# EE200: Signals, Systems and Networks

Practical Report 1: Frequency Mixer

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## Contents

1	Introduction	2
2	Governing Equations: 2D Fourier Transform	2
3	Analysis of an Input Image 3.1 Spectrum Analysis and Centering	
4	The Frequency Mixer System 4.1 System Design and Transfer Functions	
5	Conclusion	5
A	Final Python Code	5

#### 1 Introduction

The human visual system (HVS) does not process an image uniformly; instead, it performs multi-scale analysis, instinctively separating coarse structure from fine details. This project explores this concept by treating images as 2D signals and manipulating them in the frequency domain. The core objective is to design and implement a "frequency mixer," a system that fuses two distinct images into a single, perceptually interesting hybrid. This is achieved by combining the low-frequency components of one image, which represent the overall structure and shape, with the high-frequency components of another, which represent the fine textures and edges. The final result is an image that can be perceived differently depending on viewing distance, directly demonstrating the link between spatial frequency and visual perception.

### 2 Governing Equations: 2D Fourier Transform

To analyze an image's frequency content, we utilize the 2D Discrete Fourier Transform (DFT). The DFT is a mathematical tool that decomposes a signal from its original domain (in this case, the spatial domain) into its constituent frequencies. For an image, I(x,y), the spatial coordinates (x,y) define the pixel locations. The DFT transforms this into a frequency domain representation, F(u,v), where (u,v) represent the horizontal and vertical spatial frequencies.

**2D Discrete Fourier Transform (DFT):** For an N x M image I(x, y), the 2D DFT, which transforms the image from the spatial domain to the frequency domain, is defined as:

$$F(u,v) = \sum_{x=0}^{N-1} \sum_{y=0}^{M-1} I(x,y) e^{-j2\pi(\frac{ux}{N} + \frac{vy}{M})}$$
 (1)

where F(u, v) is the complex value of the frequency component (u, v). This equation calculates the presence and phase of each frequency component (u, v) within the original image I(x, y).

**2D Inverse DFT (IDFT):** To reconstruct the image from its frequency representation, the Inverse DFT is used:

$$I(x,y) = \frac{1}{NM} \sum_{u=0}^{N-1} \sum_{v=0}^{M-1} F(u,v) e^{j2\pi(\frac{ux}{N} + \frac{vy}{M})}$$
 (2)

This equation reconstructs the original image by summing all its frequency components, each weighted by its complex magnitude from F(u, v).

## 3 Analysis of an Input Image

An initial analysis was performed on a single input image (the dog) to understand its spectral properties.

#### 3.1 Spectrum Analysis and Centering

The 2D DFT of the image was calculated and its magnitude spectrum was plotted in normal (log scaled for visibility) and decibel (dB) form, as shown in Figure 1.

**Spectrum Centering:** The raw output of the DFT algorithm places the zero-frequency component (DC value), which represents the average brightness of the entire image, at the **top-left corner (index [0,0])**. As a result, the other low-frequency components are located at the four corners of the spectrum image, which is not intuitive for analysis. To correct this, the

scipy.fft.fftshift function was used. This function swaps the quadrants of the spectrum, moving the low frequencies to the center and the high frequencies to the outer regions. This centered representation is standard practice, as it provides a clear visual map where the bright central area corresponds to the dominant, low-frequency structural components of the image, and the dimmer outer areas correspond to the high-frequency details and edges.

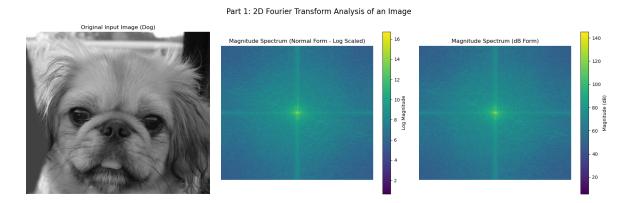


Figure 1: Analysis of the dog image's Fourier magnitude spectrum.

#### 3.2 Effect of Image Rotation

The input image was rotated 90 degrees anticlockwise to observe the corresponding effect in the frequency domain.

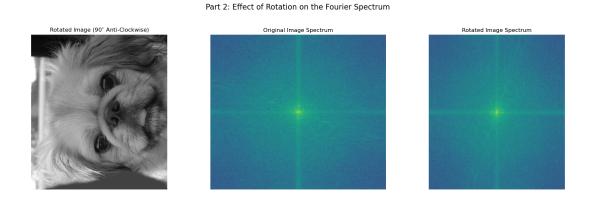


Figure 2: Comparison of the original spectrum and the spectrum of the rotated image.

**Observation:** As demonstrated in Figure 2, a 90 degree rotation of the image in the spatial domain results in an identical 90-degree rotation of its magnitude spectrum in the frequency domain. This result visually confirms the **rotation property of the 2D Fourier Transform**, where a rotation in the spatial domain corresponds directly to an equivalent rotation in the frequency domain.

## 4 The Frequency Mixer System

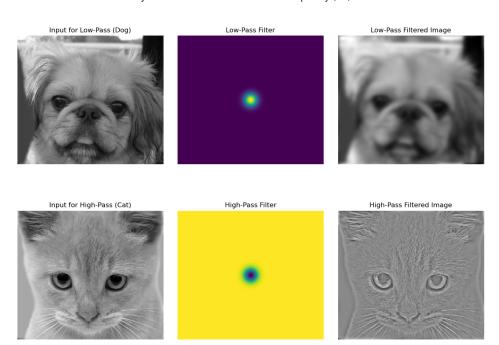
A system was designed to fuse the two input images. The low-frequency structural information from the dog image was combined with the high-frequency detail information from the cat image.

#### 4.1 System Design and Transfer Functions

The system operates by filtering each image in the frequency domain. These filters act as the system's **transfer functions**, dictating which frequencies are passed and which are attenuated for each input signal. A specific cutoff frequency of 13 was chosen as the primary design parameter, as it produced a visually effective and compelling hybrid illusion.

- 1. Low-Pass Filter (LPF): A Gaussian LPF was designed to isolate the low frequencies from the dog image. A Gaussian function was specifically chosen because it is smooth and has no sharp edges. This property is crucial as it prevents the introduction of "ringing" artifacts (Gibbs phenomenon) in the reconstructed image, which would occur with an ideal, sharp-edged filter. Its transfer function,  $H_{low}(u, v)$ , is shown in Figure 3.
- 2. **High-Pass Filter (HPF):** A corresponding HPF was created by subtracting the Gaussian LPF from an all-pass filter:  $H_{high}(u,v) = 1 H_{low}(u,v)$ . This complementary filter was used to extract the fine details from the cat image by attenuating its low-frequency components.

Figure 3 provides a detailed plot of this designed system, showing the inputs, the transfer functions, and the resulting filtered images.



System Overview for Best Cutoff Frequency (13)

Figure 3: Detailed overview of the frequency mixer system for the chosen cutoff frequency of 15. Top Row: The low-pass path. Bottom Row: The high-pass path.

#### 4.2 Final Result and Component Visualization

The final hybrid image is a linear summation of the low-pass filtered dog image and the high-pass filtered cat image in the frequency domain. To demonstrate how the illusion works at different perceptual scales, Figure 4 was created. It shows the final hybrid image alongside its constituent low-pass and high-pass components generated at four different frequency cutoffs.

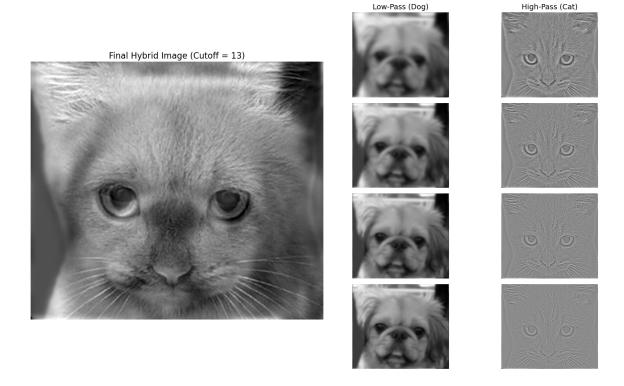


Figure 4: Final composite visualization. The main hybrid image (left) is shown alongside its low-pass (Dog) and high-pass (Cat) components at varying frequency cutoffs (right).

This visualization powerfully illustrates the core concept: when an observer is far away (or squints), their visual system naturally performs a low-pass filtering operation. This blurs out the high-frequency details of the cat, causing the low-frequency structure of the dog to dominate perception. Conversely, when viewed up close, the high-frequency details of the cat's face become salient and easily discernible, overriding the blurry, low-frequency background. The grid on the right side of Figure 4 explicitly shows these separated components, making it clear how the final image is constructed and why the perceptual effect occurs.

#### 5 Conclusion

This project successfully demonstrated the use of the 2D Fourier Transform for image analysis and manipulation. The properties of the Fourier spectrum, including its centering and response to rotation, were verified. A frequency mixer system was designed and implemented that successfully fused two images by combining their respective low and high spatial frequencies. The final visualizations effectively illustrate the system's mechanics and the perceptual basis of the hybrid image illusion.

## A Final Python Code

```
9
10 import numpy as np
import matplotlib.pyplot as plt
12 from PIL import Image
13 from scipy.fft import fft2, fftshift, ifft2, ifftshift
14 from matplotlib.gridspec import GridSpec
15 import os
17 # Input file paths
18 IMAGE_CAT_PATH = 'cat_gray.jpg'
19 IMAGE_DOG_PATH = 'dog_gray.jpg'
21 # Output directory for all generated files
22 OUTPUT_DIR = 'q1_final_submission_outputs'
# --- Parameters for the Hybrid Image ---
_{25} # The cutoff frequency that produces the best visual illusion for the main
     \hookrightarrow hybrid image.
26 BEST_HYBRID_CUTOFF = 13
_{28} # To demonstrate the effect of changing the filter parameters.
29 GRID_CUTOFF_FREQUENCIES = [10, 15, 20, 25]
31 # Create the output directory
32 os.makedirs(OUTPUT_DIR, exist_ok=True)
33 print(f"All outputs for Question 1 will be saved in: '{OUTPUT_DIR}/'")
34
36 # --- PART 1: 2D FOURIER TRANSFORM OF A SINGLE IMAGE ---
39 print("\nPART 1: Analyzing the 2D Fourier Transform of a Single Image...")
40
41 try:
      # We'll use the dog image for this initial analysis
42
      img_single_pil = Image.open(IMAGE_DOG_PATH).convert('L')
43
44 except FileNotFoundError:
      print(f"Error: '{IMAGE_DOG_PATH}' not found. Please check the file path.")
45
      # Fallback to a dummy image to prevent script crash
      img_single_pil = Image.fromarray(np.random.randint(0, 255, (400, 400),
      → dtype=np.uint8))
49 img_single_array = np.array(img_single_pil, dtype=float)
50 F_single_shifted = fftshift(fft2(img_single_array))
_{\rm 52} # Calculate spectra in normal and dB forms
53 magnitude_spectrum_normal = np.abs(F_single_shifted)
54 magnitude_spectrum_db = 20 * np.log10(magnitude_spectrum_normal + 1)
56 # Create and save the analysis plot
57 fig1, axes1 = plt.subplots(1, 3, figsize=(18, 6))
58 fig1.suptitle('Part 1: 2D Fourier Transform Analysis of an Image', fontsize=16)
60 axes1[0].imshow(img_single_array, cmap='gray');
61 axes1[0].set_title('Original Input Image (Dog)');
62 axes1[0].axis('off')
64 im1 = axes1[1].imshow(np.log(magnitude_spectrum_normal + 1), cmap='viridis');
65 axes1[1].set_title('Magnitude Spectrum (Normal Form - Log Scaled)');
66 axes1[1].axis('off'); fig1.colorbar(im1, ax=axes1[1], label='Log Magnitude')
68 im2 = axes1[2].imshow(magnitude_spectrum_db, cmap='viridis');
69 axes1[2].set_title('Magnitude Spectrum (dB Form)');
```

```
70 axes1[2].axis('off'); fig1.colorbar(im2, ax=axes1[2], label='Magnitude (dB)')
72 fig1.tight_layout(rect=[0, 0.03, 1, 0.95])
73 plt.savefig(os.path.join(OUTPUT_DIR, 'q1_part1_spectra_analysis.png'))
74 plt.show()
76 # -----
77 # --- PART 2: ROTATION ANALYSIS ---
78 # -----
80 print("\nPART 2: Analyzing the Effect of Rotation on the Fourier Spectrum...")
82 img_rotated = img_single_pil.rotate(90, expand=True)
83 img_rotated_array = np.array(img_rotated, dtype=float)
84 magnitude_spectrum_rotated = np.log(np.abs(fftshift(fft2(img_rotated_array))) +
      \hookrightarrow 1)
85
86 # Create and save the rotation analysis plot
87 fig2, axes2 = plt.subplots(1, 3, figsize=(18, 6))
88 fig2.suptitle('Part 2: Effect of Rotation on the Fourier Spectrum', fontsize
     \hookrightarrow =16)
90 axes2[0].imshow(img_rotated_array, cmap='gray');
91 axes2[0].set\_title('Rotated Image (90$^{\circ}$ Anti-Clockwise)');
92 axes2[0].axis('off')
94 axes2[1].imshow(np.log(magnitude_spectrum_normal + 1), cmap='viridis');
95 axes2[1].set_title('Original Image Spectrum');
96 axes2[1].axis('off')
98 axes2[2].imshow(magnitude_spectrum_rotated, cmap='viridis');
99 axes2[2].set_title('Rotated Image Spectrum');
100 axes2[2].axis('off')
102 fig2.tight_layout(rect=[0, 0.03, 1, 0.95])
plt.savefig(os.path.join(OUTPUT_DIR, 'q1_part2_rotation_analysis.png'))
104 plt.show()
107 # --- PART 3: CREATIVE FUSION (CAT-HIGH, DOG-LOW) ---
108 # -----
110 print("\nPART 3: Creating and Visualizing the Hybrid Image...")
111
112 try:
      img_high_pil = Image.open(IMAGE_CAT_PATH).convert('L') # Cat provides high
113
      → frequencies
      img_low_pil = Image.open(IMAGE_DOG_PATH).convert('L')  # Dog provides low
114
      \hookrightarrow frequencies
115 except FileNotFoundError: exit("Error: Could not find Cat or Dog image.
      → Aborting.")
117 if img_high_pil.size != img_low_pil.size: img_high_pil = img_high_pil.resize(
     → img_low_pil.size)
119 arr_high = np.array(img_high_pil, dtype=float); arr_low = np.array(img_low_pil,

    dtype=float)

120 F_high_shifted = fftshift(fft2(arr_high)); F_low_shifted = fftshift(fft2(
      → arr_low))
122 # --- A) Generate components for the multi-level grid visualization ---
123 low_pass_components, high_pass_components = [], []
124 print("--> Generating component images for the multi-level grid...")
```

```
125 for cutoff in GRID_CUTOFF_FREQUENCIES:
       rows, cols = arr_low.shape; crow, ccol = rows // 2, cols // 2
      x, y = np.meshgrid(np.arange(cols), np.arange(rows)); dist = np.sqrt((x -
127
      lpf = np.exp(-(dist**2) / (2 * cutoff**2)); hpf = 1.0 - lpf
128
       F_low_f = F_low_shifted * lpf; F_high_f = F_high_shifted * hpf
129
      low_pass_components.append(np.clip(np.real(ifft2(ifftshift(F_low_f)))), 0,
130
      high_pass_components.append(np.clip(np.real(ifft2(ifftshift(F_high_f)))) +
      \hookrightarrow 128, 0, 255))
133 # --- B) Create the final hybrid and the detailed system overview for the BEST
      134 print(f"--> Creating final hybrid and detailed system overview for chosen

    cutoff = {BEST_HYBRID_CUTOFF}...")

135 rows, cols = arr_low.shape; crow, ccol = rows // 2, cols // 2
136 x, y = np.meshgrid(np.arange(cols), np.arange(rows)); dist = np.sqrt((x - ccol)
      \hookrightarrow **2 + (y - crow)**2)
137 final_lpf = np.exp(-(dist**2) / (2 * BEST_HYBRID_CUTOFF**2)); final_hpf = 1.0 -
      → final_lpf
138
139 F_final_low = F_low_shifted * final_lpf; F_final_high = F_high_shifted *
      → final_hpf
140 F_final_hybrid = F_final_low + F_final_high
141 final_hybrid_image = np.clip(np.real(ifft2(ifftshift(F_final_hybrid))), 0, 255)
142 Image.fromarray(final_hybrid_image.astype(np.uint8)).save(os.path.join(
      → OUTPUT_DIR, 'Cat-Dog_Hybrid_Final.png'))
143
144 final_low_pass_img = np.clip(np.real(ifft2(ifftshift(F_final_low))), 0, 255)
145 final_high_pass_display_img = np.clip(np.real(ifft2(ifftshift(F_final_high))) +
      \hookrightarrow 128, 0, 255)
147 # --- Plot A: The Detailed System Overview for Best Cutoff ---
148 fig_overview, axes_overview = plt.subplots(2, 3, figsize=(15, 10))
149 fig_overview.suptitle(f'System Overview for Best Cutoff Frequency ({

→ BEST_HYBRID_CUTOFF})', fontsize=16)
150
axes_overview[0, 0].imshow(arr_low, cmap='gray');
axes_overview[0, 0].set_title('Input for Low-Pass (Dog)');
axes_overview[0, 1].imshow(final_lpf, cmap='viridis'); \
axes_overview[0, 1].set_title('Low-Pass Filter');
157 axes_overview[0, 2].imshow(final_low_pass_img, cmap='gray');
axes_overview[0, 2].set_title('Low-Pass Filtered Image');
axes_overview[1, 0].imshow(arr_high, cmap='gray');
axes_overview[1, 0].set_title('Input for High-Pass (Cat)');
162
axes_overview[1, 1].imshow(final_hpf, cmap='viridis');
164 axes_overview[1, 1].set_title('High-Pass Filter');
166 axes_overview[1, 2].imshow(final_high_pass_display_img, cmap='gray');
axes_overview[1, 2].set_title('High-Pass Filtered Image');
168
for ax in axes_overview.flat: ax.axis('off')
171 fig_overview.subplots_adjust(hspace=0.3, wspace=0.1)
172 plt.savefig(os.path.join(OUTPUT_DIR, 'q1_part3_system_overview.png'))
173 plt.show()
175 # --- Plot B: The Final Composite Visualization ---
176 print("--> Assembling the final composite visualization figure...")
```

```
177 fig_composite = plt.figure(figsize=(16, 10))
178 gs = GridSpec(len(GRID_CUTOFF_FREQUENCIES), 4, figure=fig_composite)
180 ax_main = fig_composite.add_subplot(gs[:, 0:2]);
181 ax_main.imshow(final_hybrid_image, cmap='gray');
182 ax_main.set_title(f'Final Hybrid Image (Cutoff = {BEST_HYBRID_CUTOFF}))',
     → fontsize=16);
183 ax_main.axis('off')
185 for i in range(len(GRID_CUTOFF_FREQUENCIES)):
      ax_lp = fig_composite.add_subplot(gs[i, 2]); ax_lp.imshow(
      \hookrightarrow low_pass_components[i], cmap='gray'); ax_lp.axis('off')
      if i == 0: ax_lp.set_title('Low-Pass (Dog)', fontsize=14)
187
      ax_hp = fig_composite.add_subplot(gs[i, 3]); ax_hp.imshow(
188

    high_pass_components[i], cmap='gray'); ax_hp.axis('off')

      if i == 0: ax_hp.set_title('High-Pass (Cat)', fontsize=14)
189
190
191 fig_composite.tight_layout()
192 plt.savefig(os.path.join(OUTPUT_DIR, 'q1_part3_composite_visualization.png'))
193 plt.show()
194
195 # ======
196 # --- END ---
197 # -----
```

Listing 1: Python script for Question 1.