Data Structures and Algorithms 2001

Answer notes:

A directed graph G(V,E) is a set V of vertices and a set E of directed edges connecting selected pairs of vertices from V. A strongly connected component is a maximal subset of V for which paths exists connecting any of its vertices to any other.

```
DFS(v)
{ mark(v)
  setdiscoverytime(v,t++)
 for each w in successors(v) do
    if unmarked(w) do { DFS(w); addtreeedge(v,w) }
  setfinishingtime(v, t++)
}
t := 1
while w is an unmarked vertex do DFS(w)
setdiscoverytime(v,t) // set the discovery time
setfinishingtime(v,t) // set the finishing time
addtreeedge(v,w)
                       // add edge (v,w) to the depth first
                       // spanning tree
                       // eg: tsuccs(v) := mk2(tsuccs(v), w)
                       // and/or
                       // parent(w) := v
           discovery time
                             finishing time
              d1
                                   f1
phi(v)
              d2
                                   f2
```

Forefather property: there is a path from phi(v) to v

d1<d2<f2<d2

no -- (1) fails

d2<d1<f1<f2

yes -- so there is a path from phi(v) to v

so v and phi(v) are in the same strongly connected component

Algorithm

1 do DFS on graph to assign finishing numbers

- 2 find the vertex v with largest finishing time that is not yet in a strongly connected component. This is a forefather. Find all vertices that can be reached from v in the graph with all its edges reversed.
- 3 repeat 2 until all found

The cost is O(n) since it just used DFS twice.