

Satisfiability Checking

16 Branch and bound

Prof. Dr. Erika Ábrahám

RWTH Aachen University
Informatik 2
LuFG Theory of Hybrid Systems

WS 22/23

Definition

An **integer linear system** S is a linear system in general form $Ax = 0$ with $x = x_1, \dots, x_{n+m}$, $\bigwedge_{i=1}^m l_i \leq x_i \leq u_i$ for $i = n+1, \dots, m$ and with the additional **integrality requirement** that **all variables** are of type **integer**.

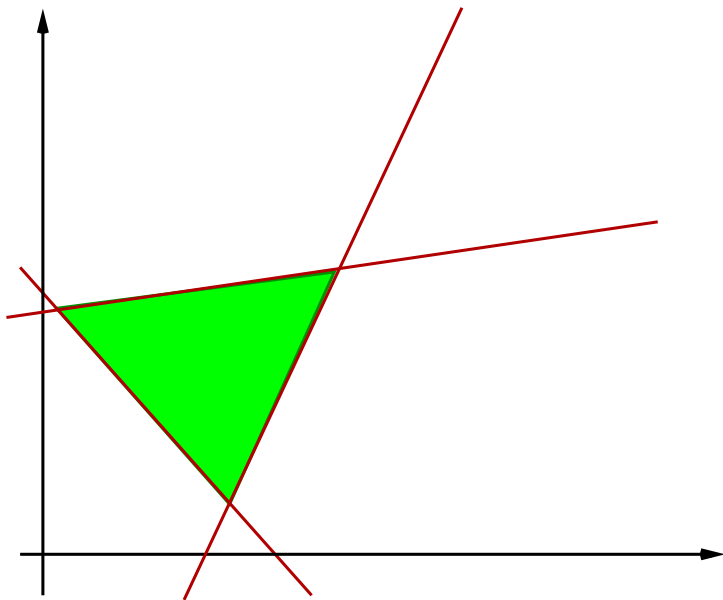
Definition (relaxed system)

Given an **integer linear system** S , its **relaxation** $\text{relaxed}(S)$ is S without the **integrality requirement**.

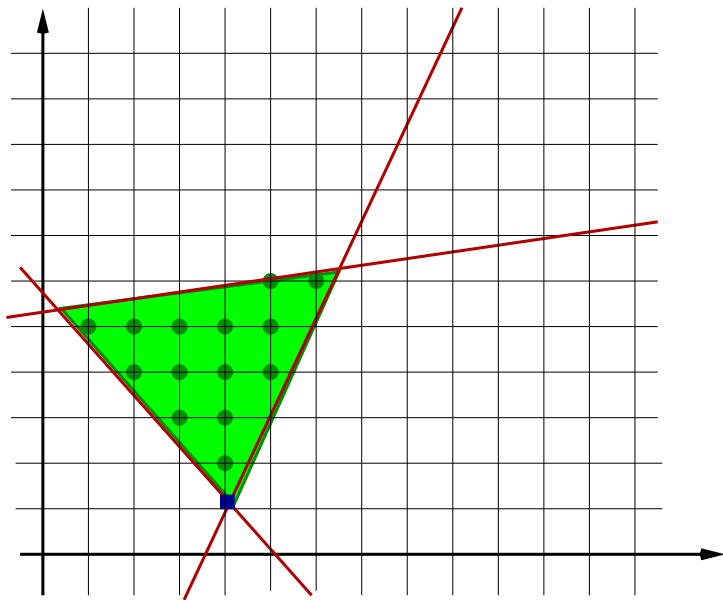
S *satisfiable* \Rightarrow $\text{relax}(S)$ *satisfiable*

S *unsatisfiable* \Leftarrow $\text{relax}(S)$ *unsatisfiable*

Geometric interpretation

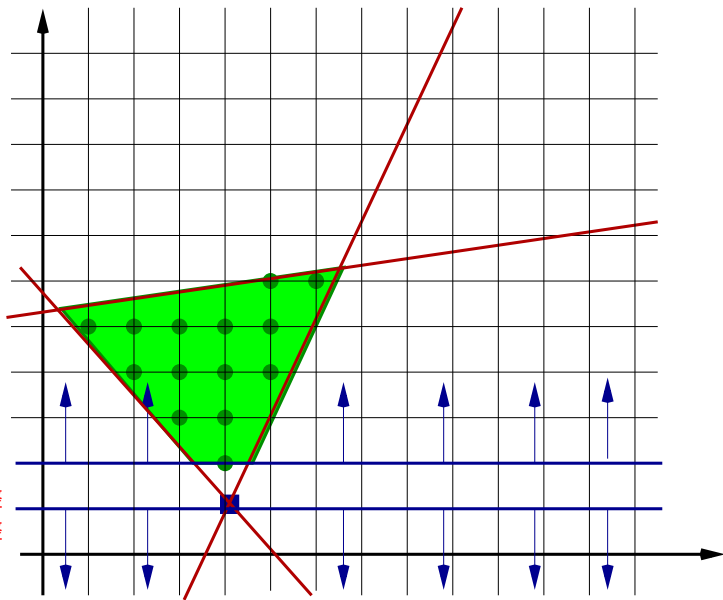


Geometric interpretation

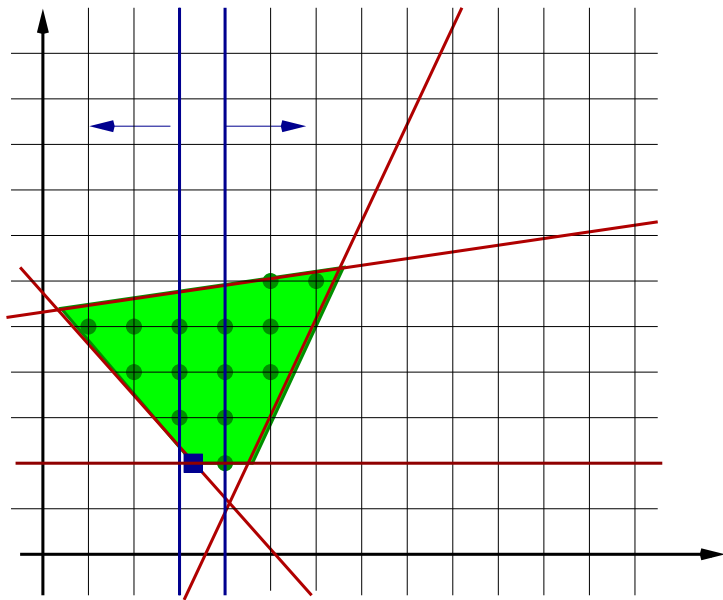


Geometric interpretation

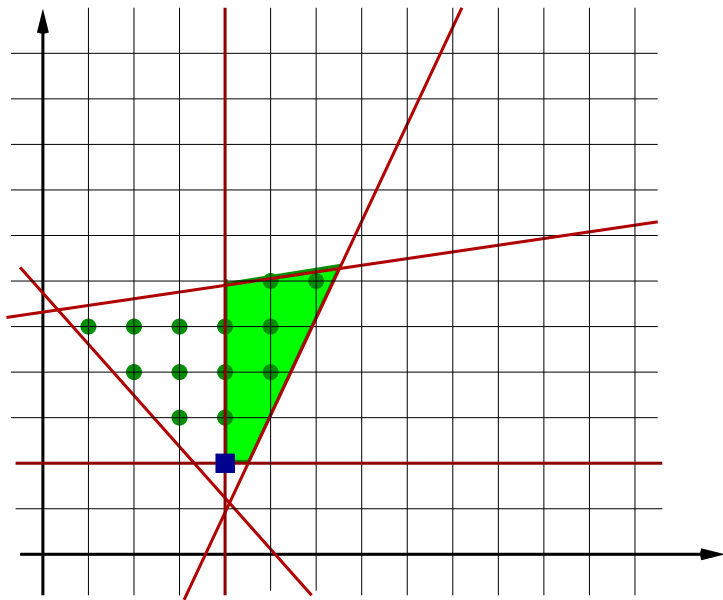
Branch:
分成2部分
 \leq 向下取整
 \geq 向上取整



Geometric interpretation



Geometric interpretation

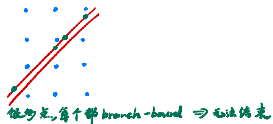


Branch and bound algorithm

Input: An integer linear system S

Output: SAT if S is satisfiable, UNSAT otherwise

```
procedure Branch-and-Bound( $S$ ) {  
  linear programming  
  res = LP(relaxed( $S$ ));  
  if (res==UNSAT) return UNSAT;  
  else if (res is integral) return SAT;  
  else {  
    Select a variable  $v$  that is assigned a non-integral value  $r$ ;  
    if (Branch-and-Bound( $S \cup \{v \leq \lfloor r \rfloor\}$ ))==SAT) return SAT;  
    else if (Branch-and-Bound( $S \cup \{v \geq \lceil r \rceil\}$ ))==SAT) return SAT;  
    else return UNSAT;  
  }  
}
```

- The algorithm is **incomplete**.
- Example: $1 \leq 3x - 3y \leq 2$ has **unbounded real solutions** but **no integer solutions** \rightarrow the algorithm loops forever.
- The algorithm **can be made complete** for formulae with the **small-model property**: if there is a solution, then there is also a solution within a (computable) **finite bound**.
- The algorithm can be extended to **mixed integer linear programming**, where **some** of the variables are **integer-valued** while the **others** are **real-valued**.

Branch and bound

- **Branch:** Split the search space
- **Bound:** Exclude unsatisfiable sub-spaces
- We have seen: Depth-first search
- Also possible: Breadth-first search

bound: 形成界限limit, 即把不符合要求的区域排除
(整数之间的区域)

Optimizations:

- **Constraints** can be **removed**: $x_1 + x_2 \leq 2$, $x_1 \leq 1$, $x_2 \leq 1$.
First constraint is redundant.

- **Bounds** can be **tightened**: $2x_1 + x_2 \leq 2$, $x_2 \geq 4$, $x_1 \leq 3$
From the first two constraints we get $x_1 \leq -1$

General case: Assume a constraint $\sum_i a_i x_i \leq b$ with $l_i \leq x_i \leq u_i$.

$$\leadsto a_k x_k \leq b - \sum_{i \neq k} a_i x_i$$

$$\text{If } a_k > 0, \text{ we have } x_k \leq \frac{b - (\sum_{i \neq k, a_i > 0} a_i l_i) - (\sum_{i \neq k, a_i < 0} a_i u_i)}{a_k}.$$

if $a_i > 0$, lower bound if $a_i < 0$, upper bound

$$\text{If } a_k < 0, \text{ we have } x_k \geq \frac{b - (\sum_{i \neq k, a_i > 0} a_i u_i) - (\sum_{i \neq k, a_i < 0} a_i l_i)}{a_k}.$$

After the next summary, we will learn **interval constraint propagation**, which generalizes this idea to polynomial constraints.

- How can we extend the simplex method to branch-and-bound in order to find integer solutions?
- Is branch-and-bound complete?
- Which preprocessing steps are possible to simplify the input integer linear system?