

# Unit-III

## Shading Models

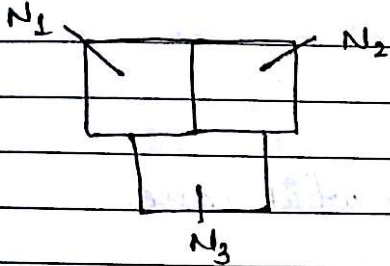
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27/09/17

→ Gouraud Shading Model -

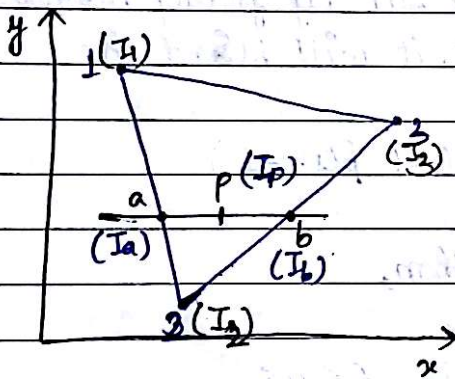
- i) Calculate avg. normal vector of given polygon surface
- ii) Apply Illumination Model
- iii) Calculate linear interpolated intensities of surface polygon vertices



$$N_v = \frac{N_1 + N_2 + N_3}{|N_1 + N_2 + N_3|}$$

In general form,

$$N_v = \frac{\sum_{i=0}^n N_i}{|\sum_{i=0}^n N_i|}$$



for vertex 1 & 2, intensities are  $I_1$  &  $I_2$

So, for any point 'a' on the vertex 1 to 2, intensity at 'a' is

$$I_a = \frac{y_a - y_2}{y_1 - y_2} (I_1) + \frac{y_1 - y_a}{y_1 - y_2} (I_2)$$

Similarly,

$$I_b = \frac{y_b - y_2}{y_3 - y_2} (I_3) + \frac{y_3 - y_b}{y_3 - y_2} (I_2)$$

$$\text{and, } I_p = \frac{x_b - x_a}{x_b - x_a} (I_a) + \frac{x_p - x_a}{x_b - x_a} (I_b)$$

Now, for the next line (ie. y-1), the intensity  $I'$  will be calculated as

$$I' = I + \frac{I_2 - I_1}{y_1 - y_2}$$

at Horizontal projection position,

$$I' = I + \frac{I_b - I_a}{x_b - x_a}$$

Disadvantages -

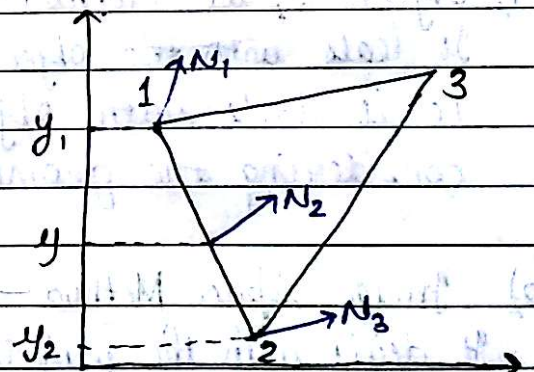
The linear intensity interpolation can result in bright or dark intensity streaks or patches appearing on the surface.

These patches are called Mach-bands.

→ Phong Shading Model -

- i) Determine unit normal vector for every polygon surface
- ii) Linearly interpolate the vertex normal over polygon surface (N)
- iii) Apply Illumination Model

$$N = \left[ \frac{y - y_2}{y_1 - y_2} \cdot N_1 \right] + \left[ \frac{y_1 - y}{y_1 - y_2} \cdot N_3 \right]$$

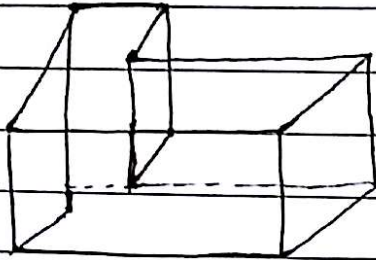


→ Flat Shading Model -

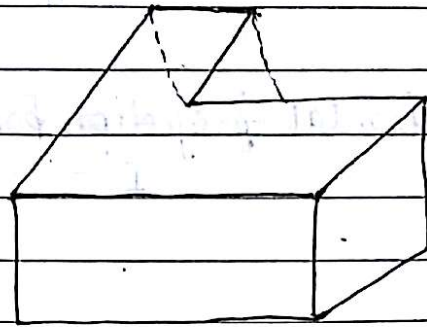
→ Polygon mesh



## → Visible Surface Detection -



(Hidden Surface Display)



(Hidden Surface Removal)

- The surfaces that are drawn or hidden from view must be removed in order to construct a realistic view of the 3-D scene.
- The identification and removal of these surfaces is called 'Hidden Surface Problem'.
- This problem is solved by applying Hidden Surface Algorithms which are categorized into two methods -

### 1) Object Space Method -

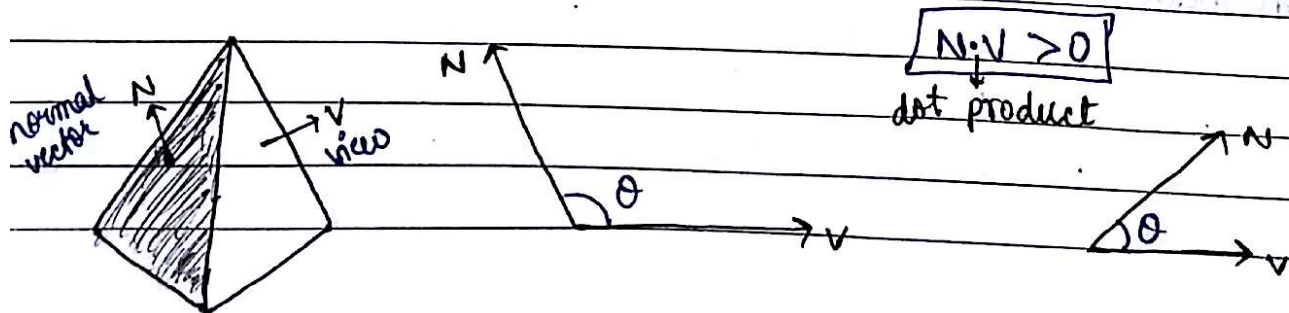
It deals with the object definition directly  
i.e. it deals with object in one-world co-ordinate system considering the geometrical relationship b/w the actual objects.

### 2) Image Space Method -

It deals with the projected image with screen co-ordinate system by considering pixel position on the view plane.

## → Object Space Method

### Back Face Detection Method -



i) This algorithm is based upon 'Inside-Outside Test' for identifying the back face of a polygon.

ii) The dir<sup>n</sup> of the light can be identified by examining the result  $N \cdot V > 0$ , where  $N \rightarrow$  normal vector to the polygon surface  
 $V \rightarrow$  vector in the view direction

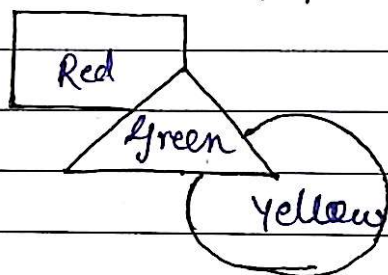
iii) When both the vectors are in the <sup>same</sup> direction, then cosine will be +ve ( $> 0$ ). It means  $N$  &  $V$  that the polygon is visible.

v) If  $N$  &  $V$  are in opp. direction, then  $\cos \theta < 0$   
 $\Rightarrow$  polygon is back-faced

Image Space Method mainly consists of -

1) Z Buffer / Depth Buffer Method

- deals with overlapping solid shapes where one shape/colour completely overlaps another shape

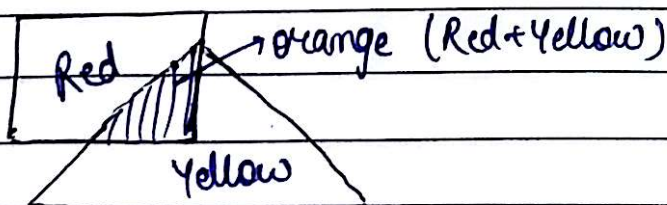


2) A Buffer

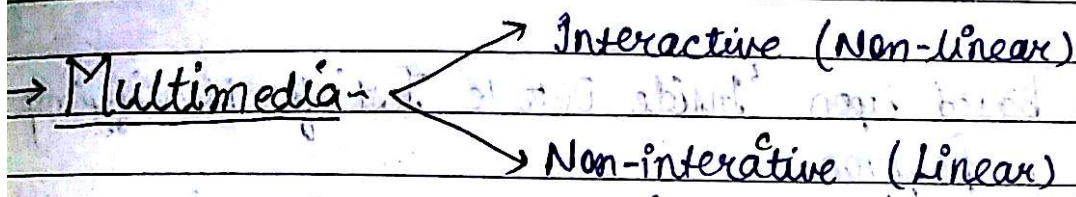
- overlapping of two surfaces is partial

eg. ~~an~~ transparent glass window over a background scenery

- Colours are mixed to give a third colour rather than one colour completely domination over other







1) What do you mean by Multimedia?

2) Diff. b/w interactive / non-interactive

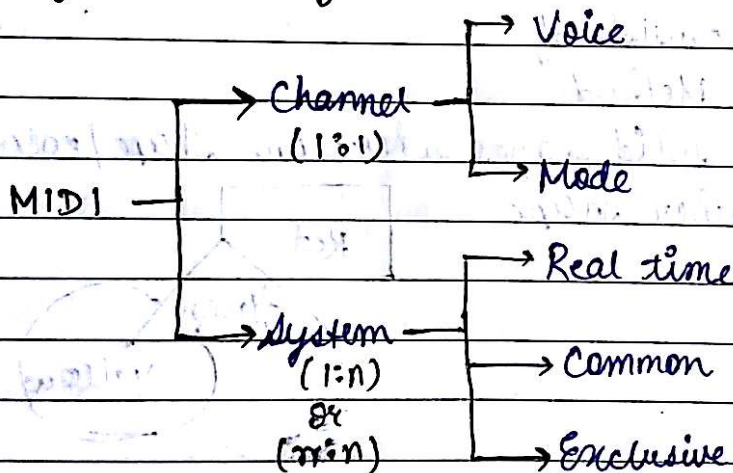
3) Diff. b/w hypertext & hypermedia

4) Applications of multimedia

5) What do you mean by virtual reality?

MIDI - Musical Instrument Digital Interface

Type of MIDI Messages -



→ Animation -

→ Cell animation - Key frames? Tweening

→ Computer

→ Morphing Tech.

→ Wrapping Tech.

→ Interpolation Technique