#### Analysis of Algorithms

V. Adamchik CSCI 570

Lecture 13 University of Southern California

## Approximation Algorithms

The Design of Approximation Algorithms,

D. Williamson and D. Shmoys, Cambridge University Press, 2011.

#### Exam - II

Date: Thursday April 29

Time: starts at 5pm Pacific time

Length: 2 hrs and 20 mins

Time Frame: 12 hours

Locations: online, DEN Quiz

Practice: will be posted

TA Review: April 27 and April 28

Open book and notes
Use scratch paper
Follow the Honor Code (obey all rules for taking exams)
No internet searching
No talking to each other (chat, phone, messenger)

#### Exam - II

True/False

Multiple Choice

#### Written Problems:

- Network Flow (max flow, circulation)
- Linear Programming (standard and dual forms)
- NP Completeness (a proof by reduction)
- Approximations





Suppose we are given an NP-hard problem to solve.

Can we develop a polynomial-time algorithm that produces a "good enough" solution?

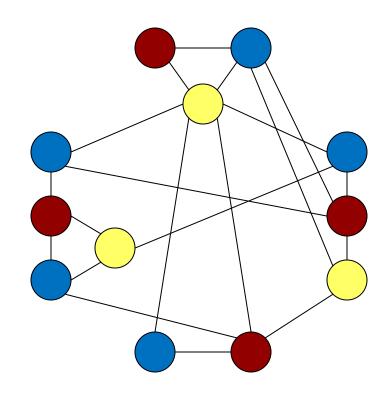
An algorithm that returns near-optimal solutions is called an approximation algorithm.

### Graph Coloring

Given a graph G=(V,E), find the minimum number of colors required to color vertices, so no two adjacent vertices have the same color.

This is NP-hard problem.

Let us develop a solution that is close enough to the optimal solution.



### Greedy Approximation

Given G=(V,E) with n vertices.

Use the integers {1,2,3, ..., n} to represent colors.

Order vertices by degree in descending order.

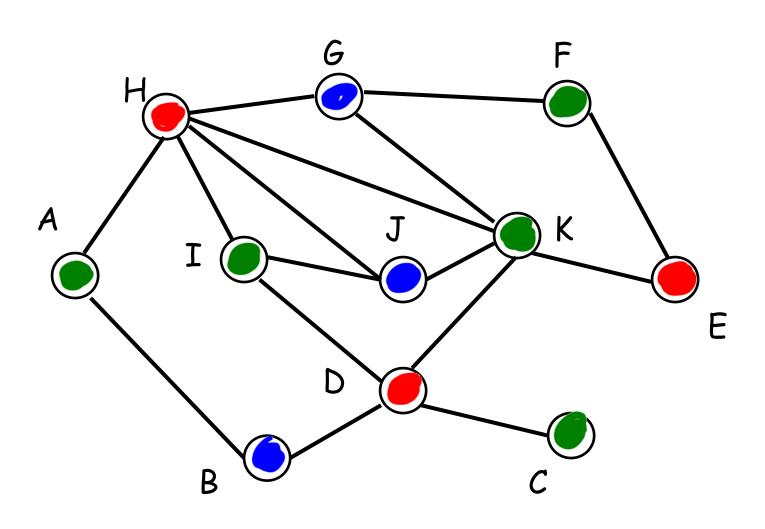
Color the first vertex (highest degree) with color 1.

Go down the vertex list and color every vertex not adjacent to it with color 1.

Remove all colored vertices from the list.

Repeat for uncolored vertices with color 2.

## Example



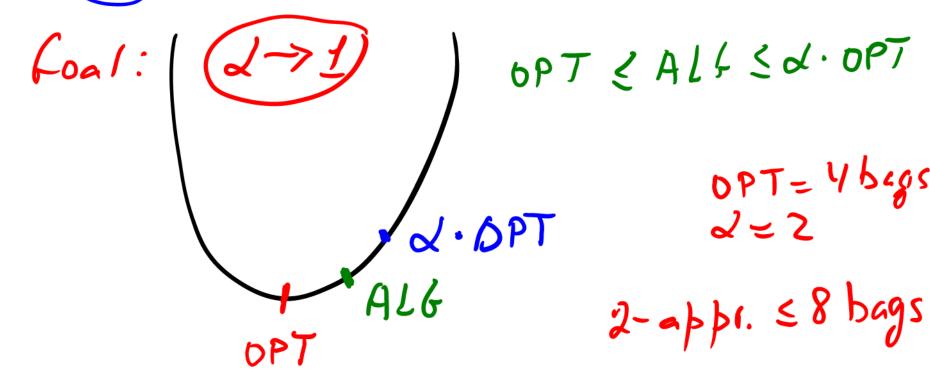
Order: H, K, B, B, Z, J, &, B, Z, J, &

#### Formal Definition

#### cohvex

Let P be a <u>minimization</u> problem, and I be an instance of P. Let ALG(I) be a solution returned by an algorithm, and let OPT(I) be the optimal solution.

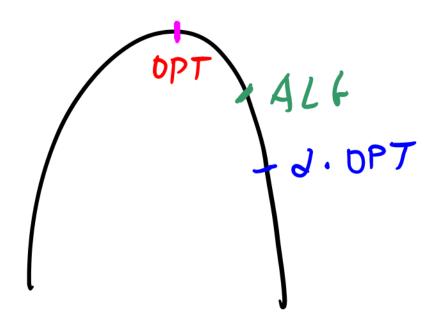
Then ALG(I) is said to be a  $\alpha$ -approximation algorithm for some  $\alpha > 1$  if for  $ALG(I) \leq \alpha \cdot OPT(I)$ .



#### Maximization Problem

Let P be a <u>maximization</u> problem, and I be an instance of P. Let ALG(I) be a solution returned by an algorithm, and let OPT(I) be the optimal solution.

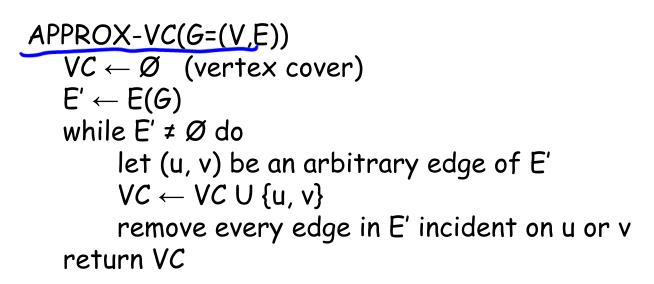
Then ALG(I) is said to be a  $\alpha$  -approximation algorithm for some  $0 < \alpha < 1$ , if for  $ALG(I) \ge \alpha \cdot OPT(I)$ .

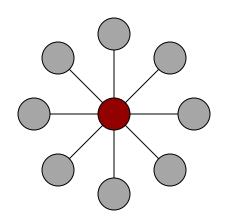


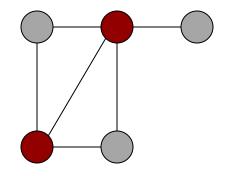
#### Vertex cover

Given G=(V,E), find the smallest  $S\subset V$  s.t. every edge is incident on a vertex in S.

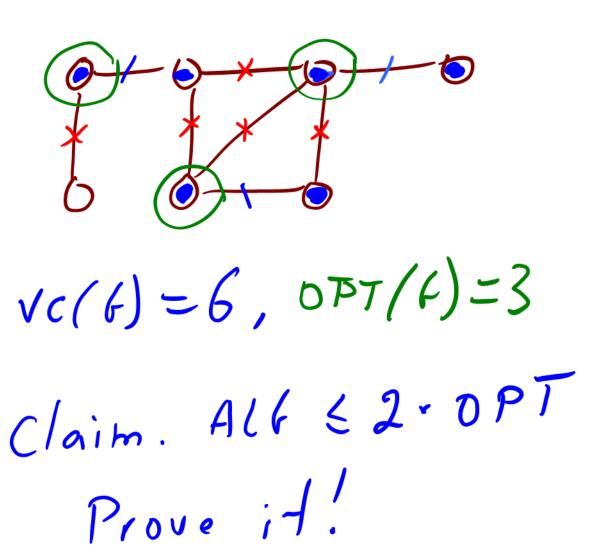
Let us design a <u>randomized</u> algorithm for vertex cover.







## Example



#### Vertex Cover

Lemma. Let M be a matching in G, and VC be a vertex cover, then

| VC| \geq | M|

Proof.

VC must cover each odg in M

# 2-Approximation Vertex Cover 10+ maximum (1): 2 < 2.

not maximum

Approx-VC(G):

M - (maximal) matching on G

VC - take both endpoints of edges in M

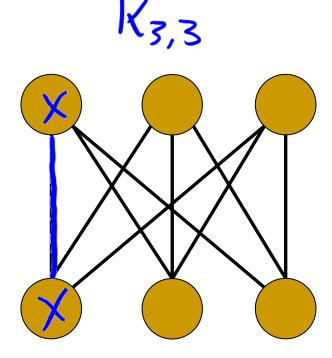
Return VC

Theorem. Let OPT(G) be the size of the optimal vertex cover and VC = Approx VC(G). Then  $|VC| \le 2 \cdot OPT(G)$ .

Proof. |VC| = 2. |M| \( \frac{1}{2} \). DPT

Can we do better than 2-Approximation?

ALF 
$$VC(K_{h,h}) = 2 - h$$



# Traveling Salesman Problem

The traveling salesman problem consists of a salesman and a set of cities (a complete weighted graph). The salesman has to visit each one of the cities starting from a certain one (e.g. the hometown) and returning to the same city. The challenge of the problem is that the traveling salesman wants to minimize the total length of the trip.

#### Theorem.

The traveling salesman problem is NP-complete.

NP-hard.

## Proof Liven K.

First, we have to prove that TSP belongs to NP. Secondly, we prove that TSP is NP-hard.

HC 
$$\leq_P$$
 TS P

Construction

(1) make complete

$$F = (V, F)$$

$$\omega(u, v) = \begin{cases} 0, (u, v) \in E \\ 1, (u, v) \notin E \end{cases}$$

$$F=(V,F)$$

Claim.  $f$  has a HC iff,  $f'$  has a TSP-four  $f$  construction.

Show that  $f$  has a TSP-four  $f$  construction.

## Solving TSP

Given an undirected complete graph G=(V,E) with edge cost c: $E\in R^+$ , find a min cost Hamiltonian cycle.

We will consider a metric TSP.

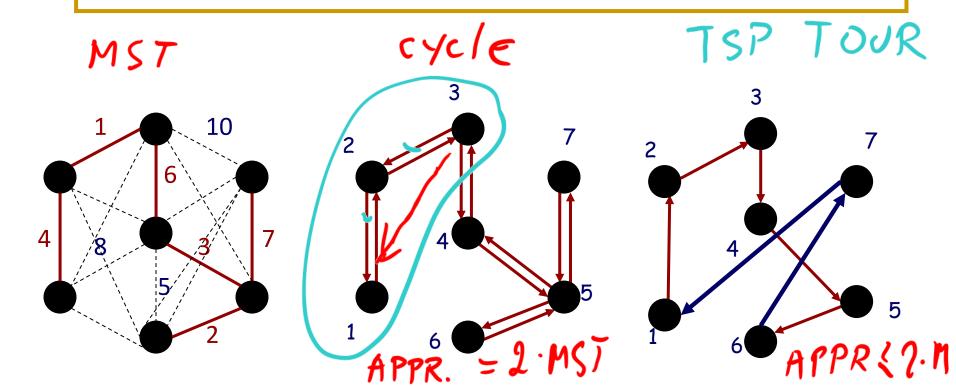
In the metric TSP, edge costs have to satisfy the triangle inequality, i.e. for any three vertices x, y, z,  $c(x,z) \le c(x,y) + c(y,z)$ .

We develop approximation greedy algorithm.

## Approximation Greedy Algorithm

#### Approx-TSP(G):

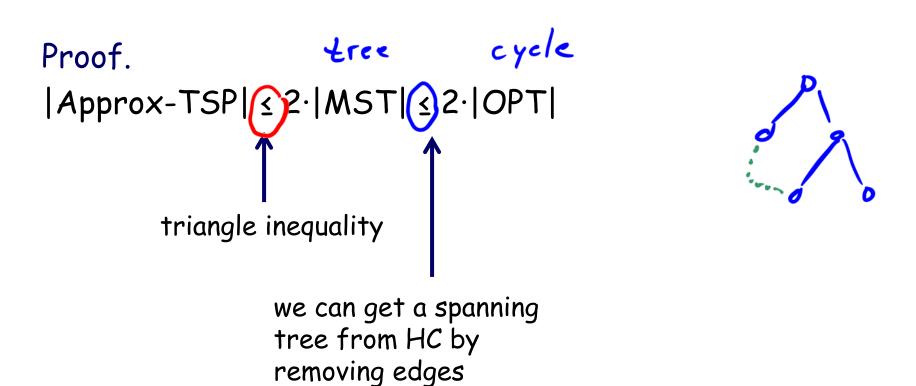
- 1) Find a MST of G (complete graph)
- 2) Create a cycle by doubling edges
- 3) Remove double visited edges



### Approximation TSP



Theorem. Approx-TSP is a 2-approximation algorithm for a metric TSP.



#### Christofides Algorithm € C MU

Observe that a factor 2 in the approximation ratio is due to doubling edges.

But any graph with even degrees vertices has an Eulerian cycle. (A Eulerian path visits each edge exactly once)

Thus we have to add edges only between odd degree vertices

min-wost matching

## Christofides Algorithm

Theorem (without proof).
Christofides is 3/2 approximation for Metric TSP

The algorithm has been known for over 40 years and yet no improvements have been made since its discovery.

#### General TSP

Theorem (If P $\neq$ NP) then for  $\forall \alpha$ >1 there is NO a polynomial time  $\alpha$ -approximation of general TSP.

#### Proof.

Suppose for contradiction that such an  $\alpha$  -approximation algorithm exists. We will use this algorithm to solve the Hamiltonian Cycle problem.

Start with G=(V,E) and create a new complete graph G' with the cost function

$$c(u,v) = 1$$
, if  $(u,v) \in E$   
 $c(u,v) = \alpha \cdot V + 1$ , otherwise

#### General TSP

Proof (continue)

$$c(u,v) = 1$$
, if  $(u,v) \in E$   
 $c(u,v) = \alpha \cdot V + 1$ , otherwise

If G has HC, then 
$$|TSP(G')| = V$$
.

2) If G has no HC, then

$$|TSP(G')| \ge (V-1) + \alpha \cdot V + 1 = V + \alpha \cdot V \ge \alpha \cdot V$$

Since the |TSP| differs by a factor  $\alpha$ , our approx. algorithm can be able to distinguish between two cases, thus decides if G has a ham-cycle. Contradiction.

## Bin Packing

You have an infinite supply of bins, each of which can hold M maximum weight. You also have n objects, each of which has a weight  $w_i$  ( $w_i$  is at most M). Our goal is to partition the objects into bins, such that we use as few bins as possible. This problem in general is NP-hard.

Devise a 2-approximation algorithm.

## Online algo First-fit approach

1. process items in the original order

Runtime-?

- 2. if an item doesn't fit the first bin, put it into the next bin
- 3. if an item does not fit into any bins, open a new bin

```
Example, items = \{40, 20, 35, 15, 25, 5, 30, 10\}
M = 45
40, 5
25
35
35
25
30
30
30
30
```

ALG = m 
$$m \le 7 \cdot m^*$$
, ALG  $\le 2 \cdot DP7$   
DPT =  $m^*$  Proof: a 2-approximation

Suppose we use m bins.

Let m\* denote the optimal number of bins.

Clearly, m\* ≥ (\(\Su\_i\)/M, \(\left\) \(\sime\) \(\sime\) \(\sime\)

On the other hand,  $(\Sigma w_i)/M > (m-1)/2$ 

This follows form the fact that at least (m-1) bins impossible are more than half full.

Because, if there are two bins less than half full, items in the second bin will be placed into the first by our algorithm.

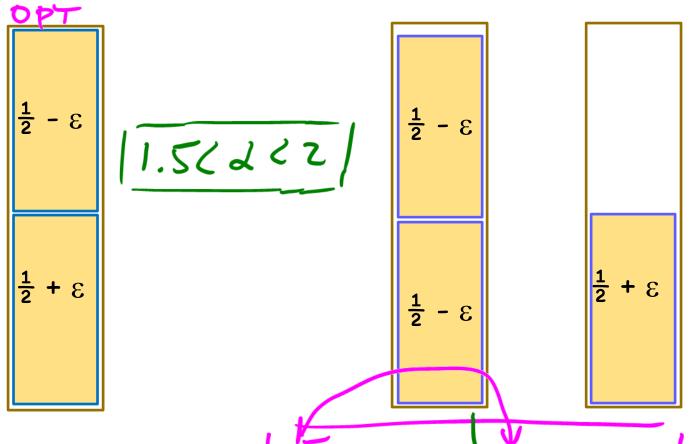
We have showed,  $m^* \ge (\sum w_i)/M > (m-1)/2$ 

Comparing the left and right hand sides, we derive

 $2m^* > m-1$  or,

m ≤ 2m\*

# Developing a lower bound (M=1)



Insert 2N items: 
$$\frac{1}{2} - \epsilon, ..., \frac{1}{2} - \epsilon, \frac{1}{2} + \epsilon, ..., \frac{1}{2} + \epsilon$$

T: N bins

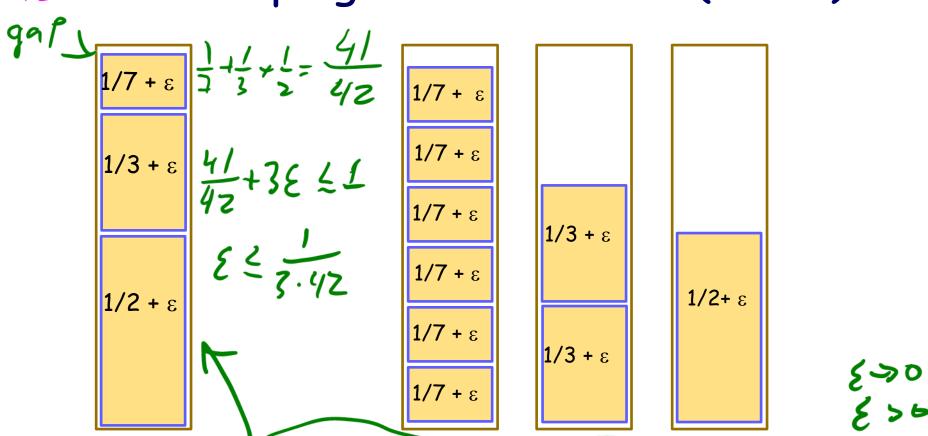
(FF) 
$$N/2$$
 bins = 1.5 N

N bins = 
$$1.5 N$$

FF ≥ 1.5 OPT

## 1/1/2

## Developing a lower bound (M = 1)



3N) items:  $(1/7 + \epsilon)$ ,...,  $1/7 + \epsilon$ ,  $1/3 + \epsilon$ ,...,  $1/3 + \epsilon$ ,  $1/2 + \epsilon$ ,...,  $1/2 + \epsilon$ 

OPT: N bins

FF: N/6 + N/2 + N bins = 5/3 N

## Developing a lower bound

99P

$$\frac{1/43 + \epsilon}{1/7 + \epsilon}$$

$$\frac{1/3 + \epsilon}{1/2 + \epsilon}$$

Observe

$$1 - (1/2 + 1/3 + 1/7) = 1/42$$

$$1 - \left(\frac{1}{2} + \frac{1}{3} + \frac{1}{7} + \frac{1}{7} + \frac{1}{7}\right) = \frac{1}{1806}$$

4N items:  $\frac{1}{43} + \epsilon, ..., \frac{1}{43} + \epsilon, \frac{1}{7} + \epsilon, ..., \frac{1}{7} + \epsilon, \frac{1}{3} + \epsilon, ..., \frac{1}{3} + \epsilon$ 

OPT: N bins

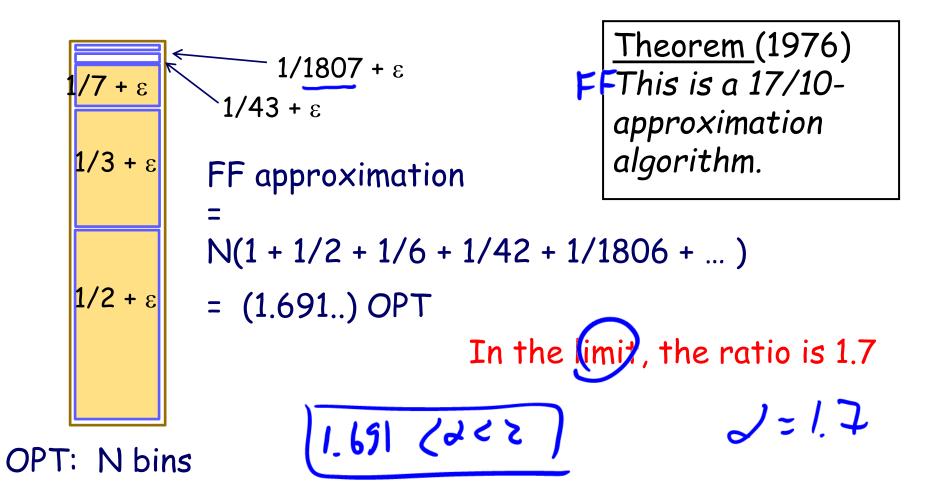
FF: N/42 + N/6 + N/2 + N = 71/42 N

FF ≥ 1.6905 OPT



## Developing a lower bound

Observe, 1 - (1/2+1/3+1/7+1/43) = 1/1806



## Offline algo Sorted First-fit approach

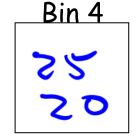
- 1. sort the input in descending order
- 2. apply the first-fit algorithm

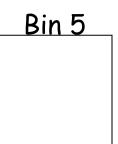
Theorem.
This is a 11/9 approximation
algorithm.

```
Example,
items = \{40, 20, 35, 15, 25, 5, 30, 10\}
M = 45 \{40, 35, 30, 25, 20, 15, 10, 5\}
```

Alb=4 OPT=4

Bin 1
1.0
40
5





#### Discussion Problem

Suppose you are given a set A of positive integers  $a_1$ ,  $a_2$ , ...,  $a_n$  and a positive integer B. A subset  $S \subseteq A$  is called feasible if the sum of the numbers in S does not exceed B. You would like to select a feasible subset  $S \subseteq A$  whose total sum is as large as possible. Give a linear time algorithm that finds a feasible set  $S \subseteq A$  whose total sum is at least half as large as the maximum total sum of any feasible set. You may assume that  $a_i \leq B$ .

**Example:** If  $A = \{8, 2, 4, 3, 5\}$  and B = 11 then the optimal solution is the subset  $S = \{8, 3\}$ . S+3 = 11

ALF 3 B/2

Algorithm: 1 Add items from A (in siven order) to some set X. until the total 2. Let the next How belong to another set Y.  $X = \{8,2\}$   $X = \{8,2\}$   $X = \{4,2\}$   $X = \{4,2\}$   $X = \{4,2\}$ solution: either X or Y.

Note, X+Y>B one of them >, B/2