

Synthesis

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1 Abstract

Here goes the abstract

2 Introduction

Musical instruments have been part of human culture and craft since prehistory, playing a part in both written and verbal art, ceremony and celebration [Rault, 2000]. This report describes an attempted recreation using digital synthesis of two acoustic musical instruments from the western European musical tradition: A mandolin and a flute. Acoustic musical instruments use an excited **physical part?** to generate waves which are manipulated and shaped by the body or of the musical instrument **NEEDS A TIED-IN CITATION**. The generation of these waves, and their manipulation by the body of the musical instrument can be modelled using a series of oscillators, filters and modulators. Audio synthesis using analog circuitry was explored as soon as simple oscillators were readily available, leading to early electronic musical instruments such as the theremin. In order to emulate the sound of musical instruments, first we must understand the mathematical nature of sound as a signal. Thus, this report will describe the programmatic mathematical analysis of the aforementioned two recordings. **Frequency modulation and additive synthesis methods are explored in this report.**

3 Theory

3.1 Signal processing, generation and analysis

Any periodic continuous signal can be broken down into an infinite sum of weighted sines and cosines [Weisstein, 2004]. A more generalised application of the Fourier series can be found in the Fourier transform, which in continuous time takes the form:

$$X(\omega) = \int_{-\infty}^{+\infty} x(t)e^{-j\omega t} dt \quad (1)$$

However, as digital audio works in the discrete time domain, the integrals can be represented as sums and the Fourier transform becomes:

$$X(\omega) = \sum_{-\infty}^{+\infty} x[n]e^{-j\omega t}dt \quad (2)$$

In the 1960s, J.W. Cooley and John Tukey developed an algorithm to efficiently compute the discrete Fourier transform [Cooley and Tukey, 1965]. This, and other discrete-time Fourier transform algorithms became known as the fast Fourier transform(s) (FFT). MATLAB's in-built FFT function uses a more modern FFT algorithm from the the FFTW library [Frigo and Johnson, 1998]. Using a Fourier transform, a complex sound can be broken down into it's frequency components. This allows the fundamental frequency and harmonics of the played note to be identified, due they will be the most prominent components of the frequency spectrum. However, the Fourier transform does not only show harmonic frequency content of a signal, it shows all frequency content of a signal. As such, any noise or other anharmonic frequency component, musical or not, will be shown on the transform. The simple inclusion of an observed frequency component may or may not be constructive to emulating the original played note.

Early musical synthesizers were constructed to facilitate additive synthesis techniques. This is where a series of oscillators generate basic waveforms such as sines, sawtooth and pulse waves; a sawtooth wave can be seen in Figure 1.

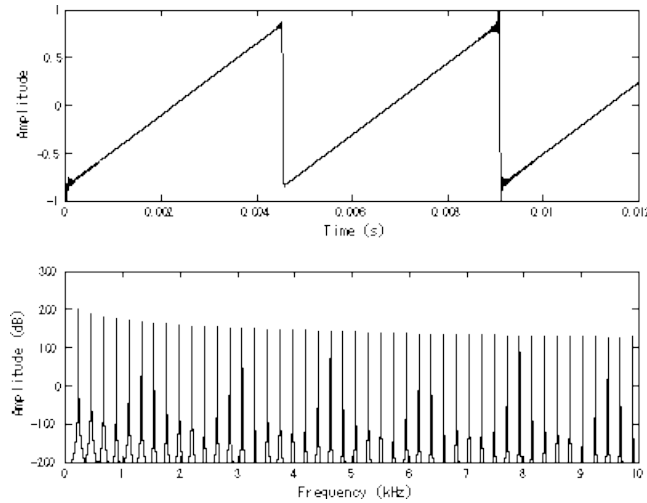


Figure 1: Waveform and frequency response of a sawtooth wave.
[Kraft and Zölzer, 2017]

These oscillators may be used to generate sound, or used as modulators to other oscillators's outputs. Different waveforms generated by these oscillators

have different harmonic content. For example: in Figure 1 a sawtooth wave is shown as having many harmonics in the frequency domain plot. In fact, a sawtooth wave contains all harmonics, both even and odd, of a fundamental tone [Roederer, 1995]. In the 1970s, FM synthesis was beginning to take form as a method of musical instrument emulation, especially after Chowning’s work outlined specific FM techniques for the emulation of various instruments [Chowning, 1973]. Products such as the Yamaha DX7 helped to popularise FM synthesis into the 1980s.

3.2 Musical instruments

4 Methodology

4.1 Analysis

4.1.1 Mandolin

All code written for this report was executed in MATLAB. First, the sample values and sampling rates of the recordings were imported into MATLAB as a vector and constant, respectively. Using the sampling rate and total number of samples, a vector of time data was created. This allowed the sample values to be plotted against time, as seen in Figure 2.

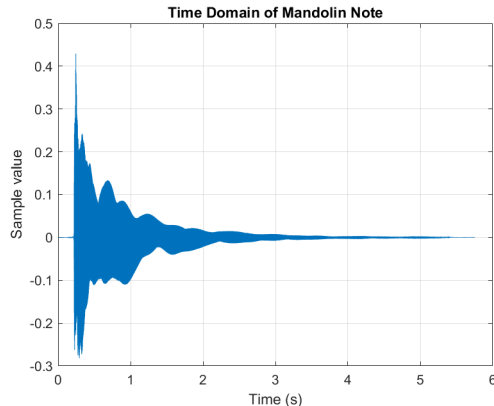


Figure 2: Mandolin sample value over time.

Next, analysis of the signal in the frequency domain was performed. Using MATLAB’s in-built FFT function, a frequency domain plot of the signal, averaged over time, was plotted. This data was supplemented with another frequency domain plot using `pwelch()`, a function that uses the Welch algorithm to obtain power spectral density as a function of frequency, instead of sample magnitude [Solomon Jr, 1991]. A plot of the frequency and phase responses generated by `pwelch` are shown in Figure 4. The frequency amplitude information gathered

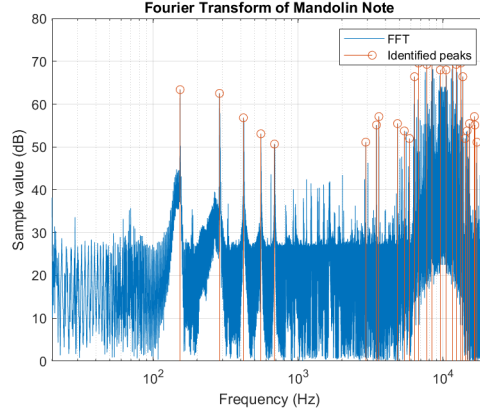


Figure 3: Mandolin sample value over time.

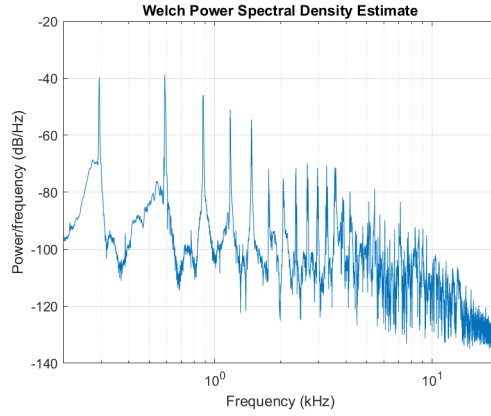


Figure 4: Mandolin sample value over time.

from the Fourier transform and Welch power spectral density estimate is averaged over the entire duration of the signal. While this information is very useful, it is limited: Much of the frequency content of a signal varies in time, and this time-varying nature of the frequency response contributes greatly to the To see the amplitudes of each frequency component as a function of time, a spectrogram was used.

MATLAB's `spectrogram()` function has a high degree of operability and can take many arguments. The function works using a Used as a standalone function, it gives the user a two dimensional graph of frequency versus time, with frequency amplitude as a third, coloured dimension. There is a trade-off between resolution in the frequency and time domains when using this spectrogram function. Higher resolution in the time domain allows for a more visually understandable spectrogram when using a waterfall plot. If a high frequency-

domain resolution is used, a waterfall plot becomes cluttered and hard to read, as shown. Using a hamming window with length $n = 2560$, a 2650-point spectrogram was computed and plotted on a waterfall graph, shown in Figure 6.

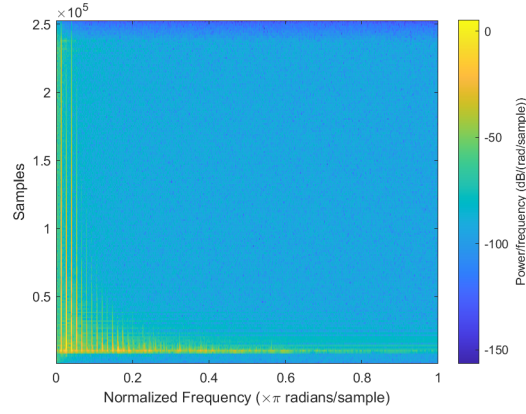


Figure 5: Mandolin sample value over time.

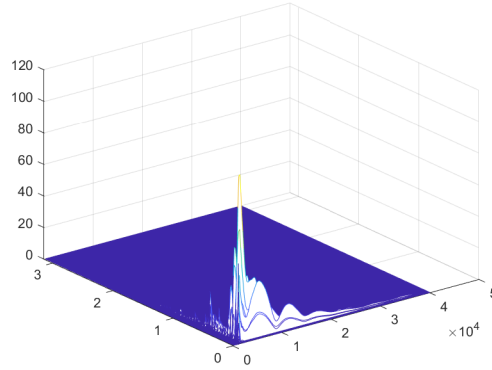


Figure 6: Mandolin sample value over time.

4.1.2 Flute

4.2 Synthesis

4.2.1 Additive Synthesis

Additive synthesis follows the intuition found in Fourier analysis: Any continuous signal is a sum of an infinite number of sine waves. Thus, it should

be possible to recreate any given signal by breaking it down into its frequency components, and reproducing these frequency components as sinusoids weighted according to the frequency domain of the analysed signal. A programmatic approach was taken in MATLAB: A fourier transform of the recorded signal would return a set of data that may be parsed to find the frequencies of the dominant harmonics of the Mandolin. This was implemented by feeding the result of the fourier transform into MATLAB's `findpeaks()` function, which allows the user to define arguments as to the minimum height and prominence of maxima within a set of data, these maxima would be the harmonics. Using `findpeaks()` required some trial and error adjusting function arguments to avoid less useful peaks within the Fourier transform. The found frequencies and their amplitudes would then be substituted into a looping summation of generic sine wave formulae, to produce the output: a complex signal with a similar frequency response to the input; importantly with the same harmonics. This formula is shown in Eq.3.

$$y[t] = \sum_{n=1}^N A_n \sin(2\pi f_n t), \text{ where: } n = \text{harmonic number} \quad (3)$$

This produced a signal which contained similar frequency-domain characteristics as the Mandolin recording, but had no amplitude envelope. Thus when played using MATLAB's `sound()` function, the synthesised sound was missing the characteristic plucked attack of a Mandolin. To compensate for this, an amplitude envelope was extrapolated from the recorded signal using MATLAB's `env()` function. When passing only the sample value vector to `env()` a vector of the absolute value of the sample values is returned. This is problematic; the sharp changes in amplitude, as shown in Fig.7, will result in additional high-frequency components being added to the signal when the envelope is applied to the synthesized sound. Passing an `'rms'` argument to `env()` gave a smoother

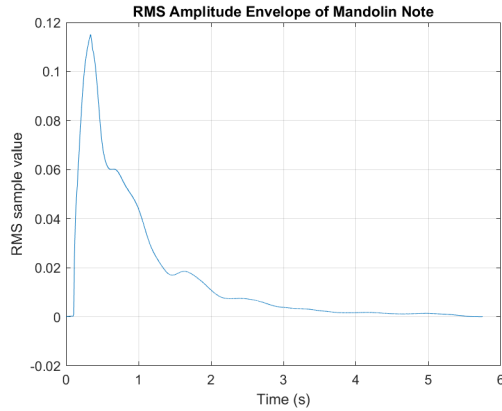


Figure 7: Envelope reflecting the absolute value of each sample.

envelope than simply taking the absolute value of the time-domain waveform,

this addressed the aforementioned problems with using an absolute envelope. This new envelope is seen superimposed in Fig.7. To apply the envelope, simply multiplying it with the synthesized signal was sufficient. Figure 8 shows the envelope applied to the synthesized signal. Comparing to Fig.2, we can see a similarity in the time-domain.

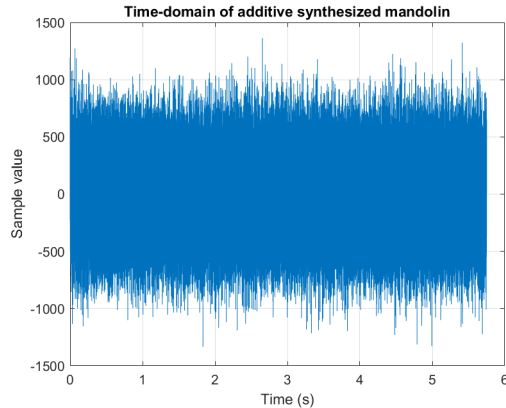


Figure 8: Time-domain of the synthesized signal with envelope applied.

Whilst the spectrograms shown in Figures 5 and 6 were useful in illustrating and conveying the amplitude envelopes of a large amount of frequencies across the recording’s spectrum, the additive synthesis method chosen chooses to reproduce only a specific few of the harmonic components of the recorded signal. Thus, a new spectrogram function will have to be computed targeting the harmonics identified with `findpeaks()`. MATLAB’s spectrogram function thankfully allows for an argument to define target frequencies, so after passing the frequency vector extrapolated from `findpeaks()`, a two-dimensional array of amplitude envelopes for each identified frequency was generated. This spectrogram can be seen in Figs.9 & 10.

4.2.2 Frequency Modulation Synthesis

To emulate the recorded flute, frequency modulation (FM) synthesis was used. FM synthesis generates signals with rich harmonic content using only two waveforms, as opposed to the theoretically limitless number of oscillators typically used in additive synthesis. Instead of summing the oscillators as in additive synthesis, the two oscillators are multiplied. The two waves are referred to as the “carrier” and the “modulator” Chowning elaborates on the relationship between the two waves: “In FM the instantaneous frequency of a carrier wave is varied according to a modulating wave, or modulating frequency” [Chowning, 1973].

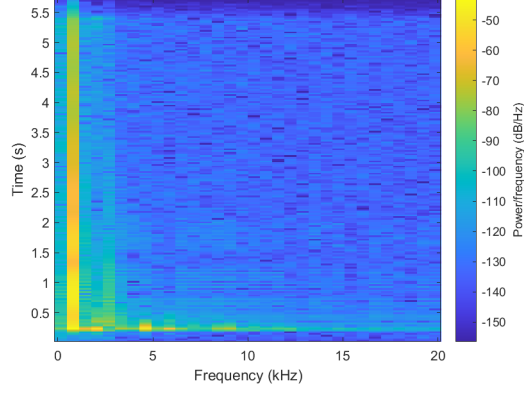


Figure 9: Mandolin sample value over time.

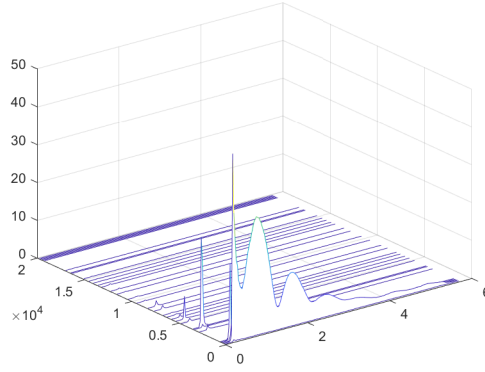


Figure 10: Mandolin sample value over time.

This is reflected in the general equation for FM synthesis:

$$y(t) = A \sin(\omega_c t + I \sin \omega_m)$$

Where:

A = Amplitude coefficient (4)

ω_c = angular frequency of carrier

ω_m = angular frequency of modulator

I = modulation index

Returning to Chowning's paper, parameter sets and methods for use of the above equation targeting the sound of certain instruments are given. Chowning states that a woodwind sound may be achieved: By setting the carrier frequency

to be an integral multiple of the modulating frequency, or by making the index function inversely proportional to the amplitude function.”

5 Discussion and Conclusions

6 Appendix

6.1 Code

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