```
#include "opencv2/highgui/highgui.hpp"
#include <fstream>
#include <iostream>
#include<stdio.h>
#include<Windows.h>
#include"timer.h"
using namespace cv;
using namespace std;
int w, h,lmt=50,lmt2=100,*fBgk,xT=0,yT=0,*mat,*matCmp,*matDet,touch=0;
float speed = 0,f=1,density=0;
bool fDetected = false, calib = false, l_Click = false,
r_Click=false,d_Click=false,drag=false,scroll=false,allowedC = false, allowedRC = false;
timer cntrl_1,cntrl_2;
Mat frameC,frameTmp;
POINT cP1, cP2;
struct bigPt
{
      double x = 0, y = 0;
}p1,p2;
float mod(float x)
{
      if (x > 0)
            return x;
     else return -x;
}
void circle(Mat frame, int x, int y, float rad, int r = 150, int g = 0, int b = 0)
      for (float agl = 0; agl \leftarrow (2 * 22) / 7.0; agl \leftarrow 0.01)
      {
            Vec3b p;
            p.val[0] = b;
            p.val[1] = g;
            p.val[2] = r;
            int xC = x + rad*sin(agl), yC = y + rad*cos(agl);
            if (xC>0 && xC<w&&yC>0 && yC<h)
                  frame.at<Vec3b>(Point(xC, yC)) = p;
```

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}
float distnc(bigPt pt1, bigPt pt2)
{
     return sqrt((pt1.x - pt2.x)*(pt1.x - pt2.x) + (pt1.y - pt2.y)*(pt1.y - pt2.y));
}
void line(Mat frame, float x1, float y1, float x2, float y2, int r = 0, int g = 200, int b = 0)
{
     Vec3b p;
     p.val[0] = b;
     p.val[1] = g;
     p.val[2] = r;
     if (x1 == x2)
     {
            for (int i = y1; i != y2&&i>0 && i<h&&x1>0 && x1<w; (y1<y2 ? i++ : i--))
                  frame.at<Vec3b>(Point(x1, i)) = p;
     }
     else
     {
            float slope = (y1 - y2) / (x1 - x2);
            float intcpt = y2 - slope*x2;
            if (mod(slope)<1)</pre>
                  for (float i = x1; i != x2&&i>0 &&i< w; (x1 < x2 ? i++ : i--))
                  {
                        int j = slope*i + intcpt;
                        if (i>0 && i < w&& j>0 && j < h)
                              frame.at<Vec3b>(Point(i, j)) = p;
                  }
            else
                  for (float i = y1; i != y2&&i>0 && i<h; (y1 < y2 ? i++ : i--))
                  {
                        int j = (i - intcpt) / slope;
                        if (i>0 && i < w&&j>0 && j < h)
                              frame.at<Vec3b>(Point(j, i)) = p;
                  }
     }
void rect(Mat frame, int x1, int y1, int 1nth, int x1, int x1 = 255, int x1 = 0, int x1
{
     Vec3b p;
     p.val[0] = b;
     p.val[1] = g;
```

```
p.val[2] = r;
      for (int i = 0; i < lnth || i < brth; i++)</pre>
      {
            if (i < lnth&&i + x1<w&&i + x1>0)
            {
                  if (y1>0 && y1<h)
                        frame.at<Vec3b>(Point(i + x1, y1)) = p;
                  if (y1 + brth<h&y1 + brth>0)
                         frame.at<Vec3b>(Point(i + x1, y1 + brth)) = p;
            }
            if (i < brth&&i + y1 < h&&i + y1 > 0)
                  if (x1>0 && x1<w)
                         frame.at<Vec3b>(Point(x1, y1 + i)) = p;
                  if (x1 + lnth < w&x1 + lnth > 0)
                         frame.at<Vec3b>(Point(x1 + lnth, y1 + i)) = p;
            }
     }
void compControl()
     POINT p;
     GetCursorPos(&p);
      if (fDetected&&cntrl_1.elapsed()>50)
      {
            if (distnc(p1, p2) > 2)
            {
                  if (distnc(p1, p2) < 10)
                        f = 2;
                  else if (distnc(p1, p2) < 20)
                         f = 2.5;
                  else
                        f = 3.5;
            }
            else
                  f = 0;
            float xDif = p1.x - p2.x, yDif = p1.y - p2.y;
            if (mod(xDif) < 50 \&\& mod(yDif) < 50)
            {
                  xDif *= -f;
                  yDif *= f;
            }
            else
                  xDif = yDif = 0;
```

}

{

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int xNew = p.x + xDif, yNew = p.y + yDif * 2;
            if (xNew > 0 && yNew > 0 && yNew < 1080 && xNew < 1920 &&
xDif&&!scroll&&(drag?cntrl_1.elapsed()>200:1))
                  SetCursorPos(xNew, yNew);
            p2 = p1;
     }
     if (l_Click&&cntrl_1.elapsed()>200&&!r_Click)
      {
            l_Click = false;
            d_Click = false;
            INPUT input = { 0 };
            input.type = INPUT_MOUSE;
            input.mi.dwFlags = MOUSEEVENTF_LEFTDOWN;
            ::SendInput(1, &input, sizeof(INPUT));
            ::ZeroMemory(&input, sizeof(INPUT)); // why zeroMemory? removing this code changes
nothing that i can tell
            input.type = INPUT_MOUSE; // why reset this variable? is it not already set?
            input.mi.dwFlags = MOUSEEVENTF_LEFTUP;
            ::SendInput(1, &input, sizeof(INPUT));
     }
     else if (d_Click&&cntrl_1.elapsed() > 200&&!drag)
     {
            d_Click = false;
            for (int i = 0; i < 2; i++)
            {
                  l_Click = false;
                  INPUT input = { 0 };
                  input.type = INPUT_MOUSE;
                  input.mi.dwFlags = MOUSEEVENTF_LEFTDOWN;
                  ::SendInput(1, &input, sizeof(INPUT));
                  ::ZeroMemory(&input, sizeof(INPUT)); // why zeroMemory? removing this code changes
nothing that i can tell
                  input.type = INPUT_MOUSE; // why reset this variable? is it not already set?
                  input.mi.dwFlags = MOUSEEVENTF_LEFTUP;
                  ::SendInput(1, &input, sizeof(INPUT));
            }
     }
     else if (r_Click)
      {
            r_Click = false;
            INPUT input = { 0 };
            input.type = INPUT_MOUSE;
            input.mi.dwFlags = MOUSEEVENTF_RIGHTDOWN;
            ::SendInput(1, &input, sizeof(INPUT));
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::ZeroMemory(&input, sizeof(INPUT)); // why zeroMemory? removing this code changes
nothing that i can tell
            input.type = INPUT_MOUSE; // why reset this variable? is it not already set?
            input.mi.dwFlags = MOUSEEVENTF_RIGHTUP;
            ::SendInput(1, &input, sizeof(INPUT));
     }
}
int main(int argc, char* argv[])
{
      bool access = false, access2 = false;
      int camNo = 0;
      cvNamedWindow("Output", CV_WINDOW_AUTOSIZE);
      if (!access)
      {
            system("cls");
            int no_of_cam = -1;
            VideoCapture cap(0);
            int i;
            for (i = 0; cap.open(i)\&\&i<9; i++);
            cout << "
                              SELECT THE CAM\n\n";
            if (i > 1)
            {
                  cout << i << " cams are detected. You are required to choose the one inside the
touch pad. Look in the webcam feed window.";
                  cout << "\nYou can change the cam using the left and right arrow keys. When you</pre>
select the right cam press enter.";
                  cout << "(Before this please click on the cam window)";</pre>
                  while (!access)
                  {
                         int keyIn = waitKey(1);
                         static int tmp=-1;
                         if (keyIn == 2424832 && camNo > 0)
                               camNo--;
                         if (\text{keyIn} == 2555904 \&\& camNo < 9 \&\& camNo < i-1)
                               camNo++;
                         if (tmp!=camNo)
                         cap.open(camNo);
                         tmp = camNo;
                        Mat frame;
                        cap >> frame;
                         imshow("Output", frame);
                         if (keyIn == 13)
                               access = true;
                  }
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}
}
VideoCapture cap(camNo); // open the video camera no. 0
w = cap.get(CV_CAP_PROP_FRAME_WIDTH); //get the width of frames of the video
h = cap.get(CV_CAP_PROP_FRAME_HEIGHT); //get the height of frames of the video
timer t1;
t1.start();
fBgk = new int[w*h];
memset(fBgk, 0, sizeof(int)*w*h);
cntrl_1.start();
cntrl_2.start();
mat = new int[w*h];
matCmp = new int[w*h];
matDet = new int[w*h];
memset(mat, 0, sizeof(int)*w*h);
memset(matCmp, 0, sizeof(int)*w*h);
memset(matDet, 0, sizeof(int)*w*h);
system("cls");
cout << "Wait till the cam is calibrated";</pre>
while (1)
{
      memset(matDet, 0, sizeof(int)*w*h);
      Mat frame;
      double nPix = 0;
      cap >> frame;
      for (int i = 1; i < w; i++)
            for (int j = 1; j < h; j++)
            {
                  Vec3b p = frame.at<Vec3b>(Point(i, j));
                  mat[i+j*w]=p.val[0] = p.val[1] = p.val[2] = (p.val[0] + p.val[1] + p.val[2])
                  frame.at<Vec3b>(Point(i, j)) = p;
            }
      frameC = frame.clone();
      if (t1.elapsed()>3000) //Uses to identify the outof view region
      {
            if (t1.elapsed() > 3500)
            {
                  t1.stop();
                  calib = true;
                  memcpy(matCmp, mat, sizeof(int)*w*h);
                  system("cls");
                  cout << "R E A D Y - C A L I B E R A T E D\n\n";
                  cout << "CONTROLS:\n";</pre>
                  cout << "Move Finger: To Move Cursor\n";</pre>
```

/ 3;

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cout << "Left Single Click: Tap for once\n";</pre>
                         cout << "Left Double Click: Double Tap\n";</pre>
                         cout << "Right click: Tap twice and hold the finger down\n";</pre>
                         cout << "Left click and drag: Tap thrice and hold finger down\n";</pre>
                         cout << "\n\n\nYou can change the threshold of finger detection using '+'</pre>
and '-' keys\n";
                         cout << "\n\nTo exit press 'ESC'";</pre>
                   }
                   for (int i = 1; i < w; i++)
                         for (int j = 1; j < h; j++)
                                if (mat[i+j*w] < lmt)</pre>
                                      fBgk[i + j*w] = 1;
            }
            //To color the detected hand region
            for (int j = 1; j < h&&calib; j++)</pre>
                   for (int i = 1; i < w; i++)
                   {
                         Vec3b p = frame.at<Vec3b>(Point(i, j));
                         int lmtT=matCmp[i+j*w]/255.0*lmt;
                         if (fBgk[i + j*w] != 1 && mat[i + j*w] < lmtT)</pre>
                         {
                                p.val[1] = 200;
                                matDet[i + j*w]=1;
                         }
                         else
                                matDet[i + j*w]=0;
                         frame.at<Vec3b>(Point(i, j)) = p;
                   }
            //To indentify the forward most set of pixels
            bool cont = true, det = false,detected=false;
            for (int j = 1; j < h&&cont&&calib; j++)</pre>
                   for (int i = 1; i < w&&cont; i++)</pre>
                   {
                         if (matDet[i+j*w] ==1)
                         {
                                detected = false;
                                nPix = 0;
                                p1.x = p1.y = 0;
                                int s = 60;
                                float area = 0,blank=0;
                                for (int l = 0; l <= s; l++) //To find the mid of the finger tip
                                {
                                      int a=-1, b=100;
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```
for (int k = -s / 2; k \le s / 2; k++)
                                      {
                                             if (i + k > 0 \&\& i + k < w\&\&j + 1 > 0 \&\& j + 1 < h)
                                             {
                                                   int lmtT = matCmp[i + k + (j + 1)*w] / 255.0*lmt;
                                                   if (mat[k + i + (l + j)*w] < lmtT && fBgk[i + k + (j + k)*w]
+ 1)*w] != 1)
                                                   {
                                                          nPix++;
                                                         p1.x += i + k;
                                                          p1.y += j + 1;
                                                          if (a == -1)
                                                                a = i + k;
                                                          b = i + k;
                                                   }
                                                   else if (a != -1)
                                                         blank++;
                                            }
                                      }
                                      if (a!=-1)
                                      area += (b-a)+1;
                                }
                                density = nPix / area;
                                if (nPix > 100)
                                      cont = false;
                                if (nPix > 100 \&\& density > 0.85\&\& density < 1)
                                {
                                      p1.x /= nPix;
                                      p1.y /= nPix;
                                      int a = 0, b = 0;
                                      int lmtT = matCmp[i + j*w] / 255.0*lmt;
                                      bool flag = false;
                                      for (int k = 1; k < w&&!flag; k++)</pre>
                                             for (int l = p1.y - 10; l < p1.y + 50 && l < h&& !flag;
1++)
                                             {
                                                   if (1 > 0 \&\& matDet[k + 1*w] == 1)
                                                   {
                                                         bool flag2 = true;
                                                          int m;
                                                          for (m = 0; m < 5; m++)
                                                                if (m + 1 < h\&matDet[k + (m + 1)*w] ==
0)
                                                                       flag2 = false;
```

```
if (m == 5 && flag2)
                                                        {
                                                               flag = true;
                                                               a = k;
                                                        }
                                                  }
                                           }
                                     flag = false;
                                     for (int k = w - 2; k > 1 && !flag; k--)
                                           for (int l = p1.y - 10; l < p1.y + 30 && l < h&& !flag;
1++)
                                            {
                                                  if (1 > 0 \& matDet[k + 1*w] == 1)
                                                  {
                                                        bool flag2 = true;
                                                        int m;
                                                        for (m = 0; m < 5; m++)
                                                              if (m + 1 < h\&\&matDet[k + (m + 1)*w] ==
0)
                                                                     flag2 = false;
                                                        if (m == 5 && flag2)
                                                        {
                                                               flag = true;
                                                               b = k;
                                                        }
                                                  }
                                           }
                                     if (b - a < 80)
                                     {
                                           if (!fDetected&&cntrl_1.elapsed() < 200)</pre>
                                            {
                                                  allowedRC = true;
                                           }
                                           if (!fDetected&&cntrl_1.elapsed() > 50)
                                            {
                                                  p2 = p1;
                                                  GetCursorPos(&cP1);
                                                  cntrl_1.reset();
                                           }
                                           fDetected = true;
                                           cntrl_1.start();
                                           circle(frame, p1.x, p1.y, 15, 255);
                                           circle(frame, p1.x, p1.y, 16, 255);
                                            circle(frame, p1.x, p1.y, 17, 255);
```

```
detected = true;
                                     }
                               }
                        }
            if (!detected&&fDetected)
                  fDetected = false;
                  allowedC = true;
            }
            GetCursorPos(&cP2);
            if (!fDetected&&cntrl_1.elapsed() < 500 && mod(cP1.x - cP2.x) < 10 && mod(cP1.y - cP2.y)</pre>
< 10&&allowedC&&touch==0)
            {
                  l_Click = true;
                  allowedC = false;
                  drag = false;
                  scroll = false;
                  cntrl_1.reset();
                  touch++;
            }
            if (fDetected&&cntrl_1.elapsed() > 250 && mod(cP1.x - cP2.x) < 10 && mod(cP1.y - cP2.y) < 1
10 && allowedRC&&touch==1&&!drag)
            {
                  l_Click = false;
                  r_Click = true;
                  allowedRC = false;
            if (!fDetected&&cntrl_1.elapsed() < 500 && mod(cP1.x - cP2.x) < 10 && mod(cP1.y - cP2.y)
< 10 && allowedC&&touch == 1&&!drag)
            {
                  l_Click = false;
                  d_Click = true;
                  allowedC = false;
                  cntrl_1.reset();
                  touch++;
            }
            if (fDetected&&cntrl_1.elapsed() > 100 && mod(cP1.x - cP2.x) < 10 && mod(cP1.y - cP2.y) < 1
10 && allowedRC&&touch >= 2)
            {
                  allowedRC = false;
                  l_Click = false;
                  r_Click = false;
                  d_Click = false;
                  INPUT input = { 0 };
```

```
input.type = INPUT_MOUSE;
      input.mi.dwFlags = MOUSEEVENTF_LEFTDOWN;
      ::SendInput(1, &input, sizeof(INPUT));
      drag = true;
}
if (drag)
{
      d_Click = false;
      INPUT input = { 0 };
      input.type = INPUT_MOUSE;
      input.mi.dwFlags = MOUSEEVENTF_LEFTDOWN;
      ::SendInput(1, &input, sizeof(INPUT));
}
if (cntrl_1.elapsed() > 500)
      touch = 0;
if (calib)
{
      rect(frame, 20, 20, 50, 50, 50, 200, 50);
      rect(frame, 21, 21, 50, 50, 50, 200, 50);
      rect(frame, 19, 19, 50, 50, 50, 200, 50);
      line(frame, 25, 25, 65, 25);
      line(frame, 25, 26, 65, 26);
      line(frame, 25, 25, 25, 65);
      line(frame, 26, 25, 26, 65);
      line(frame, 25, 65, 65, 65);
      line(frame, 25, 64, 65, 64);
}
else
{
      rect(frame, 20, 20, 50, 50, 200);
      rect(frame, 21, 21, 50, 50, 200);
      rect(frame, 19, 19, 50, 50, 200);
}
imshow("Output", frame);
compControl();
int keyIn = waitKey(1);
if (keyIn == 27)
{
      break;
}
if (keyIn == 13)
{
}
if (keyIn == '+')
      lmt++;
```