

Dynamic Programming III

CSci 4041: Algorithms and Data Structures

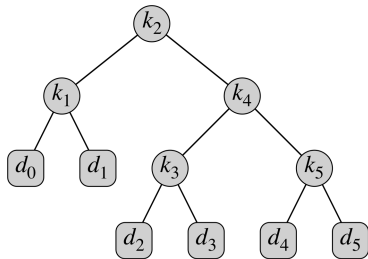
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March 31, 2015

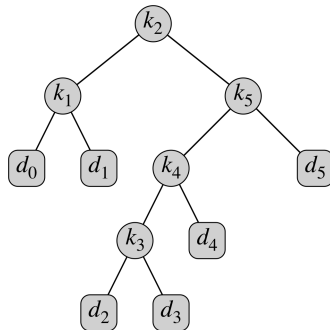
Optimal Binary Search Tree (BST)

- Expected time in binary search trees
 - Depends on frequency of queries
 - Keys queried frequently should be towards the top
- Sequence of sorted keys $K = \langle k_1, k_2, \dots, k_n \rangle$
 - Probability of querying k_i is p_i
- Also $(n + 1)$ dummy keys d_0, d_1, \dots, d_n
 - d_0 represents values less than k_1
 - d_n represents values more than k_n
 - d_i represents all values between k_i and k_{i+1}
 - Probability of querying d_i (between k_i and k_{i+1}) is q_i

Example: Optimal BST



(a)



(b)

i	0	1	2	3	4	5
p_i		0.15	0.10	0.05	0.10	0.20
q_i	0.05	0.10	0.05	0.05	0.05	0.10

- Expected cost of (a) is 2.80, of (b) is 2.75

Expected Cost of Search

- Total probably: successful or unsuccessful search

$$\sum_{i=1}^n p_i + \sum_{i=0}^n q_i = 1$$

- Cost for a node = depth of the node + 1
- Expected cost over all nodes

$$\begin{aligned} E[\text{cost}(T)] &= \sum_{i=1}^n (\text{depth}_T(k_i) + 1) \cdot p_i + \sum_{i=0}^n (\text{depth}_T(d_i) + 1) \cdot q_i \\ &= 1 + \sum_{i=1}^n \text{depth}_T(k_i) \cdot p_i + \sum_{i=0}^n \text{depth}_T(d_i) \cdot q_i \end{aligned}$$

- Goal: Find BST with minimum expected cost
 - Cannot evaluate each BST, total number is $\Omega(4^n/n^{3/2})$

Example: Expected Cost of Search

i	0	1	2	3	4	5
p_i		0.15	0.10	0.05	0.10	0.20
q_i	0.05	0.10	0.05	0.05	0.05	0.10

node	depth	probability	contribution
k_1	1	0.15	0.30
k_2	0	0.10	0.10
k_3	2	0.05	0.15
k_4	1	0.10	0.20
k_5	2	0.20	0.60
d_0	2	0.05	0.15
d_1	2	0.10	0.30
d_2	3	0.05	0.20
d_3	3	0.05	0.20
d_4	3	0.05	0.20
d_5	3	0.10	0.40
Total			2.80

Step 1: Structure of an Optimal BST

- Consider any subtree of a BST
 - Has keys in contiguous range k_i, \dots, k_j , $1 \leq i \leq j \leq n$
 - Has dummy keys d_{i-1}, d_i, \dots, d_j as leaves
- Optimal substructure: Assume T is optimal
 - Let T' be a subtree with keys k_i, \dots, k_j
 - Then T' is optimal for keys k_i, \dots, k_j , dummy keys d_{i-1}, \dots, d_j
- The 'cut-and-paste' argument
 - If a different T'' had lower cost, we can use it to get a better overall solution compared to T
 - Contradicts optimality of overall solution T

Step 1: Structure of an Optimal BST

- For keys k_i, \dots, k_j , one key k_r will be root
 - Left subtree k_i, \dots, k_{r-1} , dummy keys d_{i-1}, \dots, d_{r-1}
 - Right subtree k_{r+1}, \dots, k_j , dummy keys d_r, \dots, d_j
- Explore all k_r as possible root
 - Optimal subtrees on k_i, \dots, k_{r-1} , and k_{r+1}, \dots, k_j
- Need to consider empty subtrees
 - $k_r = k_i$, left subtree has no keys, only dummy key d_{i-1}
 - $k_r = k_j$, right subtree has no keys, only dummy key d_j

Step 2: A Recursive Solution

- Consider keys k_i, \dots, k_j
- Denote $e[i, j]$ as the expected cost of optimal BST
 - $i \geq 1, j \leq n$, and $j \geq i - 1$
 - When $j = i - 1$, no key, only d_{i-1} , so $e[i, i - 1] = q_{i-1}$
- For $j \geq i$, need to select a key k_r from k_i, \dots, k_j
 - Subtree k_i, \dots, k_{r-1} and k_{r+1}, \dots, k_j
 - The depth of keys in the subtrees increase by 1

Step 2: A Recursive Solution

- Denote

$$w(i, j) = \sum_{\ell=i}^j p_{\ell} + \sum_{\ell=j-1}^j q_{\ell}$$

- If k_r is the root of the optimal subtree containing k_i, \dots, k_j

$$e[i, j] = p_r + (e[i, r-1] + w(i, r-1)) + (e[r+1, j] + w(r+1, j))$$

- Since $w(i, j) = w(i, r-1) + p_r + w(r+1, j)$, we have

$$e[i, j] = e[i, r-1] + e[r+1, j] + w(i, j)$$

- Since we need to minimize over k_r , we get the recursion

$$e[i, j] = \begin{cases} q_{i-1} & \text{if } j = i - 1, \\ \min_{i \leq r \leq j} \{e[i, r-1] + e[r+1, j] + w(i, j)\} & \text{if } i \leq j. \end{cases}$$

Step 3: Computing the Expected Cost

- A direct recursive execution would be inefficient
- Working with contiguous indices, store $e[i, j]$ in a table
- Table $e[1 \dots n, 0 \dots n]$
 - First index runs till $(n + 1)$, since $e[n + 1, n]$ considers d_n
 - Second index starts from 0, since $e[1, 0]$ considers d_0
- Table $root[i, j]$ stores root of subtree on k_i, \dots, k_j
- Also maintain table for $w(i, j)$, rather than recomputing
 - Avoid $\Theta(j - i)$ additions each time
 - Table $w(1 \dots n + 1, 0 \dots n)$
 - Base case $w(i, i - 1) = q_i$, and for $j \geq i$

$$w(i, j) = w(i, j - 1) + p_j + q_j$$

Algorithm: Optimal BST

OPTIMAL-BST(p, q, n)

let $e[1 \dots n + 1, 0 \dots n]$, $w[1 \dots n + 1, 0 \dots n]$, and $root[1 \dots n, 1 \dots n]$ be new tables

for $i = 1$ **to** $n + 1$

$e[i, i - 1] = 0$

$w[i, i - 1] = 0$

for $l = 1$ **to** n

for $i = 1$ **to** $n - l + 1$

$j = i + l - 1$

$e[i, j] = \infty$

$w[i, j] = w[i, j - 1] + p_j$

for $r = i$ **to** j

$t = e[i, r - 1] + e[r + 1, j] + w[i, j]$

if $t < e[i, j]$

$e[i, j] = t$

$root[i, j] = r$

return e and $root$

Example: Tables for Optimal BST

