SOLUTION NOTES - CGIP PAPER 5, 2003

(a) The A-buffer is described in detail in the notes [slides 173-178 of the 2000 notes] using a 4×8 sub-pixel mask. The requirement for a 4×4 subpixel mask is to separate out those students who have memorised the notes without understanding them.

The students need to reproduce the majority of shides 174 and 175, wrapped up in enough algorithmic detail to indicate that they understand it.

(b) Human Vision can only see to a limited resolution. Below this resolution it averages together the intensties of what it sees so, at high enough resolution of black dots on white paper will look, to the human eye, at like a single grey blob. By varying the proportion of black to white you can vary the perceived intensty of grey. The human eye can see ~ 300 pixels per inch in greyscate so you need black & white pixels at a higher resolution to get a good approximation. 1200 ppi in the case of part (c).

(c) This requires either an ordered dither or half-tone algorithm. You need a 4×4 mask For each greyscale pixel with 13 5 9 15 1 9 3 12 value p, 0 ≤ p ≤ 255 11 1 3 6 13 5 14 6 calculate q = P/15 7 4 2 10 4 11 2 10 Every pixel in the mask 16 12 8 14 16 7 15 8 with value 29 is its black, HALF-TONE ORDERED DITHER the rest are white.

This may be combined with error diffusion for even greater accuracy, but this is not required fall full marks

| MARKING SCHEME - CGIP paper 5, 2003 - page 2 of | 2 | |
|------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----|
| (a) store a list of mask for each pixel | 1 | |
| (a) store a list of mask for each pixel what is a mask? | 2 | |
| need to store depth + colour for each mask | 1 | |
| need to store depth + colour for each mask how do I get the final colour of a pixel basic idea | 3 | |
| basic idea | | |
| efficiency (no need to store masks behind a full mask) clarity & completeness of algorithm | · · · · · · · · · · · · · · · · · · · | |
| Clarity Completeness of algorithm | - All Salar | 10 |
| (b) human vision has limited resolution | | |
| perform area averaging integration over its area | | |
| : a tiny bunch of black dots will book grey | | |
| performs area averaging / integration over its area :. a tiny bunch of black dots will book grey :. varying the proportion of black: white gives greyscale | | 4 |
| (c)* basic idea | 2 | |
| correct 4×4 mark | 2 | |
| correct 4×4 mark correct division/quantisation & black: white ratios | 2 | |
| | 6 | · |
| | · | |
| | 440 CANCEZ EM 111 48 C | 20 |
| *adding error diffusion will give an extra mark to someon who has otherwise scored less than 6 on part (c) | <u>e</u> | |
| - Who has otherwise scored less Than 6 on part (c) | | |

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CGIP (Computer Graphics & Image Processing)

Overall Scheme for Exam Questions 2003 The course has four sections: Background 3 lectures 2D Computer Graphics 3D Computer Graphics Image Processing 4 lectures 5 lectures 3 lectures These must all be tested in exam, preferably in proportion to the number of lectures given MARKU ALLOCATED
BG 2D 3D IP SLIDES IN 2000 NOTES QUESTION 37 (29-38) p3 (a) 269-271 (258-290) (b) (c) 78-84, 110-111 p5 (a) 173-178 (161-179) (b) 17-26, 39-40 (c) 246-2*50* p6 (a) 101-109,124-133 (P) 98-100 These questions give a good spread across the whole syllabus, test both algorithms and more general knowledge & require a student to understand at least two disparate parts of the course in order to get good marks on any of