

MATH1231/1241 Final Exam Revision Session – Algebra (Semester 2, 2017)



UNSW Mathematics Society

UNSW Sydney

26 October, 2017

Introduction

Today, we will cover

- Vector spaces
- Linear transformations
- Eigenvalues and eigenvectors
- Introduction to probability and statistics.

We will go through sample exam questions from these topics, showing how to approach such questions for the final exam.

Several of the questions presented here may be taken or adapted from UNSW past exam papers and homework sheets, and all copyright of the original questions belongs to the UNSW School of Mathematics and Statistics.

Vector spaces – Problem 1

[MATH1231 2014 S2 Q1 iv)]

$$\text{Let } S = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : z^2 = x^2 + y^2 \right\}.$$

- a) Prove that S is closed under scalar multiplication.
- b) Prove that S is **not** a subspace of \mathbb{R}^3 .

Vector spaces – Problem 2

[MATH1231 2016 S2 Q3 ii)]

Consider the set $S = \left\{ \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \\ 4 \end{pmatrix} \right\}$ of vectors in \mathbb{R}^3 .

- a) Prove that S is linearly dependent.
- b) Write the last vector in S as a linear combination of the other two.

Vector spaces – Problem 3

[MATH1231 2014 S2 Q3 vi)]

Let $B = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ be a set of three non-zero vectors in \mathbb{R}^3 .

- a) State the definition for the set B to be a linearly independent set.
- b) Prove that if B is an orthogonal set then B is linearly independent.
- c) Hence explain why any orthogonal set of 3 non-zero vectors in \mathbb{R}^3 forms a basis for \mathbb{R}^3 .

Vector spaces – Problem 4

[MATH1241 2016 S2 Q3 iii)]

The field $\mathbb{F} = \text{GF}(4)$ has elements $\{0, 1, \alpha, \beta\}$, with addition and multiplication defined by the following tables.

+	0	1	α	β
0	0	1	α	β
1	1	0	β	α
α	α	β	0	1
β	β	α	1	0

\times	0	1	α	β
0	0	0	0	0
1	0	1	α	β
α	0	α	β	1
β	0	β	1	α

For the vectors $\mathbf{b}_1 = \begin{pmatrix} 1 \\ \alpha \\ \beta \end{pmatrix}$, $\mathbf{b}_2 = \begin{pmatrix} \beta \\ 1 \\ 1 \end{pmatrix}$, $\mathbf{b}_3 = \begin{pmatrix} 1 \\ 0 \\ \alpha \end{pmatrix}$, $\mathbf{v} = \begin{pmatrix} \alpha \\ 0 \\ 0 \end{pmatrix}$,

- show that $\{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$ is a basis for \mathbb{F}^3
- explain without calculation why $\{\mathbf{b}_1, \mathbf{b}_1 + \mathbf{b}_2, \mathbf{b}_2 + \mathbf{b}_3, \mathbf{b}_3\}$ is a spanning set but not a basis for \mathbb{F}^3 ;
- find the coordinate vector of \mathbf{v} with respect to the ordered basis $\{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$ of \mathbb{F}^3 .

Linear transformations – Problem 1

[MATH1231 2012 S2 Q3 v)]

Suppose A is a 3×2 matrix and let A^T denote its transpose.

- a) Prove that the column space of the matrix AA^T is a subset of the column space of A and deduce that $\text{rank}(AA^T) \leq \text{rank}(A)$.
- b) Deduce that $\text{nullity}(AA^T) \geq 1$, and explain why the matrix AA^T can never be the identity.

Linear transformations – Problem 2

[MATH1231 2013 S2 Q3 ii)]

Let

$$A = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 2 & 3 & 5 & 3 \\ 1 & 3 & 4 & 9 \end{pmatrix}.$$

- a) Find a basis for $\ker(A)$.
- b) Hence state the value of $\text{nullity}(A)$. Give a reason.

Linear transformations – Problem 3

[MATH1241 2014 S2 Q3 iii)]

Let $\mathcal{R}[\mathbb{R}]$ denote the vector space of all real-valued functions defined on \mathbb{R} . Let S be the subspace of $\mathcal{R}[\mathbb{R}]$ that is spanned by the **ordered** basis $\mathcal{B} = \{\cos x, \sin x\}$. Define the linear map $T : S \rightarrow S$ by

$$T(f) = f - 2f', \quad \text{where } f' \equiv \frac{df}{dx}.$$

- a) Calculate the matrix C that represents T with respect to the basis \mathcal{B} .
- b) State the rank of the matrix C found in part a).
- c) From part b), what can be deduced about the solutions $y \in S$ of the differential equation

$$y - 2y' = g,$$

where g is a given function in S ?

- d) Using parts a) and c), or otherwise, find all solutions $y \in S$ of the differential equation

$$y - 2y' = \cos x.$$

Eigenvalues and eigenvectors – Problem 1

[MATH1231 2013 S2 Q3 iii)]

Let

$$C = \begin{pmatrix} 1 & 2 \\ -2 & 5 \end{pmatrix}.$$

- a) Find the eigenvalue(s) of C and for each eigenvalue, find the corresponding eigenvectors.
- b) Is C diagonalisable? Give a reason for your answer.

Eigenvalues and eigenvectors – Problem 2

[MATH1231 2014 S2 Q2 iv)]

Consider the set S consisting of the vectors $\mathbf{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$, $\mathbf{v}_2 = \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix}$

from \mathbb{R}^3 and let $\mathbf{u} = \begin{pmatrix} 1 \\ -1 \\ 12 \end{pmatrix}$.

- a) Find scalars λ and μ such that $\mathbf{u} = \lambda\mathbf{v}_1 + \mu\mathbf{v}_2$.
- b) A linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ has $\mathbf{v}_1, \mathbf{v}_2$ as eigenvectors with eigenvalues 2 and -1 , respectively.
 - α) Find $T(\mathbf{u})$ as a linear combination of $\mathbf{v}_1, \mathbf{v}_2$.
 - β) Denote $T(T(\mathbf{u}))$ by $T^2(\mathbf{u})$, $T(T(T(\mathbf{u})))$ by $T^3(\mathbf{u})$, and so on. Express $T^n(\mathbf{u})$ as a linear combination of $\mathbf{v}_1, \mathbf{v}_2$, where n is a positive integer.

Eigenvalues and eigenvectors – Problem 3

[MATH1241 2015 S2 Q3 iv)]

A linear transformation $P : V \rightarrow V$ is said to be **idempotent** if $P(P(\mathbf{v})) = P(\mathbf{v})$ for all $\mathbf{v} \in V$ (in other words, $P^2 = P$).

- a) Show that the only possible eigenvalues for an idempotent linear transformation are 0 and 1.
- b) Show that if P is idempotent and P is neither the zero nor the identity transformation on V , then both 0 and 1 are eigenvalues.

Introduction to probability and statistics – Problem 1

[MATH1231 2012 S2 Q3 iv), MATH1241 2012 S2 Q3 i)]

A six-sided die, with faces numbered 1 to 6, is suspected of being unfair, so that the number 6 will occur more frequently than should happen by chance. During 300 test rolls of the die, the number 6 occurred 68 times.

- a) Write down an expression for a tail probability that measures the chance of rolling a 6 at least 68 times.
- b) Use the normal approximation to the binomial to estimate this probability.
- c) Is this evidence that the die is unfair?

Introduction to probability and statistics – Problem 2

[MATH1231 2013 S2 Q1 iii)]

A collection of discs consists of DVDs and Blu-ray discs. In the collection, 75% are DVDs and 25% are Blu-ray discs. Among the DVDs, 60% are movies. Among the Blu-ray discs, 90% are movies.

- a) Find the probability that a disc chosen randomly from the collection is a movie.
- b) Find the probability that a randomly chosen disc from the collection is a Blu-ray disc given that it is a movie.

Introduction to probability and statistics – Problem 3

The probability density function f of a continuous random variable X is given by

$$f(x) = \begin{cases} 3(1-x)^2 & \text{for } 0 \leq x \leq 1 \\ 0 & \text{otherwise.} \end{cases}$$

- a) Sketch the graph of $y = f(x)$.
- b) Find $\mathbb{E}[X]$ and $\text{Var}(X)$.
- c) Find $\mathbb{P}\left(\frac{1}{2} < \sin(\pi X) < \frac{1}{\sqrt{2}}\right)$.
- d) The **median** of a distribution is defined to be the real number m such that $\mathbb{P}(X \leq m) = \frac{1}{2}$. Find the median of the above distribution.

Introduction to probability and statistics – Problem 4

[The log-normal distribution]

Let X be a normal random variable with mean μ and standard deviation σ . Find the probability density function of the random variable $Y := e^X$. (Y is said to be a *log-normal* random variable with parameters μ and σ .)

General tips

- Know the formal **definitions** of **all** key terms and concepts and precise **statements** of **all** key theorems/propositions. E.g. you should be able to give a precise mathematical definition of “linearly independent set”.
- Past final exam questions have asked to state definitions of such terms (e.g. 2015 MATH1231/1241 Question 2 v) a)). If you know your definitions, these are essentially free marks!
- Look at pages *xiii* and *xiv* of the Algebra course pack notes (**pages 13-14 of electronic PDF copy**). They tell you which definitions you should know, and which theorems/propositions you should be able to state (search these up in the relevant sections of the notes).
- To show something is **not** the case, it suffices to just give a specific/numerical example showing this. E.g. to show a set S is not a subspace, it suffices to find specific vectors $\mathbf{x}, \mathbf{y} \in S$ and demonstrate that $\mathbf{x} + \mathbf{y} \notin S$. No need for any sort of general argument.

General tips (cont.)

- When finding eigenvectors, when you row-reduce $A - \lambda I$ after having found λ , the row-echelon form **must** have at least one zero row. If it doesn't, you know you've made a mistake somewhere (perhaps found the wrong value for λ), and should go back and fix it.
- For any square matrix A ,

sum of eigenvalues of A = sum of diagonal entries of A .

This gives you a useful check on your calculations: if the sum of the eigenvalues you have found does not equal the sum of diagonal entries of A , you must have made a mistake somewhere. Always use this check when asked to find the eigenvalues of a matrix!

- Remember, for **continuous** random variables, it does not matter whether you use strict or non-strict inequalities for probabilities. E.g. $\mathbb{P}(a \leq X \leq b) = \mathbb{P}(a < X \leq b) = \mathbb{P}(a \leq X < b) = \mathbb{P}(a < X < b)$ **if X is continuous.** (This is because $\mathbb{P}(X = x) = 0$ for any x if X is continuous. I.e. the probability that X takes on any specific value is 0.)

- For **discrete** random variables however, the strictness of inequality signs does matter in general.

Good luck!

**ANY QUESTIONS?
GOOD LUCK FOR YOUR FINAL EXAMS!
MATHSOC WISHES YOU ALL THE BEST IN YOUR
FUTURE STUDY.**

UNSW MATHSOC MATH1231/1241 FINAL EXAM REVISION SESSION – ALGEBRA (Semester 2, 2017)

PRESENTED BY:

AARON HASSAN & SAMIR MUSTAVI

Slides designed by Aaron Hassan

