Numerical Analysis I - Question A 2004

Context: IEEE arithmetic; absolute and velotive errors; machine epsilon.

(a) A binary floating point number can be expressed as

± do. d, d2 ... dp-1 x 2e

where e is the exponent, do.d, dz...dp-1 is the binary significand, and p is the precision.

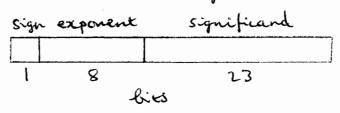
The sign lit is the sign of the significand and determines whether the number is positive (0) or negative (1).

If do = 1 then the number is normalised. In IEEE Single Precision normalised numbers have an exponent in the range emin $\leq e \leq e \max$.

If $e = e_{min}$ and $d_o = 0$ then the number is said to be denormal; by convention this is denoted by the exponent $e_{min} - 1$ (rather than e_{min}).

[6 marks]

(b) For normalised or denormal numbers do can be predicted from the expanent so is not stored; this is called the hidden bit. The hidden bit is I for normalised numbers, O for denormal numbers. The exponent is stored as e + e max so that the exponent does not need a sign bit.



[4 marks]

C) Let
$$x^*$$
 denote the floating point representation of x .

Absolute error E_x is defined by

$$x^* = x + \epsilon_x$$
.

$$x^* = x(1 + \delta_x) = x + x\delta_x$$

$$\therefore \in_{\mathbf{x}} = \mathbf{x} \delta_{\mathbf{x}}$$
.

Machine epsilon Em is the smallest Em>0 for which

$$(1+\epsilon_m)^* > 1$$

[3 marks]

(d) Add relative errors on multiplying

Add absolute errors when subtracting

$$\varepsilon_{w} = |\varepsilon_{z}| + |\varepsilon_{xy}| = |z|\varepsilon_{m} + 2|xy|\varepsilon_{m}$$

$$= (|z| + z|xy|)\varepsilon_{m}$$

If w #0

$$\delta_w = \frac{\epsilon_w}{|w|} = \frac{|z| + z|xy|}{|z - xy|} \epsilon_w$$

(4 marks)

$$w* = 4.058 - 4.052 = 0.006$$

$$S_{w} \simeq \frac{4 + 2x4}{0.006} \in = 2 \times 10^{3} \times 0.5 \times 10^{-3}$$

[3 marlis]