

## ROS Stack Management

We have been utilizing ROS stacks to manage our individual ROS packages. We will try to use a single package per node. This will encourage appropriate message passing between nodes and make sure they are not too tightly coupled.

Stacks utilize a `stack.xml` file which contains dependencies to be included for every package. The ROS stack will automatically build all packages within it's root directory.

Complete documentation can be found at [ROSWiki](#).