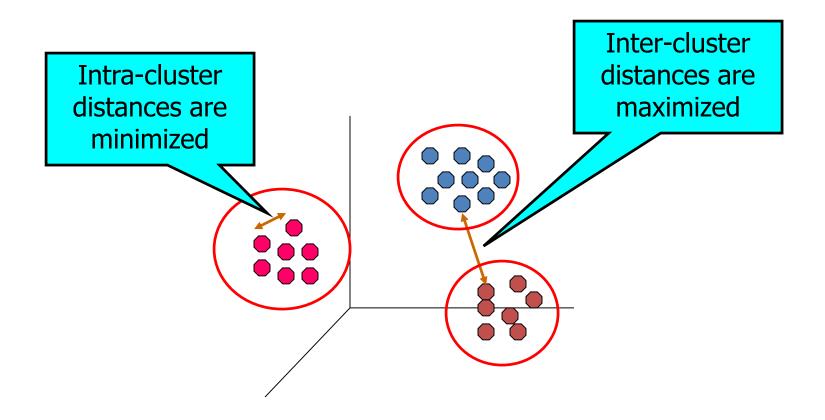
What is a Clustering?

 In general a grouping of objects such that the objects in a group (cluster) are similar (or related) to one another and different from (or unrelated to) the objects in other groups



Applications of Cluster Analysis

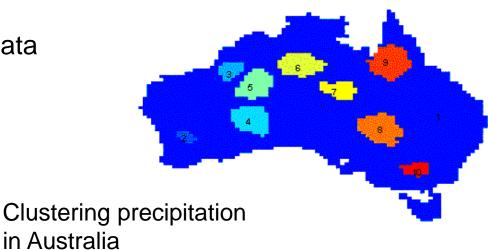
Understanding

 Group related documents for browsing, group genes and proteins that have similar functionality, or group stocks with similar price fluctuations

	Discovered Clusters	Industry Group
1	Applied-Matl-DOWN,Bay-Network-Down,3-COM-DOWN, Cabletron-Sys-DOWN,CISCO-DOWN,HP-DOWN, DSC-Comm-DOWN,INTEL-DOWN,LSI-Logic-DOWN, Micron-Tech-DOWN,Texas-Inst-Down,Tellabs-Inc-Down, Natl-Semiconduct-DOWN,Oracl-DOWN,SGI-DOWN, Sun-DOWN	Technology1-DOWN
2	Apple-Comp-DOWN,Autodesk-DOWN,DEC-DOWN, ADV-Micro-Device-DOWN,Andrew-Corp-DOWN, Computer-Assoc-DOWN,Circuit-City-DOWN, Compaq-DOWN, EMC-Corp-DOWN, Gen-Inst-DOWN, Motorola-DOWN,Microsoft-DOWN,Scientific-Atl-DOWN	Technology2-DOWN
3	Fannie-Mae-DOWN,Fed-Home-Loan-DOWN, MBNA-Corp-DOWN,Morgan-Stanley-DOWN	Financial-DOWN
4	Baker-Hughes-UP,Dresser-Inds-UP,Halliburton-HLD-UP, Louisiana-Land-UP,Phillips-Petro-UP,Unocal-UP, Schlumberger-UP	Oil-UP

Summarization

Reduce the size of large data sets



Early applications of cluster analysis

John Snow, London 1854

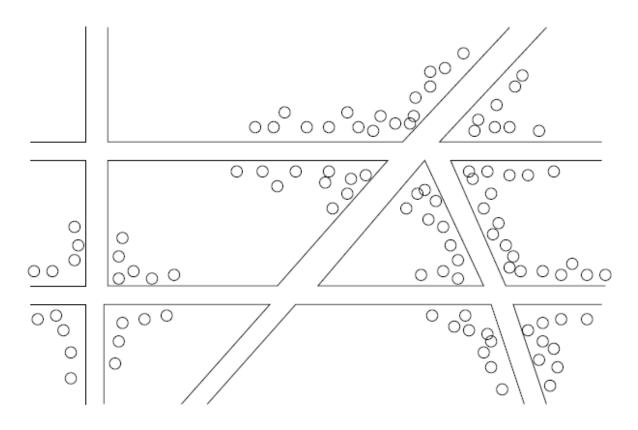
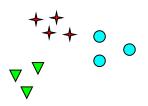


Figure 1.1: Plotting cholera cases on a map of London

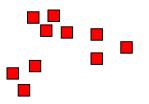
Notion of a Cluster can be Ambiguous

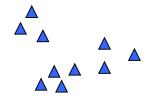


How many clusters?

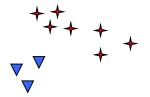


Six Clusters

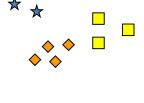




Two Clusters



Four Clusters

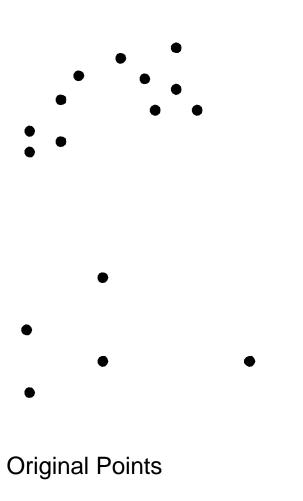


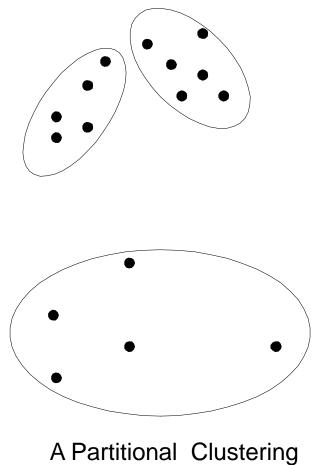


Types of Clusterings

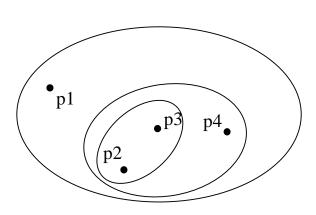
- A clustering is a set of clusters
- Important distinction between hierarchical and partitional sets of clusters
- Partitional Clustering
 - A division data objects into subsets (clusters) such that each data object is in exactly one subset
- Hierarchical clustering
 - A set of nested clusters organized as a hierarchical tree

Partitional Clustering

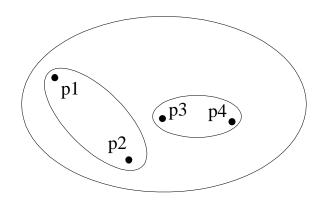




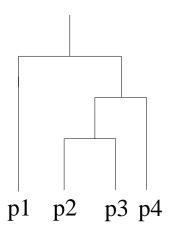
Hierarchical Clustering



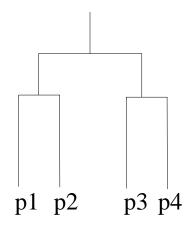
Traditional Hierarchical Clustering



Non-traditional Hierarchical Clustering



Traditional Dendrogram



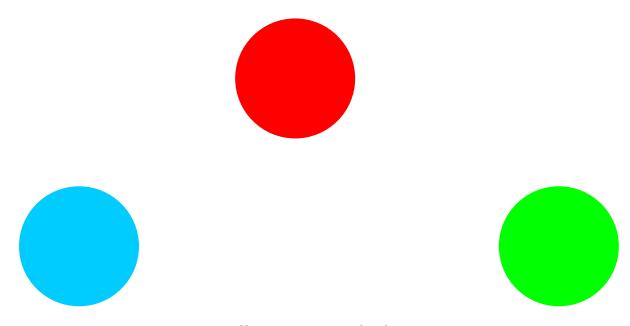
Non-traditional Dendrogram

Other types of clustering

- Exclusive (or non-overlapping) versus nonexclusive (or overlapping)
 - In non-exclusive clusterings, points may belong to multiple clusters.
 - Points that belong to multiple classes, or 'border' points
- Fuzzy (or soft) versus non-fuzzy (or hard)
 - In fuzzy clustering, a point belongs to every cluster with some weight between 0 and 1
 - Weights usually must sum to 1 (often interpreted as probabilities)
- Partial versus complete
 - In some cases, we only want to cluster some of the data

Types of Clusters: Well-Separated

- Well-Separated Clusters:
 - A cluster is a set of points such that any point in a cluster is closer (or more similar) to every other point in the cluster than to any point not in the cluster.



3 well-separated clusters

Types of Clusters: Center-Based

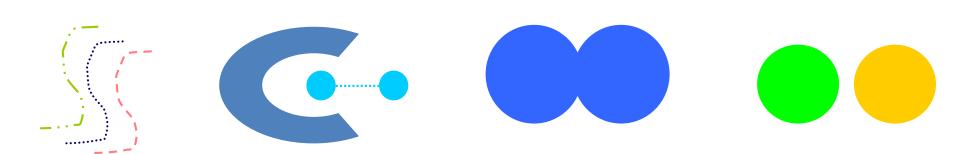
Center-based

- A cluster is a set of objects such that an object in a cluster is closer (more similar) to the "center" of a cluster, than to the center of any other cluster
- The center of a cluster is often a centroid, the minimizer of distances from all the points in the cluster, or a medoid, the most "representative" point of a cluster



Types of Clusters: Contiguity-Based

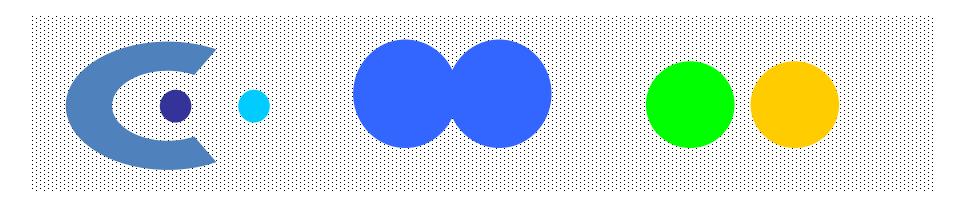
- Contiguous Cluster (Nearest neighbor or Transitive)
 - A cluster is a set of points such that a point in a cluster is closer (or more similar) to one or more other points in the cluster than to any point not in the cluster.



Types of Clusters: Density-Based

Density-based

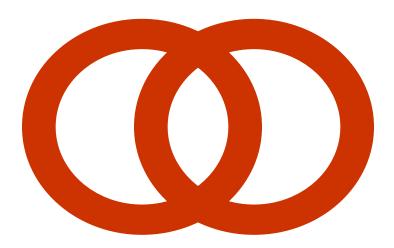
- A cluster is a dense region of points, which is separated by low-density regions, from other regions of high density.
- Used when the clusters are irregular or intertwined, and when noise and outliers are present.



Types of Clusters: Conceptual Clusters

- Shared Property or Conceptual Clusters
 - Finds clusters that share some common property or represent a particular concept.

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Types of Clusters: Objective Function

- Clustering as an optimization problem
 - Finds clusters that minimize or maximize an objective function.
 - Enumerate all possible ways of dividing the points into clusters and evaluate the `goodness' of each potential set of clusters by using the given objective function. (NP Hard)
 - Can have global or local objectives.
 - Hierarchical clustering algorithms typically have local objectives
 - Partitional algorithms typically have global objectives
 - A variation of the global objective function approach is to fit the data to a parameterized model.
 - The parameters for the model are determined from the data, and they
 determine the clustering
 - E.g., Mixture models assume that the data is a 'mixture' of a number of statistical distributions.

Clustering Algorithms

- K-means and its variants
- Hierarchical clustering

DBSCAN

K-MEANS

K-means Clustering

- Partitional clustering approach
- Each cluster is associated with a centroid (center point)
- Each point is assigned to the cluster with the closest centroid
- Number of clusters, K, must be specified
- The objective is to minimize the sum of distances of the points to their respective centroid

K-means Clustering

 Problem: Given a set X of n points in a ddimensional space and an integer K group the points into K clusters C= {C₁, C₂,...,C_k} such that

$$Cost(C) = \sum_{i=1}^{k} \sum_{x \in C_i} dist(x, c)$$

is minimized, where c_i is the centroid of the points in cluster C_i

K-means Clustering

- Most common definition is with euclidean distance, minimizing the Sum of Squares Error (SSE) function
 - Sometimes K-means is defined like that
- Problem: Given a set X of n points in a ddimensional space and an integer K group the points into K clusters C= {C₁, C₂,...,C_k} such that

$$Cost(C) = \sum_{i=1}^{\kappa} \sum_{x \in C_i} (x - c_i)^2$$

is minimized, where c_i is the mean of the points in cluster C_i

Complexity of the k-means problem

- NP-hard if the dimensionality of the data is at least 2 (d>=2)
 - Finding the best solution in polynomial time is infeasible

 For d=1 the problem is solvable in polynomial time (how?)

A simple iterative algorithm works quite well in practice

K-means Algorithm

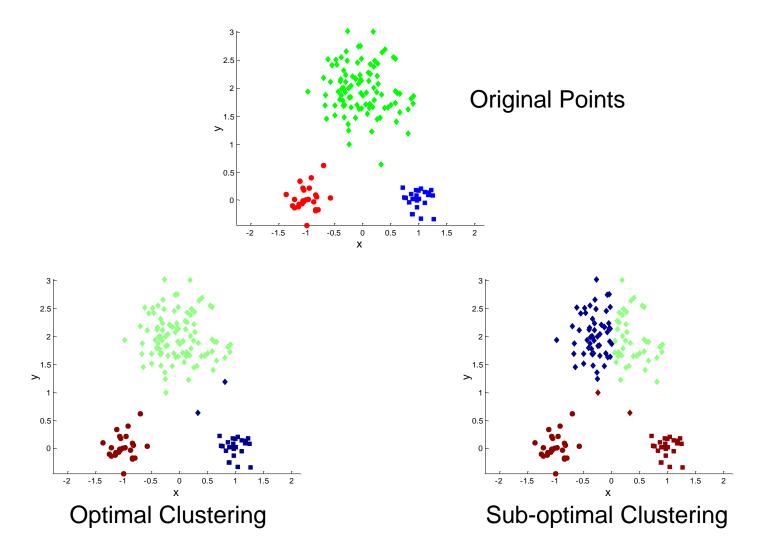
- Also known as Lloyd's algorithm.
- K-means is sometimes synonymous with this algorithm

- 1: Select K points as the initial centroids.
- 2: repeat
- 3: Form K clusters by assigning all points to the closest centroid.
- 4: Recompute the centroid of each cluster.
- 5: **until** The centroids don't change

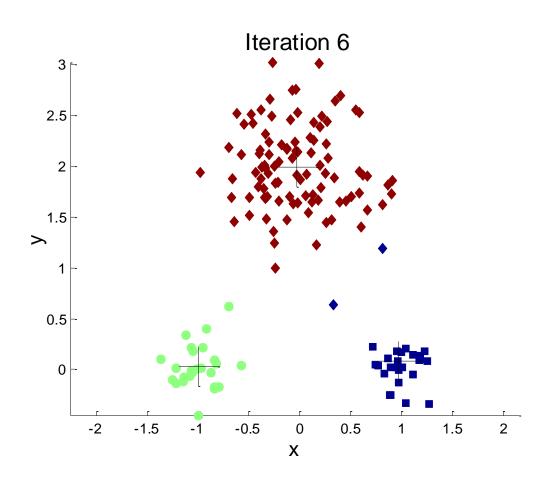
K-means Algorithm — Initialization

- Initial centroids are often chosen randomly.
 - Clusters produced vary from one run to another.

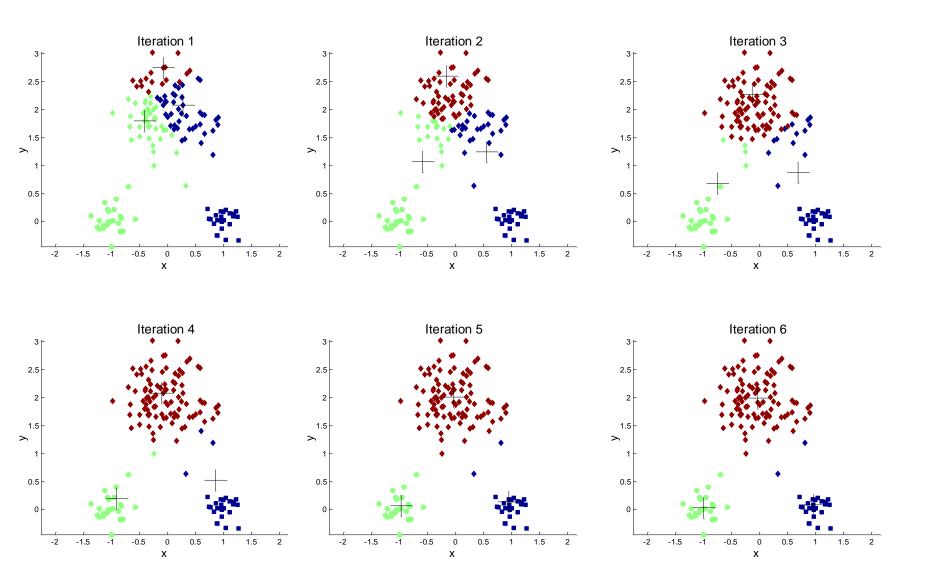
Two different K-means Clusterings



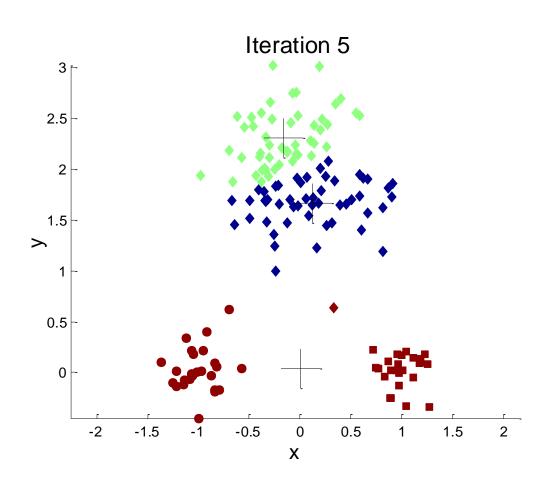
Importance of Choosing Initial Centroids



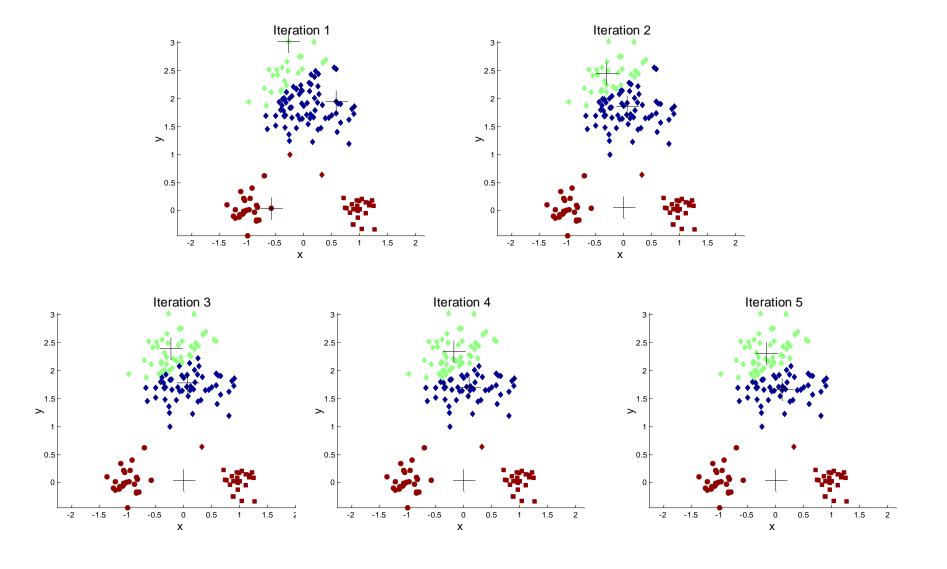
Importance of Choosing Initial Centroids



Importance of Choosing Initial Centroids



Importance of Choosing Initial Centroids ...



Dealing with Initialization

 Do multiple runs and select the clustering with the smallest error

 Select original set of points by methods other than random. E.g., pick the most distant (from each other) points as cluster centers (K-means++ algorithm)

K-means Algorithm – Centroids

- The centroid depends on the distance function
 - The minimizer for the distance function
- 'Closeness' is measured by Euclidean distance (SSE), cosine similarity, correlation, etc.
- Centroid:
 - The mean of the points in the cluster for SSE, and cosine similarity
 - The median for Manhattan distance.
- Finding the centroid is not always easy
 - It can be an NP-hard problem for some distance functions
 - E.g., median form multiple dimensions

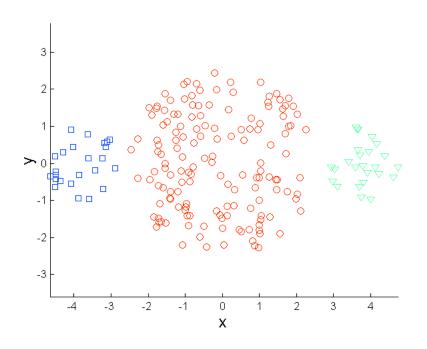
K-means Algorithm – Convergence

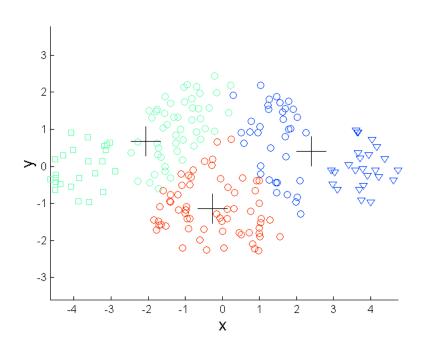
- K-means will converge for common similarity measures mentioned above.
 - Most of the convergence happens in the first few iterations.
 - Often the stopping condition is changed to 'Until relatively few points change clusters'
- Complexity is O(n * K * I * d)
 - n = number of points, K = number of clusters,
 I = number of iterations, d = dimensionality
- In general a fast and efficient algorithm

Limitations of K-means

- K-means has problems when clusters are of different
 - Sizes
 - Densities
 - Non-globular shapes
- K-means has problems when the data contains outliers.

Limitations of K-means: Differing Sizes

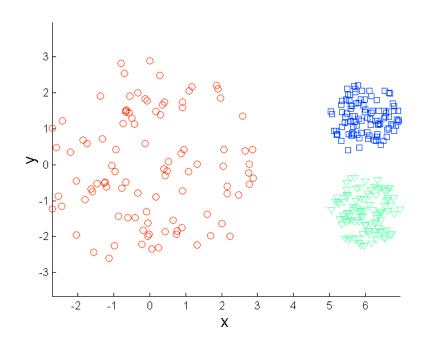


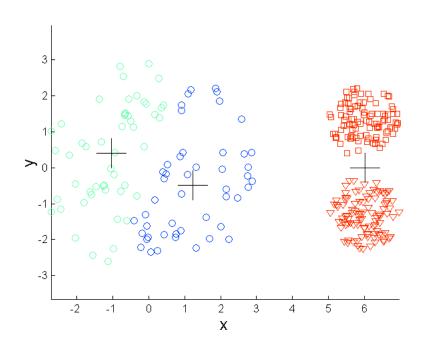


Original Points

K-means (3 Clusters)

Limitations of K-means: Differing Density

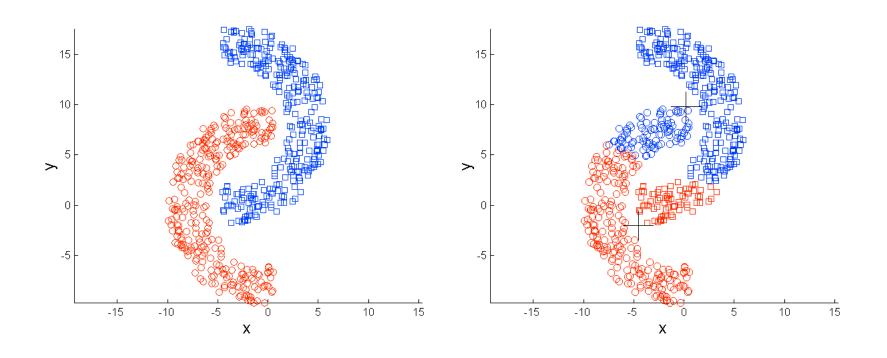




Original Points

K-means (3 Clusters)

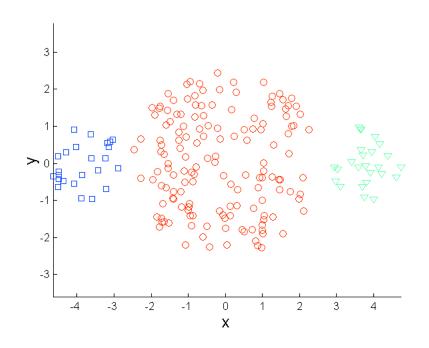
Limitations of K-means: Non-globular Shapes

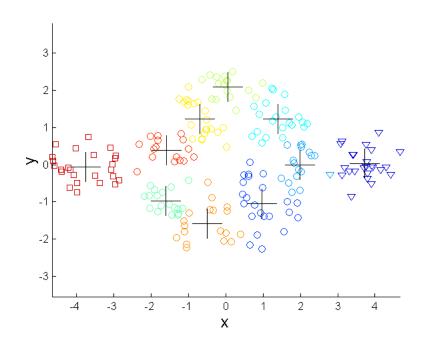


Original Points

K-means (2 Clusters)

Overcoming K-means Limitations



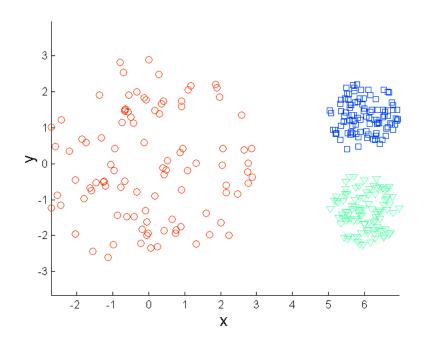


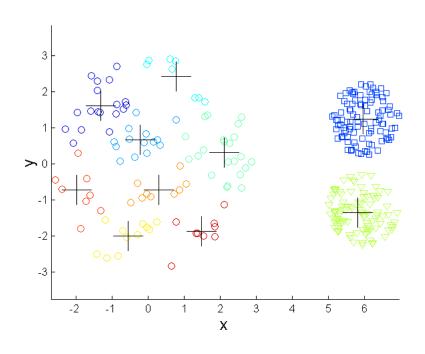
Original Points

K-means Clusters

One solution is to use many clusters. Find parts of clusters, but need to put together.

Overcoming K-means Limitations

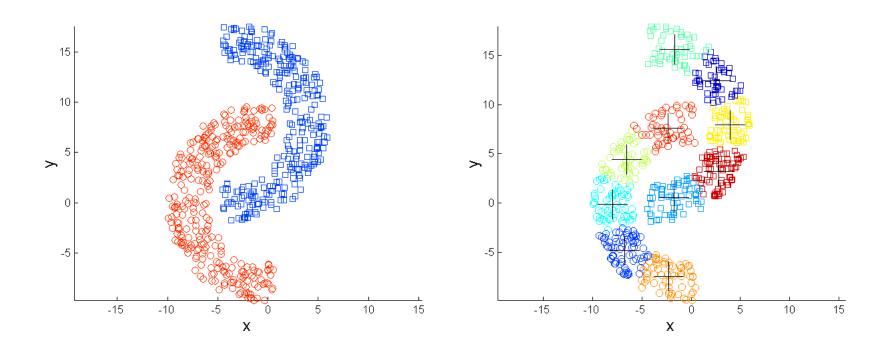




Original Points

K-means Clusters

Overcoming K-means Limitations



Original Points

K-means Clusters

Variations

K-medoids: Similar problem definition as in K-means, but the centroid of the cluster is defined to be one of the points in the cluster (the medoid).

K-centers: Similar problem definition as in K-means, but the goal now is to minimize the maximum diameter of the clusters (diameter of a cluster is maximum distance between any two points in the cluster).