

# TERMES: Termite tracking in collaboration with Harvard University

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**Abstract.** 10 linjer  
problem stilling  
evaluation  
resultat

- State the problem - There is no existing software that allows tracking of termites using the HP plotter provided by harvard as well as being able to extract relevant statistics.
- Say why it's an interesting problem - It will enable biologists to make better analyses based on more empirical data
- Say what your solution achieves - A way to control the plotter that tracks an ant/termite in real time and collects data that can be extracted as statistics
- Say what follows from your solution - While this is just a prototype (in a lab environment) it is a step towards making new and better field equipment for biologists along with corresponding software.

**Keywords:** Computer Vision, Image Processing, Termite Tracking, Biology, Computer Science.

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## 1 Introduction

NÆVN AT KASPER ER VORES VEJLEDER og antal ECTS, projekt periode: 1 september 2013–16 december 2013.

- General statement introducing the area;

You can most likely start with the first paragraph from your project description and evolve it. - The Self-Organizing System Research Lab on Harvard has created a autonomous robot for tracking African termites in a lab environment. Working with and tracking these termites is cumbersome as they only thrive in environments that resemble their native environment and only when they are together with other termites. Therefore automatic tracking of specific termites is necessary, as tracking up until now has been done manually. Hardware has been created to handle this, however it lacks proper software support.

- Explanation of the specific problem and why do we care about the problem. (MOTIVATON)

This project aims to develop software that is able to track both ants and termites in a natural environment using a HP plotter provided by Harvard University. While it is already possible to communicate with the plotter using the program called "Termite"(ref) a need for software that integrates tracking, plotter communication, statistics and a GUI exists. The end product is to be used by biologists in the field and this software will enable them to track ants/termites with more precision and with better data being produced.

- Explanation of your solution, and how it improves on the work by others. Relation to related work can be very brief, given that you have a separate extensive section devoted to this.

A team at Harvard University previously experimented with using the plotter to track the ants/termites with some success. We the details of this effort were somewhat unknown to us we decided to start this project from scratch.

- A hint on how the solution was evaluated and what was the outcome of this evaluation.

Since tracking of ants/termites is very hard to test systematically we have chosen to evaluate it by describing in what instances we expect the tracking to work as intended and in what instance we expect it not to. SKRIV NOGET OM OUTCOME.

- A summary (a “map”) of how the paper is organized. TODO

## 2 Project Proposal

The Self-Organizing System Research Lab on Harvard has created a autonomous robot for tracking African termites in a lab environment. Working with and

tracking these termites is cumbersome as they only thrive in environments that resemble their native environment and only when they are together with other termites. Therefore automatic tracking of specific termites is necessary, as tracking up until now has been done manually. Hardware has been created to handle this, however it lacks proper software support.

The purpose of this project is to develop software, such that the hardware can be used to track these termites and analyse the output, as well as providing basic user input to the robot tracker.

There are three parts in this project:

- 1) Tracking termites using a low resolution camera. In order to track a termite, it is necessary to be able to determine its position and move the camera to its new position using image analysis on the camera output.
- 2) Interact with the tracking device and update the camera's position with the result from the tracking software.
- 3) Design and develop a user interface that can be used by biologists to retrieve statistical data from the tracking.

## 3 Background

Projektet er erstatning for GSD hvad betyder det for os? Hvilket udstyr havde vi at arbejde med? Umiddelbart ville vi gerne have logic code i C++ og GUI i Java så vidt muligt. Hvilke fordele giver det os? hvorfor? Hvad for nogen myrer havde vi og var der nogen udfordringer her? (tænk: hvis jeg skal gøre det igen, hvad skal jeg så huske om myrer) Hvordan var det med at male myrerne?

### 3.1 Assumptions

TODO

### 3.2 Scope

Kun test i et lab environment test på myrer, regner med at det kan generaliseres til termitter (andre størrelser) Kun test med de farver maling vi har Kun test med denne plotter Kontrollerede lysforhold Tracker kun een myre ad gangen

### 3.3 Requirements

Maa jeg foreslaa at i laver 2 modes (man kan f.eks. vælge mode i menuen af toppen af programmet). 1. Den ene er kalibrerings mode hvor man kan se det

direkte feed oeverst til venstre, samt billedbehandlet billede oeverst til hoejre, og sliders nedenfor. 2. Nummer to er tracking mode hvor man kan see feedet fra kameraet taet paa oeverst til venstre, feedet fra overview-kameraet oeverst til hoejre, og saa statistik/grafer nederst til venstre, og valgmuligheder mht til statistik og hvor filerne skal gemmes mv. nederst til hoejre? + start knap. 3. Hvis i faar tid kan i tilfoeje en bias-mode hvor man kan klikke paa et punkt i skaalen som plotteren skal forsoege at traekke myren imod (ved hjalp af mad).

1. Position i skaalen over tid (marker dens rute). + indstilling for hvor lang tid tilbage ruten skal vises. 1. Gennemsnitshastighed/tid (siden start), +indstilling for running average. 2. Heatmap over hvor myren opholder sig mest i skaalen, (groft firkantet grid er fint til at starte med). 3. Heatmap over hvor myren holder pauser i skaalen, +indstilling for hvor lang en 'pause' er, hvor lav den gennemsnitshastighed skal vaere. 3. Tael andre myrer den moeder/tid. +Indstilling for afstand af et 'moede'. 4. Hvor lang tid der gaar imellem den moeder andre/tid (siden start). 5. Hvor meget tid den pauser naer andre myrer/tid. +Indstilling for afstand+pause laengde 6. Hvor meget af skaalen den har undersøegt (Additivt) over tid. +Indstilling for radius af hovedet, (hvor langt fra center af hovedet den kan undersøege af gangen) 7. Hvor meget nyt areal den daekker hvert interval over tid. +indstilling for interval: f.eks. 30s/1min/2min 8. Mean free path. (maal hvor lang tid der gaar mellem pauser. Pauserne defineres af lav gennemsnitshastighed)

Mht gui'en er et mere objekt-orienteret sprog fint med mig. Saa laenge at selve data- og billed behandlingen foregaar i C/C++. Nedenfor har jeg forsoegt at beskrive projektet lidt mere specifikt. Hvis i stadig er interesseret i projektet synes jeg at vi skal tage en skype-snak om helt noejagtige instruktioner.

1. UI: Brugervenligt, visning af live video, samt statistikker for opsamlet data. Bruger input til manuel styring af plotteren, aendring af billed behandlings-parametre i tilfaelde af at udstyret skal bruges til andre insekter i fremtiden, samt input af punkter i arenaen plotteren skal forsoege at styre imod, eller undgaa.

2. Tracking: Formentlig den stoerste udfordring. Plotteren skal kunne tracke en termit maerket med roed og groen maling ud fra et lav resolutions-kamera monteret paa manipulatore. (Hvis i finder et bedre alternativ til det nuvaerende kamera, kan vi sagtens koebe et nyt). Termitten er hvid og brun, og dens baggrund roed/brun jord, derudover vil den vaere omgivet af mange andre (u-maerkede) termitter. De bevaeger sig op til 2cm/s og manipulatore skal helst bevares indenfor 0.5cm radius af hovedet (uden at ramme den eller andre termitter). Jeg vil foreslaa at i starter med at tracke myrer (de er nemmest at finde), paa hvid baggrund, og derefter paa jord.

3. Styring af manipulator: Manipulatorens position skal aendres afhaengigt af outputtet fra tracking-softwaret. Hardwaret kan modtage serielle kommandoer om ny oensket position. Hvis i oensker adgang til softwaren paa microcontrollere som styrer plotteren kan det ogsaa sagtens arrangeres. Det kan blive noedvendigt at indfoere soft-start hvis plotteren skal bevaeges langt for at undgaa pludselige ryk i maskinen der kan skraemme insekterne.

5. Data behandling: Dette vil involvere mange maader at behandle den indsamlede data paa. F.eks. beregning af hastighed/tid, mean-free-path/tid, histogram af position i arenaen/tid, maengde af interaktion/tid, mm. Jeg sender gerne en laengere liste hvis i er interesserede.

## 4 Tracking

Image Segmentation Thresholding Dilating Eroding Alternatives and why we don't use them

### 4.1 Communication with the plotter

Hvilken plotter er det og hvilket udstyr sidder på den Hvordan er den sat til computeren hvad vil vi gerne have den til hvordan gør vi dette hvilke "services" ender vi med at udstille til resten af programmet (flyt til koordinat, current coordinate?)

\* 0x01 = send coordinate to plotter \* 0x01 + 2 bytes for x + 2 bytes for y (up to 10 bits) up to 0x03FF (y probably only up to 01F0) \* 0x02 in response = success \* 0xFE in response = failure

## 5 Integration with camera

TODO

## 6 Graphical user interface

TODO

### 6.1 Statistics

## 7 Process

Vi har modtaget video først for at kunne starte før vi fik plotteren.

### 7.1 International collaboration

TODO

### 7.2 Tools

TODO

## 8 Reflection/Future work

TODO

## 9 Evaluation

vis hvornår det virker og hvornår det virker. Se at det virker når vi regnede med at det virkede.

## 10 Threats to validity

TODO

### 10.1 Threats to internal validity

Internal Validity is concerned with confirming that the correlation between the treatment and the outcome is indeed casual, and not accidental, or caused by some third variable that has not been observed. For example we may discover that all programmers in C were faster than programmers in Java, but forget that all the programmers in Java took the experiment very late at night, when they were tired.

### 10.2 Threats to external validity

External validity discusses how far the results are generalizable, or in other words how representative the sample of subjects and the circumstances of the experiment were, to be able to draw general conclusion. Do you expect the same results to be confirmed in somewhat modified conditions?

## 11 Related Work

TODO

## 12 Future Work

More statistics Bias mode Support for multiple plotters Plotter control as a library Tests with real termites Developer terminal/log (print was is sent to the plotter and the answer + the hard tracking coordinate data)

## 13 Conclusion

TODO

## **14 Defition of terms**

TODO

## **References**

[1] TestTitle - TestPublisher - 1999

## **A First Appendix**