

SMART SPOON FOR PARKINSON'S PATIENTS

Technical Team leader | World Robot Olympiad Germany | Jun 2022 - Dec 2023



[Link to the Youtube video!](#)

CONTEXT

Developed a **compact, intelligent stabilizing spoon** to assist individuals with **Parkinson's disease** who experience **hand tremors** while eating. **Inspired by my uncle** who suffers from PD, our goal was to create an **accessible, affordable and effective mechatronic assistive device** to improve the quality of life through **robotics in healthcare**.

GOALS

- Design an **ergonomic** and compact spoon that compensates involuntary hand tremors.
- Use **IMU data** and motor feedback to stabilize the spoon in real time.
- Develop a **responsive PID control system** to counteract pitch and roll axis of the spoon.
- Optimize the system for low to mid frequency tremors. (2 - 7Hz)
- Ensure cost effectiveness and accessibility for the Indian healthcare market.

TECHNOLOGIES USED

- CAD & Prototyping: Onshape, 3D Printing
- Microcontroller: Arduino Nano (C++ via Arduino IDE)
- Sensors & Actuators: **MPU9250 IMU**, N20 Gear Motors with Encoder, **Kalman filter** for sensor fusion
- Control Systems: Self tuned PID algorithm, PWM motor driver
- Electronics: DRV8833 Motor Driver, Boost Converter, LiPo Battery
- System Design: Embedded programming, hardware interrupt based motor feedback, **iterative testing**

CONTRIBUTIONS

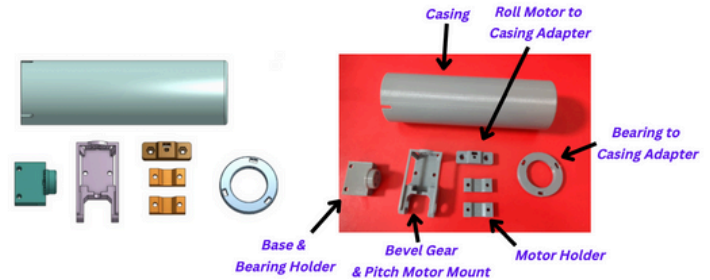
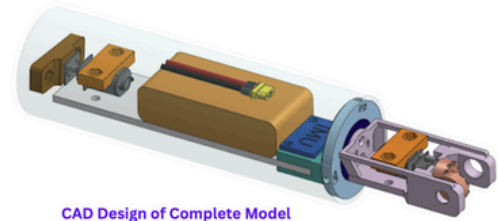
As the technical team lead, I was responsible for **research and development** of this product

Mechanical Design:

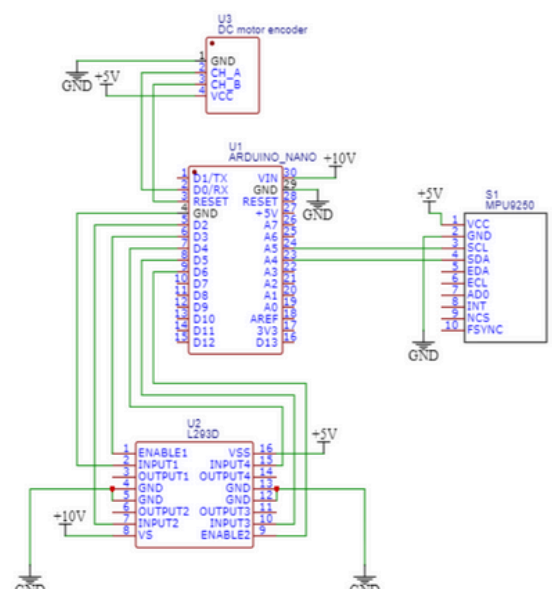
- Created the full 3D CAD of the smart spoon using Onshape.
- Designed compact housings for motors, bearings and IMU.
- Iterated across multiple prototypes (60mm -> 40mm casing), balancing **ergonomics** and internal volume.

Electronics & Soldering:

- Designed the **circuit architecture** and hand soldered the full electronic system, including the IMU, motor drivers, DC-DC converters, LiPo power delivery.



Circuit Diagram

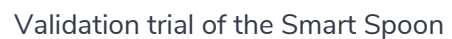


- Tuned a **custom PID controller** for two axes of motion using real time IMU feedback.
- Made sure this tuned PID controller works well for low to medium frequency hand tremors and with the weight of food on the spoon
- Integrated motor encoder readings via hardware interrupts for **precise positioning**.

- Programmed the Arduino Nano in **C++**, implementing logic to stabilize the spoon based on roll and pitch angle values.
- Added **logic** to pause motion when the user is picking up food.

- Switched from MPU6050 to MPU9250 to improve angular range and use the magnetometer.
- Switched from using the Pro Mini to Nano for better reliability and easier integration
- Replaced **FDM printed gears** with **SLA printed** and LEGO based alternatives for less backlash and durability.

- Performed system validation with Parkinson's patients via collaboration with RV College of Physiotherapy. Made technical improvements based on medical expert and patient trial feedback.



- Successfully stabilized spoon's pitch and roll, **reducing tremor transfer by ~70% in testing.**
- **Spoon's responsiveness** was proved sufficient for low and medium frequency tremors by patient trials and testing.
- Recognized by neurologists and designers from **Dozee, Dynocardia, and Max Planck Institute** for the immense real world impact.
- Medical publication is in progress and planned startup collaborations for manufacturing.

