Assignment 3: Question duplicates

Welcome to the third assignment of course 3. In this assignment you will explore Siamese networks applied to natural language processing. You will further explore the fundamentals of TensorFlow and you will be able to implement a more complicated structure using it. By completing this assignment, you will learn how to implement models with different architectures.

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Overview

In particular, in this assignment you will:

- Learn about Siamese networks
- Understand how the triplet loss works
- Understand how to evaluate accuracy
- Use cosine similarity between the model's outputted vectors
- Use the data generator to get batches of guestions
- Predict using your own model

Before getting started take some time to read the following tips:

TIPS FOR SUCCESSFUL GRADING OF YOUR ASSIGNMENT:

- All cells are frozen except for the ones where you need to submit your solutions.
- You can add new cells to experiment but these will be omitted by the grader, so don't rely on newly created cells to host your solution code, use the provided places for this.
- You can add the comment # grade-up-to-here in any graded cell to signal the grader that it must only evaluate up to that point. This is helpful if you want to check if you are on the right track even if you are not done with the whole assignment. Be sure to remember to delete the comment afterwards!
- To submit your notebook, save it and then click on the blue submit button at the beginning of the page.

By now, you should be familiar with Tensorflow and know how to make use of it to define your model. We will start this homework by asking you to create a vocabulary in a similar way as you did in the previous assignments. After this, you will build a classifier that will allow you to identify whether two questions are the same or not.

Your model will take in the two questions, which will be transformed into tensors, each tensor will then go through embeddings, and after that an LSTM. Finally you will compare the outputs of the two subnetworks using cosine similarity.

Before taking a deep dive into the model, you will start by importing the data set, and exploring it a bit.

Part 1: Importing the Data

1.1 Loading in the data

You will be using the 'Quora question answer' dataset to build a model that can identify similar questions. This is a useful task because you don't want to have several versions of the same question posted. Several times when teaching I end up responding to similar questions on piazza, or on other community forums. This data set has already been labeled for you. Run the cell below to import some of the packages you will be using.

```
import os
os.environ['TF_CPP_MIN_LOG_LEVEL'] = '3'
import os
import numpy as np
import pandas as pd
```

```
import random as rnd
import tensorflow as tf

# Set random seeds
rnd.seed(34)
import w3_unittest
```

You will now load the data set. We have done some preprocessing for you. If you have taken the deeplearning specialization, this is a slightly different training method than the one you have seen there. If you have not, then don't worry about it, we will explain everything.

```
data = pd.read csv("questions.csv")
N = len(data)
print('Number of question pairs: ', N)
data.head()
Number of question pairs: 404351
   id qid1 qid2
question1 \
          1
                2 What is the step by step guide to invest in sh...
   0
                4 What is the story of Kohinoor (Koh-i-Noor) Dia...
                6 How can I increase the speed of my internet co...
   2
          5
3
                  Why am I mentally very lonely? How can I solve...
               10 Which one dissolve in water quikly sugar, salt...
                                           question2 is duplicate
  What is the step by step guide to invest in sh...
  What would happen if the Indian government sto...
                                                                 0
                                                                 0
  How can Internet speed be increased by hacking...
3
   Find the remainder when [math]23^{24}[/math] i...
                                                                 0
            Which fish would survive in salt water?
                                                                 0
```

First, you will need to split the data into a training and test set. The test set will be used later to evaluate your model.

```
N_train = 300000
N_test = 10240
data_train = data[:N_train]
data_test = data[N_train:N_train + N_test]
print("Train set:", len(data_train), "Test set:", len(data_test))
del (data) # remove to free memory

Train set: 300000 Test set: 10240
```

As explained in the lectures, you will select only the question pairs that are duplicate to train the model. You need to build two sets of questions as input for the Siamese network, assuming that question $q 1_i$ (question i in the first set) is a duplicate of $q 2_i$ (question i in the second set), but all other questions in the second set are not duplicates of $q 1_i$.

The test set uses the original pairs of questions and the status describing if the questions are duplicates.

The following cells are in charge of selecting only duplicate questions from the training set, which will give you a smaller dataset. First find the indexes with duplicate questions.

You will start by identifying the indexes in the training set which correspond to duplicate questions. For this you will define a boolean variable td_index, which has value True if the index corresponds to duplicate questions and False otherwise.

```
td_index = data_train['is_duplicate'] == 1
td_index = [i for i, x in enumerate(td_index) if x]
print('Number of duplicate questions: ', len(td_index))
print('Indexes of first ten duplicate questions:', td_index[:10])

Number of duplicate questions: 111486
Indexes of first ten duplicate questions: [5, 7, 11, 12, 13, 15, 16, 18, 20, 29]
```

You will first need to split the data into a training and test set. The test set will be used later to evaluate your model.

```
print(data_train['question1'][5])
print(data_train['question2'][5])
print('is_duplicate: ', data_train['is_duplicate'][5])

Astrology: I am a Capricorn Sun Cap moon and cap rising...what does that say about me?
I'm a triple Capricorn (Sun, Moon and ascendant in Capricorn) What does this say about me?
is_duplicate: 1
```

Next, keep only the rows in the original training set that correspond to the rows where td index is True

```
Q1_train = np.array(data_train['question1'][td_index])
Q2_train = np.array(data_train['question2'][td_index])

Q1_test = np.array(data_test['question1'])
Q2_test = np.array(data_test['question2'])
y_test = np.array(data_test['is_duplicate'])
```

Let's print to see what your data looks like.

```
print('TRAINING QUESTIONS:\n')
print('Question 1: ', Q1_train[0])
print('Question 2: ', Q2_train[0], '\n')
print('Question 1: ', Q1_train[5])
print('Ouestion 2: ', Q1_train[5])
print('Question 2: ', Q2 train[5], '\n')
print('TESTING QUESTIONS:\n')
print('Question 1: ', Q1_test[0])
print('Question 2: ', Q2_test[0], '\n')
print('is_duplicate =', y_test[0], '\n')
TRAINING QUESTIONS:
Question 1: Astrology: I am a Capricorn Sun Cap moon and cap
rising...what does that say about me?
Question 2: I'm a triple Capricorn (Sun, Moon and ascendant in
Capricorn) What does this say about me?
Question 1: What would a Trump presidency mean for current
international master's students on an F1 visa?
Question 2: How will a Trump presidency affect the students presently
in US or planning to study in US?
TESTING QUESTIONS:
Question 1: How do I prepare for interviews for cse?
Question 2: What is the best way to prepare for cse?
is duplicate = 0
```

Finally, split your training set into training/validation sets so that you can use them at training time.

```
# Splitting the data
cut_off = int(len(Q1_train) * 0.8)
train_Q1, train_Q2 = Q1_train[:cut_off], Q2_train[:cut_off]
val_Q1, val_Q2 = Q1_train[cut_off:], Q2_train[cut_off:]
print('Number of duplicate questions: ', len(Q1_train))
print("The length of the training set is: ", len(train_Q1))
print("The length of the validation set is: ", len(val_Q1))

Number of duplicate questions: 111486
The length of the training set is: 89188
The length of the validation set is: 22298
```

1.2 Learning question encoding

The next step is to learn how to encode each of the questions as a list of numbers (integers). You will be learning how to encode each word of the selected duplicate pairs with an index.

You will start by learning a word dictionary, or vocabulary, containing all the words in your training dataset, which you will use to encode each word of the selected duplicate pairs with an index.

For this task you will be using the TextVectorization layer from Keras. which will take care of everything for you. Begin by setting a seed, so we all get the same encoding.

```
tf.random.set_seed(0)
text_vectorization =
tf.keras.layers.TextVectorization(output_mode='int',split='whitespace'
, standardize='strip_punctuation')
text_vectorization.adapt(np.concatenate((Q1_train,Q2_train)))
```

As you can see, it is set to split text on whitespaces and it's stripping the punctuation from text. You can check how big your vocabulary is.

```
print(f'Vocabulary size: {text_vectorization.vocabulary_size()}')
Vocabulary size: 36224
```

You can also call text_vectorization to see what the encoding looks like for the first questions of the training and test datasets

```
print('first question in the train set:\n')
print(Q1 train[0], '\n')
print('encoded version:')
print(text vectorization(Q1 train[0]),'\n')
print('first question in the test set:\n')
print(Q1 test[0], '\n')
print('encoded version:')
print(text vectorization(Q1 test[0]) )
first question in the train set:
Astrology: I am a Capricorn Sun Cap moon and cap rising...what does
that say about me?
encoded version:
tf.Tensor(
                     10 8988 2442 35393 761 13 6636 28205
[ 6984
           6
               178
31
   28
        483
                     98], shape=(16,), dtype=int64)
first question in the test set:
```

```
How do I prepare for interviews for cse?

encoded version:

tf.Tensor([ 4 8 6 160 17 2079 17 11775],
shape=(8,), dtype=int64)
```

Expected output:

```
first question in the train set:
Astrology: I am a Capricorn Sun Cap moon and cap rising...what does
that say about me?
encoded version:
tf.Tensor(
[ 6984
               178
                      10 8988 2442 35393
                                            761
                                                      6636 28205
31
                     98], shape=(16,), dtype=int64)
   28
first question in the test set:
How do I prepare for interviews for cse?
encoded version:
                                                 17 11775],
tf.Tensor([
                              160
                                     17
                                         2079
                          6
shape=(8,), dtype=int64)
```

Part 2: Defining the Siamese model

2.1 Understanding the Siamese Network

A Siamese network is a neural network which uses the same weights while working in tandem on two different input vectors to compute comparable output vectors. The Siamese network you are about to implement looks something like this:

You get the question, get it vectorized and embedded, run it through an LSTM layer, normalize v_1 and v_2 , and finally get the corresponding cosine similarity for each pair of questions. Because of the implementation of the loss function you will see in the next section, you are not going to have the cosine similarity as output of your Siamese network, but rather v_1 and v_2 . You will add the cosine distance step once you reach the classification step.

To train the model, you will use the triplet loss (explained below). This loss makes use of a baseline (anchor) input that is compared to a positive (truthy) input and a negative (falsy) input. The (cosine) distance from the baseline input to the positive input is minimized, and the distance from the baseline input to the negative input is maximized. Mathematically, you are trying to maximize the following.

$$L(A,P,N)=max(\|f(A)-f(P)\|^2-\|f(A)-f(N)\|^2+\alpha,0),$$

where A is the anchor input, for example $q\,1_1$, P is the duplicate input, for example, $q\,2_1$, and N is the negative input (the non duplicate question), for example $q\,2_2$. α is a margin; you can think about it as a safety net, or by how much you want to push the duplicates from the non duplicates. This is the essence of the triplet loss. However, as you will see in the next section, you will be using a pretty smart trick to improve your training, known as hard negative mining.

Exercise 01

Instructions: Implement the **Siamese** function below. You should be using all the functions explained below.

To implement this model, you will be using TensorFlow. Concretely, you will be using the following functions.

- tf.keras.models.Sequential: groups a linear stack of layers into a tf.keras.Model.
 - You can pass in the layers as arguments to Sequential, separated by commas, or simply instantiate the Sequential model and use the add method to add layers.

```
- For example: Sequential(Embeddings(...),
    AveragePooling1D(...), Dense(...), Softmax(...)) or
model = Sequential()    model.add(Embeddings(...))
model.add(AveragePooling1D(...))    model.add(Dense(...))
model.add(Softmax(...))
```

- tf.keras.layers.Embedding: Maps positive integers into vectors of fixed size. It will have shape (vocabulary length X dimension of output vectors). The dimension of output vectors (called d_featurein the model) is the number of elements in the word embedding.
 - Embedding(input_dim, output_dim).
 - input_dim is the number of unique words in the given vocabulary.
 - output_dim is the number of elements in the word embedding (some choices for a word embedding size range from 150 to 300, for example).
- tf.keras.layers.LSTM: The LSTM layer. The number of units should be specified and should match the number of elements in the word embedding.
 - LSTM(units) Builds an LSTM layer of n_units.

- tf.keras.layers.GlobalAveragePooling1D: Computes global average pooling, which essentially takes the mean across a desired axis.

 GlobalAveragePooling1D uses one tensor axis to form groups of values and replaces each group with the mean value of that group.
 - GlobalAveragePooling1D() takes the mean.
- tf.keras.layers.Lambda: Layer with no weights that applies the function f, which should be specified using a lambda syntax. You will use this layer to apply normalization with the function
 - tfmath.l2 normalize(x)
- tf.keras.layers.Input: it is used to instantiate a Keras tensor. Remember to set correctly the dimension and type of the input, which are batches of questions. For this, keep in mind that each question is a single string.
 - Input(input_shape,dtype=None,...)
 - input shape: Shape tuple (not including the batch axis)
 - dtype: (optional) data type of the input
- tf.keras.layers.Concatenate: Layer that concatenates a list of inputs. This layer will concatenate the normalized outputs of each LSTM into a single output for the model.
 - Concatenate()

```
# GRADED FUNCTION: Siamese
def Siamese(text vectorizer, vocab_size=36224, d_feature=128):
    """Returns a Siamese model.
   Args:
        text vectorizer (TextVectorization): TextVectorization
instance, already adapted to your training data.
        vocab size (int, optional): Length of the vocabulary. Defaults
to 56400.
        d model (int, optional): Depth of the model. Defaults to 128.
    Returns:
        tf.model.Model: A Siamese model.
    0.00
    ### START CODE HERE ###
    branch = tf.keras.models.Sequential(name='sequential')
    # Add the text vectorizer layer. This is the text vectorizer you
instantiated and trained before
    branch.add(text vectorizer)
    # Add the Embedding layer. Remember to call it 'embedding' using
the parameter `name`
    branch.add(tf.keras.layers.Embedding(input dim=vocab size,
output dim=d feature))
```

```
# Add the LSTM layer, recall from W2 that you want to the LSTM
layer to return sequences, of just one value.
    # Remember to call it 'LSTM' using the parameter `name`
    branch.add(tf.keras.layers.LSTM(name='LSTM', units=d feature,
return sequences=True))
    # Add the GlobalAveragePooling1D layer. Remember to call it 'mean'
using the parameter `name`
    branch.add(tf.keras.layers.GlobalAveragePooling1D(name='mean'))
    # Add the normalizing layer using the Lambda function. Remember to
call it 'out' using the parameter `name`
    branch.add(tf.keras.layers.Lambda(name='out', function=lambda x:
tf.math.l2 normalize(x)))
    # Define both inputs. Remember to call them 'input 1' and
'input 2' using the `name` parameter.
    # Be mindful of the data type and size
    input1 = tf.keras.layers.Input(shape=(1,), dtype=None,
name='input 1')
    input2 = tf.keras.layers.Input(shape=(1,), dtype=None,
name='input 2')
    # Define the output of each branch of your Siamese network.
Remember that both branches have the same coefficients,
    # but they each receive different inputs.
    branch1 = branch(input1)
    branch2 = branch(input2)
    # Define the Concatenate layer. You should concatenate columns,
you can fix this using the `axis`parameter.
    # This layer is applied over the outputs of each branch of the
Siamese network
    conc = tf.keras.layers.Concatenate(axis=1, name='conc 1 2')
([branch1, branch2])
    ### END CODE HERE ###
    return tf.keras.models.Model(inputs=[input1, input2],
outputs=conc, name="SiameseModel")
```

Setup the Siamese network model

```
# check your model
model = Siamese(text_vectorization,
vocab_size=text_vectorization.vocabulary_size())
model.build(input_shape=None)
model.summary()
model.get_layer(name='sequential').summary()

Model: "SiameseModel"
```

Layer (type) Connected to ====================================	Output	Shape		=====	Param #	
input_1 (InputLayer)	[(None	, 1)]			0	[]
<pre>input_2 (InputLayer)</pre>	[(None	, 1)]			0	[]
<pre>sequential (Sequential) ['input_1[0][0]',</pre>	(None,	128)			4768256	
'input_2[0][0]']						
<pre>conc_1_2 (Concatenate) ['sequential[0][0]',</pre>	(None,	256)			0	
'sequential[1][0]']						
Non-trainable params: 0 (0.0 Model: "sequential"	0 Byte) 					
Layer (type)	Output	Shape		Pa	ram #	
text_vectorization (TextVe ctorization)		None)		 Θ	======	
embedding (Embedding)	(None,	None,	128)	463	36672	
LSTM (LSTM)	(None,	None,	128)	13	1584	
mean (GlobalAveragePooling 1D)	(None,	128)		0		
out (Lambda)	(None,	128)		0		
======================================)			======	

```
Non-trainable params: 0 (0.00 Byte)
```

Expected output:

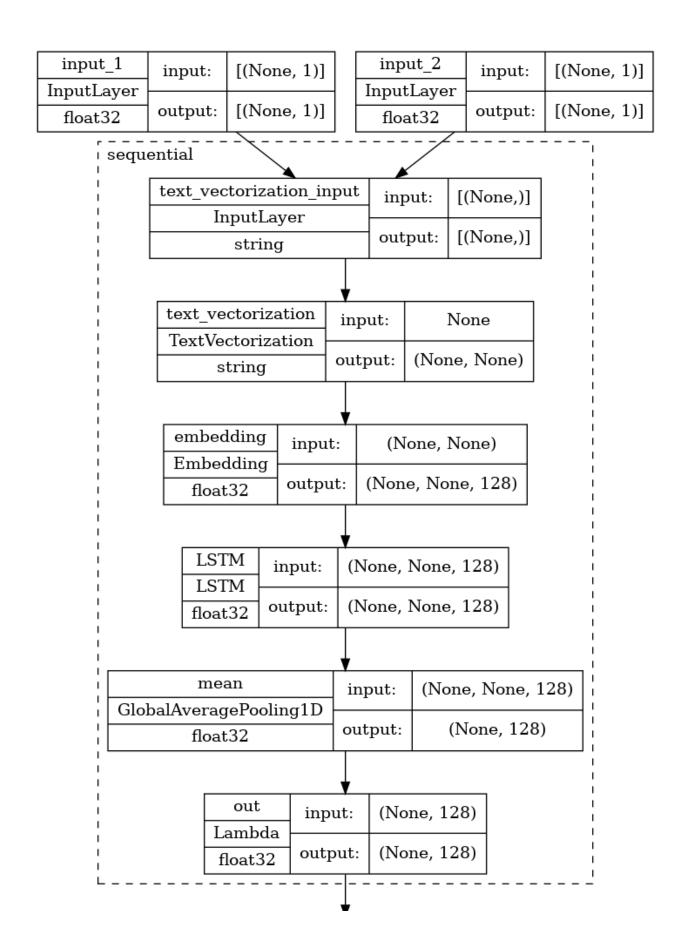
```
```Model: "SiameseModel"
 Layer (type) Output Shape Param # Connected to

input_2 (InputLayer) [(None, 1)] 0 []
sequential (Sequential) (None, 128) 4768256 ['input_1[0][0]',
'input_2[0][0]']
conc_1_2 (Concatenate) (None, 256) 0 ['sequential[0][0]',
'sequential[1][0]']

(18.19 MB) Non-trainable params: 0 (0.00 Byte)
 _ Model: "sequential"
 _ Layer (type) Output
Shape Param #

text_vectorization (TextVe (None, None) 0
ctorization)
embedding (Embedding) (None, None, 128) 4636672
LSTM (LSTM) (None, None, 128) 131584
mean (GlobalAveragePooling (None, 128) 0
1D)
out (Lambda) (None, 128) 0
params: 4768256 (18.19 MB) Trainable params: 4768256 (18.19 MB) Non-trainable params: 0
(0.00 Byte) _____
You can also draw the model for a clearer view of your Siamese network
tf.keras.utils.plot model(
 model,
 to file="model.png",
 show shapes=True,
 show_dtype=True,
```

show\_layer\_names=True,
rankdir="TB",
expand\_nested=True)



```
Test your function!
w3_unittest.test_Siamese(Siamese)
All tests passed!
```

### 2.2 Hard Negative Mining

You will now implement the **TripletLoss** with hard negative mining. As explained in the lecture, you will be using all the questions from each batch to compute this loss. Positive examples are questions  $q1_i$ , and  $q2_i$ , while all the other combinations  $q1_i$ ,  $q2_j$  ( $i\neq j$ ), are considered negative examples. The loss will be composed of two terms. One term utilizes the mean of all the non duplicates, the second utilizes the *closest negative*. Our loss expression is then:

Further, two sets of instructions are provided. The first set, found just below, provides a brief description of the task. If that set proves insufficient, a more detailed set can be displayed.

#### Exercise 02

**Instructions (Brief):** Here is a list of things you should do:

- As this will be run inside Tensorflow, use all operation supplied by tf.math or tf.linalg, instead of numpy functions. You will also need to explicitly use tf.shape to get the batch size from the inputs. This is to make it compatible with the Tensor inputs it will receive when doing actual training and testing.
- Use tf.linalg.matmul to calculate the similarity matrix  $v_2v_1^T$  of dimension batch size x batch size.
- Take the score of the duplicates on the diagonal with tf.linalg.diag part.
- Use the TensorFlow functions tf.eye and tf.math.reduce\_max for the identity matrix and the maximum respectively.

We'll describe the algorithm using a detailed example. Below,  $V_1$ ,  $V_2$  are the output of the normalization blocks in our model. Here you will use a <code>batch\_size</code> of 4 and a <code>d\_model of 3</code>. As explained in lecture, the input questions, Q1, Q2 are arranged so that corresponding inputs are duplicates while non-corresponding entries are not. The outputs will have the same pattern.

This testcase arranges the outputs,  $V_1$ ,  $V_2$ , to highlight different scenarios. Here, the first two outputs  $V_1[0]$ ,  $V_2[0]$  match exactly, so the model is generating the same vector for Q1[0] and Q2[0] inputs. The second pair of outputs, circled in orange, differ greatly on one of the values, so

the transformation is not quite the same for these questions. Next, you have examples  $V_1[3]$  and  $V_2[3]$ , which match almost exactly. Finally,  $V_1[4]$  and  $V_2[4]$ , circled in purple, are set to be exactly opposite, being 180 degrees from each other.

The first step is to compute the cosine similarity matrix or score in the code. As explained in the lectures, this is

$$V_2V_1^T$$
.

This is generated with tf.linalg.matmul. Since matrix multiplication is not commutative, the order in which you pass the arguments is important. If you want columns to represent different questions in Q1 and rows to represent different questions in Q2, as seen in the video, then you need to compute  $V_2V_1^T$ .

The clever arrangement of inputs creates the data needed for positive and negative examples without having to run all pair-wise combinations. Because Q1[n] is a duplicate of only Q2[n], other combinations are explicitly created negative examples or Hard Negative examples. The matrix multiplication efficiently produces the cosine similarity of all positive/negative combinations as shown above on the left side of the diagram. 'Positive' are the results of duplicate examples (cells shaded in green) and 'negative' are the results of explicitly created negative examples (cells shaded in blue). The results for our test case are as expected,  $V_1[0]\cdot V_2[0] \text{ and } V_1[3]\cdot V_2[3] \text{ match producing '1', and '0.99' respectively, while the other 'positive' cases don't match quite right. Note also that the <math>V_2[2]$  example was set to match  $V_1[3]$ , producing a not so good match at <code>score[2,2]</code> and an undesired 'negative' case of a '1', shown in grey.

With the similarity matrix (score) you can begin to implement the loss equations. First, you can extract cos(A,P) by utilizing tf.linalg.diag\_part. The goal is to grab all the green entries in the diagram above. This is positive in the code.

Next, you will create the  $closest\_negative$ . This is the nonduplicate entry in  $V_2$  that is closest to (has largest cosine similarity) to an entry in  $V_1$ , but still has smaller cosine similarity than the positive example. For example, consider row 2 in the score matrix. This row has the cosine similarity between  $V_2[2]$  and all four vectors in  $V_1$ . In this case, the largest value in the off-diagonal isscore [2,3]  $v_2[3] v_1[2]$ , which has a score of 1. However, since 1 is grater than the similarity for the positive example, this is not the  $closest\_negative$ . For this particular row, the  $closest\_negative$  will have to be score[2,1]=0.36. This is the maximum value of the 'negative' entries, which are smaller than the 'positive' example.

To implement this, you need to pick the maximum entry on a row of score, ignoring the 'positive'/green entries, and 'negative/blue entry greater that the 'positive' one. To avoid selecting these entries, you can make them larger negative numbers. For this, you can create a mask to identify these two scenarios, multiply it by 2.0 and subtract it out of scores. To create the mask, you need to check if the cell is diagonal by computing tf.eye(batch\_size) ==1, or if the non-diagonal cell is greater than the diagonal with (negative\_zero\_on\_duplicate > tf.expand dims(positive, 1). Remember that positive already has the diagonal

values. Now you can use tf.math.reduce\_max, row by row (axis=1), to select the maximum which is closest negative.

Next, we'll create <code>mean\_negative</code>. As the name suggests, this is the mean of all the 'negative'/blue values in <code>score</code> on a row by row basis. You can use <code>tf.linalg.diag</code> to create a diagonal matrix, where the diagonal matches <code>positive</code>, and just subtract it from <code>score</code> to get just the 'negative' values. This is <code>negative\_zero\_on\_duplicate</code> in the code. Compute the mean by using <code>tf.math.reduce\_sum</code> on <code>negative\_zero\_on\_duplicate</code> for <code>axis=1</code> and divide it by (<code>batch size - 1</code>). This is mean <code>negative</code>.

Now, you can compute loss using the two equations above and tf.maximum. This will form triplet loss1 and triplet loss2.

triplet loss is the tf.math.reduce sum of the sum of the two individual losses.

```
GRADED FUNCTION: TripletLossFn
def TripletLossFn(v1, v2, margin=0.25):
 """Custom Loss function.
 Args:
 v1 (numpy.ndarray or Tensor): Array with dimension
(batch size, model dimension) associated to Q1.
 v2 (numpy.ndarray or Tensor): Array with dimension
(batch size, model dimension) associated to Q2.
 margin (float, optional): Desired margin. Defaults to 0.25.
 Returns:
 triplet loss (numpy.ndarray or Tensor)
 ### START CODE HERE ###
 # use `tf.linalg.matmul` to take the dot product of the two
batches.
 # Don't forget to transpose the second argument using
`transpose b=True`
 scores = tf.linalg.matmul(v2, v1, transpose b=True)
 # calculate new batch size and cast it as the same datatype as
scores.
 batch size = tf.cast(tf.shape(v1)[0], scores.dtype)
 # use `tf.linalg.diag part` to grab the cosine similarity of all
positive examples
 positive = tf.linalg.diag_part(scores)
 # subtract the diagonal from scores. You can do this by creating a
diagonal matrix with the values
 # of all positive examples using `tf.linalg.diag`
 negative zero on duplicate = scores - tf.linalq.diaq(positive)
use `tf.math.reduce_sum` on `negative_zero_on_duplicate` for
`axis=1` and divide it by `(batch_size - 1)`
```

```
mean negative = tf.math.reduce sum(negative_zero_on_duplicate,
axis=1) / (batch size - 1)
 # create a composition of two masks:
 # the first mask to extract the diagonal elements.
 # the second mask to extract elements in the
negative zero on duplicate matrix that are larger than the elements in
the diagonal
 mask exclude positives = tf.cast((tf.eye(batch size) == 1))
(negative zero on duplicate > tf.expand dims(positive, 1)),
scores.dtype)
 # multiply `mask exclude positives` with 2.0 and subtract it out
of `negative zero on duplicate`
 negative without_positive = scores - mask_exclude_positives * 2.0
#negative zero on duplicate - mask exclude positives * 2.0
 # take the row by row `max` of `negative_without_positive`.
 # Hint: `tf.math.reduce max(negative without_positive, axis = None
 closest negative = tf.math.reduce max(negative without positive,
axis=1)
 # compute `tf.maximum` among 0.0 and `A`
 # A = subtract `positive` from `margin` and add `closest negative`
 A = margin - positive + closest negative
 triplet loss1 = tf.math.maximum(0.0, A)
 # compute `tf.maximum` among 0.0 and `B`
 # B = subtract `positive` from `margin` and add `mean negative`
 B = margin - positive + mean negative
 triplet loss2 = tf.math.maximum(0.0, B)
 # add the two losses together and take the `tf.math.reduce sum` of
it
 triplet loss = tf.math.reduce sum(triplet loss1 + triplet loss2)
 ### END CODE HERE ###
 return triplet loss
```

Now you can check the triplet loss between two sets. The following example emulates the triplet loss between two groups of questions with batch\_size=2

#### **Expected Output:**

```
Triplet Loss: ~ 0.70
```

To recognize it as a loss function, keras needs it to have two inputs: true labels, and output labels. You will not be using the true labels, but you still need to pass some dummy variable with size (batch\_size,) for TensorFlow to accept it as a valid loss.

Additionally, the out parameter must coincide with the output of your Siamese network, which is the concatenation of the processing of each of the inputs, so you need to extract  $v_1$  and  $v_2$  from there.

```
def TripletLoss(labels, out, margin=0.25):
 _, embedding_size = out.shape # get embedding size
 v1 = out[:,:int(embedding_size/2)] # Extract v1 from out
 v2 = out[:,int(embedding_size/2):] # Extract v2 from out
 return TripletLossFn(v1, v2, margin=margin)

Test your function!
w3_unittest.test_TripletLoss(TripletLoss)

All tests passed!
```

# Part 3: Training

Now it's time to finally train your model. As usual, you have to define the cost function and the optimizer. You also have to build the actual model you will be training.

To pass the input questions for training and validation you will use the iterator produced by tensorflow.data.Dataset. Run the next cell to create your train and validation datasets.

```
train_dataset = tf.data.Dataset.from_tensor_slices(((train_Q1,
train_Q2),tf.constant([1]*len(train_Q1))))
val_dataset = tf.data.Dataset.from_tensor_slices(((val_Q1,
val_Q2),tf.constant([1]*len(val_Q1))))
```

### 3.1 Training the model

You will now write a function that takes in your model to train it. To train your model you have to decide how many times you want to iterate over the entire data set; each iteration is defined as an epoch. For each epoch, you have to go over all the data, using your Dataset iterator.

#### Exercise 03

**Instructions:** Implement the train\_model below to train the neural network above. Here is a list of things you should do:

- Compile the model. Here you will need to pass in:
  - loss=TripletLoss
  - optimizer=Adam() with learning rate lr
- Call the fit method. You should pass:
  - train dataset
  - epochs
  - validation data

You will be using your triplet loss function with Adam optimizer. Also, note that you are not explicitly defining the batch size, because it will be already determined by the Dataset.

This function will return the trained model

```
GRADED FUNCTION: train model
def train model(Siamese, TripletLoss, text vectorizer, train dataset,
val_dataset, d_feature=128, lr=0.01, epochs=5):
 """Training the Siamese Model
 Args:
 Siamese (function): Function that returns the Siamese model.
 TripletLoss (function): Function that defines the TripletLoss
loss function.
 text vectorizer: trained instance of `TextVecotrization`
 train dataset (tf.data.Dataset): Training dataset
 val dataset (tf.data.Dataset): Validation dataset
 \overline{d} feature (int, optional) = size of the encoding. Defaults to
128.
 lr (float, optional): learning rate for optimizer. Defaults to
0.01
 train steps (int): number of epochs
 Returns:
 tf.keras.Model
 ## START CODE HERE ###
 # Instantiate your Siamese model
 model = Siamese(text_vectorizer,
 vocab size = text vectorizer.vocabulary size(),
 d feature = d feature)
 # Compile the model
 model.compile(loss=TripletLoss,
 optimizer=tf.keras.optimizers.Adam(learning rate=lr)
 # Train the model
 model.fit(train dataset,
 epochs=epochs,
```

```
validation_data=val_dataset
)
END CODE HERE
return model
```

Now call the train\_model function. You will be using a batch size of 256.

To create the data generators you will be using the method batch for Dataset object. You will also call the shuffle method, to shuffle the dataset on each iteration.

```
epochs = 2
batch size = 256
train_generator = train_dataset.shuffle(len(train_Q1),
 seed=7,
reshuffle each iteration=True).batch(batch size=batch size)
val generator = val dataset.shuffle(len(val Q1),
reshuffle each iteration=True).batch(batch size=batch size)
model = train model(Siamese, TripletLoss,text vectorization,
 train generator,
 val generator,
 epochs=epochs,)
Epoch 1/2
UnimplementedError
 Traceback (most recent call
last)
Cell In[30], line 9
 3 train_generator = train dataset.shuffle(len(train Q1),
 4
 seed=7,
 5
reshuffle each iteration=True).batch(batch size=batch size)
 6 val generator = val dataset.shuffle(len(val Q1),
 7
 seed=7,
reshuffle each iteration=True).batch(batch size=batch size)
----> 9 model = train model(Siamese, TripletLoss, text vectorization,
 10
 train generator,
 11
 val generator,
 12
 epochs=epochs,)
Cell In[29], line 31, in train model(Siamese, TripletLoss,
text vectorizer, train dataset, val dataset, d feature, lr, epochs)
 26 model.compile(loss=TripletLoss,
```

```
27
optimizer=tf.keras.optimizers.Adam(learning rate=lr)
 28
 30 # Train the model
---> 31 model.fit(train dataset,
 32
 epochs=epochs,
 33
 validation data=val dataset
 34
 36 ### END CODE HERE ###
 38 return model
File
/usr/local/lib/python3.8/dist-packages/keras/src/utils/traceback utils
.py:70, in filter traceback.<locals>.error handler(*args, **kwargs)
 filtered tb = process traceback frames(e. traceback)
 68
 # To get the full stack trace, call:
 # `tf.debugging.disable traceback filtering()`
 69
---> 70
 raise e.with traceback(filtered tb) from None
 71 finally:
 72 del filtered tb
File
/usr/local/lib/python3.8/dist-packages/tensorflow/python/eager/execute
.py:53, in quick execute(op name, num outputs, inputs, attrs, ctx,
name)
 51 try:
 52
 ctx.ensure initialized()
 tensors = pywrap tfe.TFE Py Execute(ctx. handle,
device name, op name,
 54
 inputs, attrs,
num outputs)
 55 except core._NotOkStatusException as e:
 if name is not None:
UnimplementedError: Graph execution error:
Detected at node 'SiameseModel/Cast' defined at (most recent call
last):
 File "/usr/lib/python3.8/runpy.py", line 194, in
run module as main
 return run code(code, main globals, None,
 File "/usr/lib/python3.8/runpy.py", line 87, in run code
 exec(code, run globals)
 File
"/usr/local/lib/python3.8/dist-packages/ipykernel launcher.py", line
17, in <module>
 app.launch new instance()
 File
"/usr/local/lib/python3.8/dist-packages/traitlets/config/application.p
y", line 1043, in launch instance
```

```
app.start()
 File
"/usr/local/lib/python3.8/dist-packages/ipykernel/kernelapp.py", line
728. in start
 self.io loop.start()
"/usr/local/lib/python3.8/dist-packages/tornado/platform/asyncio.py",
line 195, in start
 self.asyncio loop.run forever()
 File "/usr/lib/python3.8/asyncio/base events.py", line 570, in
run forever
 self. run once()
 File "/usr/lib/python3.8/asyncio/base events.py", line 1859, in
run once
 handle. run()
 File "/usr/lib/python3.8/asyncio/events.py", line 81, in run
 self. context.run(self. callback, *self. args)
 File
"/usr/local/lib/python3.8/dist-packages/ipykernel/kernelbase.py", line
516, in dispatch queue
 await self.process one()
 File
"/usr/local/lib/python3.8/dist-packages/ipykernel/kernelbase.py", line
505, in process one
 await dispatch(*args)
 File
"/usr/local/lib/python3.8/dist-packages/ipykernel/kernelbase.py", line
412, in dispatch shell
 await result
"/usr/local/lib/python3.8/dist-packages/ipykernel/kernelbase.py", line
740, in execute request
 reply content = await reply content
 File
"/usr/local/lib/python3.8/dist-packages/ipykernel/ipkernel.py", line
422, in do execute
 res = shell.run cell(
"/usr/local/lib/python3.8/dist-packages/ipykernel/zmqshell.py", line
540, in run cell
 return super().run cell(*args, **kwargs)
"/usr/local/lib/python3.8/dist-packages/IPython/core/interactiveshell."
py", line 3009, in run cell
 result = self._run_cell(
 File
"/usr/local/lib/python3.8/dist-packages/IPython/core/interactiveshell.
py", line 3064, in run cell
 result = runner(coro)
```

```
File
"/usr/local/lib/python3.8/dist-packages/IPython/core/async_helpers.py"
, line 129, in _pseudo_sync_runner
 coro.send(None)
 File
"/usr/local/lib/python3.8/dist-packages/IPython/core/interactiveshell.
py", line 3269, in run cell asvnc
 has raised = await self.run ast nodes(code ast.body, cell name,
 File
"/usr/local/lib/python3.8/dist-packages/IPython/core/interactiveshell.
py", line 3448, in run ast nodes
 if await self.run code(code, result, async =asy):
 File
"/usr/local/lib/python3.8/dist-packages/IPython/core/interactiveshell.
py", line 3508, in run code
 exec(code obj, self.user global ns, self.user ns)
 File "/tmp/ipykernel_14/35\overline{3}903586\overline{2}.py", line 9, in <module>
 model = train_model(Siamese, TripletLoss,text_vectorization,
 File "/tmp/ipykernel 14/2469359431.py", line 31, in train model
 model.fit(train dataset,
 File
"/usr/local/lib/python3.8/dist-packages/keras/src/utils/traceback util
s.py", line 65, in error handler
 return fn(*args, **kwargs)
 File
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/training.py",
line 1742, in fit
 tmp logs = self.train function(iterator)
 File
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/training.py",
line 1338, in train function
 return step_function(self, iterator)
 File
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/training.py",
line 1322, in step function
 outputs = model.distribute strategy.run(run step, args=(data,))
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/training.py",
line 1303, in run step
 outputs = model.train step(data)
 File
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/training.py",
line 1080, in train step
 y pred = self(x, training=True)
"/usr/local/lib/python3.8/dist-packages/keras/src/utils/traceback util
s.py", line 65, in error handler
 return fn(*args, **kwargs)
 File
```

```
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/training.py",
line 569, in call
 return super(). call (*args, **kwargs)
"/usr/local/lib/python3.8/dist-packages/keras/src/utils/traceback util
s.py", line 65, in error handler
 return fn(*args, **kwargs)
 File
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/base layer.py
", line 1150, in __call_
 outputs = call fn(inputs, *args, **kwargs)
"/usr/local/lib/python3.8/dist-packages/keras/src/utils/traceback util
s.py", line 96, in error_handler
 return fn(*args, **kwargs)
 File
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/functional.py
", line 512, in call
 return self. run internal graph(inputs, training=training,
mask=mask)
 File
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/functional.py
", line 651, in run internal graph
 y = self. conform to reference input(y, ref input=x)
 File
"/usr/local/lib/python3.8/dist-packages/keras/src/engine/functional.py
", line 748, in _conform_to_reference_input
 tensor = tf.cast(tensor, dtype=ref input.dtype)
Node: 'SiameseModel/Cast'
2 root error(s) found.
 (0) UNIMPLEMENTED: Cast string to float is not supported
 [[{{node SiameseModel/Cast}}]]
 (1) CANCELLED: Function was cancelled before it was started
O successful operations.
O derived errors ignored. [Op: inference train function 27966]
```

The model was only trained for 2 steps because training the whole Siamese network takes too long, and produces slightly different results for each run. For the rest of the assignment you will be using a pretrained model, but this small example should help you understand how the training can be done.

```
Test your function!
w3_unittest.test_train_model(train_model, Siamese, TripletLoss)
All tests passed!
```

# Part 4: Evaluation

# 4.1 Evaluating your siamese network

In this section you will learn how to evaluate a Siamese network. You will start by loading a pretrained model, and then you will use it to predict. For the prediction you will need to take the output of your model and compute the cosine loss between each pair of questions.

```
model = tf.keras.models.load model('model/trained model.keras',
safe mode=False, compile=False)
Show the model architecture
model.summary()
Model: "SiameseModel"
Layer (type)
 Output Shape
 Param #
Connected to
 input 1 (InputLayer)
 []
 [(None, 1)]
 input 2 (InputLayer)
 [(None, 1)]
 []
 sequential (Sequential)
 (None, 128)
 4768256
['input 1[0][0]',
'input 2[0][0]']
conc 1 2 (Concatenate)
 (None, 256)
 0
['sequential[0][0]',
'sequential[1][0]']
Total params: 4768256 (18.19 MB)
Trainable params: 4768256 (18.19 MB)
Non-trainable params: 0 (0.00 Byte)
```

### 4.2 Classify

To determine the accuracy of the model, you will use the test set that was configured earlier. While in training you used only positive examples, the test data, Q1\_test, Q2\_test and y\_test, is set up as pairs of questions, some of which are duplicates and some are not. This routine will run all the test question pairs through the model, compute the cosine similarity of each pair, threshold it and compare the result to y\_test - the correct response from the data set. The results are accumulated to produce an accuracy; the confusion matrix is also computed to have a better understanding of the errors.

#### Exercise 04

#### Instructions

- Loop through the incoming data in batch\_size chunks, you will again define a tensorflow.data.Dataset to do so. This time you don't need the labels, so you can just replace them by None,
- split the model output pred into v1 and v2. Note that v1 is the first part of the pred while v2 is the second part of pred (see how the split was accomplished in TripletLoss function above),
- for each element of the batch Find the cosine similarity between v1 and v2:

  Multiply v1 and v2 element-wise and use tf.math.reduce\_sum on the result. This operation is the same as vector dot product and the resulting value is cosine similarity since v1 and v2 are normalized (by your model's last layer), determine if d > threshold, increment accuracy if that result matches the expected results (y test[j]).

Instead of running a for loop, you will vectorize all these operations to make things more efficient,

• compute the final accuracy and confusion matrix and return. For the confusion matrix you can use the tf.math.confusion matrix function.

```
GRADED FUNCTION: classify
def classify(test_Q1, test_Q2, y_test, threshold, model,
batch_size=64, verbose=True):
 """Function to test the accuracy of the model.

Args:
 test_Q1 (numpy.ndarray): Array of Q1 questions. Each element
of the array would be a string.
 test_Q2 (numpy.ndarray): Array of Q2 questions. Each element
of the array would be a string.
```

```
y test (numpy.ndarray): Array of actual target.
 threshold (float): Desired threshold
 model (tensorflow.Keras.Model): The Siamese model.
 batch size (int, optional): Size of the batches. Defaults to
64.
 Returns:
 float: Accuracy of the model
 numpy.array: confusion matrix
 y_pred = []
 test gen = tf.data.Dataset.from tensor slices(((test Q1,
test Q2), None)).batch(batch size=batch size)
 ### START CODE HERE ###
 for (batch Q1, batch Q2), in test gen:
 pred = model.predict((batch Q1, batch Q2))
 _, embedding_size = pred.shape
 v1 = pred[:, :embedding size // 2]
 v2 = pred[:, embedding_size // 2:]
 \# v1, v2 = tf.split(pred, num or size splits=2, axis=1)
 # Compute the cosine similarity. Using `tf.math.reduce sum`.
 # Don't forget to use the appropriate axis argument.
 d = tf.reduce sum(v1 * v2, axis=1) / (tf.norm(v1, axis=1) *
tf.norm(v2, axis=1))
 # Check if d>threshold to make predictions
 y pred batch = tf.cast(d > threshold, tf.float64)
 y pred.append(y pred batch)
 # Concatenate all predictions
 y_pred = tf.concat(y_pred, axis=0)
 # take the average of correct predictions to get the accuracy
 accuracy = tf.reduce mean(tf.cast(tf.equal(y pred, tf.cast(y test,
tf.float64)), tf.float64))
 # compute the confusion matrix using `tf.math.confusion matrix`
 cm = tf.math.confusion matrix(y test, tf.cast(y pred, tf.float64))
 ### END CODE HERE ###
 return accuracy, cm
this takes around 1 minute
accuracy, cm = classify(Q1 test,Q2 test, y test, 0.7, model,
batch size = 512)
print("Accuracy", accuracy.numpy())
print(f"Confusion matrix:\n{cm.numpy()}")
16/16 [=======] - 1s 3ms/step
16/16 [========] - 0s 3ms/step
```

```
16/16 [=======] - Os 3ms/step
16/16 [========] - Os 3ms/step
16/16 [========] - 0s 3ms/step
16/16 [=======] - Os 3ms/step
16/16 [=======] - Os 3ms/step
16/16 [========] - 0s 3ms/step
16/16 [=======] - Os 3ms/step
16/16 [========] - 0s 3ms/step
16/16 [========] - 0s 3ms/step
16/16 [========] - 0s 3ms/step
Accuracy 0.72470703125
Confusion matrix:
[[4872 1510]
[1309 2549]]
```

### **Expected Result**

Accuracy ~0.725

Confusion matrix:

```
[[4876 1506]
[1300 2558]]
Test your function!
w3 unittest.test classify(classify, model)
16/16 [========] - Os 3ms/step
16/16 [=======] - 0s 3ms/step
16/16 [========] - Os 3ms/step
16/16 [========] - 0s 3ms/step
16/16 [=======] - Os 3ms/step
16/16 [=======] - Os 3ms/step
16/16 [=========] - 0s 3ms/step
16/16 [=======] - Os 3ms/step
14/14 [=======] - 0s 3ms/step
```

```
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [========] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
6/6 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 4ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 4ms/step
8/8 [=======] - 0s 3ms/step
8/8 [=======] - 0s 3ms/step
6/6 [=======] - 0s 3ms/step
Wrong accuracy for threshold=0.7 and batch size=512
 Expected: 0.7148571428571429,
 Got: 0.7122857142857143.
Wrong confusion matrix for threshold=0.7 and batch size=512
 Expected: [[1624 525]
[473 878]],
 Got:[[1622 527]
[480 871]].
Wrong accuracy for threshold=0.75 and batch size=512
 Expected: 0.7048571428571428.
 Got: 0.7068571428571429.
Wrong confusion matrix for threshold=0.75 and batch_size=512
 Expected: [[1747 421]
[612 720]],
 Got:[[1757
 411]
[615 717]].
Wrong accuracy for threshold=0.7 and batch size=256
 Expected: 0.7174285714285714,
 Got:0.718.
```

# Part 5: Testing with your own questions

In this final section you will test the model with your own questions. You will write a function predict which takes two questions as input and returns True or False depending on whether the question pair is a duplicate or not.

Write a function predict that takes in two questions, the threshold and the model, and returns whether the questions are duplicates (True) or not duplicates (False) given a similarity threshold.

#### Exercise 05

#### Instructions:

- Create a tensorflow.data.Dataset from your two questions. Again, labels are not important, so you simply write None (this is completed for you),
- use the trained model output to extract v1, v2 (similar to Exercise 04),
- compute the cosine similarity (dot product) of v1, v2 (similarly to Exercise 04),
- compute res (the decision if questions are duplicate or not) by comparing d to the threshold.

```
GRADED FUNCTION: predict
def predict(question1, question2, threshold, model, verbose=False):
 """Function for predicting if two questions are duplicates.
```

```
Args:
 question1 (str): First question.
 question2 (str): Second question.
 threshold (float): Desired threshold.
 model (tensorflow.keras.Model): The Siamese model.
 data generator (function): Data generator function. Defaults
to data generator.
 verbose (bool, optional): If the results should be printed
out. Defaults to False.
 Returns:
 bool: True if the questions are duplicates, False otherwise.
 generator = tf.data.Dataset.from tensor slices((([guestion1],
[question2]), None)).batch(batch size=1)
 ### START CODE HERE ###
 # Call the predict method of your model and save the output into
v1v2
 v1v2 = model.predict(generator)
 # Extract v1 and v2 from the model output
 embedding size = v1v2.shape[-1]
 v1 = v1v2[:, :embedding size // 2]
 v2 = v1v2[:, embedding size // 2:]
 # Take the dot product to compute cos similarity of each pair of
entries, v1, v2
 # Since v1 and v2 are both vectors, use the function
tf.math.reduce sum instead of tf.linalg.matmul
 d = tf.reduce sum(v1 * v2, axis=-1) / (tf.norm(v1, axis=-1) *
tf.norm(v2, axis=-1))
 # Is d greater than the threshold?
 res = d > threshold
 ### END CODE HERE ###
 if(verbose):
 print("Q1 = ", question1, "\nQ2 = ", question2)
print("d = ", d.numpy())
print("res = ", res.numpy())
 return res.numpy()
Feel free to try with your own questions
question1 = "When will I see you?"
question2 = "When can I see you again?"
1 means it is duplicated, 0 otherwise
predict(question1 , question2, 0.7, model, verbose = True)
```

**Expected Output** 

If input is:

```
question1 = "When will I see you?"
question2 = "When can I see you again?"
```

Output is (d may vary a bit):

```
Q1 = When will I see you?
Q2 = When can I see you again?
d = 0.8422112
res = True
Feel free to try with your own questions
question1 = "Do they enjoy eating the dessert?"
question2 = "Do they like hiking in the desert?"
1 means it is duplicated, 0 otherwise
predict(question1 , question2, 0.7, model, verbose=True)
1/1 [=======] - 0s 14ms/step
Q1 = Do they enjoy eating the dessert?
Q2 = Do they like hiking in the desert?
d = [0.12625803]
res = [False]
array([False])
```

Expected output

If input is:

```
question1 = "Do they enjoy eating the dessert?"
question2 = "Do they like hiking in the desert?"
```

Output (d may vary a bit):

```
d = 0.12625802
res = False
False
```

You can see that the Siamese network is capable of catching complicated structures. Concretely it can identify question duplicates although the questions do not have many words in common.

#### On Siamese networks

Siamese networks are important and useful. Many times there are several questions that are already asked in quora, or other platforms and you can use Siamese networks to avoid question duplicates.

Congratulations, you have now built a powerful system that can recognize question duplicates. In the next course we will use transformers for machine translation, summarization, question answering, and chatbots.

