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The ELF file format

Giovanni Lagorio

DIBRIS - Dipartimento di Informatica, Bioingegneria, Robotica e Ingegneria dei Sistemi University of Genova, Italy

Outline

- ELF structure
- 2 Program execution (and kernel binary formats)
- Opnomic link libraries
 - Building (PIC and DSO)
- Implicit dynamic linking
- 5 Library interposition (and explicit linking)
- 6 Initialization and termination

Executable and Linkable Format

Very flexible file format, can be used for

- executables
- shared objects, AKA dynamic libraries
- object files, AKA relocatable files
- core dumps
 dumps of th

dumps of the addres space of the process include the state of the process, snapshot of the state of system. puo aiutare a fare una analisi dopo che il programma è crashato

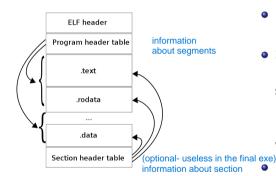
3 / 46

References:

- ELF(5), core(5) and gcore(1)
- en.wikipedia.org/wiki/Executable_and_Linkable_Format
- https://refspecs.linuxfoundation.org/elf/elf.pdf
- https://uclibc.org/docs/elf-64-gen.pdf

A nice video on ELF is "In-depth: ELF" https://youtu.be/nC1U1LJQL8o

Two views: segments and sections



https://commons.wikimedia.org/wiki/File:

Elf-layout--en.svg

- ELF header at the beginning is a "road map"
- Section header table, if present, holds linking information: instructions, data, symbol table, relocation information,

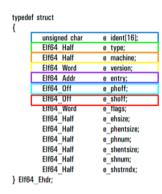
Beware: sections *can* be present without their header

Program header table, if present, describes segments; that is, tells how to build a process image for execution

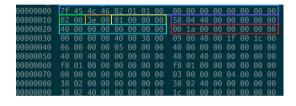
section use by the static linker, the os dosent use it.

The os use use the segments, they specify how to map the file in memory and to set the protection (readeable, writable ecc). it is not a great idea to put files with different level of security (one file only readble others also executable).

ELF (file) header



varie info little -endian big



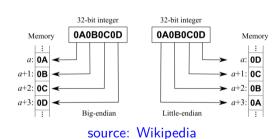
5 / 46

https://blog.k3170makan.com/2018/09/introduction-to-elf-format-elf-header.html

All structure definitions can be found in /usr/include/elf.h

Endianness

e_ident[EI_DATA] describes the endianness



BIG-ENDIAN

LITTLE-ENDIAN

source: Simply Explained

Intel CPUs use. . . little endian

Demos/Exercises

- Change the OS ABI in hello-world-ok; does the program still run?
- What's wrong with hello-world-maybe-broken?
 - Hint: try comparing the bytes inside the two files (with a hex-editor or vbindiff)

Common names of main sections

```
text Code
     .data/.rodata/.bss Data / read-only data / uninitialized data
             .init/.fini Initialization/Termination code
.init_array/.fini_array Pointers to initialization/termination code
           .ctors/.dtors Old version of the previous
                  .interp Interpreter, AKA dynamic-linker
   .dynamic/.got*/.plt* "stuff" for dynamic linking
                  .debug* Debugging information
          *.gnu.*/.gcc*/ GNU/Linux extensions
                .eh frame Exception handling unwinding information
                     .rel* Relocations
                    *sym* Symbols
                    *str* String tables
```

Main segment types

```
PT_LOAD something to "load", typically to mmap
PT_PHDR the program header itself, when available in the process memory
PT_INTERP .interp section
PT_DYNAMIC .dynamic section
PT_GNU_EH_FRAME .eh_frame_hdr section, used to locate the .eh_frame section
PT_GNU_STACK empty segment, whose flag specify whether the stack should be made executable
```

Fun with ELF

Some people created very small ELFs, by abusing the format. E.g.,

- overlapping different things
- putting code inside "holes" in the headers
- omitting trailing zeros
- . . .

there are even challenges where the goal is to build the smallest ELF

To know more:

- Write-ups for "PlaidCTF 2020 golf.so" https://ctftime.org/task/11305
- "A Whirlwind Tutorial on Creating Really Teensy ELF Executables for Linux (or, "Size Is Everything")"

www.muppetlabs.com/~breadbox/software/tiny/teensy.html

 "Adventures in Binary Golf - netspooky" https://www.youtube.com/watch?v=VLmrsfSE-tA

Giovanni Lagorio (DIBRIS) The ELF file format October 10, 2024

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Program execution

- What happens when (from, for instance, bash) we run ./hello-world?
- Which syscalls are involved when a file gets executed?
 - the shell use fork(2) and execve(2), typically through exec(3)
- execve
 - creates a new (virtual) address space
 - maps the PT_LOAD segments
 - creates some runtime segments
 - stack/data regions might be *executable*, depending on segment GNU_STACK and kernel version. See: https://stackoverflow.com/a/64837581
 - copies filename, command line arguments, and environment into it
 - if the file is an $\times 86/\times 64$ ELF (i.e. corresponding to HW architecture) it can be run
 - \dots otherwise? \rightarrow hello-world.arm

https://ownyourbits.com/2018/05/23/the-real-power-of-linux-executables/

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Binary formats

- Linux supports a bunch of binary formats
- Each format is run by a specific handler
 - some handlers come with the standard kernel (ELF, a.out, scripts, ...)
 - others can be added through loadable modules
- Whenever a file is to be executed through execve, its 128 first bytes are read and passed on to every handler
 - that can accept or ignore it, depending on some magic value; e.g. 0x7F 'E' 'L' 'F' \rightarrow ELF #! \rightarrow a script
- One, user extensible, handler is binfmt_misc
 - offers a /proc interface to the system administrator
 - sudo sh -c 'echo 1 > /proc/sys/fs/binfmt_misc/status' to enable, 0 to disable
 - specifies what userland interpreter should run for specific file types

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Virtual FS: binfmt_misc

- Interpreters specified inside /proc/sys/fs/binfmt_misc
 - E.g. qemu-arm allows us to run ARM executables on Intel machines (installed by qemu-user-binfmt)
- \bullet These handlers can be enabled/disabled/removed by writing 1/0/-1 to the corresponding files; e.g. to disables ARM emulation:
 - echo 0 > /proc/sys/fs/binfmt_misc/qemu-arm
- New entries can be added by writing to /proc/sys/fs/binfmt_misc/register; see https://www.kernel.org/doc/html/latest/admin-guide/binfmt-misc.html

WSL

On WSL the package qemu-user-binfmt does not seem to register the qemu-arm interpreter, so arm binaries cannot be run automagically

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Outline

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Dynamic link libraries

Why?

- Smaller programs, that (automatically) use the most recent libraries
- Code pages can be (ro-)shared among different processes

However,

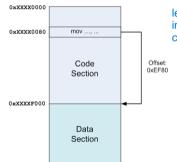
- Different processes may (need to) map libraries at different addresses
- To share pages, we can't relocate by using runtime patching, so:
 - Position Independent Code
 - instead of absolute addresses, EIP/RIP relative addressing
 - in the binary the program base is 0 (and can be mapped everywhere)
 - (Relocatable) external references use indirections through data
 - each external variable/function is accessed indirectly
- Libraries "must" be PIC; however, executables arewere typically position-dependent (more efficient, especially on 32 bits)

How?

Key insights (1/5)

- offsets between text and data sections statically known
- 2 we can use IP-relative offsets to access (statically linked) data
 - requires thunking on 32 bits; x64 can use RIP-relative offsets

cosi il programma usa il puntatore per chiamare la funzione, cosi non devi portarti in giro il codice ma pè in unico posto



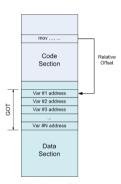
le librerie sono compilato con position indipendent code, in questo modo si puo caricare librerie da qualsisi posizione

> per ogni funzione esterna che il programma vuole chaimare abbiamo un puntatore

Taken from PIC in shared libraries

Key insights (2/5)

- we use an indirection, through the GOT Global Offset Table, for dynamically linking external references
 - GOT resides in the data section and
 - the (static) linker generates
 - (dynamic) relocation entries for it
 - one relocation entry for each variable v, regardless the number of times v is accessed



Taken from PIC in shared libraries

Key insights (3/5)

Functions could be treated in the same way, however

- a program may import a lot of functions, and most/some of them could be rarely called
- applying all relocations at startup, slows it down

Idea: lazy binding = fixing relocations on-the-fly when needed

• that is, the first time a function is called

viene fatto il collegamento du tutte le libreir

19 / 46

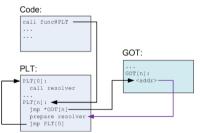
- this is the default for 1d and was the default for gcc
 - gcc option: -z lazy
- on Ubuntu, gcc now tells 1d to direct 1d.so to resolve all symbols when the program is started
 - gcc option: -z now
 - this is more secure, as we'll discuss

lazy binding= i binding vengono fatti solo quando chiamati la fuznione,

now fatti tutti prima(ormai fatto cosi perche piu sicuro e non molto costoso per gli standard moderni)

Key insights (4/5)

- calls to dynamic symbols = calls into the Procedure Linkage Table
 - PLT = array of stubs that call the "real" functions using GOT
 - only functions can be lazily bound, variables are always eagerly bound
 - functions, whose address has been taken, are eagerly bound too
- first entries of PLT/GOT are "special"; PLT[0]/GOT[0] is the resolver

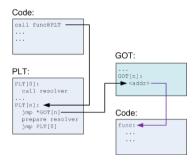


La GOT è una tabella che memorizza gli indirizzi delle variabili globali e delle funzioni esterne (cioè definite in altre librerie condivise) che vengono usate nel programma. Durante l'esecuzione, il programma utilizza questa tabella per accedere agli indirizzi reali delle funzioni

Taken from PIC in shared libraries

Key insights (5/5)

When the symbol has been resolved:



For more details see PIC in shared libraries and [DFCS+15]

Variations

With early-binding:

 depending on gcc version/options, PLT entries could be shortened to 8 bytes, instead of 16 (these are found in .plt.got instead of .plt):

```
Disassembly of section .plt: [...]
0000000000001040 <printf@plt>:
   1040: ff 25 8a 2f 00 00
                                          QWORD PTR [rip+0x2f8a]
                                   qmj
   1046: 68 01 00 00 00
                                   push
                                          0x1
   104b: e9 d0 ff ff ff
                                          1020 <.plt>
                                   qmj
Disassembly of section .plt.got:
000000000001050 <__cxa_finalize@plt>:
   1050: ff 25 a2 2f 00 00
                                          QWORD PTR [rip+0x2fa2]
                                   qmi
    1056: 66 90
                                   xchg
                                          ax.ax
```

- gcc allows to avoid the PLT, option -fno-plt, by generating:
 call QWORD PTR [GOT-func] instead of: call func@PLT
 - simpler and more efficient

Security considerations GOT/PLT

GOT is an interesting data-structure, which might be writable

Food for thought:

- GOT overwrite = calling system when you want to call printf ©
- leaking the address of, say puts, may help to find the address of system

RELRO is a memory corruption mitigation

Related 1d options:

- -z norelro: don't create PT_GNU_RELRO
- -z relro: create PT_GNU_RELRO segment, which will be made read-only after relocation

23 / 46

Full relro protection in gcc: -z relro -z now

Building PIC/PIE

GCC options

- -fpic generate PIC, which accesses external symbols through a GOT
- -fpie similar to -fpic, but generated PIC can be only linked into executables; typically used with -pie

Be consistent (for predictable results)

- -f... are for the compiler, -pie/-shared/-static for the linker
 - -static static linking; shared libraries are ignored
 - -shared -fpic produce a shared object
 - ullet -pie -fpie produce an "executable" shared object o better ASLR
 - (only in recent gcc) -static-pie https://gcc.gnu.org/onlinedocs/gcc/Link-Options.html

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How to build dynamic libraries

ELF shared objects, created by using -shared

- gcc -shared -fpic -o libfuncs.so my-lib*.c
- gcc main.c -L. -lfuncs
- LD_LIBRARY_PATH=. ./a.out
 - If LD_LIBRARY_PATH is defined, it is searched before looking in standard library directories
 - unless the executable is set-UID/GID (more details in the man)
 - a production application should never rely on LD_LIBRARY_PATH; shared libraries should be either installed in
 - standard directories, or
 - directories specified by DT_RUNPATH/DT_RPATH inside the ELF (by using 1d option -rpath).
 Inside R(UN)PATH the name \$ORIGIN means: "the directory containing the application" see 1d.so(8) for more

Giovanni Lagorio (DIBRIS) The ELF file format October 10, 2024 26 / 46

Outline

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Program execution

```
Dynamically linked executables contain special segments: 
PT_INTERP the "interpreter" (=the dynamic loader) 
PT_DYNAMIC linking data
```

When a program p is run

- the kernel creates the address space and maps p's PT LOAD segments
- if there is no PT_INTERP, the execution continues in p's entry point
- else, the "interpreter" is mapped along p and run

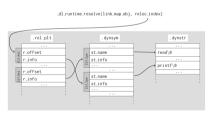
Dynamic tables

```
PT_DYNAMIC contains tags/values; listed by readelf --dynamic DT_NEEDED specifies a needed library DT_STRTAB points to the dynamic string table
```

DT_SYMTAB points to the dynamic symbol table

DT_PLTREL specifies whether PLT uses REL or RELA relocations

DT_REL[A] points to the relocations, whose size is given by DT_REL[A]SZ



From [DFCS+15]

Dynamic loader

The dynamic linker is 1d.so(8), actually

- ld.so handles a.out binaries
- ld-linux.so* handles *ELF*
 - /lib/ld-linux.so.1 for libc5
 - /lib/ld-linux.so.2 for glibc2, which has been used for years

same behavior, and same support files; for details: ldconfig(8)

lt:

- Finishes mapping needed libraries and then jumps to p's entry-point
- It's a lighter process w.r.t. static linking and uses different sections

In gdb (+GEF) you can observe this process by:

- set stop-on-solib-events 1
- r
- info shared / vmmap / xfiles

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Debugging the dynamic loading

Environment variable LD_DEBUG (ignored in secure-execution mode) can enable the output of debugging information about operation of the dynamic linker.

To get you started:

LD_DEBUG=libs /bin/echo BASC

For more information: ld.so(8)

Symbol resolution

Shared libraries were designed so that the default semantics for symbol resolution exactly mirrored those of static ones

- that is, a previous definition of a global symbol, e.g. in the main program, overrides definitions in following libraries
 - If defined multiple times, bound to the first definition found by scanning libraries in the left-to-right order in which they were listed
- this makes transition from static to shared relatively easy; however
- with default semantics, a shared lib is not a self-contained subsystem
- to guarantee that an invocation of foo in a shared library call its own version of foo, we can
 - override default binding with, for instance, ld -Bsymbolic ...
 - change default visibility with -fvisibility=hidden and/or use __attribute__((visibility ("default")))
 - ...

More details in *How To Write Shared Libraries* [Dre11], by Ulrich Drepper, which contains all details and also covers *symbol versioning*

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Library interposition

Linux linkers support *library interposition*:

- intercepting calls to library functions, and executing your own code
- basic idea: calls to a *target function* are replaced with calls to a wrapper function, with the same signature

Three kinds:

- compile-time: using macros of C preprocessor. . . boring ©
- link-time: using --wrap flag in ld (typically through -Wl,--wrap, func-name from gcc)
 - any undefined reference to *symbol* will be resolved to __wrap_*symbol*. Any undefined reference to __real_*symbol* will be resolved to *symbol*
- run-time, using the linker API (\rightarrow next slide)

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Dynamic Linker API

```
void *dlopen(const char *filename, int flags);
```

explicitly loads the dynamic shared object (shared library) filename, and returns an opaque handle for the loaded object

```
void *dlsym(void *handle, const char *symbol);
```

takes a *handle* and a symbol name, and returns the address where symbol is loaded into memory

There are two special pseudo-handles:

- RTLD_DEFAULT: find the first occurrence of the desired sympol using the default shared object search order

 ma neanche in quresto momento ci ho capito molto
- RTLD_NEXT: find the next occurrence of the desired symbolish the search onder after the current object. This allows to provide a wrapper after the object

in pratica puoi usare altre library fatte a mano invece di

35 / 46

quelle esterne, equesto è un metodo per non

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LD_PRELOAD

Environment variable LD_PRELOAD specifies shared objects to be loaded *before* all others; can be used to override functions

- Indeed, this technique was used by some recent malware; e.g., https://blogs.blackberry.c om/en/2022/06/symbiote-a-new-nearly-impossible-to-detect-linux-threat
- To debug, use:

```
strace -E to set environment variables for the traced command
  gdb set environment LD PRELOAD=...
```

• LD_PRELOAD ignored for set-UID/GID programs (see man for details)

Interposition example

```
#define _GNU_SOURCE
#include <stdio.h>
#include <string.h>
#include <dlfcn.h>
int strcmp(const char *s1, const char *s2)
        static int (*real_strcmp)(const char *, const char *) = 0;
        if (!real strcmp)
                real_strcmp = dlsym(RTLD_NEXT, "strcmp");
        int result = real_strcmp(s1, s2);
        fprintf(stderr, "strcmp(%s, %s)=%d\n", s1, s2, result);
        /* return result: */
        return 0:
```

 \rightarrow interposition

Exercise: antidebug1

- ./antidebug1
- ② strace -o /dev/null ./antidebug1

Isn't that suspicious? Let's analyze the behavior:

- let's try: strace ./antidebug1
 - the interesting part is almost at the end of the output
- can you bypass the check?
 - On my Ubuntu the actual prototype for current implementation is: long int ptrace(enum __ptrace_request __request, ...) (see /usr/include/x86_64-linux-gnu/bits/ptrace-shared.h)

You can also take a look at antidebug{2,3} Beware: you can't solve all of them (with the tools we have seen so far...stay tuned ©)

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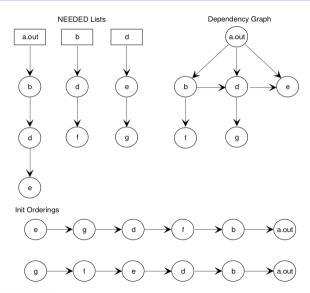
Initialization and termination order

From ELF standard:

- After the dynamic linker has built the process image and performed the relocations, each shared object gets the opportunity to execute some initialization code
 - All s.o. initializations happen before the executable gains control
- Before the initialization code for any object A is called, the initialization code for any
 other objects that object A depends on are called. For these purposes, an object A
 depends on another object B, if B appears in A's list of needed objects (recorded in the
 DT_NEEDED entries of the dynamic structure)
 - The order of initialization for circular dependencies is undefined

Example...

Construction order example



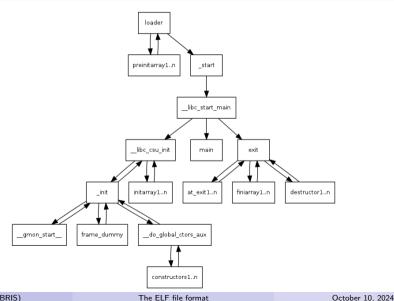
Initialization and termination sections

- Two section types:
 - array of pointers: .preinit_array, .init_array and .fini_array
 - the link-editor encodes these information inside DYNAMIC segment
 - Gcc used also a similar .ctors
 - obsolete, a single code block: .init

built by concatenating like sections from relocatable objects

- The runtime linker (or a startup mechanism) executes:
 - functions whose addresses are contained in the .preinit_array
 - for executables only
 - 2 the .init section, as an individual function, _init
 - functions whose addresses are contained in the .init_array
- Analogously, for termination
 - .fini_array, .fini (and .dtors)

Going down to the rabbit hole



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Constructor/destructor example

```
#include <stdio.h>
__attribute__((constructor))
void foo() {
        printf("Hello!\n");
attribute ((destructor))
void bar() {
        printf("Bye\n");
int main()
        printf("... in main ...\n");
```

More resources

- The ELF file format https://www.gabriel.urdhr.fr/2015/09/28/elf-file-format/
- ELF loading and dynamic linking https://www.gabriel.urdhr.fr/2015/01/22/elf-linking/
- Anatomy of an ELF core file https://www.gabriel.urdhr.fr/2015/05/29/core-file/
- Preeny, a collection of LD_PRELOADed CTF-oriented "tricks": https://github.com/zardus/preeny

References

[DFCS+15] Alessandro Di Federico, Amat Cama, Yan Shoshitaishvili, Christopher Kruegel, and Giovanni Vigna.

How the ELF Ruined Christmas.

In USENIX Security Symposium, pages 643-658, 2015.

[Dre11] Ulrich Drepper.

How to write shared libraries, 2011.