

# CS 472 HW 2

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## 1 Problem 3.6, Russel

Give a complete problem formulation for each of the following. Choose a formulation that is precise enough to be implemented.

d.) You have three jugs, measuring 12 gallons, 8 gallons, and 3 gallons, and a water faucet. You can fill the jugs up or empty them out from one to another or onto the ground. You need to measure out exactly one gallon.

Initial State	A 3-dimensional vector <b>jugs</b> = $[a, b, c]$ , where at $t_0$ $\mathbf{jugs} = [0, 0, 0]$
Goal State / Test	If either jug $a$ , $b$ or $c$ is equal to exactly 1.
Successor Function	The vector state can transition by filling or emptying jugs. Ex. $[0, 0, 0] \rightarrow [12, 0, 0] \rightarrow [0, 0, 0]$ . The vector can also be modified by emptying jugs into other jugs of different capacity. Ex. $[0, 8, 0] \rightarrow [8, 0, 0]$ However, if jug $b$ at full capacity 8 is added to jug $a$ with capacity 12, jug $a$ simply <i>overflows</i> . $[8, 8, 0] \rightarrow [12, 0, 0]$
Cost Function	$J = N_{pours} + M_{empties}$ <p>or perhaps</p> $J = f(N_{pours} + M_{empties}) + g(\text{Gal. Dumped on Floor})$ <p>.</p>

## 2 Problem 3.9, Russel

The missionaries and cannibals problem is usually stated as follows. Three missionaries and three cannibals are on one side of a river, along with a boat that can hold one or two people. Find a way to get everyone to the other side without ever leaving a group of missionaries in one place outnumbered by the cannibals in that place. This problem is famous in AI because it was the subject of the first paper that approached problem formulation from an analytical viewpoint (Amarel, 1968).

**a. Formulate the problem precisely, making only those distinctions necessary to ensure a valid solution. Draw a diagram of the complete state space.**

Initial State	A 6-dimensional vector representing the state of missionaries, cannibals and boats on each side 1 and 2 $\mathbf{S} = [m_1, c_1, b_1, m_2, c_2, b_2]$
Goal State / Test	If all of people (cannibals and humans) are on side 2. or if $m_2 \wedge c_2 = 3$
Successor Function	If $b_i = 1$ , you can move at most 2 people ( $(m_i + c_i) \leq 2$ ) total from the $i$ th side to the $j$ th side. $[3, 3, 1, 0, 0, 0] \rightarrow [2, 2, 0, 1, 1, 1]$ . Notice that the $i$ th boat value becomes zero and the $j$ th boat is 1 ( $-b_i, -b_j$ ). Every successor state must obey the constraint that for any $i$ th side, $m_i \geq c_i$ or that the cannibals can not outnumber missionaries at any time. Also, of course $m_i, c_i \geq 0$ .
Cost function	Number of actions.

**b. Implement and solve the problem optimally using an appropriate search algorithm. Is it a good idea to check for repeated states?** It may be a good idea to check for repeated states especially if using a depth-first search method (infinite loop) being that we can assume that given a current state is independent of all previous states. However, this would require a small amount of memory. We could avoid using history by using a breadth-first search strategy, but it turns out that since the state space is so small, the only history ever required to avoid a repeated state

is the previous state (2 previous states of successor. The following implementation uses a depth-first search, checking if a successor state satisfies the following conditions for every node expansion:

$$\begin{aligned}
& S_{k+1} \neq S_{k-1} \\
& \text{at } k+1 : \\
& m_1 \geq c_1 \text{ and } m_2 \geq c_2 \\
& m_1, c_1, m_2, c_2 \geq 0
\end{aligned} \tag{1}$$

It can be observed that the branching factor and state space of allowable states is actually very small. So small infact that they can be exhausted on this page.

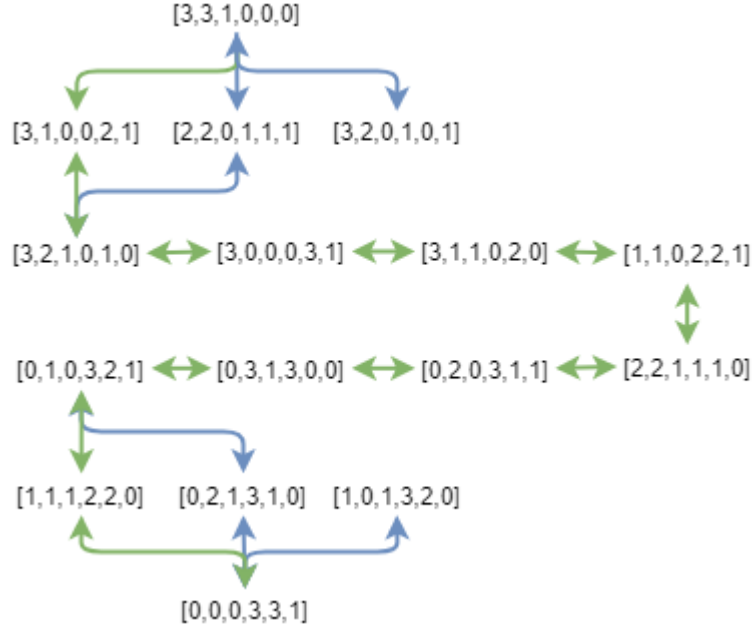


Figure 1: The state-space in respect to the cannibal-missionary constraint is relatively small. Shown is one of the possible solutions in green (strictly forward from either direction following a depth first search strategy). Either breadth-first or depth-first search will give an optimal solution assuming that your search obeys that the successor state is not the same as the previous state of your current state.

**c. Why do you think people have a hard time solving this puzzle, given that the state space is so simple?** As mentioned before, the branching factor of this 6-D state space may seem large, but after the constraints eq 1 are applied, the number of legal transition states is very small. The legal state space actually collapses into a single path and only branches once more before solution. There are 4 optimal solutions (in respect to number of actions).