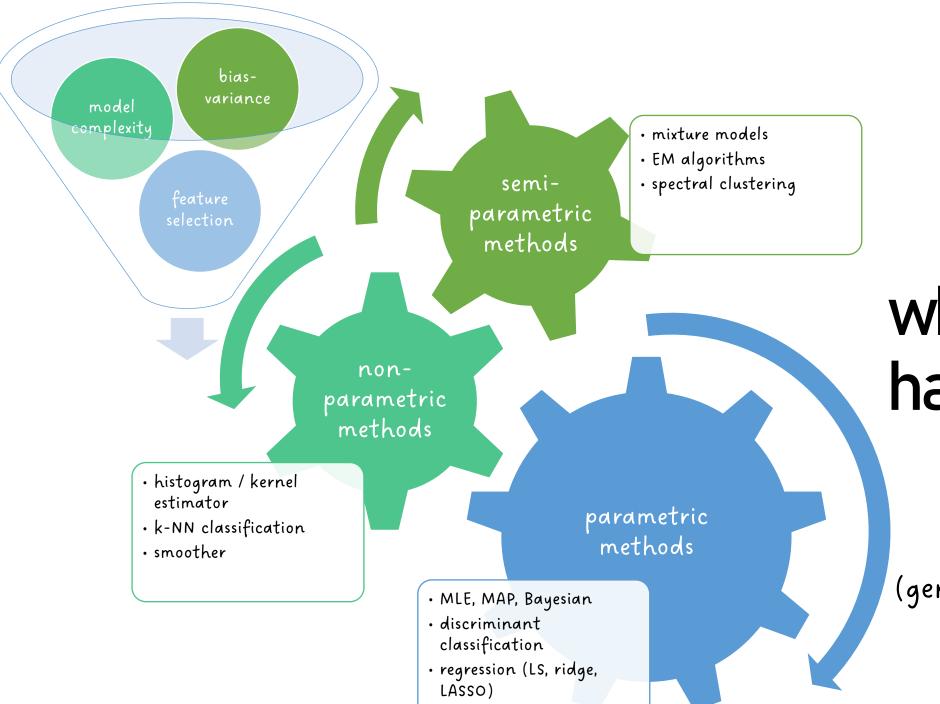


Kernel

STATS 303 Statistical Machine Learning

Spring 2022

Lecture 11



what we have so far ...

density-based (generative approach)

Vapnik's Principle

 If you possess a restricted amount of information for solving some problem, try to solve the problem directly and never solve a more general problem as an intermediate step.



linear SVM

• The best example that follows Vapnik's Principle is the support vector machine (SVM) that we learned in STATS302.

Wx+6=0 lw^Tx_n+b x X 0

linear SVM

- Let $\{\mathbf{x}_n, t_n\}_{n=1}^N$ be the sample of training data for the classification problem, where $t_n \in \{+1, -1\}$ is the label.
- The linear SVM solves

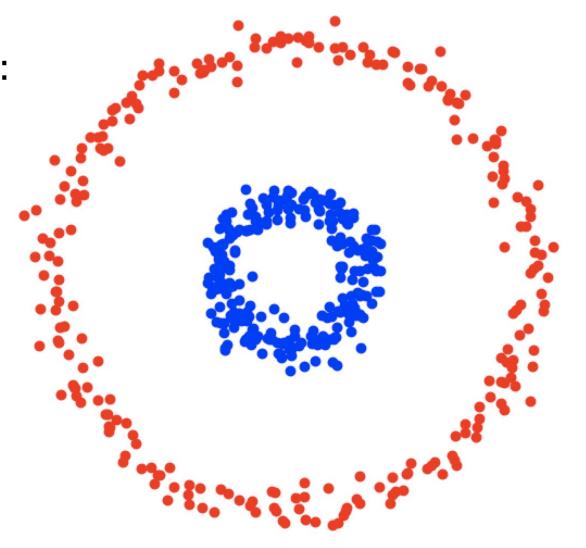
$$\min_{\mathbf{w},b} \frac{1}{2} \| \mathbf{w} \|^2$$
s. t. $t_n(\mathbf{w}^T \mathbf{x}_n + b) \ge 1$ for any n

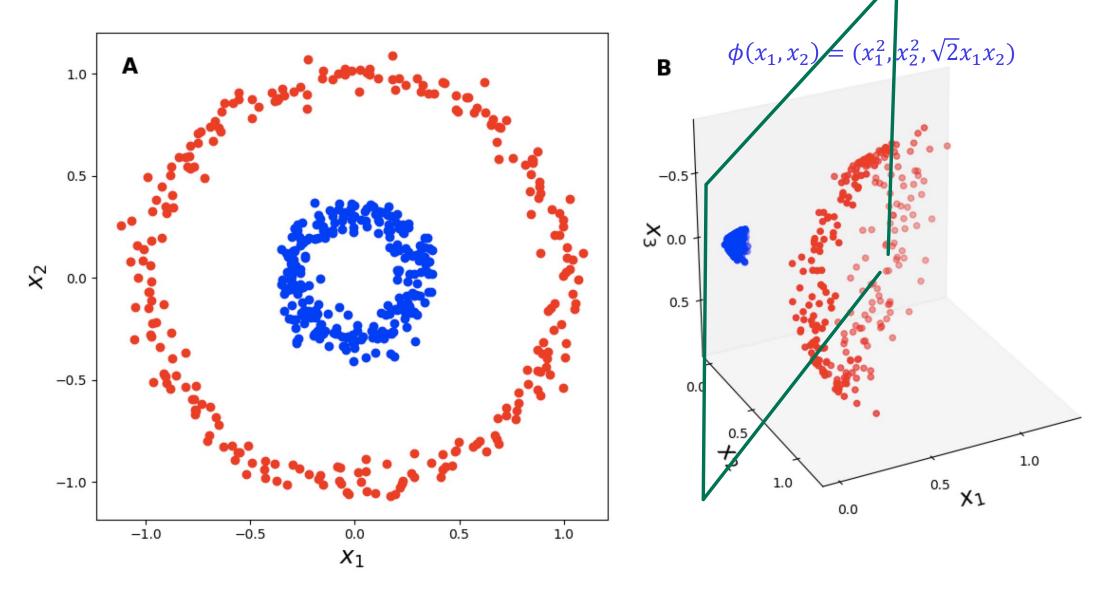
The dual problem is

$$\max_{\mathbf{a}} \sum_{n=1}^{N} a_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} a_n a_m t_n t_m \mathbf{x}_n^{\mathsf{T}} \mathbf{x}_m$$
s.t. $a_n \ge 0$ for all n ; and $\sum_{n=1}^{N} a_n t_n = 0$

$$\sum_{n=1}^{N} a_n t_n = 0$$
Lagrange multipliers

• If data are not linearly separable:





• Replacing each data point \mathbf{x}_n by $\phi(\mathbf{x}_n)$ in the formulation of SVM:

$$\min_{\mathbf{w},b} \frac{1}{2} \| \mathbf{w} \|^2$$

s.t. $t_n(\mathbf{w}^T \phi(\mathbf{x}_n) + b) \ge 1$ for any n

• Also, the dual problem becomes:

$$\max_{\mathbf{a}} \sum_{n=1}^{N} a_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} a_n a_m t_n t_m \phi(\mathbf{x}_n)^T \phi(\mathbf{x}_m)$$
s.t. $a_n \ge 0$ for all n ; and $\sum_{n=1}^{N} a_n t_n = 0$

• Oftentimes, instead of finding a good mapping $\phi(\cdot)$, it is easier to define a "kernel" K, such that

$$K(\mathbf{x}_n, \mathbf{x}_m) = \phi(\mathbf{x}_n)^{\mathrm{T}} \phi(\mathbf{x}_m)$$

Given that, the dual form of the kernel SVM problem becomes

$$\max_{\mathbf{a}} \sum_{n=1}^{N} a_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} a_n a_m t_n t_m K(\mathbf{x}_n, \mathbf{x}_m)$$
s.t. $a_n \ge 0$ for all n ; and $\sum_{n=1}^{N} a_n t_n = 0$

$$y(\mathbf{x}) = \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x}) + b = \sum_{n=1}^{N} a_n t_n K(\mathbf{x}, \mathbf{x}_n) + b$$

$$\mathcal{Y} = \sum_{n=1}^{N} a_n t_n K(\mathbf{x}, \mathbf{x}_n) + b$$

example of nonlinear map ϕ

• Let
$$\mathbf{x} = [x_1, x_2]^T$$
, $\mathbf{y} = [y_1, y_2]^T$

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• Let \phi(\mathbf{x}) = [1, \sqrt{2}x_1, \sqrt{2}x_2, \sqrt{2}x_1x_2, x_1^2, x_2^2]^T
\phi(\mathbf{x})^{\mathsf{T}} \phi(\mathbf{y}) = \mathbf{1} + 2\mathbf{x}_1\mathbf{y}_1 + 2\mathbf{x}_2\mathbf{y}_1 + 2\mathbf{x}_1\mathbf{x}_2\mathbf{y}_1 + 2\mathbf{x}_1\mathbf{y}_1\mathbf{y}_2 + \mathbf{x}_1^{\mathsf{T}}\mathbf{y}_1^{\mathsf{T}} + \mathbf{x}_1^{\mathsf{T}
```

use K instead of ϕ

- In practice, instead of starting with ϕ , we can directly start with K.
- Popular choices of *K*:
 - polynomial: $K(\mathbf{x}, \mathbf{y}) = (\mathbf{x}^{\mathrm{T}}\mathbf{y} + 1)^{q}$
 - radial basis function (RBF): $K(\mathbf{x}, \mathbf{y}) = \exp\left(-\frac{\|\mathbf{x} \mathbf{y}\|^2}{2\sigma^2}\right)$
 - sigmoidal: $K(\mathbf{x}, \mathbf{y}) = \tanh(2\mathbf{x}^T\mathbf{y} + 1)$

food for thought

1. In general, what *K* can be chosen?

2. If e.g.,
$$K(x,y) = \exp\left(-\frac{\|x-y\|^2}{2\sigma^2}\right)$$
, what ϕ is behind it?

kernel PCA

kernel PCA

- Kernel methods are not just for SVMs.
- Suppose we want to do dimension reduction using principal component analysis (PCA) for some data that do not show a clear linear structure.
- Nevertheless, after applying a nonlinear function ϕ , the transformed data show a clear linear low-dimensional structure.
- We can apply PCA to $\{\phi(\mathbf{x}_n)\}_{n=1}^N$
- The question is how to avoid defining ϕ and use K instead.

 $\frac{1}{N} \sum_{k=1}^{N} \phi(x_k)^{T} \phi(x_k) + \frac{1}{N^2} \sum_{k=1}^{N} \sum_{k=1}^{N} \phi(x_k)^{T} \phi(x_k)$

Let K be the Gram matrix whose
$$(n,n)$$
-th entry is given by $K(n,m) = \phi(x_n)^T \phi(x_m)$

$$= \phi(x_n)^{\mathsf{T}} \phi(x_m) - \frac{1}{N} \sum_{k=1}^{N} \phi(x_k)^{\mathsf{T}} \phi(x_m) - \frac{1}{N^2} \sum_{k=1}^{N} \sum_{k=1}^{N} \phi(x_k)^{\mathsf{T}} \phi(x_k) + \frac{1}{N^2} \sum_{k=1}^{N} \sum_{k=1}^{N} \phi(x_k)^{\mathsf{T}} \phi(x_k)$$

$$= \frac{\text{Column sum}}{\text{Column sum}} \quad \text{"Yow sum"}$$

$$= \frac{1}{N} \sum_{l=1}^{N} K(l, m) - \frac{1}{N} \sum_{l=1}^{N} K(n, l) + \frac{1}{N} \sum_{$$

$$\frac{1}{N^2} \sum_{k=1}^{N} \sum_{k=1}^{N} K(l,k)$$

"column & row sum"

Consider
$$1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$
. Then $11^T = \begin{pmatrix} 1 & \cdots & 1 \\ 1 & \cdots & 1 \end{pmatrix}$ and $(11^T K)(n,m) = \sum_{l=1}^{N} (11^T)(n,l) K(l,m)$

$$= \sum_{l=1}^{N} K(l,m) = \text{ column sum}.$$

and
$$(11^{\mathsf{T}} \mathsf{K})(\mathsf{N},\mathsf{m}) = \sum_{l=1}^{\mathsf{T}} (11^{\mathsf{T}})(\mathsf{N},\mathsf{l}) \mathsf{K}(\mathsf{l},\mathsf{m})$$

$$=\sum_{k=1}^{\infty}K(l, m) =$$
 "column sum"

Similarly,
$$(K11^T)(n,m) = \sum_{l=1}^{N} K(n,l) = \text{"row sum"}$$
.
Therefore,

$$\Phi \Phi^{T} = K - \frac{1}{N} 11^{T} K - \frac{1}{N} K 11^{T} + \frac{1}{N} 11^{T} K 11^{T}$$

• In ridge regression, suppose our model is $y(\mathbf{x}) = \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x})$:

$$J(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left\{ \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}_n) - t_n \right\}^2 + \frac{\lambda}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w}$$

Taking gradient w.r.t. w yields:

$$\frac{\partial J(w)}{\partial w} = \sum_{n=1}^{N} (w^{T} \varphi(x_{n}) - t_{n}) \varphi(x_{n}) + \lambda w \stackrel{\text{set}}{=} 0$$

$$\mathbf{w} = -\frac{1}{\lambda} \sum_{n=1}^{N} \left\{ \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x}_n) - t_n \right\} \phi(\mathbf{x}_n) = \sum_{n=1}^{N} a_n \phi(\mathbf{x}_n) = \mathbf{\Phi}^{\mathrm{T}} \mathbf{a}$$
Let $\mathbf{a}_n = -\frac{1}{\lambda} \left(\mathbf{w}^{\mathrm{T}} \phi(\mathbf{x}_n) - \mathbf{t}_n \right)$

• In ridge regression, suppose our model is $y(\mathbf{x}) = \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x})$:

$$J(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left\{ \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}_n) - t_n \right\}^2 + \frac{\lambda}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w}$$

• Taking gradient w.r.t. w yields: (cont'd from previous shide)

Let
$$\Phi = \begin{bmatrix} \phi(\mathbf{x}_1)^T \\ \phi(\mathbf{x}_2)^T \end{bmatrix}$$
, $\mathbf{A} = \begin{bmatrix} \mathbf{A}_1 \\ \mathbf{A}_2 \\ \vdots \\ \mathbf{A}_n \end{bmatrix}$

$$\mathbf{w} = -\frac{1}{\lambda} \sum_{n=1}^{N} \left\{ \mathbf{w}^T \phi(\mathbf{x}_n) - t_n \right\} \phi(\mathbf{x}_n) = \sum_{n=1}^{N} a_n \phi(\mathbf{x}_n) = \mathbf{\Phi}^T \mathbf{a}$$

$$J(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left\{ \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}_n) - t_n \right\}^2 + \frac{\lambda}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w}$$

• With
$$\mathbf{w} = \Phi^{\mathrm{T}} \mathbf{a}$$

$$\sum_{n=1}^{N} \left(\mathbf{w}^{\mathrm{T}} \varphi(\mathbf{x}_{n}) - t_{n} \right)^{2} = \begin{bmatrix} \mathbf{w}^{\mathrm{T}} \varphi(\mathbf{x}_{n}) - t_{1} \\ \mathbf{w}^{\mathrm{T}} \varphi(\mathbf{x}_{n}) - t_{2} \end{bmatrix} \begin{bmatrix} \mathbf{w}^{\mathrm{T}} \varphi(\mathbf{x}_{n}) - t_{1} \\ \mathbf{w}^{\mathrm{T}} \varphi(\mathbf{x}_{n}) - t_{2} \end{bmatrix}$$

$$= \left(\mathbf{\Phi} \mathbf{w} - t \right)^{\mathrm{T}} \left(\mathbf{\Phi} \mathbf{w} - t \right) \quad \text{where } t = \left(t_{1}, t_{2}, \dots, t_{N} \right)^{\mathrm{T}}$$

$$= \left(\mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a} - t \right)^{\mathrm{T}} \left(\mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a} - t \right)$$

Hence,
$$J(\mathbf{a}) = \frac{1}{2}\mathbf{a}^{\mathrm{T}}\mathbf{\Phi}\mathbf{\Phi}^{\mathrm{T}}\mathbf{\Phi}\mathbf{\Phi}^{\mathrm{T}}\mathbf{a} - \mathbf{a}^{\mathrm{T}}\mathbf{\Phi}\mathbf{\Phi}^{\mathrm{T}}\mathbf{t} + \frac{1}{2}\mathbf{t}^{\mathrm{T}}\mathbf{t} + \frac{\lambda}{2}\mathbf{a}^{\mathrm{T}}\mathbf{\Phi}\mathbf{\Phi}^{\mathrm{T}}\mathbf{a}$$

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a} - \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{t} + \frac{1}{2} \mathbf{t}^{\mathrm{T}} \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a}$$

$$K_{nm} = \phi(\mathbf{x}_n)^{\mathrm{T}} \phi(\mathbf{x}_m) = k(\mathbf{x}_n, \mathbf{x}_m) \quad \text{Gram matrix} \quad \mathbf{K} = \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}}$$

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^{\mathrm{T}} \mathbf{K} \mathbf{K} \mathbf{a} - \mathbf{a}^{\mathrm{T}} \mathbf{K} \mathbf{t} + \frac{1}{2} \mathbf{t}^{\mathrm{T}} \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^{\mathrm{T}} \mathbf{K} \mathbf{a}$$

• From
$$a_n = -\frac{1}{\lambda} \left\{ \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x}_n) - t_n \right\}$$
 $\mathbf{w} = \mathbf{\Phi}^{\mathrm{T}} \mathbf{a}$, we have

Therefore,

$$\mathbf{a} = (\mathbf{K} + \lambda \mathbf{I}_N)^{-1} \mathbf{t}$$

$$y(\mathbf{x}) = \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}) = \mathbf{a}^{\mathrm{T}} \boldsymbol{\Phi} \boldsymbol{\phi}(\mathbf{x}) = \mathbf{k}(\mathbf{x})^{\mathrm{T}} \left(\mathbf{K} + \lambda \mathbf{I}_{N} \right)^{-1} \mathbf{t}$$



Questions?

Reference

- *Kernel methods:*
 - [Al] Ch.13.5-13.7
 - [Bi] Ch.7.1, 6.1-6.2
- Kernel PCA:
 - [HaTF] Ch.14.5.4
- Gaussian processes:
 - [Bi] Ch.6.4.1-6.4.2, 6.4.5
 - [HaTF] Ch.5.8.1-5.8.2

Tasty & Healthy

Individual Pack

No Food Additives Added

