

Solving the RCK example: Brute-force value function iteration

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Outline

1 Previously, on Desperate Economists ...

2 Illustrative Example

- Value function iteration
- Policy Function

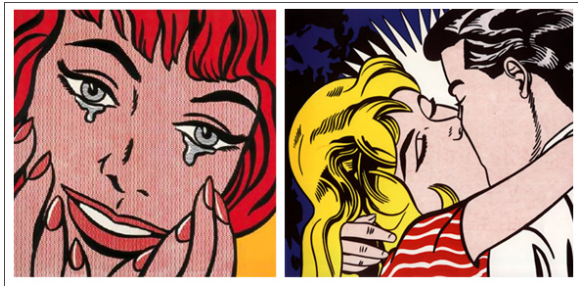
3 Remarks

What you need to own



- Batteries not included:
 - ❶ Optimization (Math A for Economists)
 - ❷ High school calculus
 - ❸ High school (elementary) algebra

Previously ...



Oh Joy! [Apologies to Roy Lichtenstein]

Amore a prima vista I

- Sequence problem was:

$$v(k_0) = \max_{\{k_{t+1} \in \Gamma(k_t)\}_{t \in \mathbb{N}}} \left\{ \sum_{t=0}^{\infty} \beta^t \ln(k_t^\alpha - k_{t+1}) : k_0 \text{ given} \right\}.$$

- Claimed (without basis): We could rewrite problem as the following *Recursive Functional* mapping:

$$v(k) = \max_{k_+ \in \Gamma(k)} \left\{ \ln(k^\alpha - k_+) + \beta v(k_+) : k \text{ given} \right\}.$$

Amore a prima vista II

- At first glance ...
- This seems an easy problem to solve, given that we no longer have to choose infinite list $\{k_{t+1}\}_{t \in \mathbb{N}}$.
- We now just choose a finite object k_+ (i.e. k_{t+1}) as some function, say g_t of the current decision state k (i.e. k_t).
- $k_{t+1} = g_t(k_t)$ is just a solution to the right-hand-side finite-dimensional maximization problem.
- Easy, no?

Amore a prima vista III

But we still have a **problem** to deal with. ...

What is the function v ?

... We actually don't know what v looks like.

Amore a prima vista IV

- Is this an improvement? We couldn't solve the infinite sequence Lagrangean problem directly. So we re-wrote it as the RFM above. But now we don't know what is v .
- So now, our goal shifts to one of finding v first.
- If we can find v we can solve for the optimal decision function(s) g_t .
- Observe that v is a **function**. Mathematically, it is an element in an infinite dimensional space!
- Turns out we can solve for this v , at least “approximately”. How good is the approximation is what we'll find out during this course.

Value function iteration I

Now we are ready to illustrate the technique—a.k.a. successive value function approximation using the Bellman functional equation (operator).

IDEA:

- Suppose we don't know what v is. Can we inductively find an approximation of v ?
- Consider at any current k , we write

$$v_{n+1}(k) = \max_{k_+ \in \Gamma(k)} \left\{ \ln(k^\alpha - k_+) + \beta v_n(k_+) : k \text{ given} \right\}.$$

- Inductively construct a sequence of approximations to the mysterious function v , denoted by (v_0, v_1, \dots) , where each function $v_n : X \rightarrow \mathbb{R}$, is indexed by $n = 0, 1, \dots$
- Is it true that $\lim_{n \rightarrow \infty} v_n \rightarrow v$?

Value function iteration II

The following steps will illustrate our proposed solution strategy.

Step $n = 0$. Guess that $v_0(k_+) = 0$ for all k_+ . Then,

$$v_1(k) = \max_{k_+ \in \Gamma(k)} \left\{ \ln(k^\alpha - k_+) : k \text{ given} \right\}.$$

This is looking good. It's just a static maximum problem. Given k fixed, the maximum is attained by choosing $k_+ = g_0(k) = 0$.

So the value of the problem is

$$v_1(k) = \alpha \ln(k).$$

Value function iteration III

Step $n = 1$. Use the last result, i.e. $v_1(k_+) = \alpha(k)$ for all k_+ , then,

$$\begin{aligned} v_2(k) &= \max_{k_+ \in \Gamma(k)} \left\{ \ln(k^\alpha - k_+) + \beta v_1(k_+) : k \text{ given} \right\} \\ &= \max_{k_+ \in \Gamma(k)} \left\{ \ln(k^\alpha - k_+) + \beta [\alpha \ln(k_+)] : k \text{ given} \right\}. \end{aligned}$$

Value function iteration IV

This is still looking good. It's just a two-period maximum problem. Given k fixed, the maximum is attained by choosing k_+ s.t.:

$$-\frac{1}{(k^\alpha - k_+)} + \beta \frac{\alpha}{k_+} = 0.$$

Solving for k_+ as a function of k we have

$$k_+ = \frac{\alpha\beta}{1 + \alpha\beta} k^\alpha =: g_1(k).$$

The value of this problem is

$$v_2(k) = \ln \left(\frac{1}{1 + \alpha\beta} \right) + \alpha\beta \ln \left(\frac{\alpha\beta}{1 + \alpha\beta} \right) + \alpha(1 + \alpha\beta) \ln(k).$$

Value function iteration V

Step $n = 2$. Now using the known v_2 , find v_3 . Try this as an exercise!

Notice that as you work along each iteration n ,

- the sequence of value functions have a particular form:
$$v_n(k) = A_n + B_n \ln(k).$$
- Corresponding to each known v_n , we have an optimal decision rule of the form: $k_+ = C_n k^\alpha =: g_n(k)$.
- the coefficients (A_n, B_n, C_n) are functions of the model's underlying microeconomic parameters (α, β) .

Value function iteration VI

Why don't we try for $n \geq 3$?

Value function iteration VII

Exercise

Show inductively that, at each $n \geq 2$ using the value function derived from the last $(n - 1)$ -th iteration, we can derive the corresponding optimal decision rule as

$$k_+ = \alpha\beta \left[\frac{1 - (\alpha\beta)^n}{1 - (\alpha\beta)^{n+1}} \right] k^\alpha =: g_n(k).$$

And we can derive the updated $(n + 1)$ -th value function as

$$\begin{aligned} v_{n+1}(k) = & \sum_{m=0}^n \beta^m \ln \left(\frac{1}{1 + \alpha\beta + \cdots + (\alpha\beta)^{n-m}} \right) \\ & + \sum_{m=0}^{n-1} \left\{ \beta^m \alpha\beta (1 + \alpha\beta + \cdots + (\alpha\beta)^{n-1-m}) \right. \\ & \quad \times \left[\ln \left(\alpha\beta \frac{1 + \alpha\beta + \cdots + (\alpha\beta)^{n-1-m}}{1 + \alpha\beta + \cdots + (\alpha\beta)^{n-m}} \right) \right] \left. \right\} \\ & + \alpha \left[\sum_{m=0}^n (\alpha\beta)^m \right] \ln(k). \end{aligned} \tag{†}$$

Value function iteration VIII

- Consider the sequences of the three terms (functions) indexed by n , that make up v_{n+1} .
- As we take $n \rightarrow \infty$, the first term on the right of (\dagger) , has the limit

$$\frac{\ln(1 - \alpha\beta)}{1 - \beta},$$

since $\beta \in (0, 1)$ and $\alpha \in (0, 1)$, so that $\alpha\beta \in (0, 1)$.

- As we take $n \rightarrow \infty$, the second term on the right of (\dagger) , has the limit

$$\frac{\alpha\beta}{(1 - \alpha\beta)(1 - \beta)} \ln(\alpha\beta).$$

Value function iteration IX

- Finally, as we take $n \rightarrow \infty$, the last term on the right of (\dagger), has the limit

$$\lim_{n \rightarrow \infty} \alpha \left[\sum_{m=0}^n (\alpha\beta)^m \right] \ln(k) = \frac{\alpha}{1 - \alpha\beta} \ln(k).$$

- These three terms — (a sum of two) constant and slope terms, respectively A_n and B_n , of v_n — all converge monotonically as $n \rightarrow \infty$.
- Moreover, each successive function is converging geometrically fast.

Value function iteration X

Punchline:

- We have illustrated: from a naïve guess of the value function v_n ,
- Using the Bellman operator, approximate v as a limit of a sequence of updated value function approximations:

$$v(k) = \lim_{n \rightarrow \infty} v_n,$$

and

- in this analytical example,

$$v(k) = \frac{1}{1 - \beta} \left\{ \ln(1 - \alpha\beta) + \frac{\alpha\beta}{(1 - \alpha\beta)} \ln(\alpha\beta) \right\} + \frac{\alpha}{1 - \alpha\beta} \ln(k).$$

Policy Function I

Now that we have found v we can solve the finite-dimensional problem:

$$v(k) = \max_{k_+ \in \Gamma(k)} \left\{ \ln(k^\alpha - k_+) + \beta v(k_+) : k \text{ given} \right\}.$$

The first order condition yields the decision rule

$$k_+ = \alpha\beta k^\alpha =: g(k).$$

If we take the limit as $n \rightarrow \infty$, the sequence of approximate decision rules $\{g_n\}$ associated with $\{v_n\}$ has the limit

$$\lim_{n \rightarrow \infty} g_n(k) = \lim_{n \rightarrow \infty} \alpha\beta \left[\frac{1 - (\alpha\beta)^n}{1 - (\alpha\beta)^{n+1}} \right] k^\alpha = \alpha\beta k^\alpha =: g(k).$$

So the sequence of approximate decision rules $\{g_n\}$ also converges monotonically and the rate of convergence is geometric.

Policy Function II

Exercise

In this example, can you characterize the optimal trajectory of the economy $\{k_{t+1}(k_0)\}_{t \in \mathbb{N}}$, given k_0 ?

Qualitatively, what does it look like? Does it look qualitatively similar to the Solow-Swan model you studied as undergraduates?

In what way does it differ from that model?

Remarks and Lookahead I

- So the solution method above:
 - gave us a form for the value function v .
 - Once we know v the problem appears to be a simple two-period optimization problem.
 - The solution to that problem is a decision function g .
 - The optimal decision function induces the optimal trajectory of the economy (by recursion), given an initial state: $k_+ = g(k)$.

Remarks and Lookahead II

- Try this at home:
 - Alternatively, use the Euler equation to brute-force iterate on a guess of an optimal decision function.
 - (See Exercise 6.2.3(1) in Class Notes.)
 - This is mechanically similar to the value function iteration, except that we take the *Euler equation* as the recursive functional equation (i.e., the Euler Operator).

Remarks and Lookahead III

- Lookahead:
 - It turns out if a model economy's market solution (general/competitive equilibrium) has equivalent allocation to its hypothetical social planner's allocation, then we can pretend to solve the market equilibrium as a planner's problem.
 - Given the equivalent planner's (or command economy) allocation, we can back out implied market relative prices.
 - But as we'll see most interesting models have some form of market friction: market power, distorting taxes, contractual frictions. In those settings, solving the models require a bit more specialization and often the Euler Operator method is used. (More in "applications" part of this course.)