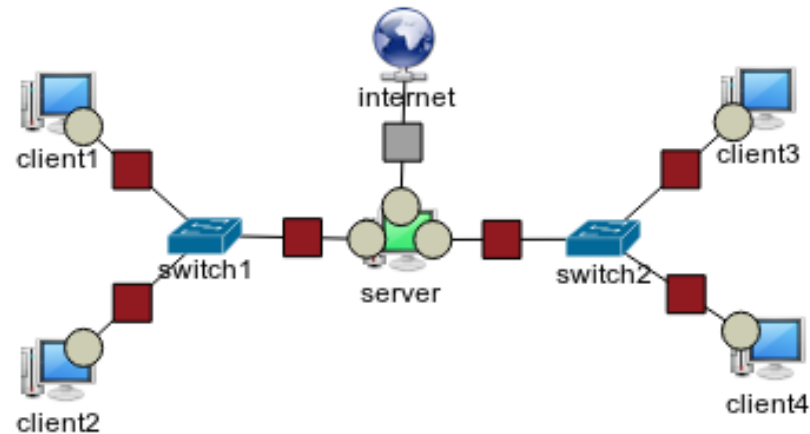


# **ToMaTo - Programmable Devices**

# ToMaTo, Topology Management Tool

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ToMaTo is topology-oriented, i.e. users build topologies for their experiments.



## Devices

- produce and consume data
- can run software

## Three kinds of devices

- KVM devices
- OpenVZ devices
- Programmable devices

## Connectors

- forward and manipulate data
- connect devices

## Two kinds of connectors

- VPN networks
- External networks

# Programmable devices

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Programmable devices run scripts written in Repy, a sandboxed Python dialect. Using these devices, networking data can be read and written as raw Ethernet packages.

## Difference between Repy and Python

- No global variables. Instead Repy has a dictionary `mycontext` that can be used to store global variables.
- No user input via `input` or `raw_input`
- Some Python builtins are not available. The most important are:
  - `import` and `reload`, Repy does not allow library loading
  - `print`, use `echo("message")` instead
  - `input`, `raw_input`, `eval` and `execfile`
  - `lambda` and `yield`
  - `hasattr`, `getattr` and `setattr`
- Parameters to the script are passed as `callargs`

# Script library: tomatolib

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The library is part of the ToMaTo source code and located at Github. It contains the following:

- Implementations of common Internet protocols (some are stubs)

- Example Repy scripts

- Utility methods for Repy scripts

- Makefile to include libraries in scripts and build combined script

Library files can be found in the `lib` directory and can be included like in the C programming language

```
1 #include <some_file/in_lib.repy>
2
3 def your_code(comes, here):
4     ...
```

Build your final output script using these steps:

1. Put your code in the `src` directory
2. Call `make` in the base directory
3. Find your output script in the `build` directory

# Packet reading

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## Reading from one device

```
1 packet = tuntap_read("eth0", timeout=None)
```

## Timeout values

- `timeout=T` waits at most for T seconds for a packet, otherwise returns None
- `timeout=0.0` returns packet (or None) immediately, no timeout
- `timeout=None` returns when a packet has been received, infinite timeout

## Reading from all devices at once

```
1 (dev, packet) = tuntap_read_any(timeout=None)
```

## Default reading loop

```
1 while True:  
2     try:  
3         (dev, packet) = tuntap_read_any(timeout=None)  
4         if packet:  
5             handle(dev, packet)  
6     except Exception, e:  
7         print_exc(e)
```

# Packet sending

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## Sending on one device

```
1 tuntap_send("eth0", packet)
```

## Sending on all devices

```
1 for dev in tuntap_list():  
2     send(dev, packet)
```

## Sending and receiving (simple switch example)

```
1 #include <layer2/ethernet_proto.repy>  
2  
3 mac_table = {}  
4  
5 while True:  
6     (dev, packet) = tuntap_read_any(timeout=None)  
7     ether = ethernet_decode(packet)  
8     mac_table[ether.src] = dev  
9     dst = mac_table.get(ether.dst)  
10    if dst:  
11        tuntap_send(dst, packet)  
12    else:  
13        for dst in tuntap_list():  
14            if dst != dev:  
15                tuntap_send(dst, packet)
```

# Working with protocols - dissecting headers

## Packets are strings

- `packet[index]` is one character (one byte)
- `len(packet)` is the size of a packet
- `packet[start:end]` is a byte range from start to end-1
- `ord(char)` converts a character to a number
- `chr(num)` converts a number to a character

## Example: IP

```
1 # This is only the IP header
2
3 # Source and destination address are 4 bytes each starting at bytes 12 and 16
4 src = packet[12:16]
5 dst = packet[16:20]
6
7 # IP header length is last 4 bits of the first byte
8 ihl = ord(packet[0]) & 0x0f
9
10 # IP header length counts length in 4-byte blocks
11 # First 5 blocks are normal header, rest are option headers
12 options = []
13 for i in range(5, ihl):
14     options.append(packet[4*i:4*i+4])
15
16 # After the header comes the payload
17 payload = packet[ihl*4:]
```

# Packing and unpacking binary data using struct

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## Decoding binary data

```
1 (byte1, byte2, int1, int2) = struct.unpack("!BBHH", packet[0:6])
```

## Encoding binary data

```
1 packet = struct.pack("!BBHH", byte1, byte2, int1, int2)
```

## Struct codes

- ! means network byte order, must be first character
- Each character stands for one field
  - **B** is a number that takes 1 byte (**B**yte)
  - **H** is a number that takes 2 bytes (**H**alf-integer)
  - **I** is a number that takes 4 bytes (**I**nteger)
  - **Q** is a number that takes 8 bytes
- Uppercase is unsigned, lowercase is signed

See the python struct documentation for more info.



# Tips & Tricks

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**Code sharing:** *Share your code with others on Github to improve the library and to get feedback.*

**Performance:** *Code that uses struct to convert binary data to numbers is a faster but the fastest code avoids conversions.*

**Exception handling:** *Wrap the per-packet code in a try-except block, otherwise the script will abort on an error.*

**80-20 rule:** *80% of the functionality of a protocol is implemented in 20% of its code, and vice versa. Most protocols have optional features that are not needed in most cases.*

**Arguments:** *Scripts can take arguments, no need to write different scripts just to have different addresses.*

# Obtaining and contributing

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## How to get ToMaTo

ToMaTo is Open-Source! It can be simply downloaded from the Github page. There is also a step-by-step tutorial on how to setup ToMaTo in a testbed. ToMaTo includes some nice features that make it pretty easy to install it in an experimental facility:

- All components packaged for debian (updates come automatically)
- Multiple authentication plugins: LDAP, htaccess, SQL-Database, Planet-Lab, ...
- Automatic checks and problem reports for the ToMaTo hosts

## How to contribute to ToMaTo

As an Open-Source project ToMaTo is open for hints and contributions.

- Github offers an easy way to fork the project and offer contributions as pull requests
- The wiki is publically editable so everyone can help by adding to the documentation
- The issue tracking system can be used for bug reports and feature requests