# Data Structure

TREE

UNIT - 3

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DEPARTMENT OF INFORMATION TECHNOLOGY

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ASST. PROFESSOR

#### Which Book To Follow?

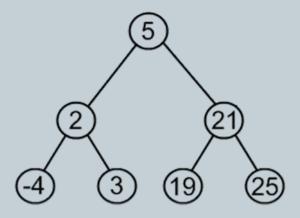
- Text Book
  - o Data Structures, Schaum's Outlines, Seymour Lipschutz
- Reference Book
  - o Data Structure Using C, Udit Aggarwal

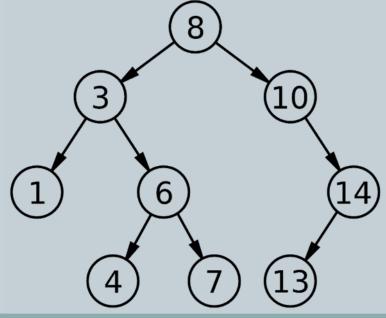
# Binary Search Tree

# Binary Search Tree (BST)

#### Binary Search Tree

- Binary Tree T is called Binary Search Tree (or Binary Sorted Tree) if each Node N of T has following property:
  - × Value at N is Greater than every value in the Left Subtree & is Less than every value in Right Subtree of N.
- Assumption:
  - × All the Node Values are Distinct.





# Binary Search Tree



- Suppose six Numbers are Inserted in order into empty Binary
   Search Tree:
  - **40**, 60, 50, 33, 55, 11

## Searching in Binary Search Tree

- ALGORITHM: FIND (INFO, LEFT, RIGHT, ROOT, ITEM, LOC, PAR)
  - The algorithm finds location LOC of ITEM in Binary Search Tree T and also location of parent PAR of ITEM.
    - If ROOT = NULL, then: Set LOC := NULL and PAR := Null, and Return.
    - If ITEM = INFO[ROOT], then Set LOC := ROOT and PAR := NULL, and Return.
    - 3. If ITEM < INFO[ROOT], then:

```
Set PTR := LEFT[ROOT] and SAVE := ROOT.
```

Else:

Set PTR := RIGHT[ROOT] and SAVE := ROOT.

- 4. Repeat Steps 5 & 6 while PTR != NULL:
- If ITEM = INFO[PTR], then: Set LOC := PTR and PAR := SAVE, and Return.
- 6. If ITEM < INFO[PTR], then:
- Set SAVE := PTR and PTR := LEFT[PTR].
- 8. Else:
- 9. Set SAVE := PTR and PTR := RIGHT[PTR].
- 10. Set LOC := NULL and PAR := SAVE
- 11. Exit.

# Insertion in Binary Search Tree

- ALGORITHM: INSBST (INFO, LEFT, RIGHT, ROOT, AVAIL, ITEM, LOC)
  - The algorithm finds location LOC of ITEM in Binary Search Tree T and adds ITEM as new node in T at location LOC.
    - call FIND (INFO, LEFT, RIGHT, ROOT, ITEM, LOC, PAR)
    - 2. If LOC = NULL, then Exit.
    - a) If AVAIL = NULL, then: Write OVERFLOW, and Exit.
      - b) Set NEW := AVAIL, AVAIL := LEFT[AVAIL] and INFO [NEW] := ITEM.
      - c) Set LOC := NEW, LEFT[NEW] := NULL and RIGHT[NEW] := NULL
    - 4. If PAR = NULL, then:

Set ROOT := NEW.

Else If ITEM < INFO[PAR], then:

Set LEFT[PAR] := NEW.

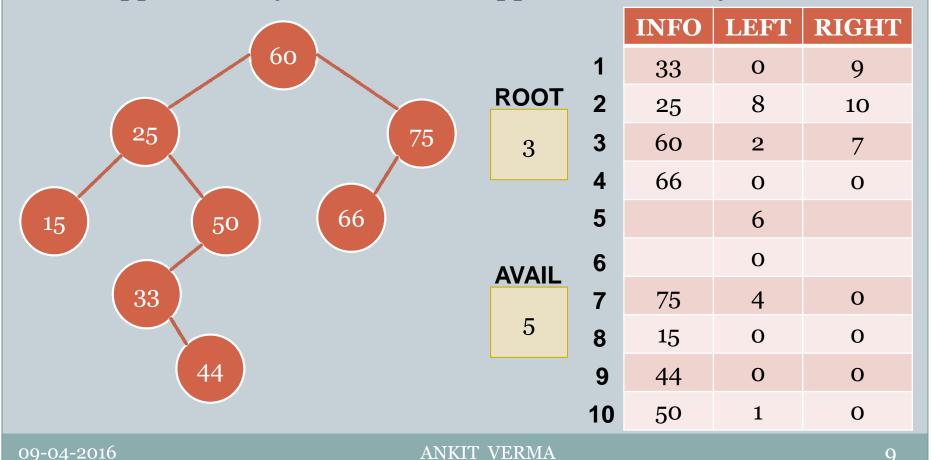
Else

Set RIGHT[PAR] := NEW.

5. Exit

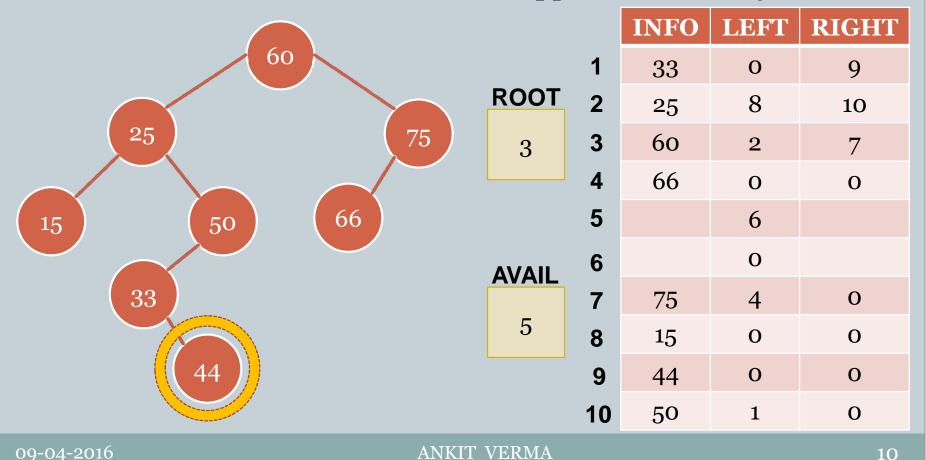
- Deleting in Binary Search Tree (BST)
  - Three Cases of Deletion:
    - × Case 1
      - Node N has No Children
    - × Case 2
      - Node N has exactly One Children
    - × Case3
      - o Node N has Two Children

- Linked Representation of Binary Search Tree (BST)
  - Suppose Binary Search Tree T appears in Memory as follows:



#### Case 1 – Node N has No Children

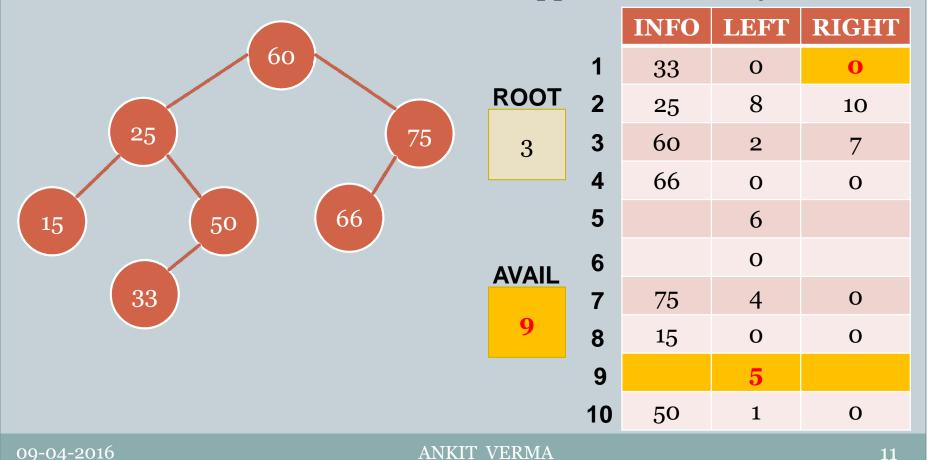
O Node 44 is Deleted from T then T appears in Memory as follows:



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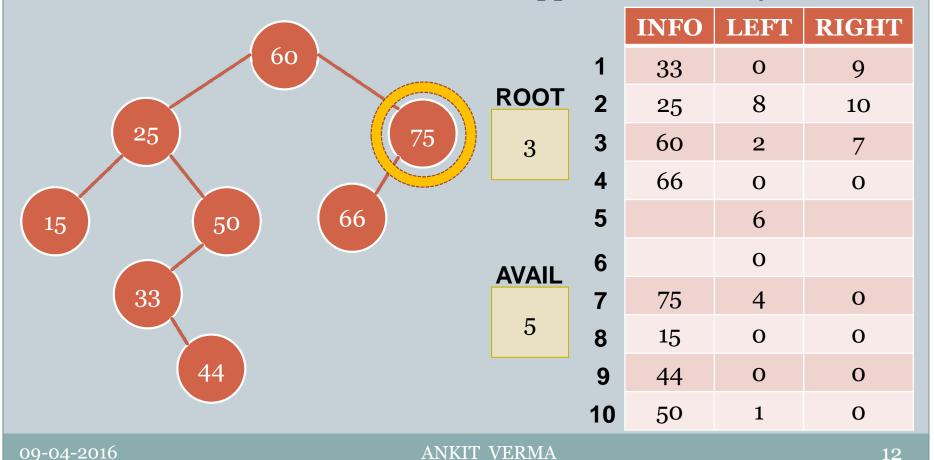
- Case 1 Node N has No Children
  - O Node 44 is Deleted from T then T appears in Memory as follows:



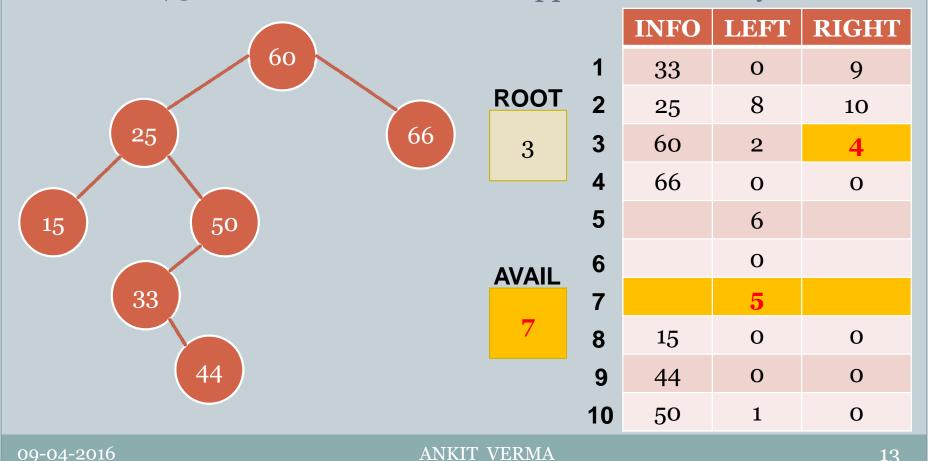
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- Case 2 Node N Has exactly One Child
  - O Node 75 is Deleted from T then T appears in Memory as follows:

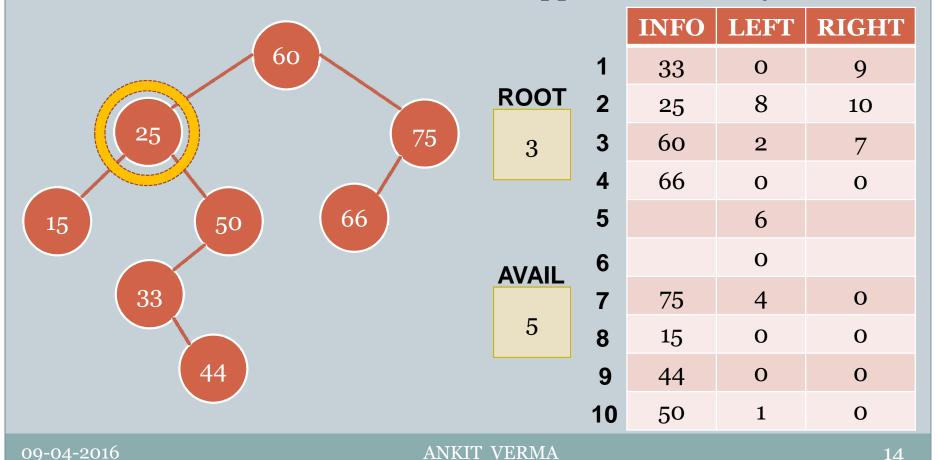


- Case 2 Node N Has exactly One Child
  - O Node 75 is Deleted from T then T appears in Memory as follows:

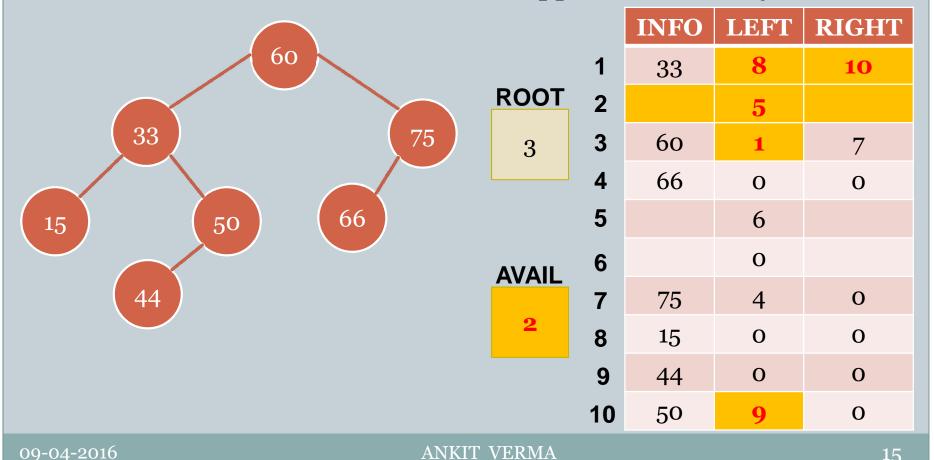


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- Case 3 Node N has Two Children
  - O Node 25 is Deleted from T then T appears in Memory as follows:



- Case 3 Node N has Two Children
  - O Node 25 is Deleted from T then T appears in Memory as follows:



- ALGORITHM: CASEA (INFO, LEFT, RIGHT, ROOT, LOC, PAR)
  - The algorithm deletes node N at location LOC, where N does not have two children, it have one child or no child. Pointer PAR have location of Parent of N, if PAR = NULL indicates N is root node. Pointer CHILD gives location of only child of N, if CHILD = NULL indicates N has no children.

- ALGORITHM: CASEB (INFO, LEFT, RIGHT, ROOT, LOC, PAR)
  - The algorithm deletes node N at location LOC, where N have two children. Pointer PAR have location of Parent of N, if PAR = NULL indicates N is root node. Pointer SUC gives location of inorder successor of N, and PERSUC gives location of parent of inorder successor.

```
a) Set PTR := RIGHT[LOC] and SAVE := LOC
b) Repeat while LEFT[PTR] != NULL:
    Set SAVE := PTR and PTR := LEFT[PTR].
c) Set SUC := PTR and PARSUC := SAVE.
Call CASEA(INFO , LEFT, RIGHT, ROOT, SUC, PARSUC).
a) If PAR != NULL, then:
    If LOC = LEFT[PAR], then:
        Set LEFT[PAR] := SUC.
Else:
        Set RIGHT[PAR] := SUC.
Else:
        Set ROOT := SUC.
b) Set LEFT[SUC] := LEFT[LOC] and RIGHT[SUC] := RIGHT[LOC].
```

Exit

- ALGORITHM: DEL (INFO, LEFT, RIGHT, ROOT, AVAIL, ITEM)
  - T is Binary Search Tree in Memory and an ITEM of information is given. This algorithm deletes ITEM from the tree T.
    - call FIND(INFO, LEFT, RIGHT, ROOT, ITEM, LOC, PAR).
    - If LOC = NULL, then: Write: ITEM not in tree, and Exit.
    - If RIGHT[LOC] != NULL and LEFT[LOC] != NULL, then:
      Call CASEB(INFO, LEFT, RIGHT, ROOT, LOC, PAR).

Else:

Call CASEA(INFO, LEFT, RIGHT, ROOT, LOC, PAR).

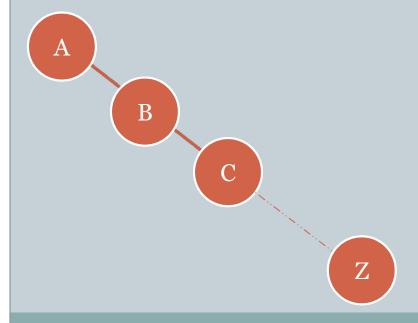
- Set LEFT[LOC] := AVAIL and AVAIL := LOC.
- 3. Exit

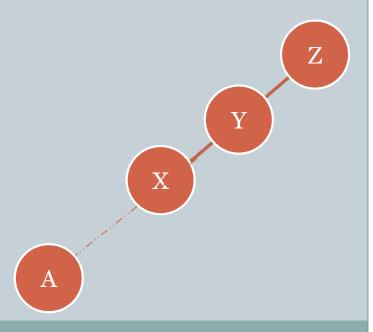


# Skewed Binary Search Tree

- Skewed Binary Search Tree
  - o Right Skewed
    - $\times$  A, B, C, D, . . . . , Z

- Left Skewed
  - $\times$  Z, Y, X, W, . . . . , A





## Skewed Binary Search Tree

- Disadvantages of Skewed Binary Search Tree
  - Worst Case Time Complexity of Search is O(n)
    - ▼ Take More Time for Searching in Worst Case
- Solution to Overcome Disadvantage
  - o Binary Search Tree should be of Balanced Height
    - ▼ Worst Case Time Complexity of Search will be O(log n)
      - Take Less Time for Searching in Worst Case

#### **AVL Tree**



- Most popular Balanced Tree
- Introduced in 1962 by Adelson − Velskii & Lendis
- Also known as AVL Tree or AVL Search Tree
- Worst Case Time Complexity of Search is Less
- Take Less Time for Searching in Worst Case

#### **AVL Tree**

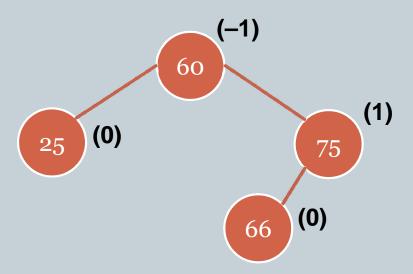
#### Definition

- An empty Binary Tree is an AVL Tree. A non empty Binary T is an AVL Tree if given  $T^L$  &  $T^R$  to be the Left & Right Subtrees of T and  $h(T^L)$  &  $h(T^R)$  to be the Heights of Subtrees  $T^L$  &  $T^R$  respectively,  $T^L$  &  $T^R$  are AVL Trees and  $|h(T^L) h(T^R)| <= 1$
- o Balance Factor (BF)
  - Is known as Balance Factor (BF)
  - $\times$  Balancing Factor of a Node in AVL Tree can be either 0, 1 or -1

#### **AVL Tree**

#### Representation of AVL Tree

 AVL Tree like Binary Search Tree are represented using Linked Representation and every Node registers its Balance Factor



#### Insertion in AVL Tree

#### Insertion in AVL Tree

- Inserting Element in AVL Tree is similar to Binary Search Tree
- After Insertion, Balance Factor of any Node may affected and Tree may become Unbalanced
- Rotations are made on Unbalanced Tree to Restore the Balanced Tree
- To perform Rotation it is necessary to identify Node A whose BF(A) is neither 0, 1 or −1, and which is nearest ancestor to Inserted Node on path from Inserted Node to Root
  - ▼ This implies that all Nodes on the Path from the Inserted Node to A
     will have their Balance Factors to be either 0, 1 or −1

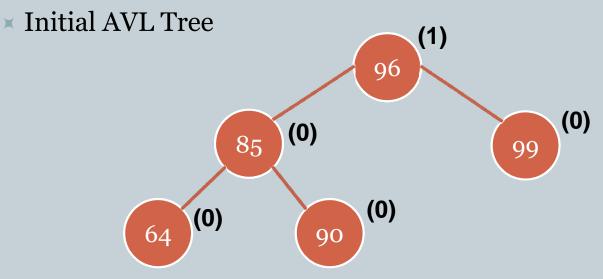
#### Rotations while Insertion in AVL Tree

- Rebalancing Rotations while Insertion in AVL Tree are classified into Four Types:
  - **X** LL Rotation
    - Inserted Node is in Left Subtree of Left Subtree of Node A
  - **RR** Rotation
    - Inserted Node is in Right Subtree of Right Subtree of Node A
  - **X** LR Rotation
    - Inserted Node is in Right Subtree of Left Subtree of Node A
  - **RL** Rotation
    - Inserted Node is in Left Subtree of Right Subtree of Node A

### LL Rotation



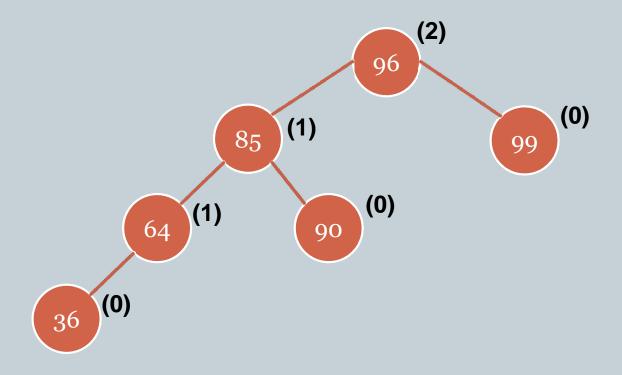
- o Inserted Node is in Left Subtree of Left Subtree of Node A
- Example:



[ Balanced AVL Tree ]

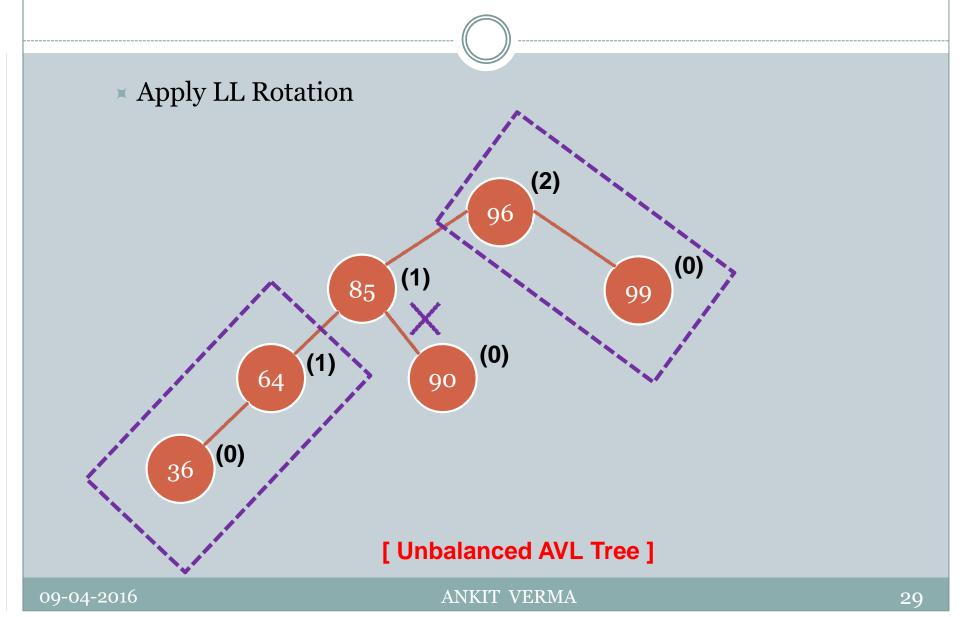
### LL Rotation

× Insert Node 36



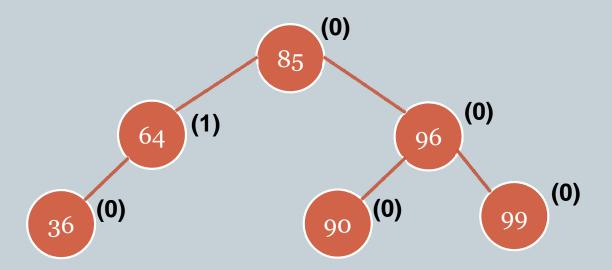
[ Unbalanced AVL Tree ]





### LL Rotation





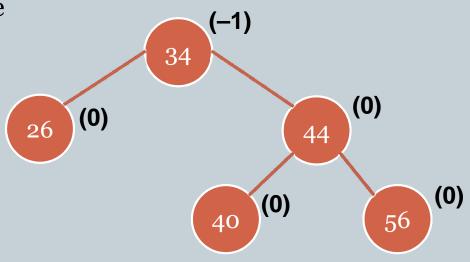
[ Balanced AVL Tree ]

#### **RR** Rotation



- o Inserted Node is in Right Subtree of Right Subtree of Node A
- Example:

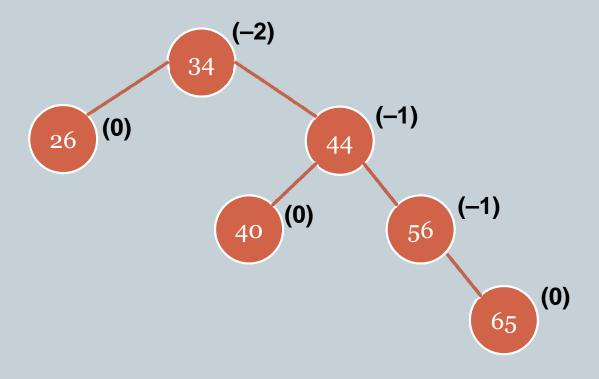
× Initial AVL Tree



[ Balanced AVL Tree ]

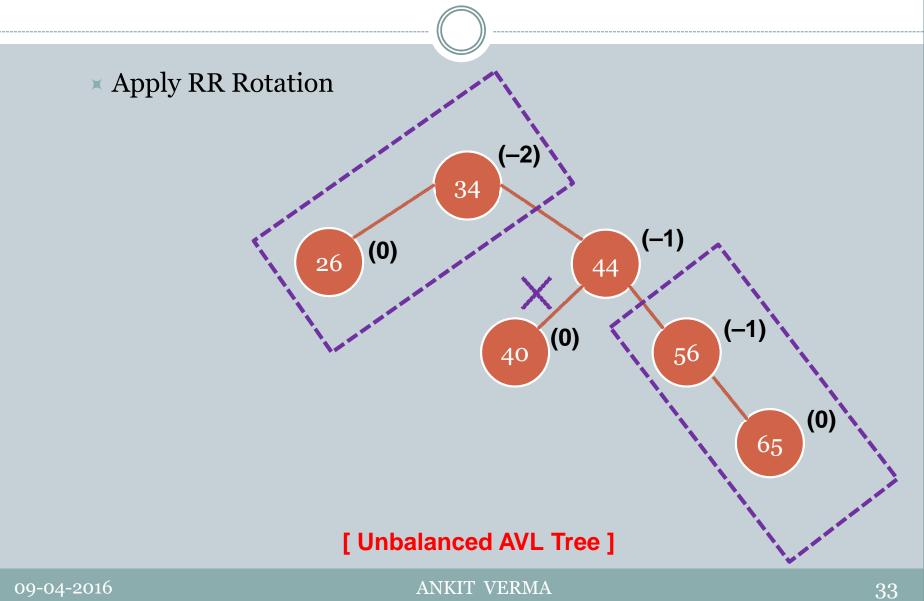
#### **RR** Rotation

× Insert 65



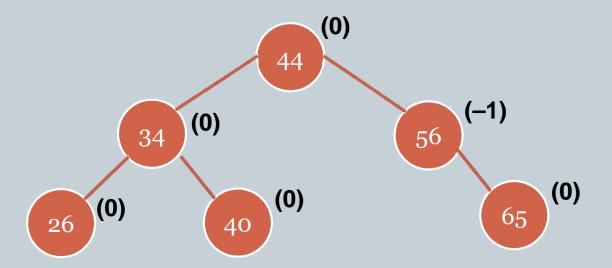
[ Unbalanced AVL Tree ]





#### **RR** Rotation





[ Balanced AVL Tree ]

#### LR & RL Rotation

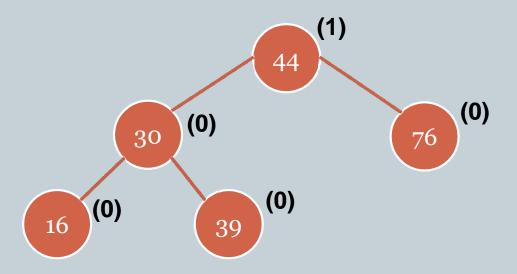
#### LR & RL Rotation

- o Both are Similar in nature but are Mirror Images of One Another
- LL & RR are called Single Rotations but
   LR & RL are called Double Rotations.
- LR Rotation
  - ▼ Inserted Node is in Right Subtree of Left Subtree of Node A
- RL Rotation
  - ➤ Inserted Node is in Right Subtree of Left Subtree of Node A
- Time Complexity of AVL Insertion is O(height) = O(log n)

#### LR Rotation



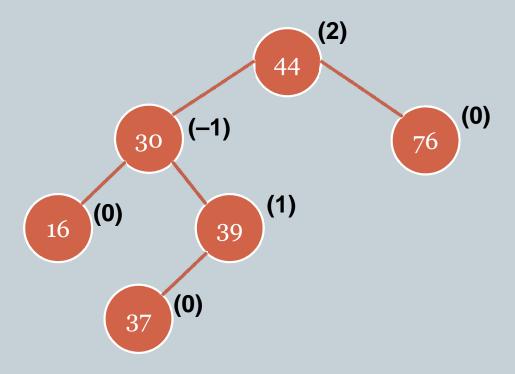
× Initial AVL Tree



[ Balanced AVL Tree ]

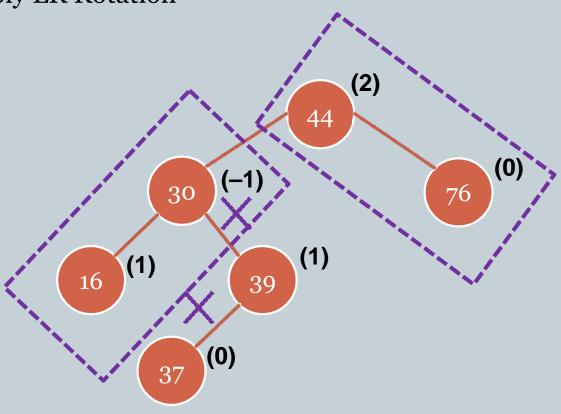
# LR Rotation

× Insert Node 37



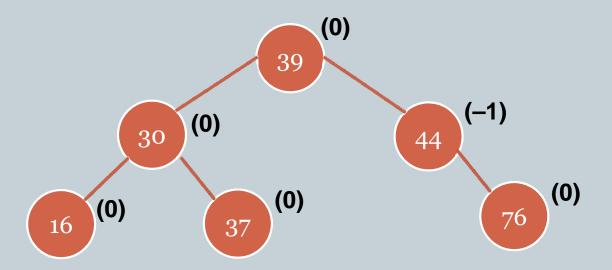
# LR Rotation





# LR Rotation





# **AVL Tree Construction**



0 64, 1, 14, 26, 13, 110, 98, 85

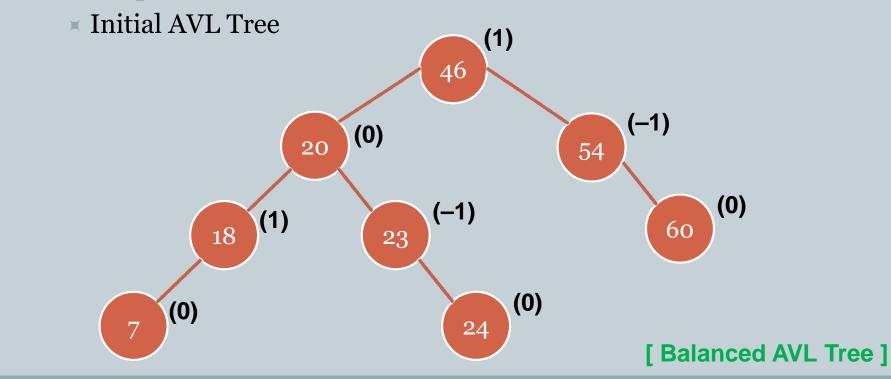
# Deletion in AVL Tree

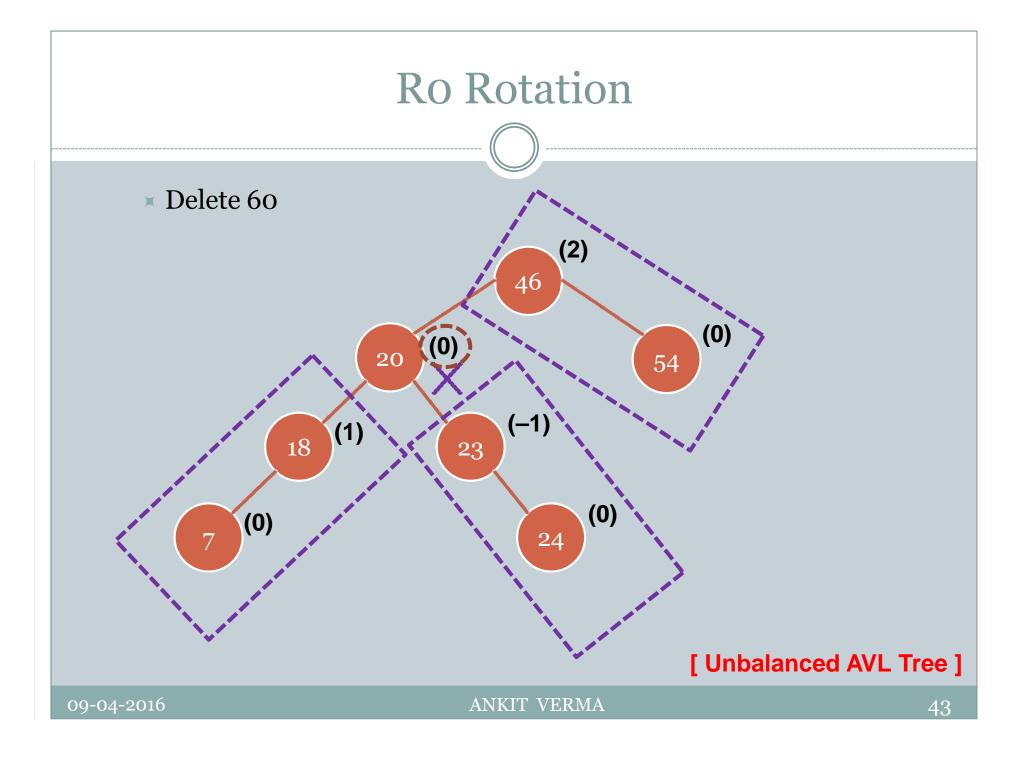
#### Deletion in AVL Tree

- Imbalance due to Deletion, One or More Rotations need to be applied to Balance the Tree
- o After Deletion of Node X, let A be Closest Ancestor Node on path from X to Root, with BF +2 or −2
- o To Restore Balance the Rotation are classified as L or R depend on whether Deletion occurred at Left or Right Subtree of A
- Depending on Value of BF(B) where B is the Root of Left or Right Subtree of A, the
  - **R** Rotation are further classified
    - o R o, R 1 & R −1
  - × L Rotation are further classified
    - o L o, L 1 & L −1

## Ro Rotation

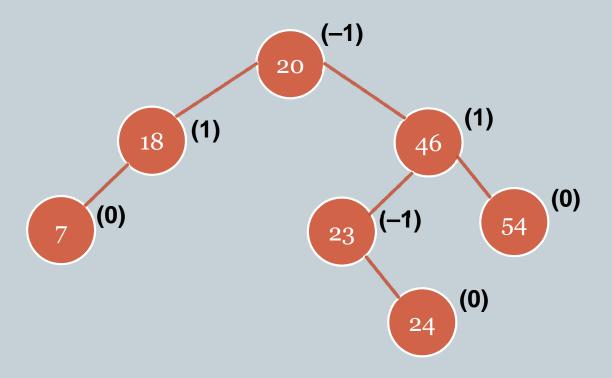
- Ro Rotation
  - o If BF(B) = 0, the Ro Rotation is executed
  - o Example:





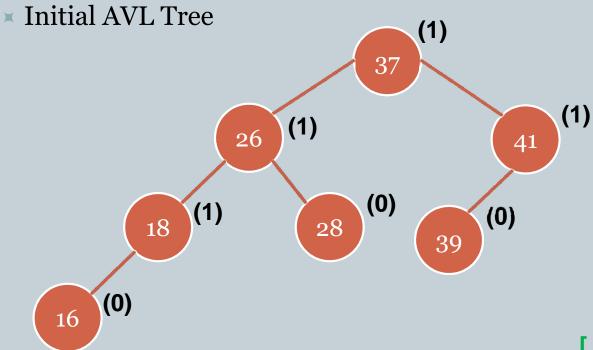
# Ro Rotation

**After Ro Rotation** 

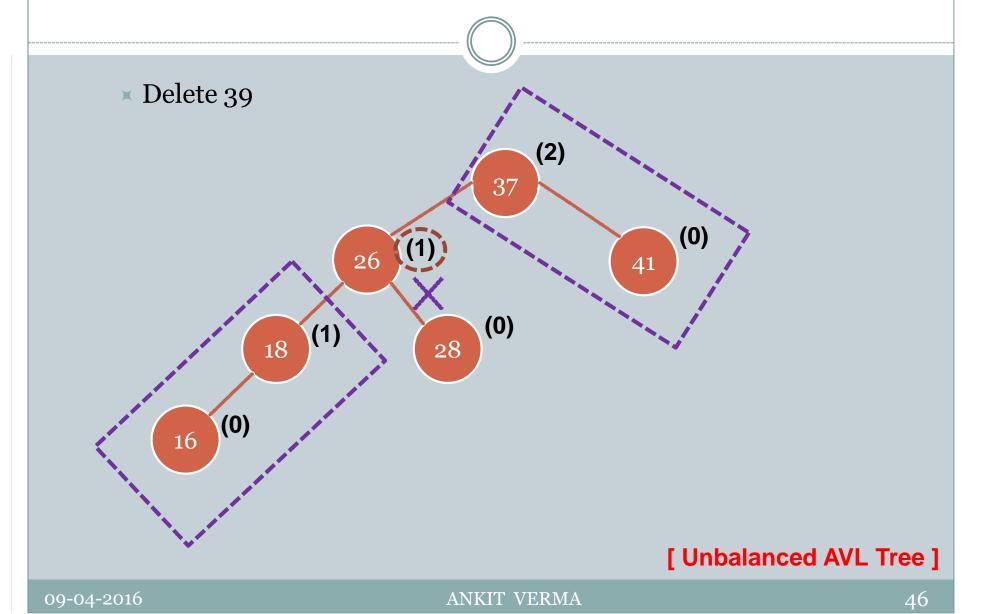


# R<sub>1</sub> Rotation

- R1 Rotation
  - o If BF(B) = 1, the R1 Rotation is executed
  - o Example:

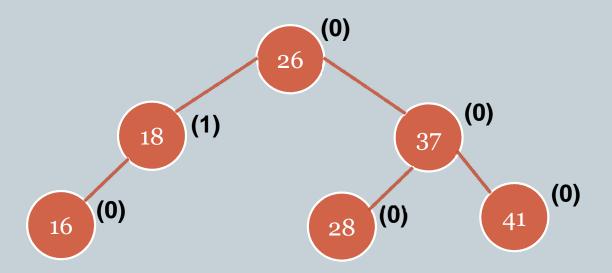






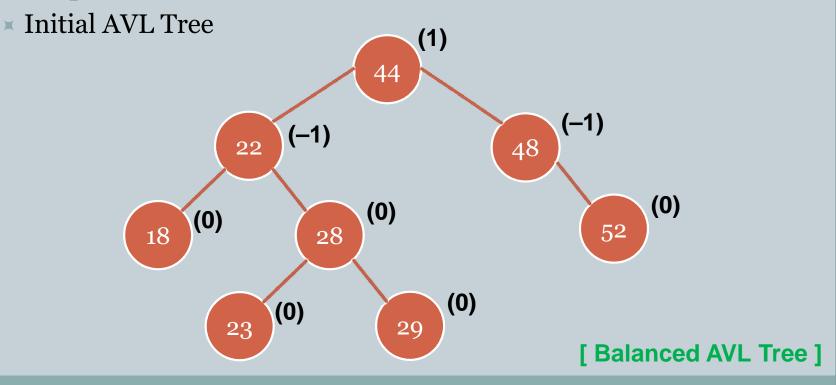
# R<sub>1</sub> Rotation



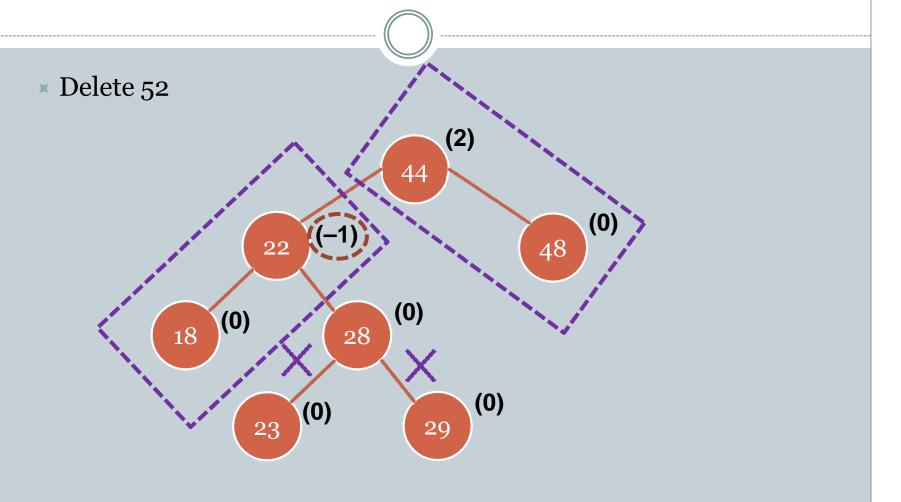


## R-1 Rotation

- R-1 Rotation
  - o If BF(B) = -1, the R-1 Rotation is executed
  - o Example:

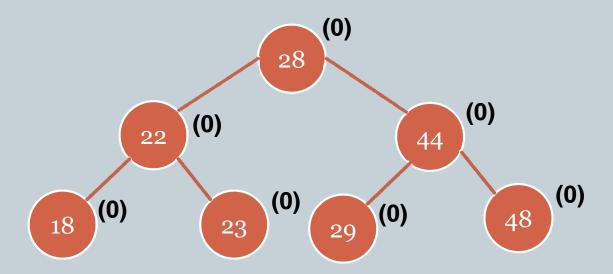






# R-1 Rotation

#### x After R-1 Rotation



#### Data Structure Stored in Internal Memory

 All Data Structure described till, stored in Internal Memory & Support Internal Information Retrieval

#### Data Structure Stored in External Memory

- Favor Retrieval & Manipulation of Data Stored in External Memory (i.e. Disks)
- o E.g. m-Way Tree, B Tree, B+ Tree

#### m-Way Tree

- o Generalized version of Binary Search Tree (BST)
- o Goal is to Minimize Accesses while retrieving Key from a File
- Height h calls fro O(h) Number of Accesses for an Insert / Delete
   / Retrieval Operation
- o But Height h is close to  $\log_m(n + 1)$ , because Number of Elements in m-Way Tree of Height h Ranges from a Minimum of h to a Maximum of  $m^h 1$
- So m-Way Tree of n Elements Ranges from a Minimum Height of log<sub>m</sub>(n + 1) to Maximum Height of n
- Hence there is need to maintain Balanced m-Way Tree. B-Tree are Balanced m-Way Tree

#### Definition

- o An m-Way Tree T may be an Empty Tree
- o If T is Not Empty, it Satisfies following Properties:
  - For some integer m, known as **Order of Tree**, each Node is of Degree which can reach a Maximum of m
    - Each Node has at most m Child Nodes
    - A Node is represented as  $A_0$ ,  $(K_1, A_1)$ ,  $(K_2, A_2)$  . . .  $(K_{m-1}, A_{m-1})$  where,  $K_i$ ,  $1 \le i \le m-1$  are the Keys and  $A_i$ ,  $0 \le i \le m-1$  are Pointers to Subtree of T
  - If a Node has k Child Nodes where  $k \le m$ , then Node can have only (k-1) Keys K1, K2, . . . ,  $K_{k-1}$ , contained in Node such that  $K_i \le K_{i+1}$  and Each of the Keys Partitions all the Keys in Subtree into k Subsets

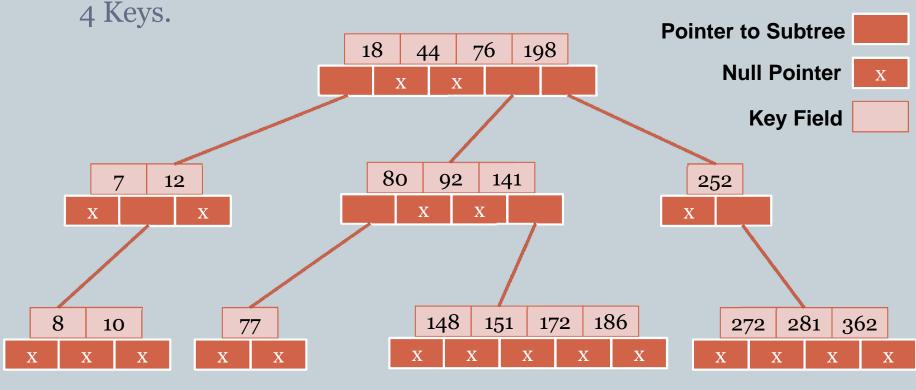
- For a Node  $A_0$ ,  $(K_1, A_1)$ ,  $(K_2, A_2)$  ...  $(K_{m-1}, A_{m-1})$ , all Key Values in Subtree pointed to by  $A_i$  are less than the Key  $K_{i+1}$ , 0 <= i <= m-2, and all Key Values in Subtree pointed to by  $A_{m-1}$  are Greater than  $K_{m-1}$
- Each of Subtree in  $A_i$ ,  $0 \le i \le m 1$  are also m-Way Trees



• Example: 5-Way Tree

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• Each Node has at most 5 Child Nodes and therefore has at most



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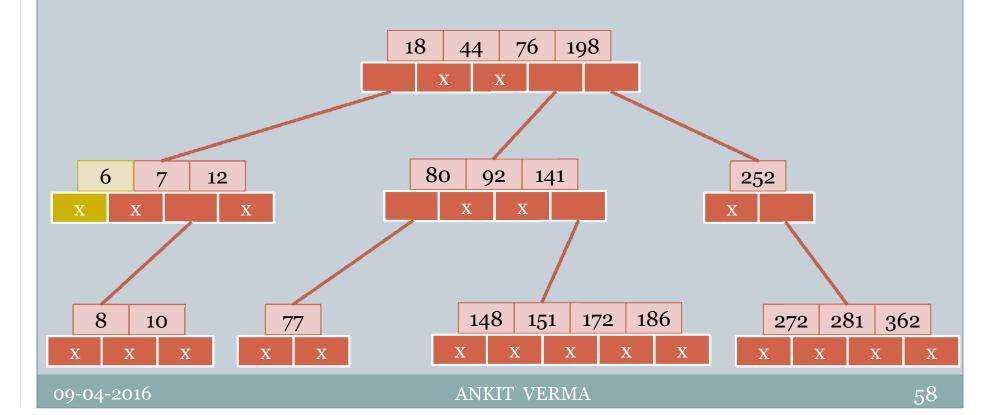
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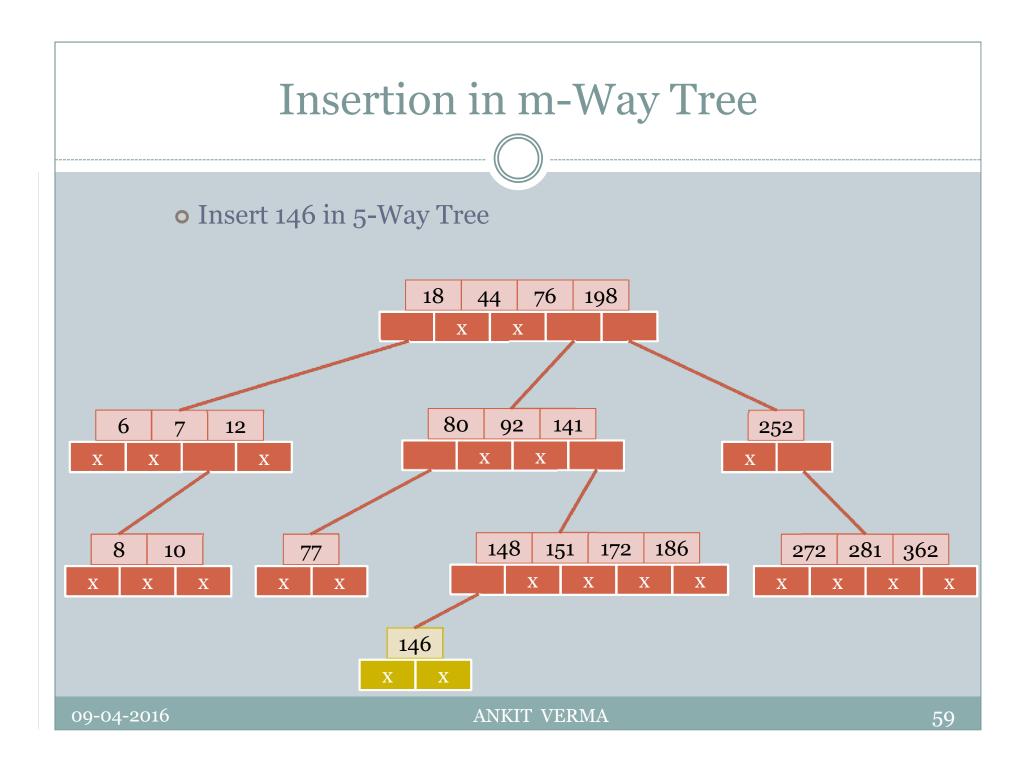
# m-Way Tree Operations

- m-Way Tree Operations
  - Searching in m-Way Tree
    - Searching in m-Way Tree is Similar to Binary Search Tree
  - o Insertion in m-Way Tree
    - ▼ Insertion in m-Way Tree is Similar to Binary Search Tree
      - Search the Location for New Element
      - Insert the Element in Searched Location
  - Deletion in m-Way Tree

# Insertion in m-Way Tree

- o Insertion in m-Way Tree
  - **Example:** 
    - Insert 6 in 5-Way Tree





# m-Way Tree Construction

- m-Way Tree Construction
  - o 3-Way Tree Constructed out of Empty Search Tree with following Keys in the order:
    - × D, K, P, V, A, G



#### **B-Tree**



- M-Way Tree have Advantage of Minimizing File Accesses due to their Restricted Height
- Height of Tree should be kept as Low as Possible and maintain Balanced m-Way Tree
- o Balanced m-Way Tree is called B-Tree

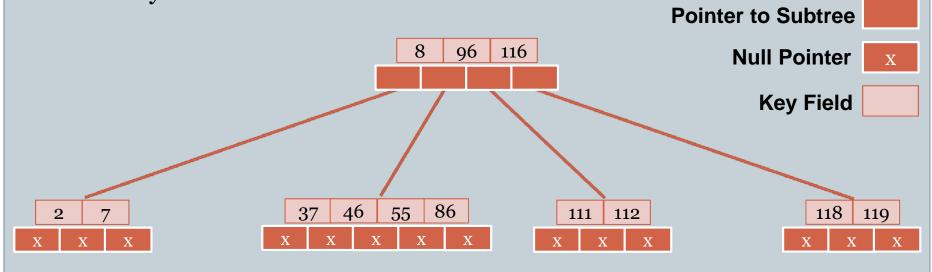
#### **B-Tree**

#### Definition

- A B-Tree of Order m, is Non Empty, is an m-Way Tree in which:
  - Root has at Least Two Child Nodes and at Most m Child Nodes
  - Internal Nodes except the Root have at Least  $\left| \frac{m}{2} \right|$  Child Nodes and at Most m Child Nodes
  - Number of Keys in each Internal Node is One Less than the Number of Child Nodes and these Keys Partition the Keys in Subtrees of Node in a manner to that of m-Way TreeType equation here.
  - All Leaf Nodes are on Same Level



- B-Tree of Order 5
  - Example
    - x Each Node has at most 5 Child Nodes and therefore has at most 4 Keys.



# Insertion in B-Tree

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- Insertion in B-Tree
  - Example:
    - ➤ Insert 4 in B-Tree of Order 5

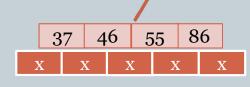
**Pointer to Subtree** 

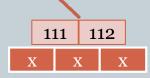
**Null Pointer** 







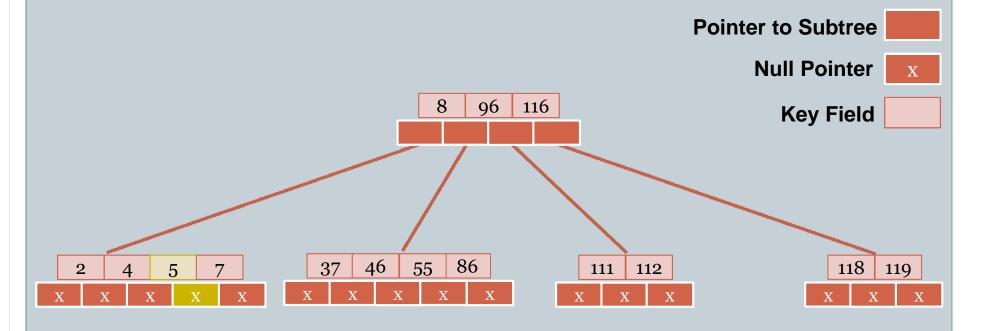






# Insertion in B-Tree

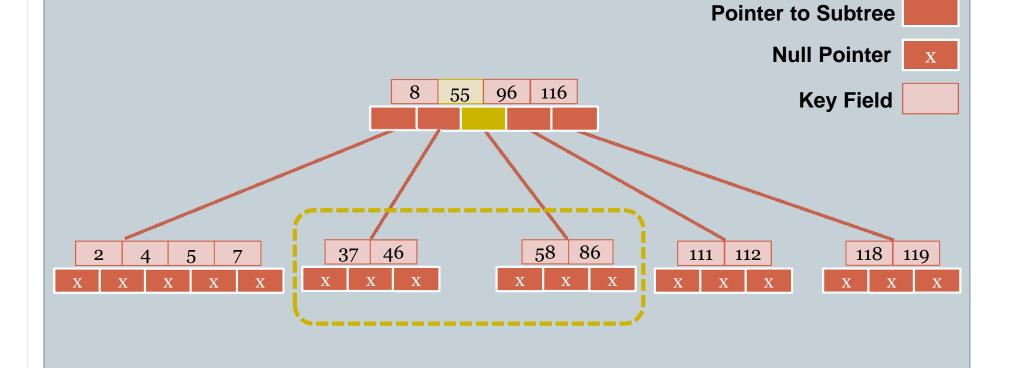
x Insert 5 in B-Tree of Order 5





x Insert 58 in B-Tree of Order 5

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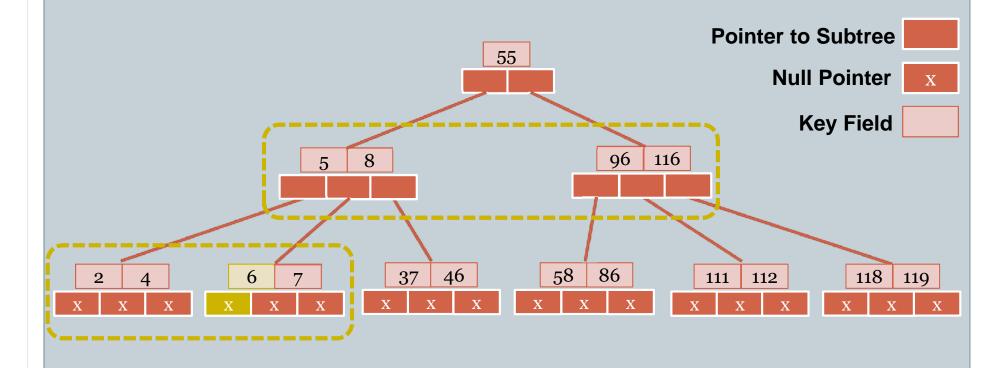


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x Insert 6 in B-Tree of Order 5

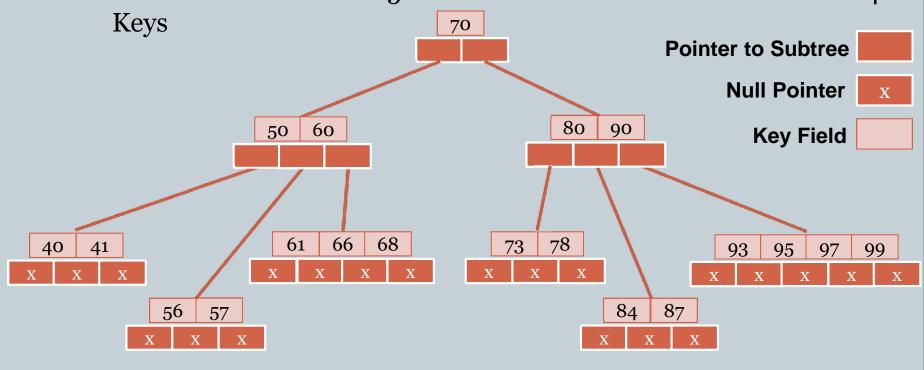


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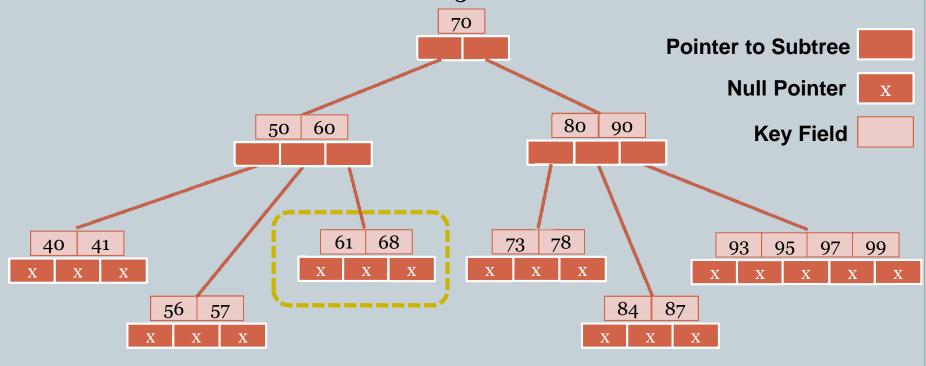
- B-Tree of Order 5
  - o Example:

x Each Node has at most 5 Child Nodes and therefore has at most 4 € Each Node has at most 5 Child Nodes and therefore has at most 4 € Each Node has at most 5 Child Nodes and therefore has at most 4 € Each Node has at most 5 Child Nodes and therefore has at most 4 € Each Node has at most 5 Child Nodes and therefore has at most 4 € Each Node has at most 5 Child Nodes and therefore has at most 4 € Each Node has at most 5 Child Node has at most 4 € Each Node has at most 5 Child Node has at most 4 € Each Node has at most 5 Child Node has at most 4 € Each Node has at most 5 Child Node has at most 4 € Each Node has

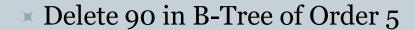


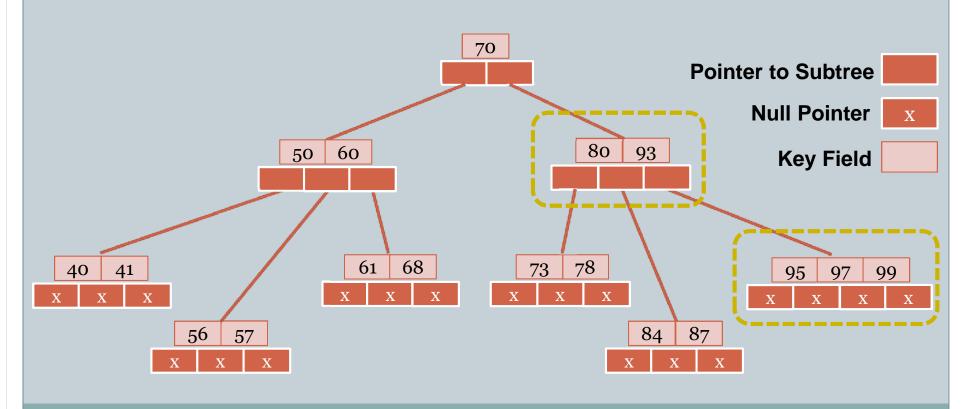
# Deletion in B-Tree

- Deletion in B-Tree
  - Example:
    - ➤ Delete 66 in B-Tree of Order 5

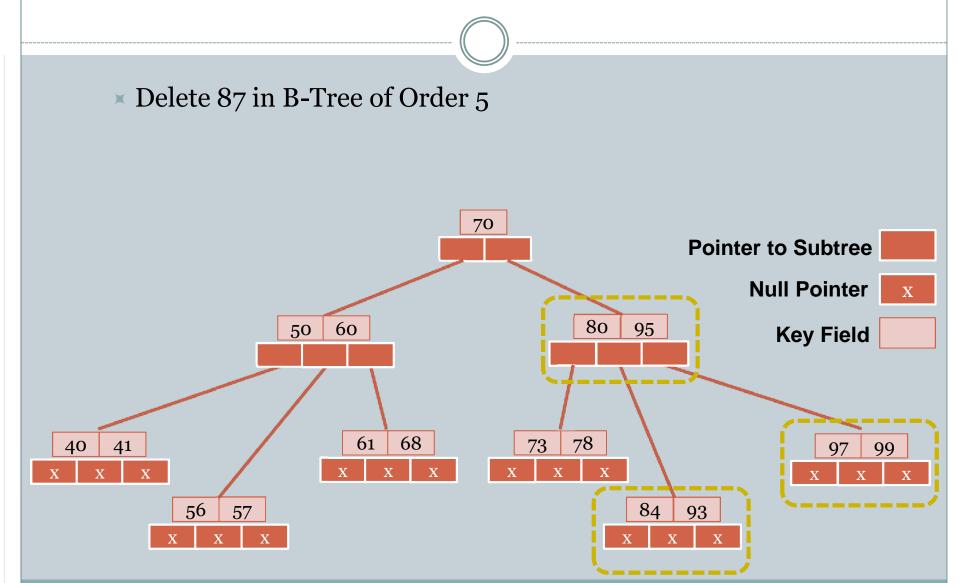


# Deletion in B-Tree









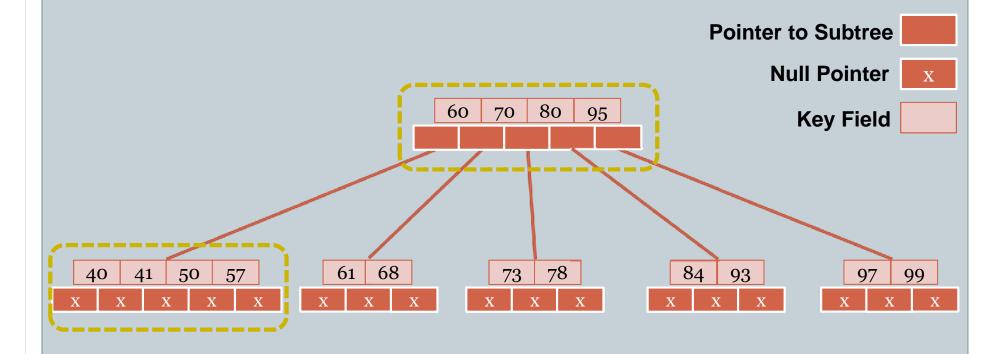
ANKIT VERMA

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# Deletion in B-Tree

× Delete 56 in B-Tree of Order 5



09-04-2016 ANKIT VERMA

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# THANKYOU



PRESENTATION BY:
ANKIT VERMA
(IT DEPARTMENT)

**ANKIT VERMA** 

ASST. PROFESSOR