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<u>ID:</u> 1001656408

EE5353 NEURAL NETWORKS and DEEP LEARNING

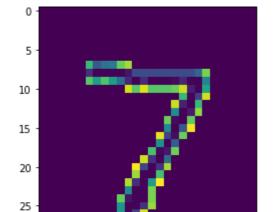
ASSIGNMENT 6:

CONVOLUTIONAL NEURAL NETS using KERAS using GOOGLE COLAB

```
#reference https://towardsdatascience.com/building-a-convolutional-neural-network-
cnn-in-k
   # reference https://elitedatascience.com/keras-tutorial-deep-learning-in-python
   from keras.datasets
   import mnist import
   matplotlib.pyplot as
   plt
   from keras.utils import
   to_categorical from
   keras.models import
   Sequential
   from keras.layers import Dense, Conv2D, Flatten,
   MaxPooling2D, Dropout import numpy as np
   def gen_image(arr):
       two_d = (np.reshape(arr, (28, 28)) * 255).astype(np.uint8)
       plt.imshow(two_d, interpolation='nearest')
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       t
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       n
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       t
   #download mnist data and split into train and test sets
   (X_train, y_train), (X_test, y_test) = mnist.load_data()
   #check image shape
   X_train[0].shape
   #normalization values between 0 and 1
   #X_train = X_train / 255
   \#X_{\text{test}} = X_{\text{test}} / 255
   #reshape data to fit model
   X train =
   X_train.reshape(60000,28,28,1)
   X_{test} =
   X_test.reshape(10000,28,28,1)
   #one-hot encode target column which is equal to generate_t in
   program 5 y_train = to_categorical(y_train)
   y_test = to_categorical(y_test)
   y_train[0]
```

```
model = Sequential()
#add model layers
model.add(Conv2D(64, kernel_size=3, activation='relu', input_shape=(28,28,1)))
        # 64 are the number of filters, kernel size is the size of the filters
        example 3*3
#model.add(Conv2D(32, kernel_size=3, activation='relu'))
#model.add(MaxPooling2D(pool_si
ze=(2,2)))
model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))
# 8. Compile model
model.compile(loss='categorical_cros
sentropy',
              optimizer=
 С→
              'adam',
              metrics=['
              accuracy']1
# 9. Fit model on training data
model.fit(X_train, y_train,
          batch_size=32, nb_epoch=10, verbose=1) #epochs = iterations(Nit)
# 10. Evaluate model on test data
score = model.evaluate(X_test, y_test, verbose=1)
print('Testing accuracy - > ',score[1] * 100)
ytested = model.predict_classes(X_test)
for i in range(4):
  gen_image(X_test[i]).show() # printing image vs the predicted image below
  print("The Predicted Testing image is =%s" % (ytested[i]))
```

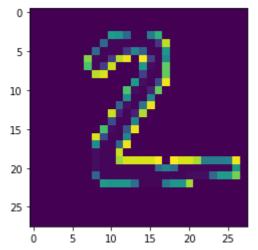
```
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:56: UserWarning: The `nb
Epoch 1/10
60000/60000 [============= ] - 11s 183us/step - loss: 11.9718 - acc:
Epoch 2/10
60000/60000 [============= ] - 11s 176us/step - loss: 8.7755 - acc: 0
Epoch 3/10
Epoch 4/10
60000/60000 [============= ] - 11s 178us/step - loss: 5.8809 - acc: 0
Epoch 5/10
60000/60000 [============= ] - 11s 176us/step - loss: 5.6240 - acc: 0
Epoch 6/10
60000/60000 [============= ] - 11s 178us/step - loss: 5.3556 - acc: 0
Epoch 7/10
60000/60000 [============= ] - 11s 183us/step - loss: 5.2619 - acc: 0
Epoch 8/10
60000/60000 [============== ] - 11s 176us/step - loss: 5.2982 - acc: 0
Epoch 9/10
60000/60000 [============ ] - 11s 177us/step - loss: 5.0499 - acc: 0
Epoch 10/10
60000/60000 [============== ] - 11s 177us/step - loss: 5.1202 - acc: 0
10000/10000 [========= ] - 1s 59us/step
Testing accuracy - > 73.09
```



The Predicted Testing image is =7

20

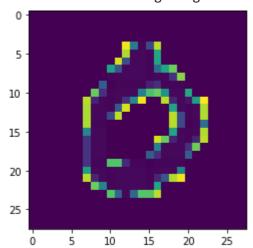
10



The Predicted Testing image is =2



The Predicted Testing image is =1



The Predicted Testing image is =6

3+4

score

6

[0.026925411104456, 0.9924]

score[1] * 100



99.27

3. Import libraries and modules
import numpy as np
np.random.seed(123) # for reproducibility

from keras.lavers import Dense. Drop

from keras.layers import Dense, Dropout, Activation, Flatten

from keras.layers import Convolution2D, MaxPooling2D

from keras.utils import np_utils

from keras.datasets import mnist

4. Load pre-shuffled MNIST data into train and test sets
(X_train, y_train), (X_test, y_test) = mnist.load_data()

5. Preprocess input data

img_rows = X_train.shape[1]

img_cols = X_train.shape[2]

X_train = X_train.reshape(X_train.shape[0], img_cols, img_rows, 1)
X_test = X_test.reshape(X_test.shape[0], img_cols, img_rows, 1)
#X_train = X_train.reshape(X_train.shape[0], 1, 28, 28)

#X_test = X_test.reshape(X_test.shape[0], 1, 28, 28)

```
#X_train = X_train.astype('float32')
#X_test = X_test.astype('float32')
X_train = X_train / 255
X_{\text{test}} = X_{\text{test}} / 255
# 6. Preprocess class labels
Y_train = np_utils.to_categorical(y_train, 10)
Y_test = np_utils.to_categorical(y_test, 10)
# 7. Define model architecture
model = Sequential()
model.add(Convolution2D(32, 3, 3, activation='relu', input_shape=(1,28,28)))
model.add(Convolution2D(32, 3, 3, activation='relu'))
model.add(MaxPooling2D(pool_size=(2,2)))
model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))
# 8. Compile model
model.compile(loss='categorical_crossentropy',
              optimizer='adam',
              metrics=['accuracy'])
# 9. Fit model on training data
model.fit(X_train, Y_train,
          batch_size=32, nb_epoch=10, verbose=1)
# 10. Evaluate model on test data
score = model.evaluate(X_test, Y_test, verbose=0)
```

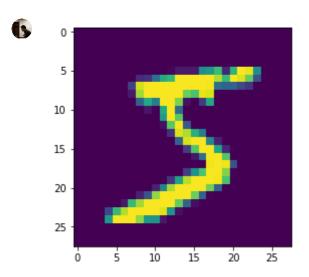
ł

InvalidArgumentError

Traceback (most recent call last)

```
import matplotlib.pyplot as plt
#plot the first image in the dataset
plt.imshow(X_train[0])
#check image shape
X_train[0].shape
```

#reshape data to fit model
X_train = X_train.reshape(60000,28,28,1)
X_test = X_test.reshape(10000,28,28,1)



```
from keras.utils import to_categorical
   #one-hot encode target column
   y_train = to_categorical(y_train)
   y_test = to_categorical(y_test)
   y_train[0]
   #X_train = X_train.reshape(60000,28,28,1)
   #X_test = X_test.reshape(10000,28,28,1)
   #X_train = X_train.reshape((-1, 1, 100, 1))
   from keras.models import Sequential
   from keras.layers import Dense, Conv2D, Flatten
   #create model
   model = Sequential()
   #add model layers
   model.add(Conv2D(64, kernel_size=3, activation='relu', input_shape=(28,28,1)))
   model.add(Conv2D(32, kernel size=3, activation='relu'))
https://colab.research.google.com/drive/1bzwAc4w7yMHmWLj-Nm08kPZQ_REEZW2F#printMode=true
```

```
model.add(Flatten())
model.add(Dense(10, activation='softmax'))

#compile model using accuracy to measure model performance
model.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])

#train the model
model.fit(X_train, y_train, validation_data=(X_test, y_test), epochs=3)

#predict first 4 images in the test set
model.predict(X_test[:4])

#actual results for first 4 images in test set
y_test[:4]
```



WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow_core/python Instructions for updating:

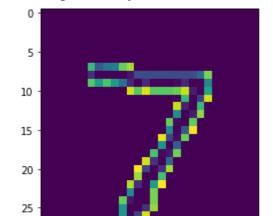
Use tf.where in 2.0, which has the same broadcast rule as np.where Train on 60000 samples, validate on 10000 samples Epoch 1/3

[0., 0., 0., 0., 0., 0., 0., 0., 0., 0.], [0., 1., 0., 0., 0., 0., 0., 0., 0.], [1., 0., 0., 0., 0., 0., 0., 0., 0.]], dtype=float32)

```
#reference https://towardsdatascience.com/building-a-convolutional-neural-
network-cnn-in-k
# reference https://elitedatascience.com/keras-tutorial-deep-learning-in-python
from keras.datasets
import mnist import
matplotlib.pyplot as
plt
from keras.utils import
to_categorical from
keras.models import
Sequential
from keras.layers import Dense, Conv2D, Flatten,
MaxPooling2D, Dropout import numpy as np
def gen_image(arr):
    two_d = (np.reshape(arr, (28, 28)) * 255).astype(np.uint8)
    plt.imshow(two d, interpolation='nearest')
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   t
#download mnist data and split into train and test sets
(X_train, y_train), (X_test, y_test) = mnist.load_data()
#check image shape
X_train[0].shape
#normalization values between 0 and 1
#X train = X train / 255
\#X_{\text{test}} = X_{\text{test}} / 255
#reshape data to fit model
X train =
X_train.reshape(60000,28,28,1)
X test =
X_test.reshape(10000,28,28,1)
#one-hot encode target column which is equal to generate t in
program 5 y_train = to_categorical(y_train)
y_test = to_categorical(y_test)
y_train[0]
```

```
1/6/2000del = Sequential()
                                        Keras_CNN_MNIST.ipynb - Colaboratory
   #add model layers
  model.add(Conv2D(64, kernel_size=3, activation='relu', input_shape=(28,28,1)))
           # 64 are the number of filters, kernel size is the size of the filters
           example 3*3
   #model.add(Conv2D(32, kernel_size=3,
   activation='relu'))
  model.add(MaxPooling2D(pool_size=(2,2)))
  model.add(Dropout(0.25))
  model.add(Flatten())
  model.add(Dense(128, activation='relu'))
  model.add(Dropout(0.5))
  model.add(Dense(10, activation='softmax'))
  # 8. Compile model
  model.compile(loss='categorical_cros
   sentropy',
                 optimizer=
    \Box
                 'adam',
                 metrics=['
                 accuracy']
                 )1
  # 9. Fit model on training data
  model.fit(X_train, y_train,
             batch_size=32, nb_epoch=10, verbose=1) #epochs = iterations(Nit)
  # 10. Evaluate model on test data
   score = model.evaluate(X_test, y_test, verbose=1)
  print('Testing accuracy - > ',score[1] * 100)
  ytested = model.predict_classes(X_test)
  for i in range(4):
     gen_image(X_test[i]).show() # printing image vs the predicted image below
     print("The Predicted Testing image is =%s" % (ytested[i]))
```

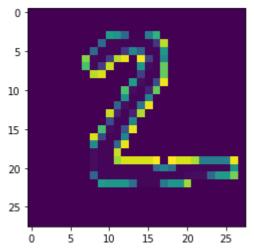
```
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:56: UserWarning: The `nb
Epoch 1/10
60000/60000 [============= ] - 8s 133us/step - loss: 4.2292 - acc: 0.
Epoch 2/10
60000/60000 [============= ] - 8s 126us/step - loss: 0.1996 - acc: 0.
Epoch 3/10
Epoch 4/10
Epoch 5/10
60000/60000 [============== ] - 7s 125us/step - loss: 0.1250 - acc: 0.
Epoch 6/10
60000/60000 [============= ] - 8s 125us/step - loss: 0.1193 - acc: 0.
Epoch 7/10
60000/60000 [============= - 7s 125us/step - loss: 0.1069 - acc: 0.
Epoch 8/10
60000/60000 [============= - 7s 125us/step - loss: 0.1064 - acc: 0.
Epoch 9/10
Epoch 10/10
60000/60000 [============== ] - 8s 132us/step - loss: 0.1028 - acc: 0.
10000/10000 [=========== ] - 1s 56us/step
Testing accuracy - > 98.21
```



The Predicted Testing image is =7

20

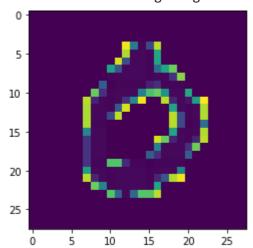
10



The Predicted Testing image is =2



The Predicted Testing image is =1



The Predicted Testing image is =0

3+4

score

6

[0.026925411104456, 0.9924]

score[1] * 100



99.27

3. Import libraries and modules
import numpy as np
np.random.seed(123) # for reproducibility

from keras.models import Sequential
from keras.layers import Dense, Dropout, Activation, Flatten
from keras.layers import Convolution2D, MaxPooling2D
from keras.utils import np_utils
from keras.datasets import mnist

4. Load pre-shuffled MNIST data into train and test sets
(X_train, y_train), (X_test, y_test) = mnist.load_data()

5. Preprocess input data
img_rows = X_train.shape[1]
img_cols = X_train.shape[2]

X_train = X_train.reshape(X_train.shape[0], img_cols, img_rows, 1)
X_test = X_test.reshape(X_test.shape[0], img_cols, img_rows, 1)
#X_train = X_train.reshape(X_train.shape[0], 1, 28, 28)
#X_test = X_test.reshape(X_test.shape[0], 1, 28, 28)

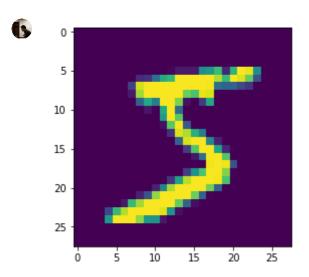
```
#X_train = X_train.astype('float32')
#X_test = X_test.astype('float32')
X_train = X_train / 255
X_{\text{test}} = X_{\text{test}} / 255
# 6. Preprocess class labels
Y_train = np_utils.to_categorical(y_train, 10)
Y_test = np_utils.to_categorical(y_test, 10)
# 7. Define model architecture
model = Sequential()
model.add(Convolution2D(32, 3, 3, activation='relu', input_shape=(1,28,28)))
model.add(Convolution2D(32, 3, 3, activation='relu'))
model.add(MaxPooling2D(pool_size=(2,2)))
model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))
# 8. Compile model
model.compile(loss='categorical_crossentropy',
              optimizer='adam',
              metrics=['accuracy'])
# 9. Fit model on training data
model.fit(X_train, Y_train,
          batch_size=32, nb_epoch=10, verbose=1)
# 10. Evaluate model on test data
score = model.evaluate(X_test, Y_test, verbose=0)
```

InvalidArgumentError

Traceback (most recent call last)

```
import matplotlib.pyplot as plt
#plot the first image in the dataset
plt.imshow(X_train[0])
#check image shape
X_train[0].shape
```

#reshape data to fit model
X_train = X_train.reshape(60000,28,28,1)
X_test = X_test.reshape(10000,28,28,1)



```
from keras.utils import to_categorical
   #one-hot encode target column
   y_train = to_categorical(y_train)
   y_test = to_categorical(y_test)
   y_train[0]
   #X_train = X_train.reshape(60000,28,28,1)
   #X_test = X_test.reshape(10000,28,28,1)
   #X_train = X_train.reshape((-1, 1, 100, 1))
   from keras.models import Sequential
   from keras.layers import Dense, Conv2D, Flatten
   #create model
   model = Sequential()
   #add model layers
   model.add(Conv2D(64, kernel_size=3, activation='relu', input_shape=(28,28,1)))
   model.add(Conv2D(32, kernel size=3, activation='relu'))
https://colab.research.google.com/drive/1bzwAc4w7yMHmWLj-Nm08kPZQ_REEZW2F#printMode=true
```

Epoch 3/3

```
model.add(Flatten())
model.add(Dense(10, activation='softmax'))
#compile model using accuracy to measure model performance
model.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
#train the model
model.fit(X_train, y_train, validation_data=(X_test, y_test), epochs=3)
#predict first 4 images in the test set
model.predict(X_test[:4])
#actual results for first 4 images in test set
y_test[:4]
    WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow_core/python
    Instructions for updating:
    Use tf.where in 2.0, which has the same broadcast rule as np.where
    Train on 60000 samples, validate on 10000 samples
    Epoch 1/3
    60000/60000 [============= ] - 25s 423us/step - loss: 9.5803 - acc: 0
    Epoch 2/3
    60000/60000 [============= ] - 18s 303us/step - loss: 7.7504 - acc: 0
```

60000/60000 [=============] - 18s 304us/step - loss: 7.5434 - acc: 0

array([[0., 0., 0., 0., 0., 0., 1., 0., 0.],

[0., 0., 1., 0., 0., 0., 0., 0., 0., 0.], [0., 1., 0., 0., 0., 0., 0., 0., 0., 0.],

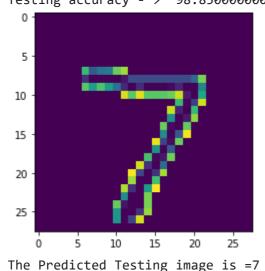
[1., 0., 0., 0., 0., 0., 0., 0., 0.]], dtype=float32)

```
#reference https://towardsdatascience.com/building-a-convolutional-neural-
network-cnn-in-k
# reference https://elitedatascience.com/keras-tutorial-deep-learning-in-python
from keras.datasets
import mnist import
matplotlib.pyplot as
plt
from keras.utils import
to_categorical from
keras.models import
Sequential
from keras.layers import Dense, Conv2D, Flatten,
MaxPooling2D, Dropout import numpy as np
def gen_image(arr):
    two_d = (np.reshape(arr, (28, 28)) * 255).astype(np.uint8)
    plt.imshow(two_d, interpolation='nearest')
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   t
#download mnist data and split into train and test sets
(X_train, y_train), (X_test, y_test) = mnist.load_data()
#check image shape
X train[0].shape
#normalization values between 0 and 1
#X_train = X_train / 255
\#X_{\text{test}} = X_{\text{test}} / 255
#reshape data to fit model
X_train =
X_train.reshape(60000,28,28,1)
X test =
X_test.reshape(10000,28,28,1)
#one-hot encode target column which is equal to generate_t in
program 5 y_train = to_categorical(y_train)
y_test = to_categorical(y_test)
y_train[0]
#create model
```

model = Sequential()

```
#add model layers
model.add(Conv2D(64, kernel_size=3, activation='relu', input_shape=(28,28,1)))
        # 64 are the number of filters, kernel size is the size of the filters
example 3*3 model.add(Conv2D(32, kernel_size=3, activation='relu'))
model.add(MaxPooling2D(pool_size=(2,2)))
model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))
# 8. Compile model
model.compile(loss='categorical_cros
sentropy',
              optimizer=
              'adam',
              metrics=['
              accuracy']
 \Box
              )1
# 9. Fit model on training data
model.fit(X_train, y_train,
          batch_size=32, nb_epoch=10, verbose=1) #epochs = iterations(Nit)
# 10. Evaluate model on test data
score = model.evaluate(X_test, y_test, verbose=1)
print('Testing accuracy - > ',score[1] * 100)
ytested = model.predict_classes(X_test)
for i in range(4):
  gen_image(X_test[i]).show() # printing image vs the predicted image below
  print("The Predicted Testing image is =%s" % (ytested[i]))
```

```
WARNING:tensorflow:From
                      /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From
                      /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From
                      /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
60000/60000 [============== ] - 28s 460us/step - loss: 2.9217 - acc: 0
Epoch 2/10
60000/60000 [============== ] - 20s 335us/step - loss: 0.1529 - acc: 0
Epoch 3/10
60000/60000 [============= ] - 20s 331us/step - loss: 0.1185 - acc: 0
Epoch 4/10
60000/60000 [=============== ] - 20s 329us/step - loss: 0.1000 - acc: 0
Epoch 5/10
60000/60000 [============== ] - 20s 330us/step - loss: 0.0890 - acc: 0
Epoch 6/10
60000/60000 [============== ] - 20s 329us/step - loss: 0.0820 - acc: 0
Epoch 7/10
60000/60000 [============== ] - 20s 330us/step - loss: 0.0753 - acc: 0
Epoch 8/10
60000/60000 [============= ] - 20s 329us/step - loss: 0.0715 - acc: 0
Epoch 9/10
60000/60000 [============== ] - 20s 328us/step - loss: 0.0681 - acc: 0
Epoch 10/10
60000/60000 [============== ] - 20s 332us/step - loss: 0.0638 - acc: 0
10000/10000 [========== ] - 1s 107us/step
Testing accuracy - > 98.85000000000001
```



5 -10 -15 -20 -

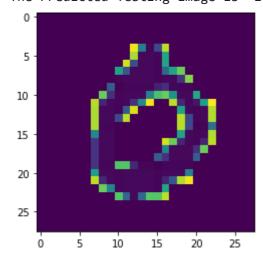
The Predicted Testing image is =2

20

25

10

The Predicted Testing image is =1



The Predicted Testing image is =0

```
3+4
score
1
score[1] * 100
1
# 3. Import libraries and modules
import numpy as np
np.random.seed(123) # for reproducibility
from keras.models import Sequential
from keras.layers import Dense, Dropout, Activation, Flatten
from keras.layers import Convolution2D, MaxPooling2D
from keras.utils import np_utils
from keras.datasets import mnist
# 4. Load pre-shuffled MNIST data into train and test sets
(X_train, y_train), (X_test, y_test) = mnist.load_data()
# 5. Preprocess input data
img_rows = X_train.shape[1]
img_cols = X_train.shape[2]
X_train = X_train.reshape(X_train.shape[0], img_cols, img_rows, 1)
X test = X test.reshape(X test.shape[0], img cols, img rows, 1)
#X_train = X_train.reshape(X_train.shape[0], 1, 28, 28)
\#X_{\text{test}} = X_{\text{test.reshape}}(X_{\text{test.shape}}[0], 1, 28, 28)
#X_train = X_train.astype('float32')
#X_test = X_test.astype('float32')
X_{train} = X_{train} / 255
X_{\text{test}} = X_{\text{test}} / 255
# 6. Preprocess class labels
Y_train = np_utils.to_categorical(y_train, 10)
Y_test = np_utils.to_categorical(y_test, 10)
# 7. Define model architecture
model = Sequential()
model.add(Convolution2D(32, 3, 3, activation='relu', input_shape=(1,28,28)))
model.add(Convolution2D(32, 3, 3, activation='relu'))
model.add(MaxPooling2D(pool_size=(2,2)))
model.add(Dropout(0.25))
```

```
import matplotlib.pyplot as plt
#plot the first image in the dataset
plt.imshow(X_train[0])
#check image shape
X_train[0].shape

#reshape data to fit model
X_train = X_train.reshape(60000,28,28,1)
X_test = X_test.reshape(10000,28,28,1)
```



```
from keras.utils import to_categorical
#one-hot encode target column
y_train = to_categorical(y_train)
y_test = to_categorical(y_test)
y_train[0]
#X_train = X_train.reshape(60000,28,28,1)
#X test = X test.reshape(10000,28,28,1)
#X_train = X_train.reshape((-1, 1, 100, 1))
from keras.models import Sequential
from keras.layers import Dense, Conv2D, Flatten
#create model
model = Sequential()
#add model layers
model.add(Conv2D(64, kernel_size=3, activation='relu', input_shape=(28,28,1)))
model.add(Conv2D(32, kernel_size=3, activation='relu'))
model.add(Flatten())
model.add(Dense(10, activation='softmax'))
#compile model using accuracy to measure model performance
model.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
#train the model
model.fit(X_train, y_train, validation_data=(X_test, y_test), epochs=3)
#predict first 4 images in the test set
model.predict(X_test[:4])
#actual results for first 4 images in test set
y_test[:4]
```

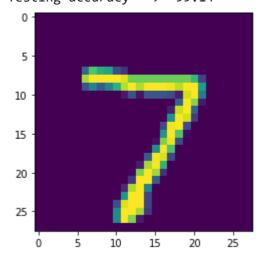
```
#reference https://towardsdatascience.com/building-a-convolutional-neural-
network-cnn-in-k
# reference https://elitedatascience.com/keras-tutorial-deep-learning-in-python
from keras.datasets
import mnist import
matplotlib.pyplot as
plt
from keras.utils import
to categorical from
keras.models import
Sequential
from keras.layers import Dense, Conv2D, Flatten,
MaxPooling2D, Dropout import numpy as np
def gen image(arr):
    two_d = (np.reshape(arr, (28, 28)) * 255).astype(np.uint8)
    plt.imshow(two d, interpolation='nearest')
   e
   t
   р
   1
   t
#download mnist data and split into train and test sets
(X_train, y_train), (X_test, y_test) = mnist.load_data()
#check image shape
X_train[0].shape
#normalization values between 0 and 1
X train = X train / 255
X_{\text{test}} = X_{\text{test}} / 255
#reshape data to fit model
X train =
X_train.reshape(60000,28,28,1)
X test =
X_test.reshape(10000,28,28,1)
#one-hot encode target column which is equal to generate t in
program 5 y train = to categorical(y train)
y_test = to_categorical(y_test)
y train[0]
```

```
model = Sequential()
#add model layers
model.add(Conv2D(64, kernel_size=3, activation='relu', input_shape=(28,28,1)))
        # 64 are the number of filters, kernel size is the size of the filters
example 3*3 model.add(Conv2D(32, kernel_size=3, activation='relu'))
model.add(MaxPooling2D(pool_size=(2,2)))
model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(10, activation='softmax'))
# 8. Compile model
model.compile(loss='categorical_cros
sentropy',
              optimizer='adam',1
              metrics=['accuracy'])
 Г⇒
# 9. Fit model on training data
model.fit(X_train, y_train,
          batch_size=32, nb_epoch=10, verbose=1) #epochs = iterations(Nit)
# 10. Evaluate model on test data
score = model.evaluate(X_test, y_test, verbose=1)
print('Testing accuracy - > ',score[1] * 100)
ytested = model.predict_classes(X_test)
for i in range(4):
  gen_image(X_test[i]).show() # printing image vs the predicted image below
  print("The Predicted Testing image is =%s" % (ytested[i]))
```

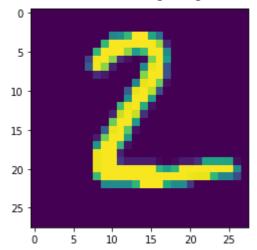
Using TensorFlow backend.

```
The default version of TensorFlow in Colab will soon switch to TensorFlow 2.x. We recommend you <u>upgrade</u> now or ensure your notebook will continue to use TensorFlow 1.x via the %tensorflow_version 1.x magic: <u>more info</u>.
```

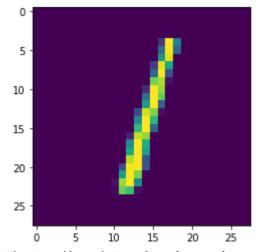
```
Downloading data from <a href="https://s3.amazonaws.com/img-datasets/mnist.npz">https://s3.amazonaws.com/img-datasets/mnist.npz</a>
WARNING:tensorflow:From
                        /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From
                        /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From
                        /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
                        /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
Instructions for updating:
Please use `rate` instead of `keep prob`. Rate should be set to `rate = 1 - keep prob
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/optimizers.py:79
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow_core/python
Instructions for updating:
Use tf.where in 2.0, which has the same broadcast rule as np.where
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:57: UserWarning: The `nb
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From
                        /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
Epoch 1/10
WARNING:tensorflow:From
                        /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From
                        /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From
                        /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From
                        /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorfl
60000/60000 [============= ] - 28s 468us/step - loss: 0.2044 - acc: 0
Epoch 2/10
60000/60000 [============= ] - 21s 348us/step - loss: 0.0837 - acc: 0
Epoch 3/10
60000/60000 [============== ] - 21s 345us/step - loss: 0.0651 - acc: 0
Epoch 4/10
60000/60000 [============== ] - 21s 348us/step - loss: 0.0550 - acc: 0
Epoch 5/10
60000/60000 [============= ] - 21s 346us/step - loss: 0.0472 - acc: 0
Epoch 6/10
60000/60000 [============== ] - 21s 350us/step - loss: 0.0420 - acc: 0
Epoch 7/10
60000/60000 [============== ] - 21s 352us/step - loss: 0.0379 - acc: 0
Epoch 8/10
60000/60000 [============== ] - 21s 350us/step - loss: 0.0336 - acc: 0
Epoch 9/10
```



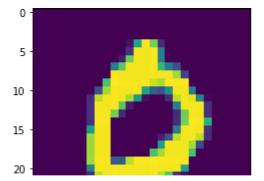
The Predicted Testing image is =7



The Predicted Testing image is =2



The Predicted Testing image is =1



```
The Predicted Testing image is =0
3+4
score
1
score[1] * 100
1
# 3. Import libraries and modules
import numpy as np
np.random.seed(123) # for reproducibility
from keras.models import Sequential
from keras.layers import Dense, Dropout, Activation, Flatten
from keras.layers import Convolution2D, MaxPooling2D
from keras.utils import np utils
from keras.datasets import mnist
# 4. Load pre-shuffled MNIST data into train and test sets
(X_train, y_train), (X_test, y_test) = mnist.load_data()
# 5. Preprocess input data
img_rows = X_train.shape[1]
img_cols = X_train.shape[2]
X_train = X_train.reshape(X_train.shape[0], img_cols, img_rows, 1)
X_test = X_test.reshape(X_test.shape[0], img_cols, img_rows, 1)
#X_train = X_train.reshape(X_train.shape[0], 1, 28, 28)
#X_test = X_test.reshape(X_test.shape[0], 1, 28, 28)
#X_train = X_train.astype('float32')
#X_test = X_test.astype('float32')
X_{train} = X_{train} / 255
X_{\text{test}} = X_{\text{test}} / 255
# 6. Preprocess class labels
Y_train = np_utils.to_categorical(y_train, 10)
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# 7. Define model architecture
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model.add(Convolution2D(32, 3, 3, activation='relu'))
model.add(MaxPooling2D(pool_size=(2,2)))
model.add(Dropout(0.25))
```



```
import matplotlib.pyplot as plt
#plot the first image in the dataset
plt.imshow(X_train[0])
#check image shape
X_train[0].shape

#reshape data to fit model
X_train = X_train.reshape(60000,28,28,1)
X_test = X_test.reshape(10000,28,28,1)
```



```
from keras.utils import to_categorical
#one-hot encode target column
y_train = to_categorical(y_train)
y_test = to_categorical(y_test)
y_train[0]
#X_train = X_train.reshape(60000,28,28,1)
#X test = X test.reshape(10000,28,28,1)
#X_train = X_train.reshape((-1, 1, 100, 1))
from keras.models import Sequential
from keras.layers import Dense, Conv2D, Flatten
#create model
model = Sequential()
#add model layers
model.add(Conv2D(64, kernel_size=3, activation='relu', input_shape=(28,28,1)))
model.add(Conv2D(32, kernel_size=3, activation='relu'))
model.add(Flatten())
model.add(Dense(10, activation='softmax'))
#compile model using accuracy to measure model performance
model.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
#train the model
model.fit(X_train, y_train, validation_data=(X_test, y_test), epochs=3)
#predict first 4 images in the test set
model.predict(X_test[:4])
```

#actual results for first 4 images in test set y_test[:4]

CONCLUSION:

- A Convolutional Neural Net is an algorithm which takes input in the form of image and some properties of the image will be considered to differentiate each other. In older methods the filters are made with information present in the image by various algorithms and training, but with help of ConvNets it is possible to learn the filter characteristics.
- The architecture of the ConvNets is similar to that of neurons in the human brain, so when we consider an image it will be in matrix form of pixel values. So, when we go with a feed forward network it vectorizes the matrix and makes it into a single column, so it has to map the pixel adjacent to it to create a relation. When it reaches to the last pixel it will map its next pixel in the next row, so when that happens there is chance of the error to be high.
- When we use ConvNets it will be matrix form and it will create a relation between the pixels around the current pixel instead of just creating a relation to the adjacent pixels. So that's why ConvNets will be able to capture the Spatial and Temporal dependencies. This will increase the accuracy of the image and the error probability will be less. So hence we go for ConvNets instead of Feed Forward Network. Since the ConvNets is able to learn these features it will be easier to process the image without losing any critical parameters.
- The top layer of the CNN is the convolutional layer. This layer is responsible for obtaining the good edges for the image and the lower layer is implemented to find the other parameters like color, orientation and the ConvNets will be able to adapt to these features. The Convolutional layer has a part called the Kernel.
- The Kernel uses a filter which moves based on the stride value until it parses the entire image (I,e) the filter parses entire matrix by moving right and hops down to left to parse the next=t matrix. This is done until the entire image is traversed.
- When image has multiple channels, the Kernel uses the same depth as that of the input and the multiplication is done b/w the filters which parses the matrix and the results are summed up to provide a convoluted output.
- To do this kind of Operation there is two methods,

Valid Padding

Same Padding

- Same padding will have a dimension of the input after convolving it with the kernel and the Valid padding will have a dimension as that of the kernel.
- The next layer is the Pooling layer, in this layer the spatial size of the image is reduced. This is done in order to conserve power required to process the data. Moreover, it useful in extracting the dominant features of the position of the image model.
- There are two types of pooling: Max pooling and Average Pooling.
- Max pooling, as the name suggest it used to find the max value of image, means to find the mas pixel value of a portion of the image and Average pooling is used to find the average pixel value of the same portion of the image. Since max pooling gives max value, we can suppress the noise and the average pooling reduction in the dimension of the image.

- The noises are noting but the randomly selected neurons during the regularization process and these neurons are dropped out.
- The next layer is the fully connected neural network layer. The fully connected neural network uses a ReLU activation function. The activation function is just like additional weight provided to the layers, it is just like some energy which is used to fire the neurons in our brain.
- The Feed Forward Network uses the sigmoid function. The purpose and function of a sigmoid function is same as that of the ReLU function but the Sigmoid is a slower process, whereas the ReLU is a fast process. This is also another reason to use CNN over Feed Forward Network.
- The reason for using activation function (i,e) ReLU is provide non linearities because when a nonlinear function is implemented the Neural nets will be able to provide a better approximation of result.
- Once a fully connected layer is provided with an activation function, high level features are obtained at the output. So, the ConvNets will be able to learn that nonlinear function is the space.
- By the means of SoftMax technique we can increase the accuracy of the image. This is possible when a converted image is processed by MLP and fed to Feed Forward Network and back propagation is applied to every iteration.
- We can see that the accuracy increases for each task as we add convolution, activation function and training it with back propagation.