Northwestern University

Department of Electrical and Computer Engineering

ELEC ENG 422 Winter 2020

Problem set 2 Solutions:

Problems:

1. a.) X_2 and X_{10} are I.I.D. Bernoulli random variables and so their joint p.m.f. is simply

$$p_{X_2,X_{10}}(x_2,x_{10}) = \begin{cases} p^2, & \text{if } x_2 = x_{10} = 1, \\ p(1-p), & \text{if } (x_2 = 1 \text{ and } x_{10} = 0) \text{ or } (x_2 = 0 \text{ and } x_{10} = 1), \\ (1-p)^2, & \text{if } x_2 = x_{10} = 0, \\ 0, & \text{otherwise.} \end{cases}$$

b.) Z_t will be a geometric random variable (just like the interarrival times discussed in class). Hence,

$$p_{Z_t}(z) = \begin{cases} (1-p)^{z-1}(p), & \text{if } z = 1, 2, 3, \dots \\ 0, & \text{otherwise.} \end{cases}$$

- c.) If $W_t = w$, then looking backward in time it means that there were w 1 time instants with no arrivals and then one with an arrival. Since the arrivals are independent, this is again a geoemetric random variable with the same p.m.f. as Z_t in the previous part.
- d.) Note that W_t is a function of the arrivals before time t and Z_t is a function of th earrivals after time t, since these are independent sets of arrivals, then W_t and Z_t will be independent.
- 3. a.) Consider the case where X is a continuous zero mean random variable. Since it has a finite expectation, it must be that $\int_{-\infty}^{\infty} x f_X(x) dx$ converges. For the variance to be infinite, it must be that $\int_{-\infty}^{\infty} x^2 f_X(x) dx$ does not converge. A sufficient condition for satisfying both of these is that $f_X(x) \approx 1/|x|^3$ as x goes to ∞ and $-\infty$. This means that $x f_X(x)$ would decrease like $1/x^2$, which is integrable, but $x^2 f_X(x)$ would decrease like 1/x which is not.
 - b.) No if a random variable has a finite second moment its first moment must also be finite. One way to argue this for continuous random variables is that the "tails" of $xf_X(x)$ must decrease faster than the tails fo $x^2f_X(x)$ and so if the later is integrable, the former must be too. Another way to show this is to use the Cauchy-Schwartz inequality.
- 4. Using linearity of expectations we have:

$$E[(X-z)^2] = E(X^2) - 2zE(X) + z^2$$

The right-hand side of this is a convex quadratic function of z and so can be minimized by setting its derivative equal to zero. Doing this and solving for z gives the desired result.

Note: this has a natural physical analog: one can view $E(X-z)^2$ as analogous to the moment of inertia of a solid about z - this is minimized when z is the center of mass, which corresponds to E(X).

6.

a.) Let A be the event: ' X_1 is even.' One way to solve this is condition on the possible values of X_1 and then use iterative expectation, i.e.,

$$E(X|A) = \sum_{i=2,4,6} E(X|A, X_1 = i)P(X_1 = i|A),$$

where $P(X_1 = i|A) = 1/3$.

To calculate $E(X|A, X_1 = i)$ note that

$$P(X = k | A \text{ and } X_1 = i) = \begin{cases} 1/6, & \text{for } k = 1+1, i+2, \dots, i+6 \\ 0, & \text{otherwise.} \end{cases}$$

and so
$$E(X|A, X_1 = i) = i + 3.5$$
. Finally, $E(X|A) = (1/3)(5.5 + 7.5 + 9.5) = 7.5$.

- b.) In this case note that if X = 9, then the only possible value of X_1 are 3, 4, 5, 6. These are all equally likely conditioned on X = 9 and so $E(X_1|X=9) = 4.5$.
- 8. a.) For any number m, let X be a random variable which takes on the two values km and 0, with probabilities 1/k and 1-1/k, respectively. Note that E(X)=(1/k)(km)+(1-1/k)(0)=m and thus this clearly satisfies $\Pr(X \geq kE(X))=\Pr(X \geq km)=1/k$.
 - b.) Note that

$$\Pr(X \ge kE(X)) = \Pr(X - E(X) \ge (k - 1)E(X))$$

$$= \Pr(|X - E(X)| \ge (k - 1)E(X))$$

$$\le \frac{Var(X)}{(k - 1)^2(E(X))^2}$$

where the second line follows since X is non-negative and the third line follows from Chebyshev's inequality. For the given random variable in part (a), $Var(X) = \frac{1}{k}((k-1)^2(E(X))^2) + (1-\frac{1}{k})(E(X))^2$. Substituting this into the above bound and simplifying, we have

$$\Pr(X \ge kE(X)) \le \frac{1}{k} + \frac{1}{k(k-1)}$$

which is clearly larger than the bound given by Markov's inequality.

- c.) The key here is that the argument in class applied to a fixed random variable as we increased k. Here, as k changes in part (a), we are changing the random variable. To make this more precise, consider a random variable X as in part (a) for a particular integer $\tilde{k} > 2$. Then for $k = \tilde{k}$, Markov's inequality does give a tighter bound than Chebyshev's on the probability that $X \geq kE(X)$, but if we increase k and do not change the random variable, eventually Chebyshev's inequality will give a better bound.
- 9. First note that $|X| \ge 10$ if and only if $X^4 \ge 10^4$, and so

$$\Pr(|X| \ge 10) = \Pr(X^4 \ge 10^4)$$

Next, as in the proof of the Chebyshev bound in class, we can use that X^4 is non-negative, to apply the Markov inequality giving

$$\Pr(X^4 \ge 10^4) \le \frac{E(X^4)}{10^4} = \frac{30}{10^4} = .03.$$

Exercise 1.6: Show that for a continuous nonnegative rv X,

$$\int_0^\infty \Pr\{X > x\} \ dx = \int_0^\infty x \mathsf{f}_X(x) \, dx. \tag{A.2}$$

Hint 1: First rewrite $\Pr\{X > x\}$ on the left side of (A.2) as $\int_x^\infty \mathsf{f}_X(y) \, dy$. Then think through, to your level of comfort, how and why the order of integration can be interchanged in the resulting expression.

Solution: We have $\Pr\{X > x\} = \int_x^\infty \mathsf{f}_X(y) \, dy$ from the definition of a continuous rv. We look at $\mathsf{E}[X] = \int_0^\infty \Pr\{X > x\} \, dx$ as $\lim_{a \to \infty} \int_0^a \mathsf{F}^\mathsf{c}(x) \, dx$ since the limiting operation $a \to \infty$ is where the interesting issue is.

$$\int_{0}^{a} F^{c}(x) dx = \int_{0}^{a} \int_{x}^{\infty} f_{X}(y) dy dx
= \int_{0}^{a} \int_{x}^{a} f_{X}(y) dy dx + \int_{0}^{a} \int_{a}^{\infty} f_{X}(y) dy dx
= \int_{0}^{a} \int_{0}^{y} f_{X}(y) dx dy + aF_{X}^{c}(a).$$

We first broke the integral on the right into two parts, one for y < x and the other for $y \ge x$. Since the limits of integration on the first part were finite, they could be interchanged. The inner integral of the first part is $yf_X(y)$, so

$$\lim_{a \to \infty} \int_0^a \mathsf{F}_X^{\mathsf{c}}(x) \, dx = \lim_{a \to \infty} \int_0^a y \mathsf{f}_X(y) \, dy + \lim_{a \to \infty} a \mathsf{F}_X^{c}(a).$$

Assuming that $\mathsf{E}[X]$ exists, the integral on the left is nondecreasing in A and has the finite limit \overline{X} . The first integral on the right is also nondecreasing and upper bounded by the first integral, so it also has a limit. This means that $\lim_{a\to\infty} a\mathsf{F}_X^\mathsf{c}(a)$ must also have a limit, say β . Now if $\beta>0$, then for any $\epsilon\in(0,a)$, $a\mathsf{F}_X(a)>\beta-\epsilon$ for all sufficiently large a. For all such a, then $\mathsf{F}_X^\mathsf{c}(a)>(\beta-\epsilon)/a$. This would imply that $\overline{X}=\int_0^\infty\mathsf{F}_X^\mathsf{c}(x)\,dx=\infty$, which is a contradiction. Thus $\beta=0$, i.e., $\lim_{a\to\infty} a\mathsf{F}_X^\mathsf{c}(a)=0$, establishing (A.2) for the case where $\mathsf{E}[X]$ is finite. The case where $\mathsf{E}[X]$ is infinite is a minor perturbation.

The result that $\lim_{a\to\infty} aF_X^{\mathsf{c}}(a) = 0$ is also important and can be seen intuitively from Figure 1.3.

Hint 2: As an alternate approach, derive (A.2) using integration by parts.

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Solution: Using integration by parts and being less careful,

$$\int_0^\infty d\big(x\mathsf{F}_X^\mathsf{c}(x)\big) = -\int_0^\infty x\mathsf{f}_X(x)\,dx + \int_0^\infty \mathsf{F}_X^\mathsf{c}(x)\,dx.$$

The left side is $\lim_{a\to\infty} a\mathsf{F}_X^\mathsf{c}(a) - 0\mathsf{F}_X(0)$ so this shows the same thing, again requiring the fact that $\lim_{a\to\infty} a\mathsf{F}_X^\mathsf{c}(a) = 0$ when $\mathsf{E}[X]$ exists.

Exercise 1.11: a) For any given rv Y, express E[|Y|] in terms of $\int_{y<0} F_Y(y) dy$ and $\int_{y>0} F_Y^c(y) dy$. Hint: Review the argument in Figure 1.4.

Solution: We have seen in (1.34) that

$$\mathsf{E}[Y] = -\int_{y < 0} \mathsf{F}_Y(y) \, dy + \int_{y > 0} \mathsf{F}_Y^\mathsf{c}(y) \, dy.$$

Since all negative values of Y become positive in |Y|,

$$\mathsf{E}\left[|Y|\right] = + \int_{y < 0} \mathsf{F}_Y(y) \, dy + \int_{y \ge 0} \mathsf{F}_Y^\mathsf{c}(y) \, dy.$$

To spell this out in greater detail, let $Y = Y^+ + Y^-$ where $Y^+ = \max\{0, Y\}$ and $Y^- = \max\{0, Y\}$

$$\min\{Y,0\}$$
. Then $Y = Y^+ + Y^-$ and $|Y| = Y^+ - Y^- = Y^+ + |Y^-|$. Since $\mathsf{E}[Y^+] = \int_{y \geq 0} \mathsf{F}_Y^{\mathsf{c}}(y) \, dy$ and $\mathsf{E}[Y^-] = -\int_{y < 0} \mathsf{F}_Y(y) \, dy$, the above results follow.

b) For some given rv X with $E[|X|] < \infty$, let $Y = X - \alpha$. Using (a), show that

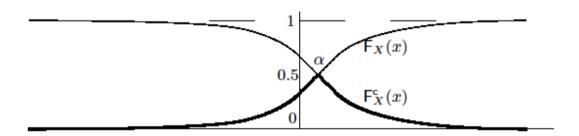
$$\mathsf{E}\left[|X-lpha|
ight] = \int_{-\infty}^{lpha} \mathsf{F}_X(x)\,dx + \int_{lpha}^{\infty} \mathsf{F}_X^\mathsf{c}(x)\,dx.$$

Solution: This follows by changing the variable of integration in (a). That is,
$$\mathsf{E}\left[|X-\alpha|\right] \ = \ \mathsf{E}\left[|Y|\right] = + \int_{y<0} \mathsf{F}_Y(y) \, dy + \int_{y\geq0} \mathsf{F}_Y^\mathsf{c}(y) \, dy \\ = \int_{-\infty}^{\alpha} \mathsf{F}_X(x) \, dx + \int_{-\infty}^{\infty} \mathsf{F}_X^\mathsf{c}(x) \, dx,$$

where in the last step, we have changed the variable of integration from y to $x - \alpha$.

c) Show that $E[|X - \alpha|]$ is minimized over α by choosing α to be a median of X. Hint: Both the easy way and the most instructive way to do this is to use a graphical argument illustrating the above two integrals Be careful to show that when the median is an interval, all points in this interval achieve the minimum.

Solution: As illustrated in the picture, we are minimizing an integral for which the integrand changes from $F_X(x)$ to $F_X^c(x)$ at $x = \alpha$. If $F_X(x)$ is strictly increasing in x, then $F_X^c = 1 - F_X$ is strictly decreasing. We then minimize the integrand over all x by choosing α to be the point where the curves cross, *i.e.*, where $F_X(x) = .5$. Since the integrand has been minimized at each point, the integral must also be minimized.



If F_X is continuous but not strictly increasing, then there might be an interval over which $F_X(x) = .5$; all points on this interval are medians and also minimize the integral; Exercise 1.10 (c) gives an example where $F_X(x) = 0.5$ over the interval [1, 2). Finally, if $F_X(\alpha) \ge 0.5$ and $F_X(\alpha - \epsilon) < 0.5$ for some α and all $\epsilon > 0$ (as in parts (a) and (b) of Exercise 1.10), then the integral is minimized at that α and that α is also the median.

 $\overline{X}_1 + \cdots + \overline{X}_n$. You may assume that the rv's have a joint density function, but do not assume that the rv's are independent. Solution: We assume that the rv's have a joint density, and we ignore all mathematical

Exercise 1.14: a) Let X_1, X_2, \ldots, X_n be rv's with expected values $\overline{X}_1, \ldots, \overline{X}_n$. Show that $\mathsf{E}[X_1 + \cdots + X_n] = 0$

fine points here. Then

$$\mathsf{E}\left[X_1 + \dots + X_n\right] = \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} (x_1 + \dots + x_n) \mathsf{f}_{X_1 \dots X_n}(x_1, \dots, x_n) \, dx_1 \dots dx_n$$

$$= \sum_{j=1}^n \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} x_j \, \mathsf{f}_{X_1 \dots X_n}(x_1, \dots, x_n) \, dx_1 \dots dx_n$$

$$= \sum_{j=1}^n \int_{-\infty}^{\infty} x_j \mathsf{f}_{X_j}(x_j) \, dx_j = \sum_{j=1}^n \mathsf{E}\left[X_j\right].$$

Note that the separation into a sum of integrals simply used the properties of integration and that no assumption of statistical independence was made.

b) Now assume that X_1, \ldots, X_n are statistically independent and show that the expected value of the product is equal to the product of the expected values.

Solution: From the independence, $f_{X_1...X_n}(x_1,...,x_n) = \prod_{j=1}^n f_{X_j}(x_j)$. Thus

$$\mathsf{E}\left[X_1 X_2 \cdots X_n\right] = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \prod_{j=1}^{n} x_j \prod_{j=1}^{n} \mathsf{f}_{X_j}(x_j) \, dx_1 \cdots dx_n$$
$$= \prod_{j=1}^{n} \int_{-\infty}^{\infty} x_j \, \mathsf{f}_{X_j}(x_j) \, dx_j = \prod_{j=1}^{n} \mathsf{E}\left[X_j\right].$$

c) Again assuming that X_1, \ldots, X_n are statistically independent, show that the variance of the sum is equal to the sum of the variances.

Solution: Since (a) shows that $\mathsf{E}\left[\sum_{j}X_{j}\right]=\sum_{j}\overline{X}_{j}$, we have

$$VAR \left[\sum_{j=1}^{n} X_{j} \right] = E \left[\left(\sum_{j=1}^{n} X_{j} - \sum_{j=1}^{n} \overline{X}_{j} \right)^{2} \right]$$

$$= E \left[\sum_{j=1}^{n} \sum_{i=1}^{n} (X_{j} - \overline{X}_{j})(X_{i} - \overline{X}_{i}) \right]$$

$$= \sum_{j=1}^{n} \sum_{i=1}^{n} E \left[(X_{j} - \overline{X}_{j})(X_{i} - \overline{X}_{i}) \right], \quad (A.5)$$

where we have again used (a). Now from (b) (which used the independence of the X_j), $\mathsf{E}\left[(X_j - \overline{X}_j)(X_i - \overline{X}_i)\right] = 0$ for $i \neq j$. Thus(A.5) simplifies to

$$\mathsf{VAR}\left[\sum_{j=1}^n X_j\right] \ = \ \sum_{j=1}^n \mathsf{E}\left[(X_j - \overline{X}_j)^2\right] \ = \ \sum_{j=1}^n \mathsf{VAR}\left[X_j\right].$$