LU Factorization

- To further improve the efficiency of solving linear systems
- Factorizations of matrix A:LU and QR
- LU Factorization Methods:
 - Using basic Gaussian Elimination (GE)
 - Factorization of Tridiagonal Matrix
 - Using Gaussian Elimination with pivoting
 - Direct LU Factorization
 - Factorizing Symmetrix Matrices (Cholesky Decomposition)
- Applications
- Analysis

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LU/QR Factorization

LU/OR Factorization

LU Decomposition

 \blacksquare A matrix A can be decomposed into a lower triangular matrix L and upper triangular matrix U so that

$$\mathbf{A} = \mathbf{L}\mathbf{U}$$

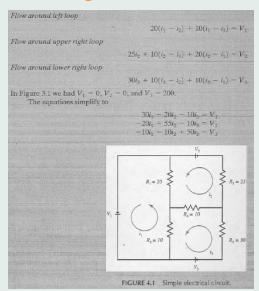
- lacksquare LU decomposition is performed once; can be used to solve multiple right hand sides.
- Similar to Gaussian elimination, care must be taken to avoid roundoff errors (partial or full pivoting)
- Special Cases: Banded matrices, Symmetric matrices.

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LU/QR Factorization

LU Decomposition: Motivation



LU Decomposition

Forward pass of Gaussian elimination results in the upper triangular matrix

$$U = \begin{bmatrix} 1 & u_{12} & u_{13} & \cdots & u_{1n} \\ 0 & 1 & u_{23} & \cdots & u_{2n} \\ 0 & 0 & 1 & \cdots & u_{3n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix}$$

We can determine a matrix L such that

$$LU = A$$
 , and

$$L = \begin{bmatrix} l_{11} & 0 & 0 & \cdots & 0 \\ l_{21} & l_{22} & 0 & \cdots & 0 \\ l_{31} & l_{32} & l_{33} & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ l_{n1} & l_{n2} & l_{n3} & \cdots & 1 \end{bmatrix}$$

LU Decomposition via Basic Gaussian Elimination

$$\mathbf{A} = \begin{bmatrix} 4 & 12 & 8 & 4 \\ 1 & 7 & 18 & 9 \\ 2 & 9 & 20 & 20 \\ 3 & 11 & 15 & 14 \end{bmatrix}.$$
Initialize
$$\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \mathbf{U} = \begin{bmatrix} 4 & 12 & 8 & 4 \\ 1 & 7 & 18 & 9 \\ 2 & 9 & 20 & 20 \\ 3 & 11 & 15 & 14 \end{bmatrix}.$$
Step 1: $m(2,1) = -u(2,1)u(1,1) = -1/4; m(3,1) = -u(3,1)/u(1,1) = -2/4$
Now
$$\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \\ 1/2 & 0 & 1 & 0 \end{bmatrix} \quad \mathbf{U} = \begin{bmatrix} 4 & 12 & 8 & 4 \\ 1 & 7 & 18 & 9 \\ 2 & 9 & 20 & 20 \\ 3 & 11 & 15 & 14 \end{bmatrix}.$$
Step 2: $m(3,2) = -u(3,1)/u(2,1) = -3/4;$
Now
$$\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \\ 3/4 & 1/2 & 0 & 1 \end{bmatrix} \quad \mathbf{U} = \begin{bmatrix} 4 & 12 & 8 & 4 \\ 0 & 3 & 16 & 18 \\ 0 & 2 & 9 & 11 \end{bmatrix}.$$
Step 2: $m(3,2) = -u(3,2)/u(2,2) = -3/4; m(4,2) = -u(4,2)/u(2,2) = -2/4.$
Now
$$\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \\ 3/4 & 1/2 & 0 & 1 \end{bmatrix} \quad \mathbf{U} = \begin{bmatrix} 4 & 12 & 8 & 4 \\ 0 & 4 & 16 & 8 \\ 0 & 0 & 4 & 12 \\ 0 & 2 & 1 & 7 \end{bmatrix}.$$
Step 3: $m(4,3) = -u(4,3)/u(3,3) = -1/4;$
Now
$$\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \\ 3/4 & 1/2 & 1/4 & 1 \end{bmatrix} \quad \mathbf{U} = \begin{bmatrix} 4 & 12 & 8 & 4 \\ 0 & 4 & 16 & 8 \\ 0 & 0 & 4 & 12 \\ 0 & 2 & 0 & 4 \end{bmatrix}$$
Multiply \mathbf{L} by \mathbf{U} to verify the result:
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \\ 3/4 & 1/2 & 1/4 & 1 \end{bmatrix} \quad \mathbf{U} = \begin{bmatrix} 4 & 12 & 8 & 4 \\ 0 & 4 & 16 & 8 \\ 0 & 0 & 4 & 12 \\ 0 & 2 & 0 & 4 \end{bmatrix}$$
Multiply \mathbf{L} by \mathbf{U} to verify the result:
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \end{bmatrix} \quad \mathbf{d} = \begin{bmatrix} 4 & 12 & 8 & 4 \\ 0 & 4 & 16 & 8 \\ 0 & 0 & 4 & 12 \\ 0 & 2 & 0 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 4 & 12 \\ 0 & 0 & 4 & 12 \\ 0 & 0 & 0 & 4 \end{bmatrix} \quad \mathbf{d} = \begin{bmatrix} 4 & 12 & 8 & 4 \\ 0 & 4 & 16 & 8 \\ 0 & 0 & 4 & 12 \\ 0 & 2 & 0 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1/4 & 1 & 0 & 0 \\ 0 & 0 & 4 & 16 \\ 0 & 0 & 4 & 16 \\ 0 & 0 & 4 & 16 \\ 0 & 0 & 4 & 12 \\ 0 & 2 & 0 & 20 \\ 0 & 3 & 11 & 15 \\ 1 & 15 & 14 \end{bmatrix}$$

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LU/QR Factorization

Banded Matrices

- Matrices that have non-zero elements close to the main diagonal
- Example: matrix with a bandwidth of 3 (or half band of 1)

$$\begin{bmatrix} a_{11} & a_{12} & 0 & 0 & 0 \\ a_{21} & a_{22} & a_{23} & 0 & 0 \\ 0 & a_{32} & a_{33} & a_{34} & 0 \\ 0 & 0 & a_{43} & a_{44} & a_{45} \\ 0 & 0 & 0 & a_{54} & a_{55} \end{bmatrix}$$

- Efficiency: Reduced pivoting needed, as elements below bands are zero.
- Iterative techniques are generally more efficient for sparse matrices, such as banded systems.

LU Decomposition via Basic Gaussian Elimination: Algorithm

```
A
                                     n-by-n matrix to be factored
                                     dimension of A
Initialize
   L = I
                                     n-by-n identity matrix
   U = A
Compute
For k = 1 to n-1
   For i = k + 1 to n
                                    each row of matrix U after the kth row
       m(i,k) = -U(i,k)/U(k,k)
       For i = k \text{ to } n
                                    transform row i
           U(i, j) = U(i, j) + m(i,k)*U(k, j)
       L(i,k) = -m(i,k)
                                    update L matrix
   End
End
Return
                                    lower triangular matrix
   U
                                    upper triangular matrix
```

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LU/QR Factorization

LU Decomposition of Tridiagonal Matrix

```
\mathbf{M} = \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}, which can be represented by the vectors \mathbf{d} = [2, 2, 2, 2]; \ \mathbf{a} = \{-1, -1, -1, 0\}; \ \mathbf{b} = [0, -1, -1, -1], For this example, n = 4, Begin computation dd_1 = d_1 = 2 For i = 2 bb_2 = b_2 dd_1 \\ dd_2 = d_2 - bb_2 a_1 = 2 - (-1/2)(-1) = 3/2 For i = 3 bb_3 = b_3 dd_2 = -1/(3/2) \\ dd_3 = d_3 - bb_3 a_2 = 2 - (-2/3)(-1) = 4/3 For i = 4 bb_4 = b_3 dd_3 = -1/(4/3) \\ dd_4 = d_4 - bb_4 a_3 = 2 - (-3/4)(-1) = 5/4 In general, the factorization is \mathbf{L} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ bb_2 & 1 & 0 & 0 \\ 0 & bb_3 & 1 & 0 \\ 0 & 0 & bb_4 & 1 \end{bmatrix}, \ \mathbf{U} = \begin{bmatrix} dd_1 & a_1 & 0 & 0 \\ 0 & dd_2 & a_2 & 0 \\ 0 & 0 & dd_3 & a_3 \\ 0 & 0 & 0 & dd_4 \end{bmatrix} which, for this example, is \mathbf{L} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1/2 & 1 & 0 & 0 \\ 0 & -2/3 & 1 & 0 \\ 0 & 0 & -3/4 & 1 \end{bmatrix}, \ \mathbf{U} = \begin{bmatrix} 2 & -1 & 0 & 0 \\ 0 & 3/2 & -1 & 0 \\ 0 & 0 & 3/2 & -1 & 0 \\ 0 & 0 & 0 & 4/3 & -1 \\ 0 & 0 & 0 & 5/4 \end{bmatrix}
```

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LU/OR Factorization

LU Decomposition of Tridiagonal Matrix: Algorithm

```
upper diagonal of M (matrix to be factored) with a_n = 0
    a
                       diagonal of matrix M
    d
    b
                       lower diagonal of matrix M, with b_1 = 0
                       number of components in a, d, and b
Initialize
bb_1 = 0
dd_1 = d_1
Compute For i = 2 to n
    bb; = -
          dd_{i-1}
    dd_i = d_i - bb_i a_{i-1}
End
Return
    bb
                       lower diagonal of L (main diagonal is [1, 1, ..., 1])
    dd
                       main diagonal of U (upper diagonal is a)
```

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LU/QR Factorization

LU Decomposition via GE with Pivoting

LU/QR Factorization

LU Decomposition via GE with Pivoting: Algorithm

```
matrix to be factored (n-by-n)
   U = A
L = I
P = I
                                             n-by-n identity matrix
For k = 1 to n-1
   pivot = |U(k,k)|
p = k
For i = k + 1 to n
If (|U(i,k)| > pivot)
                                             pivot element
                   pivot = | U(i,k) | update pivot element
p = i update pivot row
         End
    End
    If (p > k)
          t_1 = u(k,:)

U(k,:) = U(p,:)
                                             interchange rows k and p of matrix U
         U(k, :) = U(p, :)

U(p, :) = t_1

t_2 = P(k, :)

P(k, :) = P(p, :)

P(p, :) = t_2

For j = 1 to k-1
                                             interchange rows k and p of matrix P
                                             (if k > 1)
              t_3 = L(k, j)

L(k, j) = L(p, j)

L(p, j) = t_3
                                              interchange columns 1 \dots k-1 of rows k and p
                                             in matrix L
          End
         s = -U(i, k)/U(k,k)
           U(i,:) = U(i,:) + s^*U(k,:) update row i in U
    End
Return
                                                 lower triangular matrix
```

Direct LU Decomposition

$$\begin{bmatrix} l_{11} & 0 & 0 & \cdots & 0 \\ l_{21} & l_{22} & 0 & \cdots & 0 \\ l_{31} & l_{32} & l_{33} & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ l_{n1} & l_{n2} & l_{n3} & \cdots & 1 \end{bmatrix} \begin{bmatrix} 1 & u_{12} & u_{13} & \cdots & u_{1n} \\ 0 & 1 & u_{23} & \cdots & u_{2n} \\ 0 & 0 & 1 & \cdots & u_{3n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{bmatrix}$$

The above equation shows the coefficient matrix A can be decomposed into L and U; L and U can be determined by the computing the product and equating like terms.

Determining L and U

$$\begin{array}{ll} l_{i1} &=& a_{i1}, i=1,2,\ldots,n \\ u_{1j} &=& \frac{a_{1j}}{l_{11}}, j=2,3,\ldots,n \\ \\ l_{ij} &=& a_{ij} - \sum_{k=1}^{j-1} l_{ik} u_{kj}, \\ & \text{for } j=2,3,\ldots,n-1 \text{ and } i=j,j+1,\ldots,n \\ u_{ji} &=& \frac{a_{ji} - \sum_{k=1}^{j-1} l_{jk} u_{ki}}{l_{jj}}, \\ & \text{for } j=2,3,\ldots,n-1 \text{ and } i=j+1,j+2,\ldots,n \\ \\ l_{nn} &=& a_{nn} - \sum_{k=1}^{n-1} l_{nk} u_{kn} \end{array}$$

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LU/QR Factorization

Direct LU Decomposition: Algorithm

```
Input
                   n-by-n matrix to be factored
   n
                   dimension of A
Initialize
   U = 0(n)
                  initialize U to n-by-n zero matrix
                   initialize L to identity matrix
   L = I(n)
Compute
For k = 1 to n
    U(k, k) = A(k, k) - L(k, 1:k - 1)*U(1:k - 1, k)
    For j = k + 1 to n
            U(k, j) = A(k, j) - L(k, 1:k - 1)*U(1:k - 1), j
            L(j, k) = (A(j, k) - L(j, 1:k - 1)*U(1:k - 1, k))/U(k, k)
    End
End
```

Direct LU Decomposition: Example

```
Example 4.4 Doolittle Form of LU Factorization

To find the LU factorization for \mathbf{A} = \begin{bmatrix} 1 & 4 & 5 \\ 4 & 20 & 32 \\ 5 & 32 & 64 \end{bmatrix}
by Doolittle's method, we write the desired product as

\begin{bmatrix} 1 & 0 & 0 \\ \ell_{21} & 1 & 0 \end{bmatrix} \begin{bmatrix} u_{11} & u_{12} & u_{13} \\ 0 & u_{22} & u_{23} \end{bmatrix} = \begin{bmatrix} 1 & 4 & 5 \\ 4 & 20 & 32 \\ 5 & 32 & 64 \end{bmatrix}
We begin by solving for the first row of U and the first column of L:

(1) u_{11} = a_{11} = 1, \quad (1) u_{12} = a_{12} = 4, \quad (1) u_{13} = a_{13} = 5;
\ell_{21} u_{11} = a_{21} = 4, \quad \ell_{21} u_{12} = a_{22} = 4, \quad (1) u_{12} = a_{13} = 5;
Next, using these values, we find the second row of U and the second column of L:

\begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 5 & \ell_{32} & 1 \end{bmatrix} \begin{bmatrix} 1 & 4 & 5 \\ 0 & u_{22} & u_{33} \\ 0 & 0 & u_{33} \end{bmatrix} = \begin{bmatrix} 1 & 4 & 5 \\ 4 & 20 & 32 \\ 5 & 32 & 64 \end{bmatrix},
(4)(4) + u_{22} = 20 \implies u_{22} = 20 - 16 = 4;
(4)(5) + u_{23} = 32 \implies u_{23} = 32 - 20 = 12;
(5)(4) + \ell_{22} u_{22} = 32 \implies \ell_{23} = (32 - 20)/4 = 3.
Finally, the only remaining unknown in matrix U is determined:

\begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 5 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 4 & 5 \\ 4 & 20 & 32 \\ 5 & 32 & 64 \end{bmatrix} = \begin{bmatrix} 1 & 4 & 5 \\ 4 & 20 & 32 \\ 5 & 32 & 64 \end{bmatrix}
(5)(5) + (3)(12) + u_{30} = 64 \implies u_{33} = 64 - 25 - 36 = 3.
The factorization is

\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 5 & 3 & 1 \end{bmatrix}, \quad \mathbf{U} = \begin{bmatrix} 1 & 4 & 5 \\ 0 & 4 & 12 \\ 0 & 0 & 3 \end{bmatrix}
```

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LU/QR Factorization

Symmetric Matrices

- Symmetric square matrices common in engineering, for example stiffness matrix (stiffness properties of structures).
- For a symmetric matrix A

$$A = A^T$$

where A^T is the transpose of A. Hence

For a symmetric matrix A

$$A = LL^T$$

Symmetric Matrices: LU Decomposition

We can use Cholesky Decomposition to compute the LU decomposition of A

$$\begin{array}{l} l_{11} \ = \ \sqrt{a_{11}} \\ \\ l_{ii} \ = \ \sqrt{a_{ii} - \sum_{k=1}^{i-1} l_{ik}^2}, \ \text{for} \ i = 2, 3, \ldots, n \\ \\ l_{ij} \ = \ \frac{a_{ij} - \sum_{k=1}^{j-1} l_{ik} l_{jk}}{l_{jj}}, \ \text{for} \ j = 2, 3, \ldots, i-1, \ \text{and} \ j < 1 \end{array}$$

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LU/QR Factorization

LU (Cholesky) Decomposition of Symmetric Matrices

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LU/QR Factorization

LU (Cholesky) Decomposition: Algorithm

Applications of LU Decomposition:Solving Linear systems

$$[A]\vec{X} = [L][U][\vec{X}] = C$$
$$= [L]\vec{e} = C$$

where
$$\vec{e} = [U]\vec{X}$$

- Solve for \vec{e} using L (forward substitution)
- Solve for \vec{X} using U (back substitution)

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Solving Linear Systems

Forward Substitution

Solve for \vec{e} ,

$$e_1 = rac{C_1}{l_{11}}$$
 $e_i = rac{C_i - \sum_{j=1}^n l_{ij} e_j}{l_{ii}}, ext{ for } i = 2, 3, \dots n$

Back Substitution

Solve for \vec{X}

$$X_n = e_n$$
 $X_i = e_i - \sum_{j=i+1}^n u_{ij} X_j$, for $i = n-1, n-2, \dots 1$

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LU/OR Factorization

Solving Linear Systems

Solving Linear Systems: Example Example 4.6 Solving an Electrical Circuit for Several Voltages

Consider again the electric circuit of Figure 3.1 with resistances as shown, but with $V_1 = 0$, $V_2 = 80$, and $V_3 = 0$. The system to be solved is $\mathbf{A} \mathbf{x} = \mathbf{b}$, where $\mathbf{A} = \begin{bmatrix} 30 & -20 & -10 \\ -20 & 55 & -10 \\ -10 & -10 & 50 \end{bmatrix} \text{ and } \mathbf{b} = \begin{bmatrix} 0 \\ 80 \\ 0 \end{bmatrix}.$ $\mathbf{A} = \mathbf{L} \mathbf{U}, \text{ with}$ $\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 \\ -2/3 & 1 & 0 \\ -1/3 & -2/5 & 1 \end{bmatrix} \text{ and } \mathbf{U} = \begin{bmatrix} 30 & -20 & -10 \\ 0 & 125/3 & -50/3 \\ 0 & 0 & 40 \end{bmatrix}.$ We first solve $\mathbf{L} \mathbf{y} = \mathbf{b}$, i.e., $\begin{bmatrix} 1 & 0 & 0 \\ -2/3 & 1 & 0 \\ -1/3 & -2/5 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 80 \\ 0 \end{bmatrix},$ and find, by forward substitution, that $y_1 = 0, y_2 = 80, \text{ and } y_3 = (2/5)(80) = 32.$ Next, we solve $\mathbf{U} \mathbf{x} = \mathbf{y}, \text{ or}$ $\begin{bmatrix} 30 & -20 & -10 \\ 0 & 125/3 & -50/3 \\ 0 & 0 & 40 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 80 \\ 32 \end{bmatrix},$ and find, by backward substitution, that $x_3 = 32/40 = 4/5,$ $x_2 = (80 + 40/3)(3/125) = 56/25,$ and $x_1 = (1/30)[-20(56/25) - 10(4/5)] = 44/25.$

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 $i_1 = 1.76, i_2 = 2.24$, and $i_3 = 0.80$.

The resulting electrical currents in each of the three loops are

LU/QR Factorization

Solving Linear Systems: Algorithm

```
lower triangular matrix (with I's on diagonal)
                upper triangular matrix
    В
                right-hand side matrix (n-by-m)
                number of rows or columns in L or U, number of rows in B
    n
                number of columns in B
Solve L Z = B using forward substitution
For j = 1 to m
    Z(1,j) = B(1,j)
    For i = 2 to n
        Z(i, j) = B(i, j) - L(i, :)*Z(:, j)
                                                       ith row of L dot jth col of Z
    End
End
Solve U X = Z using back substitution
For i = 1 to m
    X(n, :) = Z(n, :)/U(i, i)
   For i = n - 1 to 1
        X(i,j) = (Z(i,j) - U(i,:)*X((:,j))/U(i,i) \quad i^{th} \text{ row of } U \text{ dot } j^{th} \text{ col of } Z
    End
End
Return
   X
                              matrix of solutions
```

Application 2: Tridiagonal Systems

```
above diagonal of matrix U; (with a_n = 0)
   a
                diagonal of matrix U
   b
                below diagonal of matrix L (with \mathbf{b}_1 = 0)
                right-hand side of linear system
                number of components in each vector
Solve L z = b using forward substitution
z(1) = r(1)
For k = 2 to n
  z(k) = r(k) - b(k) z(k-1)
Solve Ux = z using back substitution
x(n) = z(n)/d(n)
For k = n - 1 to 1
  x(k) = (z(k) - a(k) x(k + 1))/d(k)
End
Return
                vector of solution
```

Example 4.7 Solving a Tridiagonal System Using LU Factorization

To illustrate the use of the preceding algorithm, we solve the linear system, $\mathbf{M}\mathbf{x} = \mathbf{r}$, with $\mathbf{r} = (\mathbf{a} - 3 \, 9 - 10)$, and the LU factorization of \mathbf{M} given by the vectors $\mathbf{a} = (-1 - 1 - 1)$ $\mathbf{0}, \mathbf{d} = (2.32 \, 4.53 \, 44), \mathbf{b} = (0 - 1)2 - 2/3 - 3/4)$ (see Example 4.2). We begin by solving $\mathbf{L} = \mathbf{b}$ using forward substitution $z(1) = r(1) \qquad = 4 \\ z(2) = r(2) - b(2) z(1) = -3 - (-12)(4) \qquad = -1 \\ z(3) = r(3) - b(3) z(2) = 9 - (-23)(-1) \qquad = 25/3 \\ z(4) = r(4) - b(4/2(3) = -10 - (-34)(25/5) = -15/4 \\ \text{We then solve } \mathbf{U}\mathbf{x} = \mathbf{z} \text{ using back substitution}$ $z(1) = z(4)/(4) \qquad = -3 \\ z(3) = (2(3) - a(3) \, x(4))/d(3) = (25/3 - (-1)(-3))(3/4) = 4 \\ z(2) = (z(2) - a(2) \, x(3))/d(2) = (-1 - (-1)/4)/(23) = 2 \\ z(1) = (z(1) - a(1) \, x(2))/d(1) = (4 - (-1)2)/(12) \qquad = 3 \\ \text{The solution vector is}$ $\mathbf{x} = (3 \, 2 \, 4 - 3)$

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Application 3: Matrix Inverse

Example 4.8 Inverse of a Matrix

Using the LU factorization of $\bf A$ and the algorithm to solve $\bf L\,U\,x=B$ given in section 4.3.1, we can construct $\bf X=A^{-1}$ by taking $\bf B$ to be the identity matrix. To illustrate the process, we find the inverse of $\bf A$, using its LU factorization, where

$$\mathbf{A} = \begin{bmatrix} 1 & -1 & 2 \\ -2 & 1 & 1 \\ -1 & 2 & 1 \end{bmatrix}, \quad \mathbf{L} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -1 & -1 & 1 \end{bmatrix}, \quad \mathbf{U} = \begin{bmatrix} 1 & -1 & 2 \\ 0 & -1 & 5 \\ 0 & 0 & 8 \end{bmatrix}.$$

$$\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \end{bmatrix} \begin{bmatrix} y_{11} & y_{12} & y_{13} \\ y_{21} & y_{22} & y_{23} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

$$\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -1 & -1 & 1 \end{bmatrix} \begin{bmatrix} y_{11} \\ y_{21} \\ y_{31} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}.$$

$$\mathbf{Y} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 1 & 1 \end{bmatrix}.$$

$$\begin{bmatrix} 1 & -1 & 2 \\ 0 & -1 & 5 \\ 0 & 0 & 8 \end{bmatrix} \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 1 & 1 \end{bmatrix}$$

$$\mathbf{X} = \mathbf{A}^{-1} = \begin{bmatrix} 1/8 & -5/8 & 3/8 \\ -1/8 & -3/8 & 5/8 \\ 3/8 & 1/8 & 1/8 \end{bmatrix}$$

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LU/OR Factorization

Analysis: LU Decomposition

Gradual tranformation of I towards LU:

$$I.A = A$$

$$I.M_1^{-1}.M_1.A = A$$

$$I.M_1^{-1}.M_2.M_1.A = A$$

 $M_2.M_1.A$ is U and $I.M_1^{-1}.M_2^{-1}$ is L, given by

$$\begin{bmatrix} 1 & 0 & 0 \\ -m_{21} & 1 & 0 \\ -m_{31} & -m_{32} & 1 \end{bmatrix}$$

Analysis: LU Decomposition

- Why does LU decomposition work?
- Consider the first elimination step:

$$\begin{bmatrix} 1 & 0 & 0 \\ m_{21} & 1 & 0 \\ m_{31} & 0 & 1 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a'_{22} & a'_{23} \\ 0 & a'_{32} & a'_{33} \end{bmatrix}$$

Define

$$M_1 = egin{bmatrix} 1 & 0 & 0 \ m_{21} & 1 & 0 \ m_{31} & 0 & 1 \end{bmatrix}, M_2 = egin{bmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & m_{32} & 1 \end{bmatrix}$$

Hence

$$M_1^{-1} = egin{bmatrix} 1 & 0 & 0 \ -m_{21} & 1 & 0 \ -m_{31} & 0 & 1 \end{bmatrix}, M_2^{-1} = egin{bmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & -m_{32} & 1 \end{bmatrix},$$
Thus, to Numerical Methods

Analysis:LU Decomposition with Pivoting

Decomposition results in the factorization of PA, where P is the permutation matrix.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

Assume no pivoting in column 1, pivoting in column 2:

$$I.A = A$$

$$I.M_1^{-1}.M_1.A = A$$

$$I.M_1^{-1}.P.P.M_1.A = A$$

$$I.M_1^{-1}.P.M_2^{-1}.M_2.P.M_1.A = A$$

- $M_2.P.M_1.A$ is upper triangular, but $I.M_1^{-1}.P.M_2^{-1}$ is not lower triangular.
- Premultiply both sides by *P*:

$$\frac{P{M_1}^{-1}.P.{M_2}^{-1}.M_2.P.M_1.A=P.A}{{\it ITCS~4133/5133:~Intro.~to~Numerical~Methods}}$$
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