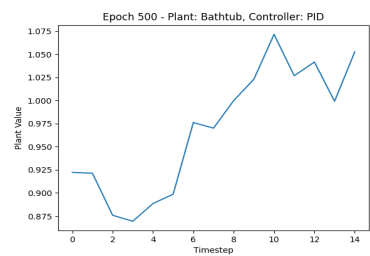
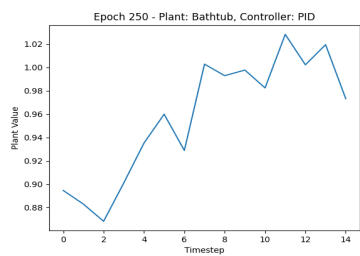
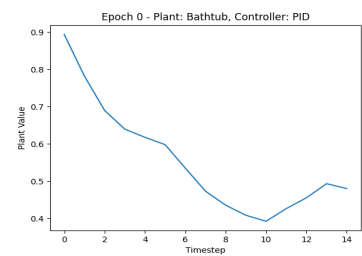
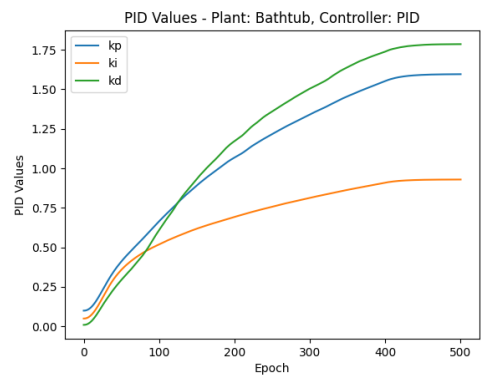
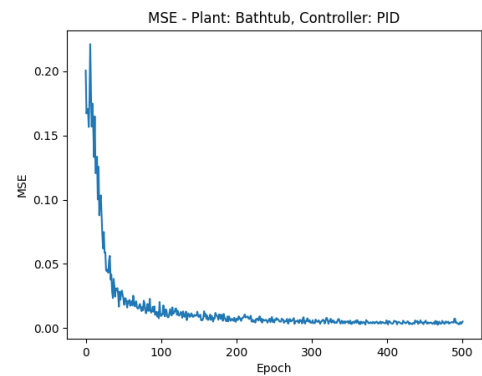


# Report for Plant: Bathtub, Controller: PID

## Configuration Parameters:

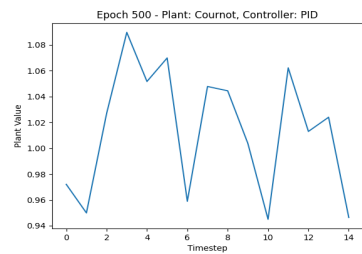
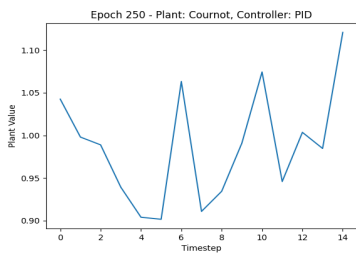
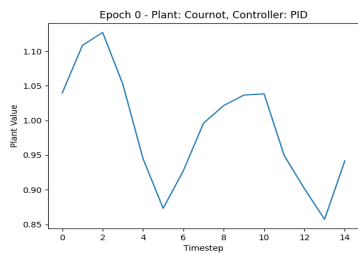
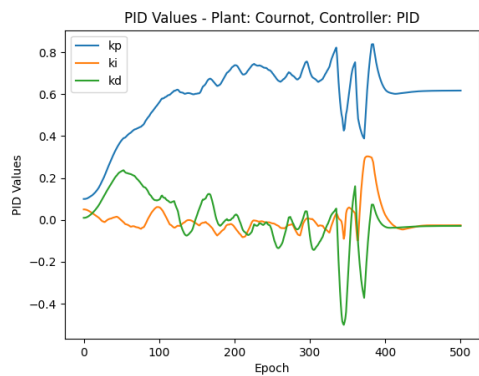
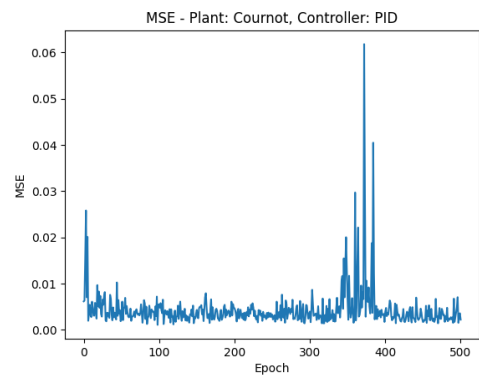
Plant: Bathtub  
Controller: PID  
Target Value: 1.0  
Epochs: 501  
Timesteps: 15  
Learning Rate: 0.05  
Warmup Time: 0.2  
Cooldown Time: 0.2  
Noise Range: 0.2  
Bathtub: Cross-sectional Area (A): 5.0  
Bathtub: Drain Area (C): 0.1  
Bathtub: Initial Height (H\_init): 1.0  
Bathtub: Gravitational Constant (g): 9.81  
PID: kp\_init: 0.1  
PID: ki\_init: 0.05  
PID: kd\_init: 0.01



# Report for Plant: Cournot, Controller: PID

## Configuration Parameters:

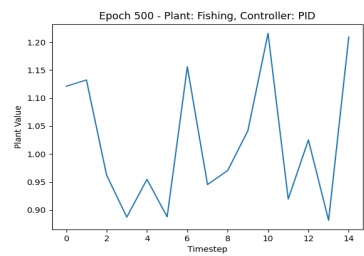
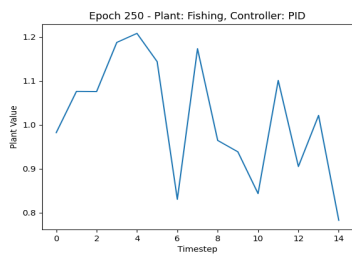
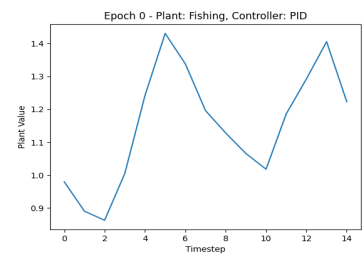
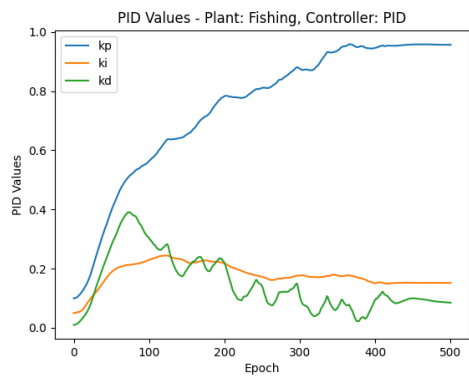
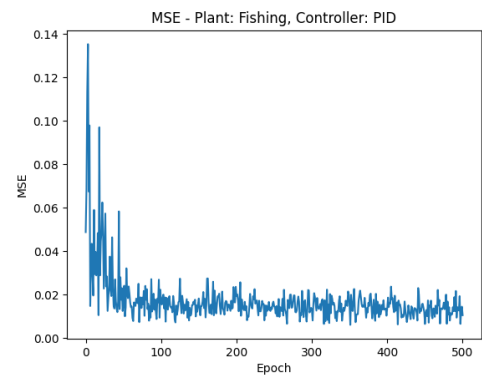
Plant: Cournot  
Controller: PID  
Target Value: 1.0  
Epochs: 501  
Timesteps: 15  
Learning Rate: 0.05  
Warmup Time: 0.2  
Cooldown Time: 0.2  
Noise Range: 0.2  
Cournot: Maximum Price ( $P_{\max}$ ): 3.0  
Cournot: Marginal Cost ( $C_m$ ): 0.01  
Cournot: Initial Production  $q_1$ : 0.5  
Cournot: Initial Production  $q_2$ : 0.5  
PID:  $k_p$ \_init: 0.1  
PID:  $k_i$ \_init: 0.05  
PID:  $k_d$ \_init: 0.01



# Report for Plant: Fishing, Controller: PID

## Configuration Parameters:

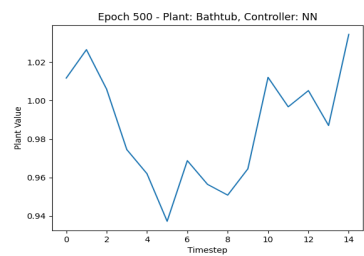
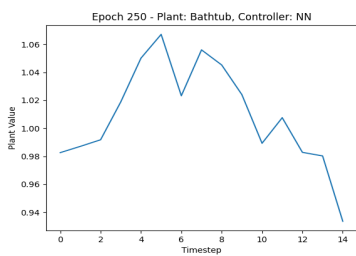
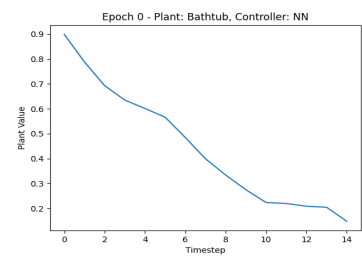
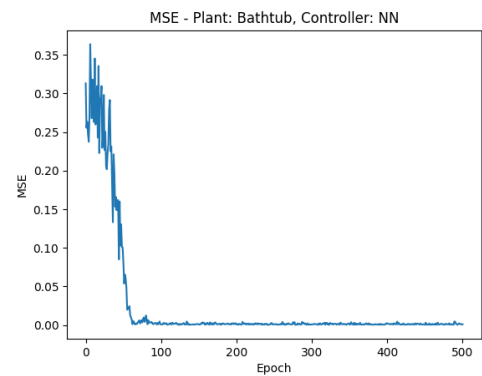
Plant: Fishing  
Controller: PID  
Target Value: 1.0  
Epochs: 501  
Timesteps: 15  
Learning Rate: 0.05  
Warmup Time: 0.2  
Cooldown Time: 0.2  
Noise Range: 0.2  
Fishing: Initial Fish Population ( $F_{init}$ ): 1.0  
Fishing: Growth Rate ( $r$ ): 0.1  
Fishing: Carrying Capacity ( $N$ ): 3.0  
PID:  $k_p$ \_init: 0.1  
PID:  $k_i$ \_init: 0.05  
PID:  $k_d$ \_init: 0.01



# Report for Plant: Bathtub, Controller: NN

## Configuration Parameters:

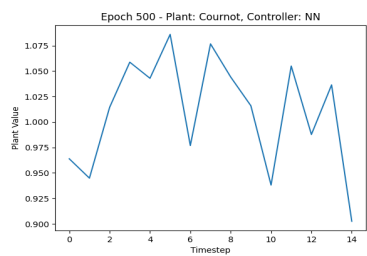
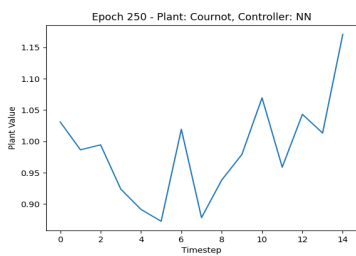
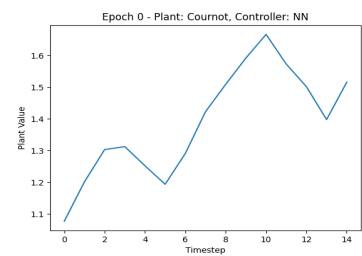
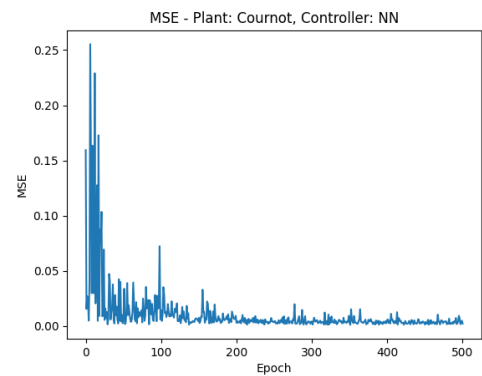
Plant: Bathtub  
Controller: NN  
Target Value: 1.0  
Epochs: 501  
Timesteps: 15  
Learning Rate: 0.005  
Warmup Time: 0.2  
Cooldown Time: 0.2  
Noise Range: 0.2  
Bathtub: Cross-sectional Area (A): 5.0  
Bathtub: Drain Area (C): 0.1  
Bathtub: Initial Height (H\_init): 1.0  
Bathtub: Gravitational Constant (g): 9.81  
NN: Hidden Layer Sizes: [5, 5, 5]  
NN: Init Range: 0.1  
NN: Activation Function: relu



# Report for Plant: Cournot, Controller: NN

## Configuration Parameters:

Plant: Cournot  
Controller: NN  
Target Value: 1.0  
Epochs: 501  
Timesteps: 15  
Learning Rate: 0.005  
Warmup Time: 0.2  
Cooldown Time: 0.2  
Noise Range: 0.2  
Cournot: Maximum Price ( $P_{\max}$ ): 3.0  
Cournot: Marginal Cost ( $C_m$ ): 0.01  
Cournot: Initial Production  $q_1$ : 0.5  
Cournot: Initial Production  $q_2$ : 0.5  
NN: Hidden Layer Sizes: [5, 5, 5]  
NN: Init Range: 0.1  
NN: Activation Function: relu



# Report for Plant: Fishing, Controller: NN

## Configuration Parameters:

Plant: Fishing  
Controller: NN  
Target Value: 1.0  
Epochs: 501  
Timesteps: 15  
Learning Rate: 0.005  
Warmup Time: 0.2  
Cooldown Time: 0.2  
Noise Range: 0.2  
Fishing: Initial Fish Population ( $F_{init}$ ): 1.0  
Fishing: Growth Rate ( $r$ ): 0.1  
Fishing: Carrying Capacity ( $N$ ): 3.0  
NN: Hidden Layer Sizes: [5, 5, 5]  
NN: Init Range: 0.1  
NN: Activation Function: relu

