

**Simple ATM Machine**

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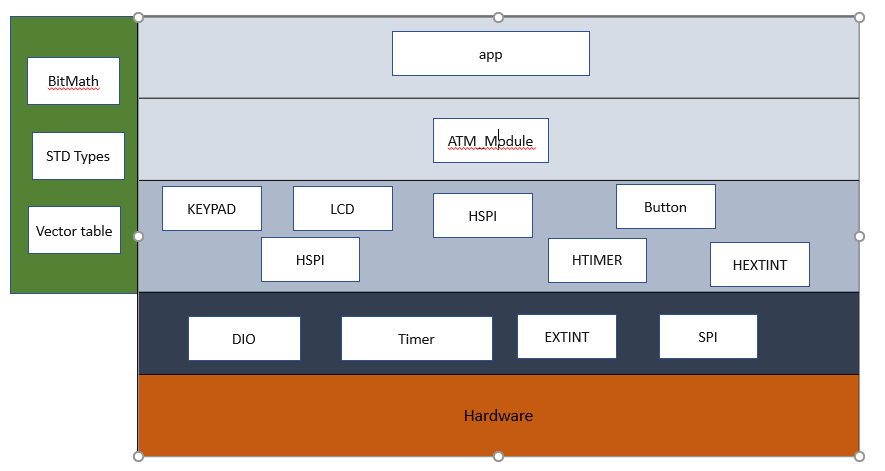
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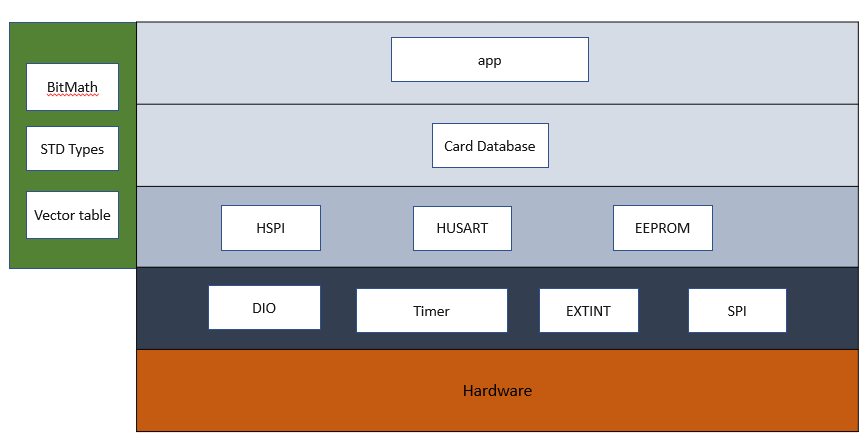
# INTRODUCTION

# High Level Design

## **Layered Architecture**



**ATM MACHINE:**

**CARD MCU**

## **Modules Description**

**MCAL Layer:**

* **DIO:** For controlling GPIO pins
* **Timer:** Provides an interface with timer 0 low-level capabilities.
* **EXTINT:** it controls three external hardware interrupts on pins PD2, PD3, and PB2 which are referred to as INT0, INT1, and INT2 respectively
* **USART:** Enables MCU to communicate using serial protocols.
* **SPI:** Provides interface with SPI’s low-level functionalities.
* **I2C:** Handles the i2c address oriented, multi-master, multi-slave communication.

**HAL Layer:**

* **Keypad:** Deal witha set of buttons arranged in a block. The 3 x 3 matrix keypad usually is used as input in a project
* **LCD:** Use for display data
* **Buzzer:** Simple module to control a buzzer.
* **HTimer:** Provides high-level functions using the lower-level timer 0 module capabilities.
* **H\_EXT\_INT:** Provides middle ware layer between app and external interrupt in MCAL.
* **HUSART:** Provides middle ware layer between app and UART in MCAL.
* **HSPI:** Provides high-level functionalities for using SPI communication.
* **EEPROM:** Enables MCU to interface with external EEPROM using i2c.
* **Button:** Interface with button to get its state (Enter/Zero).
* **Buzzer:** Enables MCU to control any given buzzer.

**Service Layer:**

* **STD\_Types:** Contains all the standard types used by all the layers.
* **BIT\_Math:** Provides bit-wise operations.
* **Vect\_table:** Contains all interrupt vectors and provides macros for dealing with general interrupt.

**Application Layer:**

Contains the main logic of the project.

## **Drivers’ Documentation**

### **MCAL Layer**

#### **DIO**

/\*

\* AUTHOR : Bassel Yasser

\* Function : DIO\_s8SETPinDir

\* Description : Set Pin Direction

\* Arguments :

\* - enPinCopy {DIO\_PINA\_0...., DIO\_PIND\_7}

\* - enPortDir {INPUT , OUTPUT}

\* Return : Sint8\_t

\*/

Sint8\_t **DIO\_s8SETPinDir** (enu\_pin enPinCopy, enu\_dir enPortDir)

/\*

\* AUTHOR : Bassel Yasser

\* Function : DIO\_s8SETPinVal

\* Description : Set Pin Value

\* Arguments :

\* - enPinCopy {DIO\_PINA\_0...., DIO\_PIND\_7}

\* - enPortDir {HIGH , LOW}

\* Return : Sint8\_t

\*/

Sint8\_t **DIO\_s8SETPinVal** (enu\_pin enPinCopy, enu\_val enPortVal)

/\*

\* AUTHOR : Bassel Yasser

\* Function : DIO\_s8GETPinVal

\* Description : Set Pin Value

\* Arguments :

\* - enPinCopy {DIO\_PINA\_0...., DIO\_PIND\_7}

\* - pu8Val address of variable that u want to save value on it

\* Return : Sint8\_t

\*/

Sint8\_t **DIO\_s8GETPinVal** (enu\_pin enPinCopy, Uint8\_t\* pu8Val)

#### **Timer 0**

/\*\*

\* \brief Initialize the timer with given mode

\* \param u8\_a\_Mode

\* \return en\_TIMErrorState\_t

\*/

en\_TIMErrorState\_t TIM0\_voidInit(en\_TIMMode\_t u8\_a\_Mode);

/\*\*

\* \brief Start the timer clock after prescaling it with given value

\* \param u8\_a\_prescaler

\* \return en\_TIMErrorState\_t

\*/

en\_TIMErrorState\_t TIM0\_Start(en\_TIM\_CLK\_SELECT\_t u8\_a\_prescaler);

/\*\*

\* \brief Function to stop timer 0

\* \return void

\*/

void TIM0\_Stop();

/\*\*

\* \brief Set the timer to start from a certain value

\* \param u8\_a\_FlagValue The value to start the timer from

\* \return void

\*/

void TIM0\_SetValue(Uchar8\_t u8\_a\_startValue);

/\*\*

\* \brief Function to get the value of the overflow flag of timer 0

\* \param u8\_a\_FlagValue reference to a variable to store flag value \*

\* \return en\_TIMErrorState\_t

\*/

en\_TIMErrorState\_t TIM0\_GetOVF(Uchar8\_t\* u8\_a\_FlagValue);

/\*\*

\* \brief Function to clear timer 0 overflow flag

\* \return void

\*/

void TIM0\_ClearOVF(void);

/\*\*

\* \brief Function to get the timer state (running/stopped)

\* \param u8\_a\_State reference to a variable to store timer state

\* \return en\_TIMErrorState\_t

\*/

en\_TIMErrorState\_t TIM0\_GetState(en\_TIMState\_t\* u8\_a\_State);

/\*\*

\* \brief Function to set a function to call when the timer0

\* Overflow Interrupt is triggered

\* \param pv\_a\_CallbackFn reference to the function to call

\* \return en\_TIMErrorState\_t

\*/

#### **EXTINT:**

// EXT\_INT TYPEDEFS

typedef enum EN\_EXTINT\_ERROR {

EXTINT\_OK=0,

EXTINT\_NOT\_OK

}EN\_EXTINT\_ERROR;

typedef enum EN\_Sence\_Control {

LOW\_LEVEL=0,

FALLING\_EDGE,

RISING\_EDGE,

ANY\_LOGICAL\_CHANGE

}EN\_Sence\_Control;

typedef enum EN\_EXINT\_NUMBER{

EXTINT0=0,

EXTINT1,

EXTINT2,

}EN\_EXINT\_NUMBER;

typedef enum EN\_GLOBAL\_INT{

DISABLE=0,

ENABLE

}EN\_GLOBAL\_INT;

// EXT\_INT prototypes

/\*

Description : This function initializes the GLOBAL\_INTERRUPT

ARGS : takes the state ( ENABLE OR DISABLE )

return : return EXTINT\_OK if the PIN initializes correctly, EXTINT\_NOT\_OK otherwise

\*/

EN\_EXTINT\_ERROR SET\_GLOBAL\_INTERRUPT(EN\_GLOBAL\_INT state);

/\*

Description : This function initializes the external interrupt number and it's detecting type

ARGS : takes the EXINT\_NUMBER( INT0,INT1 OR INT2) and sense control.

return : return EXTINT\_OK if the EXINT\_NUMBER initializes correctly, EXTINT\_NOT\_OK otherwise

\*/

EN\_EXTINT\_ERROR EXTINT\_init(EN\_EXINT\_NUMBER INTx ,EN\_Sence\_Control INTxSense);

/\*

Description : This function takes the external interrupt number and initialize call back function.

ARGS : takes the EXINT\_NUMBER( INT0,INT1 OR INT2) and pointer to the function we want to execute.

return : return EXTINT\_OK if the EXINT\_NUMBER initializes correctly, EXTINT\_NOT\_OK otherwise

\*/

EN\_EXTINT\_ERROR EXTINT\_CallBack(EN\_EXINT\_NUMBER INTx,void(\*ptrfunc)(void));

#### **I2C:**

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

/\* 01- i2c\_init\_master() \*/

/\* ----------------------------------------------------------------------------------

\* @func : I2C master Initialization

\* @in : void

\* @out : void

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

**void** **i2c\_init\_master**(**void**);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

/\* 02- i2c\_init\_slaver() \*/

/\* ----------------------------------------------------------------------------------

\* @func : I2C slave Initialization

\* @in : void

\* @out : void

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

**void** **i2c\_init\_slave** (**void**);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

/\* 03- i2c\_start() \*/

/\* ----------------------------------------------------------------------------------

\* @func : Send start condition

\* @in : void

\* @out : void

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

**void** **i2c\_start**(**void**);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

/\* 04- i2c\_repeated\_start() \*/

/\* ----------------------------------------------------------------------------------

\* @func : Send repeated start condition

\* @in : void

\* @out : void

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

**void** **i2c\_repeated\_start**(**void**);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

/\* 05- i2c\_send\_slave\_address\_with\_write\_req() \*/

/\* ----------------------------------------------------------------------------------

\* @func : send write request from master to slave

\* @in[1] : slave\_address

\* - Slave address that you want to write on it

\* @out : void

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

**void** **i2c\_send\_slave\_address\_with\_write\_req**(Uint8\_t slave\_address);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

/\* 06- i2c\_send\_slave\_address\_with\_read\_req() \*/

/\* ----------------------------------------------------------------------------------

\* @func : send read request from master to slave

\* @in[1] : slave\_address

\* - Slave address that you want to read from it

\* @out : void

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

**void** **i2c\_send\_slave\_address\_with\_read\_req**(Uint8\_t slave\_address);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

/\* 07- i2c\_write\_byte() \*/

/\* ----------------------------------------------------------------------------------

\* @func : Write data to slave

\* @in[1] : byte

\* - write data that u need to send

\* @out : void

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

**void** **i2c\_write\_byte**(Uint8\_t byte);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

/\* 08- i2c\_read\_byte() \*/

/\* ----------------------------------------------------------------------------------

\* @func : read data from slave

\* @in : void

\* @out : returned data

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

Uint8\_t **i2c\_read\_byte**(**void**);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

/\* 09- i2c\_stop() \*/

/\* ----------------------------------------------------------------------------------

\* @func : Send Stop condition

\* @in : void

\* @out : void

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

**void** **i2c\_stop(void**);

#### **UART:**

typedef enum EN\_USART\_ERROR{

USART\_OK=0,

USART\_NOT\_OK

}EN\_USART\_ERROR;

/\*

Name : USART\_init

Description : This function initializes USART Module with selected options in USART.cfg file.

Args : Void (all options defined as macros).

return : Std\_ReturnType (E\_OK) if Module initializes Correctly, (E\_NOT\_OK) otherwise.

\*/

EN\_USART\_ERROR USART\_init(void);

/\*

Name : USART\_sendData

Description : This function Send Data To Receiver (we can change size of data from USART.cfg file) we select 8 bits data size.

Args : take one argument (data to be sent) must be same size as the size we select in Initialization function.

return : Std\_ReturnType (E\_OK) if module sent data Correctly, (E\_NOT\_OK) otherwise.

\*/

EN\_USART\_ERROR USART\_sendData(Uchar8\_t data);

/\*

Name : USART\_receiveData

Description : This function Receive Data from sender (we can change size of data from USART.cfg file) we select 8 bits data size.

Args : void

return : data received. must be same size as the size we select in Initialization function.

\*/

Uchar8\_t USART\_receiveData(void);

/\*

Name : USART\_sendSTRING

Description : This function send array of data To Receiver. (we can change size of data from USART.cfg file) we select 8 bits data size.

Args : pointer to the array of data to be sent

return : void

\*/

void USART\_sendSTRING(Uchar8\_t \* str);

/\*

Name : USART\_receiveSTRING

Description : This function receive data from sender and store it in array.

Args : pointer to the array to store data received in it and size of data.

return : void

\*/

void USART\_receiveSTRING(Uchar8\_t \* str,Uchar8\_t size);

#### **SPI:**

/\*\*

\* (Author: Alaa Hisham)

\* \brief Initialize the MCU as the Master

\* in SPI communication

\* \return void

\*/

void SPI\_MasterInit(void);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Initialize the MCU as a slave

\* in SPI communication

\*

\* \return void

\*/

void SPI\_SlaveInit(void);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Sets the value of the SPI data register

\* \param u8\_a\_data: Desired value

\* \return void

\*/

void SPI\_SetValue(Uchar8\_t u8\_a\_data);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Exchange a letter with selected slave

\* \param u8\_a\_character: Character to send

\* \param pu8\_a\_receivedChar: Pointer to character to store received value

\* \return en\_SPI\_ErrorState\_t

\*/

en\_SPI\_ErrorState\_t SPI\_TranscieveChar(Uchar8\_t u8\_a\_character, Uchar8\_t\* pu8\_a\_receivedChar);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Exchange a letter with selected slave

\* \param u8\_a\_character: Character to send

\* \param pu8\_a\_receivedChar: Pointer to character to store received value

\* \return en\_SPI\_ErrorState\_t

\*/

en\_SPI\_ErrorState\_t SPI\_SlaveTranscieve(Uchar8\_t u8\_a\_character, Uchar8\_t\* pu8\_a\_receivedChar);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Set a notification function for the SPI Interrupt

\* \param pv\_a\_CallbackFn: reference to the function to callback

\* when the SPI Interrupt is triggered

\* \return en\_SPI\_ErrorState\_t

\*/

en\_SPI\_ErrorState\_t SPI\_SetCallback(void (\*pv\_a\_CallbackFn)(void));

### **HAL Layer:**

#### **Keypad**

// Macros

#define R1 DIO\_PINC\_2

#define R2 DIO\_PINC\_3

#define R3 DIO\_PINC\_4

#define C1 DIO\_PINC\_5

#define C2 DIO\_PINC\_6

#define C3 DIO\_PINC\_7

// user defined datatypes

typedef enum EN\_KEYPAD\_BTNS

{

KEY\_1=0,

KEY\_2,

KEY\_3,

KEY\_4T,

KEY\_5,

KEY\_6,

KEY\_7,

KEY\_8,

KEY\_9,

KEY\_NOTHING

}EN\_KEYPAD\_BTNS;

// functions prototypes

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

Name : KEYPAD\_init()

Description : This Function Initializes keypad pins (Rows are outputs & Columns are inputs).

ARGS : void

return : void

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

void KEYPAD\_init(void);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

\*

Name : KEYPAD\_GetButton

Description : This Function loops over other three functions (Checks (R1,R2,R3)).

ARGS : void

return : the pressed key or Nothing pressed

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

EN\_KEYPAD\_BTNS KEYPAD\_GetButton(void);

/\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

\*

Name : KEYPAD\_checkR1 , KEYPAD\_checkR2, KEYPAD\_checkR3

Description : functions are checking the entire row if it pressed or not.

ARGS : void

return : the pressed key or Nothing pressed

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*/

EN\_KEYPAD\_BTNS KEYPAD\_checkR1(void);

EN\_KEYPAD\_BTNS KEYPAD\_checkR2(void);

EN\_KEYPAD\_BTNS KEYPAD\_checkR3(void);

#### **HTimer:**

/\*\*

\* \brief Generate Synchronous delay (busy waiting)\*

\* \param Copy\_delayTime Desired delay

\* \param Copy\_timeUnit Time units (Seconds, mSeconds, uSeconds)

\*

\* \return en\_HTIMErrorState\_t

\*/

en\_HTIMErrorState\_t TIM0\_SyncDelay(Uint32\_t u32\_a\_delay, en\_timeUnits\_t u8\_a\_timeUnit);

/\*\*

\* \brief Generates delay asynchronously

\* \param u32\_a\_delay desired delay

\* \param u8\_a\_timeUnit delay time units

\* \param Copy\_pvCallbackFn function to call when delay is complete

\*

\* \return en\_TIMErrorState\_t

\*/

en\_HTIMErrorState\_t TIM0\_AsyncDelay(Uint32\_t u32\_a\_delay, en\_timeUnits\_t u8\_a\_timeUnit, void (\*Copy\_pvCallbackFn)(void));

/\*\*

\* \brief Function to end a delay asynchronously

\* To Stop Async Delay: No Restrictions

\* To Stop Sync Delay: should only be called in an ISR/Callback function

\*

\* \return void

\*/

void TIM0\_AsyncEndDelay();

#### **HLCD**

/\*

\* function : HLCD\_vidInit

\* description : func to set LCD initialization

\* input param : void

\* return : void

\* \*/

**void** **HLCD\_vidInit**(**void**)

/\*

\* function : HLCD\_vidWritecmd

\* description : func to configure some commands on lcd

\* input param :

\* u8commandCopy --> take lcd cmd instructions from instruction table <https://components101.com/sites/default/files/component\_datasheet/16x2%20LCD%20Datasheet.pdf>

\* return : void

\* \*/

**void** **HLCD\_vidWritecmd**(Uint8\_t u8commandCopy)

/\*

\* function : HLCD\_vidWriteChar

\* description : func to write char on lcd

\* input param : u8CharCopy -> take ascii code of char or char address on CGROM

\* return : void

\* \*/

**void** **HLCD\_vidWriteChar**(Uint8\_t u8CharCopy)

/\*

\* function : HLCD\_ClrDisplay

\* description : func to clear anything on lcd

\* input param : void

\* return : void

\* \*/

**void** **HLCD\_ClrDisplay**(**void**)

/\*

\* function : HLCD\_gotoXY

\* description : func to determine position which char print at this position on lcd ### NOTE : (2rows x 16coloms)

\* input param :

\* row -> take row number 0 or 1

\* pos -> take colom number from 0 ~ 16

\* return : void

\* \*/

**void** **HLCD\_gotoXY**(Uint8\_t row, Uint8\_t pos)

/\*

\* function : HLCD\_WriteString

\* description : func to write string on lcd

\* input param : str --> which take string as argument

\* return : void

\* \*/

**void** **HLCD\_WriteString**(Uint8\_t\* str)

/\*

\* function : HLCD\_WriteInt

\* description : func to write integer number on lcd

\* input param : number --> which take number as argument

\* return : void

\* \*/

**void** **HLCD\_WriteInt**(Uint32\_t number)

/\*

\* function : HLCD\_vidCreatCustomChar

\* description : func to store new patterm on CGRAM

\* input param :

\* pu8custom -> take pointer to array which having LCD Custom Character Generated data ### take only 8 characters

\* u8Location -> determine location on CGRAM [0 ~ 8]

\* return : void

\* \*/

**void** **HLCD\_vidCreatCustomChar**(Uint8\_t\* pu8custom, Uint8\_t u8Location)

/\*\*

\* (Author: Alaa Hisham)

\* \brief Display floating point number on LCD

\*

\* \param f32\_a\_number: number to display

\* \return void

\*/

void HLCD\_DisplayFloat(float32\_t f32\_a\_number);

#### **Buzzer**

/\*\*

\* \brief Initialize buzzer pin as output

\* \param pst\_a\_buzzer reference to buzzer

\* \return void

\*/

void BUZ\_Init(st\_Buzzer\_t\* pst\_a\_buzzer);

/\*\*

\* \brief Turn the buzzer on/off

\* \param pst\_a\_buzzer reference to buzzer

\* \param u16\_a\_state BUZ\_ON (or) BUZ\_OFF

\* \return en\_BuzzerErrorState\_t

\*/

en\_BuzzerErrorState\_t BUZ\_SetState(st\_Buzzer\_t\* pst\_a\_buzzer, en\_BuzzerState\_t en\_a\_state);

#### **Button**

/\*

\* AUTHOR : Bassel Yasser Mahmoud

\* FUNCTION : HButton\_Init

\* DESCRIPTION : Initialize specified pin as input and pull up

\* RETURN : enu\_buttonError\_t {BUTTON\_NOK, BUTTON\_OK}

\*/

enu\_buttonError\_t **HButton\_Init**(enu\_pin en\_pinx);

/\*

\* AUTHOR : Bassel Yasser Mahmoud

\* FUNCTION : HButton\_ExtIntInit

\* DESCRIPTION : Initialize specified as pull up for external interrupt

\* RETURN : enu\_buttonError\_t {BUTTON\_NOK, BUTTON\_OK}

\*/

enu\_buttonError\_t **HButton\_ExtIntInit**(enu\_pin en\_pinx);

/\*

\* AUTHOR : Bassel Yasser Mahmoud

\* FUNCTION : HButton\_getPinVal

\* DESCRIPTION : Get pin status if it is high or low

\* RETURN : enu\_buttonError\_t {BUTTON\_NOK, BUTTON\_OK}

\*/

enu\_buttonError\_t **HButton\_getPinVal**(enu\_pin en\_pinx, Uint8\_t\* pu8\_refVal );

\*

Description : This function initializes the external interrupt number and it's detecting type and initialize call back function.

ARGS : takes the EXINT\_NUMBER( INT0,INT1 OR INT2) and sense control and and pointer to the function we want to execute when interrupt occurs.

return : return EXTINT\_OK if the EXINT\_NUMBER initializes correctly, EXTINT\_NOT\_OK otherwise

\*/

EN\_EXTINT\_ERROR H\_EXTINT\_create(EN\_EXINT\_NUMBER INTx ,EN\_Sence\_Control INTxSense,void(\*ptrfunc)(void));

#### **HEXT\_INT**

\*

Description : This function initializes the external interrupt number and it's detecting type and initialize call back function.

ARGS : takes the EXINT\_NUMBER( INT0,INT1 OR INT2) and sense control and and pointer to the function we want to execute when interrupt occurs.

return : return EXTINT\_OK if the EXINT\_NUMBER initializes correctly, EXTINT\_NOT\_OK otherwise

\*/

EN\_EXTINT\_ERROR H\_EXTINT\_create(EN\_EXINT\_NUMBER INTx ,EN\_Sence\_Control INTxSense,void(\*ptrfunc)(void));

#### **HSPI**

/\*\*

\* (Author: Alaa Hisham)

\* \brief Initialize the MCU as the Master in SPI communication

\* \return void

\*/

void HSPI\_MasterInit(void);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Initialize the MCU as a slave in SPI communication

\* \return void

\*/

void HSPI\_SlaveInit(void);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Function to send a single character

\* \param u8\_a\_character character to send

\* \return void

\*/

void HSPI\_SendChar(Uchar8\_t u8\_a\_character);

/\*\*

\* \brief Receive data in the given buffer

\*

\* \param pu8\_a\_data: reference to buffer to store received data

\* \param u8\_a\_DataSize: Size (length) of data to receive

\*

\* \return void

\*/

void HSPI\_ReceiveData(Uchar8\_t \*pu8\_a\_data, Uchar8\_t u8\_a\_DataSize);

/\*\*

\* \brief Send given data byte by byte to selected slave

\* and receive data in exchange into given array

\* \param pu8\_a\_TxDataArr: Reference to array of data to be transmitted

\* \param pu8\_a\_RxDataArr: Reference to array to store received data

\* \param u8\_a\_DataLen: Length of data to exchange (in bytes)

\* (Must be less than or equal SPI\_BUFFER\_SIZE)

\*

\* \return en\_HSPI\_ErrorState\_t

\*/

en\_HSPI\_ErrorState\_t HSPI\_ExchangeData(Uchar8\_t\* pu8\_a\_TxDataArr, Uchar8\_t\* pu8\_a\_RxDataArr, Uchar8\_t u8\_a\_DataLen);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Request to send data to the master

\* \param u8\_a\_data: data to send

\* \return void

\*/

void HSPI\_SlaveRequest(Uchar8\_t\* pu8\_a\_dataPtr, Uchar8\_t u8\_a\_DataSize);

#### **EEPROM:**

/\*\* AUTHOR : Sherif Ashraf Khadr

\* \brief : This Function Just Call To Initialize I2C as Master

\*

\* \param : Void

\*

\* \return void

\*/

void eeprom\_init(void)

/\*\* AUTHOR : Sherif Ashraf Khadr

\* \brief : This Function Call To Make The Sequence Of I2C Frame To Write Byte On A Device

\*

\* \param : Uint16\_t address : This Is Device Address

\* : Uchar8\_t data : This Is Data That Will Be Write

\*

\* \return void

\*/

void eeprom\_write\_byte(Uint16\_t address, Uchar8\_t data)

/\*\* AUTHOR : Sherif Ashraf Khadr

\* \brief : This Function Call To Make The Sequence Of I2C Frame To Read Byte On A Device

\*

\* \param : Uint16\_t address : This Is Device Address

\*

\* \return Uchar8\_t : Function Will Return Uchar8\_t Contain The Data

\*/

Uchar8\_t eeprom\_read\_byte(Uint16\_t address)

/\*\* AUTHOR : Sherif Ashraf Khadr

\* \brief : This Function Call When You Need To Write A String In The EEPROM

\*

\* \param : Uint16\_t address : This Is Device Address

\* : Uchar8\_t \*str : This Pointer Will Store The Address Of The Array Of The Chars

\* \return Void

\*/

void eeprom\_write\_string(Uint16\_t Copy\_u8Address, const Uchar8\_t\* str)

/\*\* AUTHOR : Sherif Ashraf Khadr

\* \brief : This Function Call When You Need To Read A String From The EEPROM

\*

\* \param : Uint16\_t address : This Is Device Address

\* : Uchar8\_t \*str : This Pointer Will Store The Address Of The Array Of The Chars That Will Return String In It

\* \return Void

\*/

void eeprom\_read\_string(Uint16\_t Copy\_u8Address, Uchar8\_t\* str)

### **Card\_Database Layer (CARD MCU)**

/\*

\* AUTHOR : Bassel Yasser Mahmoud

\* FUNCTION : APP\_terminalPinGet

\* DESCRIPTION : Get pin from User within terminal and doing some validation

\* RETURN : en\_terminalPinGetStatus\_t {PINGET\_NOK or PINGET\_OK}

\*/

en\_terminalPinGetStatus\_t **APP\_terminalPinGet**(Uchar8\_t\* arr);

/\*

\* AUTHOR : Sharpel

\* FUNCTION : APP\_terminalPanGet

\* DESCRIPTION : Get pan from User within terminal and doing some validation

\* RETURN : en\_terminalPanGetStatus\_t {PANGET\_NOK or PANGET\_OK}

\*/

en\_terminalPanGetStatus\_t **APP\_terminalPanGet**(Uchar8\_t\* arr);

/\*

\* FUNCTION : SaveCardData

\* DESCRIPTION : Saving PAN and PIN in EEPROM

\* RETURN : EN\_TerminalDataState {DATA\_SAVED, DATA\_NSAVED, DATA\_READ, DATA\_NREAD}

\*/

EN\_TerminalDataState **SaveCardData**(Uchar8\_t \*CardPan,Uchar8\_t \*CardPin);

/\*

\* FUNCTION : ReadCardData

\* DESCRIPTION : Reading PAN and PIN from EEPROM

\* RETURN : EN\_TerminalDataState {DATA\_SAVED, DATA\_NSAVED, DATA\_READ, DATA\_NREAD}

\*/

EN\_TerminalDataState **ReadCardData**(Uchar8\_t \*CardPan,Uchar8\_t \*CardPin);

/\*

\* FUNCTION : CARD\_MatchPINs

\* DESCRIPTION : Validate if PIN no and Confirmed PIN no is Matched or not

\* RETURN : en\_CardPinMatchError\_t { PIN\_Match\_NOK, PIN\_Match\_OK}

\*/

en\_CardPinMatchError\_t **CARD\_MatchPINs**();

### **ATM\_MODULE Layer (ATM MCU)**

#### **ATM:**

/\*\*

\* \brief Displays welcome routine

\*

\* \return void

\*/

void Welcome(void);

/\*\*

\* (Author: Sherif Ashraf)

\* \brief Check if the pin user enters is the same as the cardholder's pin

\* \param pinFromAtm : reference to pin entered by user

\* \param pinFromServer: reference to pin received from card

\* \return EN\_PinState

\*/

EN\_PinState PIN\_checkPinMatching(Uchar8\_t \*pinFromAtm,Uchar8\_t \*pinFromServer);

/\*

\* AUTHOR : Sharpel

\* FUNCTION : Get\_pin

\* DESCRIPTION : get pin from user (on the atm )

\* ARGS : pointer to array (the size of array must be 5 or more) to store entered pin by user

\* RETURN : PIN\_OK if user enters 4 numbers , PIN\_NOT\_OK otherwise

\*/

EN\_PinState Get\_pin(Uchar8\_t \*enteredpin);

/\*\*

\* (Author: Sherif Ashraf)

\* \brief Locks the system and sound the buzzer

\* \param pst\_a\_buzzer: reference to the buzzer

\* \return en\_BuzzerErrorState\_t

\*/

en\_BuzzerErrorState\_t deinitAtm(st\_Buzzer\_t\* pst\_a\_buzzer);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Get the card pan and pin

\* \param pu8\_a\_pan: reference to buffer to receive pan from card

\* \param pu8\_a\_pin: reference to buffer to receive pin from card

\* \return EN\_PinState

\*/

EN\_PinState ATM\_GetCardData(Uchar8\_t \*pu8\_a\_pan, Uchar8\_t \*pu8\_a\_pin);

/\*

\* AUTHOR : Sharpel

\* FUNCTION : get\_amount\_left

\* DESCRIPTION : get amount from user ( on the atm )

\* ARGS : pointer to array (the size of array must be 8 or more and equal "0000.00" initial value) to store entered pin by user

\* RETURN : void

\*/

void get\_amount\_left (Uchar8\_t \* amount);

/\*

\* AUTHOR : Bassel Yasser

\* FUNCTION : EXTINT\_FUNC

\* DESCRIPTION : when timer 2 ISR is fire it changes the state of (Enter or Zero)

\* ARGS : void

\* RETURN : void

\*/

void EXTINT\_FUNC(void);

/\*\*

\* (Author: Alaa Hisham)

\* \brief Carries out the routine for approved card

\* \param f32\_a\_NewBalance: the balance to display after transaction

\* \return void

\*/

void ATM\_ApprovedCard(float32\_t f32\_a\_NewBalance);

#### **Database\_check:**

/\*

\* FUNCTION : isValidPanAccount

\* DESCRIPTION : Check If PAN No. Valid or not

\* RETURN : EN\_dataError\_t {APPROVED ,FRAUD\_CARD,CARD\_STOLEN,EXCEED\_MAX\_DAILY\_AMOUNT,INSUFFICIENT\_FUND, DATA\_ERROR}

\*/

EN\_dataError\_t **isValidPanAccount**(Uchar8\_t \* pan);

/\*

\* FUNCTION : isRunningAccount

\* DESCRIPTION : Checking if card stolen or not

\* RETURN : EN\_dataError\_t {APPROVED ,FRAUD\_CARD,CARD\_STOLEN,EXCEED\_MAX\_DAILY\_AMOUNT,INSUFFICIENT\_FUND, DATA\_ERROR}

\*/

EN\_dataError\_t **isRunningAccount**(Uchar8\_t \* pan);

/\*

\* FUNCTION : isValidAccountAmount

\* DESCRIPTION : Checking if there is INSUFFICIENT\_FUND or not

\* RETURN : EN\_dataError\_t {APPROVED ,FRAUD\_CARD,CARD\_STOLEN,EXCEED\_MAX\_DAILY\_AMOUNT,INSUFFICIENT\_FUND, DATA\_ERROR}

\*/

EN\_dataError\_t **isValidAccountAmount**(Uchar8\_t \* pan,Uchar8\_t \* amount,float32\_t \*newAmount);

/\*

\* FUNCTION : isBelowMaxDailyAmount

\* DESCRIPTION : Checking if transfered money is below limited daily amount or not

\* RETURN : EN\_dataError\_t {APPROVED ,FRAUD\_CARD,CARD\_STOLEN,EXCEED\_MAX\_DAILY\_AMOUNT,INSUFFICIENT\_FUND, DATA\_ERROR}

\*/

EN\_dataError\_t **isBelowMaxDailyAmount**(Uchar8\_t \* amount);

/\*

\* FUNCTION : DATABASE\_checking

\* DESCRIPTION : Card Database checking

\* RETURN : EN\_dataError\_t {APPROVED ,FRAUD\_CARD,CARD\_STOLEN,EXCEED\_MAX\_DAILY\_AMOUNT,INSUFFICIENT\_FUND, DATA\_ERROR}

\*/

EN\_dataError\_t **DATABASE\_checking** (Uchar8\_t \* pan,Uchar8\_t \* amount,float32\_t \*newAmount);

### **Application Layer:**

#### **Card MCU**

/\*\*

\* \brief Initializations of all used peripherals

\* \return void

\*/

void APP\_Init(void);

/\*\*

\* \brief The main logic of the Card

\* \return void

\*/

void APP\_Start(void);

#### **ATM MCU**

/\*\*

\* \brief Initializations of all used peripherals

\* \return void

\*/

void APP\_Init(void);

/\*\*

\* \brief The main logic of the ATM

\* \return void

\*/

void APP\_Start(void);

# Low Level Design

### **MCAL Layer:**

#### **DIO**

Sint8\_t **DIO\_s8SETPinDir** (enu\_pin enPinCopy, enu\_dir enPortDir)

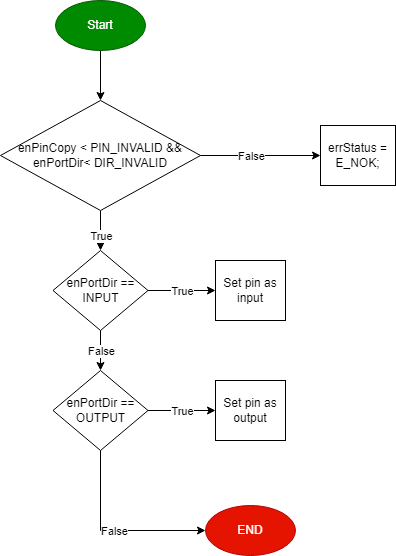
****

Figure 2 DIO\_s8SETPinDir Flow Chart

Sint8\_t **DIO\_s8SETPinVal** (enu\_pin enPinCopy, enu\_val enPortVal)

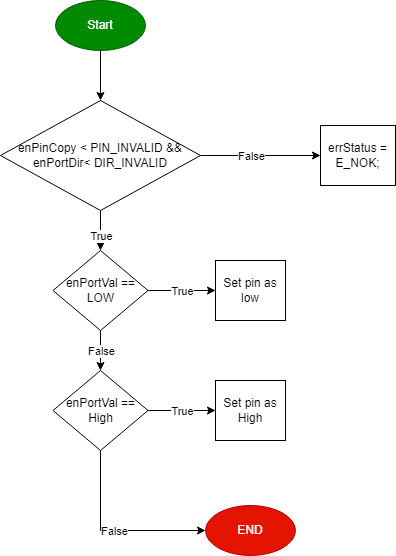
****

Figure 3 DIO\_s8SETPinVal Flow chart

Sint8\_t **DIO\_s8GETPinVal** (enu\_pin enPinCopy, Uint8\_t\* pu8Val)

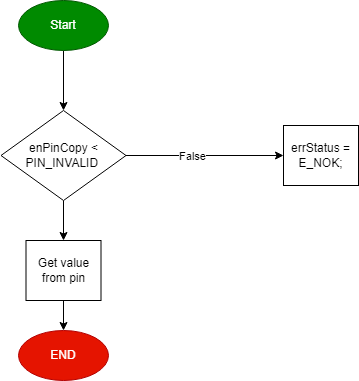
****

Figure 4 DIO\_s8GETPinVal Flow Chart

#### **Timer:**

**TIM0\_Init**

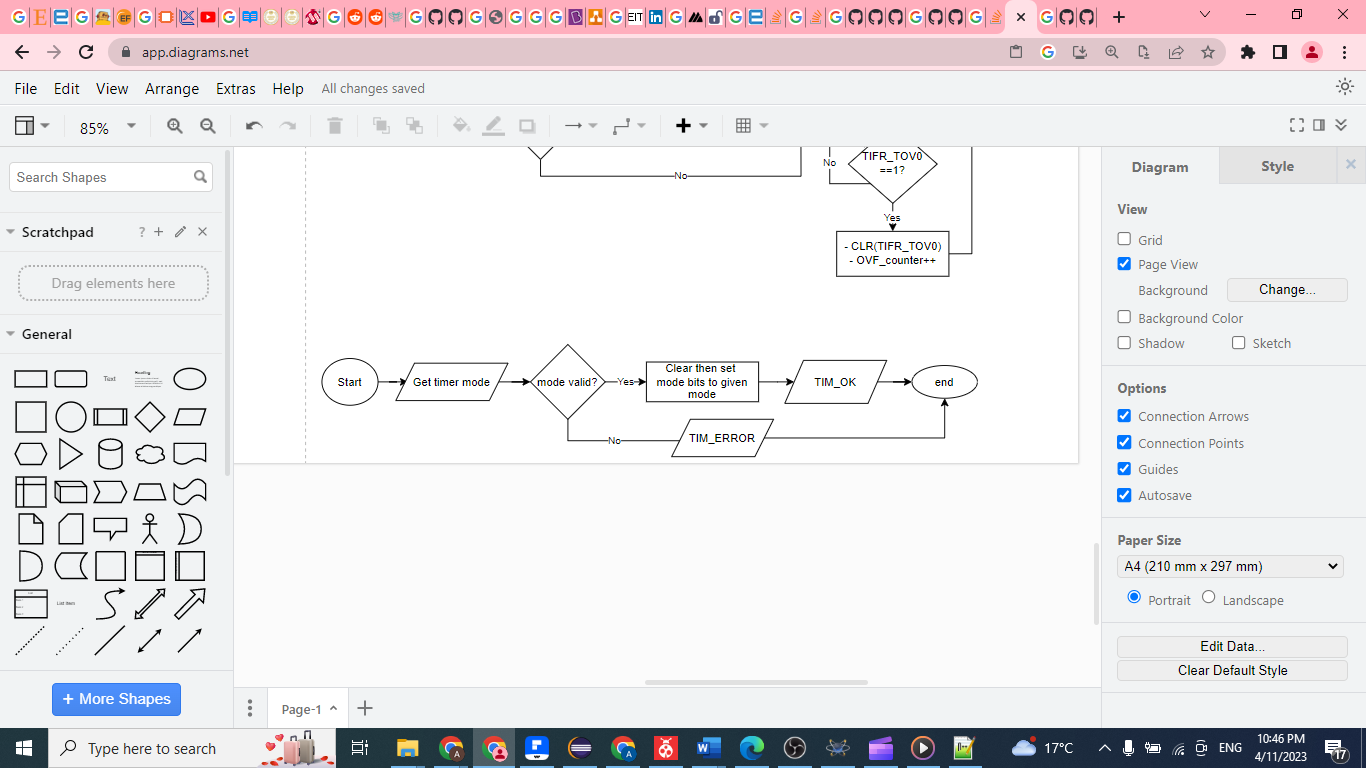


Figure 5 TIM0\_Init Flow Chart

**TIM0\_Start**

****

Figure 6 TIM0\_Start Flow Chart

**TIM0\_Stop**

****

Figure 7 TIM0\_Stop Flow Chart

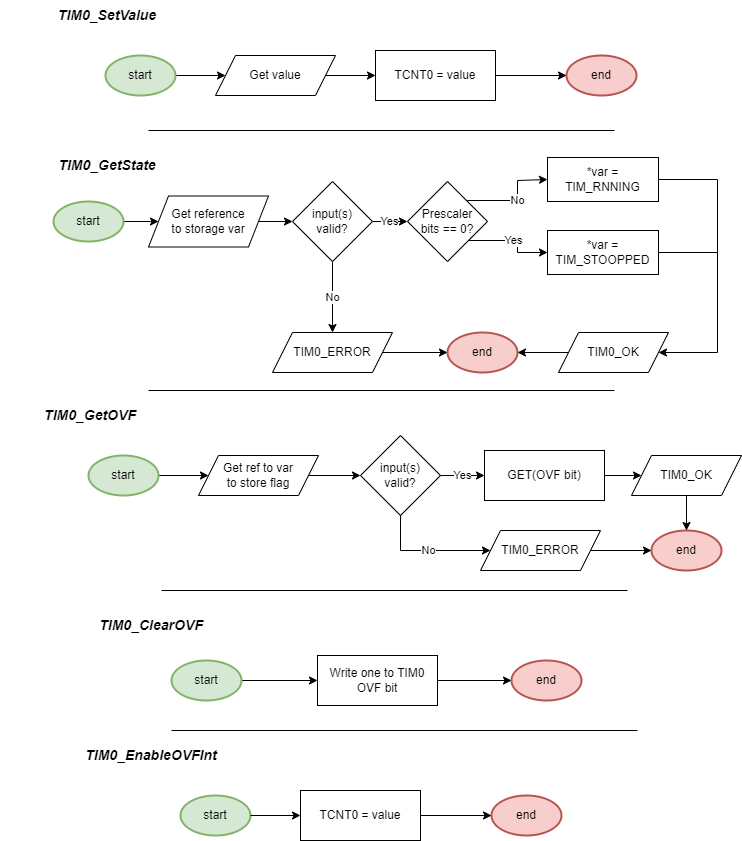
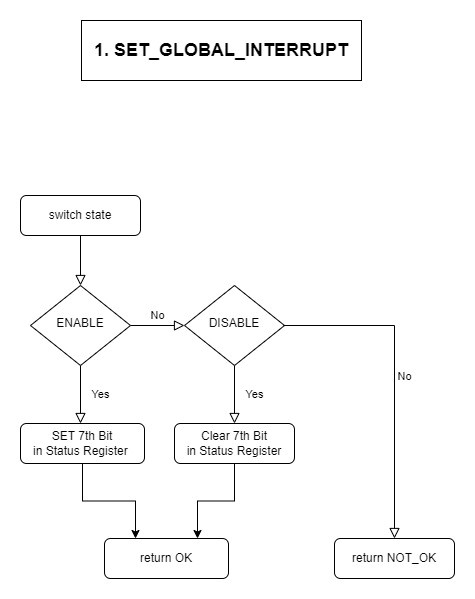
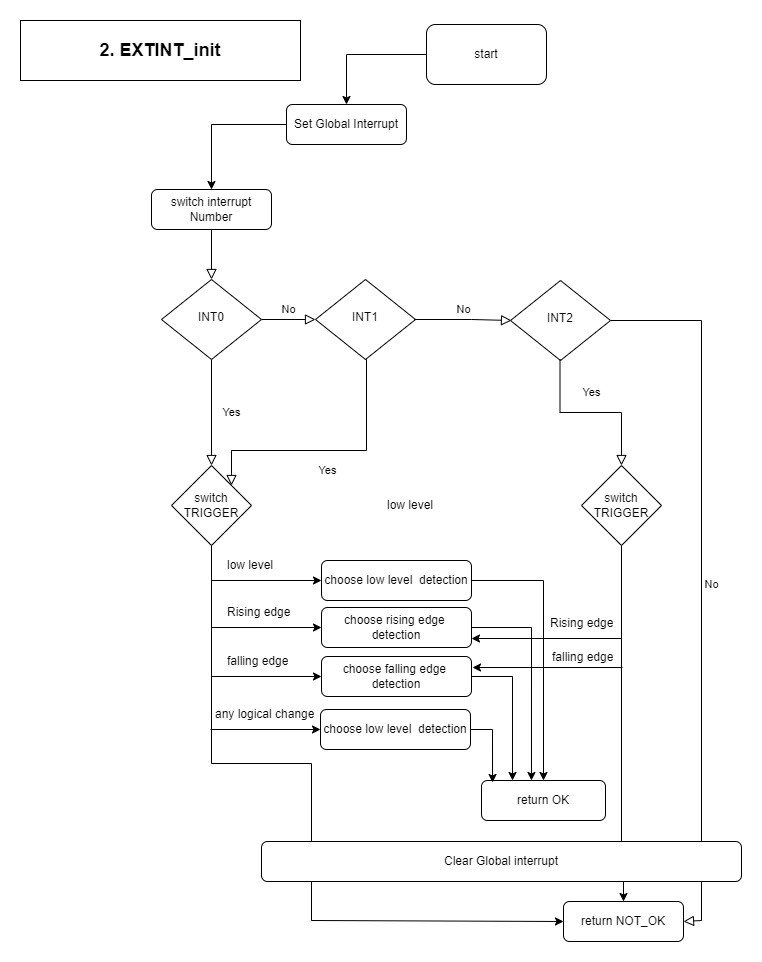
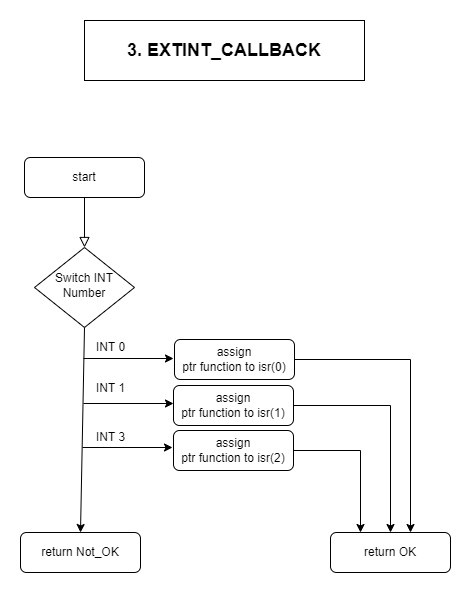


Figure 8 TIM0 remaining Flow Charts

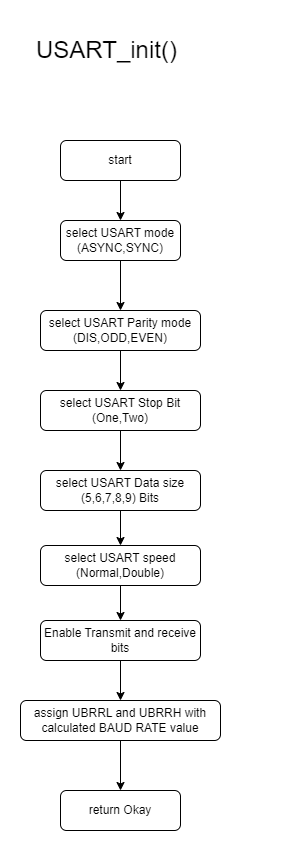
#### **EXTINT:**

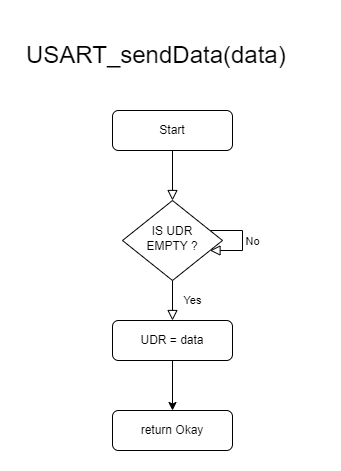
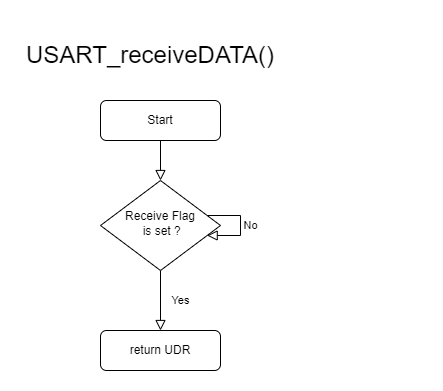


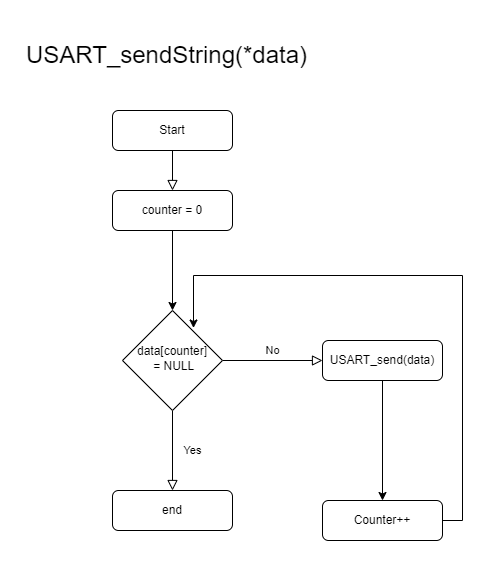
****

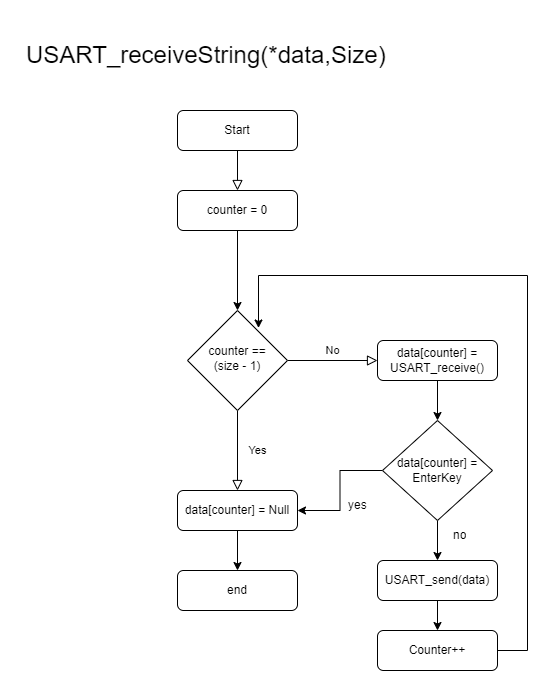
****

#### **UART:**

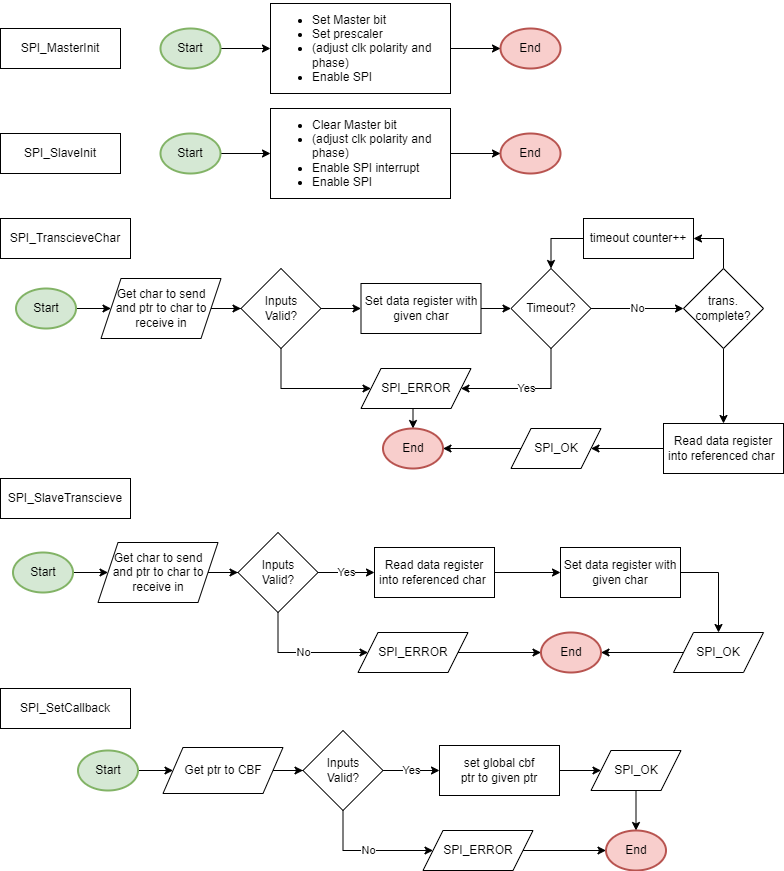






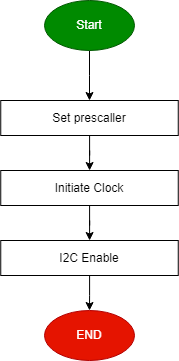


#### **SPI:**

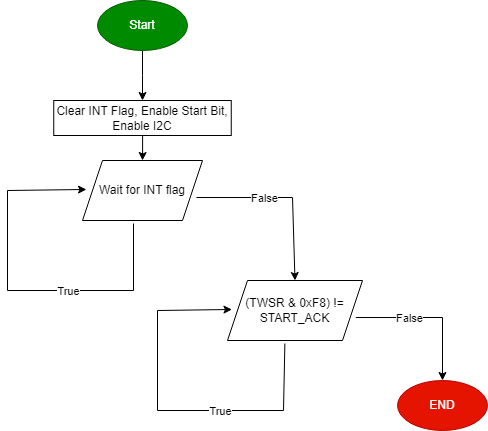


#### **I2C:**

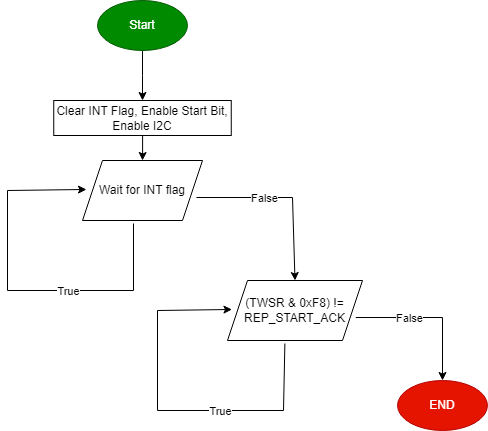
**void** **i2c\_init\_master**(**void**);



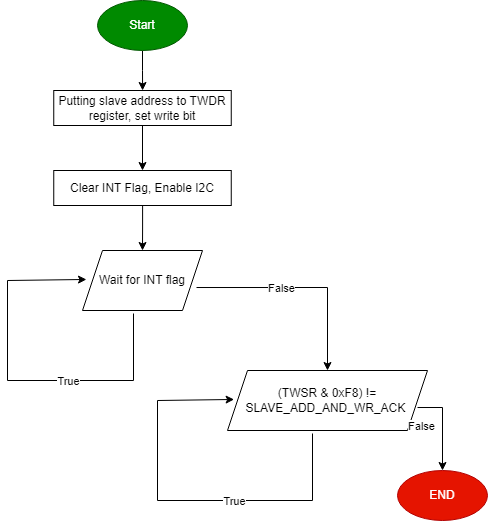
**void** **i2c\_start**(**void**);



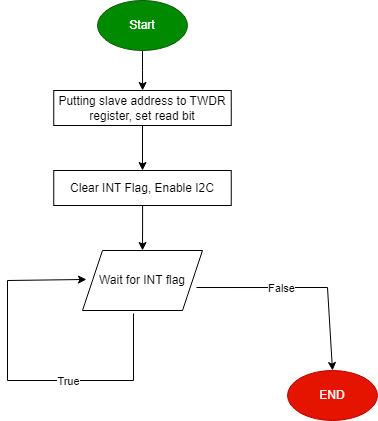
**void** **i2c\_repeated\_start**(**void**);



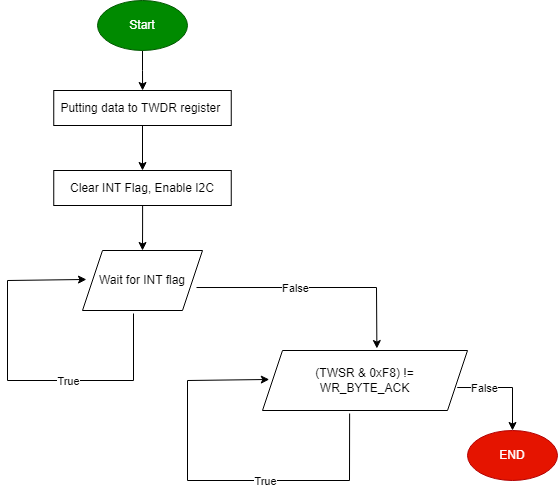
**void** **i2c\_send\_slave\_address\_with\_write\_req**(Uint8\_t slave\_address);



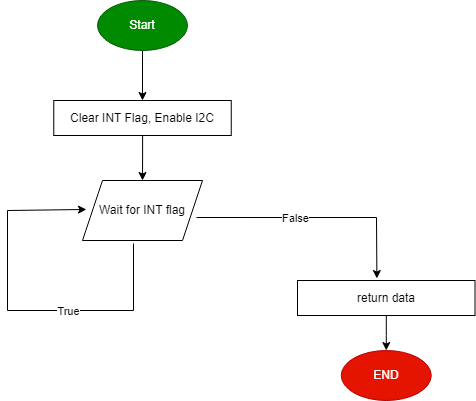
**void** **i2c\_send\_slave\_address\_with\_read\_req**(Uint8\_t slave\_address);



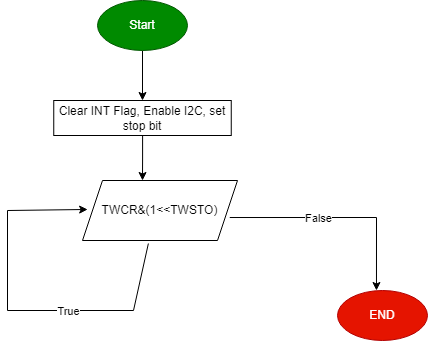
**void** **i2c\_write\_byte**(Uint8\_t byte);



Uint8\_t **i2c\_read\_byte**(**void**);



**void** **i2c\_stop**(**void**);

****

### **HAL Layer**

#### **HTimer0**

**HTIM0\_SyncDelay**

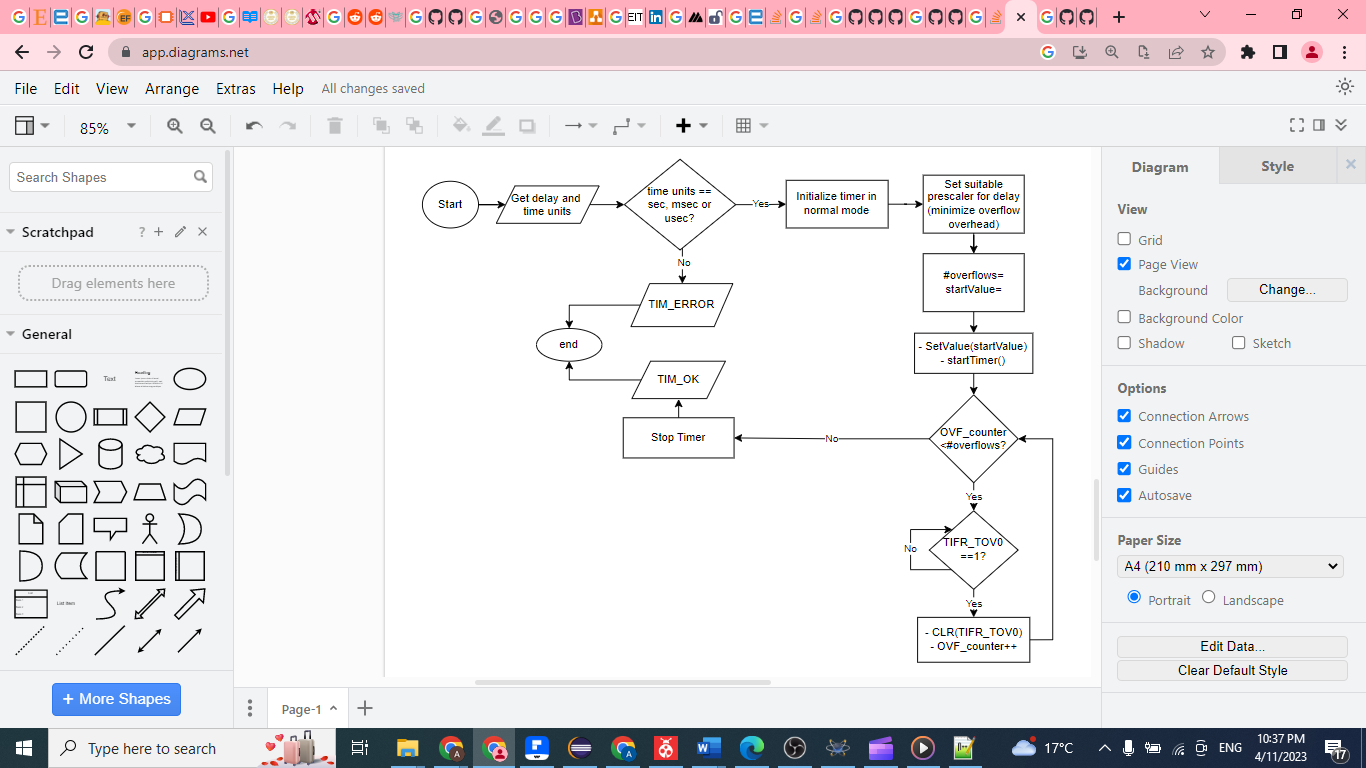


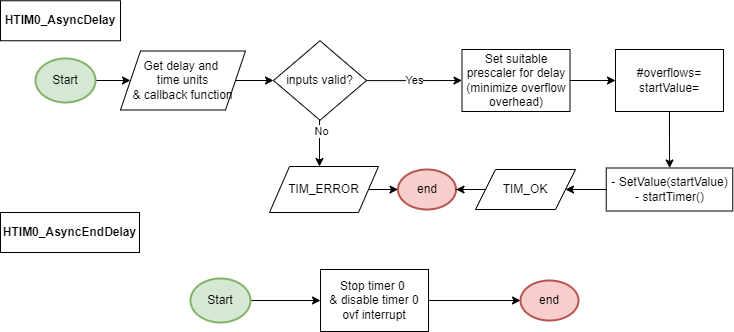
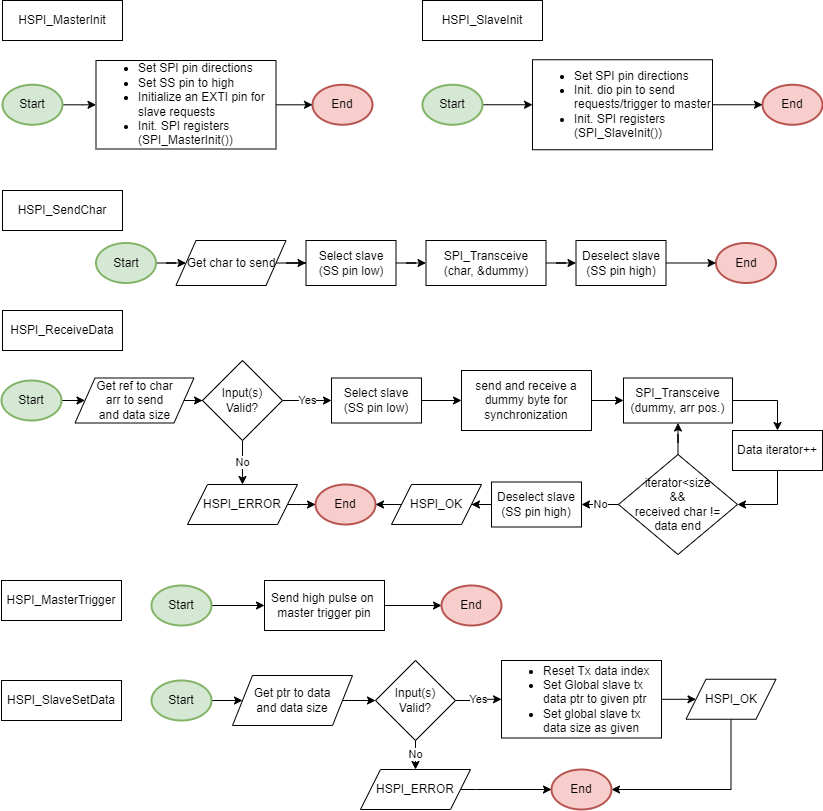
Figure 15 HTIM0\_SyncDelay Flow Chart

Figure 16 HTIM0\_AsyncDelay and EndDelay

#### **HSPI**



#### **LCD**

**void** **HLCD\_vidInit**(**void**)

Figure 17 HLCD\_vidInit Flow Chart

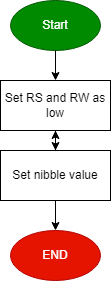
**void** **HLCD\_vidWritecmd**(Uint8\_t u8commandCopy)

Figure 18 HLCD\_vidWritecmd Flow Chart

**void** **HLCD\_vidWriteChar**(Uint8\_t u8CharCopy)

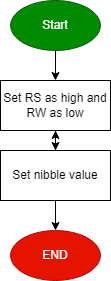
****

Figure 19 HLCD\_vidWriteChar Flow Chart

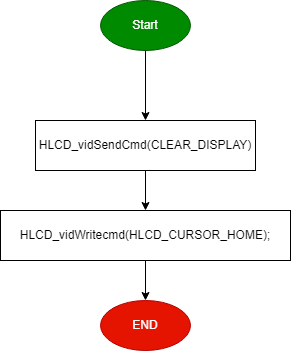
**void** **HLCD\_ClrDisplay**(**void**)

Figure 20 HLCD\_ClrDisplay Flow Chart

**void** **HLCD\_gotoXY**(Uint8\_t row, Uint8\_t pos)

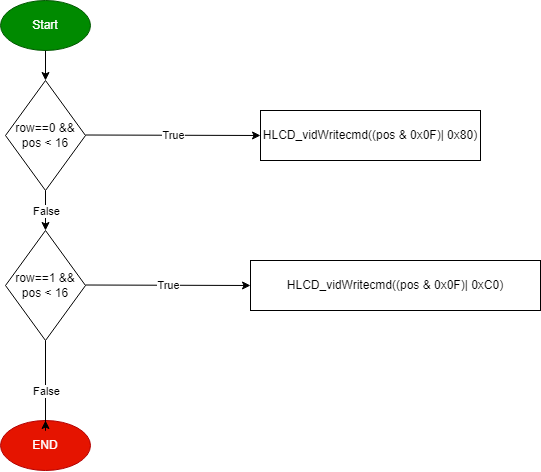
****

Figure 21 HLCD\_gotoXY Flow Chart

**void** **HLCD\_WriteString**(Uint8\_t\* str)

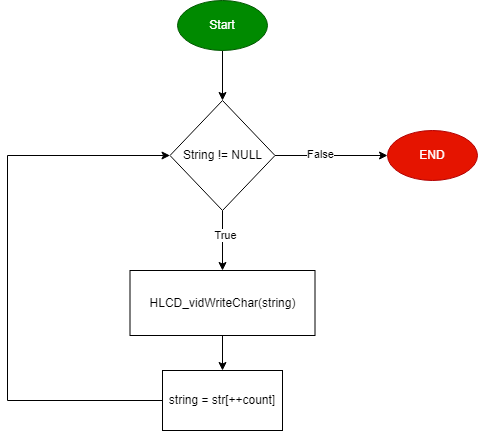
****

Figure 22 HLCD\_WriteString Flow Chart

**void** **HLCD\_WriteInt**(Uint32\_t number)

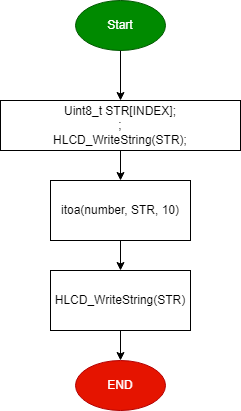
****

Figure 23 HLCD\_WriteInt Flow Chart

**void** **HLCD\_vidCreatCustomChar**(Uint8\_t\* pu8custom, Uint8\_t u8Location)

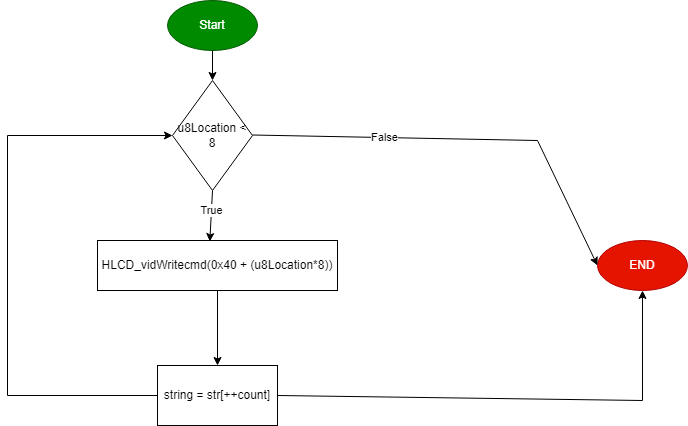
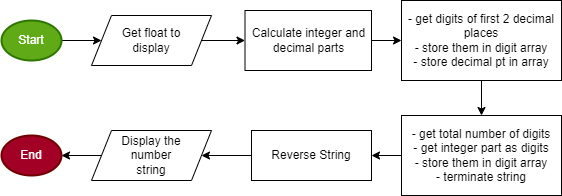
****

Figure 24 HLCD\_vidCreatCustomChar Flow Chart

void HLCD\_DisplayFloat(float32\_t f32\_a\_number);

#### **Keypad**

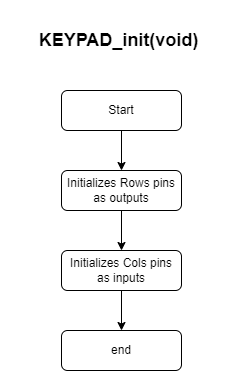


Figure 25 KEYPAD\_Init Flow Chart

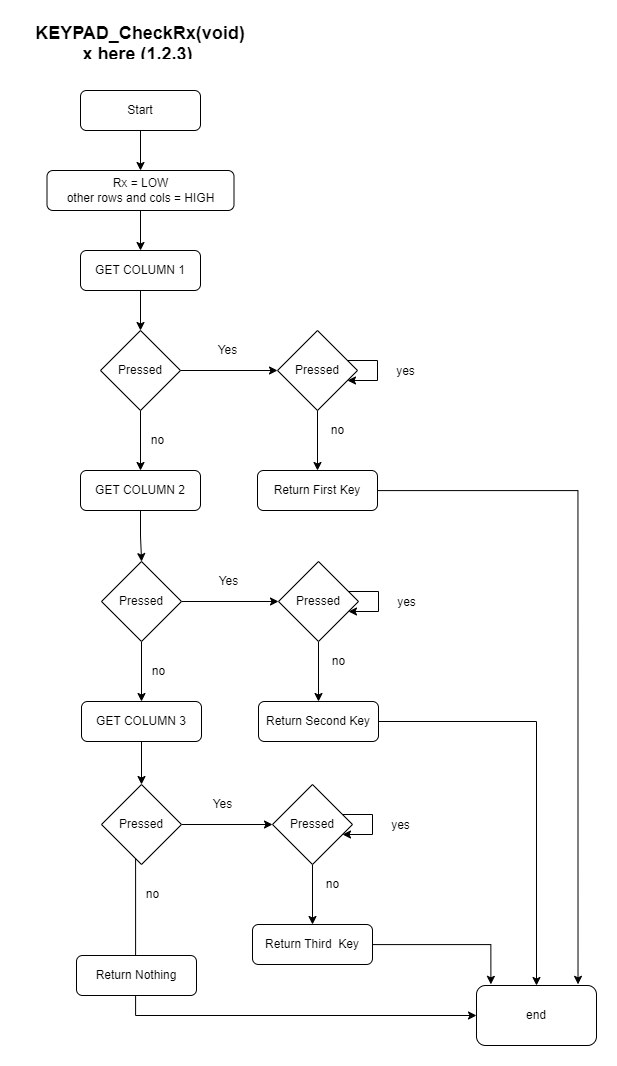


Figure 26 KEYPAD\_CheckRx Flow Chart

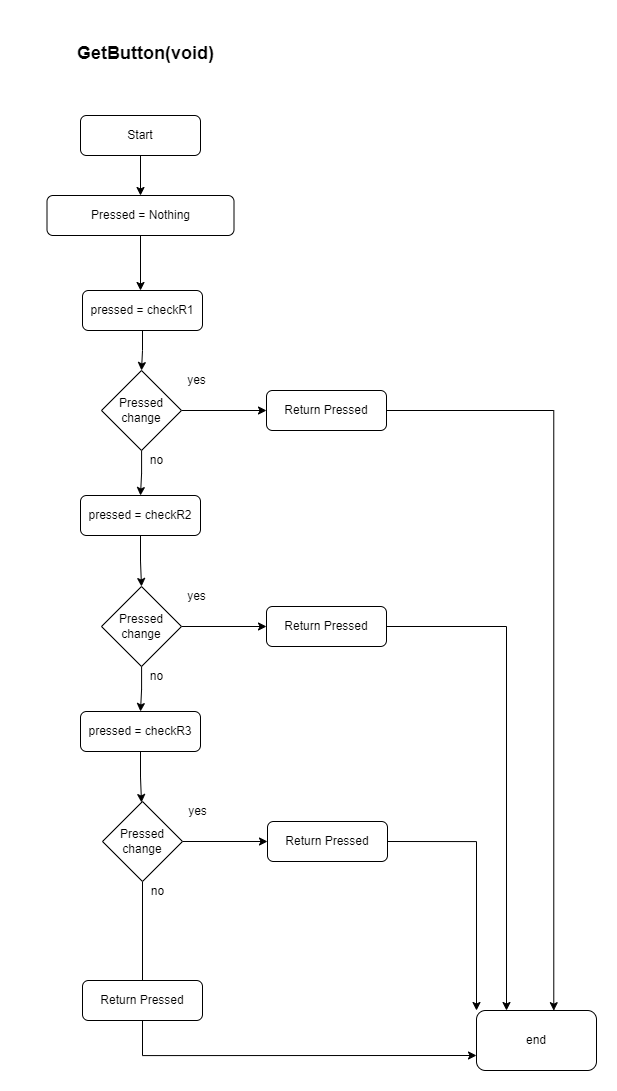
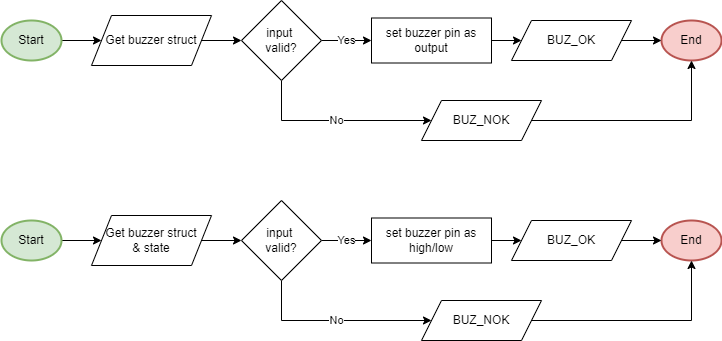


Figure 27 GetButton Flow Chart

#### **Buzzer**

****

**BUZ\_SetState**

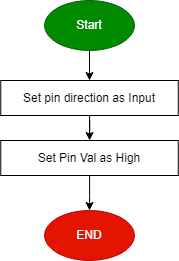
Figure 28 Buzzer Init & SetState Flow Charts

**BUZ\_Init**

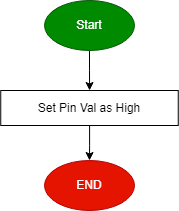
#### **HEXTINT:**

#### **Button:**

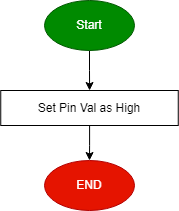
enu\_buttonError\_t **HButton\_Init**(enu\_pin en\_pinx);



enu\_buttonError\_t **HButton\_ExtIntInit**(enu\_pin en\_pinx);

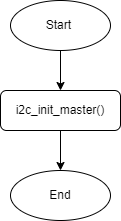


enu\_buttonError\_t **HButton\_getPinVal**(enu\_pin en\_pinx, Uint8\_t\* pu8\_refVal );

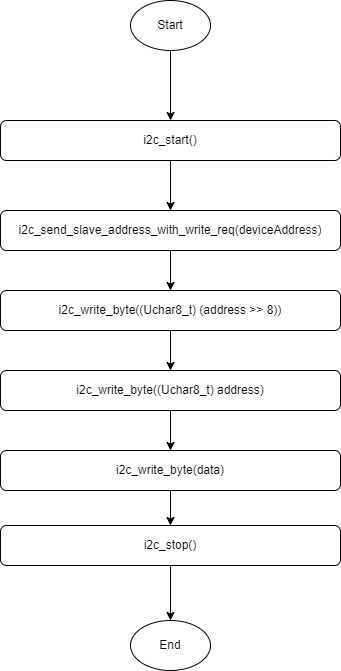
****

#### **EEPROM**

void eeprom\_init(void)



void eeprom\_write\_byte(Uint16\_t address, Uchar8\_t data)

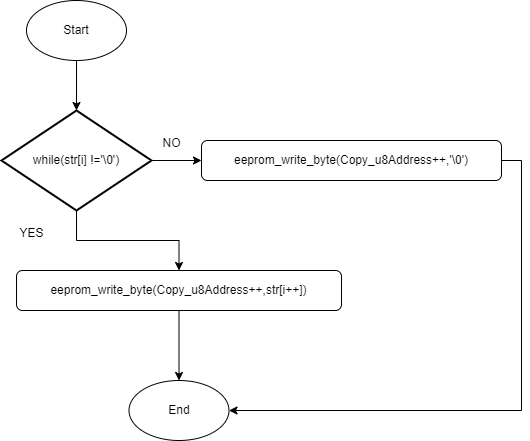


Uchar8\_t eeprom\_read\_byte(Uint16\_t address)

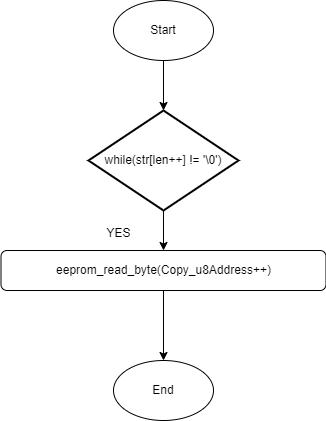
A picture containing diagram

Description automatically generated

void eeprom\_write\_string(Uint16\_t Copy\_u8Address, const Uchar8\_t\* str)

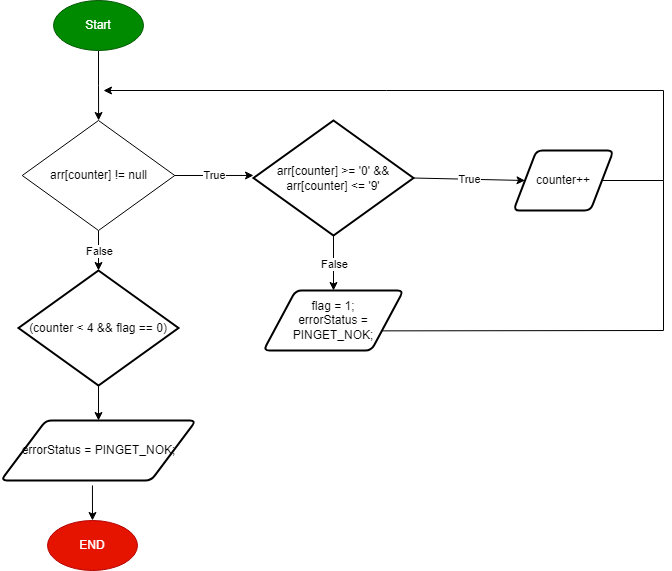


void eeprom\_read\_string(Uint16\_t Copy\_u8Address, Uchar8\_t\* str)

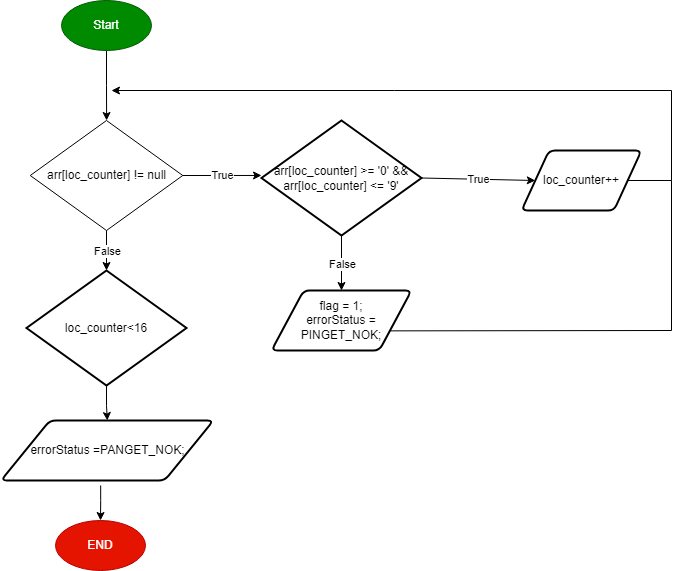


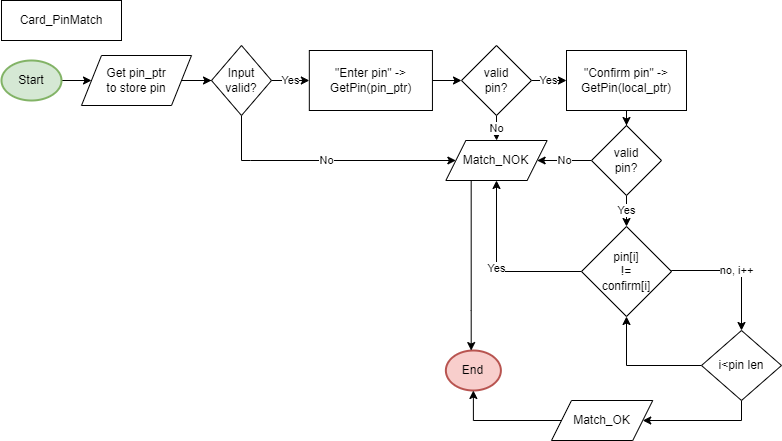
### **Card\_Database Layer (CARD MCU)**

en\_terminalPinGetStatus\_t **APP\_terminalPinGet**(Uchar8\_t\* arr);



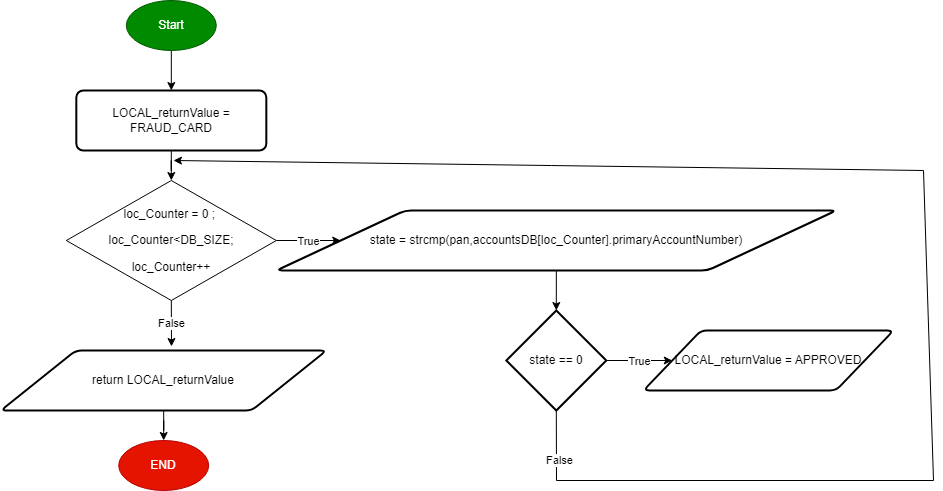
en\_terminalPanGetStatus\_t **APP\_terminalPanGet**(Uchar8\_t\* arr);

****

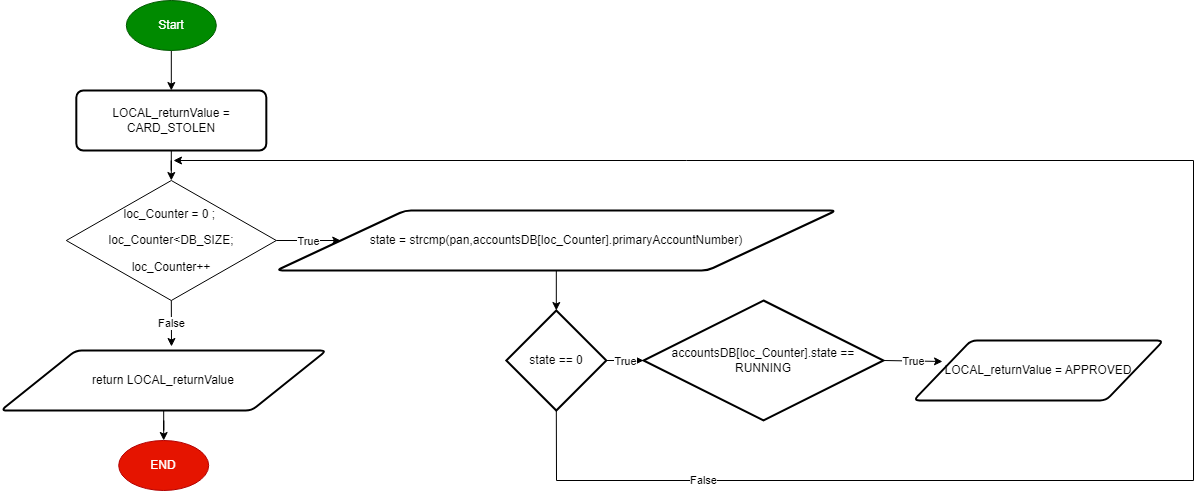


#### **Database\_check:**

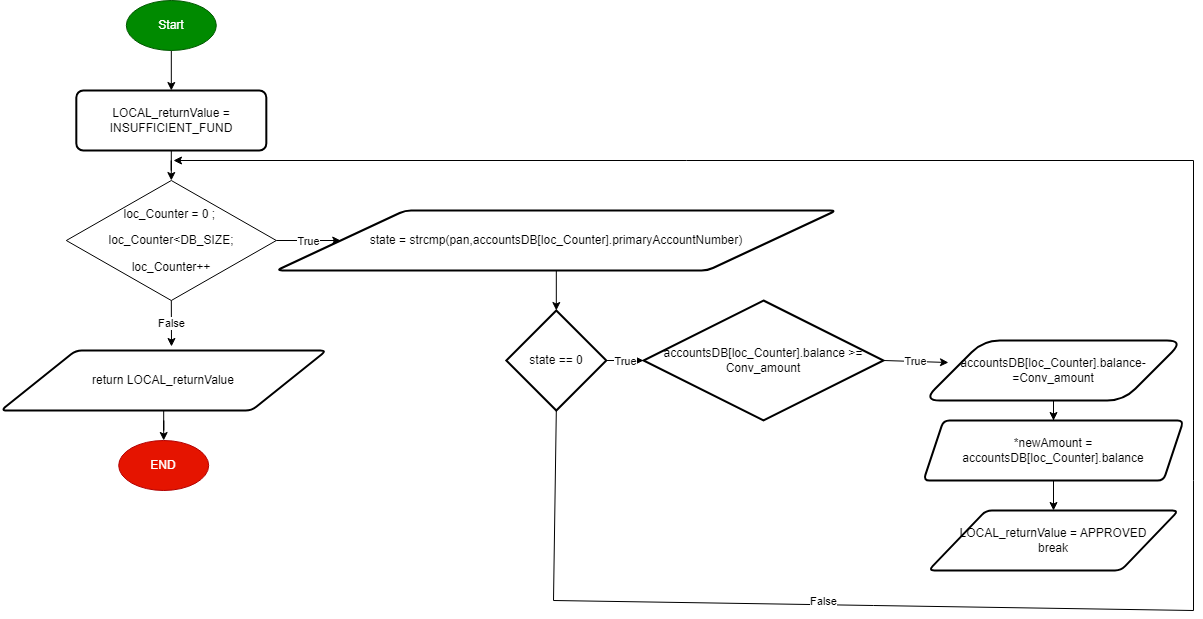
EN\_dataError\_t **isValidPanAccount**(Uchar8\_t \* pan);



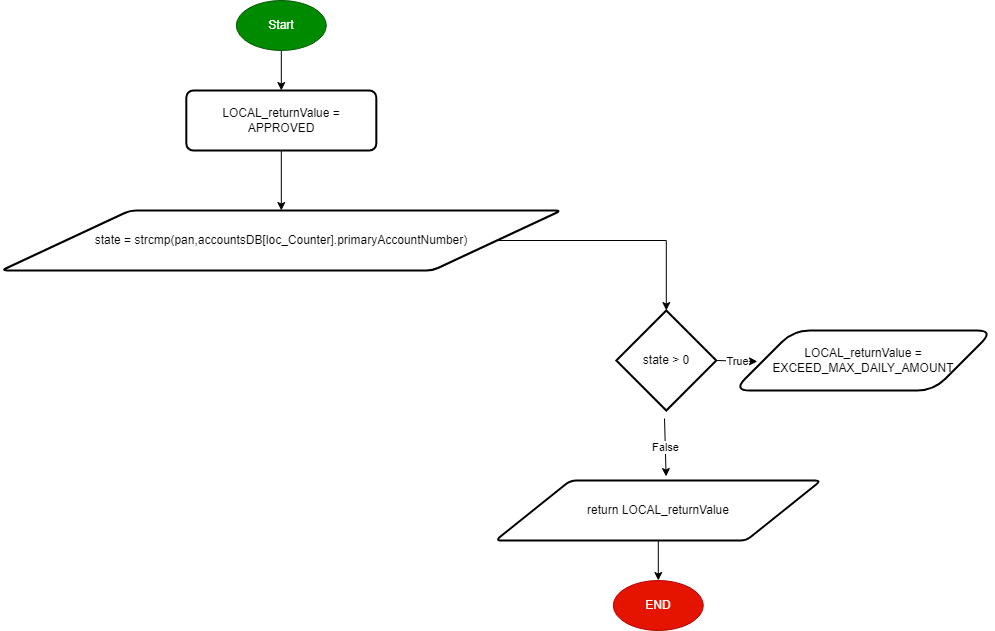
EN\_dataError\_t **isRunningAccount**(Uchar8\_t \* pan);

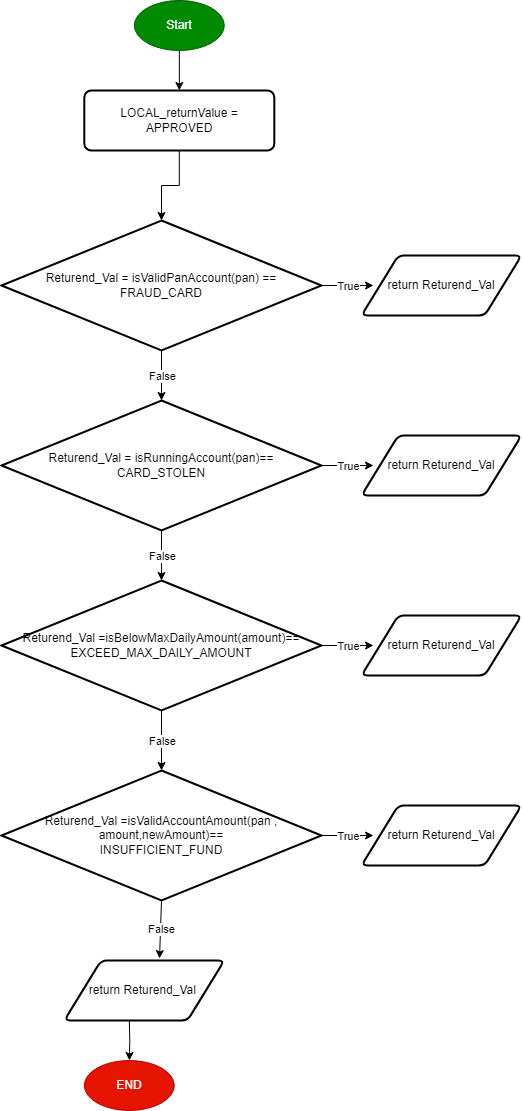


EN\_dataError\_t **isValidAccountAmount**(Uchar8\_t \* pan,Uchar8\_t \* amount,float32\_t \*newAmount);

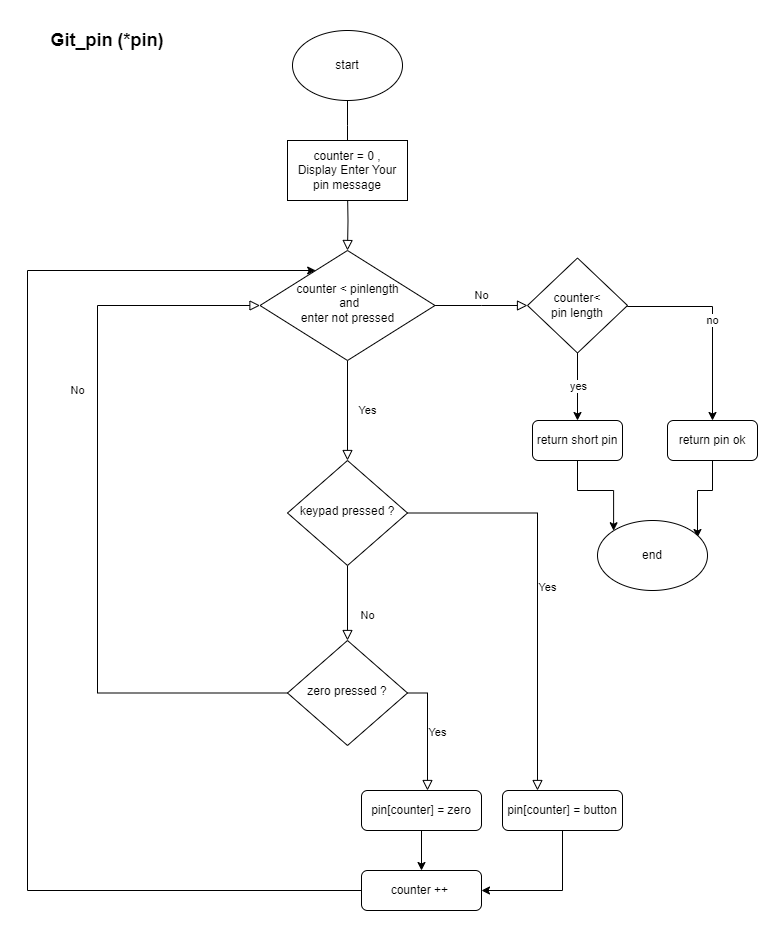


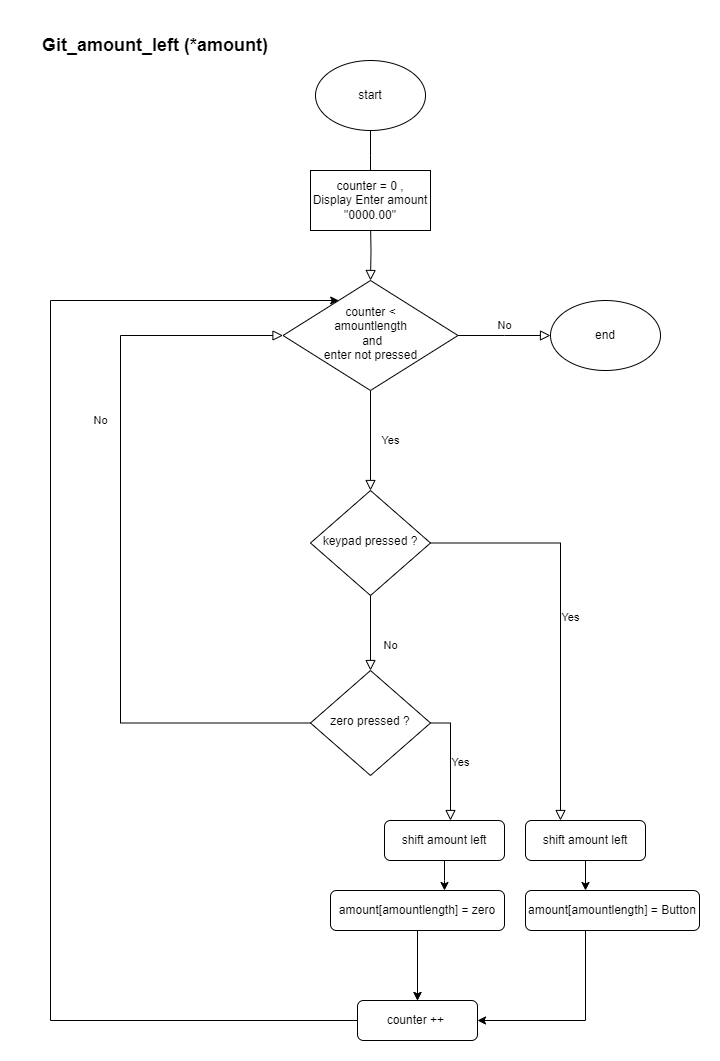
EN\_dataError\_t **isBelowMaxDailyAmount**(Uchar8\_t \* amount);

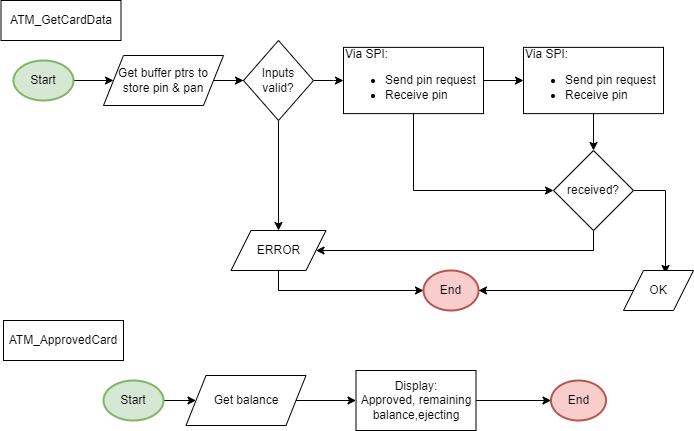


EN\_dataError\_t **DATABASE\_checking** (Uchar8\_t \* pan,Uchar8\_t \* amount,float32\_t \*newAmount);

#### **ATM Module**







### **Application Layer:**

### **Card App**

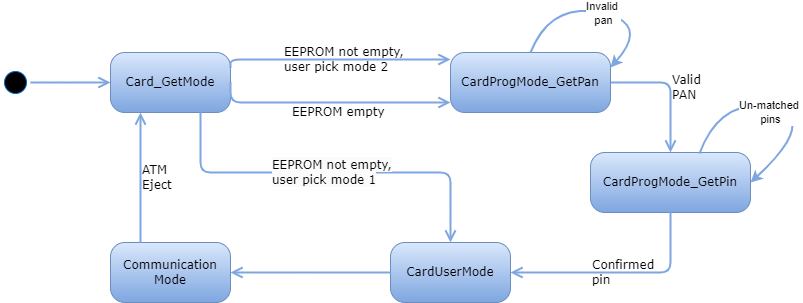


Figure 30 Card App. APIs Flow Charts

### **ATM App**

