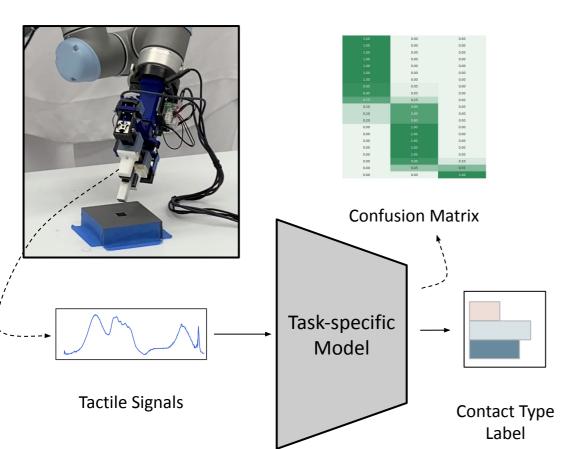
Learning task-specific models



Policy learning Diagonal Line Contact Contact Observation Contact State Observation Model Type Ground-truth Action **Imitation** Learning Control **Policy** Line Contact

Action

Observations

(w/ history)