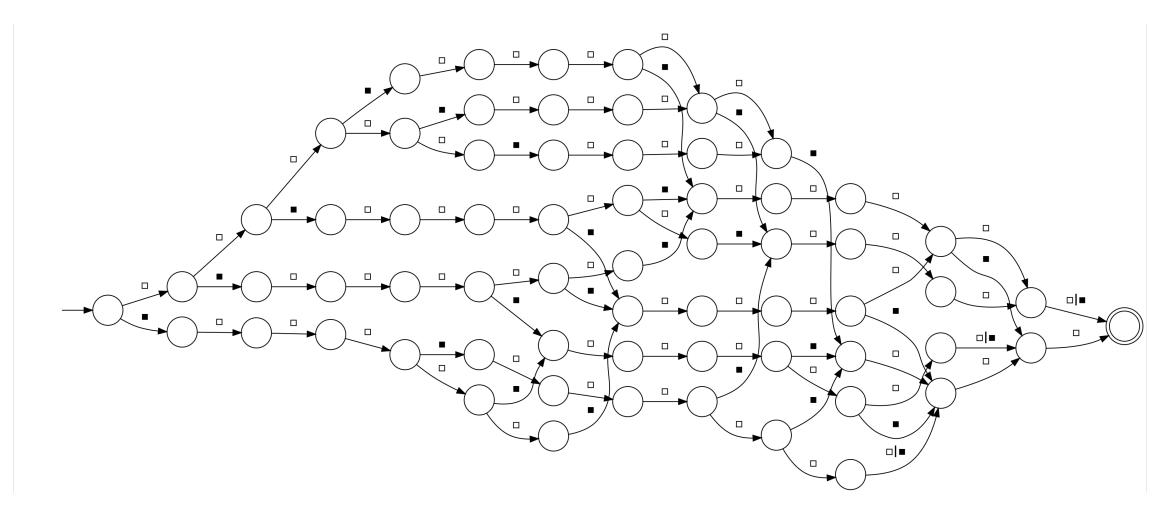
The key property we care about is, this formulation allows us to sample lazily from language intersections, without first materializing the product automaton.

## **Example: Determinantal Point Processes**

Consider a time series, A, whose points which are not too close nor far apart, and  $n \leq \sum_{i=1}^{|A|} [A_i = \blacksquare]$ . We want to sample the typical set using an LLM.

- ullet The words are bitvectors of some length T, i.e.,  $A=\{\Box,\blacksquare\}^T$
- ullet Consecutive lacksquare separated by  $\Box^{[a,b]}$ , i.e.,  $B=\Box^*(lacksquare^{[a,b]})^{[n,\infty)}\{lacksquare,\epsilon\}\Box^*$

The DPP language is regular. Let C be an FSA such that  $\mathcal{L}(C) = \mathcal{L}(A) \cap \mathcal{L}(B)$ . For example, here is the minimal automaton for T = 13, a = 3, b = 5, n = 2.



This automaton for  $\mathcal{L}(C)$  can grow very large, and we may only need to sample a small sublanguage with probabilistic support. Question: Can we incrementally sample  $\mathcal{L}(C)$  while ensuring there is always a valid rightwards continuation?



